

Supporting Information for

**Skillful Multiyear Sea Surface Temperature Predictability in CMIP6 Models
and Historical Observations**

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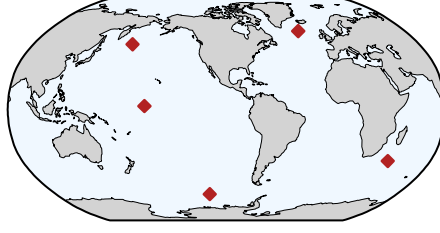
Hyperparameter tuning:

We tune the CNN hyperparameters using one GCM (*MPI-ESM1-2-LR*) and five locations across the globe (Fig S1a). The goal is to find a set of hyperparameters that performs well across all locations, and to then use the same architecture for all CNNs. We select hyperparameters sequentially using the following steps. In step 1, we tune the learning rate; in step 2, we tune the number of dense layers and neurons; in step 3, we tune the number of convolutional layers and filters; and in step 4, we tune the dropout rate and activity regularization parameter. At each step, we use keras tuner to train CNNs with different hyperparameter configurations. We then select a combination of hyperparameters that performs well on the validation set across all five locations before moving to the next step of tuning. In general, we find similarities in the best parameter combinations for each location, which supports our approach of using the same CNN architecture for all grid cells. However, it is possible that higher accuracy could be achieved in certain regions by tuning the architecture for that specific location, and therefore our results may slightly underestimate predictability. The results of the hyperparameter tuning are shown in Fig. S1. We found similar results when using different initial starting hyperparameters (results not shown).

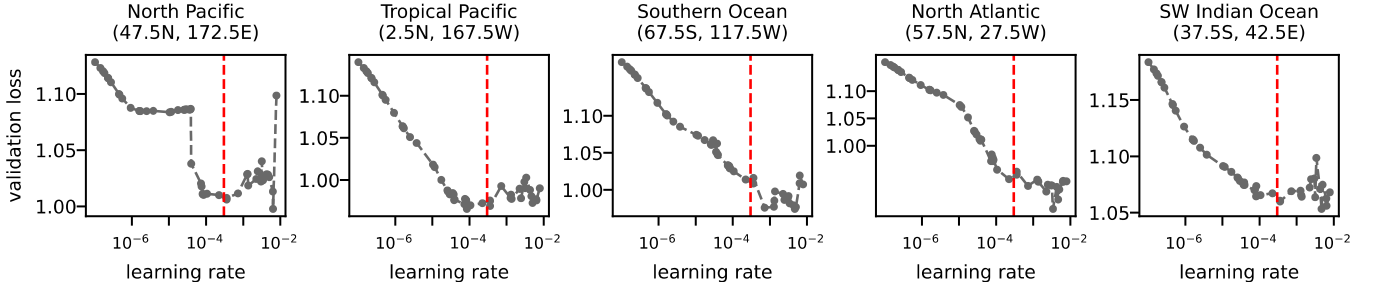
CNN training:

We use a categorical cross-entropy loss function with the Adam optimizer, a batch size of 32, and define an epoch as 100 steps. The initial learning rate is 0.0003, and we use a learning rate scheduler to decrease the learning rate by a factor of $e^{-0.05}$ each epoch after the first 10 epochs. We use a dropout rate of 0.2 on the dense layer. We use early stopping to end training once the validation loss increases for at least 5 epochs. We train each CNN with three different random initializations, and we select the trained model that has lowest validation loss for later analyses.

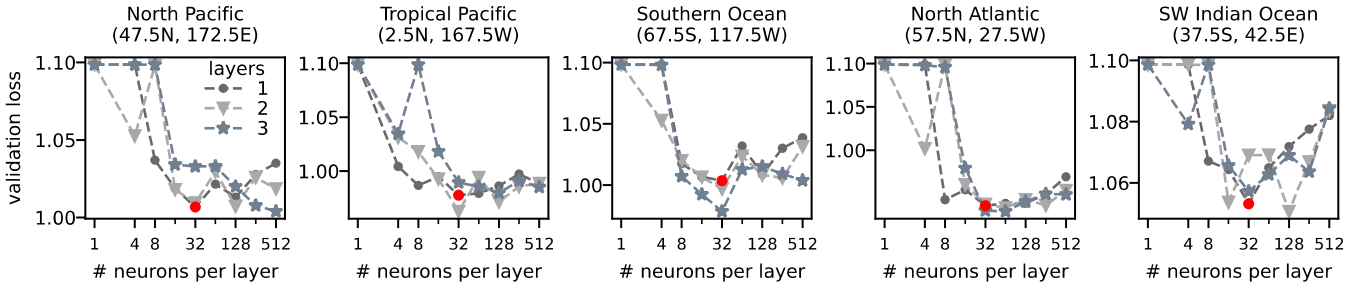
a) Locations used for hyperparameter tuning



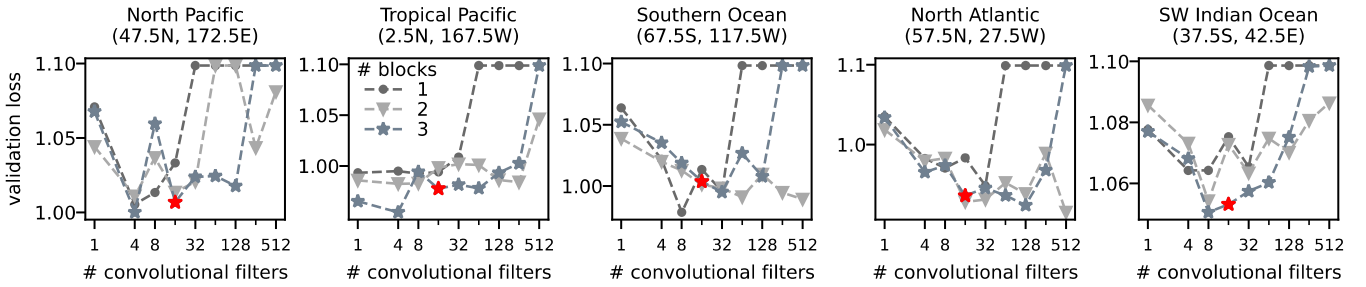
b) Learning Rate:



c) Dense Layer Configuration:



d) Convolutional Layer Configuration:



e) Regularization:

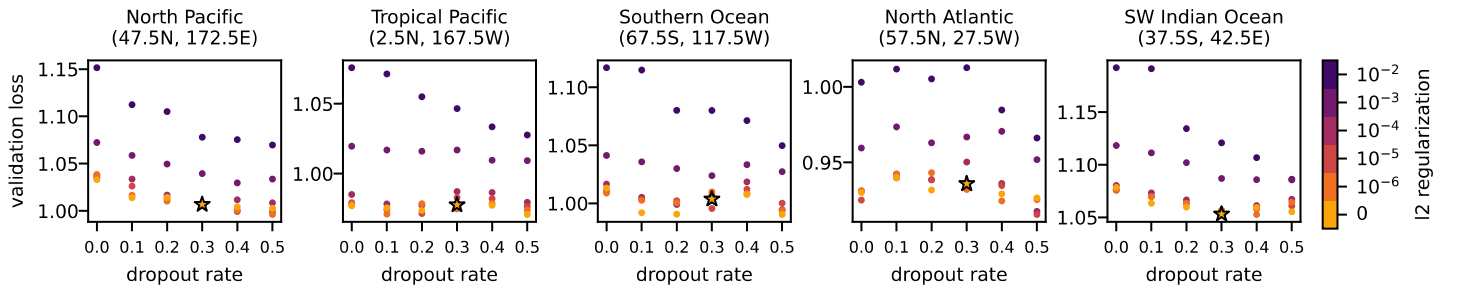


Figure S1. Hyperparameter tuning results. Selected parameters are shown by the red dashed line in b), red markers in c) and d), and the black stars in e).

