

Optimization of Convolutional Neural Network models for spatially coherent multi-site fire danger predictions

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Abstract

The accurate prediction of the Fire Weather Index (FWI), a multivariate climate index for wildfire risk characterization, is crucial for both wildfire management and climate-resilient planning. Moreover, consistent multisite fire danger predictions are key for targeted allocation of resources and early intervention in high-risk areas, as well as for “megafire” risk detection. In this regard, Convolutional Neural Networks (CNNs) are known to capture complex spatial patterns in climate data. This study compares different CNN architectures and traditional Statistical Downscaling (SD) methods (regression and analogs) for predicting daily FWI across diverse locations in Spain, considering marginal, distributional and spatial coherence measures for validation. Overall, the CNN-Multi-Site-Multi-Gaussian configuration, which explicitly accounts for the inter-site variability in the output layer structure, showed a superior performance. These insights provide a methodological guidance for the successful application of CNNs in the context wildfire risk assessment, enhancing wildfire response strategies and climate adaptation planning.

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Key Points:

- Convolutional neural networks (CNNs) are compared with classical statistical down-scaling methods for Fire Weather Index (FWI) prediction.
- The best CNN setup provides balanced results for all validation metrics, including accuracy, simulation of extremes and spatial consistency.
- Our findings provide a methodological basis for the development of more robust, spatially coherent regional future FWI scenarios.

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18 Abstract

19 The accurate prediction of the Fire Weather Index (FWI), a multivariate climate
20 index for wildfire risk characterization, is crucial for both wildfire management and climate-
21 resilient planning. Moreover, consistent multisite fire danger predictions are key for tar-
22 geted allocation of resources and early intervention in high-risk areas, as well as for “megafire”
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26 for predicting daily FWI across diverse locations in Spain, considering marginal, distri-
27 butional and spatial coherence measures for validation. Overall, the CNN-Multi-Site-Multi-
28 Gaussian configuration, which explicitly accounts for the inter-site variability in the out-
29 put layer structure, showed a superior performance. These insights provide a method-
30 ological guidance for the successful application of CNNs in the context wildfire risk as-
31 sessment, enhancing wildfire response strategies and climate adaptation planning.

32 **Keywords:** deep learning, statistical downscaling, Generalized Linear Models, analogs,
33 spatial structure, future wildfire risk assessment.

34 Plain Language Summary

35 This study focuses on the Fire Weather Index (FWI), a pivotal climate index for
36 the assessment of wildfire risk. Accurate FWI predictions are vital for wildfire manage-
37 ment. This study explores the viability of employing Convolutional Neural Networks (CNNs)
38 as a Statistical Downscaling (SD) technique for precise FWI prediction across diverse
39 locations in Spain in comparison with two conventional SD methodologies: Generalized
40 Linear Models and analogs. Following a cross-validation scheme based on observed daily
41 FWI data, we find that the CNN-Multi-Site-Multi-Gaussian (CNN-MSMG) configura-
42 tion exhibits noteworthy proficiency in daily FWI prediction. This model explicitly in-
43 corporates the covariance structure of the predictands into the CNN architecture, yield-
44 ing spatially consistent FWI predictions. Furthermore, CNN-MSMG has optimal prop-
45 erties for use in the context of climate change, providing a robust replication of extreme
46 events and extrapolation capabilities if applied to novel climate scenarios. These find-
47 ings have substantial implications for improving regional-to-local FWI scenarios used to
48 inform vulnerability and impact assessment studies.

49 1 Introduction

50 Climate fire danger indices are key to assess and predict the risk of wildfire occur-
51 rence and severity. They are based on the integration of daily near-surface temperature,
52 humidity, wind speed and precipitation records (de Groot et al., 2006), and thus provide
53 more accurate wildfire risk forecasts than their input variables alone (see e.g. Dowdy et
54 al., 2009; Fugioka et al., 2009). Beyond the near-term prediction horizon, fire danger in-
55 dices are also useful to monitor changes in wildfire risk over time. As a result, downscaled
56 fire danger scenarios are essential for vulnerability and adaptation strategies in regional
57 to local applications, since General Circulation Model (GCM) outputs (Eyring et al., 2016)
58 can’t provide actionable climate information at these spatial scales (Giorgi et al., 2009).
59 Given their suitability for most impact studies, statistical downscaling (SD, Maraun &
60 Widmann, 2018) of future fire weather scenarios is often required, including *perfect-prognosis*
61 methods (Bedia et al., 2013, see Sec. 2.1) or bias-adjustment tools (Abatzoglou & Brown,
62 2012; Casanueva et al., 2018). In this case, there are three key aspects to focus on: (1)
63 the reproducibility of extremes, as they can substantially increase wildfire impacts (Turco
64 et al., 2018); (2) extrapolation capability is vital for predicting of out-of-sample values,
65 since fire danger conditions are expected to change drastically in many regions (Bedia
66 et al., 2015; Quilcaille et al., 2023), and (3) the ability to keep the predictand’s (FWI)

67 spatial consistency is important to identify potentially hazardous fire risk scenarios af-
68 fecting a wide geographical area, thereby increasing the odds of “fire clusters” with catas-
69 trophic potential (San-Miguel-Ayanz et al., 2013).

70 While most standard SD methods show good performance in at least one of these
71 3 aspects (Maraun et al., 2019), none of them is able to effectively accomplish all of them.
72 In this context, the classical analog method (Lorenz, 1969; Zorita & von Storch, 1999;
73 Brands et al., 2011) is still a competitive benchmark due to its ability to model both the
74 extremes and the spatial structure (Widmann et al., 2019). However, if applied in its origi-
75 nal form (Zorita & von Storch, 1999), this method fails to extrapolate beyond observed
76 extremes, limiting its use for climate change applications (Bedia et al., 2013). In this sense,
77 regression-based models are the better choice since they allow for better extrapolation
78 (Baño-Medina et al., 2021; Balmaceda-Huarte et al., 2023) but, on the downside, they
79 usually underestimate the extremes (Hertig et al., 2019). A further disadvantage of stan-
80 dard regression models (including Generalized Linear Models, GLMs) is their single-site
81 structure unable to effectively model the spatial dependencies of the predictand variable(s).
82 Other proposed alternatives combine the benefits of perfect-prog models and Weather
83 Generators (PP-WG, see e.g.: Cannon, 2008; Carreau & Vrac, 2011), allowing to esti-
84 mate the uncertainty of a local predictand variable and even to sample from the condi-
85 tional distributions to recover the variability of the time series. To date, however, and
86 with some exceptions (Legasa et al., 2023), most of these studies have focused on the es-
87 timation of uni-variate, single-site distributions, thereby not taking into account the spa-
88 tial structure of the predictand nor its relationships with other predictand variables.

89 In this regard, deep learning methods, and in particular Convolutional Neural Net-
90 works (CNNs, LeCun et al., 1995) may offer a suitable alternative to meet these require-
91 ments with an adequate tuning. CNNs perform convolutions with learnable kernels over
92 the spatial dimensions of atmospheric fields, inferring a non-linear mapping between low-
93 resolution predictor fields and high-resolution predicand fields that has been shown to
94 outperform conventional SD methods in many aspects (Baño-Medina et al., 2020). Re-
95 garding extrapolation ability, CNNs can produce plausible future climate change scenar-
96 ios (Baño-Medina et al., 2021), comparable to those provided by dynamical downscal-
97 ing (Baño-Medina et al., 2022). For a better reproducibility of extremes, parametric-CNNs
98 (P-CNNs, Sec. 2.3) can estimate the parameters of conditional distributions given cer-
99 tain atmospheric conditions. As in the PP-WG approach, an adequate CNN architec-
100 ture is able to estimate the parameters of the whole joint (multi-site) probability struc-
101 ture of the covariance matrix and can coherently reproduce the spatial structure of the
102 predicted fire danger series across all predictand locations.

103 In this study we describe different CNN-based regression models for multi-site ex-
104 treme fire danger assessment under climate change conditions, based on Canadian Fire
105 Weather Index (van Wagner, 1987) records at 29 locations in Spain. We deploy three
106 alternative CNN topologies based on the PP-WG approach that estimate either uni-variate
107 or multi-variate Gaussian distributions on daily timescale. The validation is based on
108 specific measures of extreme reproducibility and spatial coherence, using classical SD meth-
109 ods (analogs and GLMs) as benchmark.

110 2 Data and Methods

111 2.1 Predictor set

112 Perfect-prognosis SD establishes empirical relationships between 1) the variabil-
113 ity of atmospheric variables operating on large scales, typically derived from a global re-
114 analysis with a resolution similar to that offered by current global climate models (Eyring
115 et al., 2016) and 2) the local-scale variability of the predictand of interest (here: FWI)
116 as represented by in-situ observations or gridded observational datasets derived there-

117 from. Once the SD model is calibrated, the learnt relationships can be applied to GCM
 118 (instead of reanalysis) predictors in order to derive local climate change projections if,
 119 ideally, the following requirements are fulfilled: The predictor variables should be real-
 120 istically represented by the GCMs (Fernandez-Granja et al., 2021; Brands, 2022; Brands
 121 et al., 2023), should carry the climate change signal and be physically related with the
 122 local variable. In addition, the SD model should be capable to extrapolate the learnt re-
 123 lationships to altered/unobserved climate regimes (Gutiérrez et al., 2013). For the case
 124 of FWI downscaling, the predictor selection under such non-perfect circumstances has
 125 been explored in a previous study we built upon here (Bedia et al., 2013). Namely, we
 126 use daily-mean 2m air temperature, the zonal and meridional wind velocity components
 127 at 10m, as well as temperature and specific humidity at the 850 hPa pressure level, cov-
 128 ering a spatial domain centered on the target region. These data have been retrieved from
 129 ERA-Interim (Dee et al., 2011) for the period 1985–2011 (see Table A2).

130 **2.2 Predictand: Fire Weather Index observations**

131 The FWI is a multivariable index, and therefore the downscaling approach must
 132 carefully consider the physical consistency of its input variables. When these are sep-
 133 arately downscaled, inter-variable dependencies may be modified leading to spatio-temporal
 134 inconsistencies in the simulated output fields that would affect the coherence of the out-
 135 put FWI predictions (see e.g.: Vrac & Friederichs, 2015). This uncertainty source is here
 136 circumvented by using the FWI index, rather than its components, as sole predictand
 137 variable. To this end, in-situ observations from 29 weather stations of the Spanish Me-
 138 teorological Agency (AEMET) were obtained, recording the required data for FWI cal-
 139 culation. The AEMET dataset provides instantaneous values of temperature, relative
 140 humidity and wind speed at 13:00 UTC, and last 24-h accumulated precipitation, recorded
 141 at 07:00 UTC. FWI calculation follows the methodology described by Bedia et al. (2013).
 142 For an optimal dataset completeness, we consider the calibration period 1985–2011.

