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Frequency Dependent Mantle Viscoelasticity via the Complex Viscosity: cases from Antarctica and Western North America

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Key Points:

- Differing estimates of viscosity and plate thicknesses are observed from various loading processes across Antarctica and North America
- Using new theory and laboratory laws, frequency dependent viscosity and plate thickness are predicted for Antarctic and North America
- Our results indicate that these predictions of viscosity and plate thickness can significantly contribute to the observed discrepancies

23 **Abstract**

24
25 Studies of glacial isostatic adjustment (GIA) often use paleoshorelines and present-day
26 deformation to constrain the viscosity of the mantle and the thickness of the lithosphere.
27 However, different studies focused on similar locations have resulted in different estimates of
28 these physical properties even when considering the same model of viscoelastic deformation.
29 We argue that these different estimates infer apparent viscosities and apparent lithospheric
30 thicknesses, dependent on the timescale of deformation. We use recently derived relationships
31 between these frequency dependent apparent quantities and the underlying thermodynamic
32 conditions to produce predictions of mantle viscosity and lithospheric thickness across a broad
33 spectrum of geophysical timescales for three locations (Western North America, Amundsen Sea,
34 and the Antarctic Peninsula). Our predictions require the self-consistent consideration of elastic,
35 viscous, and transient deformation and also include non-linear steady state deformation, which
36 have been determined by several laboratories. We demonstrate that these frequency dependent
37 predictions of apparent lithospheric thickness and viscosity display a significant range and that
38 they align to first order with estimates from GIA studies on different timescales. Looking
39 forward, we suggest that observationally based studies could move towards a framework of
40 determining the frequency trend in apparent quantities – rather than single, frequency
41 independent values of viscosity – to gain deeper insight into the rheological behavior of Earth
42 materials.

44 **1 Introduction**

45 The growth and decay of ice sheets over the Pleistocene represent large variations in Earth's
46 climate system and induces significant deformation of Earth's solid surface and subsurface. This
47 deformation (including associated changes to Earth's gravity field and rotation), in response to
48 the redistribution of ice and ocean mass, is known as 'glacial isostatic adjustment' (GIA). Areas
49 that were formerly covered by or close to major ice sheets during the last glacial period, such as
50 North America and Antarctica, continue to experience the highest rates of GIA-related
51 deformation, even though ice has retreated partially or entirely (e.g., Sella et al., 2007). Pertinent
52 to understanding this solid Earth deformation (and, as a consequence, related climatological
53 feedbacks) is knowledge of the subsurface viscoelastic structure.

54
55 The variation of GIA responses to the wide variety of mass perturbations is well studied (Nield et
56 al., 2014; Samrat et al., 2020; Barletta et al., 2018, Ivins et al., 2011; Creveling et al., 2017;
57 Wolstencroft et al., 2015) and analyses are often cast in terms of two controlling Earth
58 parameters: the asthenospheric viscosity (η_{AST}) and the thickness of the lithosphere (z_{LAB}). Fig.
59 1 displays estimates of these two parameters from a selection of regionally overlapping

60 geophysical studies that observed GIA responses to rapid ice sheet collapses (Barletta et al.,
 61 2018), unloading of ancient lakes (Austermann et al., 2020), glacial-interglacial scale melting
 62 (Creveling et al., 2017), and postseismic relaxation (Pollitz et al., 2000). Figs 1(a,b) reveal
 63 seemingly perplexing inconsistencies between the inferred values for these parameters even
 64 within similar study regions (see Fig. 1(c,d) for general locations, where “W-NA”, “W-ANT”,
 65 and “ANT-P” refer to Western North America, Western Antarctica, and Antarctic Peninsula,
 66 respectively). Indeed, lateral variations in viscoelastic properties are expected as a consequence
 67 of longterm convection. Within similar locations, however, viscosity estimates from different
 68 kinds of measurements can still give rise to very different values. This apparent discrepancy can
 69 arise from two main sources: (i) differences in how the process samples interior structure; and
 70 (ii) differences in the nature – more specifically, the stress and time dependence – of the GIA
 71 response to mass perturbations (note that the studies in Fig. 1 span a wide range of timescales).

72

73 While the combination of lateral variations and subsurface sampling are significant contributors
 74 to these discrepancy (van der Waal et al., 2015; Crawford et al., 2018) and we address these
 75 issues in a first order manner, our focus here is (ii), the timescale-dependent nature of GIA. For
 76 each of these regions, by investigating predictions the frequency dependent behavior using a new
 77 theoretical framework (Lau & Holtzman, 2019) and constraints based on seismic observations
 78 and laboratory experiments, we aim to demonstrate that the consideration of timescales can also
 79 result in substantial variations in estimated values of η_{AST} and z_{LAB} . These forward predictions
 80 are independent of the GIA observations, which allows us to investigate to what extent transient
 81 rheology can reconcile estimates of η_{AST} and z_{LAB} within the three regions shown in Fig. 1.

82

83 Lateral and depth-dependent viscosity variations have been studied extensively in the literature
 84 (e.g., Hager et al., 1985; Nakada & Lambeck, 1989; Peltier, 2004; van der Wal et al., 2013;
 85 Peltier et al., 2015;). While relatively new to GIA considerations (e.g., Caron et al., 2017; Ivins
 86 et al., 2020), the timescale-dependent behavior of viscosity has long been shown in experimental
 87 studies of the mechanical behavior of rock. The endmember elastic (and anharmonic) and
 88 viscous properties of rock have been well characterized in the experimental and theoretical rock
 89 physics community (e.g., Stixrude and Lithgow-Bertelloni, 2005; Hirth and Kohlstedt, 2004). In
 90 between these endmembers is the *anelastic* or *transient* regime, which is currently being

91 explored by several laboratories working on olivine samples (Faul and Jackson, 2015; Sundberg
92 and Cooper, 2010) and analogue materials (Takei, 2017). This work is building towards a clearer
93 picture of the grain-scale processes that govern macroscopic transient creep, including both
94 diffusion- and dislocation- (both linear and non-linear) related grain boundary processes (e.g.,
95 Hansen et al., 2020). (See Havlin et al. (2020) for a summary of these processes.) From these
96 microphysical mechanisms, distinct frequency-dependent rheological properties of rock are
97 predicted.

98

99 In order to incorporate these frequency-dependent properties into geophysical forward
100 predictions, they are described by phenomenological parameterizations via combinations of
101 springs and viscous dashpots that, in isolation, characterize elastic and viscous behavior,
102 respectively. The simplest arrangement is a single spring-dashpot pair in series, known as the
103 Maxwell model (see Fig. 2). This is the most common viscoelastic model considered in GIA
104 studies. Additional *transient* elements can be added to the Maxwell model to account for
105 anelastic effects, giving rise to more complex models such as the Andrade model (Sundberg and
106 Cooper, 2010), the Extended Burgers model (Faul and Jackson, 2015), and relaxation function
107 fitting approaches (Takei, 2017; McCarthy et al., 2011) (Fig. 3). In addition, complexity can
108 arise from non-linear (stress-dependent) effects (Hirth and Kohlstedt, 2004; Hansen et al., 2020).
109 Transient behavior in form of a Burger's rheology has been considered in some GIA studies
110 (e.g., Caron et al., 2017) in which observations are used to constrain the two viscosities of the
111 two distinct dashpots (Fig. 2). Comparisons between model predictions including steady-state
112 non-linear effects and observations of deglacial sea level have also been considered in GIA (e.g.
113 van der Wal et al., 2013; Huang et al., 2019).

114

115 In this study, we will quantify and test the role of frequency dependent viscoelastic deformation
116 in three specific study regions (Fig. 1). In contrast to other GIA studies, we will not use GIA
117 observations to infer the viscosity/ies of distinct dashpot/s, but instead apply the theoretical
118 framework introduced by Lau and Holtzman (2019) to predict the continuous frequency
119 dependent behavior for the different regions based on seismic observations and laboratory
120 | experiments. Specifically, we derive the complex viscosities, $\eta^*(\omega)$ (which is a measure of
121 viscosity or viscous dissipation), of the viscoelastic models spanning geophysically relevant

122 frequencies. With this approach we will treat viscoelastic rheology in a manner akin to mapping
123 attenuation, $Q^{-1}(\omega)$, as a function of frequency within the fields of seismology and Earth tides
124 (Shito et al., 2004; Benjamin et al., 2006; Lekic et al., 2009; Lau and Faul, 2019). In order to
125 compare our viscosity predictions to results from prior GIA studies we first determine the
126 frequency content of the time-domain GIA data and then test whether the predicted values of
127 both η_{AST} and z_{LAB} as a function of frequency can explain, at least in part, some of the variation
128 observed in these estimates.

