

Entrainment and Dynamics of Ocean-derived Impurities within Europa's Ice Shell

J. J. Buffo^{1,2}, B. E. Schmidt¹, C. Huber³, and C. C. Walker⁴

¹Georgia Institute of Technology ²Dartmouth College ³Brown University ⁴Woods Hole Oceanographic Institution

Corresponding author: Jacob Buffo (jacob.j.buffo@dartmouth.edu)

Key Points:

- Planetary ices contain a chemical fingerprint of parent liquid reservoir thermochemical properties and dynamics
- Observable thermochemical heterogeneities in Europa's ice shell can be used to infer the geophysical evolution of the shell
- Constraining material entrainment and transport within planetary ices will aid in assessing the habitability of ice-ocean worlds

Abstract

Compositional heterogeneities within Europa's ice shell likely impact the dynamics and habitability of the ice and subsurface ocean, but the total inventory and distribution of impurities within the shell is unknown. In sea ice on Earth, the thermochemical environment at the ice-ocean interface governs impurity entrainment into the ice. Here, we simulate Europa's ice-ocean interface and bound the impurity load (1.053-14.72 ppt bulk ice shell salinity) and bulk salinity profile of the ice shell. We derive constitutive equations that predict ice composition as a function of the interfacial thermal gradient and ocean composition. We show that evolving solidification rates of the ocean and hydrologic features within the shell produce compositional variations (ice bulk salinities of 5-50% of the ocean salinity) that can affect ice's material properties. These results imply that ocean materials entrained within Europa's ice shell affect the formation of geologic terrain and could be resolved by future spacecraft observations.

Plain Language Summary

Europa, the second innermost moon of Jupiter, likely houses an interior ocean that could provide a habitat for life. This ocean resides beneath a ~10-30 km thick ice shell which could act as a barrier or conveyor for ocean-surface interactions thought to play a crucial role in facilitating the ocean's habitability. A key component of these ocean-surface interactions is the transport of ocean derived materials through the shell. Additionally, these ocean-derived impurities likely play a significant role in the geophysics of the moon's icy exterior. That said, little is known about the interior properties of the ice shell or ocean. On Earth, the characteristics and properties of ocean-derived ices are governed by their thermochemical environment at the time of their formation. Here we extend models of sea ice to accommodate the Europa ice-ocean environment and produce physically realistic predictions of Europa's ice shell composition and the thermochemical evolution of water bodies (fractures and lenses) within the shell. These results provide a method for relating observable ice characteristic to interior ocean properties and dynamics as well as a predictive tool for simulating the evolution of Europa's ice shell and water bodies. This has direct implications for assessing the moon's habitability, understanding the evolution of geophysical structures within the ice shell, and the interpretation of upcoming mission data (e.g. ice penetrating radar measurements made by Europa Clipper).

1. Introduction

Europa's ocean was the first detected beyond Earth [Khurana *et al.*, 1998; Kivelson *et al.*, 2000]. Studies [Cassen *et al.*, 1979; R Pappalardo *et al.*, 1999; Ross and Schubert, 1987; Squyres *et al.*, 1983] indicate that Europa's internal structure hosts a thick global ocean bounded by a silicate mantle below and a water ice shell above. These findings have fueled interest in the moon's interior dynamics, which may facilitate environments suitable for life [Board and Council, 2012; Chyba and Phillips, 2001; Des Marais *et al.*, 2008; Reynolds *et al.*, 1983; Russell *et al.*, 2017]. Europa's ice shell plays a crucial role in the moon's dynamics and evolution, as both a barrier and conveyor between the ocean and surface. Because most of the data available for Europa is derived from remote sensing techniques, the ice shell is a primary medium through which the properties of the ocean and interior can be understood, as the ice expresses how the body has evolved through its geology and composition. However, at present many of the ice shell's properties are not well constrained, including ice thickness, ice chemistry, and the distribution of shallow water [Billings and Kattenhorn, 2005; Schmidt *et al.*, 2011; Walker and Schmidt, 2015; Mikhail Y Zolotov and Shock, 2001]. Locating potentially habitable niches, understanding the transport processes

supporting them, investigating their connectivity, and constraining characteristics of the European environment are planned objectives of the Europa Clipper mission currently under development by NASA [Phillips and Pappalardo, 2014]. As such, quantifying the physical, thermal, chemical, and mechanical properties of the ice shell is imperative to understanding Europa's geophysical and material transport processes that control its habitability.

Heterogeneities in the ice shell have been linked to a number of proposed dynamic processes: solid state convection in the lower ice shell [Han and Showman, 2005; Howell and Pappalardo, 2018; McKinnon, 1999], subduction or subsumption of surface material [Johnson et al., 2017b; Kattenhorn, 2018; Kattenhorn and Prockter, 2014], eutectic melting that may lead to the formation of chaos and lenticulae [Manga and Michaut, 2017; Michaut and Manga, 2014; Schmidt et al., 2011], formation and sustenance of water bodies within the shell [Kargel et al., 2000; M Yu Zolotov and Kargel, 2009]. Yet the process by and rate at which impurities are entrained within the ice remain poorly constrained, and while current models implement a range of potential impurity loads to test model sensitivity to variations in ice composition [Han and Showman, 2005; Johnson et al., 2017a; R T Pappalardo and Barr, 2004] they do not predict ice composition directly. Furthermore, observations reveal that young, active terrain is richer in non-ice material than the average ice [McCord et al., 2002] (Supplementary Figure S1), suggesting recent interaction with subsurface water reservoirs enriched with salts [Manga and Michaut, 2017; Michaut and Manga, 2014; Schmidt et al., 2011], the effusion of ocean materials through fractures [Fagents, 2003], or melt through of a thin ice shell [Greenberg et al., 1999].

When ice forms in an aqueous environment, it preserves a thermochemical record of the water from which it formed [Feltham et al., 2006; Hunke et al., 2011; Turner and Hunke, 2015]. For Europa, the ice shell grew from the freezing of, and is thus a window into, the ocean. With a geologically young surface ($<10^8$ yr [Carr et al., 1998]) suggesting active ice shell overturn, dynamic regions of Europa's surface (e.g. bands and chaos) may harbor 'fossil ocean material' entrained in the ice shell as recently as 1Mya [Howell and Pappalardo, 2018]. This could provide an accessible sample of the contemporary ocean, as it is highly likely that Europa's ice, much like sea ice and marine ice on Earth, contains pockets and channels filled with brine, salts, gasses, and other impurities derived from the dynamics of freezing at the ice-ocean interface [Eicken, 2003; R T Pappalardo and Barr, 2004; M Yu Zolotov and Kargel, 2009; Zotikov et al., 1980] (See Figure 1). On Earth, sea ice captures such a record of the thermochemical processes in the upper ocean during its formation [Buffo et al., 2018]. As the ocean solidifies, dissolved solutes are rejected as crystalline ice forms and a porous water-ice matrix filled with hypersaline interstitial fluid is produced [Buffo et al., 2018; Feltham et al., 2006; Hunke et al., 2011; Turner and Hunke, 2015]. This process produces a compositionally-driven gravitational instability in the newly formed porous ice layer that results in buoyancy-driven convection of the denser pore fluid into the underlying liquid reservoir. Referred to as gravity drainage, this process has been observed to be the primary method of desalination during sea ice formation and has been successfully incorporated into a number of numerical models [Buffo et al., 2018; Griewank and Notz, 2013; Turner and Hunke, 2015; Wells et al., 2011].

Quantifying the relationship between Europa's ice composition and interfacial thermochemistry at the time of formation would provide a technique for linking observed ice properties to characteristics of its origin liquid water reservoir (a 'frozen fingerprint' of the source water) and forecasting the properties of ice produced under diverse thermal and chemical conditions – informing the synthesis of future mission data and geodynamic models. Impurities and structural heterogeneities within ice alter its thermal, physicochemical, and dielectric

properties [Feltham *et al.*, 2006; Hunke *et al.*, 2011; Weeks and Ackley, 1986]. Thus, beyond the ice shell's chemistry, the dynamics of impurity entrainment will affect the potentially appreciable, and ongoing, hydrological activity within Europa's ice shell in the form of perched water lenses, fractures, dikes, and sills [Manga and Michaut, 2017; Michaut and Manga, 2014; Schmidt *et al.*, 2011; Walker and Schmidt, 2015]. Moreover, interpretation of measurements taken by Europa Clipper's ice penetrating radar, REASON, depend critically on ice composition and dielectric properties [Kalousova *et al.*, 2017; Weeks and Ackley, 1986]. If the ice shell is impurity rich it has the potential to reflect and attenuate radar signals, which can be used to investigate the ice shell's interior structure but may also prevent observation of the ice-ocean interface [Kalousova *et al.*, 2017].