143 **2.3 Convolutional Neural Networks**

144 To identify the key factors of the FWI spatial structure, we deploy three CNN ar-
 145 chitectures of increasing topological complexity (see Fig. 1). The backbone of these topolo-
 146 gies builds on well tested CNNs known to outperform both analogs and GLMs in tem-
 147 perature and precipitation downscaling (Baño-Medina et al., 2020). The hidden struc-
 148 ture consists of 3 convolutional layers followed by two fully-connected ones. The convo-
 149 lutional layers consist of a block of three layers with 50, 25, and 10 (3×3) kernels respec-
 150 tively, while the fully-connected (dense) layers each contain 50 neurons for the CNN-Multi-
 151 Site (CNN-MS) and CNN-Multi-Site-Gaussian (CNN-MSG) configuration, or 200 neu-
 152 rons for the CNN-Multi-Site-Multi-Gaussian (CNN-MSMG) version (see Fig. 1). A non-
 153 linear ReLU activation function is applied between the layers. The output, where we find
 154 the main differences across models, is a dense fully-connected network with a linear ac-
 155 tivation function in CNN-MSG and CNN-MSMG. In the case of CNN-MS, the output
 156 layer consists of 29 neurons, each neuron corresponding to a point location (Table A1),
 157 yielding deterministic FWI predictions at each site.

158 In order to improve the representation of FWI extremes, we introduce modifica-
 159 tions to the P-CNN structures in CNN-MSG and CNN-MSMG. In CNN-MSG, the out-
 160 put is modeled stochastically using an *independent* Gaussian distribution to estimate the
 161 parameters of $\mathcal{N}(\mu, \sigma)$ (mean and standard deviation respectively). Thus, for each of the
 162 29 stations, two pairs of neurons are added to the output layer, one for each parameter.
 163 CNN-MSMG, in turn, aims to estimate the parameters of a *multivariate* Gaussian dis-
 164 tribution $\mathcal{N}(\mu, \Sigma)$. In this case, μ denotes the mean and Σ represents the covariance ma-
 165 trix. Therefore, the output layer consists of a pair of neuron vectors, with sizes 29 and
 166 464 respectively. The 29 neurons represent the μ parameters, while the 464 neurons cor-
 167 respond to the number of unique parameters estimated in the covariance matrix Σ . The

168 aim of this multivariate Gaussian setup is to describe the values at each location as a
 169 correlated set, unlike the outcome of an independent Gaussian distribution, where the
 170 predictions at each site are independent of each other. The general architecture scheme
 171 for each P-CNN configuration is outlined in Fig. 1. To avoid model overfitting, ensure
 172 robustness and optimize parameter tuning and CNN architectures, all SD models have
 173 been fit following a cross-validation procedure comprising 4 temporal blocks spanning
 174 the periods 1985-1991, 1992-1998, 1999-2004 and 2005-2011. The loss functions used are
 175 the Mean Square Error (MSE) for CNN-MS, the negative log-likelihood of the independ-
 176 ent Gaussian distribution for CNN-MSG, and the negative log-likelihood of the mul-
 177 tivariate Gaussian distribution for CNN-MSMG. The benchmark SD methods (analogs
 178 and GLMs) have been fitted following the same cross-validation scheme (see Appendix
 179 B for additional details on these methods).

180 2.4 Validation

181 Here, the Root Mean Square Error (RMSE) and Mean Absolute Error (MAE), as
 182 well as the quantile-quantile plot (QQ-plot), are used to validate the similarity of the tem-
 183 poral sequence and empirical distribution between the downscaled and observed daily
 184 FWI time series at a given station (Déqué, 2011). Apart from these classical marginal
 185 validation metrics, the focus is put on *spatial* coherence, as outlined in the following.

186 2.4.1 Location Correlogram

187 To qualitatively evaluate whether the distinct SD methods are able to reproduce
 188 the spatial correlation structure of the observed FWI, we use the *location correlogram*
 189 (Herdin et al., 2005). Firstly, the $n = 29$ observed daily *in-situ* FWI time series from
 190 the complete station network are correlated with each other for all possible combinations
 191 (i.e. $n \times \frac{n-1}{2}$ pairs) using Spearman’s rank correlation coefficient and the resulting co-
 192 efficients are plotted against the respective pairwise station distances. Then a local 2nd-
 193 order polynomial (“loess”) is fitted to the scatter-plot, resulting in a curve that depicts
 194 the spatial correlation structure of the observed FWI. As a quantitative summary mea-
 195 sure, we use the *correlation length* (CL), defined as the geographical distance correspond-
 196 ing to the point of intersection of a given correlation threshold with the fitted loess line.
 197 A threshold of $\rho = 0.4$ has proven to be most suitable for characterizing the spatial FWI
 198 structure in this study (Table Appendix C), and the overall results are robust to changes
 199 in this choice. After applying the same method to the downscaled time series from each
 200 of the three SD methods, the CL bias between the simulated and observed spatial struc-
 201 ture is calculated as an overall measure of the methods’ capability to reproduce the spa-
 202 tial coherence of the observed FWI (Widmann et al., 2019).

203 2.4.2 Mutual information for FWI90

204 FWI extremes are particularly relevant for fire danger assessment. As a result, from
 205 the spatial consistency point of view, the users of downscaled FWI values will be primar-
 206 ily interested in a realistic representation of joint higher-percentile FWI exceedances among
 207 locations (see e.g. Bedia et al., 2014). To this aim, Mutual Information (*MI*) provides
 208 a suitable measure of the dependence between two random variables X, Y (here, predic-
 209 tions at two locations) that is unaffected by their marginal distributions and quantifies
 210 the amount of mutual information between them (see e.g. Hlinka et al., 2013). For two
 211 discrete random variables X and Y it is defined as:

$$MI(X, Y) = \sum_{x \in X} \sum_{y \in Y} p(x, y) \cdot \log \left(\frac{p(x, y)}{p(x) \cdot p(y)} \right) \quad (1)$$

212 *MI* is zero if the two events are independent, i.e. if $p(X, Y) = p(X) \cdot p(Y)$, non-negative
 213 ($MI(X, Y) \geq 0$) and symmetric ($MI(X, Y) = MI(Y, X)$).

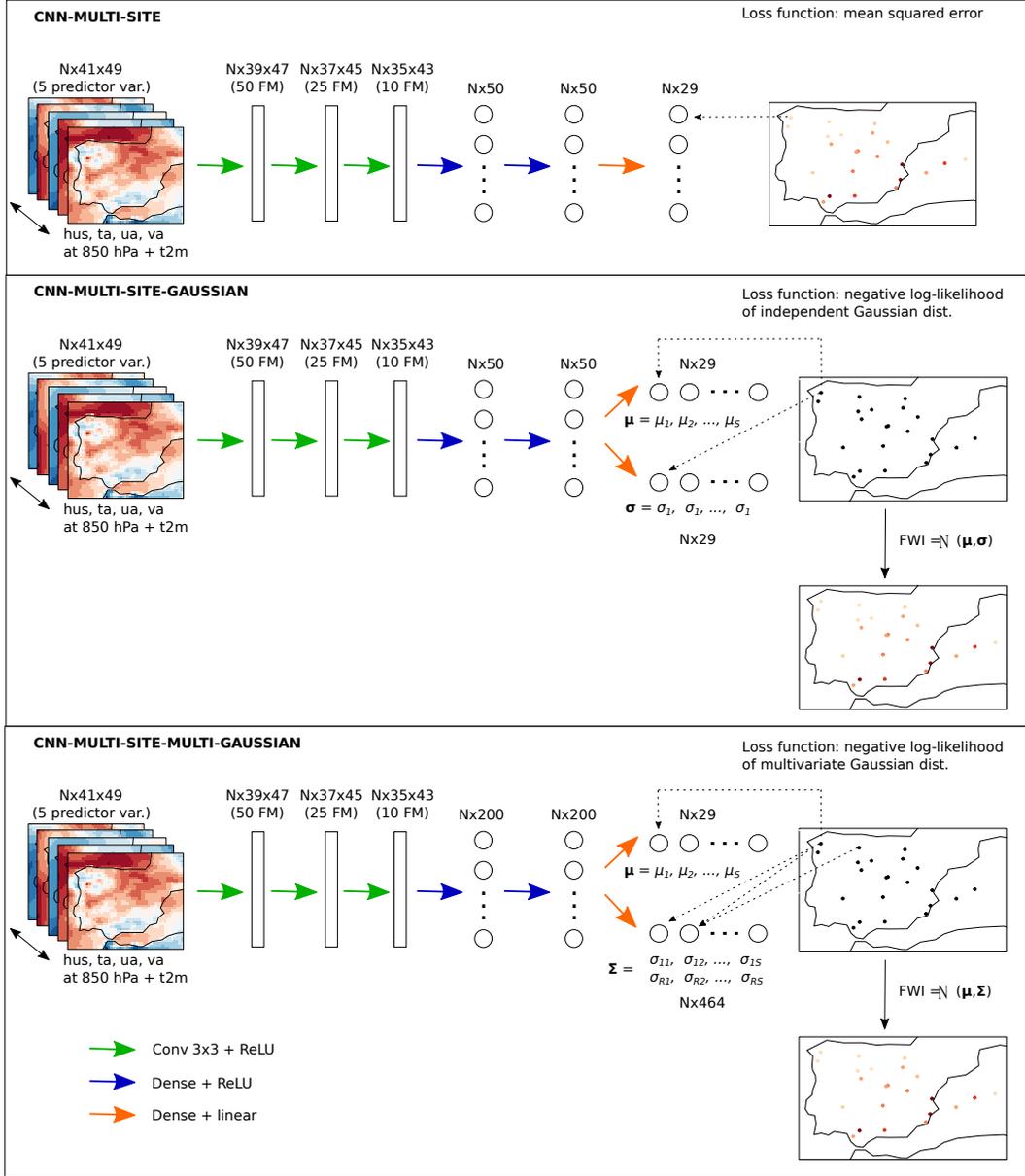


Figure 1. Scheme of the convolutional neural network architecture used in this study. The network includes a first block of three convolutional layers with 50, 25 and 10 (3x3) kernels, respectively, followed by two fully connected dense layers with 50 or 200 neurons each, depending on the model. For CNN-MSG and CNN-MMSG, the output is modeled through an independent Gaussian distribution and a multivariate Gaussian distribution respectively, and the corresponding parameters are estimated by the network, obtaining FWI as final product, either deterministically (CNN-MS) or stochastically (CNN-MSG and CNN-MMSG). The output layer is activated linearly while the previous layers of the network are activated non-linearly.

