

**A New Four-Component L\*-dependent Model for Radial Diffusion based on Solar Wind and Magnetospheric Drivers of ULF Waves**

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**Introduction**

This file contains 3 tables and 3 Figures.

Table S1 lists the satellites and instruments used in this study. Table S2 contains the fit and normalization coefficients for the linear regression  $D_{LL}^B$  and  $D_{LL}^E$ s models following the form of equations (1) and (2) in the manuscript (and below).

$$\log_{10}(D_{LL}) = c + a_1 L^* + a_2 \text{Sym-H} + a_3 B_z + a_4 V + a_5 P_{dyn} \quad (1)$$

$$D_{LL} = 10^{c+a_1 L^*+a_2 \text{SymH}+a_3 B_z+a_4 V+a_5 P_{dyn}} \quad (2)$$

Figures S3 and S4 show the distribution of model residuals as a function of independent variable,  $L^*$ ,  $\text{Sym-H}$ ,  $B_z$ ,  $V$ , and  $P_{dyn}$ , during geomagnetic storms and during geomagnetically quiet intervals. The residuals are calculated as the difference between the log10 of the modeled  $D_{LL}$ s and the satellite-derived  $D_{LL}$ s.

Figure S5 and Table S6 show the analysis used to remove the bias from the model residuals as a function of  $L^*$ . Figure S5 shows the Gaussian fits to the residuals and Table S6 contains the fit coefficients  $A_0$ ,  $A_1$ , and  $A_2$  as a function of  $L^*$ . The coefficients allow researchers to remove the bias in the modeled  $D_{LL}^B$  and  $D_{LL}^E$ s in steps of 0.1 as a function of  $L^*$ . The Gaussian fit is of the form shown in equation (3).

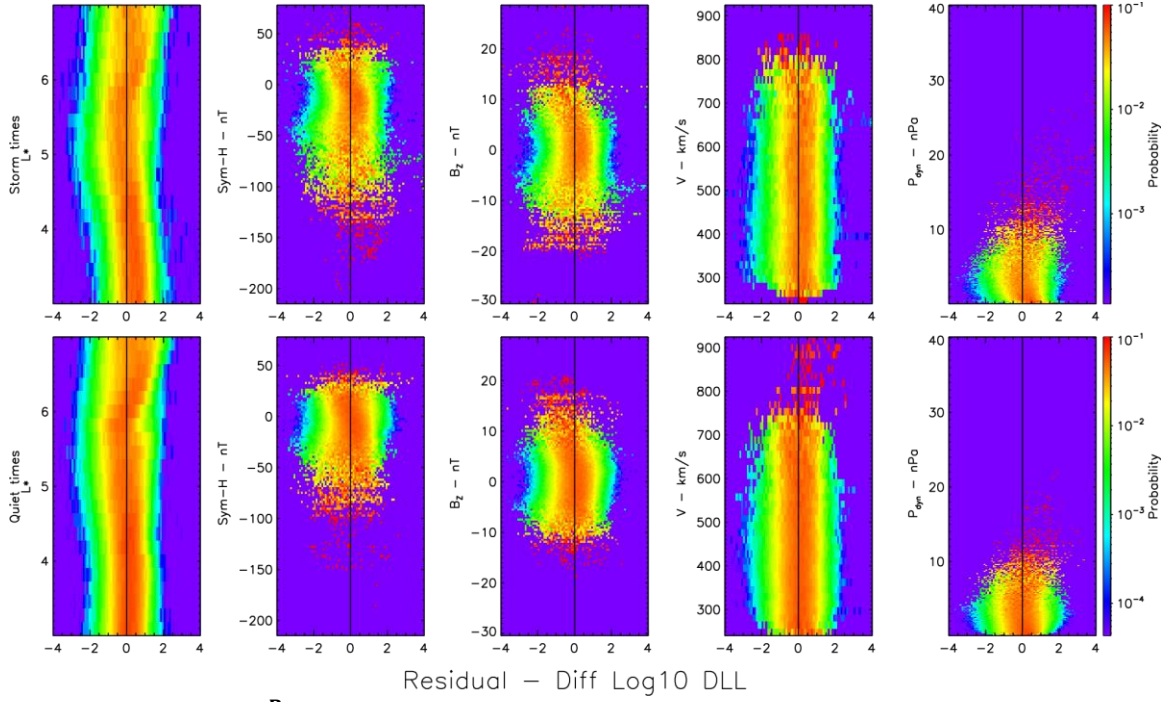
$$f(r) = A_0 e^{\left(\frac{r-A_1}{A_2}\right)^2} \quad (3)$$