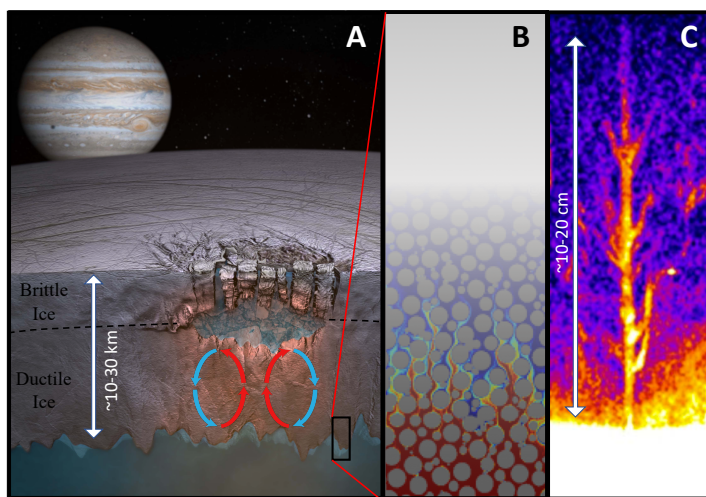


Figure 1 – The Europa ice-ocean system. A) A brittle ice lithosphere overlies a ductile ice mantle (dashed line) in contact with a subsurface ocean. A diapiir generated perched water lens is an example of a putative hydrological feature within the ice shell that may facilitate the surface expression of recently entrained ocean material. **B)** Akin to terrestrial environments, the ice-ocean interface of Europa will likely be characterized by a two-phase ice-brine system, allowing solutes and other ocean material to be trapped within pore spaces. **C)** Brine channels in terrestrial sea ice. (Image Credit: A – Adapted from Britney Schmidt/Dead Pixel FX, UT Austin. B – Adapted from Joaquín Jiménez-Martínez http://petrelharp.github.io/asn_2016/asn-2016-talk.html C – Adapted from [Worster and Rees Jones, 2015])

To constrain the impurity load within Europa's ice shell and investigate the possible dynamics associated with the presence of salt in the ice shell, we constructed a one-dimensional reactive transport model adapted from the sea ice model of [Buffo *et al.*, 2018] for the Europa environment. We performed simulations of the formation and evolution of Europa's ice shell, validated against empirical observations of sea ice and marine ice growth rates and composition. The simulations include fluid and solute transport and the associated impurity entrainment that occurs at ice-ocean/brine interfaces. The model actively tracks the dynamic ice-ocean/brine interface as it propagates and catalogs the composition of the ice as it becomes impermeable and traps solutes within the ice. Since the ice composition derives from the initial ocean, we test an array of putative European ocean chemistries and thermal regimes and derive constitutive relationships between entrainment rates and the local thermal and chemical environment.

2. Methods

2.1 Numerical Model

The growth and evolution of the ice-ocean/brine interface is treated using an adapted version of the one-dimensional, two-phase, reactive transport model of sea ice described by [Buffo *et al.*, 2018]. Water/ice mass, energy, and salinity are conserved using a coupled set of equations that combines mushy layer theory and the enthalpy method. The governing equations are:

$$\bar{\rho}c \frac{\partial T}{\partial t} = \left(\bar{k} \frac{\partial^2 T}{\partial z^2} \right) - \rho_{ice} L \frac{\partial \phi}{\partial t} \quad (1)$$

$$\phi \frac{\partial S_{br}}{\partial t} = \left(\bar{D} \frac{\partial^2 S_{br}}{\partial z^2} \right) - \frac{\rho_{ice}}{\rho_{br}} S_{br} \frac{\partial \phi}{\partial t} \quad (2)$$

$$H = c_{ice} T + L \phi \quad (3)$$

$$\phi = \begin{cases} 0 & H < H_s = c_{ice} T_m \\ (H - H_s)/L & \text{if } H_s \leq H \leq H_s + L \\ 1 & H > H_s + L \end{cases} \quad (4)$$

where ρ is density, c is specific heat capacity, T is temperature, t is time, z is the vertical coordinate, k is heat conductivity, L is the latent heat of fusion for the water to ice phase transformation, ϕ is liquid fraction, S is salinity, D is salt diffusivity, H is enthalpy, H_s is the enthalpy of a discretization cell consisting of only solid ice, and T_m is melting/freezing temperature. Subscripts *ice* and *br* refer to characteristics of the ice and brine components of the two-phase mixture, respectively, and variables carrying an over bar are volumetrically averaged quantities (i.e. $\bar{y} = \phi y_{br} + (1 - \phi) y_{ice}$). Equations 1 and 2 ensure conservation of heat and mass, respectively, and equations 3 and 4, combined, make up the enthalpy method. All variables and values used throughout the text can be found in Table 1.

The desalination of forming ice is governed by brine expulsion and gravity drainage. Brine expulsion refers to the phase change driven flux of hypersaline brine within the porous ice matrix into the underlying liquid reservoir. As a volume containing both ice and brine components continues to solidify, assuming incompressible flow, conservation of mass requires that brine must be expelled from the volume. This is due to the density difference between ice and water. Given the unidirectional solidification scenarios considered here, the brine will move downward into the ambient ocean/brine. Gravity drainage refers to the buoyancy-driven convective overturn of brine within the permeable multiphase layer. Both effects were considered by the model of Buffo *et al.* (2018); however, in line with previous research [Griewank and Notz, 2013; Wells *et al.*, 2011], gravity drainage was shown to be the primary mode of desalination. As such, with minimal loss of accuracy, we forego simulating phase change driven Darcy flow (brine expulsion) in the porous ice and opt to use the one-dimensional gravity drainage parameterization of [Griewank and Notz, 2013] to represent fluid transport. This parameterization represents the process of gravity drainage through brine channels as a linear function of the local Rayleigh number, and is widely used for solving multiphase melting/solidification problems [Griewank and Notz, 2013; Turner and Hunke, 2015; Turner *et al.*, 2013; Wells *et al.*, 2011]. Here, the mass of brine transported out of a multiphase layer j is given as:

$$br_j^\downarrow = \alpha(Ra_j - Ra_c)dz^3dt = \alpha\left(\frac{g\rho_{sw}\beta\Delta S_j\tilde{\Pi}h_j}{\kappa\mu} - Ra_c\right)dz^3dt \quad (5)$$

where α is a constant of proportionality, Ra_j is the Rayleigh number of the j th layer, Ra_c is the critical Rayleigh number, dz and dt are the spatial and temporal discretization sizes, respectively, g is acceleration due to gravity, ρ_{sw} is the density of the ambient reservoir fluid (ocean/brine), β is a density coefficient describing the relationship between density and salinity, ΔS_j is the difference in salinity of the brine from ambient fluid, h_j is the height of the j th layer above the basal surface of the ice, κ is the thermal diffusivity of seawater, μ is the kinematic viscosity of seawater, and $\tilde{\Pi}_j$ is the minimum permeability of any layer between the j th layer and the basal ice surface. The permeability function given by Griewank and Notz (2013) is utilized, and a critical porosity cutoff is implemented to prevent drainage from layers containing low liquid fractions (here $\phi < 0.05$ [K M Golden *et al.*, 2007] results in a layer's fluid transport being shut off). Heat and salt are transported out of the model domain by this convective process and the equations of mushy layer theory (Eq. 1 & 2) are modified accordingly (See [Buffo *et al.*, 2018] for details).

Symbol	Definition	Value	Units
α	1D Advection Coefficient	1.56×10^{-1}	$\text{kg m}^{-3} \text{s}^{-1}$
β	Density (Salinity) Coefficient	5.836×10^{-4}	kg ppt^{-1}
$br^{\uparrow,\downarrow}$	Vertical Brine Transport	Calculated	kg
c_{br}	Brine Heat Capacity	3985	$\text{J kg}^{-1} \text{K}^{-1}$
c_{ice}	Ice Heat Capacity	2000	$\text{J kg}^{-1} \text{K}^{-1}$
D	Salt Diffusivity	Calculated	$\text{m}^2 \text{s}^{-1}$
g	Acceleration Due to Gravity	1.32/9.8	m s^{-2}
h	Distance to Interface	Calculated	m
H	Ice Shell Thickness	Varies	km
H	Enthalpy	Calculated	J kg^{-1}
H_S	Enthalpy of Solid Cell	Calculated	J kg^{-1}
k_{br}	Brine Heat Conductivity	0.6	$\text{W m}^{-1} \text{K}^{-1}$
k_{ice}	Ice Heat Conductivity	2	$\text{W m}^{-1} \text{K}^{-1}$
κ	Thermal Diffusivity	Varies	$\text{m}^2 \text{s}^{-1}$
L, L_f	Latent Heat of Fusion	334,774	J kg^{-1}
λ	Coefficient Dependent on St	Calculated	-
μ	Kinematic Viscosity	1.88×10^{-3}	$\text{m}^2 \text{s}^{-1}$
ϕ	Liquid Fraction	Calculated	-
ϕ_c	Critical Porosity	0.05	-
Π	Permeability	Calculated	m^2
Ra	Rayleigh Number	Calculated	-
Ra_c	Critical Rayleigh Number	1.01×10^{-2}	-
ρ_{br}	Brine Density	Varies	kg m^{-3}
ρ_{ice}	Ice Density	917	kg m^{-3}
ρ_{sw}	Ocean/Reservoir Density	Varies	kg m^{-3}
S	Salinity	Calculated	ppt
S_{lim}	Minimum Salinity	Varies	ppt
S_{oc}	Ocean/Reservoir Salinity	Varies	ppt
S_{tot}	Bulk Salinity/Total Salt	Calculated	ppt
St	Stefan Number	Calculated	-
t	Time	-	s
T	Temperature	Calculated	K

T_0	Supercooled Temperature	Varies	K
T_1	Liquid Temperature	Varies	K
T_m	Melting/Freezing Temperature	Varies	K
T_{oc}	Ocean Temperature	Varies	K
T_s	Surface Temperature	100	K
v_m	Freezing Front Velocity	Calculated	m s ⁻¹
x_m	Freezing Front Position	Calculated	m
z	Vertical Coordinate	-	m

Table 1 – Variables. All variables used in the text, along with their definition, values, and units.

2.2 The Stefan Problem: Deriving the Constitutive Equations

The interpolation of results used to derive the constitutive relationships between ice characteristics and the thermochemical environment hinges on the ability to fit the simulated data to a predefined function. The form of this function should be representative of the physical processes occurring within the simulation. As the equations governing the multiphase reactive transport model do not lend themselves to an analytical solution, it is logical to seek a simplified system that does. To investigate the evolution of dissolved salt in an ice-ocean environment we make a number of simplifying assumptions and solve Equation 2 analytically.