129

130 **2 Theoretical Background and Methodology**

131

132 In the following, Section (2.1) will introduce the theoretical treatment of the complex viscosity
133 and how we can use this to produce frequency dependent estimates of lithospheric thickness and
134 asthenospheric viscosity. We will then, in (2.2), apply these ideas to the Western US and
135 Antarctica – where the observational studies listed in Fig. 1 are located. This will consist of two
136 parts: first, we estimate the thermodynamic subsurface structure at the selected locations and use
137 this to determine the mechanical properties through laboratory-derived constitutive laws. We will
138 then apply the formalism described in (2.1) to produce frequency dependent predictions of z_{LAB}
139 and η_{AST} across these settings. Finally, in (2.3), we will turn to the observational estimates listed
140 in Fig. 1. We will briefly summarize how they were determined and map the time-domain
141 observationally based estimates to their distinct frequency bands. This will allow comparison
142 between our predicted frequency trends of z_{LAB} and η_{AST} against these observations.

143

144 **2.1 Rheological Background & Complex Viscosity**

145

146 Lau & Holtzman (2019) introduced the complex viscosity, $\eta^*(\omega)$, parameter and its potential use
147 in geophysical processes involving viscoelasticity. (It is more commonly used within the
148 materials science literature, e.g., Gunasekaran & Ak, 2002.) Here we will show how $\eta^*(\omega)$
149 relates to more familiar parameters used in viscoelastic theory. In the time domain, for a linear
150 viscoelastic material, one can determine the strain, ϵ , under small increments of stress, σ , via

$$\varepsilon(t) = \int_{-\infty}^t J(t-t') d\sigma(t') \quad [1]$$

152 where $J(t)$ is the so-called creep function, which is the response of the material to a Heaviside
 153 function of stress (Nowick & Berry, 1972). Under different experimental conditions $J(t)$ may be
 154 determined to fit various functional forms. Equivalently, one may use the frequency domain
 155 $J^*(\omega)$, which may be found by taking the Fourier transform of $J(t)$. A closely related parameter
 156 is the complex modulus, $M^*(\omega)$, where $M^*(\omega) = [J^*(\omega)]^{-1}$ and for any of the spring-dashpot
 157 arrangements shown in Fig. 2, one may derive $M^*(\omega)$, which will have a distinct trend for any
 158 viscoelastic model.

159

160 In Fig. 2, all the viscoelastic models exhibit three regimes of deformation, partitioned by their
 161 frequency limits. The elastic regime occurs at infinite frequency limit ($f \rightarrow \infty$) where no energy
 162 is dissipated, and deformation is both instantaneous and fully recoverable. The anelastic regime,
 163 when $0 < f < \infty$, refers to deformation that remains fully recoverable but time dependent.
 164 Finally, the viscous, or steady-state regime, when $f \rightarrow 0$, wherein deformation is fully
 165 dissipative and is no longer recoverable. The total deformation is a combination of these
 166 behaviors and ultimately determined by the thermodynamic state. The spring ($f \rightarrow \infty$) and
 167 dashpot ($f \rightarrow 0$) that bookend this range of behavior involve the unrelaxed modulus, M_∞ ,
 168 associated with the isolated spring in series and at zero frequency, the steady state isolated
 169 dashpot in series, η_0 . (The subscripts denote their frequency limit.) These purely elastic and
 170 viscous limits are relatively well agreed upon (e.g., Stixrude & Lithgow-Bertelloni, 2005; Hirth
 171 & Kohlstedt, 2004; Hansen et al., 2011) but in between, the transient/anelastic elements are less
 172 so with many combinations suggested. Determining the trajectory of rheological behavior
 173 between these endmembers, i.e., determining $M^*(0 < \omega < \infty)$, remains a goal of many
 174 laboratory studies (for review, see Faul & Jackson, 2015; Takei, 2017) but has also been
 175 explored in geophysical observations which we discuss next.

176

177 The $\text{Re}[M^*(\omega)]$ reduces with decreasing frequency, causing dispersion, while $\text{Im}[M^*(\omega)]$
 178 captures the dissipative effects. Within seismology, dispersion manifests as the reduction of
 179 seismic wave-speeds at lower frequencies (e.g., Kanamori & Anderson, 1977). Similarly,
 180 attenuation, $Q^{-1}(\omega) = \text{Im}[M^*(\omega)]/\text{Re}[M^*(\omega)]$, increases with lower frequency (e.g., across the
 181 seismic band: Shito et al., 2004, Lekić et al., 2009; across the seismic and geodetic band:

182 Benjamin et al., 2006; Lau & Faul, 2019). In Fig. 3(a) we show a schematic figure of how
 183 $\text{Re}[M^*(\omega)]$ and $Q^{-1}(\omega)$ are sampled by seismic waves of different frequency.

184

185 We hope to extend this analogy to GIA studies, by using a more appropriate parameter, η^* . The
 186 relationship between $\eta^*(\omega)$ and $M^*(\omega)$ is

$$187 \quad \eta^*(\omega) = -i \frac{M^*(\omega)}{\omega},$$

188 and upon inspection, one can see that η^* has the same units as viscosity, where the real and
 189 imaginary parts have now been switched relative to M^* . No matter the arrangement of springs
 190 and dashpots (Fig. 2), just as with M^* , a continuous function across frequency may be derived
 191 for η^* . Just as the dispersion of wave-speed captures $\text{Re}[M^*(\omega)]$, we argue that estimated
 192 viscosities determined by different observations are sampling $\|\eta^*(\omega)\|$ at their respective
 193 frequency bands (Fig. 3b), where we have plotted $\|\eta^*(\omega)\|$ of a Maxwell viscoelastic model.
 194 This trend may be interpreted as an indication of the degree of viscous dissipation at a given
 195 forcing frequency (Lau & Holtzman, 2019).

196

197 Assuming we have determined the continuous form of $\eta^*(\omega)$ given an appropriate viscoelastic
 198 model (Fig. 2), we introduce two simple parameters, the *apparent viscosity*, $\tilde{\eta}(\omega)$ and the
 199 *apparent lithospheric thickness* $\tilde{z}_{\text{LAB}}(\omega)$, where the former is simply

$$200 \quad \tilde{\eta}^*(\omega) \equiv \|\eta^*(\omega)\| = \sqrt{\text{Re}[\eta^*(\omega)]^2 + \text{Im}[\eta^*(\omega)]^2}.$$

201 The conceptual step we have taken in this study is to *reinterpret* what the studies collated in Fig.
 202 1 termed η (or more specifically, as they applied Maxwell models, η_0) as apparent viscosity
 203 $\tilde{\eta}(\omega_{\text{obs}})$, where ω_{obs} is the frequency of observation (in practicality, this is a frequency band,
 204 Section 2.3). In the same vein, we interpret LAB depths as *apparent lithospheric thickness* or
 205 *apparent LAB depths*, $\tilde{z}_{\text{LAB}}(\omega_{\text{obs}})$. This parameter is explored in greater detail in Lau et al.
 206 (2020) and we only briefly describe the method by which we determine \tilde{z}_{LAB} below.

207

208 First, we define the Maxwell time, τ_M , of any viscoelastic media as η_0/M_∞ . Thus, considering
 209 only depth (z) dependent variation in structure, we have $\tau_M(z)$. If we are interested in z_{LAB} at a
 210 given frequency, e.g., $1/1000 \text{ y}^{-1}$, we find the depth at which the value of τ_M^{-1} is equivalent to
 211 1000^{-1} y^{-1} . This essentially marks the transition from elastic to viscous behavior at a given

212 frequency. This definition breaks down at frequencies higher than the Maxwell frequency, where
 213 we propose that z_{LAB} becomes essentially frequency independent. At these high frequencies, the
 214 notion of a plate itself becomes unclear. We note that this is just one definition of many that
 215 exist for the LAB, though this definition highlights the frequency dependence of z_{LAB} .

216

217 **2.2 Predicting of Apparent Lithospheric Thickness and Asthenospheric Viscosity in** 218 **Anarctica and western North America**

219 We focus on three regions matching those in Fig. 1: Western North America (W-NA), Western
 220 Antarctica (W-ANT), and the Antarctic Peninsula (ANT-P). For each location we determine
 221 depth dependent profiles of upper mantle mechanical properties across the full spectrum in
 222 frequency relevant to geophysical timescales. This includes implementing elastic, anelastic, and
 223 viscous constitutive laws in a self-consistent manner, using the recently released software library
 224 known as the “Very Broadband Rheology” (VBR) calculator (<https://vbr-calc.github.io/vbr/>;
 225 Havlin et al., 2020). This software library takes thermodynamic conditions and a chosen
 226 composition as input and applies chosen constitutive laws to predict $M^*(\omega)$. From $M^*(\omega)$ we
 227 may extract $\tilde{z}_{\text{LAB}}(\omega)$ and $\tilde{\eta}_{\text{AST}}(\omega)$. Hereafter, we use the term *combined constitutive laws* when
 228 referring to the full-spectrum constitutive law which ties together elastic, anelastic and viscous
 229 constitutive laws and for all the figures and calculations within the main text, we use the laws of
 230 Stixrude & Lithgow-Bertelloni (2005), MacCarthy et al. (2011), and Hirth & Kohlstedt (2004),
 231 respectively. We explore how our predictions change when different anelastic laws are applied
 232 in the Supporting Information.