**Table S1.** List of satellites and instruments used to derive magnetic and electric ULF PSD.

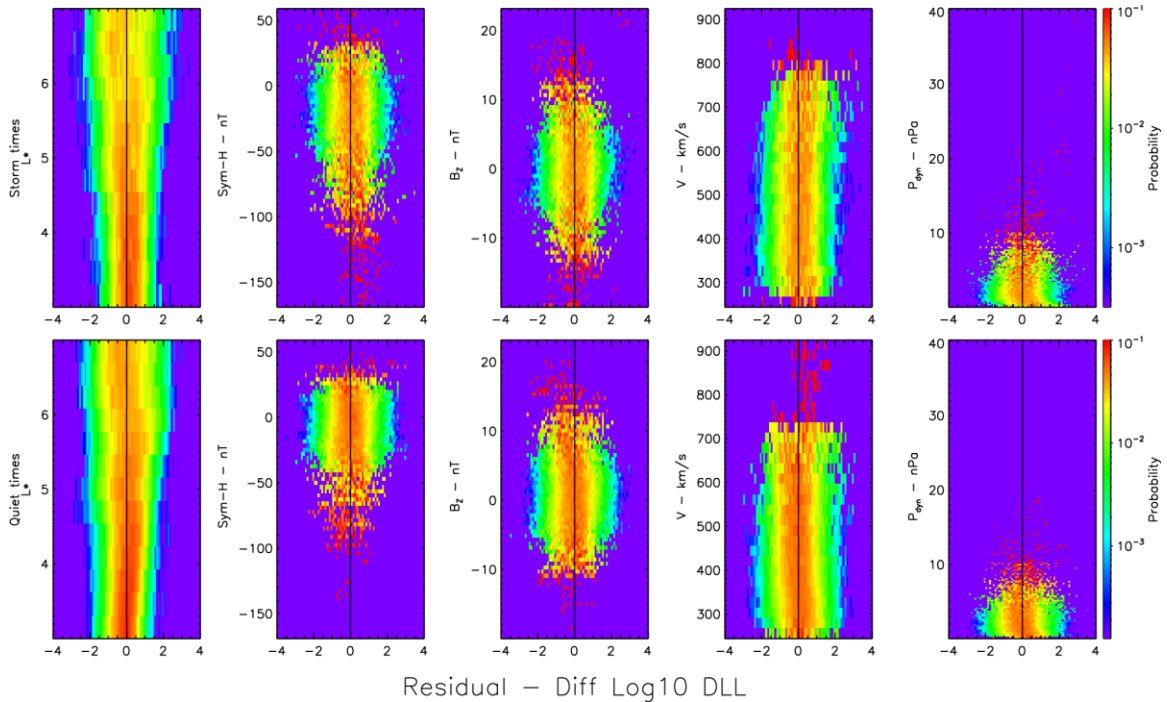
<i>Mission</i>	<i>Probe</i>	<i>Time Span</i>	<i>Instrument</i>	<i>Observation</i>
<i>GOES</i>	15 (West)	2012-2020	magnetometer (MAG)	<b>B</b>
<i>THEMIS</i>	A, D, E	2013-2020	fluxgate magnetometer (FGM)	<b>B</b>
			electric field instrument (EFI)	<b>E</b>
<i>Van Allen Probes</i>	A, B	2012-2019	Electric and magnetic field instrument suite and integrated science (EMFISIS)	<b>B</b>
			Electric field and waves (EFW)	<b>E</b>