The classic Stefan problem describes the dynamics and evolution of pure substance melting/solidification and is well documented in the literature [Huber *et al.*, 2008; Michaut and Manga, 2014; Rubinšteĭn, 2000]. The basic geometry of the problem can be seen in Supplementary Figure S2. In 1860 Carl Neumann found the analytical solution of the thermal profile in the solid and the time dependent solidification front to be [Huber *et al.*, 2008]:

$$T(x, t) = T_0 - (T_0 - T_1) \frac{\operatorname{erf}\left(\frac{x}{2\sqrt{\kappa t}}\right)}{\operatorname{erf}(\lambda)} \quad (6)$$

$$x_m(t) = 2\lambda\sqrt{\kappa t} \quad (7)$$

$$\lambda \exp(\lambda^2) \operatorname{erf}(\lambda) = \frac{St}{\sqrt{\pi}} = \frac{c(T_0 - T_1)}{L_f \sqrt{\pi}} \quad (8)$$

where $T(x, t)$ is the temperature within the solid at position x and time t , T_0 is the temperature at the undercooled surface and is lower than the melting temperature of the solid, T_1 is the temperature of the liquid, κ is the thermal diffusivity of the solid, x_m is the position of the solidification front, λ is a coefficient depending on St , erf is the error function, St is the Stefan number defined as $St = c(T_0 - T_1)/L_f$, c is the specific heat of the solid, and L_f is the latent heat of fusion for the water-ice phase transition.

While the Stefan problem represents a simpler system than that of our reactive transport model, the underlying physics governing solidification are the same and similar behavior is to be expected. It has been suggested that the amount of impurities entrained in forming ice is related to the rate at which the ice forms [Masayoshi Nakawo and Sinha, 1984; Weeks and Ackley, 1986; M Yu Zolotov and Kargel, 2009]. Equations 6-8 can be utilized to investigate the relationships between the rate of ice formation and both the freezing front position and local thermal gradient. First, differentiating Equation 7 with respect to time gives:

$$v_m(t) = \dot{x}_m(t) = \frac{\lambda\kappa}{\sqrt{\kappa t}} = \frac{2\lambda^2\kappa}{x_m(t)} \quad (9)$$

$$\Rightarrow v_m(t) \propto \frac{1}{x_m(t)} \quad (10)$$

where $v_m(t)$ is the solidification front velocity, which is equivalent to the rate of ice formation. This suggests that the rate of ice formation is inversely proportional to the position of the solidification front. Second, differentiating Equation 6 with respect to position gives:

$$\frac{\partial T(x, t)}{\partial x} = -\frac{(T_0 - T_1)}{\text{erf}(\lambda)} \frac{1}{\sqrt{\pi\kappa t}} \exp(-x^2/4\kappa t) \quad (11)$$

At the position of the solidification front, $x_m(t) = 2\lambda\sqrt{\kappa t}$, Equation 11 becomes:

$$\frac{\partial T(x_m, t)}{\partial x} = -\frac{(T_0 - T_1)}{\text{erf}(\lambda)} \frac{1}{\sqrt{\pi\kappa t}} \exp(-\lambda^2) \quad (12)$$

From Equation 9 we see that $\sqrt{\kappa t} = \lambda\kappa/v_m(t)$. Substituting this result into Equation 12 gives:

$$\frac{\partial T(x_m, t)}{\partial x} = -\frac{(T_0 - T_1)}{\text{erf}(\lambda)} \frac{1}{\sqrt{\pi}\lambda\kappa} \exp(-\lambda^2) v_m(t) \quad (13)$$

$$\Rightarrow \frac{\partial T(x_m, t)}{\partial x} \propto v_m(t) \quad (14)$$

Suggesting that the rate of ice formation is directly proportional to the local thermal gradient at the solidification front. The relationships derived in Equations 10 & 14 provide insight into the spatiotemporal evolution of the Stefan problem and its dependence on the local thermal environment. These results will be utilized below, where a modified Stefan problem (inclusion of a solute and fluid dynamics) is described and an analytical solution is derived. This solution describes the spatial and temporal distribution of the solute and provides the functional form of the constitutive equations used throughout the text.

To investigate the evolution of dissolved salt in an ice-ocean environment we make a number of simplifying assumptions and solve Equation 2 analytically. Assuming top-down unidirectional solidification of a salty ocean (e.g. sea ice, European ocean solidification) the evolution of salt in the system can be described by the equations of reactive transport (Equation 2 including the gravity drainage parameterization, with br subscripts dropped from S terms for simplicity):

$$\phi \frac{\partial S}{\partial t} = \left(\bar{D} \frac{\partial^2 S}{\partial z^2} \right) - \frac{\rho_{ice}}{\rho_{br}} S \frac{\partial \phi}{\partial t} + br_j^\downarrow \frac{\partial S}{\partial z} \quad (15)$$

where br_j^\downarrow is the brine velocity in the j th layer described by the one-dimensional gravity drainage parameterization. Introducing a new coordinate, ξ , such that $\xi = z - z_m(t)$, places the origin at the ice-ocean interface and constitutes a moving coordinate system. In this new coordinate system Equation 15 can be written as:

$$\phi \frac{\partial S}{\partial \xi} \frac{\partial \xi}{\partial t} = \bar{D} \left[\frac{\partial^2 S}{\partial \xi^2} \left(\frac{\partial \xi}{\partial z} \right)^2 + \frac{\partial S}{\partial \xi} \frac{\partial^2 \xi}{\partial z^2} \right] - \frac{\rho_{ice}}{\rho_{br}} S \frac{\partial \phi}{\partial \xi} \frac{\partial \xi}{\partial t} + br_j^\downarrow \frac{\partial S}{\partial \xi} \frac{\partial \xi}{\partial z} \quad (16)$$

Rearranging Equation 16:

$$-\bar{D} \left[\frac{\partial^2 S}{\partial \xi^2} \left(\frac{\partial \xi}{\partial z} \right)^2 + \frac{\partial S}{\partial \xi} \frac{\partial^2 \xi}{\partial z^2} \right] - br_j^\downarrow \frac{\partial S}{\partial \xi} \frac{\partial \xi}{\partial z} + \phi \frac{\partial S}{\partial \xi} \frac{\partial \xi}{\partial t} = -\frac{\rho_{ice}}{\rho_{br}} S \frac{\partial \phi}{\partial \xi} \frac{\partial \xi}{\partial t} \quad (17)$$

Taking the appropriate spatial and temporal derivatives of ξ and substituting their values into Equation 17 gives:

$$-\bar{D} \frac{\partial^2 S}{\partial \xi^2} - (br_j^\downarrow + \phi v_m(t)) \frac{\partial S}{\partial \xi} = v_m(t) \frac{\rho_{ice}}{\rho_{br}} S \frac{\partial \phi}{\partial \xi} \quad (18)$$

For simplicity, we assume that $\phi(\xi) = H(\xi)$, where $H(\xi)$ is the Heaviside step function. While this is indeed a simplification, as it represents the mushy layer as an infinitesimally thin regime, the general liquid fraction profile of evolving sea ice demonstrates similar structure (See Figures 5-7 of Buffo et al., 2018). Substituting $\phi(\xi) = H(\xi)$ into Equation 18 results in a simplified conservation of mass equation in the moving coordinate system:

$$-\bar{D} \frac{\partial^2 S}{\partial \xi^2} - (br_j^\downarrow + \phi v_m(t)) \frac{\partial S}{\partial \xi} = v_m(t) \frac{\rho_{ice}}{\rho_{br}} S \delta(\xi) \quad (19)$$

where $\delta(\xi)$ is the delta function. Equation 19 can be solved using Fourier transforms. Let the transform variable be χ , such that:

$$S(\chi) = \mathcal{FT}[S(\xi)] = \int_{-\infty}^{\infty} S(\xi) \exp(-i2\pi\chi\xi) d\xi \quad (20)$$

$$S(\xi) = \mathcal{FT}^{-1}[S(\chi)] = \int_{-\infty}^{\infty} S(\chi) \exp(i2\pi\chi\xi) d\chi \quad (21)$$

Applying the Fourier transform to Equation 19 gives:

$$4\pi^2 \chi^2 \bar{D} S(\chi) - i2\pi\chi (br_j^\downarrow + \phi v_m(t)) S(\chi) = v_m(t) \frac{\rho_{ice}}{\rho_{br}} S(\xi = 0, t) \quad (22)$$

Equation 22 has the solution:

$$S(\chi) = S(\chi, t) = \frac{v_m(t) \frac{\rho_{ice}}{\rho_{br}} S(\xi = 0, t)}{4\pi^2 \chi^2 \bar{D} - i2\pi\chi (br_j^\downarrow + \phi v_m(t))} \quad (23)$$

Taking the inverse Fourier transform of Equation 23 gives:

$$S(\xi, t) = \int_{-\infty}^{\infty} \left[\frac{v_m(t) \frac{\rho_{ice}}{\rho_{br}} S(\xi = 0, t)}{4\pi^2 \chi^2 \bar{D} - i2\pi\chi (br_j^\downarrow + \phi v_m(t))} \right] \exp(i2\pi\chi\xi) d\chi \quad (24)$$

$$= \frac{v_m(t) \frac{\rho_{ice}}{\rho_{br}} S(\xi = 0, t)}{(br_j^\downarrow + \phi v_m(t))} \left[\pm 1 \mp \exp \left(\frac{-\pi\xi (br_j^\downarrow + \phi v_m(t))}{\bar{D}} \right) \right] \quad (25)$$

Throughout this work we seek constitutive equations that relate the amount of salt entrained in forming ice to depth and local thermal gradient. Using the relationships of Equations 10 & 14, the definition of $\xi = z - z_m(t)$, and assuming in the active mushy layer near the ice-ocean interface, where reactive transport is possible, $z \sim z_m(t)$, we can rewrite Equation 25 in two forms:

$$S_{tot}(z_m) \propto \frac{1}{z_m} [1 - \exp(-z_m)] \quad (26)$$

$$S_{tot} \left(\frac{\partial T}{\partial z} \right) \propto \frac{\frac{\partial T}{\partial z}}{1 + \frac{\partial T}{\partial z}} \left[1 - \exp \left(-1 / \frac{\partial T}{\partial z} \right) \right] \quad (27)$$

where the first term on the right-hand side of each equation is a diffusion term which dominates at later times (deeper depths, lower thermal gradients) and the second term is an advection-reaction term which dominates at early times (shallower depths, larger thermal gradients). Together, Equations 26 & 27 provide the functional forms for the constitutive equations produced throughout the remainder of the text.