233

234 The self-consistency in the combined constitutive law is important to explain: The individual
 235 constitutive laws (multiple sets for elastic, viscous and anelastic) are derived from different
 236 laboratories, which have different scalings from laboratory- to earth-conditions and are all
 237 implemented within the VBR calculator, to facilitate comparison. Different anelastic models
 238 incorporate the elastic and viscous laws differently (Havlin et al., 2020), leading to different
 239 degrees of self-consistency in the combined constitutive laws, a topic beyond the scope of this
 240 paper. In this paper, we use one combined constitutive law to infer thermodynamic state from
 241 measurements made in the seismic band and then use that same law to extrapolate across the

242 entire geophysical spectrum to predict wideband mechanical behavior. Thus, our first step is to
 243 determine the thermodynamic conditions (temperature and pressure, T and P , respectively)
 244 beneath these regions. The entire workflow is summarized in Fig. 4.

245

246 **2.2.1 Determining the Thermodynamic Conditions**

247

248 To estimate the subsurface thermodynamic structure, \mathbf{S} , beneath each of our regions, we
 249 approximated each by a simple plate model characterized by a conductive lid of thickness z_{LID} ,
 250 above which heat is lost via conduction and beneath which the temperature follows that of an
 251 adiabat characterized by a potential temperature T_{P} . (Note that z_{LID} is not necessarily equivalent
 252 to z_{LAB} depending on the definition used by the different studies we include.) This estimation
 253 occurs in two steps.

254

255 First, we used seismic tomographic models to extract the observed asthenospheric shear wave-
 256 speed, v_{S} , for each region: Shen & Ritzwoller (2016) for W-NA and Lloyd et al. (2020) for all of
 257 Antarctica. For each region, we extracted a single v_{S} value by horizontally averaging over a
 258 radius of 50 km surrounding the stars (Figs 1(c,d)) and vertically averaging between the shaded
 259 orange shaded region (Figs 5a-c, subpanels i-ii), a region encapsulating the asthenosphere just
 260 beneath the plate. (We note that we tested the lateral averaging affects by repeating the
 261 calculations over radii spanning 50-200 km and our conclusions remain the same, though this
 262 length-scale may be regionally dependent (e.g., Lau et al., 2018).) Using this tomographic v_{S}
 263 value (see circle in Figs 5a, subpanels i) at its reported seismic band (see each reference), we
 264 determined the temperature at the associated depth by using the VBR calculator. For this
 265 purpose, the VBR maps state variables \mathbf{S} to mechanical properties (e.g., v_{S} at the appropriate
 266 frequency), and then using Bayesian inference, finds the best fitting set of state variables given
 267 the seismic input from tomography (Havlin et al., 2020). Extrapolating the temperature value
 268 along the adiabatic gradient to the surface provides us with the associated T_{P} (Havlin et al.,
 269 2020). The simplification of characterizing each region as a plate model means that both T_{P}
 270 along with the adiabatic gradient are sufficient to describe the asthenospheric thermal profile for

271 | each region. The smoothness of the v_s profiles from these tomography models (Fig. 5, subpanels
 272 | i) suggests that such an approximation is reasonable for these regions.

273

274 | With the asthenospheric thermal profile constrained for each region, we then create a suite of
 275 | plate profiles, \mathbf{P}_i (where $i = 1, 2, \dots, N$), where each i -th profile requires the following parameters
 276 | as input: homogenous grain size g_i , melt fraction ϕ_i , water content $X_{\text{H}_2\text{O}}$, and major composition
 277 | X_{maj} . Each profile \mathbf{P}_i is determined by solving the 1-D transient heat equation with a conductive
 278 | lid until steady state is reached for a given i -th set of parameters. To produce N profiles, we vary
 279 | the following parameters: $g = [0.001, 0.004, \dots, 0.03]$ m, and $\phi = [0., 0.005, \dots, 0.03]$; while
 280 | holding the compositions constant, i.e., $X_{\text{H}_2\text{O}} = 0$, $X_{\text{maj}} = \text{olivine (90\% forsterite)}$. We also then
 281 | vary the thickness of the conductive lid, between $[50, 60, \dots, 250]$ km. Thus far, this procedure
 282 | is shown by steps (1) and (2) in Fig. 4.

283

284 | In the second step, we set out to determine the plate profile with the best fitting z_{LID} (step (3) in
 285 | Fig. 5). We use observed values of LAB depths, or $z_{\text{LAB}}^{\text{obs}}$, derived from the seismic studies of
 286 | Hopper & Fischer (2018) for W-NA and An et al. (2015) for all of Antarctica. We treated each
 287 | differently as $z_{\text{LAB}}^{\text{obs}}$ has different definitions within the two models. (The definition of the
 288 | lithosphere is not universal, as discussed in detail by Lau et al. (2020) and further provides
 289 | motivation for the notion of *apparent plate thickness*.) We reproduced each study's version of
 290 | $z_{\text{LAB}}^{\text{obs}}$ from our N plate models. For the Antarctic lithospheric model, $z_{\text{LAB}}^{\text{obs}}$ coincides with the
 291 | intersection of the base of the conductive plate and the adiabatic gradient (estimated from
 292 | seismic data), and thus, z_{LID} , which we impose for each \mathbf{P}_i , and $z_{\text{LAB}}^{\text{obs}}$ are the same. For W-NA,
 293 | Hopper & Fischer (2018) define the LAB as the most negative $\partial v_s / \partial z$ value. Hence, for W-NA,
 294 | for our suite of \mathbf{P} , the VBR calculator predicted the v_s profile at the appropriate seismic
 295 | frequency bands using the combined constitutive laws from which we extract $\partial v_s / \partial z$ and find
 296 | the depth at which this value is most negative.

297

298 | With these LAB constraints we use Bayesian inference (see Havlin et al., 2020, for more details)
 299 | to produce posterior probability distributions of the thickness of the conductive lid and each state
 300 | variable we vary. We assumed that prior knowledge for each state variable is represented by a

301 uniform probability density function over the ranges we have stated. We ascribe a uniform
 302 uncertainty distribution of $\pm 5\%$ and ± 5 km for the observed v_s and $z_{\text{LAB}}^{\text{obs}}$. As a result, for each
 303 region, we select the model with the highest joint probability distribution. The best fitting v_s
 304 profiles are shown in Figs 5(a-c), subpanels (ii). For reference, in Figs 5(a-c), subpanels (ii), the
 305 circles mark the v_s values of the resulting best fitting models within the depth range that they
 306 were required to fit the observed profiles (shaded region). The corresponding temperature
 307 profiles, determined by a combination of assuming an adiabatic gradient and thickness of the
 308 conductive lid, are shown in Figs. 5(a-c), subpanels (iii) (black lines). In Fig. S1 we show the
 309 resulting joint probability distributions for each region, highlighting the trade-offs between
 310 various parameters.

311

312 **2.2.2 Determining apparent viscosity and apparent lithospheric thickness**

313

314 Having identified the best fitting thermodynamic conditions, i.e., $\mathbf{S}_{i=\text{best}}$, for each region, we
 315 used the VBR calculator with this input to predict several mechanical parameters using the
 316 combined constitutive law, including the complex modulus ($M^*(z, \omega)$), complex viscosity
 317 ($\eta^*(z, \omega)$), and attenuation $Q^{-1}(z, \omega)$ (shown in Fig. S2). This corresponds to step (4) in the
 318 flowchart (Fig. 4).

319

320 From Section 2.1 it is now straightforward to see how, from $M^*(z, \omega)$, one can extract $\tilde{\eta}_{\text{AST}}(\omega)$
 321 and \tilde{z}_{LAB} . In order to do this, we determine η^* from M^* , and the results of these predictions are
 322 shown in Figs 5(a-c), subpanels (iii-v). For the anelastic regime, where more uncertainty exists
 323 across different constitutive laws, we applied several other laws shown in Fig. S3 to explore this
 324 uncertainty (analogous to results of Fig. 5, using experimental laws of Faul & Jackson (2015)
 325 and the premelting model of Yamauchi and Takei (2016) (see also Takei, 2017).