Accuracy of CNN trained and tested on ACCESS-ESM1-5 simulations

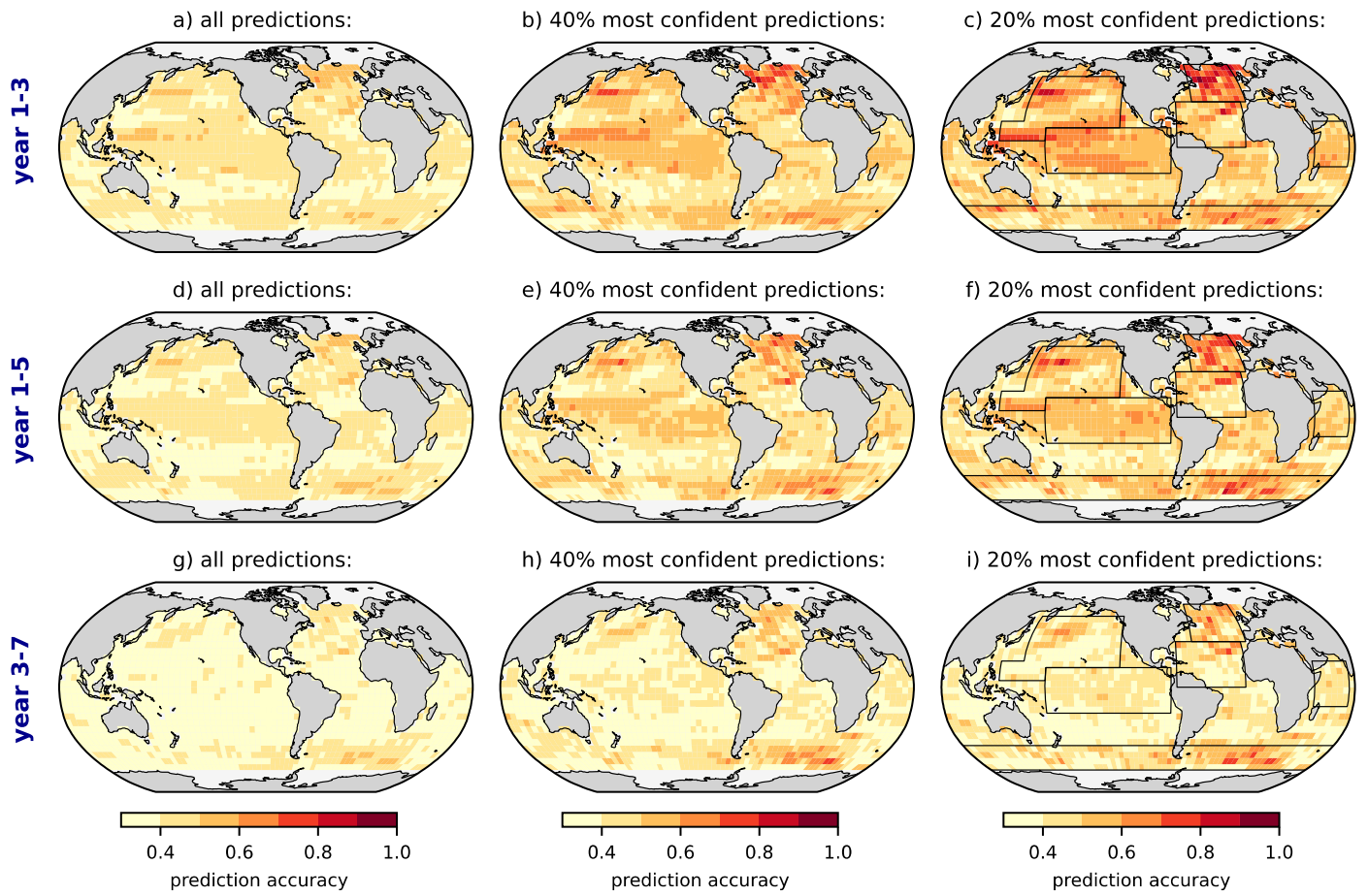


Figure S2. Same as Figure 2, but for ACCESS-ESM1-5.

Accuracy of CNN trained and tested on CanESM5 simulations

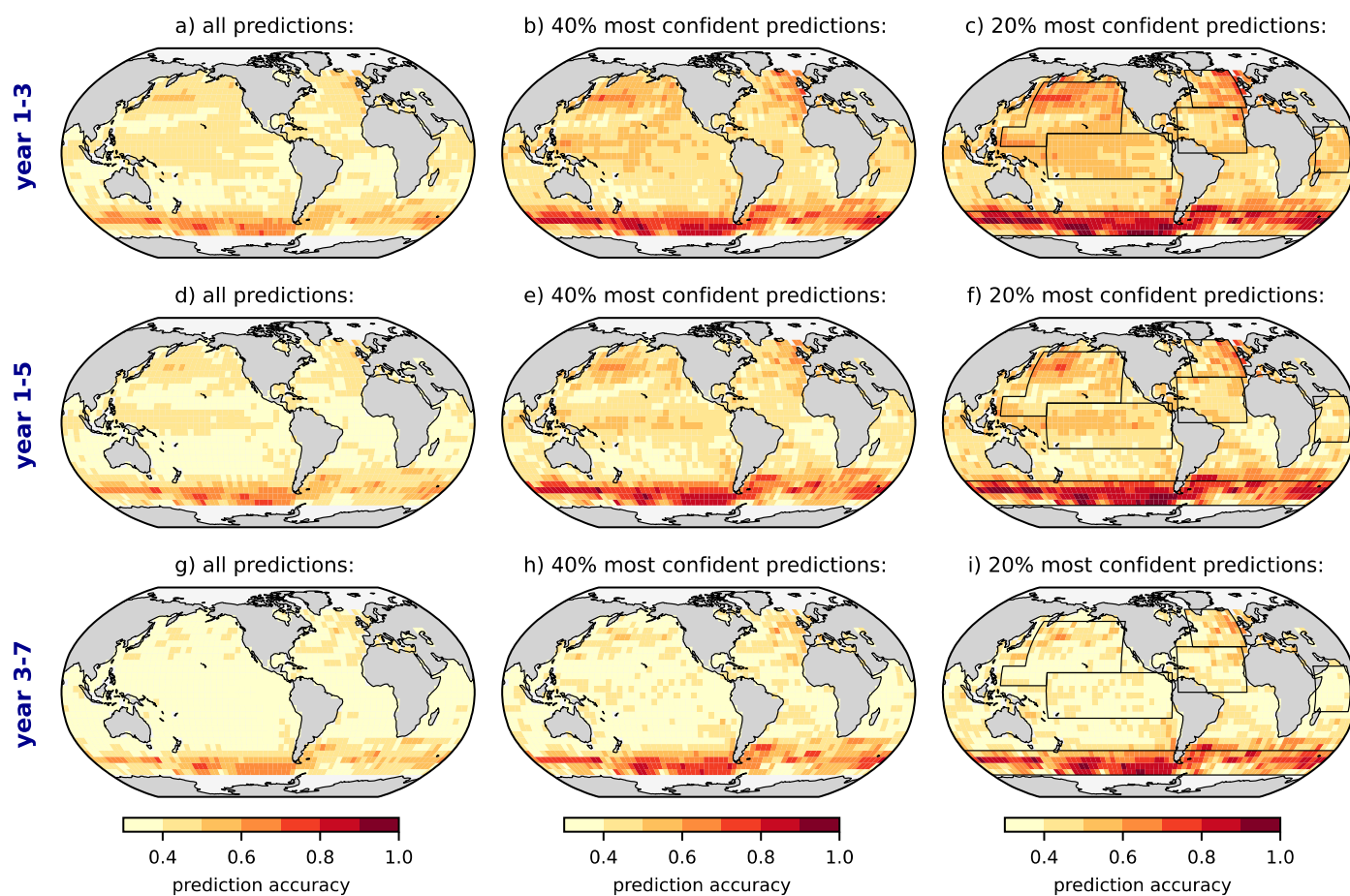


Figure S3. Same as Figure 2, but for CanESM5.