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Here, we consider the binary variables X, Y at each location, stating whether the FWI values x_i, y_i lie above or below the 90th percentile for each pair of locations. We then calculate the MI for each pair of locations following the definition above (eq. 1). As for the correlograms (Sec. 2.4.1), we plot each MI_{ij} against the distance of the lo-

218 cations i, j and fit a degree-2 loess curve to the resulting scatter-plots. We then define
 219 MI thresholds for calculating the MI lengths (MIL) in observations and for the differ-
 220 ent downscaling methods. We use a MI threshold of 0.05, yielding results comparable
 221 to those obtained from CL analysis, and focusing on the identification of potential new
 222 information about each methods' performance (Fig. C2). As in CL analysis, the MIL
 223 biases are calculated as the difference between predicted and observed MILs.

224 3 Results

225 The results presented correspond to the generic June to September fire season, rep-
 226 resentative of the Iberian Peninsula (JJAS, see e.g.: Bedia et al., 2014). It's important
 227 to highlight that the models were calibrated using the entire annual dataset. However,
 228 a subset comprising the JJAS season was used to present the results relevant for fire dan-
 229 ger assessment in this region. In the following subsections, we categorized the station
 230 network into three groups based on proximity to the sea and general climate conditions:
 231 Atlantic, Coastal Mediterranean, and Continental Mediterranean (see Table A1). The
 232 suitability of this classification for FWI aggregation is confirmed by the results obtained
 233 with the mutual information measure (Sec. 3.2.2).

234 3.1 Predictive accuracy and distributional similarity

235 In agreement with previous studies (Brands et al., 2011), the SD methods' accu-
 236 racy is *generally* lower at continental sites than near the coast. Overall, all methods per-
 237 form similarly with regard to predictive accuracy, summarized in terms of the RMSE of
 238 FWI90 predictions in Fig. C1 (Appendix C).

239 However, the distributional characteristics of the predictions differ largely among
 240 methods. The quantile-quantile (QQ) plots shown in Fig. 2 compare the observed and
 241 predicted empirical FWI distributions. While all methods perform well in predicting the
 242 mean FWI, disparities emerge at higher percentiles, crucial for fire danger analysis. The
 243 benchmarking analog approach produces best results for the right tail, closely followed
 244 by multivariate CNN-MSMG, showing similar results across regions. Conversely, GLM
 245 and CNN-MS consistently underestimate high percentile FWI events, failing to realis-
 246 tically represent most dangerous situations. CNN-MSG also achieves good results, com-
 247 parable to CNN-MSMG, but is outperformed by the latter in the Coastal Mediterranean
 248 and Atlantic regions. Notably, in the Atlantic region, CNN-MSG unrealistically inflates
 249 the highest FWI percentiles and underestimates most of the FWI distribution. On the
 250 contrary, in the Continental Mediterranean region, CNN-MSG performs slightly better
 251 than CNN-MSMG for higher percentiles.

252 In order to obtain a quantitative measure of distributional deviance with respect
 253 to the observed distribution, we calculate the RMSE considering the differences between
 254 predicted and observed quantiles of i) the entire FWI times series and ii) the FWI time
 255 series values exceeding the station-specific 90th percentile (FWI90, Fig. 2). Excluding
 256 the results for the analog method, lowest RMSE values for both indicators are obtained
 257 either by CNN-MSG or CNN-MSMG. Regardless of the specific target region, the for-
 258 mer approach demonstrates significantly better performance compared to the latter in
 259 terms of FWI, and only exhibits a slight decrease in performance for FWI90. Specifically,
 260 when emphasizing FWI90, the CNN-MS and GLM models exhibit noticeably poorer per-
 261 formance compared to the analog benchmark. In contrast, the results for CNN-MSG and
 262 CNN-MSMG models are considerably better in this regard.

263 Overall, the reference analog method performs best in representing the distribu-
 264 tion of the daily FWI in most cases. CNN-MSG and CNN-MSMG perform slightly worse,
 265 with CNN-MSG slightly overemphasizing severe FWI frequencies in the Atlantic region.
 266 The analog method performs best overall, but it's applicability in climate changes stud-

267 ies is limited due to its inability to extrapolate predictions outside the observed range.
 268 Conversely, both CNN-MSG and CNN-MSMG are competitive alternative methods in
 269 terms of distributional similarity. In the Secs. 3.2.1 and 3.2.2, we assess whether these
 270 conclusions hold for the *spatial structure* of the simulated mean and extreme FWI fields.

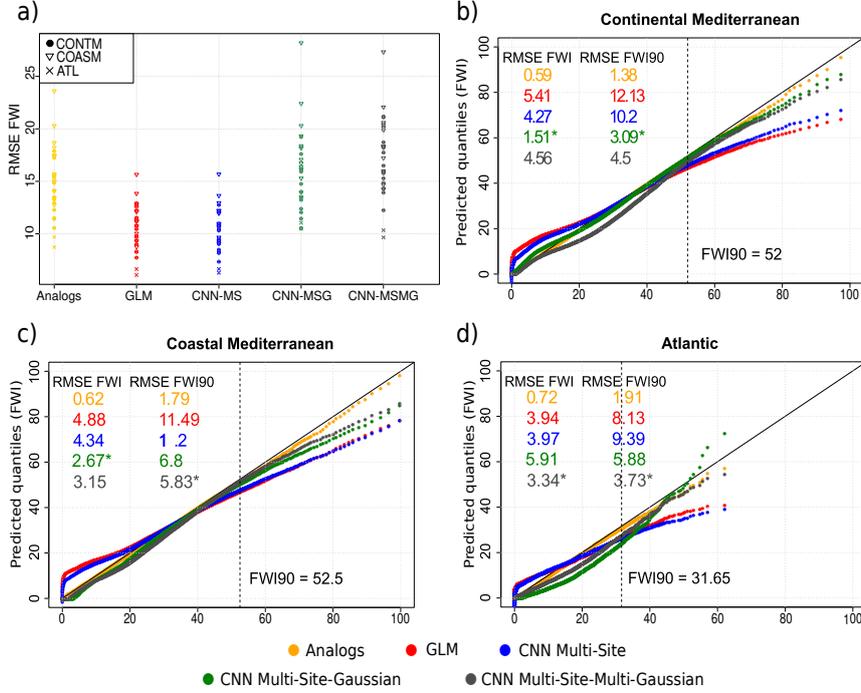


Figure 2. FWI RMSE per station and method (a) and Q-Q plots for the analog method, GLMs and the distinct CNN models (b - d). The figure is divided into 4 panels. The (a) panel refers to the RMSE for the simulated FWI per station and method distinguishing the regions by symbols. The remaining panels refer to the station subsets of (b) the Continental Mediterranean, (c) Coastal Mediterranean and (d) Atlantic regions. The method-specific distributional RMSE for the simulated FWI and FWI90 are indicated in the upper left corners of each panel and the best performing method is marked with an asterisk (excluding the benchmarking analog method). The dashed vertical line indicates the observed FWI90.

271 **3.2 Spatial validation results**

272 **3.2.1 Dependence of inter-station relationships on distance**

273 The temporal correlation coefficients' dependence on distance, analyzed as described
 274 in Sec. 3, is depicted in Fig. 3. As expected, the observed strength of the relations de-
 275 creases exponentially with increasing distance between the stations and stabilizes around
 276 $\rho = 0.1$, the CL for $\rho = 0.4$ being located at 208.30 km (panel a), grey curve). The
 277 corresponding point clouds and polynomials for the SD methods are depicted in red in
 278 panels b) through f), where the respective validation measures are also indicated (see
 279 upper right corners and also Appendix C). The exponential decay seen in the observa-
 280 tions is reproduced more or less successfully by all SD methods except CNN-MSG, that
 281 produces far too weak short distance relationships, failing to reproduce any spatial structure
 282 in the data. The analog method is, as expected, most successful in reproducing the

283 observed correlation structure, closely followed by CNN-MSMG, while GLM and CNN-
 284 MS consistently overestimate pairwise correlations. Among the suitable methods (i.e.
 285 excluding CNN-MSG), the medium-to-long-distance correlations are overestimated by
 286 all methods, particularly by GLM and CNN-MS. The stronger short-distance correlations
 287 are also generally overestimated, but to a lesser degree, and they are almost per-
 288 fectly met by the analog method and closely approximated by CNN-MSMG.

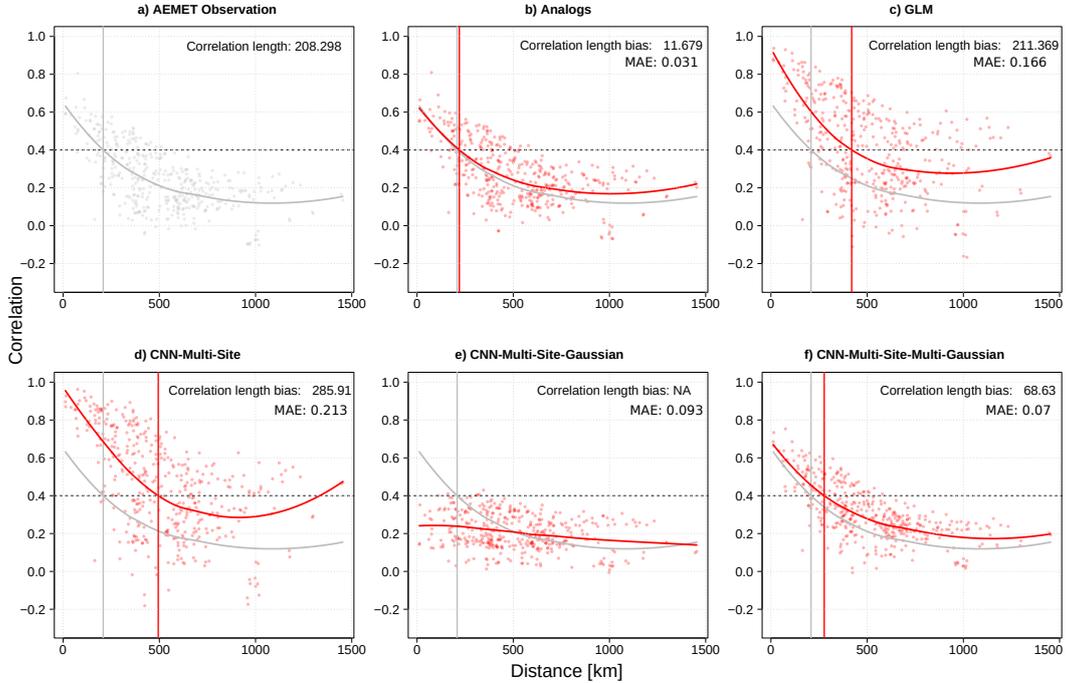


Figure 3. Correlograms illustrating the daily JJAS FWI dependence of the inter-station relationships, described by the Spearman correlation coefficients among all station pairs (y-axis), against their respective distances in kilometers (x-axis). The correlograms correspond to the observations (panel *a*) and to each SD method tested (panels *b* to *f*); the grey loess line of the observations correlogram is included in all panels for visual comparison. It is also displayed the observed Correlation Length (CL, panel *a*) and the CL bias and MAE for each SD method (in panels *b* to *f*). Here, the MAE is calculated as the difference (in absolute value) between predicted and observed correlation coefficients for each station pair.