326

327 **2.3 Determining the Frequency Content of Observationally Derived $\tilde{\eta}_{\text{AST}}$ and \tilde{z}_{LAB}**

328

329 Observationally derived estimates of lithospheric thickness and viscosity are generally obtained
 330 by combining knowledge of past load changes (ice sheets or lakes) with observations of
 331 deformation (GPS or reconstructions of paleo-water level) assuming a viscoelastic model. The

332 estimates we have used for comparison against our VBR-driven profiles are all parameters
 333 reported from studies with various observational constraints (mostly geodetic and geologic), and
 334 thus are subject to a range of simplifying assumptions. The estimates of both z_{LAB} and η_{AST}
 335 have been compiled from the following investigations for each region (listed in order of
 336 decreasing timescale): For Western North America, estimates were derived from paleo sea-level
 337 indicators that measure GIA during Marine Isotope Stages 5a and 5c (~80 and ~100 ky BP,
 338 respectively) (Creveling et al., 2017), paleo-shorelines recording rebound at Lake Bonneville and
 339 Lake Provo (~14 ky BP) (Austermann et al., 2020), and geodetic observations of postseismic
 340 relaxation after the 1992 Landers earthquake (Pollitz et al., 2000). In addition, we included the
 341 z_{LAB} estimate inferred from GPS estimates of the postseismic relaxation following the 2010 El
 342 Mayor-Cucapah earthquake (Dickinson-Lovell et al., 2018). For Western Antarctica, Barletta et
 343 al. (2018) used GPS derived measures of decadal-scale rebound at the Amundsen Sea
 344 Embayment. Finally, for the Antarctic Peninsula, decadal (Nield et al., 2014; Samrat et al., 2020)
 345 and centennial (Ivins et al., 2011; Wolstencroft et al., 2015) responses to ice mass change, once
 346 more, measured by GPS, were used to derive viscosity estimates.

347
 348 These studies result in different estimates of z_{LAB} and η (Fig. 1) and as described in the
 349 Introduction, these variations may in part arise from the differing thermodynamic conditions of
 350 the subsurface structure and how the GIA process samples this. In the most ideal scenario we
 351 would consider only observations that sample exactly the same earth structure, but only on
 352 different timescales. In reality, these kind of observations do not yet exist and we can only
 353 minimize the effect of sampling different earth structure. To do this, we have chosen to focus on
 354 studies that cover similar geographic regions and mostly sample the asthenosphere.

355
 356 In order to compare our predictions of $\tilde{\eta}_{\text{AST}}(\omega)$ and $\tilde{z}_{\text{LAB}}(\omega)$ to the observations presented in
 357 Fig. 1, we first reinterpreted these viscosities and lithospheric thicknesses as *apparent* quantities.
 358 Next, we must determine their frequency content, which requires us to consider two important
 359 timescales associated with each observation: τ_{dur} , the duration over which the loading/unloading
 360 event in question occurred, and τ_{del} , the time delay between the end of the event and when the
 361 observation of solid Earth deformation was taken. For example, z_{LAB} and η estimates from the
 362 the loading of Lake Bonneville (Austermann et al., 2020) occurred across a timespan ~4,000 y

363 | ($\tau_{\text{dur}} \sim 4,000$ y), and measurements of rebound are recorded as dated shorelines during the
 364 | loading period, and as such, we assign $\tau_{\text{del}} \sim 0$ y. (We note that the long-term GIA deformation
 365 | associated with the Laurentide ice sheet was still ongoing during the late unloading, we consider
 366 | this secular deformation as background. In that study, the authors considered the two processes
 367 | distinct.) These designations of τ_{del} and τ_{dur} – tabulated and briefly explained for each
 368 | observation in Table S1 – are approximate but our aim is to cover a wide enough frequency band
 369 | to provide the most conservative estimate possible. With these two timescales we assign each
 370 | process a frequency band, $[f_{\text{low}}, f_{\text{upp}}]$, applying an empirical relationship based on replicating
 371 | the loading history and measurement of deformation, as described below.

372

373 | In Section 2.1 we introduced how the creep function, J , relates the strain of a material to an
 374 | applied stress (Eq. 1). In order to replicate a generic loading history and measurement of
 375 | deformation, we apply the stress history shown in Fig. 6(a), where we have schematically
 376 | depicted the timespans of τ_{dur} and τ_{del} . In order to estimate the frequency content within this
 377 | deformation response, we require knowledge of $J(t)$ and $J^*(\omega)$. This is not always
 378 | straightforward (e.g., Nowick & Berry, 1972) and so we turn to the 1-D Andrade model, J_{An}
 379 | (Fig. 2). We choose the Andrade model since it can capture the full spectrum of viscoelastic
 380 | (elastic, transient, viscous) behavior with few model parameters (Cooper, 2002) and its
 381 | expression for $J_{\text{An}}^*(\omega)$ is known, where

$$J_{\text{An}}(t) = \frac{1 + t/\tau_{\text{M}}}{M_{\infty}} + \beta t^n$$

382 and

$$J_{\text{An}}^*(\omega) = J_{\infty} + \beta \Gamma(1 + n) \omega^{-n} \cos\left(\frac{n\pi}{2}\right) - i\beta \Gamma(1 + n) \omega^{-n} \sin\left(\frac{n\pi}{2}\right) + \frac{1}{\eta_0 \omega}$$

383 | (Faul and Jackson, 2015). Our aim is to use these analytical expressions to fit those that have
 384 | been output by the VBR so that we can mimic loading histories for these viscoelastic models and
 385 | readily move between the time and frequency domain. To do so, for all regions, we chose n as
 386 | 1/3 (Cooper, 2002), used the VBR output values of τ_{M} , M_{∞} associated with each region, and
 387 | solved for the best fitting β value via a grid search. More specifically, we determined apparent
 388 | viscosities from Andrade models with many values of β and selected the model that reproduced
 389 | the apparent viscosity trends from the VBR, where Fig. 6b shows our final fits for each region.

390 The solid lines are reproduced from Fig. 5 (subpanels v). With the simple time domain
 391 expression for $J(t)$ we can readily perform the convolution in Eq. 1.

392

393 We apply the linearly increasing load for a period of τ_{dur} depicted in Fig. 6(a) and perform many
 394 tests across the range ($10^{-2} \leq \tau_{\text{dur}} \leq 10^6$) years, effectively varying the stress rate, and
 395 convolve this with the best fitting $J_{\text{An}}(t)$ expressions. In order to emulate measurements made
 396 by the unloading/loading scenarios in our dataset, we determine the resulting strain rate, $\dot{\epsilon}$ from
 397 Eq. 1. We make $\dot{\epsilon}$ values at various values of τ_{del} across the range ($10^{-4}\tau_{\text{dur}} \leq \tau_{\text{del}} \leq 10^4\tau_{\text{dur}}$)
 398 years, a range that covers all scenarios. Using the strain rate, we estimate the viscosity assuming
 399 a *Maxwell viscoelastic model*, η_{est} , and that we know M_{∞} and $\sigma(t)$ (all assumptions made by the
 400 studies included here). For the simple 1-D case,

$$401 \quad \eta_{\text{est}} = \sigma \left(\dot{\epsilon} - \frac{\dot{\sigma}}{M_{\infty}} \right)^{-1}.$$

402 As argued previously, these viscosity estimates are capturing the *apparent* viscosity of the
 403 underlying Andrade model, i.e., $\tilde{\eta}_{\text{An}}$, at its respective frequency. In order to map out the
 404 frequency band for which values of η_{est} capture we first consider f_{upp} . For f_{upp} we know that,
 405 given the timescale of any process, the highest possible frequency must be bound by τ_{dur}^{-1} . The
 406 Fourier transform of a linear trend is dominated by low frequencies and longer values of τ_{del} will
 407 result in any relatively high frequency response to diminish. But just how low is this bound? For
 408 f_{low} we find the frequency for which $\tilde{\eta}_{\text{An}}$ (derived from $\tilde{J}_{\text{An}}^*(\omega)$) is equivalent to η_{est} . For each
 409 observation, we show the frequency band dictated by τ_{dur} and τ_{del} in Fig. 6(c-e).

410

411

412 **3 Results and Discussion**

413 **3.1 Reconciling observational estimates of asthenospheric viscosity and plate** 414 **thickness**

415 Fig. 1 displays differing estimates of what studies report as measures of elastic plate thickness
 416 and Maxwell viscosity at the listed locations. These differences may be due to the variations in
 417 thermodynamic setting and/or forcing timescale dependent effects. In Fig. 5, we divide these
 418 observation-driven estimates into their respective regions and account for the broad

419 thermodynamic conditions (to reduce the effect of the former) and recast these estimates as
 420 frequency dependent apparent viscosities (to highlight the latter). By doing this, we see that the
 421 frequency dependence of the forcing may play a substantial role. In all locations the apparent
 422 viscosity decreases as a function of increasing frequency, while \tilde{z}_{LAB} increases with increasing
 423 frequency. At high frequency, we find that \tilde{z}_{LAB} is at a maximum as one must go to hotter
 424 conditions (i.e., deeper depths) for this elastic-to-viscous transition to occur. Toward longer
 425 timescales, \tilde{z}_{LAB} relaxes to shallower depths (Fig. 5, subpanels (iv)).