**Table S2.** Fit and normalization coefficients for the  $D_{LL}$  models.

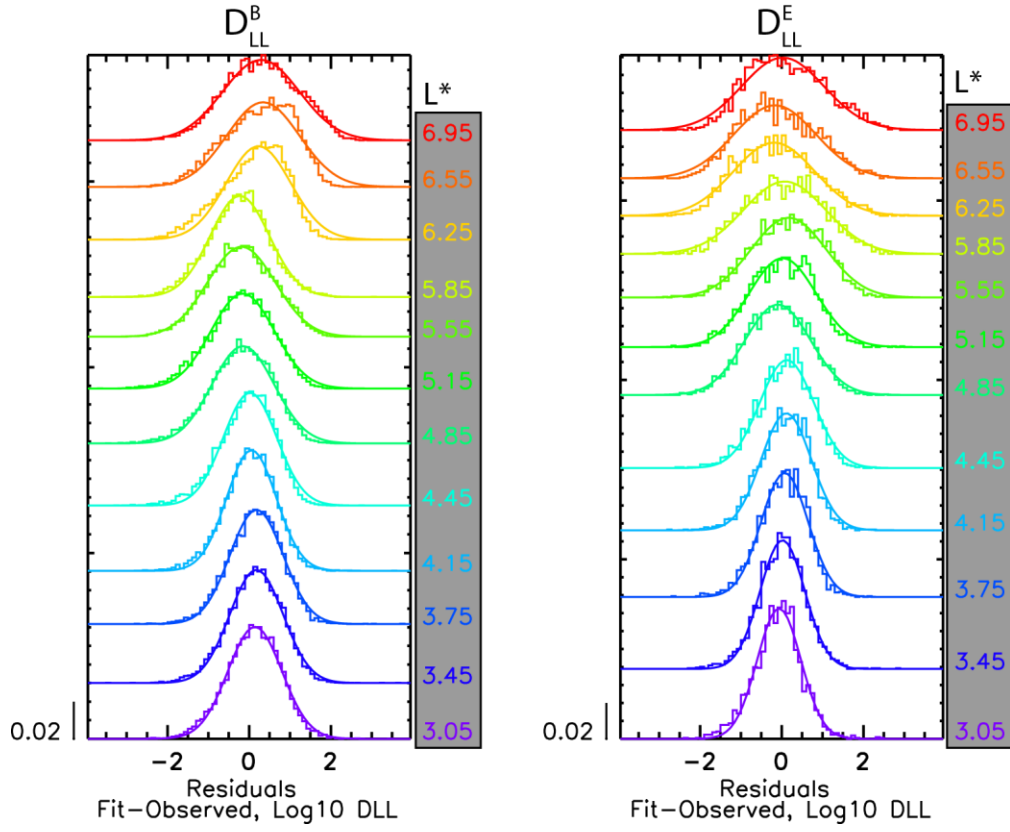
	<b>Independent Variable</b>	<b>Fitting Coefficient</b>	<b>Normalization Min</b>	<b>Normalization Max</b>	<b>Unit</b>
$D_{LL}^B$	<b><math>L^*</math>, <math>a_1</math></b>	4.2384115	3.00001	6.99997	-
	<b>Sym-H, <math>a_2</math></b>	-6.0111539	-215.000	78.	nT
	<b>Bz, <math>a_3</math></b>	-2.7546722	-30.4600	28.2700	nT
	<b>V, <math>a_4</math></b>	1.3773411	239.800	924.400	km/s
	<b>Pdyn, <math>a_5</math></b>	8.7776065	0.0500000	40.1100	nPa
	<b>Constant, <math>c</math></b>	-0.33823768	-	-	-
$D_{LL}^E$	<b><math>L^*</math>, <math>a_1</math></b>	4.6635730	3.00009	6.99997	-
	<b>Sym-H, <math>a_2</math></b>	-3.2927855	-169.000	59.0000	nT
	<b>Bz, <math>a_3</math></b>	-1.5571645	-19.9500	23.1500	nT
	<b>V, <math>a_4</math></b>	1.7016774	244.100	924.400	km/s
	<b>Pdyn, <math>a_5</math></b>	4.9563413	0.0700000	40.1100	nPa
	<b>Constant, <math>c</math></b>	-1.9675309	-	-	-



**Figure S3.** PDFs of  $D_{LL}^B$  model residuals calculated from the combined train and test data sets for each of the independent variables during geomagnetic storms and geomagnetically quiet times. The quiet times are defined as those times that are not part of geomagnetic storms.



**Figure S4.** PDFs of  $D_{LL}^E$  model residuals calculated from the combined train and test data sets for each of the independent variables during geomagnetic storms and geomagnetically quiet times. The quiet times are defined as those times that are not part of geomagnetic storms.