3. Results

3.1 Salt Entrainment on Earth

Two types of ice present on Earth provide the best end-member analogs for Europa's ice shell: sea ice and marine ice. Here, sea ice refers to frozen seawater at the ocean's surface, while marine ice is seawater-derived ice which has accreted onto the basal surface of meteoric ice shelves (e.g. [Zotikov *et al.*, 1980]). While both ices form via the directional solidification of seawater, and thus undergo the same dynamics during their formation, they form under different thermal regimes, resulting in unique compositional and physical structure. Sea ice provides the upper limit of impurity entrainment and an ideal analog for ice formed along steep thermal gradients near Europa's surface, as its formation is driven by rapid heat loss to the cold polar atmosphere. Fortunately, there exists nigh on a century's worth of observations and quantitative measurements regarding vertical heterogeneities in the thermal, chemical, and microstructural properties of sea ice [Malmgren and Institut, 1927]. With the proximity of the 100 K surface, a young, thin European

ice shell (tens to hundreds of meters thick) as well as any newly emplaced shallow liquid water features within the contemporary ice shell will experience similarly high thermal gradients, suggesting high impurity uptake akin to that of sea ice. We have previously modeled the annual growth of sea ice to study its thermochemical evolution and ability to record variations in ocean characteristics through the reproduction of ice core properties [Buffo *et al.*, 2018]. This model was adapted to actively track the advancing ice-ocean interface and accommodate potentially diverse ocean chemistries. In Figure 2, we present model results for sea ice and compare these to empirical measurements of depth dependent sea ice bulk salinity [M Nakawo and Sinha, 1981; Notz and Worster, 2009]. Actively tracking the evolution of the ice-ocean interface and simulating small-scale solute transport within the porous ice produces bulk salinity profiles that agree well with observations. We achieve salinity profiles that exhibit the characteristic ‘c-shape’ typical of first-year sea ice, represented by the ‘MARCH’ profile of Figure 2b [Malmgren and Institut, 1927], and reproduce the bulk salinity values observed in the field. Based on the constitutive relationship between depth and bulk salinity (Eq. 10), we use an inverse fit to the simulated values to extend the profile to the upper portion of the ice where extreme temperature gradients affect numerical stability when using a Neumann boundary condition. Thus, our model captures the physical processes that occur during ice formation in high thermal gradient environments, which will govern the formation of ice near Europa’s surface.

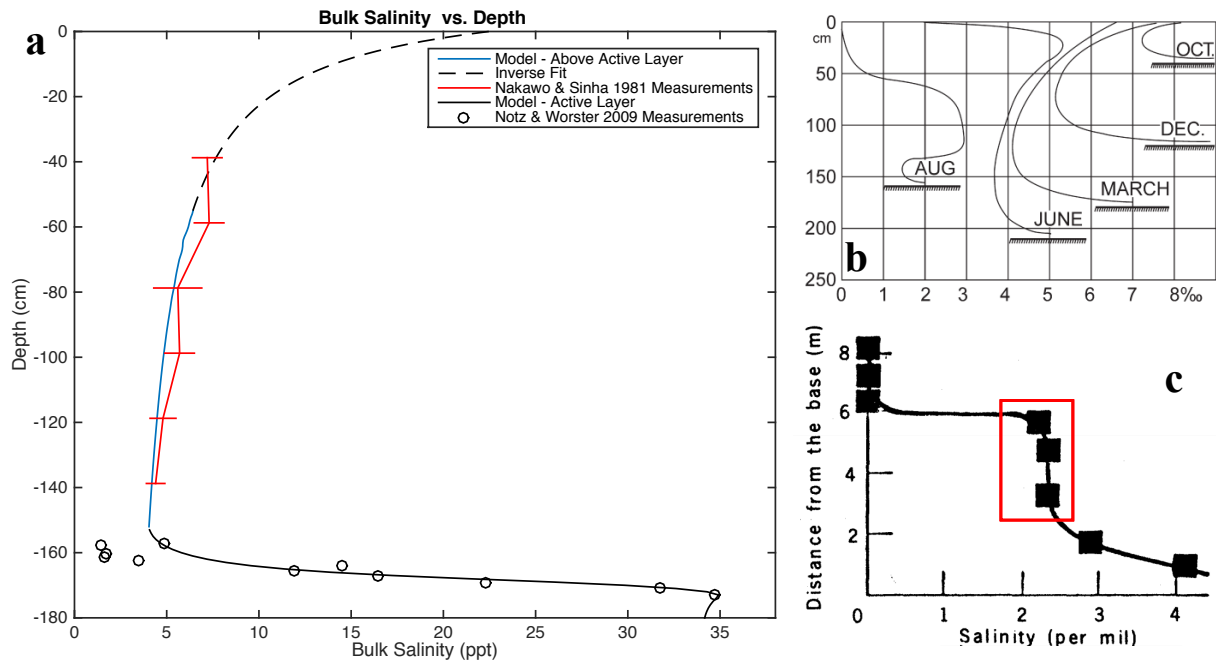


Figure 2: Salinity profiles within observed and modeled marine and sea ice. a) Modeled (blue and black solid lines), empirical (red line [M Nakawo and Sinha, 1981] and black circles [Notz and Worster, 2009]), and interpolated (black dashed line) bulk salinity profiles of sea ice. The numerical model assumes a preexisting 50 cm thick layer of sea ice in conductive equilibrium (linear temperature profile) with an atmospheric temperature of 250K and an ocean temperature of 271.5K. A conductive heat flux is maintained throughout the simulation at the upper boundary. The model was run for 1.5×10^7 sec (~ 174 days, a typical sea ice annual cycle) with a time step of 100 sec. The dashed line is the product of a Levenberg-Marquardt algorithm fit to the function $S(z) = a + b/(c - z)$, where S is bulk salinity, z is depth, and a , b , and c are constants, applied to the modeled bulk salinities above the active layer (blue solid line). While all of the bulk salinity values (blue and black solid lines) are a byproduct of the same model simulation, values in the active layer (black solid line) are excluded from the Levenberg-Marquardt fit (black dashed line) as the constitutive equations (Table 3) are derived assuming an infinitesimally thin mushy layer. **b)** Typical first-year sea ice

salinity profiles have a characteristic ‘c’ shape where the bulk salinity evolves over the season due to material transport and ice growth (from [Malmgren and Institut, 1927]). c) Bulk salinity measurements from the bottom 8 m of an ice core extracted from the Ross Ice Shelf by [Zotikov *et al.*, 1980]. The bottom 6 m is accreted marine ice, with the ‘asymptotic region’ outlined in red approaching diffusive equilibrium during ice formation.

Conversely, as thermal gradients decrease, ice composition approaches an asymptotic lower limit governed by the critical porosity of the active layer when it is in diffusive equilibrium with the underlying ocean. Here, critical porosity is analogous to a percolation threshold, where regions with porosities below this limit are no longer hydraulically connected to the surrounding pore network and any remaining salt is trapped in discrete brine pockets. Much of Europa’s deeper ice shell, below about 1 km, will have formed under these conditions. A similar environment exists at the base of deep ice on Earth, called marine ice [Zotikov *et al.*, 1980]. This unique, and less studied, variety of ocean-derived ice forms on the basal surface of terrestrial ice shelves due to much lower thermal gradients than typical open ocean sea ice (e.g. ~ 10 K/m for surficial sea ice; ~ 0.08 K/m for marine ice [Zotikov *et al.*, 1980]) leading to greatly reduced growth rates (~ 2 cm/yr [Zotikov *et al.*, 1980]). While the thermal gradients present in the marine ice system (~ 0.08 K/m) exceed the upper estimates for a thin (5-10 km) European ice shell (~ 0.02 K/m) [McKinnon, 1999; Mitri and Showman, 2005], they represent the best terrestrial analog of basally accreting ice in this thermal regime, and it can be shown that impurity entrainment has already approached its lower limit – characterized by asymptotic bulk salinity profiles (Figure 2c). Adopting a critical porosity of $\phi_c = 0.05$, based on observations of sea ice permeability [K Golden *et al.*, 1998; K M Golden *et al.*, 2007], and assuming an ocean salinity, $S_{oc} = 34$ ppt, the theoretical lower limit for salt entrainment into terrestrial ice (diffusive equilibrium when impermeability is reached) is given by $S_{lim} = \phi_c S_{oc} = 1.70$ ppt. The average bulk salinity of the ‘asymptotic region’ seen in Figure 2c is 2.32 ppt. Utilizing the constitutive equation for bulk salinity versus thermal gradient derived in the next section for terrestrial seawater in the diffusive regime ($dT/dz = 0.08$ K/m), a bulk salinity of 1.95 ppt is predicted. The difference of 0.37 ppt between the observed and predicted bulk salinity values translates to a 16% error, attributed to small variations in unconstrained parameters, such as critical porosity and permeability-porosity relationships (both of which can appreciably affect impurity entrainment rates [Buffo *et al.*, 2018]). The efficiency of brine migration through the porous ice lattice and the threshold at which percolation is possible are poorly constrained [K Golden *et al.*, 1998; K M Golden *et al.*, 2007; Wells *et al.*, 2011] but govern the dynamics of multiphase flow, brine retention in the ice, and ultimately ice composition. At the ice-ocean/brine interface, reduced permeability or a larger critical porosity would lead to more salt being entrained in the ice. Alternately, enhanced permeability or a smaller critical porosity would result in less salt entrainment. Nevertheless, our model closely reproduces observations of sea ice, and the same multiphase reactive transport physics applied in low-thermal gradient conditions match observations of marine ice composition, which capture broadly the two thermochemical regimes that ice on Europa is expected to occupy.