426

427 In Fig. 5, we have also placed the apparent viscosities and plate thicknesses obtained from
 428 observational estimates (Fig. 1) in order to compare them against our modeled predictions.
 429 Across all regions some of the observations of $\tilde{\eta}_{\text{AST}}$ (subpanels (iii)) fit our predicted values well
 430 (colored lines) and some fall within the shaded regions, which we discuss in the next section. A
 431 slightly less clear picture is seen with \tilde{z}_{LAB} , where qualitative trends agree but several
 432 observations do not align with the predictions of \tilde{z}_{LAB} (colored lines). Where \tilde{z}_{LAB} observations
 433 and predictions match reasonably well are at W-ANT and W-NA (with some falling within the
 434 shaded region). Uncertainties in \tilde{z}_{LAB} estimates in the ANT-P region are quite large and do not
 435 overlap across the same frequency bands. For this region, it is important to consider that the
 436 continental lithosphere is comprised of a narrow peninsula rather than a large continental interior
 437 and observations made at ANT-P (which, across the studies included, span the stretch of the
 438 peninsula) may be sampling aspects of both the lithosphere beneath the narrow peninsula and the
 439 surrounding oceanic region. In addition, slightly beneath the depth range we consider, there is a
 440 subducting slab that may also affect GIA (Lloyd et al., 2020). Our simple depth dependent
 441 profiles may not sufficiently capture this complexity and/or z_{LAB} measurements are not well
 442 constrained by the type of observation used.

443

444 While lateral variations in thermodynamics and the potential variability in the sampled
 445 subsurface of each observation can contribute to the variability in z_{LAB} and η_{AST} within each
 446 region, our comparison between these observation-driven estimates and VBR determined
 447 predictions of frequency dependent parameters convincingly illustrates that such processes are
 448 not only important to consider, but can in fact explain some of the variation in GIA based
 449 estimates. We therefore suggest moving towards an estimation framework that aims to map out

450 | the continuous frequency trend of $\tilde{\eta}(\omega)$ through observations of different frequency – akin to
 451 | mapping out the frequency dependence of $Q^{-1}(\omega)$ in seismic studies (Fig.3). If a complete trend
 452 | may be mapped, more concrete inferences on the underlying viscoelastic model may be made.
 453 | However, unlike the seismic application, quantifying the frequency content for any given time-
 454 | domain GIA process is not trivial and while we propose one approach here (section 2.3), we
 455 | argue that further work is required to better understand this relationship. In the next section, we
 456 | discuss the deformational processes that may be responsible for these values of $\tilde{\eta}(\omega)$.

457

458 | **3.2 Grainscale deformation processes and their manifestation in GIA**

459

460 | The steady-state viscosity profiles (Fig. 5; colored bold lines, subpanels (iii)) of each region
 461 | show the structure most relevant to mantle convection timescales. The horizontal-colored line
 462 | shows the depth at which \tilde{z}_{LAB} occurs at the zero-frequency limit. This can be thought of as the
 463 | *true* thickness of the plate – which, by many definitions with the literature, is the base of the top
 464 | thermal boundary layer of mantle convection, above which conduction is the mode of heat loss
 465 | (Fisher et al., 2010). However, as Lau et al. (2020) argue, many studies infer *apparent plate*
 466 | *thickness* at the frequency of the unloading process (colored bold lines, subpanels (iv)). For
 467 | example, changes in seismic velocity gradients, seismic anisotropy measurements, receiver
 468 | functions and attenuation data (Hopper & Fischer, 2018; Mancinelli et al., 2017) have been used
 469 | to infer \tilde{z}_{LAB} at frequencies of $\sim(0.01-0.1)$ Hz. This inference of \tilde{z}_{LAB} lies towards the far right of
 470 | subpanels (iv) (grey bar). The physical relationship between the seismic LAB and the convective
 471 | LAB is discussed in more detail in Lau et al. (2020). As can be seen, moving towards lower
 472 | frequency \tilde{z}_{LAB} relaxes to significantly shallower depths as the asthenosphere beneath becomes
 473 | increasingly viscous, impinging on the rigid plate above. These panels demonstrate that one
 474 | cannot assume that LAB values inferred on seismic timescales are appropriate for processes
 475 | acting on convection timescales. For example, in W-NA the LAB ranges from 75, 50, to 35 km
 476 | when probed at the seismic, ice age, and convective timescales, respectively. An analogous
 477 | discussion based on the *Effective Elastic Thickness* of plates at different timescales may be found
 478 | in Watts et al. (2013).

479

480 | Now examining $\tilde{\eta}_{\text{AST}}(\omega)$ (colored bold lines, subpanels (v)), we see a significant increase
 481 | towards lower frequency spanning several orders of magnitude for all regions. At the high
 482 | frequency extreme, $\tilde{\eta}(\omega \rightarrow \infty)$ tends towards zero, as we move towards the purely elastic regime
 483 | of deformation. Once more, the *apparent viscosity* cannot be mistaken for η_0 ; this latter value is
 484 | reached at low frequencies, depicted by the plateau of $\tilde{\eta}(\omega)$ on the low frequency end of our
 485 | plots. So, what might we infer from these results about the activation of certain deformation
 486 | mechanisms?

487

488 | **3.2.1 Diffusion Creep**

489

490 | For the solid lines in Fig. 5, the underlying mechanism is diffusion creep. In GIA, the most
 491 | commonly adopted viscoelastic model used to phenomenologically describe such creep is the
 492 | Maxwell model (as is the case with all the observations included here). However, such a model
 493 | does not capture *transient* diffusion creep, arising from stress concentrations at grain edges,
 494 | driving diffusive flow of matter through grain boundaries or sub-grain boundaries, causing those
 495 | stress concentrations to relax (e.g. Cooper, 2002 and references therein). This process is
 496 | considered to cause the so-called *High Temperature Background* (“HTB”) attenuation.
 497 | Additional dissipative mechanisms that can be superposed onto the HTB in the linear anelastic
 498 | regime include elastically accommodated grain boundary sliding, melt squirt, dislocation
 499 | damping (at constant dislocation density), and other processes (e.g. Cooper, 2002; Havlin et al,
 500 | 2020). Transient diffusion creep relaxes to steady-state, diffusively accommodated grain
 501 | boundary sliding (Cooper, 2002; Faul & Jackson, 2015). These processes can be activated at
 502 | different frequencies depending on the thermodynamic state, and the associated dissipation is
 503 | often parameterized within the experimental community by the intrinsic attenuation, $Q^{-1}(\omega)$
 504 | (i.e., the fractional average energy dissipated per cycle of oscillation).

505

506 | Here, we can assess here the degree to which transient creep may contribute to the trend in $\tilde{\eta}(\omega)$
 507 | captured by our selected observations. The solid color lines in subpanels (iv) and (v) capture the
 508 | trend of the HTB model (where, as well as the elastic and viscous endmembers, we include HTB
 509 | transient diffusion only – in the case of the Main Text examples, the latter is the constitutive law

510 of McCarthy et al. (2014)). The dashed colored lines are identical but with no transient creep
511 component, representing a Maxwell model with the same η_0 and M_∞ values. The departure in $\tilde{\eta}$
512 between the full and equivalent Maxwell models clearly occurs across a frequency band spanned
513 by most of the processes we consider. While these differences in $\tilde{\eta}$ seem slight in these figures,
514 the ratio between these two models can be as low as ~50%, emphasized in the plots of
515 normalized η^* in Lau et al, 2020. Our data here cannot distinguish the difference between the
516 two trends of $\tilde{\eta}$, but future studies may be designed to identify the degree of HTB transient creep
517 and explore additional dissipative mechanisms in such deformation.

518

519 **3.2.2 Dislocation Creep**

520

521 Diffusion creep rate is linear in stress and relevant at low levels of both strain and stress, where
522 deformation *probes* the microstructure but does not modify it. Processes like GIA and seismic
523 wave propagation are characterized by small strains ($\sim 10^{-5}$) and low stresses (\sim kPa), such that it
524 is possible that transient diffusion creep dominates any transient response. and likely that grain
525 sizes are not modified by those processes. However, crystallographic fabrics of xenoliths and
526 ubiquitous seismic anisotropy in the upper mantle implicate an important role for dislocation
527 creep at least at convective time scales.

528

529 A non-linear transient regime may be reached in which a forcing process produces dislocations,
530 modifying the dislocation density *during* the process and affecting the transient response (e.g.,
531 Farla et al., 2012; Cooper et al., 2016; Thieme et al., 2018). At increasing levels of stress,
532 dislocation density increases, causing rock to weaken. If the forcing level (applied stress) is
533 constant or changing slowly enough (quasi-static), dislocation density can be considered constant
534 and the dislocation creep rate is steady state, as characterized by numerous laboratory studies.
535 While full self-consistency regarding the role of dislocation creep would incorporate both the
536 transient and the steady state roles of dislocations, such a composite constitutive model across
537 the range of conditions of interest here does not yet exist, though much research is underway
538 (Hansen et al., 2020).