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3.2.2 Mutual information for fire weather extremes

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In Fig. 4 (upper panel), we present the mutual information (MI) values obtained from the observational network in the upper triangle (a1), compared with those produced by CNN-MSMG, the best performing SD method for this metric (the benchmarking analog method is excluded), in the lower triangle (a2). The stations are grouped into characteristic climate regimes as described in Sec. 3.1. Geographical proximity translates into higher MI values, as the case of Vigo and Santiago de Compostela (NW Iberia, $MI = 0.11$), Barajas and Retiro (Madrid, central Spain, $MI = 0.14$), or Valencia and Valencia-Airport (SE, Mediterranean coast, $MI = 0.13$). Furthermore, several climatologically homogeneous regions can be identified in the matrix, yielding visually discernible clusters of high MI values, e.g. the Soria-Valladolid-Salamanca-Zamora cluster pertaining to the central-north Iberian high plains. The MI pattern obtained from CNN-MSMG

301 is similar to that seen in observations and is thus approximately symmetric (compare
302 Fig. 4-a2 with a1). Nevertheless, CNN-MSMG somewhat overestimates the spatial de-
303 dependencies, indicated by slightly higher MI values than those obtained from observations,
304 and also reflected by regional clusters not seen in observations (e.g. Ciudad Real, Bada-
305 joz and Granada).

306 In Fig. 4b and c, we illustrate the MI biases relative to the observations for CNN-
307 MS and CNN-MSG (b1, b2), as well as for CNN-MSMG and GLM (c1, c2). We focus
308 on station pairs with MI values ≥ 0.05 in observations, thus discarding already inde-
309 pendent station pairs (blank matrix cells). Since the MI bias of the analog method is neg-
310 ligible for all station pairs, the corresponding results are shown in Appendix Appendix
311 C. The MI bias of CNN-MSMG is below the 0.05 threshold for most station pairs, with
312 a few exceptions with both positive or negative values (Fig. 4c1). CNN-MS exhibits a
313 consistent positive bias, consistently overestimating the spatial dependence of extreme
314 FWI events (Fig. 4b1). CNN-MSG, in turn, systematically underestimates these depen-
315 dencies (Fig. 4b2), yielding a lower bias magnitude than for CNN-MS. The GLM ap-
316 proach tends to overestimate these dependencies, albeit to a lesser extent than CNN-MS
317 (compare Fig. 4c2 with b1).

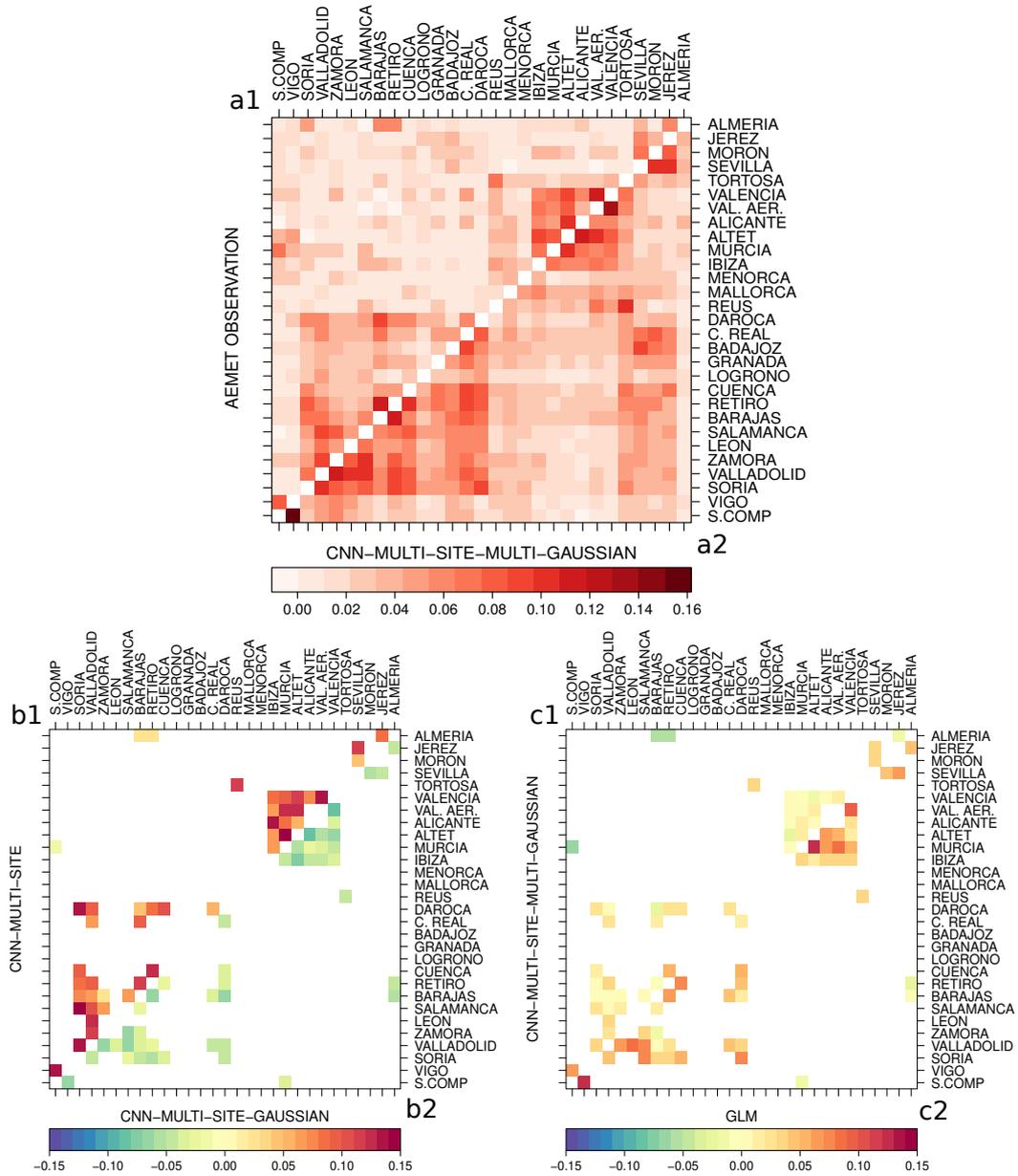


Figure 4. MI matrices for FWI90 events during the fire season (JJAS) obtained from observations (upper triangle in upper panel, a1) and from the best performing SD model (CNN-MSMG, lower triangle in upper panel, a2). Panels b and c show the MI biases for 4 remaining SD methods with respect to the observations (b1: CNN-MS, b2: CNN-MSG, c1: CNN-MSMG, c2: GLM). In b and c panels, only station pairs with $MI \geq 0.05$ in the observations are shown.

4 Conclusions

We conducted a comprehensive comparison of various Convolutional Neural Network (CNN) architectures in contrast to two established statistical downscaling (SD) methods, specifically Generalized Linear Models (GLMs) and analogs. Our assessment focused on evaluating their performance in terms of predictive accuracy, distributional congruence, and spatial coherence for Fire Weather Index (FWI) predictions across 29 locations in Spain.

Among the diverse CNN architectures scrutinized, CNN-MSMG demonstrated the most favorable outcomes across these validation criteria. This setup considers the multivariate nature of the predictions in the output layer yielding a predicted covariance matrix that explicitly accounts for the inter-site variability. It exhibited a notable capacity to accurately represent observed FWI distributions at both single-point and multi-site scales, closely aligning with the outcomes of the benchmarking analogs method. Notably, the analogs method, by design, upholds multisite spatial consistency without alteration, at the cost of limitations for extrapolation in climate change conditions that can be overcome by the rest of methods tested. In contrast CNN-MS (multisite CNN) and GLMs yielded poorer predictive accuracy and consistently overestimated the spatial dependence among sites. In turn, CNN-MSG (multisite Gaussian) attained good results in terms of single-site validation, but proved inefficient in modelling the spatial structure, essentially behaving like a single-site weather generator.

The results presented emphasize the importance of parameter tuning for CNN development in the context of statistical downscaling in order to produce credible predictions. In the particular case of FWI, an adequate tuning is needed in order to ensure actionable climate information for the prevention of wildfire impacts, and this study provides a methodological guidance for the successful application of CNNs to this aim.

5 Open Research

We follow the FAIR principles (Findability, Accessibility, Interoperability and Reuse, Wilkinson et al. (2016)) and publish the code (DOI: 10.5281/zenodo.8387558) and the data (DOI: 10.5281/zenodo.8381437) required to replicate the results presented in this manuscript. We build on the R based (R Core Team, 2020) framework *climate4R* (Iturbide et al., 2019) to digest, manipulate, downscale (see also Bedia et al., 2020) and visualize (Frías et al., 2018) the climate data. For the deep learning models, we lean on *downscaleR.keras*, a library that integrates *tensorflow* (Abadi et al., 2015) and *keras* (Gulli & Pal, 2017) into the *climate4R* framework (Baño-Medina et al., 2020).

Appendix A Input Data

Table A1 is a summary of the AEMET weather station database. We also indicate their corresponding climatic zone, according to the spatial aggregation summarizing the results in Sec. 3.1 of the main text. The *Short name* column indicates the abbreviated labels used throughout the article figures.