3.2 The Role of Thermal Gradients and Ocean Chemistry

Aside from the different surface temperature (< 110 K vs ~ 250 K), gravity (1.32 vs 9.81 m/s²) and potential compositional characteristics between Europa and Earth, one of the largest differences is sheer scale of the ice. While the majority of sea ice exhibits a maximum thickness of < 10 m [Kurtz and Markus, 2012; Laxon *et al.*, 2013] (ice drafts have been known to exceed 25 m and reach up to 47 m beneath pressure ridges [Davis and Wadhams, 1995; Lyon, 1961]) and marine ice accretion occurs at depths < 1.5 km [Craven *et al.*, 2009; Galton - Fenzi *et al.*, 2012;

Zotikov *et al.*, 1980], Europa's ice shell is likely 10-30 km thick [Billings and Kattenhorn, 2005; F Nimmo *et al.*, 2003; Tobie *et al.*, 2003]. It is important to note, however, that despite differences in ice thickness, all ice-ocean interfaces will remain at or near their pressure melting point, which for a 1.5 km thick terrestrial ice shelf is comparable to an ~11.1 km thick European ice shell. Modeling the entire ice shell thickness and lifespan at the resolution needed to capture the reactive transport dynamics occurring near the ice-ocean/brine interface is computationally intractable. To overcome these difficulties, we modified our model [Buffo *et al.*, 2018] such that it actively tracks only the permeable or 'active' region of the ice shell, determined by the critical porosity where fluid flow ceases [K Golden *et al.*, 1998; K M Golden *et al.*, 2007]. In the top-down solidification scenarios modeled, when the fluid fraction of a discretized layer drops below the critical porosity it is removed from the active domain and its properties are cataloged, along with all the cells above it, and an equal number of replacement layers are added to the bottom of the domain with ambient ocean/brine characteristics (T_{oc} , S_{oc} , ρ_{sw}). Model runs are initiated with the domain completely filled by one of the ocean chemistries investigated at a temperature just above its freezing point (Supplementary Section S1). The top boundary is governed by a Neumann boundary condition with a no-flux condition set for salt and it is assumed that the overlying ice is in conductive thermal equilibrium [McKinnon, 1999] (i.e. $dT/dz = (T_{oc} - T_s)/H$). The bottom boundary is governed by a Dirichlet boundary condition and is simulated as being in contact with an infinite ambient ocean/brine reservoir (T_{oc} , S_{oc} , ρ_{sw}) (for additional information on code functionality see [Buffo *et al.*, 2018]). To construct the full ice shell from discrete model runs, several simulations at various depths (solidification front locations) run in parallel, and the results are combined to produce the constitutive relationships that relate ice composition to its thermochemical environment at the time of formation. It is important to note that the top-down unidirectional solidification of Europa's ice shell from a quiescent ocean is likely a simplification as the aqueous differentiation of its juvenile planetesimal was likely a tumultuous and complex process [Kargel *et al.*, 2000]. This formation scenario was selected as it mirrors the formation of sea and marine ice, the only benchmarks available for the formation of ocean-derived ices. Moreover, the functional forms of the constitutive equations are derived under such conditions, requiring simulations of this type to derive the bulk salinity-thermal gradient relationships paramount to the remainder of the manuscript (e.g. basal fracture and perched lens solidification).

Composition of the ocean is critical to ice formation because of the relationship between the salinity of water and its freezing point. The conductive nature of Europa's ocean [Khurana *et al.*, 1998; Kivelson *et al.*, 2000], as well as spectrographic measurements [McCord *et al.*, 1999], suggests the presence of dissolved salts, but nearly all of its intrinsic properties (thickness, composition, structure) remain poorly constrained. Potential European ocean chemistries have been explored in a number of studies [Vance *et al.*, 2016; M Yu Zolotov and Kargel, 2009; Mikhail Y Zolotov and Shock, 2001]. Here we implement the chemistry proposed by [Mikhail Y Zolotov and Shock, 2001], who assumed that Europa's ocean formed during its differentiation via partial aqueous extraction from bulk rock with the composition of CV carbonaceous chondrites (Table 2). Alternate formation materials (e.g. CI chondrites [M Yu Zolotov and Kargel, 2009]) will alter the predicted ionic composition of the ocean, and variable molecular diffusivities, atomic masses, and v'ant Hoff factors may affect impurity entrainment rates in associated ocean-derived ices. For comparison, we also considered an ocean composition identical to terrestrial seawater (Table 2). Well-known liquidus curves exist for terrestrial seawater [Commission, 2010]. However, the freezing behavior of potentially more exotic European ocean compositions is comparatively less well known, so we constructed a new software package, Liquidus 1.0, to derive quadratic liquidus

curves for any chemistry supported by the equilibrium chemistry package FREZCHEM 6.2, which includes a wide range of material properties for the expected non-ice components of brines (Supplementary Section S1).

Species	Terrestrial Seawater (mol/kg)	European Ocean (mol/kg)
Na^+	4.69×10^{-1}	4.91×10^{-2}
K^+	1.02×10^{-2}	1.96×10^{-3}
Ca^{2+}	1.03×10^{-2}	9.64×10^{-3}
Mg^{2+}	5.28×10^{-2}	6.27×10^{-2}
Cl^-	5.46×10^{-1}	2.09×10^{-2}
SO_4^{2-}	2.82×10^{-2}	8.74×10^{-2}
Total Salt (ppt)	34	12.3

Table 2 – Ocean compositions. List of ion species and relative abundances for terrestrial seawater [Dickson and Goyet, 1994] and the proposed European ocean chemistry of [Mikhail Y Zolotov and Shock, 2001].

We forego simulating the possible precipitation of hydrated salts (e.g. mirabilite ($\text{Na}_2\text{SO}_4 \cdot 10\text{H}_2\text{O}$) [Butler et al., 2016], epsomite ($\text{MgSO}_4 \cdot 7\text{H}_2\text{O}$), meridianiite ($\text{MgSO}_4 \cdot 11\text{H}_2\text{O}$) [McCarthy et al., 2011; McCarthy et al., 2007]) for two reasons. First, implementing reactive transport modeling to simulate the evolution of ice-ocean worlds is a relatively novel approach, thus it is logical to begin with the simpler ice-brine binary system (as opposed to the ice-brine-hydrate ternary system), to both validate the approach and obtain a first order understanding of how salts are entrained in planetary ices. Second, the low thermal gradients experienced throughout much of the shell will facilitate slow ice growth, allowing for the dissipation of salt from high salinity regions via both convection and diffusion, preventing saturation and precipitation. Future work investigating ternary systems could reveal additional bulk salinity profile structure in the shallow ice shell brought about by the precipitation of such hydrated salts.

We simulated Europa's ice shell growth at eight discrete ice thicknesses (10 m, 50 m, 75 m, 100 m, 150 m, 200 m, 250 m, and 300 m), for four different hypothetical ocean compositions (European Ocean 12.3 ppt/100 ppt/282 ppt and Terrestrial Seawater 34 ppt). By the time the ice shell reaches 300 m in thickness the thermal gradient at the ice-ocean interface is shallow enough that the bulk salinity curve becomes asymptotic and variations in the salt entrainment rate will be minimal at all greater depths. This asymptotic lower limit is set by the ocean composition and critical porosity ($S_{lim} = \phi_c S_{oc}$). Simulations of larger ice thicknesses (>300 m) were therefore excluded, given the predicted ice composition below 300 m would vary by <1 ppt (see the first row of Table 3 and the following paragraph). European ocean concentrations were selected to bound the best estimates available from theory and observation: the most comprehensive estimate provided from theoretical calculations is 12.3 ppt [Mikhail Y Zolotov and Shock, 2001], while the saturation point of the same fluid would reach an ocean salinity of 282 ppt, and the upper limit based on the Galileo magnetometer data estimates a salinity of 100 ppt [Hand and Chyba, 2007]. The results for all ocean compositions can be seen in Figure 3 and Supplementary Figure S4. The results are depth-dependent and thermal gradient-dependent bulk salinity profiles, which are then interpolated using a Levenberg-Marquardt algorithm fit to the constitutive equations, the explicit form of which, including the coefficients needed to accommodate stretches and translations, are shown in Table 3.