539

540 Towards estimating the potential effects of dislocation creep in the wide-band responses
 541 considered here, we can easily incorporate steady state dislocation creep into the current
 542 framework without considering the transient role of dislocations. This extra mechanism is
 543 phenomenologically represented by an additional steady-state, stress-dependent dashpot, labeled
 544 η_{disl} , in series with the linear Maxwell steady-state dashpot, η_0 (Fig. 2). The effective steady-
 545 state stress is dominated by the dashpot with the lower viscosity. In subpanels (iii-v) of Fig. 5,
 546 shaded regions reflect the effect of steady-state dislocation creep (Hirth & Kohlstedt, 2005), and
 547 encompass variations in η_0 , \tilde{z}_{LAB} , and $\tilde{\eta}_{\text{AST}}$ from stresses (σ) ranging where ($0 \leq \sigma \leq 10$) MPa
 548 (where colored bold lines and fine gray lines coincide with 0 and 1 MPa, respectively). As shown
 549 by these regions, macroscopically, there is a reduction in all parameters in Fig. 5 and the
 550 transition of \tilde{z}_{LAB} is shifted to higher frequency as the effective Maxwell time is now reduced.
 551 We note that, in certain parts of the plate, GIA processes reach such levels of stress (in Fig. S4
 552 we show the deviatoric stress beneath the ice sheet over a representative GIA cycle). Since
 553 several of the observations fall within these shaded regions, it is possible that nonlinear
 554 deformation is occurring to explain these estimates of $\tilde{\eta}_{\text{AST}}$ and \tilde{z}_{LAB} .

555

556

557 **3.3 Implications for ice mass change and sea-level change**

558

559 Ice mass change, both past and present, span a wide frequency spectrum, and we show here that
 560 so too does the variation in the solid Earth's response to such perturbations. Based on our results
 561 we suggest that by reinterpreting estimates of viscosity and plate thickness as *apparent*
 562 *viscosities* and *apparent plate thicknesses* these seemingly diverging values may be reconciled.
 563 We also show that laboratory-based constitutive laws suggest that transient creep plays some role
 564 across the span of our observations (from rapid to ~ 10 ky timescales).

565

566 Ultimately, ignoring deformational mechanisms acting across the wide frequency range of GIA
 567 processes may lead to misestimation of the sea-level response, whether those include rapid ice
 568 collapse, where studies typically invoke a purely elastic Earth (e.g., Gomez et al., 2010) or solid
 569 Earth responses modeled purely as Maxwell viscoelastic solids. For example, following our results
 570 shown in Fig. 6(b), we predict that if the same amount of ice retreat in the Amundsen Sea area

571 occurred over 1, 10, 100, and 1000 y, the asthenospheric apparent viscosity would be $\sim 10^{18}$, $\sim 6 \times$
572 10^{18} , $\sim 10^{19}$, $\sim 6 \times 10^{19}$ Pa s. This may have implications for the stabilizing effect of GIA on the
573 Antarctic ice sheet, which affects predictions of future sea level change.

574

575 A further compounding factor on all timescales is that high frequency and high magnitude melt
576 events will result in high strain rates that may require the consideration of non-linear rheology
577 that, as discussed previously, involves changes in the dislocation structure driven by these large
578 external stresses. It is unclear how such extraneous stress regimes might alter GIA during these
579 events, but one might expect that the apparent viscosity would be significantly reduced due to
580 stress magnitude and the relatively high frequency of such intense melting events. So far non-
581 linear rheologies have only been considered in isolation (van der Waal et al., 2013, Huang et al.,
582 2019), but our preliminary calculations presented here show that these effects have repercussions
583 across a wide frequency band.

584

585 **4 Conclusions**

586

587 The adoption of the Maxwell viscoelastic models from the early semi-analytical techniques
588 derived (Wu & Peltier, 1982; Mitrovica & Milne, 2003) offered an elegant means to solve a
589 complicated viscoelastic system and fit a whole range of sea-level and geodetic observations.
590 The realization, however, that temperature effects alone result in lateral variations in viscosity
591 that span orders of magnitude required a distinct departure from these semi-analytic techniques
592 and a movement towards computationally demanding finite-element methods that continues
593 today (e.g., Zhong et al., 2003; Latychev et al., 2005; van der Waal et al., 2005).

594

595 With a growing richness in datasets that capture increasingly subtle signals of ice melt, we
596 believe the next level of complexity must be met. Our results outlined here have highlighted a
597 potential pathway towards considering both thermodynamic variations within Earth's subsurface
598 and the nature of the forcing (both frequency and stress) for GIA-related processes. We have
599 applied a means of self-consistently interpreting observational results that span the full spectrum
600 in frequency. There are several simplifications we have made in order to focus on this full
601 spectrum behavior: we have broadly interpreted viscosity estimates – drawn from a diverse set of

602 studies each with their own assumptions and spatial sensitivities – as apparent viscosities of the
603 asthenosphere, and we have considered depth dependent plate profiles for each region,
604 neglecting lateral variations in thermodynamic environment and assuming that each region may
605 be approximated as a plate model. (Though we emphasize that we were equally mindful of
606 choosing observations that reflected these specific regions both geographically, and in depth.)

607

608 Nevertheless, in doing so, we have demonstrated that our current understanding of Earth
609 deformation, derived from microphysical investigations that operate on timescales appropriate
610 for the laboratory setting, shows significant promise in explaining much of the variability we
611 observe on the planetary scale and across timescales that capture Earth’s long and nuanced
612 history. Looking to the future, we encourage both the inclusion of viscoelastic models in GIA
613 that move beyond the Maxwell model (e.g, Yuen et al., 1986; Ivins et al., 2020), the
614 determination of the frequency content within measurements of time-domain processes like GIA,
615 | and the search to map out the continuous function $\tilde{\eta}(\omega)$, rather than discrete values of η_0 , to help
616 improve predictions of cryosphere-solid Earth responses as rates of ice sheet melting and
617 collapse increasingly occur on shorter timescales.

618

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622

623
624
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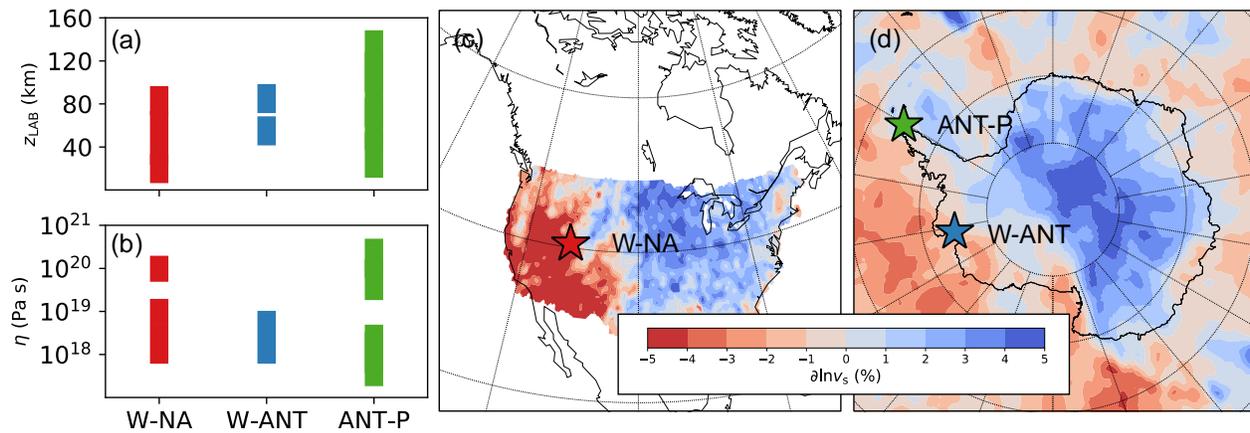
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828 **Figure 1. Estimates and locations of plate thickness and upper mantle viscosity.**
 829 A compilation of (a) lithospheric/plate thickness, z_{LAB} , and (b) upper mantle viscosity, η , across
 830 Western North America, W-NA (Creveling et al., 2017; Austermann et al., 2020; Dicinson-
 831 Lovell et al., 2018; Pollitz et al., 2000; Hopper and Fischer, 2018), Western Antarctica, W-ANT
 832 (Barletta et al., 2018; [An et al., 2015), and the Antarctic Peninsula, ANT-P (Wolstencroft et al.,
 833 2015; Ivins et al., 2011; Nield et al., 2014; Samrat et al., 2020; An et al., 2015). These estimates
 834 are derived from seismic, post-seismic relaxation, lake rebound, and GIA data. (c,d)
 835 Approximate locations of the observation-driven estimates and the tomographic models used in
 836 Section 2.2.1, where panels (c) and (d) show models at depths of 150 km of Shen & Ritzwoller
 837 (2016) and Lloyd et al. (2020), respectively.
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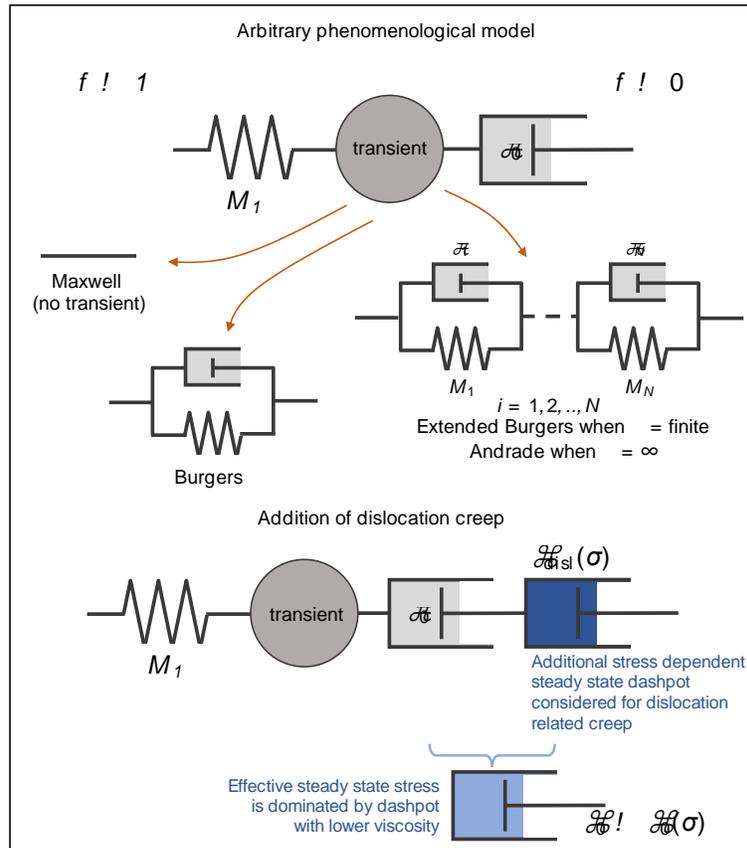