Accuracy of CNN trained and tested on CNRM-CM6-1 simulations

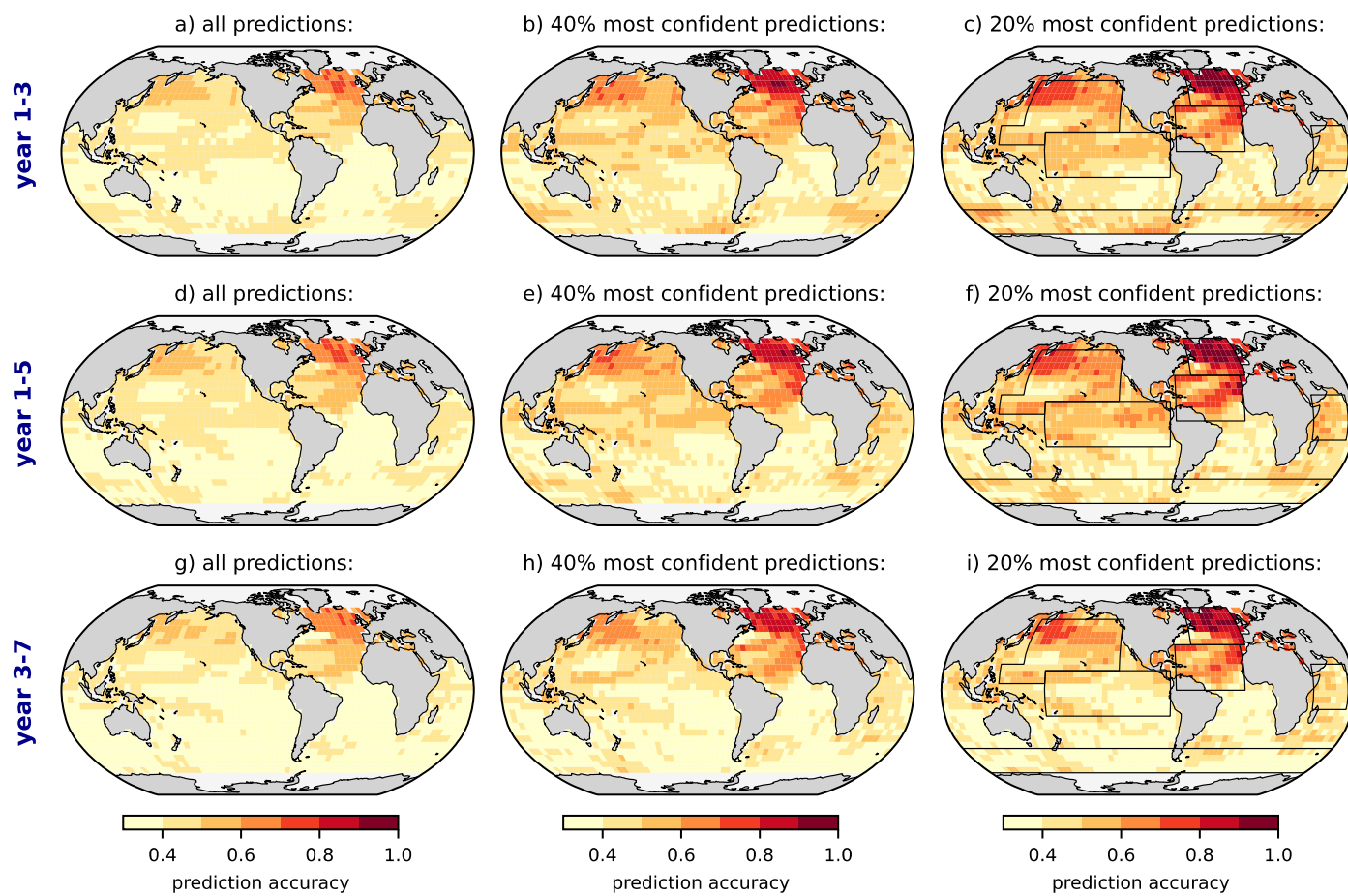


Figure S4. Same as Figure 2, but for CNRM-CM6-1.

Accuracy of CNN trained and tested on GISS-E2-1-G simulations

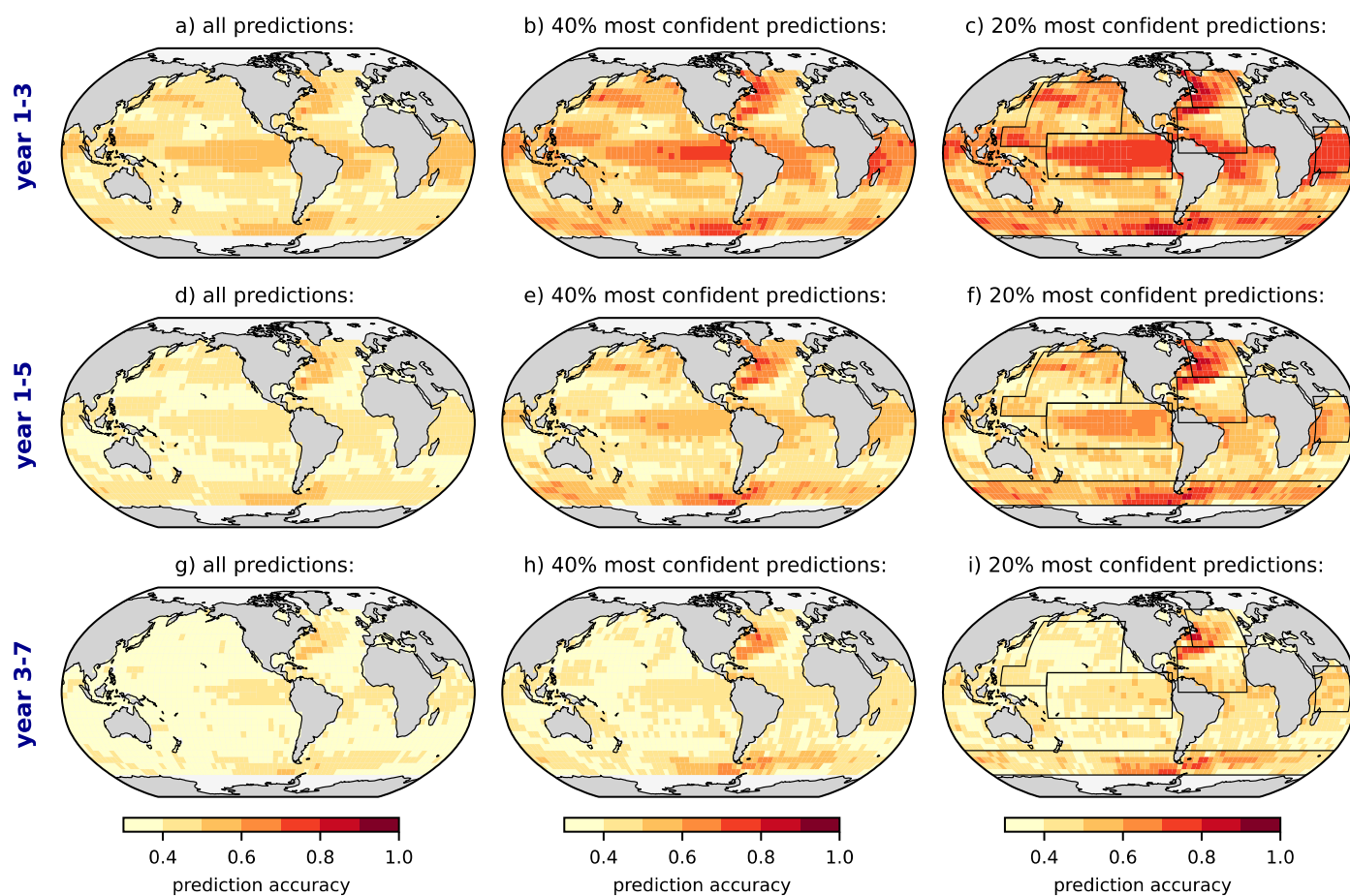


Figure S5. Same as Figure 2, but for GISS-E2-1-G.