Station name	Short name	Lon	Lat	Altitude	Climatic region
REUS–AEROPUERTO	REUS	1.18	41.15	71	COASM
SANTIAGO DE COMPOSTELA–LABACOLLA	S.COMP	-8.41	42.89	370	ATL
VIGO–PEINADOR	VIGO	-8.62	42.24	261	ATL
SORIA	SORIA	-2.48	41.77	1082	CONTM
VALLADOLID	VALLADOLID	-4.75	41.64	735	CONTM
ZAMORA	ZAMORA	-5.73	41.52	656	CONTM
LEÓN–VIRGEN DEL CAMINO	LEÓN	-5.65	42.59	916	CONTM
SALAMANCA–MATACÁN	SALAMANCA	-5.50	40.96	790	CONTM
MADRID–BARAJAS	BARAJAS	-3.56	40.47	609	CONTM
MADRID–RETIRO	RETIRO	-3.68	40.41	667	CONTM
CIUDAD REAL	C. REAL	-3.92	38.99	628	CONTM
BADAJOS–TALAVERA LA REAL	BADAJOS	-6.81	38.88	185	CONTM
GRANADA–AEROPUERTO	GRANADA	-3.79	37.19	567	CONTM
SEVILLA–SAN PABLO	SEVILLA	-5.88	37.42	34	COASM
MORÓN DE LA FRONTERA	MORÓN	-5.61	37.16	87	COASM
JEREZ DE LA FRONTERA–AEROPUERTO	JEREZ	-6.06	36.75	27	COASM
ALMERÍA–AEROPUERTO	ALMERÍA	-2.36	36.85	21	COASM
MURCIA–SAN JAVIER	MURCIA	-0.80	37.79	4	COASM
ALICANTE–EL ALTET	ALTET	-0.57	38.28	43	COASM
ALICANTE	ALICANTE	-0.49	38.37	81	COASM
CUENCA	CUENCA	-2.14	40.07	945	CONTM
VALENCIA–AEROPUERTO	VAL. AER.	-0.47	39.49	69	COASM
VALENCIA	VALENCIA	-0.37	39.48	11	COASM
LOGROÑO–AGONCILLO	LOGROÑO	-2.33	42.45	353	CONTM
DAROCA	DAROCA	-1.41	41.11	779	CONTM
TORTOSA	TORTOSA	0.49	40.82	44	COASM
PALMA DE MALLORCA–SON SAN JUAN	MALLORCA	2.74	39.56	8	COASM
MENORCA–MAÓ	MENORCA	4.22	39.85	91	COASM
IBIZA/ES CODOLA	IBIZA	1.38	38.88	6	COASM

Table A1. Selected stations of the Spanish AEMET network, indicating their position in decimal degrees and meters above sea level (Datum WGS-84). The abbreviations corresponding to the climatic regions in the column are as follows: ATL for Atlantic, COASM for Coastal Mediterranean, and CONTM for Continental Mediterranean.

Table A2 provides a summary of the reanalysis fields used as predictors in this study. The predictor set has been chosen following the methodology for FWI downscaling presented by Bedia et al. (2013), but replacing relative humidity by specific humidity, the former being not directly available in some model simulation databases. The spatial extent of these fields covers a bounding box centered over the Iberian Peninsula, limited by the geographical coordinates $-10^{\circ}/15^{\circ}\text{E}$, $35^{\circ}/45^{\circ}\text{N}$.

Appendix B Benchmarking SD methods

We next provide further methodological details on the standard SD methods used as benchmarks in this study. Both are implemented in the R package `downscaleR` (Bedia et al., 2020), part of the `climate4R` framework for climate data analysis and visualization (Iturbide et al., 2019, <https://github.com/SantanderMetGroup/climate4R>).

Code	Name	units
T2M	Air Temperature at surface	K
T850	Air Temperature at 850 hPa	K
HUS850	Specific humidity at 850 hPa	$g\ kg^{-1}$
UA850	U-wind at 850 hPa	$m\ s^{-1}$
VA850	V-wind at 850 hPa	$m\ s^{-1}$

Table A2. Predictor variables used in this study, selected from the predictor combination proposed for statistical downscaling of FWI in Bedia et al. (2013). Note that for convenience, relative humidity at 850 hPa has been replaced by specific humidity, more commonly available in GCM datasets. All fields are daily mean values.

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B1 Generalized lineal models

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GLMs (Nelder & Wedderburn, 1972) are an extension of the classical linear regression that models the expected value of a random predictand variable for different types of probability distributions and link functions. This makes them a versatile tool for modeling a wide range of data types and situations, and therefore extensively used in SD applications (see e.g.: Chandler & Wheeler, 2002; Gutiérrez et al., 2019). Here, the response variable is assumed to follow a Gaussian distribution. The relationship between the linear predictor $g(\mu)$ and the expected value of FWI is defined by the identity link function, so the linear predictor directly models the mean FWI, where $g(\mu)$ is defined as $g(\mu) = \mathbf{X}\beta$, where \mathbf{X} is the design matrix containing the predictor variables (Sec. 2.1), and β is the vector of coefficients, estimated by maximum likelihood based on the probability density function of the Gaussian distribution using a least-squares iterative algorithm implemented in the R package `stats` (R Core Team, 2020). Furthermore, predictor configuration is such that only local information is used for training at each site. Here, an optimal number of 16 closest grid-points to each predictand point-location are retained to construct the local predictor set (Bedia et al., 2020), after testing different neighbourhood sizes using cross-validation (Sec. 2.3).

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B2 Analogs

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The analog method is a simple yet powerful downscaling technique which assumes that similar (or analog) atmospheric patterns (predictor set \mathbf{X}) over a region originates similar local meteorological outcomes (daily FWI) for a particular location or set of locations (Sec. 2.2). In this study, we use the standard deterministic nearest neighbor method analog technique based on the Euclidean distance, considering the complete fields to compute distances and only the first closest nearest closest analog for prediction (San-Martín et al., 2016), similar to the standard ‘ANALOG’ method of the VALUE intercomparison experiment (described in Gutiérrez et al., 2019, A.2), and considering the implementation described in Bedia et al. (2020). Note that using the complete fields as predictors ensures the maximum spatial coherence of the predictions among stations, since the same analog dates are chosen in each case for every point-location (see e.g. Widmann et al., 2019).

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Appendix C Results

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This section contains additional results as indicated in the figure captions.

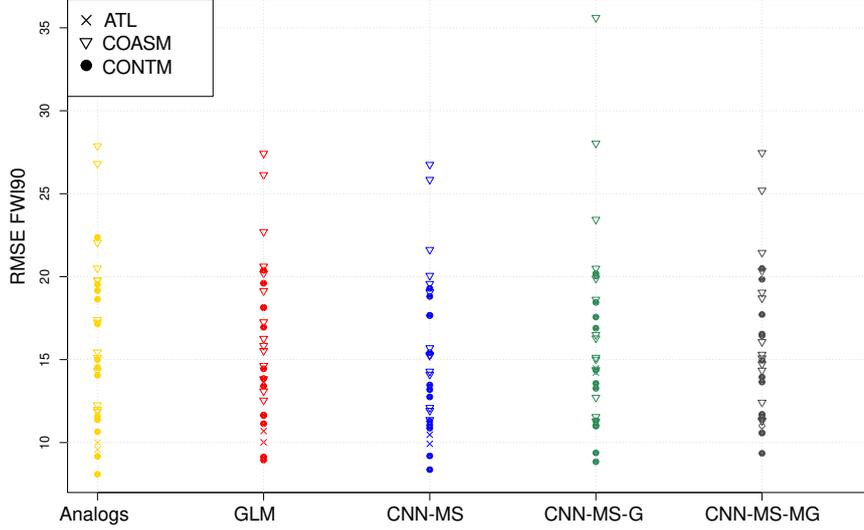


Figure C1. RMSE for the simulated FWI90 per station and method distinguishing the regions by symbols.

	CL	MIL	CL Bias	MIL Bias
AEMET_13UTC_FWI	208.30	168.22		
Analogs			11.68	-2.45
CNN-MS			285.91	259.81
CNN-MSG			<i>NA</i>	<i>NA</i>
CNN-MSMG			68.63	119.67
GLM			211.37	146.92

Table C1. The columns display the CL and MIL values for the reference observations, as well as the CL and MIL biases for the models, measured in kilometers (km). The lowest CL and MIL biases (excluding the benchmarking analogs method) are highlighted in boldface.

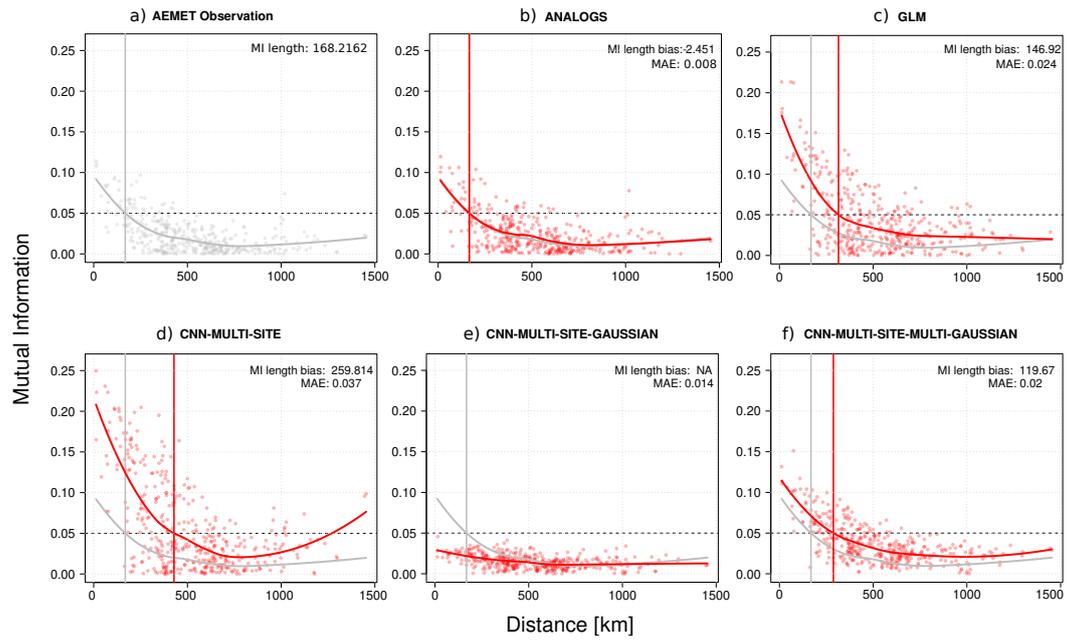


Figure C2. Mutual Information diagrams for FWI90 for fire season (JJAS) showing the mutual information of the FWI90 time series for each pair of stations against their geographical distances. The MI and MI length for the reference observations are shown in the upper left panel. In the rest of the panels, the MI length bias and the MAE are indicated at the top right of the panel.

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Optimization of Convolutional Neural Network models for spatially coherent multi-site fire danger predictions

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Key Points:

- Convolutional neural networks (CNNs) are compared with classical statistical down-scaling methods for Fire Weather Index (FWI) prediction.
- The best CNN setup provides balanced results for all validation metrics, including accuracy, simulation of extremes and spatial consistency.
- Our findings provide a methodological basis for the development of more robust, spatially coherent regional future FWI scenarios.

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18 Abstract

19 The accurate prediction of the Fire Weather Index (FWI), a multivariate climate
20 index for wildfire risk characterization, is crucial for both wildfire management and climate-
21 resilient planning. Moreover, consistent multisite fire danger predictions are key for tar-
22 geted allocation of resources and early intervention in high-risk areas, as well as for “megafire”
23 risk detection. In this regard, Convolutional Neural Networks (CNNs) are known to cap-
24 ture complex spatial patterns in climate data. This study compares different CNN ar-
25 chitectures and traditional Statistical Downscaling (SD) methods (regression and analogs)
26 for predicting daily FWI across diverse locations in Spain, considering marginal, distri-
27 butional and spatial coherence measures for validation. Overall, the CNN-Multi-Site-Multi-
28 Gaussian configuration, which explicitly accounts for the inter-site variability in the out-
29 put layer structure, showed a superior performance. These insights provide a method-
30 ological guidance for the successful application of CNNs in the context wildfire risk as-
31 sessment, enhancing wildfire response strategies and climate adaptation planning.