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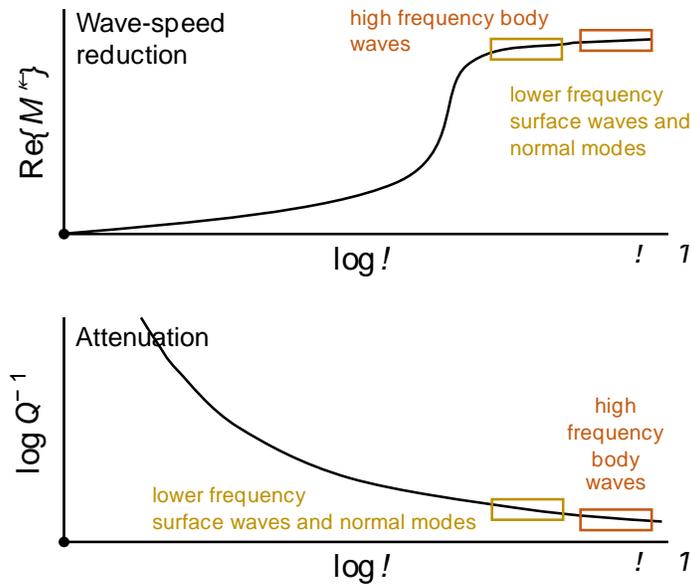
842 **Figure 2. Phenomenological Viscoelastic Models.**
 843 Depiction of 1-D phenomenological viscoelastic models. The dark gray circle symbolically
 844 represents any combination of springs and dashpots that mimic transient deformation. Replacing
 845 the circle with any of the components linked by an arrow will form the commonly adopted
 846 models labelled. With the addition of steady state dislocation creep, the viscosity of the steady
 847 state dashpot, η_0 , becomes stress, σ , dependent.
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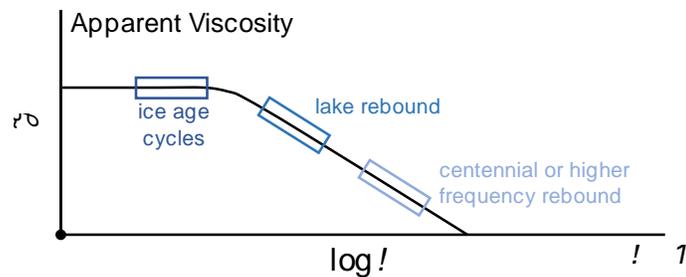
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855 **Figure 3. Mapping out dissipation parameters with geophysical observations**
 856 (a) A schematic depiction of seismic wave-speed reduction (top panel) at lower frequencies due
 857 | to dispersion (or $\text{Re}\{M^*(\omega)\}$) and the increase of attenuation, $Q^{-1}(\omega)$ (bottom panel) at lower
 858 | frequencies. The boxes denote how these trends are sampled by seismic data at different
 859 | frequencies. (b) The analog to (a) but how GIA processes may sample apparent viscosity, $\tilde{\eta}(\omega)$.
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(a) Seismic sampling of mechanical properties