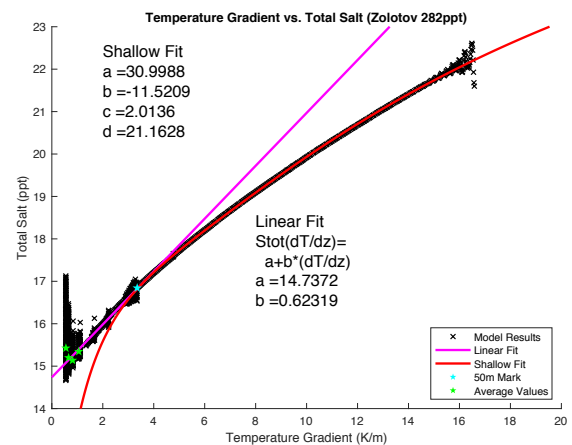
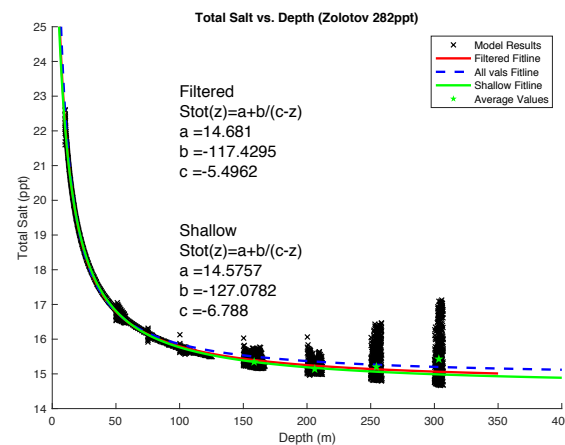
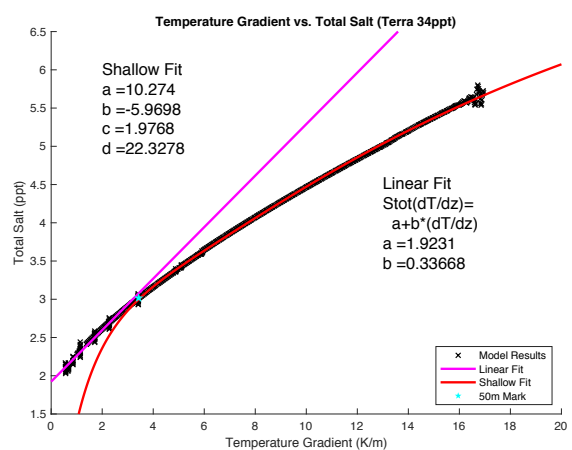
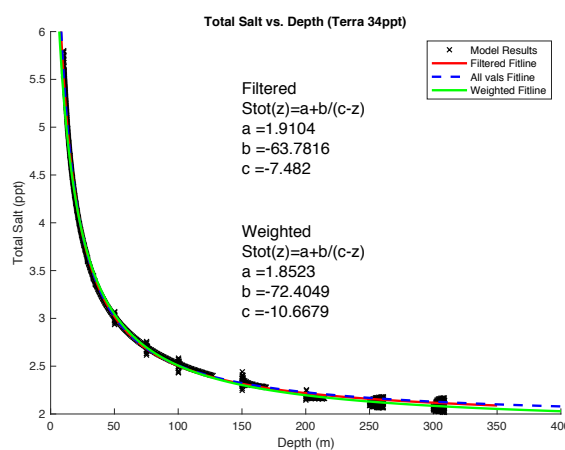
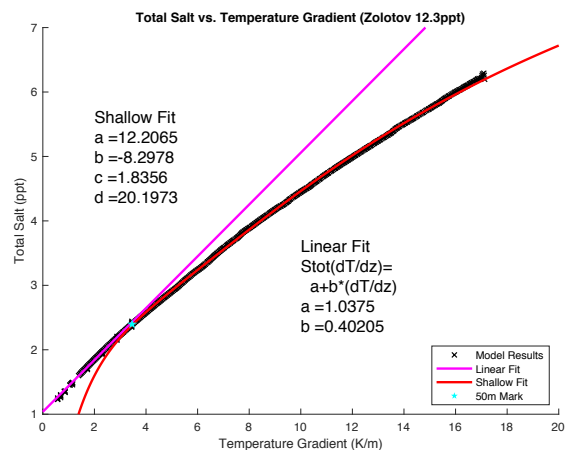
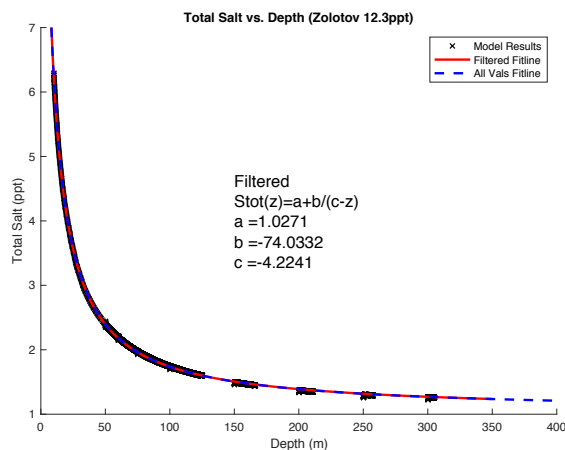


Figure 3: Simulations of depth dependent and thermal gradient dependent bulk salinity for three different ocean chemistries (100 ppt simulation is presented in Figure S4) Relationships are fit by the constitutive equations of Table 3. **Left Column**, Model results [black exes] (numerical dispersion at the onset of each run has been removed) and original (all values), filtered (numerical dispersion at run onset removed), weighted (where applicable – weighted by data density), and shallow (where applicable – fitting model results from 10-200 m runs) fit lines [blue dashed line, red line, and green lines, respectively]. **Right Column**, Simulated results [black exes] as well as linear and ‘Shallow’ (See Table 3) fit lines [pink and red lines, respectively]. Green stars represent average bulk salinity for an entire run at a given depth – highlighting that the majority of the simulated data lies near the fit lines, even when scatter is present. Blue stars identify the thermal gradient associated with a 50 m depth within an equilibrated conductive ice shell, which is the transition point between the diffusive and advective-reactive regimes.

Constitutive Equation	a	b	c	d
$S_{tot}(z) = a + \frac{b}{(c - z)}$	a _{12.3} =1.0271 a ₁₀₀ =5.38 a ₂₈₂ =14.681 a ₃₄ =1.8523	b _{12.3} =-74.0332 b ₁₀₀ =-135.096 b ₂₈₂ =-117.429 b ₃₄ =-72.4049	c _{12.3} =-4.2241 c ₁₀₀ =-8.2515 c ₂₈₂ =-5.4962 c ₃₄ =-10.6679	
$S_{tot}\left(\frac{\partial T}{\partial z}\right) = a + b \frac{\partial T}{\partial z}$	a _{12.3} =1.0375 a ₁₀₀ =5.4145 a ₂₈₂ =14.737 a ₃₄ =1.9231	b _{12.3} =0.40205 b ₁₀₀ =0.69992 b ₂₈₂ =0.62319 b ₃₄ =0.33668		
(Shallow Fit Line) $S_{tot}\left(\frac{\partial T}{\partial z}\right) = a + \frac{b\left(\frac{\partial T}{\partial z} + c\right)}{1 + \frac{\partial T}{\partial z}} \left[1 - \exp\left(\frac{-d}{\partial T/\partial z}\right)\right]$	a _{12.3} =12.21 a ₁₀₀ =22.19 a ₂₈₂ =31.00 a ₃₄ =10.27	b _{12.3} =-8.30 b ₁₀₀ =-11.98 b ₂₈₂ =-11.52 b ₃₄ =-5.97	c _{12.3} =1.836 c ₁₀₀ =1.942 c ₂₈₂ =2.014 c ₃₄ =1.977	d _{12.3} =20.20 d ₁₀₀ =21.91 d ₂₈₂ =21.16 d ₃₄ =22.33

Table 3: Constitutive Equations. The reactive transport model results are fit by constitutive equations relating bulk salinity to shell depth and temperature gradient for each of the ocean compositions, column 1, and their associated coefficients, a-d. Subscripts 12.3, 100, 282, and 34 refer to European ocean compositions with concentrations of 12.3 ppt, 100 ppt, 282 ppt, and terrestrial seawater with a concentration of 34 ppt, respectively. These equations provide a parameterization of Europa's ice shell composition's dependence on the local thermal environment at the time of ice formation, which can be utilized to provide efficient first order estimates of the properties of ice formed in a variety of chemical and thermal environments without the need for explicit simulation.

The translation of the model from the Earth system to Europa hinges on the observation that as thermal gradients near the ice-ocean/brine interface decrease ice bulk salinity asymptotically approaches a lower limit governed by molecular diffusion in the pore fluid (Figure 2c). The result of this is twofold. First, the ice shell will experience ice-ocean interface thermal gradients below those found on Earth during much of its formation. This suggests a relatively homogeneous ice layer (formed in the asymptotic regime) underlying a thin (~1 km), compositionally distinct surficial layer (formed under steep thermal gradients). This stratification would produce variations in the thermochemical and mechanical properties of these layers, potentially introducing a boundary along which rheological transitions (e.g. brittle lid vs. ductile mantle) and transport regimes (conduction vs. convection) may be promoted. Second, the lower portion of the contemporary ice shell is believed to be ductile enough to undergo solid state convection [Barr and McKinnon, 2007; Han and Showman, 2005; McKinnon, 1999; Tobie et al., 2003], providing a mechanism that would mix this region of the shell, homogenizing it chemically and flattening its thermal profile (consider the analogous geothermal profile). A convective thermal profile in this ductile region suggests an ice-ocean interface subject to very low thermal gradients [Mitri and Showman, 2005], implying that accreted ice salinities would be at or near their lower limit, irrespective of ice thickness. Thus, the ductile region of the contemporary ice shell should have a bulk composition at or near the lower limit set by the critical porosity. Such a compositional profile varies negligibly from those predicted by the unidirectional solidification scenarios we simulate here (below 1 km predicted salinities vary by <150 ppm from the theoretical lower limit). Any heterogeneities in impurity entrainment would require associated ice-ocean heat flux variations (e.g., ocean driven heating of the ice shell [Soderlund et al., 2014], thermochemical diapirism [R T Pappalardo and Barr, 2004], spatiotemporal variations in basal heat flux due to downwelling cold ice and/or the evolution of tidal heating within the ice shell [Tobie et al., 2003]) with amplitudes large enough to appreciably affect entrainment rate. Notably, this implies that for much of the ice shell it is not the thermal regime of the ice but rather its critical porosity and permeability which will determine ice composition.