**Figure S5.** Example of fitting a Gaussian to the PDF of the residuals of the  $D_{LL}^B$  and  $D_{LL}^E$  models (left and right) as a function of  $L^*$ . Each color is a different  $L^*$ , as shown in the legends to the right of each panel. The PDFs are shown as histograms and the Gaussian fits as solid lines. The Gaussian fits provide a simple means to shift the residuals and remove the bias from the modelled  $D_{LL}$ s.

**Table S6.** Fit coefficients for the Gaussians as a function of  $L^*$ . The Gaussian fits are of the form shown in equation 3 of the manuscript and here. The fits are used to remove the bias in the modeled  $D_{LL}$ s. The Gaussian fits can also be used to generate an ensemble of  $D_{LL}$ s to run perturbed input ensemble simulations of radiation belt dynamics.

$L^*$		DLLB			DLLE			$L^*$		DLLB			DLLE		
Min	Max	A0	A1	A2	A0	A1	A2	Min	Max	A0	A1	A2	A0	A1	A2
3.0	3.1	0.060	0.141	0.660	0.073	-0.065	0.536	5.0	5.1	0.051	-0.165	0.778	0.051	-0.048	0.788
3.1	3.2	0.062	0.174	0.640	0.071	-0.038	0.555	5.1	5.2	0.051	-0.157	0.778	0.050	0.022	0.818
3.2	3.3	0.062	0.179	0.640	0.072	-0.019	0.545	5.2	5.3	0.050	-0.165	0.805	0.050	0.059	0.809
3.3	3.4	0.062	0.174	0.644	0.072	-0.019	0.551	5.3	5.4	0.048	-0.161	0.842	0.048	0.128	0.837
3.4	3.5	0.061	0.179	0.654	0.072	0.019	0.548	5.4	5.5	0.048	-0.149	0.842	0.046	0.196	0.878
3.5	3.6	0.061	0.186	0.650	0.070	0.020	0.569	5.5	5.6	0.048	-0.19	0.829	0.044	0.170	0.916
3.6	3.7	0.061	0.189	0.652	0.070	0.053	0.562	5.6	5.7	0.050	-0.272	0.795	0.042	0.159	0.966
3.7	3.8	0.061	0.181	0.651	0.069	0.073	0.576	5.7	5.8	0.053	-0.291	0.751	0.041	0.100	0.988
3.8	3.9	0.062	0.18	0.647	0.068	0.042	0.589	5.8	5.9	0.054	-0.228	0.724	0.040	0.072	1.011
3.9	4.0	0.061	0.163	0.649	0.065	0.073	0.612	5.9	6.0	0.055	-0.057	0.714	0.041	-0.042	0.998
4.0	4.1	0.062	0.108	0.648	0.065	0.097	0.613	6.0	6.1	0.053	0.063	0.741	0.040	-0.122	1.009
4.1	4.2	0.065	0.058	0.610	0.065	0.111	0.613	6.1	6.2	0.052	0.148	0.770	0.041	-0.162	0.969
4.2	4.3	0.065	0.049	0.601	0.062	0.128	0.642	6.2	6.3	0.050	0.229	0.791	0.041	-0.186	0.997
4.3	4.4	0.063	0.056	0.620	0.060	0.125	0.675	6.3	6.4	0.048	0.257	0.842	0.042	-0.175	0.953
4.4	4.5	0.061	0.022	0.653	0.060	0.125	0.662	6.4	6.5	0.046	0.325	0.875	0.040	-0.177	1.005
4.5	4.6	0.058	0.009	0.688	0.057	0.097	0.697	6.5	6.6	0.046	0.341	0.891	0.041	-0.166	1.00
4.6	4.7	0.054	-0.047	0.736	0.053	0.000	0.761	6.6	6.7	0.044	0.339	0.930	0.040	-0.138	1.012
4.7	4.8	0.054	-0.092	0.742	0.052	-0.071	0.775	6.7	6.8	0.043	0.332	0.956	0.041	-0.105	0.993
4.8	4.9	0.052	-0.149	0.763	0.050	-0.095	0.803	6.8	6.9	0.043	0.32	0.949	0.041	-0.056	0.983
4.9	5.0	0.052	-0.145	0.769	0.051	-0.050	0.793	6.9	7.0	0.043	0.292	0.938	0.040	0.026	1.005