Accuracy of CNN trained and tested on MIROC-ES2L simulations

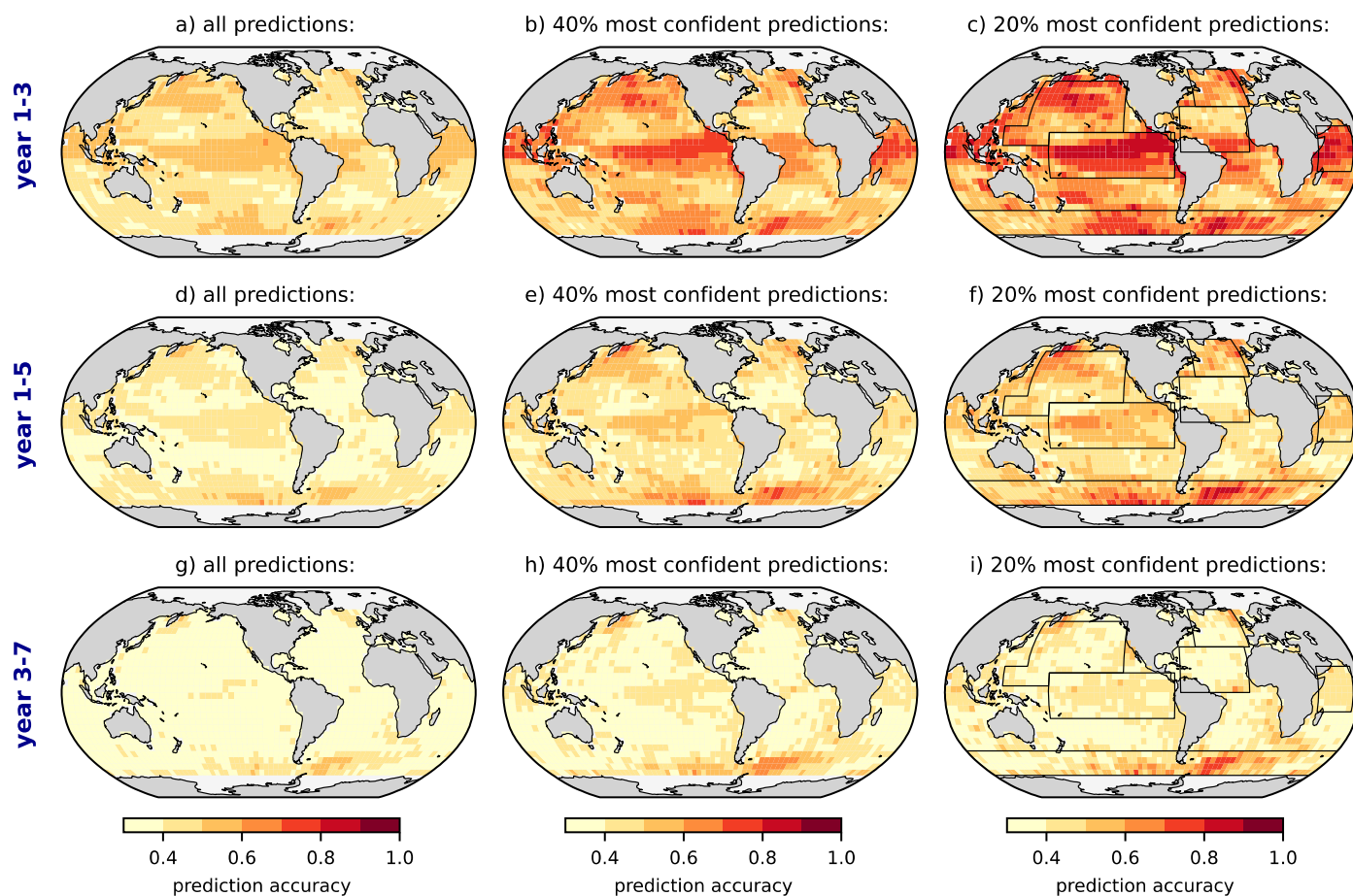


Figure S6. Same as Figure 2, but for MIROC-ES2L.

Accuracy of CNN trained and tested on MIROC6 simulations

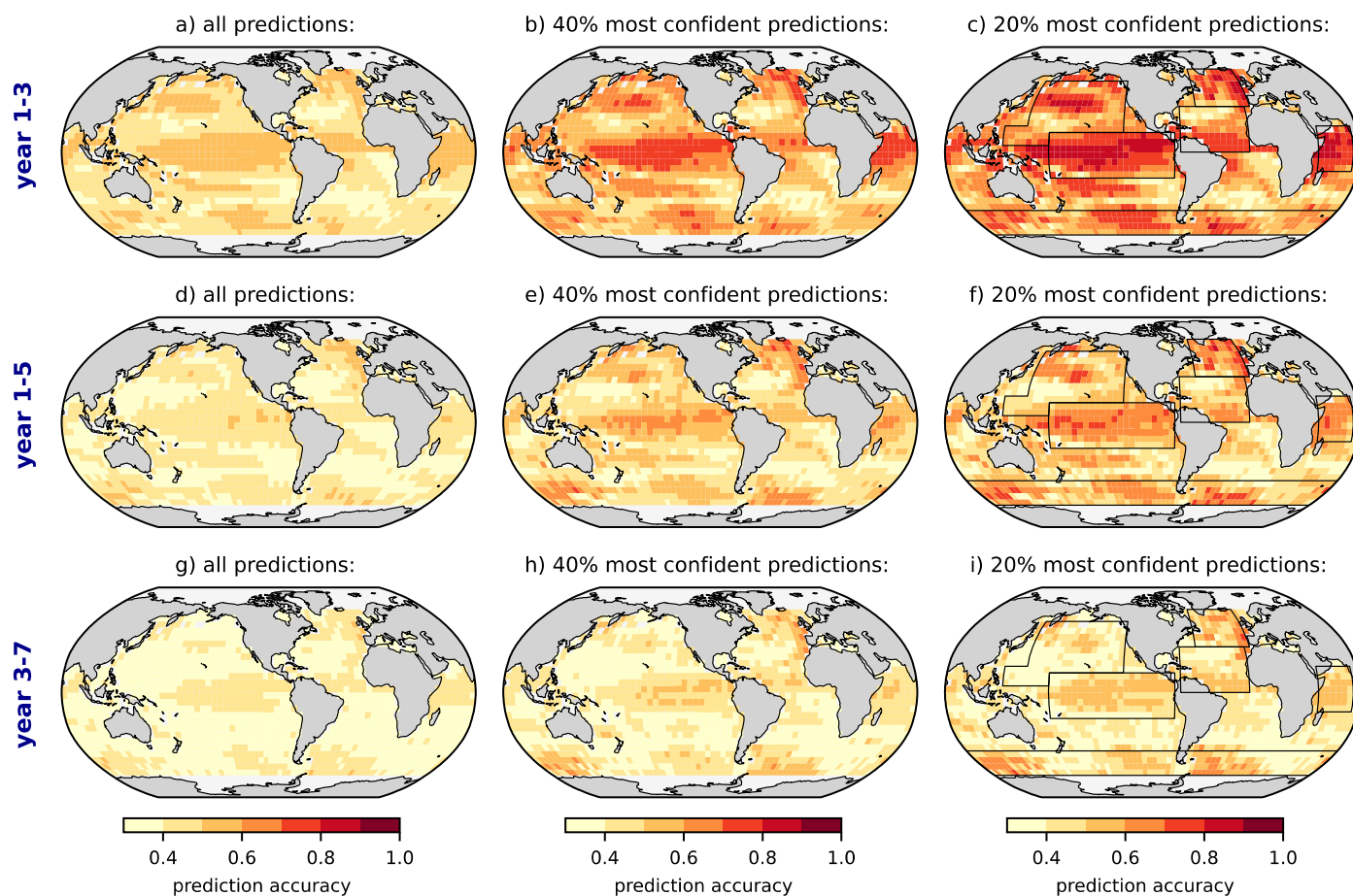


Figure S7. Same as Figure 2, but for MIROC6.