32 **Keywords:** deep learning, statistical downscaling, Generalized Linear Models, analogs,
33 spatial structure, future wildfire risk assessment.

34 Plain Language Summary

35 This study focuses on the Fire Weather Index (FWI), a pivotal climate index for
36 the assessment of wildfire risk. Accurate FWI predictions are vital for wildfire manage-
37 ment. This study explores the viability of employing Convolutional Neural Networks (CNNs)
38 as a Statistical Downscaling (SD) technique for precise FWI prediction across diverse
39 locations in Spain in comparison with two conventional SD methodologies: Generalized
40 Linear Models and analogs. Following a cross-validation scheme based on observed daily
41 FWI data, we find that the CNN-Multi-Site-Multi-Gaussian (CNN-MSMG) configura-
42 tion exhibits noteworthy proficiency in daily FWI prediction. This model explicitly in-
43 corporates the covariance structure of the predictands into the CNN architecture, yield-
44 ing spatially consistent FWI predictions. Furthermore, CNN-MSMG has optimal prop-
45 erties for use in the context of climate change, providing a robust replication of extreme
46 events and extrapolation capabilities if applied to novel climate scenarios. These find-
47 ings have substantial implications for improving regional-to-local FWI scenarios used to
48 inform vulnerability and impact assessment studies.

49 1 Introduction

50 Climate fire danger indices are key to assess and predict the risk of wildfire occur-
51 rence and severity. They are based on the integration of daily near-surface temperature,
52 humidity, wind speed and precipitation records (de Groot et al., 2006), and thus provide
53 more accurate wildfire risk forecasts than their input variables alone (see e.g. Dowdy et
54 al., 2009; Fugioka et al., 2009). Beyond the near-term prediction horizon, fire danger in-
55 dices are also useful to monitor changes in wildfire risk over time. As a result, downscaled
56 fire danger scenarios are essential for vulnerability and adaptation strategies in regional
57 to local applications, since General Circulation Model (GCM) outputs (Eyring et al., 2016)
58 can’t provide actionable climate information at these spatial scales (Giorgi et al., 2009).
59 Given their suitability for most impact studies, statistical downscaling (SD, Maraun &
60 Widmann, 2018) of future fire weather scenarios is often required, including *perfect-prognosis*
61 methods (Bedia et al., 2013, see Sec. 2.1) or bias-adjustment tools (Abatzoglou & Brown,
62 2012; Casanueva et al., 2018). In this case, there are three key aspects to focus on: (1)
63 the reproducibility of extremes, as they can substantially increase wildfire impacts (Turco
64 et al., 2018); (2) extrapolation capability is vital for predicting of out-of-sample values,
65 since fire danger conditions are expected to change drastically in many regions (Bedia
66 et al., 2015; Quilcaille et al., 2023), and (3) the ability to keep the predictand’s (FWI)

67 spatial consistency is important to identify potentially hazardous fire risk scenarios af-
68 fecting a wide geographical area, thereby increasing the odds of “fire clusters” with catas-
69 trophic potential (San-Miguel-Ayanz et al., 2013).

70 While most standard SD methods show good performance in at least one of these
71 3 aspects (Maraun et al., 2019), none of them is able to effectively accomplish all of them.
72 In this context, the classical analog method (Lorenz, 1969; Zorita & von Storch, 1999;
73 Brands et al., 2011) is still a competitive benchmark due to its ability to model both the
74 extremes and the spatial structure (Widmann et al., 2019). However, if applied in its origi-
75 nal form (Zorita & von Storch, 1999), this method fails to extrapolate beyond observed
76 extremes, limiting its use for climate change applications (Bedia et al., 2013). In this sense,
77 regression-based models are the better choice since they allow for better extrapolation
78 (Baño-Medina et al., 2021; Balmaceda-Huarte et al., 2023) but, on the downside, they
79 usually underestimate the extremes (Hertig et al., 2019). A further disadvantage of stan-
80 dard regression models (including Generalized Linear Models, GLMs) is their single-site
81 structure unable to effectively model the spatial dependencies of the predictand variable(s).
82 Other proposed alternatives combine the benefits of perfect-prog models and Weather
83 Generators (PP-WG, see e.g.: Cannon, 2008; Carreau & Vrac, 2011), allowing to esti-
84 mate the uncertainty of a local predictand variable and even to sample from the condi-
85 tional distributions to recover the variability of the time series. To date, however, and
86 with some exceptions (Legasa et al., 2023), most of these studies have focused on the es-
87 timation of uni-variate, single-site distributions, thereby not taking into account the spa-
88 tial structure of the predictand nor its relationships with other predictand variables.

89 In this regard, deep learning methods, and in particular Convolutional Neural Net-
90 works (CNNs, LeCun et al., 1995) may offer a suitable alternative to meet these require-
91 ments with an adequate tuning. CNNs perform convolutions with learnable kernels over
92 the spatial dimensions of atmospheric fields, inferring a non-linear mapping between low-
93 resolution predictor fields and high-resolution predicand fields that has been shown to
94 outperform conventional SD methods in many aspects (Baño-Medina et al., 2020). Re-
95 garding extrapolation ability, CNNs can produce plausible future climate change scenar-
96 ios (Baño-Medina et al., 2021), comparable to those provided by dynamical downscal-
97 ing (Baño-Medina et al., 2022). For a better reproducibility of extremes, parametric-CNNs
98 (P-CNNs, Sec. 2.3) can estimate the parameters of conditional distributions given cer-
99 tain atmospheric conditions. As in the PP-WG approach, an adequate CNN architec-
100 ture is able to estimate the parameters of the whole joint (multi-site) probability struc-
101 ture of the covariance matrix and can coherently reproduce the spatial structure of the
102 predicted fire danger series across all predictand locations.

103 In this study we describe different CNN-based regression models for multi-site ex-
104 treme fire danger assessment under climate change conditions, based on Canadian Fire
105 Weather Index (van Wagner, 1987) records at 29 locations in Spain. We deploy three
106 alternative CNN topologies based on the PP-WG approach that estimate either uni-variate
107 or multi-variate Gaussian distributions on daily timescale. The validation is based on
108 specific measures of extreme reproducibility and spatial coherence, using classical SD meth-
109 ods (analogs and GLMs) as benchmark.

110 2 Data and Methods

111 2.1 Predictor set

112 Perfect-prognosis SD establishes empirical relationships between 1) the variabil-
113 ity of atmospheric variables operating on large scales, typically derived from a global re-
114 analysis with a resolution similar to that offered by current global climate models (Eyring
115 et al., 2016) and 2) the local-scale variability of the predictand of interest (here: FWI)
116 as represented by in-situ observations or gridded observational datasets derived there-

117 from. Once the SD model is calibrated, the learnt relationships can be applied to GCM
 118 (instead of reanalysis) predictors in order to derive local climate change projections if,
 119 ideally, the following requirements are fulfilled: The predictor variables should be real-
 120 istically represented by the GCMs (Fernandez-Granja et al., 2021; Brands, 2022; Brands
 121 et al., 2023), should carry the climate change signal and be physically related with the
 122 local variable. In addition, the SD model should be capable to extrapolate the learnt re-
 123 lationships to altered/unobserved climate regimes (Gutiérrez et al., 2013). For the case
 124 of FWI downscaling, the predictor selection under such non-perfect circumstances has
 125 been explored in a previous study we built upon here (Bedia et al., 2013). Namely, we
 126 use daily-mean 2m air temperature, the zonal and meridional wind velocity components
 127 at 10m, as well as temperature and specific humidity at the 850 hPa pressure level, cov-
 128 ering a spatial domain centered on the target region. These data have been retrieved from
 129 ERA-Interim (Dee et al., 2011) for the period 1985–2011 (see Table A2).

130 **2.2 Predictand: Fire Weather Index observations**

131 The FWI is a multivariable index, and therefore the downscaling approach must
 132 carefully consider the physical consistency of its input variables. When these are sep-
 133 arately downscaled, inter-variable dependencies may be modified leading to spatio-temporal
 134 inconsistencies in the simulated output fields that would affect the coherence of the out-
 135 put FWI predictions (see e.g.: Vrac & Friederichs, 2015). This uncertainty source is here
 136 circumvented by using the FWI index, rather than its components, as sole predictand
 137 variable. To this end, in-situ observations from 29 weather stations of the Spanish Me-
 138 teorological Agency (AEMET) were obtained, recording the required data for FWI cal-
 139 culation. The AEMET dataset provides instantaneous values of temperature, relative
 140 humidity and wind speed at 13:00 UTC, and last 24-h accumulated precipitation, recorded
 141 at 07:00 UTC. FWI calculation follows the methodology described by Bedia et al. (2013).
 142 For an optimal dataset completeness, we consider the calibration period 1985–2011.

143 **2.3 Convolutional Neural Networks**

144 To identify the key factors of the FWI spatial structure, we deploy three CNN ar-
 145 chitectures of increasing topological complexity (see Fig. 1). The backbone of these topolo-
 146 gies builds on well tested CNNs known to outperform both analogs and GLMs in tem-
 147 perature and precipitation downscaling (Baño-Medina et al., 2020). The hidden struc-
 148 ture consists of 3 convolutional layers followed by two fully-connected ones. The convo-
 149 lutional layers consist of a block of three layers with 50, 25, and 10 (3×3) kernels respec-
 150 tively, while the fully-connected (dense) layers each contain 50 neurons for the CNN-Multi-
 151 Site (CNN-MS) and CNN-Multi-Site-Gaussian (CNN-MSG) configuration, or 200 neu-
 152 rons for the CNN-Multi-Site-Multi-Gaussian (CNN-MSMG) version (see Fig. 1). A non-
 153 linear ReLU activation function is applied between the layers. The output, where we find
 154 the main differences across models, is a dense fully-connected network with a linear ac-
 155 tivation function in CNN-MSG and CNN-MSMG. In the case of CNN-MS, the output
 156 layer consists of 29 neurons, each neuron corresponding to a point location (Table A1),
 157 yielding deterministic FWI predictions at each site.