In general, the bulk salinity profiles and their corresponding relationships to depth within the ice shell and local temperature gradients are well-represented by our derived constitutive equations, suggesting that their functional forms (Eq. 26 & 27) capture much of the reactive transport physics that govern how ice forms in the presence of dissolved materials, and the movement of this material via advection and diffusion while the ice is still permeable. The division of impurity entrainment rate into two distinct thermal regimes, diffusive (low) and advective-reactive (high), is well accommodated and justified by the terrestrial benchmarks above. While there exist uncertainties in the limit of extreme thermal gradients ($\gg 20 \text{ K/m}$) and large salinities (e.g. scatter observed for the 282 ppt ocean at low thermal gradients, a consequence of salinity's increased sensitivity to changes in porosity at high ocean concentrations [Supplementary Section S5]), the high thermal conductivity of ice relative to water quickly diffuses such thermal anomalies, and the results demonstrate that, as expected, the bulk salinity in the ice approaches the diffusive equilibrium limit under low thermal gradients. Thus, as perhaps the first quantitative estimate of impurity content, the constitutive equations derived here allow us to investigate the properties and evolution of Europa's ice shell and hydrological features contained therein.

3.3 The Evolution of Europa's Ice Shell

3.3.1 Total Salt

The constitutive equations derived above can be used to estimate the total salt content of Europa's ice shell prior to the onset of solid-state convection, producing an upper limit on the total impurity load of the ice shell. For these calculations, we assume a 25 km thick ice shell with an inner radius of 1,535 km and an outer radius of 1,560 km. The total salt content for a given ocean composition can be calculated by integrating the constitutive equation over the volume of the ice shell given the coefficients in Table 3. For an ice shell with inner radius R_1 and outer radius R_2 ,

$$\text{Total Salt in Shell} = \frac{\rho_{ice}}{1000} \int_V S_{tot}(z) dV \quad (28)$$

where ρ_{ice} is the density of ice, V is the volume of the ice shell, and $S_{tot}(z)$ is the constitutive equation relating bulk salinity and depth (Table 3). Rewriting z in terms of the spherical coordinate r , gives:

$$\text{Total Salt in Shell} = \frac{\rho_{ice}}{1000} \int_{R_1}^{R_2} \int_0^{2\pi} \int_0^{\pi} \left[a + \frac{b}{(c - (R_2 - r))} \right] r^2 \sin \varphi \, dr \, d\theta \, d\varphi \quad (29)$$

where a , b , and c are coefficients from the ocean/brine specific constitutive equation and (r, θ, φ) represent a spherical coordinate system.

The total volume of the 25 km thick European ice shell is $\sim 7.5235 \times 10^{17} \text{ m}^3$, while the approximate collective volume of Earth's oceans is $\sim 1.332 \times 10^{18} \text{ m}^3$ [Charette and Smith, 2010]. For the European ocean composition (Table 2), with concentrations of 12.3 ppt, 100 ppt, and 282 ppt the total salt entrained in a 25 km shell is $7.2894 \times 10^{17} \text{ kg}$, $3.6633 \times 10^{18} \text{ kg}$, and $1.0189 \times 10^{19} \text{ kg}$, respectively. This corresponds to average ice shell salinities (total salt/ice shell mass) of 1.0565 ppt, 5.3099 ppt, and 14.769 ppt, respectively. For a terrestrial ocean composition with a concentration of 34 ppt the total salt entrained in a 25 km shell is $1.2978 \times 10^{18} \text{ kg}$, corresponding

to an average ice shell salinity of 1.8811 ppt. For comparison, Earth's oceans contain $\sim 4.5288 \times 10^{19}$ kg of salt.

Directly related to the composition and bulk salinity of the ice is its density. Crucial in driving any potential solid-state convection on Europa, compositional buoyancy may either help or hinder large scale, thermally driven convective overturn in the ice shell. Horizontal density gradients have also been proposed as a driver of putatively observed subduction/subsumption on Europa's surface [Johnson *et al.*, 2017b; Kattenhorn, 2018]. Mirroring the profiles of bulk salinity, there exists a rapid and asymptotic decrease in ice density with depth for all ocean chemistries (Supplementary Figure S5), and subsequently throughout much of the shell the density is nearly homogeneous (e.g. for a 100 ppt European ocean chemistry $\rho_{500m}=922.54$ kg/m³ and $\rho_{25km}=922.25$ kg/m³). Our results demonstrate that, apart from a geophysically thin surface layer, significant variations in density with depth are unlikely to form as the ice shell freezes out. The maximum salt content predicted in the near surface is ~ 36 ppt (or $\sim 3.6\%$), calculated by extending the constitutive equation relating bulk salinity and shell depth for the 282 ppt ocean to the surface ($z = 0$). The same calculation for the 100 ppt, 34 ppt, and 12.3 ppt oceans results in near surface salt contents of ~ 22 ppt, ~ 9 ppt, and ~ 19 ppt (or $\sim 2.2\%$, $\sim 0.9\%$, and $\sim 1.9\%$), respectively. A number of these values are greater than, or close to, the 2% salt content needed to drive the subduction of certain laterally compositionally heterogeneous slabs calculated by [Johnson *et al.*, 2017a]. However, the physical, thermal, and chemical characteristics of the ice shell likely act in concert to control Europa's dynamics, as the material properties of ice are structurally, thermally, and chemically dependent (Supplementary Section S2). The expected salinity profile, along with the total impurity load, provides context on the nature of liquid and solid phases within the ice shell. Combined with thermal variations due to convection, tidal heating, or heat transfer from the ocean [Howell and Pappalardo, 2018; Mitri and Showman, 2005] and variations in physical properties such as porosity and viscosity [Barr and McKinnon, 2007; Johnson *et al.*, 2017a], more explicit constraints on the thermophysical formation of many of Europa's surface features are thus possible.

3.3.2 Basal Fractures

The fundamental processes that occur during the freezing of ice are not only applicable to the ocean, but to any water within the ice shell. We adapted our approach to accommodate the geometry of simple basal fractures (Supplementary Section S3), to investigate the composition of fractures upon re-freezing. Akin to the basal fractures of terrestrial ice shelves, fractures at the ice-ocean or other ice-liquid interface of Europa could either locally stabilize or destabilize the ice shell; they have the potential to suture the shell back together with newly frozen oceanic material [Khazendar *et al.*, 2009], or to propagate further, potentially penetrating to the surface [Bassis and Walker, 2011]. Such fractures appear within Europa's chaos terrain [Walker and Schmidt, 2015], a potential indicator of near-surface water reservoirs [Schmidt *et al.*, 2011] and a potential pathway for shallow water to make it to the surface in the form of plumes [Sparks *et al.*, 2017] (See Figure 1a).

We modeled basal fractures at both Europa's ice-ocean interface and a hypothetical ice-lens interface (Figure 4). The fractures are filled with fluid from the underlying reservoir (ocean or lens) and the fluid is assumed to remain well mixed during the simulations since the advective timescale for rejected brine with a density 1 kg m⁻³ greater than the ambient fluid through a 25 km fracture is <1 day (equating gravitational and viscous drag forces for a parcel of brine near the crack tip of width $\mathcal{O}(1)$, $v \sim \Delta \rho g / \eta$). Due to the high aspect ratio of the basal fractures (penetration

depth/basal width) we modeled them as solidifying horizontally inward, akin to how terrestrial magmatic dikes form, forced by the conductive profile of the ice shell into which the fracture is emplaced. The injection of water into the ice shell produces regions of very high thermal gradients between the relatively warmer water and cold ice. As a result, fractures refreeze to form ice wedges with chemically gradated composition, due to the amplified solidification rates at the fracture's edges and tip. While these simulations do not completely capture all of the inherently two-dimensional structure of the fracture (especially near the crack tip) these results currently provide the most realistic evaluation of basal fracture physicochemical evolution. The results suggest that basal fractures are geologically short-lived, at least in the upper shell, due to their high aspect ratios and rapid heat loss to the surrounding ice. At depth their lifetime may be extended by deformation processes brought about by tidal forces [Francis Nimmo and Gaidos, 2002] or the presence of a warmer ductile ice layer [Barr and McKinnon, 2007; Tobie et al., 2003]. While it is unlikely that fractures in the shallow shell contain liquid water for long, we show that the rapid injection and refreezing of saline fluid within a colder ice shell produces local chemical heterogeneities along the fracture walls that could preserve the fracture. Two important implications arise: the high salinity regions along the fracture walls produce a gradient in mechanical properties, potentially weakening the center of the fracture or concentrating stress here, while at the same time these regions could be more easily melted during reactivation of the fracture even in the absence of water from the ocean. Both of these provide mechanisms by which features can remain active even once they refreeze.

