

Fricke, Katharina^{a,c}; Baschek, Björn^{a,c}; Asgari, Maryam^b; Bongartz, Jens^{b,c}; Burkart, Andreas^d; Dzunic, Filip^b; Heuner, Maike^f; Jenal, Alexander^{b,f}; Kneer, Caspar^b; Mölter, Tina^b; Nätke, Paul; Quick, Ina^g; Rock, Gilles^e; Rommel, Edvinos^f; Schröder, Uwe^f; Weber, Immanuel^b; Wick, Svenja^g

^a German Federal Institute of Hydrology, Department Geodesy and Remote Sensing, Koblenz, Germany; ^b Geocoptix, Trier, Germany; ^c Geocoptix, Trier, Germany; ^d German Federal Institute of Hydrology, Department Vegetation Studies, Landscape Management, Koblenz, Germany; ^e German Federal Institute of Hydrology, Department Fluvial Morphology, Sediment Dynamics and Management, Koblenz, Germany; ^f German Federal Institute of Hydrology, Department Geodesy and Remote Sensing, Koblenz, Germany; ^g Geocoptix, Trier, Germany

Overview

Up-to-date information about vegetation types and hydromorphological structures and features are essential for the management of waterways. They are e.g. used for the monitoring and reporting of riparian statuses and their changes e.g. after river restoration and consequently, numerous man-days are spent on field surveys. To allow for an effective survey of vegetation and hydromorphology in large or even inaccessible areas a data acquisition and processing workflow is being developed complementing in-situ methods with remote sensing techniques.

Aerial surveys by unmanned aerial systems (UAS) and a gyrocopter are combined with ground measurements of hyperspectral reflectance signatures as well as with field mapping of vegetation types and hydromorphological structures and features. The remote sensing data is classified with an object based image analysis and classification algorithm. The mobile and at three sites continuous measurements of hyperspectral field data and the typical field surveys provide data for calibration. Contrary to other approaches that focus on what can be detected and classified with certain sensor systems and datasets, the project addresses equally the user needs to obtain certain classes for monitoring and reporting.

The intended results are (i) data acquisition, correction and classification workflow combining remote sensing and field data, identification and change detection (ii) of important vegetation and biotope types and (iii) hydromorphological structures and substrate as well as indicators necessary for the evaluation of the hydromorphological quality. The preliminary results to be presented include datasets from UAS, gyrocopter, and field surveys, an outline of processing workflow and classification algorithm based on Python scripts and eCognition software and first vegetation and hydromorphological classification results from spring and summer datasets.

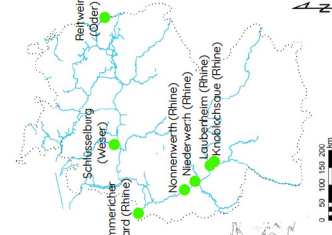


Hyperspectral reference



Project areas

- 5 areas for method development;
- 3-4 surveys per year
- 2 areas for application/validation:
- 1-2 surveys per year
- Selection criteria
 - heterogeneity with regard to hydromorphology
 - near-natural state
 - recent restoration measures
 - > dynamics, changes

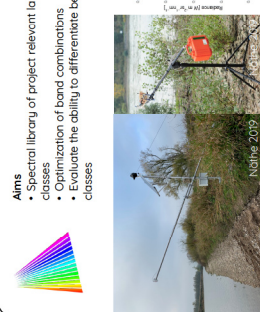


Unmanned aerial systems



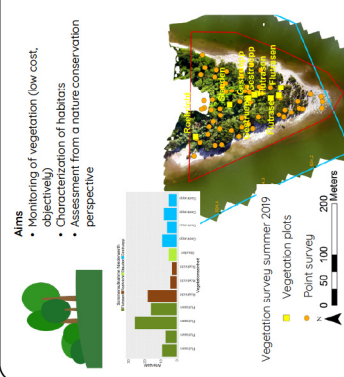
Data acquisition with MAVLink Intel Sius Pro with the Fujik-MI and RTX (c-HR RGB) and DJI Phantom 4 Pro with the Micasense RedEdge M (> multispectral imagery) (right).

Field spectroscopy

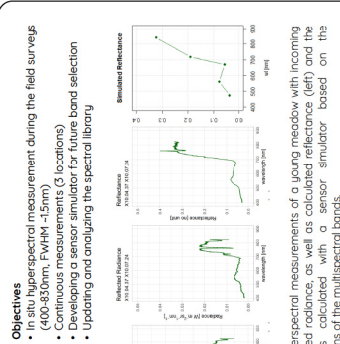
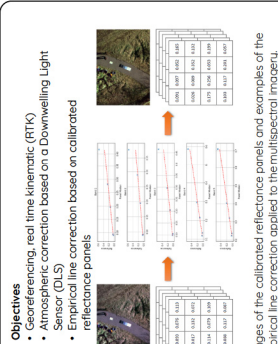


Permanent: hyperspectral reflectance measurements over water, substrate or pioneer species (depending on the season) in Emmerich (left) and example of mobile measurements during the field survey (right).