158 In order to improve the representation of FWI extremes, we introduce modifica-
 159 tions to the P-CNN structures in CNN-MSG and CNN-MSMG. In CNN-MSG, the out-
 160 put is modeled stochastically using an *independent* Gaussian distribution to estimate the
 161 parameters of $\mathcal{N}(\mu, \sigma)$ (mean and standard deviation respectively). Thus, for each of the
 162 29 stations, two pairs of neurons are added to the output layer, one for each parameter.
 163 CNN-MSMG, in turn, aims to estimate the parameters of a *multivariate* Gaussian dis-
 164 tribution $\mathcal{N}(\mu, \Sigma)$. In this case, μ denotes the mean and Σ represents the covariance ma-
 165 trix. Therefore, the output layer consists of a pair of neuron vectors, with sizes 29 and
 166 464 respectively. The 29 neurons represent the μ parameters, while the 464 neurons cor-
 167 respond to the number of unique parameters estimated in the covariance matrix Σ . The

168 aim of this multivariate Gaussian setup is to describe the values at each location as a
 169 correlated set, unlike the outcome of an independent Gaussian distribution, where the
 170 predictions at each site are independent of each other. The general architecture scheme
 171 for each P-CNN configuration is outlined in Fig. 1. To avoid model overfitting, ensure
 172 robustness and optimize parameter tuning and CNN architectures, all SD models have
 173 been fit following a cross-validation procedure comprising 4 temporal blocks spanning
 174 the periods 1985-1991, 1992-1998, 1999-2004 and 2005-2011. The loss functions used are
 175 the Mean Square Error (MSE) for CNN-MS, the negative log-likelihood of the independ-
 176 ent Gaussian distribution for CNN-MSG, and the negative log-likelihood of the mul-
 177 tivariate Gaussian distribution for CNN-MSMG. The benchmark SD methods (analogs
 178 and GLMs) have been fitted following the same cross-validation scheme (see Appendix
 179 B for additional details on these methods).

180 2.4 Validation

181 Here, the Root Mean Square Error (RMSE) and Mean Absolute Error (MAE), as
 182 well as the quantile-quantile plot (QQ-plot), are used to validate the similarity of the tem-
 183 poral sequence and empirical distribution between the downscaled and observed daily
 184 FWI time series at a given station (Déqué, 2011). Apart from these classical marginal
 185 validation metrics, the focus is put on *spatial* coherence, as outlined in the following.

186 2.4.1 Location Correlogram

187 To qualitatively evaluate whether the distinct SD methods are able to reproduce
 188 the spatial correlation structure of the observed FWI, we use the *location correlogram*
 189 (Herdin et al., 2005). Firstly, the $n = 29$ observed daily *in-situ* FWI time series from
 190 the complete station network are correlated with each other for all possible combinations
 191 (i.e. $n \times \frac{n-1}{2}$ pairs) using Spearman’s rank correlation coefficient and the resulting co-
 192 efficients are plotted against the respective pairwise station distances. Then a local 2nd-
 193 order polynomial (“loess”) is fitted to the scatter-plot, resulting in a curve that depicts
 194 the spatial correlation structure of the observed FWI. As a quantitative summary mea-
 195 sure, we use the *correlation length* (CL), defined as the geographical distance correspond-
 196 ing to the point of intersection of a given correlation threshold with the fitted loess line.
 197 A threshold of $\rho = 0.4$ has proven to be most suitable for characterizing the spatial FWI
 198 structure in this study (Table Appendix C), and the overall results are robust to changes
 199 in this choice. After applying the same method to the downscaled time series from each
 200 of the three SD methods, the CL bias between the simulated and observed spatial struc-
 201 ture is calculated as an overall measure of the methods’ capability to reproduce the spa-
 202 tial coherence of the observed FWI (Widmann et al., 2019).

203 2.4.2 Mutual information for FWI90

204 FWI extremes are particularly relevant for fire danger assessment. As a result, from
 205 the spatial consistency point of view, the users of downscaled FWI values will be primar-
 206 ily interested in a realistic representation of joint higher-percentile FWI exceedances among
 207 locations (see e.g. Bedia et al., 2014). To this aim, Mutual Information (*MI*) provides
 208 a suitable measure of the dependence between two random variables X, Y (here, predic-
 209 tions at two locations) that is unaffected by their marginal distributions and quantifies
 210 the amount of mutual information between them (see e.g. Hlinka et al., 2013). For two
 211 discrete random variables X and Y it is defined as:

$$MI(X, Y) = \sum_{x \in X} \sum_{y \in Y} p(x, y) \cdot \log \left(\frac{p(x, y)}{p(x) \cdot p(y)} \right) \quad (1)$$

212 *MI* is zero if the two events are independent, i.e. if $p(X, Y) = p(X) \cdot p(Y)$, non-negative
 213 ($MI(X, Y) \geq 0$) and symmetric ($MI(X, Y) = MI(Y, X)$).

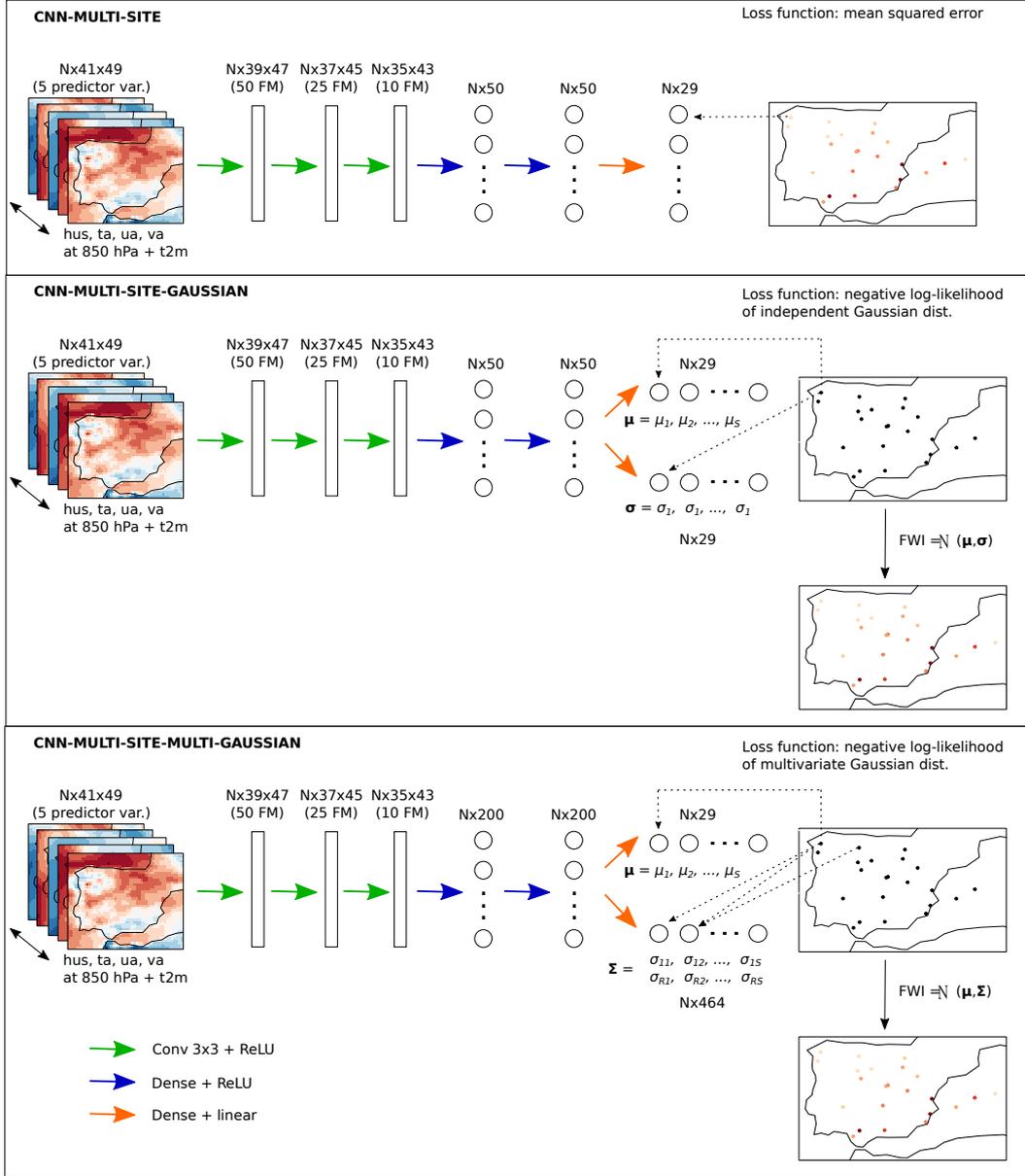


Figure 1. Scheme of the convolutional neural network architecture used in this study. The network includes a first block of three convolutional layers with 50, 25 and 10 (3x3) kernels, respectively, followed by two fully connected dense layers with 50 or 200 neurons each, depending on the model. For CNN-MSG and CNN-MMSG, the output is modeled through an independent Gaussian distribution and a multivariate Gaussian distribution respectively, and the corresponding parameters are estimated by the network, obtaining FWI as final product, either deterministically (CNN-MS) or stochastically (CNN-MSG and CNN-MMSG). The output layer is activated linearly while the previous layers of the network are activated non-linearly.

214 Here, we consider the binary variables X, Y at each location, stating whether the
 215 FWI values x_i, y_i lie above or below the 90th percentile for each pair of locations. We
 216 then calculate the MI for each pair of locations following the definition above (eq. 1).
 217 As for the correlograms (Sec. 2.4.1), we plot each MI_{ij} against the distance of the lo-

218 cations i, j and fit a degree-2 loess curve to the resulting scatter-plots. We then define
 219 MI thresholds for calculating the MI lengths (MIL) in observations and for the differ-
 220 ent downscaling methods. We use a MI threshold of 0.05, yielding results comparable
 221 to those obtained from CL analysis, and focusing on the identification of potential new
 222 information about each methods' performance (Fig. C2). As in CL analysis, the MIL
 223 biases are calculated as the difference between predicted and observed MILs.

224 3 Results

225 The results presented correspond to the generic June to September fire season, rep-
 226 resentative of the Iberian Peninsula (JJAS, see e.g.: Bedia et al., 2014). It's important
 227 to highlight that the models were calibrated using the entire annual dataset. However,
 228 a subset comprising the JJAS season was used to present the results relevant for fire dan-
 229 ger assessment in this region. In the following subsections, we categorized the station
 230 network into three groups based on proximity to the sea and general climate conditions:
 231 Atlantic, Coastal Mediterranean, and Continental Mediterranean (see Table A1). The
 232 suitability of this classification for FWI aggregation is confirmed by the results obtained
 233 with the mutual information measure (Sec. 3.2.2).

234 3.1 Predictive accuracy and distributional similarity

235 In agreement with previous studies (Brands et al., 2011), the SD methods' accu-
 236 racy is *generally* lower at continental sites than near the coast. Overall, all methods per-
 237 form similarly with regard to predictive accuracy, summarized in terms of the RMSE of
 238 FWI90 predictions in Fig. C1 (Appendix C).