Accuracy of CNN trained and tested on MPI-ESM1-2-LR simulations

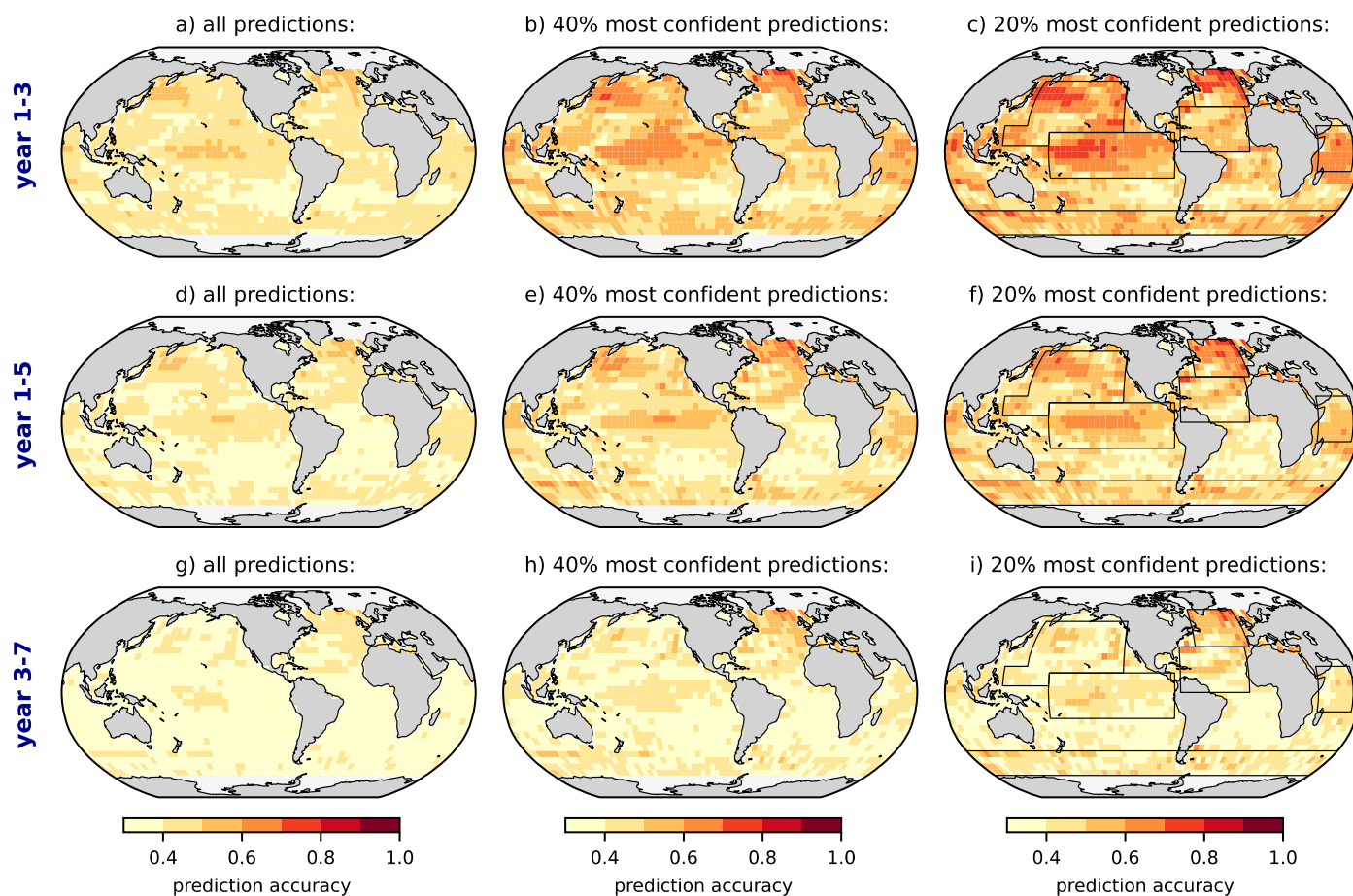


Figure S8. Same as Figure 2, but for MPI-ESM1-2-LR.

Accuracy of CNN trained and tested on NorCPM1 simulations

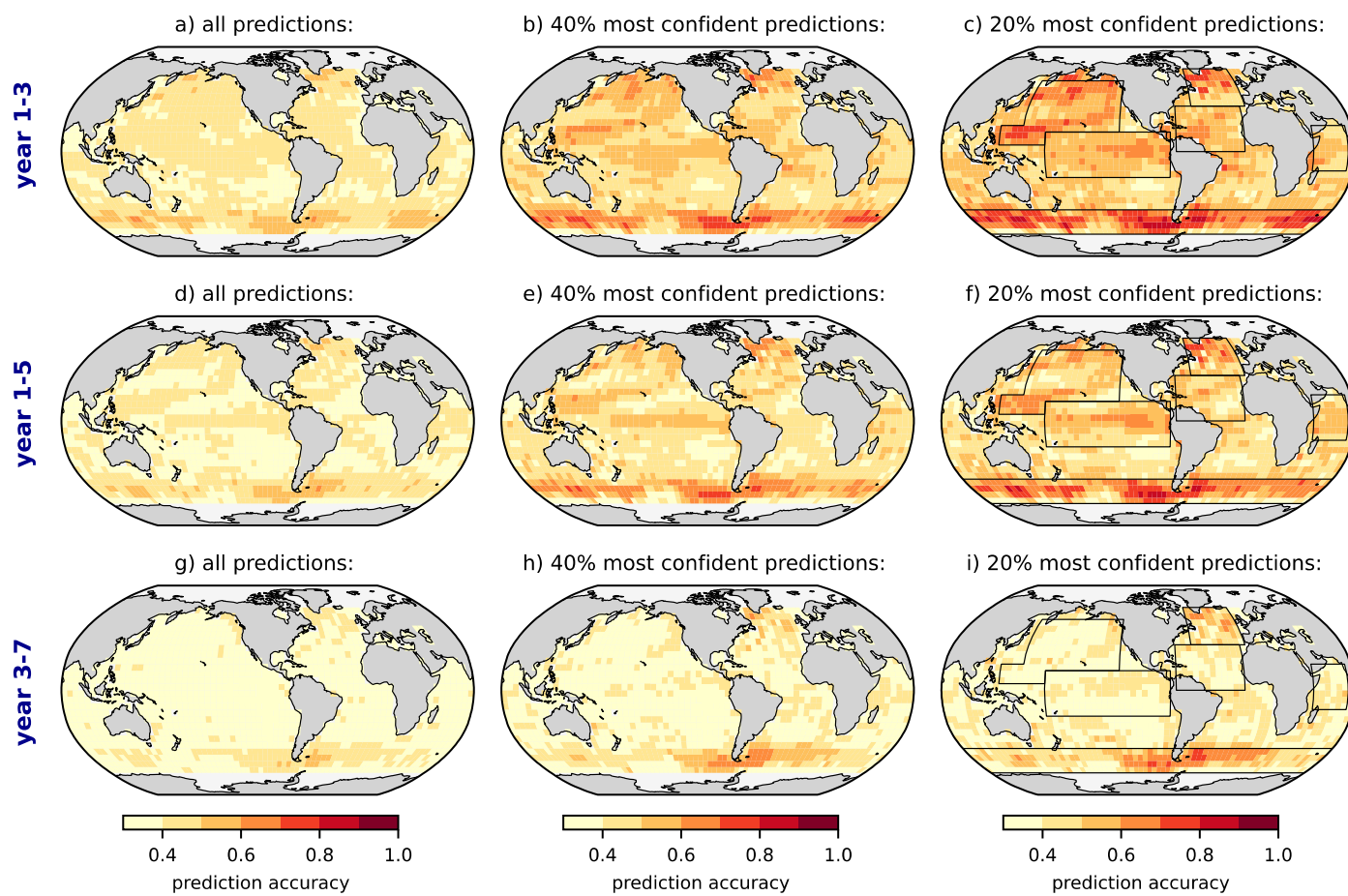


Figure S9. Same as Figure 2, but for NorCPM1.