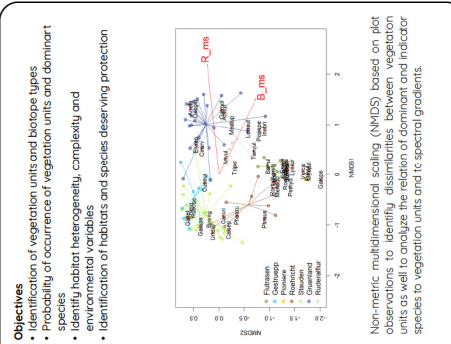
Vegetation



Example of the vegetation survey in the project area Niederwerth. Points represent punctual identification of species and their vegetation unit to train and validate remote sensing imagery. Squares represent a vegetation survey within 10 m plots with all species within and their percentage coverage were documented for species based analysis of the imagery.



Hydromorphology

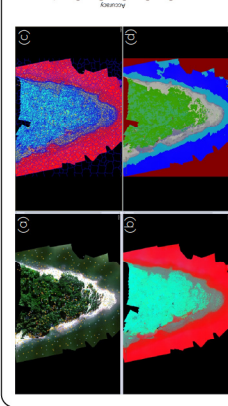


Gyrocopter



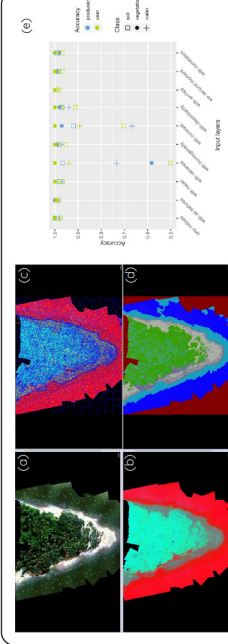
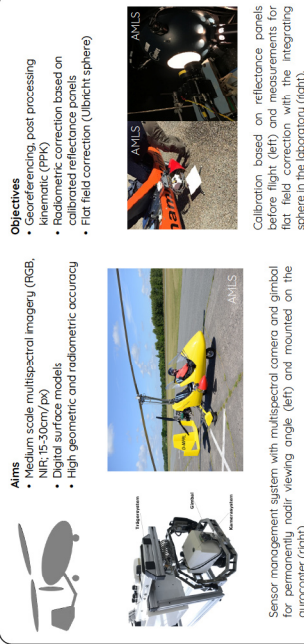
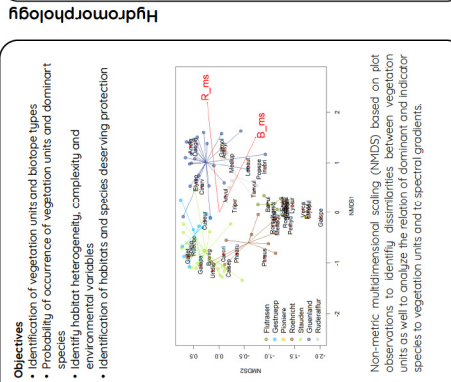
Sensor management system with multispectral camera and gimbal for permanently nadir viewing angle (left) and mounted on the gyrocopter (right).

OBIA & classification



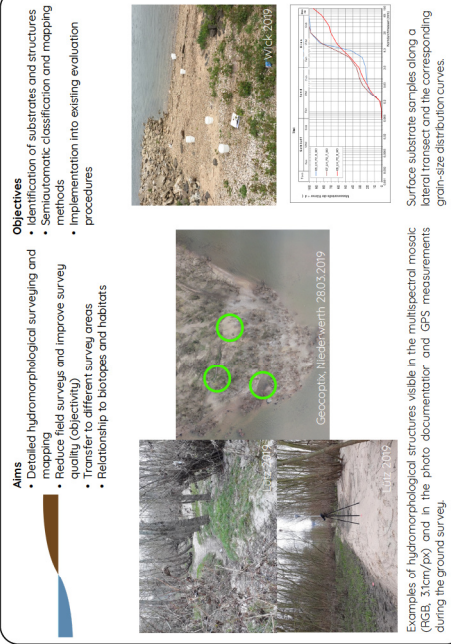
Example of a multiresolution segmentation and basic classification with the support vector machine classifier of water, vegetation and soil surface in the project area Niederwerth (a). The input layers so far consist of band indices (NDVI, NDRE, NDWI, SAVI) (b) and surface texture parameters, that are divided into object with a multiresolution segmentation algorithm (c) and then classified based on the available ground survey data (d). Several classification algorithms and input layer combinations (e support vector machine classifier) are being tested.

Hydromorphology



Example of a multiresolution segmentation and basic classification with the support vector machine classifier of water, vegetation and soil surface in the project area Niederwerth (a). The input layers so far consist of band indices (NDVI, NDRE, NDWI, SAVI) (b) and surface texture parameters, that are divided into object with a multiresolution segmentation algorithm (c) and then classified based on the available ground survey data (d). Several classification algorithms and input layer combinations (e support vector machine classifier) are being tested.

Hydromorphology



The joint research project "mDRONES4rivers" funded by the German Federal Ministry of Transport and Digital Infrastructure (09Z054A-D), <https://www.bmv.de/SharedDocs/DE/Artikel/DG/mund-projekte/mundones4rivers.html>