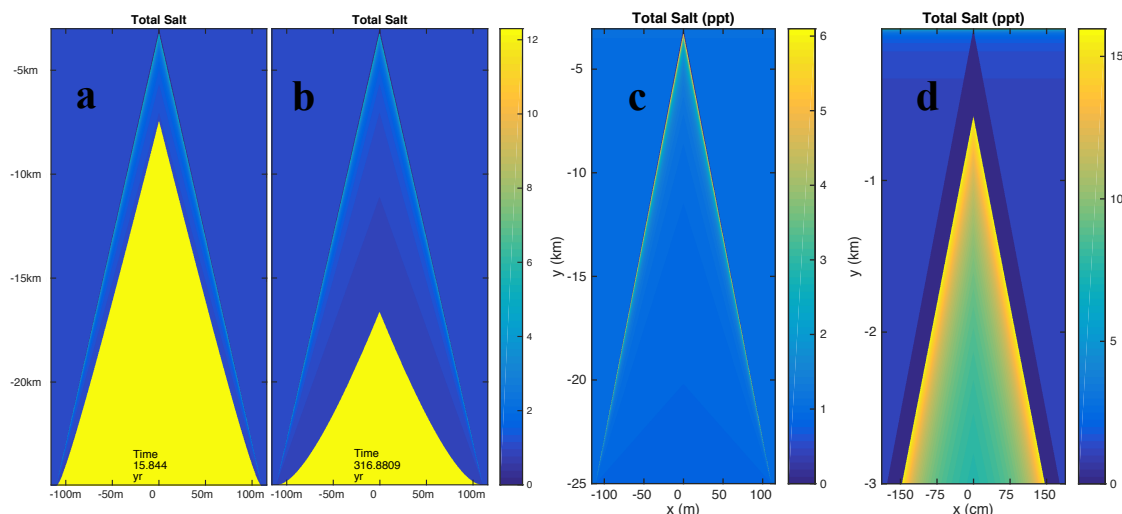


Figure 4: Basal ice fractures refreeze to produce a gradient in salinity. Temporal evolution of a hypothetical basal fracture, **a-b** (Supplementary Figures S7-8 and Sections S3-4), shows that rapid refreezing occurs, down to 5km within 15 years if the fracture can be held open over this timeframe. Profiles for deep fractures from the ice-ocean interface, **c** (due to 2 MPa stress in a 25 km shell; Depth – 21.925 km, Width – 220.9 m), and fractures from shallow lens interfaces, **d** (due to 2 MPa stress in a 3 km lid, Depth – 2.922 km, Width – 3.53 m), show similar patterns of high salt content along the fracture wall and toward the tip, and lower salinity toward the interior and base. These results show that gradients in mechanical properties are likely toward the surface where tidally modulated activity is more likely. For fractures from the ocean, the majority of the ice formed in the interior of the fracture, however, will have a salinity that is nearly indistinguishable from the bulk Europa ice. This suggests that fractures are likely to be regions of local discontinuities in ice shell properties, and potentially regions of weakness within the ice shell created by interfaces between salt and ice grains.

3.3.3 Brines within the Ice

Knowing the composition of the ice provides the chance to evaluate the formation, evolution, and longevity of water or brine systems within Europa's ice shell. For example, shallow lenses of liquid water are suggested to form *in situ* via melting of the ice shell [Schmidt *et al.*, 2011] (Figure 1a) or by injection through diking processes [Manga and Michaut, 2017; Michaut and Manga, 2014]. For such a lens, assuming the ice shell derived from a 34 ppt terrestrial ocean chemistry, letting the diffusive limit govern ice bulk salinity as shown above ($S_{lim} = \phi_c S_{oc}$) and tracking the evolving lens salinity, upon top down refreeze a 2 km thick lens located 1 km beneath a 100 K surface will produce ice compositions ranging from 0.0946 to 14.10 ppt. Additionally, upon complete refreeze, impurity rejection leads to the precipitation of an approximately 2.23 m layer of pure salt, assuming a saturation limit of 282 ppt (Figure 5). Thus, impurity entrainment and rejection during freezing produce compositional heterogeneities within the ice shell and introduce a concentration process capable of producing layers within the shell that have highly distinct mechanical, thermal, and dielectric properties. The ability to predict compositional variations around putative hydrological features in Europa's shell will both constrain how these features form and inform spacecraft observations [Blankenship *et al.*, 2009; Kalousová *et al.*, 2017].

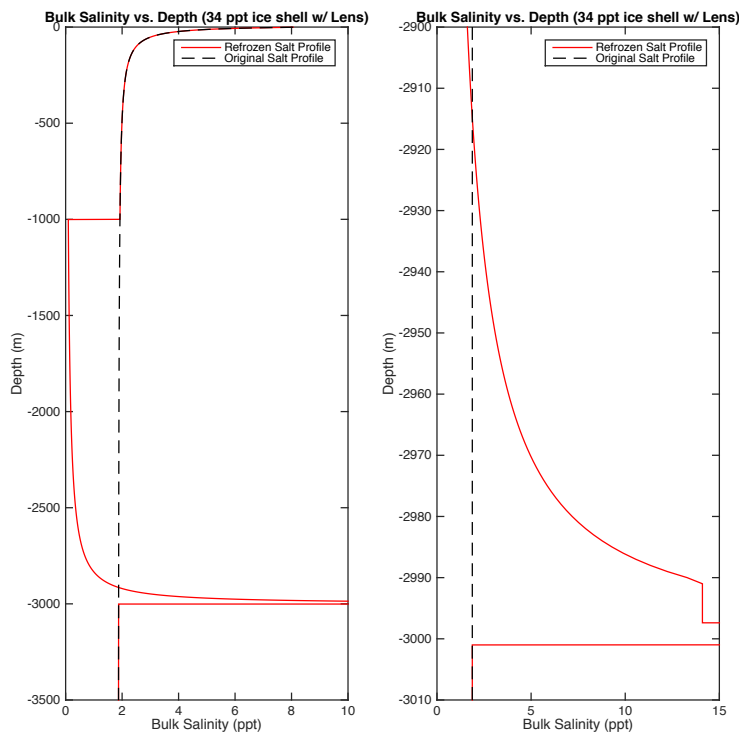


Figure 5: Bulk salinity profile of a perched water lens upon re-solidification. Left) A 2 km thick lens is assumed to form via the *in situ* melting of a preexisting ice shell, whose original composition is given by the black dashed line. Initially the lens salinity is less than that of the original ocean, but upon top down solidification salt is concentrated in the remaining liquid phase, leading to an increase in ice bulk salinity [red line] near the base of the refrozen lens as well as ~2.23 m of precipitated salt on the lens floor (1000 ppt values excluded from plot). **Right)** A magnified view of ice bulk salinity near the bottom of the lens (2.90 – 3.01 km). The lens saturates (282 ppt) when the ice reaches 2991 m, resulting in salt precipitation (2997.77 – 3000 m).

4. Discussion

The impurity load and distribution of entrained ocean materials within Europa's ice shell impacts the evolution of the ice shell, Europa's geology, and interactions between the surface and the ocean. Salts affect the rheological properties of the ice, especially relative to pure water ice, which impacts its mechanical behavior [Durham *et al.*, 2010]. We explicitly quantify the overall impurity content of Europa's ice shell, suggesting an average composition (total salt/ice shell mass) of between 1.053 and 14.72 ppt of non-ice material (depending on ocean composition),

which can be included in more realistic models of the geophysical evolution of the ice shell. These results also demonstrate regions of high material contrast within the ice shell that could promote or extend geologic activity. Compositional heterogeneities can either aid or prevent buoyancy driven convection in the ductile region of the ice shell, which is important for constraining the rates of subduction and surface recycling [Johnson *et al.*, 2017b; Kattenhorn, 2018]. Determining the lifetime of liquid water features within the ice shell is of profound importance in considering whether such reservoirs could be putative habitats; relevant for both planetary exploration and planetary protection. While our models suggest that shallow subsurface water in a conductive ice shell is short lived, the warmer, isothermal regime of an ice shell undergoing convection may provide an environment where hydrological features could persist for much longer. New constraints on the average density and composition of the ice feeds forward into the putative reductant-oxidant cycle associated with ocean-surface interaction [Vance *et al.*, 2016], by which ice shell overturn delivers surface-generated oxidants and ice-shell derived chemical species as potential energy sources to the ocean. Compositional profiles of the bulk ice shell and geologic features effectively capture the thermal and physicochemical nature of the ice that can be observed by Europa Clipper's remote sensing and radar instruments: the spatial distribution of impurities on the surface and the dielectric properties of the ice and water within the shell carry with them an accessible fingerprint of ice shell dynamics and the ocean below.

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Author Contributions

J. J. B. contributed in designing the research, constructing the multiphase reactive transport model, carrying out the research, interpreting the results, and writing/reviewing the paper.

B. E. S. contributed in designing the research, interpreting the results, and writing/reviewing the paper.

C. H. contributed in constructing the multiphase reactive transport model, interpreting the results, and writing/reviewing the paper.

C. C. W. contributed in constructing the fracture mechanics model, interpreting results, and writing/reviewing the paper.

Competing Interests

The authors declare no competing financial nor non-financial interests.

Materials and Correspondence

Code Availability

Liquidus 1.0 and its associated documentation can be found at:

<https://github.com/jbuffo/Liquidus-1.0>

SlushFund 2.0 and its associated documentation can be found at:

<https://github.com/jbuffo/SlushFund-2.0---Active-Interface-Tracking>

All correspondence and material requests should be made to Jacob J. Buffo at:

jacob.buffo@cas.gatech.edu

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