Accuracy of persistence predictions

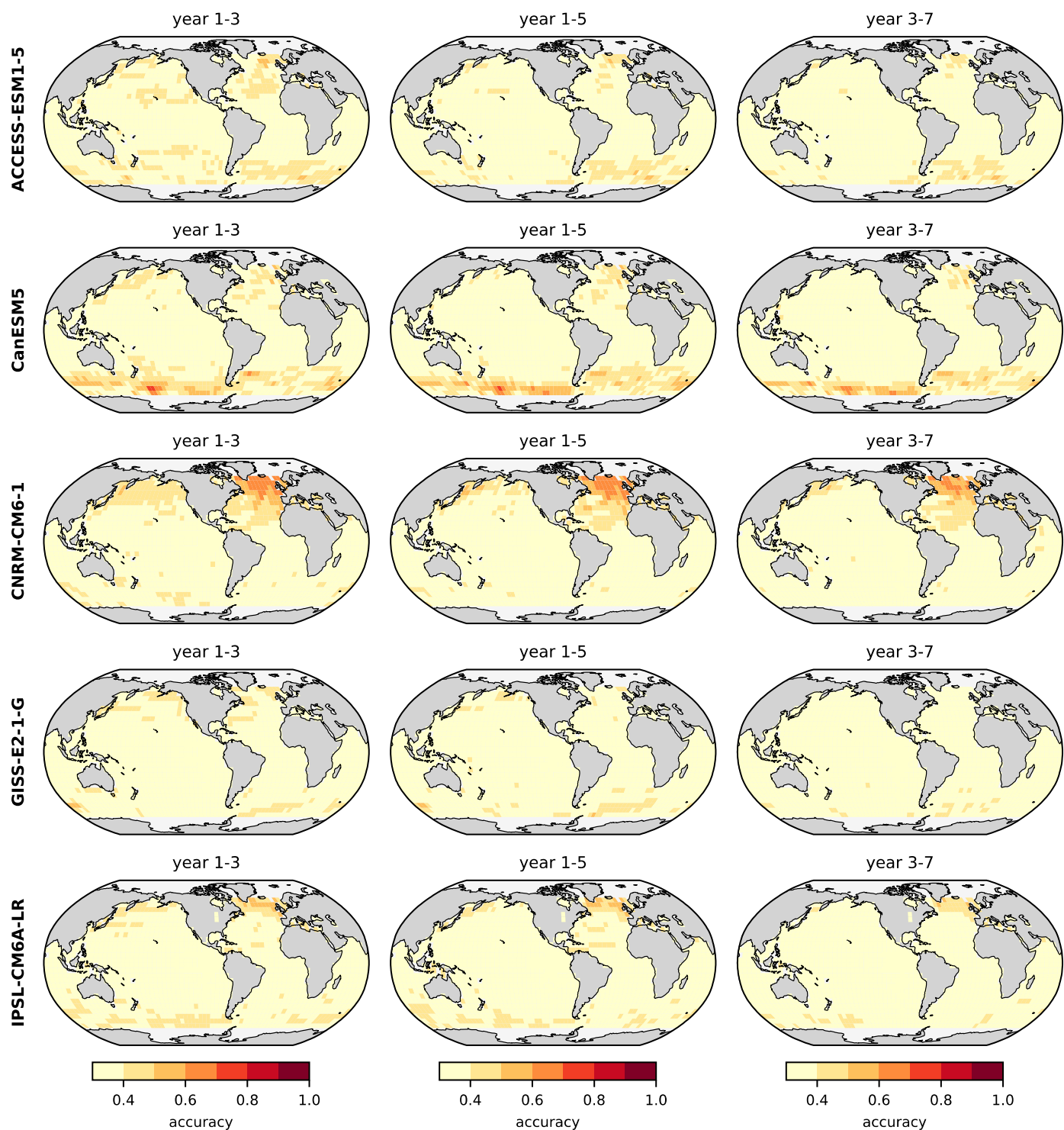


Figure S10. Accuracy of the persistence predictions for the three different lead times for ACCESS-ESM1-5, CanESM5, CNRM-CM6-1, GISS-E2-1-G, and IPSL-CM6A-LR.

Accuracy of persistence predictions

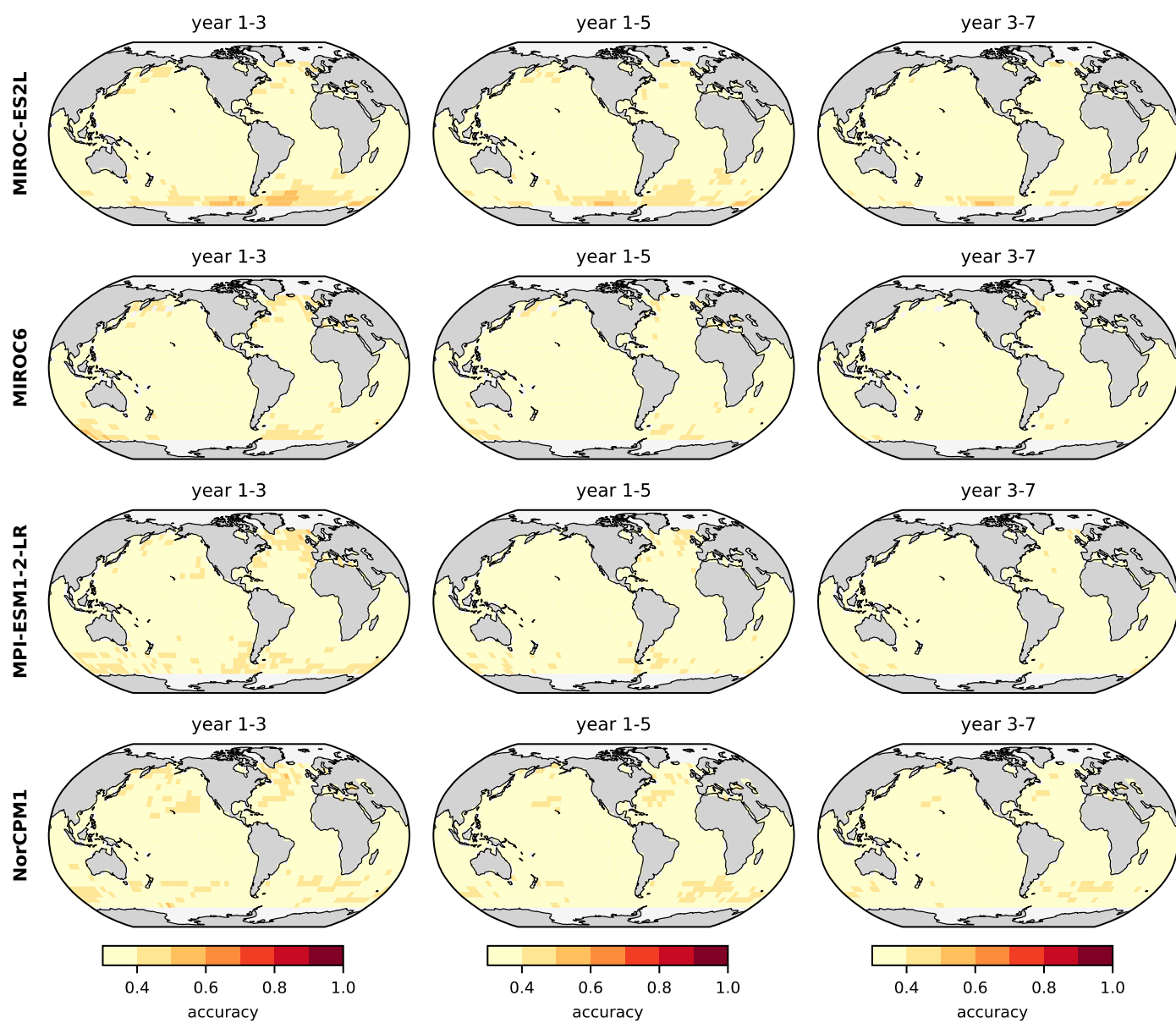


Figure S11. Same as Figure S10, but for MIROC-ES2L, MIROC6, MPI-ESM1-2-LR, NorCPM1.