(b) GIA sampling of mechanical properties

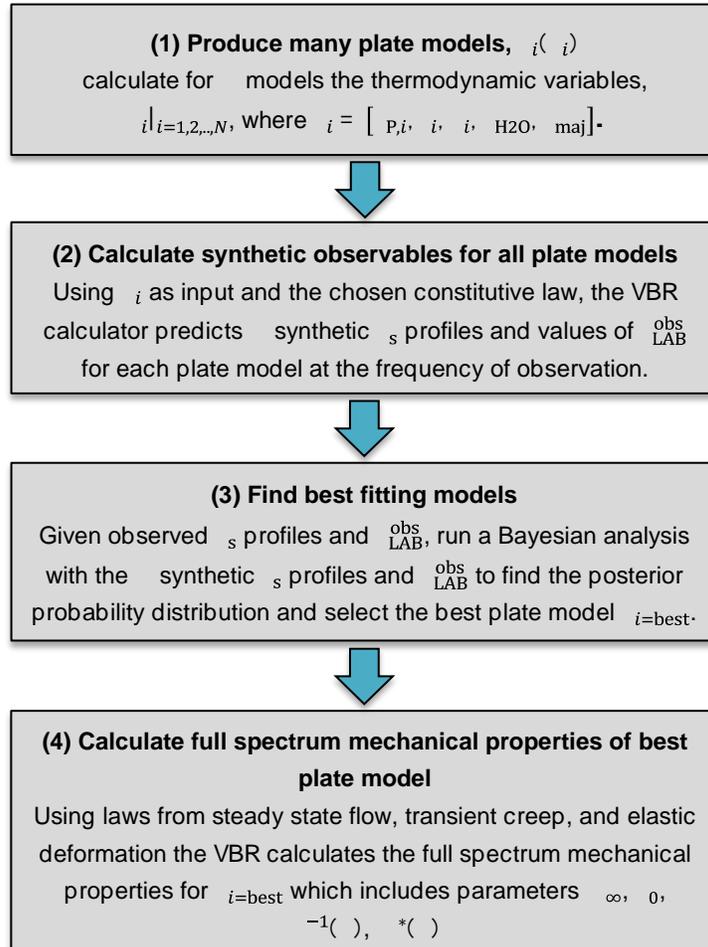


*note, these are not to scale

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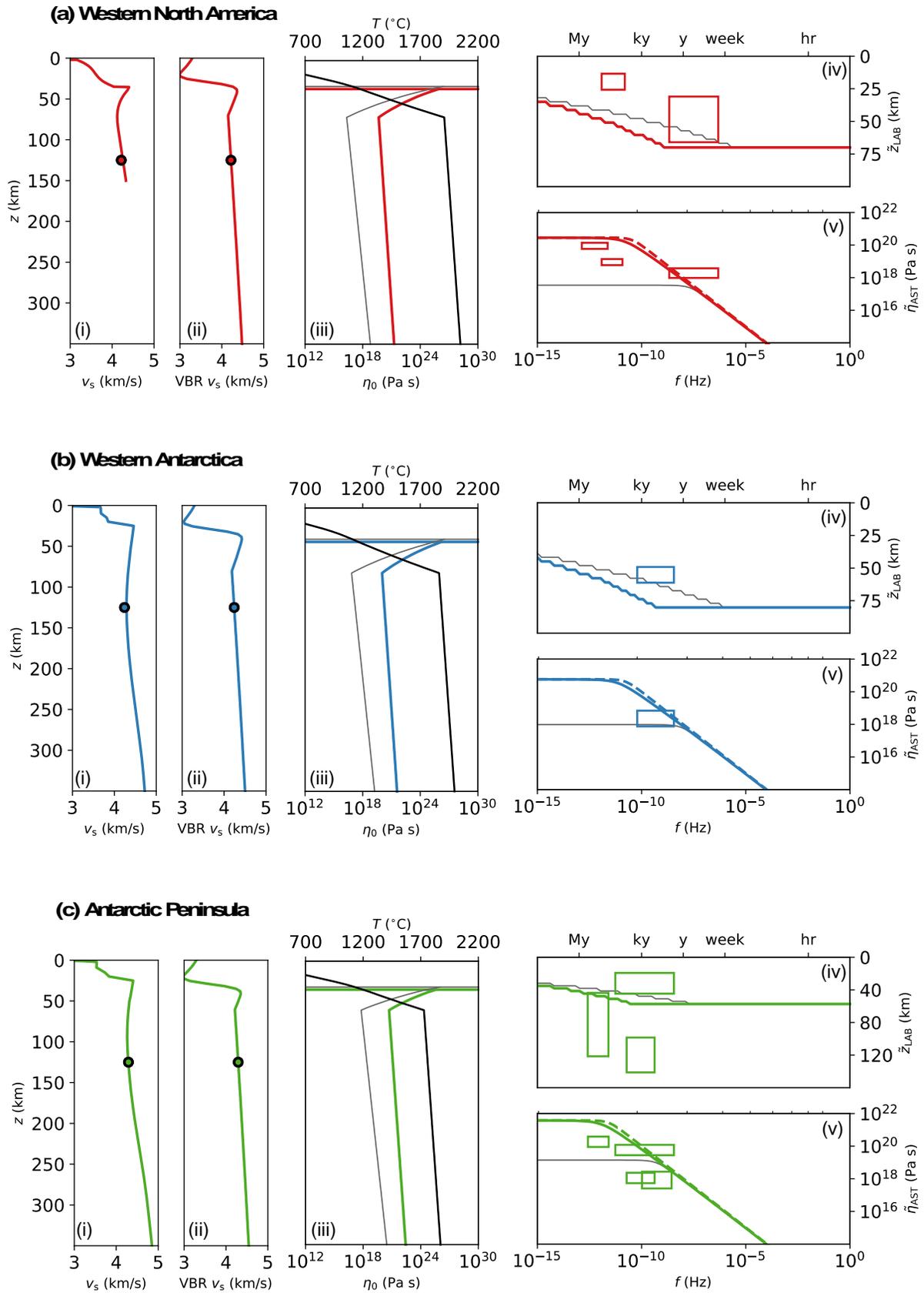
866 **Figure 4. Methodology for determining viscoelastic structure.**
 867 Schematic flowchart depicting the main steps in producing full spectrum viscoelastic structure at
 868 each case region (Section 2.2.1).

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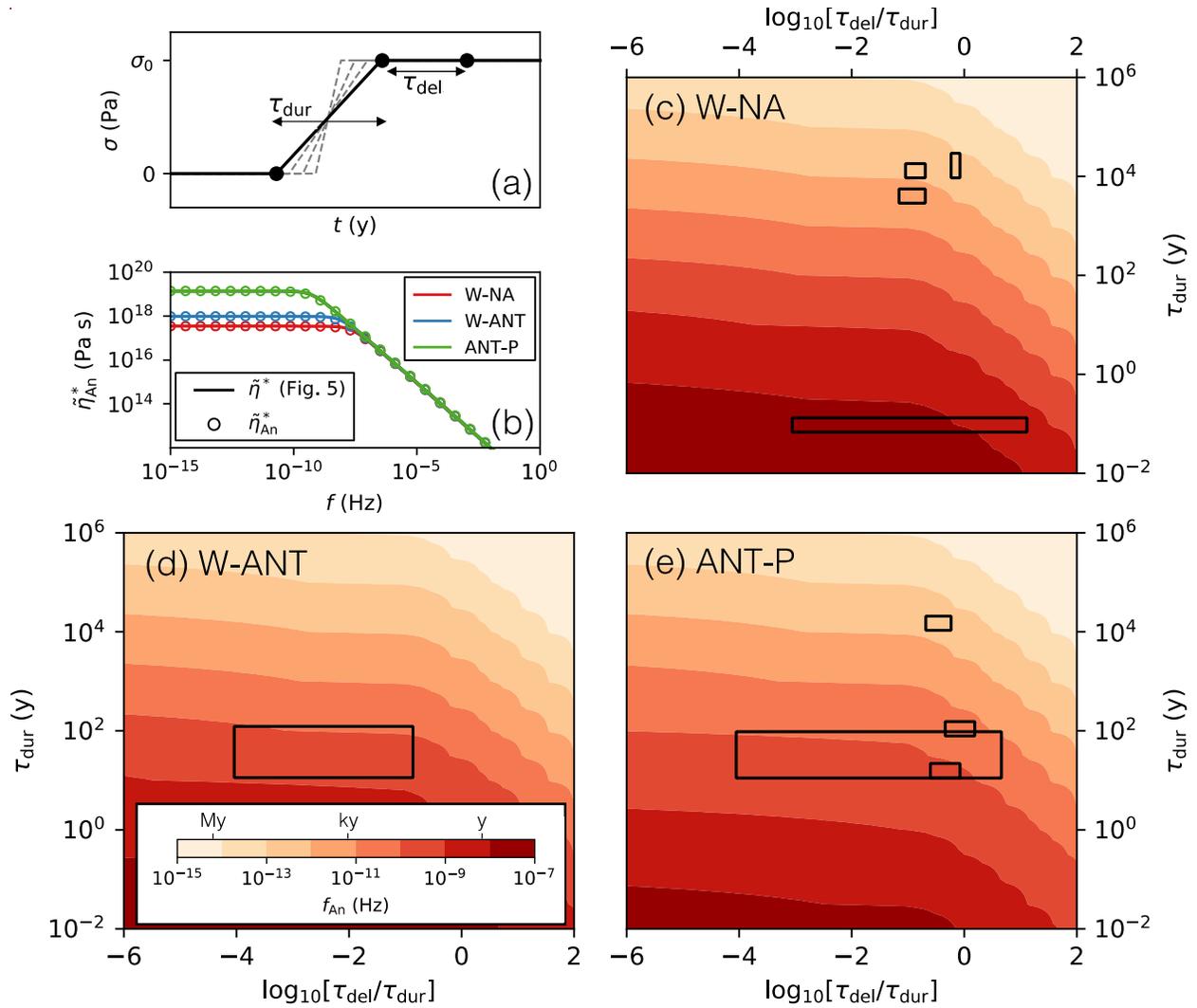
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875 **Figure 5. Resulting Thermodynamic and Mechanical Properties of Case Regions.**
876 | For each region **(a)**, **(b)**, **(c)**, subpanel **(i)** shows the shear wave-speed, v_S , profiles at select
877 | regions in Fig. 1(c,d) (averaged over a lateral radius of 50 km) from the tomographic models of
878 | Shen & Ritzwoller (2016) **(a)** and Lloyd et al. (2020) **(b,c)**. The orange shaded region marks the
879 | depth window across which we used the v_S data to constrain the sub-lithospheric temperature
880 | profile, where the circles mark the resulting averaged v_S to be fit. Subpanels **(ii-v)** are generated
881 | by the VBR fitting procedure (see Fig. 4 and Section 2.2.1), where **(ii)** shows the resulting best
882 | fit v_S while **(iii)** shows the associated temperature profile (solid black line). The following
883 | corresponding mechanical properties are, in subpanel **(iii)** the steady state viscosity η_0 , where the
884 | horizontal lines mark the base of the lithosphere; **(iv)** the apparent plate thickness, \tilde{z}_{LAB} , and **(v)**
885 | the apparent asthenospheric viscosity $\tilde{\eta}_{\text{AST}}$, as a function of frequency, f . Subpanels **(iv-v)** have
886 | been averaged in depth across the asthenosphere and the shaded regions mark the effect of
887 | including steady state dislocation creep across a stress range ($0 \leq \sigma \leq 10$ MPa). The colored
888 | solid and gray lines coincide with $\sigma = 0$ MPa and $\sigma = 1$ MPa, respectively. Within subpanels
889 | **(iv-v)**, we have placed the observationally derived estimates (boxes) from Fig. 1 where
890 | appropriate. The vertical gray shaded region spans the seismic band (within which we
891 | constrained the thermodynamic conditions) for comparison.
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895 **Figure 6. Converting time domain observations to the frequency domain**
 896 (a) Schematic depiction of applied stress history, $\sigma(t)$, labelling the two relevant timescales,
 897 τ_{dur} and τ_{del} . (b) The apparent viscosities for each region of the 1-D Andrade model that $\sigma(t)$ is
 898 applied to. The solid lines are reproduced from Fig. 5 (subpanels iii) and circles are the result of
 899 finding the best fitting Andrade parameters for each region. (c-e) For a given τ_{dur} and τ_{del} pair,
 900 the contours mark the frequency for which the estimated $\tilde{\eta}_{\text{est}}^*$ (assuming a Maxwell model) is
 901 equivalent to $\tilde{\eta}_{\text{An}}^*$ (i.e., where $\tilde{\eta}_{\text{est}}^* = \tilde{\eta}_{\text{An}}^*(f_{\text{An}})$). The boxes are the associated ranges for each
 902 observation we include (see Fig. 1).
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