Windows of Opportunity tested on ERSSTv5 observations

Accuracy of 20% most confident predictions of **year 1-3** sea surface temperature anomaly

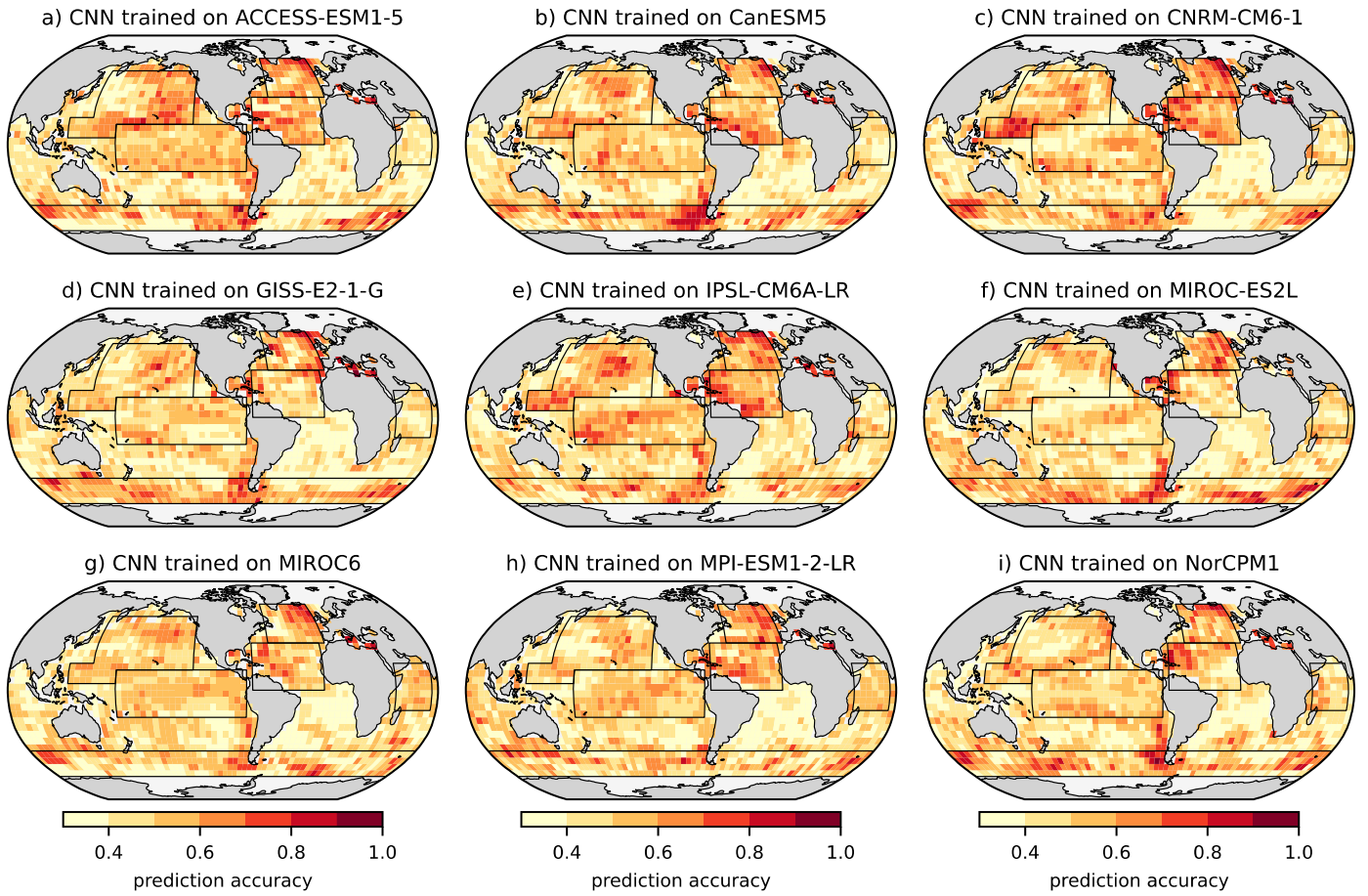


Figure S12. Same as Figure 3, but for year 1-3 predictions.

Windows of Opportunity tested on ERSSTv5 observations

Accuracy of 20% most confident predictions of **year 3-7** sea surface temperature anomaly

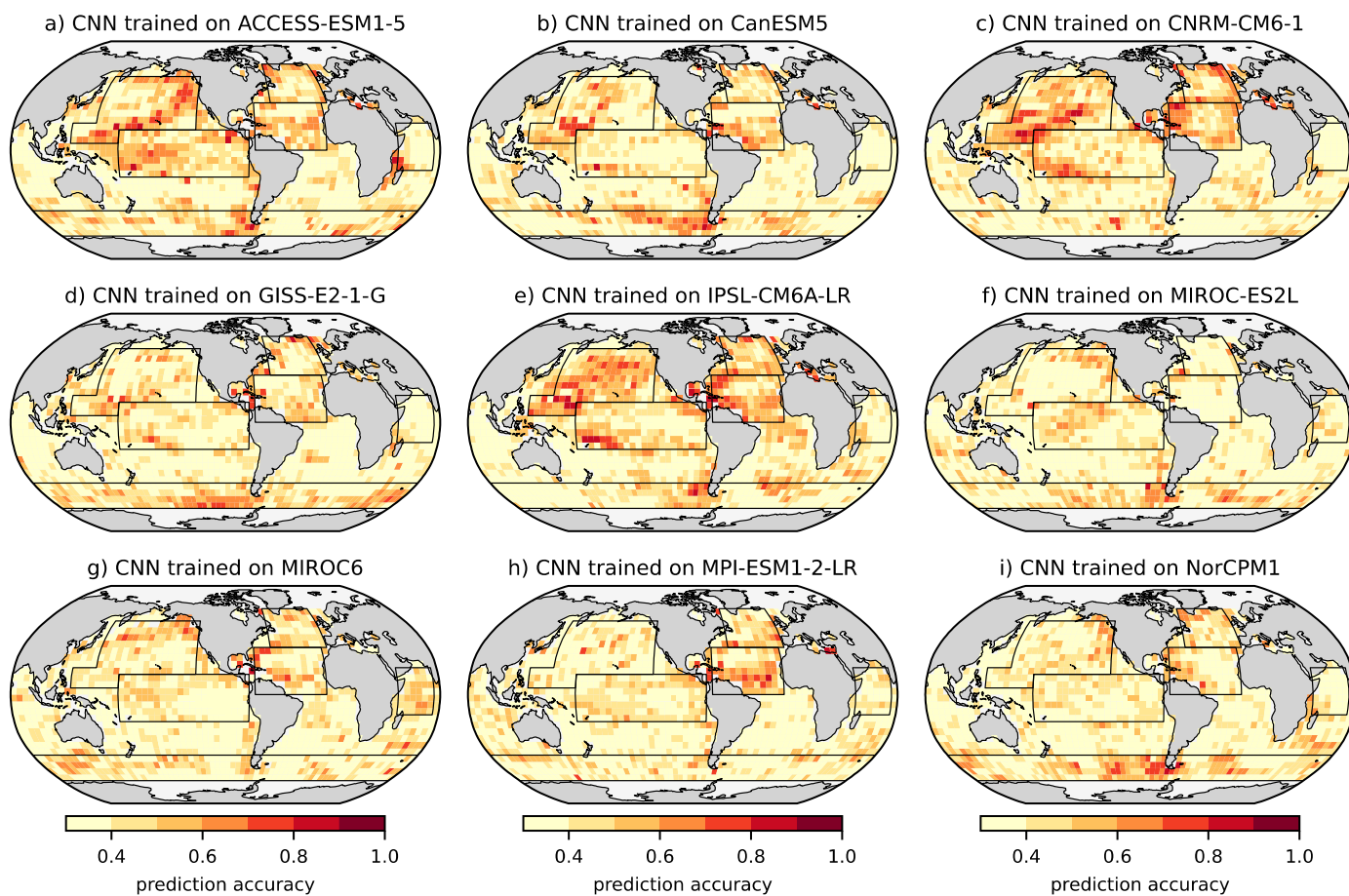


Figure S13. Same as Figure 3, but for year 3-7 predictions.

Accuracy of persistence predictions (ERSSTv5)

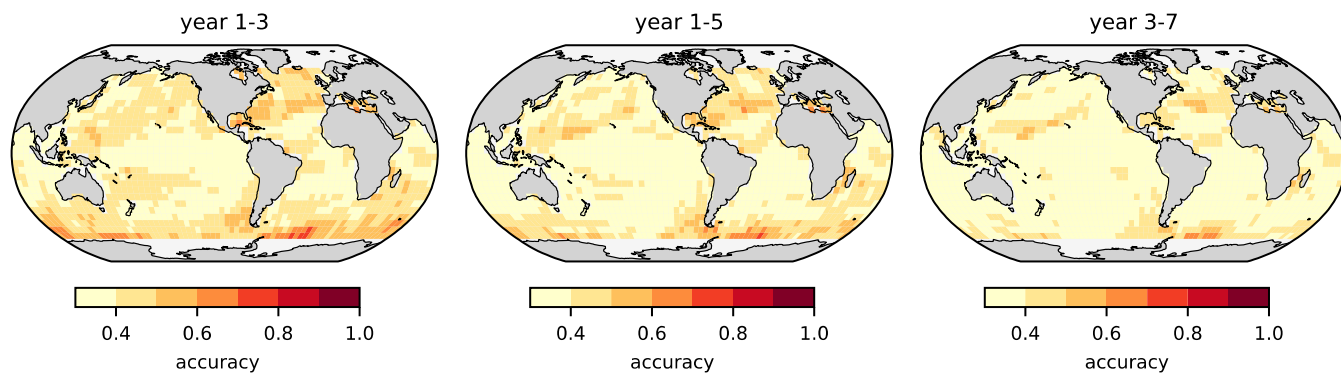


Figure S14. Accuracy of persistence predictions within ERSSTv5 observations for the three different lead times.

Table S1. Included CMIP6 models and simulations

| Model | Training (22 simulations) | Validation (3 simulations) | Testing (5 simulations) |
|---------------|--|-----------------------------------|---|
| ACCESS-ESM1-5 | r4i1p1f1, r5i1p1f1, r6i1p1f1, r7i1p1f1, r8i1p1f1, r9i1p1f1, r10i1p1f1, r11i1p1f1, r12i1p1f1, r13i1p1f1, r15i1p1f1, r16i1p1f1, r17i1p1f1, r19i1p1f1, r20i1p1f1, r22i1p1f1, r23i1p1f1, r24i1p1f1, r25i1p1f1, r26i1p1f1, r27i1p1f1, r30i1p1f1 | r14i1p1f1, r21i1p1f1, r3i1p1f1 | r18i1p1f1, r1i1p1f1, r28i1p1f1, r29i1p1f1, r2i1p1f1 |
| CanESM5 | r10i1p2f1, r11i1p2f1, r12i1p2f1, r13i1p2f1, r15i1p2f1, r16i1p2f1, r17i1p2f1, r19i1p2f1, r20i1p2f1, r22i1p2f1, r23i1p2f1, r24i1p2f1, r25i1p2f1, r26i1p2f1, r27i1p2f1, r30i1p2f1, r4i1p2f1, r5i1p2f1, r6i1p2f1, r7i1p2f1, r8i1p2f1, r9i1p2f1 | r14i1p2f1, r21i1p2f1, r3i1p2f1 | r18i1p2f1, r1i1p2f1, r28i1p2f1, r29i1p2f1, r2i1p2f1 |
| CNRM-CM6-1 | r10i1p1f2, r11i1p1f2, r12i1p1f2, r13i1p1f2, r15i1p1f2, r16i1p1f2, r17i1p1f2, r19i1p1f2, r20i1p1f2, r22i1p1f2, r23i1p1f2, r24i1p1f2, r25i1p1f2, r26i1p1f2, r27i1p1f2, r30i1p1f2, r4i1p1f2, r5i1p1f2, r6i1p1f2, r7i1p1f2, r8i1p1f2, r9i1p1f2 | r14i1p1f2, r21i1p1f2, r3i1p1f2 | r18i1p1f2, r1i1p1f2, r28i1p1f2, r29i1p1f2, r2i1p1f2 |
| GISS-E2-1-G | r10i1p1f1, r102i1p1f1, r10i1p1f1, r10i1p3f1, r1i1p1f2, r1i1p3f1, r1i1p5f1, r2i1p1f2, r2i1p3f1, r3i1p3f1, r3i1p5f1, r4i1p1f1, r4i1p5f1, r5i1p1f1, r5i1p1f2, r5i1p3f1, r6i1p1f1, r6i1p3f1, r7i1p1f1, r8i1p1f1, r8i1p3f1, r9i1p1f1 | r2i1p5f1, r3i1p1f1, r4i1p3f1 | r1i1p1f1, r2i1p1f1, r3i1p1f2, r4i1p1f2, r9i1p3f1 |
| IPSL-CM6A-LR | r10i1p1f1, r11i1p1f1, r12i1p1f1, r13i1p1f1, r15i1p1f1, r16i1p1f1, r17i1p1f1, r19i1p1f1, r20i1p1f1, r22i1p1f1, r23i1p1f1, r24i1p1f1, r25i1p1f1, r26i1p1f1, r27i1p1f1, r30i1p1f1, r4i1p1f1, r5i1p1f1, r6i1p1f1, r7i1p1f1, r8i1p1f1, r9i1p1f1 | r14i1p1f1, r21i1p1f1, r3i1p1f1 | r18i1p1f1, r1i1p1f1, r28i1p1f1, r29i1p1f1, r2i1p1f1 |
| MIROC-ES2L | r10i1p1f2, r11i1p1f2, r12i1p1f2, r13i1p1f2, r15i1p1f2, r16i1p1f2, r17i1p1f2, r19i1p1f2, r20i1p1f2, r22i1p1f2, r23i1p1f2, r24i1p1f2, r25i1p1f2, r26i1p1f2, r27i1p1f2, r30i1p1f2, r4i1p1f2, r5i1p1f2, r6i1p1f2, r7i1p1f2, r8i1p1f2, r9i1p1f2 | r14i1p1f2, r21i1p1f2, r3i1p1f2 | r18i1p1f2, r1i1p1f2, r28i1p1f2, r29i1p1f2, r2i1p1f2 |
| MIROC6 | r10i1p1f1, r11i1p1f1, r12i1p1f1, r13i1p1f1, r15i1p1f1, r16i1p1f1, r17i1p1f1, r19i1p1f1, r20i1p1f1, r22i1p1f1, r23i1p1f1, r24i1p1f1, r25i1p1f1, r26i1p1f1, r27i1p1f1, r30i1p1f1, r4i1p1f1, r5i1p1f1, r6i1p1f1, r7i1p1f1, r8i1p1f1, r9i1p1f1 | r14i1p1f1, r21i1p1f1, r3i1p1f1 | r18i1p1f1, r1i1p1f1, r28i1p1f1, r29i1p1f1, r2i1p1f1 |
| MPI-ESM1-2-LR | r10i1p1f1, r11i1p1f1, r12i1p1f1, r13i1p1f1, r15i1p1f1, r16i1p1f1, r17i1p1f1, r19i1p1f1, r20i1p1f1, r22i1p1f1, r23i1p1f1, r24i1p1f1, r25i1p1f1, r26i1p1f1, r27i1p1f1, r30i1p1f1, r4i1p1f1, r5i1p1f1, r6i1p1f1, r7i1p1f1, r8i1p1f1, r9i1p1f1 | r14i1p1f1, r21i1p1f1, r3i1p1f1 | r18i1p1f1, r1i1p1f1, r28i1p1f1, r29i1p1f1, r2i1p1f1 |
| NorCPM1 | r10i1p1f1, r11i1p1f1, r12i1p1f1, r13i1p1f1, r15i1p1f1, r16i1p1f1, r17i1p1f1, r19i1p1f1, r20i1p1f1, r22i1p1f1, r23i1p1f1, r24i1p1f1, r25i1p1f1, r26i1p1f1, r27i1p1f1, r30i1p1f1, r4i1p1f1, r5i1p1f1, r6i1p1f1, r7i1p1f1, r8i1p1f1, r9i1p1f1 | r14i1p1f1, r21i1p1f1, r3i1p1f1 | r18i1p1f1, r1i1p1f1, r28i1p1f1, r29i1p1f1, r2i1p1f1 |