239 However, the distributional characteristics of the predictions differ largely among
 240 methods. The quantile-quantile (QQ) plots shown in Fig. 2 compare the observed and
 241 predicted empirical FWI distributions. While all methods perform well in predicting the
 242 mean FWI, disparities emerge at higher percentiles, crucial for fire danger analysis. The
 243 benchmarking analog approach produces best results for the right tail, closely followed
 244 by multivariate CNN-MSMG, showing similar results across regions. Conversely, GLM
 245 and CNN-MS consistently underestimate high percentile FWI events, failing to realis-
 246 tically represent most dangerous situations. CNN-MSG also achieves good results, com-
 247 parable to CNN-MSMG, but is outperformed by the latter in the Coastal Mediterranean
 248 and Atlantic regions. Notably, in the Atlantic region, CNN-MSG unrealistically inflates
 249 the highest FWI percentiles and underestimates most of the FWI distribution. On the
 250 contrary, in the Continental Mediterranean region, CNN-MSG performs slightly better
 251 than CNN-MSMG for higher percentiles.

252 In order to obtain a quantitative measure of distributional deviance with respect
 253 to the observed distribution, we calculate the RMSE considering the differences between
 254 predicted and observed quantiles of i) the entire FWI times series and ii) the FWI time
 255 series values exceeding the station-specific 90th percentile (FWI90, Fig. 2). Excluding
 256 the results for the analog method, lowest RMSE values for both indicators are obtained
 257 either by CNN-MSG or CNN-MSMG. Regardless of the specific target region, the for-
 258 mer approach demonstrates significantly better performance compared to the latter in
 259 terms of FWI, and only exhibits a slight decrease in performance for FWI90. Specifically,
 260 when emphasizing FWI90, the CNN-MS and GLM models exhibit noticeably poorer per-
 261 formance compared to the analog benchmark. In contrast, the results for CNN-MSG and
 262 CNN-MSMG models are considerably better in this regard.

263 Overall, the reference analog method performs best in representing the distribu-
 264 tion of the daily FWI in most cases. CNN-MSG and CNN-MSMG perform slightly worse,
 265 with CNN-MSG slightly overemphasizing severe FWI frequencies in the Atlantic region.
 266 The analog method performs best overall, but it's applicability in climate changes stud-

267 ies is limited due to its inability to extrapolate predictions outside the observed range.
 268 Conversely, both CNN-MSG and CNN-MSMG are competitive alternative methods in
 269 terms of distributional similarity. In the Secs. 3.2.1 and 3.2.2, we assess whether these
 270 conclusions hold for the *spatial structure* of the simulated mean and extreme FWI fields.

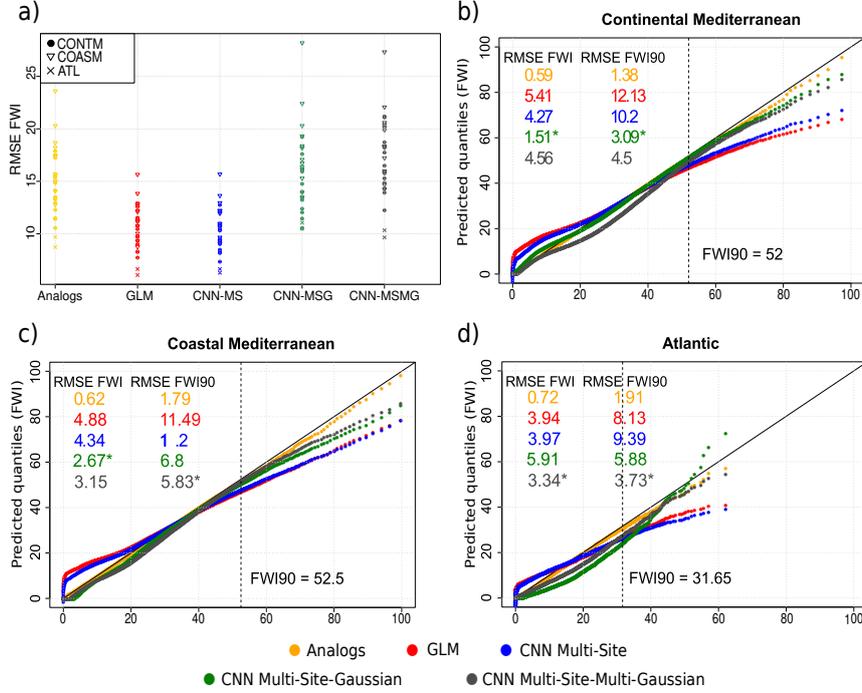


Figure 2. FWI RMSE per station and method (a) and Q-Q plots for the analog method, GLMs and the distinct CNN models (b - d). The figure is divided into 4 panels. The (a) panel refers to the RMSE for the simulated FWI per station and method distinguishing the regions by symbols. The remaining panels refer to the station subsets of (b) the Continental Mediterranean, (c) Coastal Mediterranean and (d) Atlantic regions. The method-specific distributional RMSE for the simulated FWI and FWI90 are indicated in the upper left corners of each panel and the best performing method is marked with an asterisk (excluding the benchmarking analog method). The dashed vertical line indicates the observed FWI90.

271 3.2 Spatial validation results

272 3.2.1 Dependence of inter-station relationships on distance

273 The temporal correlation coefficients' dependence on distance, analyzed as described
 274 in Sec. 3, is depicted in Fig. 3. As expected, the observed strength of the relations de-
 275 creases exponentially with increasing distance between the stations and stabilizes around
 276 $\rho = 0.1$, the CL for $\rho = 0.4$ being located at 208.30 km (panel a), grey curve). The
 277 corresponding point clouds and polynomials for the SD methods are depicted in red in
 278 panels b) through f), where the respective validation measures are also indicated (see
 279 upper right corners and also Appendix C). The exponential decay seen in the observa-
 280 tions is reproduced more or less successfully by all SD methods except CNN-MSG, that
 281 produces far too weak short distance relationships, failing to reproduce any spatial structure
 282 in the data. The analog method is, as expected, most successful in reproducing the

283 observed correlation structure, closely followed by CNN-MSMG, while GLM and CNN-
 284 MS consistently overestimate pairwise correlations. Among the suitable methods (i.e.
 285 excluding CNN-MSG), the medium-to-long-distance correlations are overestimated by
 286 all methods, particularly by GLM and CNN-MS. The stronger short-distance correlations
 287 are also generally overestimated, but to a lesser degree, and they are almost per-
 288 fectly met by the analog method and closely approximated by CNN-MSMG.

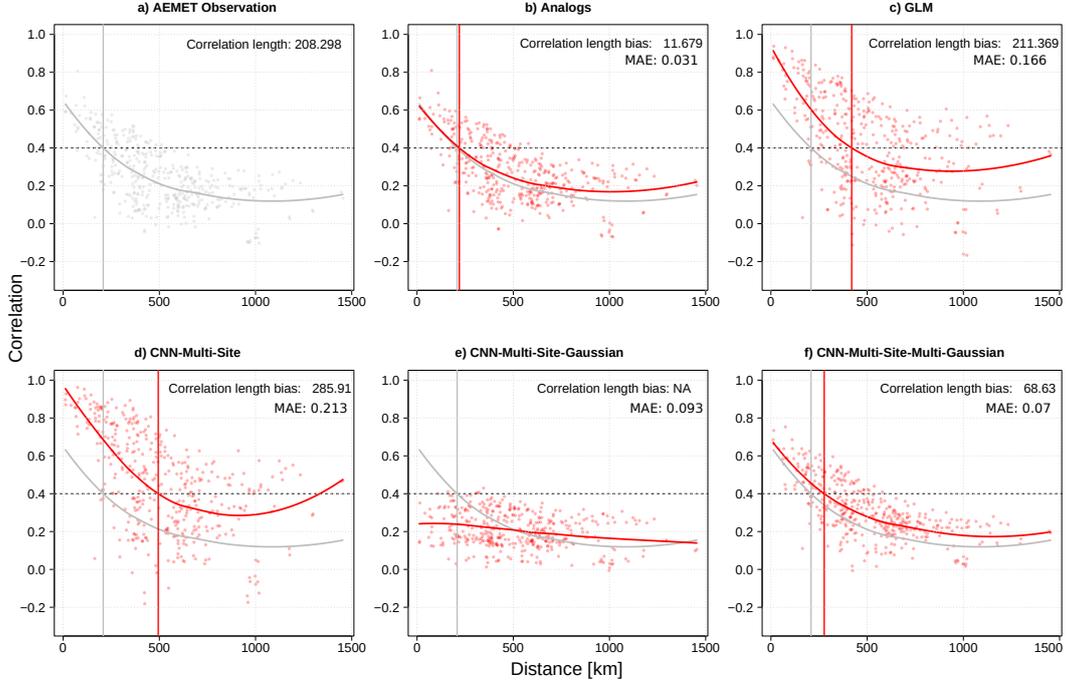


Figure 3. Correlograms illustrating the daily JJAS FWI dependence of the inter-station relationships, described by the Spearman correlation coefficients among all station pairs (y-axis), against their respective distances in kilometers (x-axis). The correlograms correspond to the observations (panel *a*) and to each SD method tested (panels *b* to *f*); the grey loess line of the observations correlogram is included in all panels for visual comparison. It is also displayed the observed Correlation Length (CL, panel *a*) and the CL bias and MAE for each SD method (in panels *b* to *f*). Here, the MAE is calculated as the difference (in absolute value) between predicted and observed correlation coefficients for each station pair.

289 **3.2.2 Mutual information for fire weather extremes**

290 In Fig. 4 (upper panel), we present the mutual information (MI) values obtained
 291 from the observational network in the upper triangle (a1), compared with those produced
 292 by CNN-MSMG, the best performing SD method for this metric (the benchmarking analog
 293 method is excluded), in the lower triangle (a2). The stations are grouped into char-
 294 acteristic climate regimes as described in Sec. 3.1. Geographical proximity translates into
 295 higher MI values, as the case of Vigo and Santiago de Compostela (NW Iberia, $MI =$
 296 0.11), Barajas and Retiro (Madrid, central Spain, $MI = 0.14$), or Valencia and Valencia-
 297 Airport (SE, Mediterranean coast, $MI = 0.13$). Furthermore, several climatologically
 298 homogeneous regions can be identified in the matrix, yielding visually discernible clus-
 299 ters of high MI values, e.g. the Soria-Valladolid-Salamanca-Zamora cluster pertaining
 300 to the central-north Iberian high plains. The MI pattern obtained from CNN-MSMG

301 is similar to that seen in observations and is thus approximately symmetric (compare
302 Fig. 4-a2 with a1). Nevertheless, CNN-MSMG somewhat overestimates the spatial de-
303 dependencies, indicated by slightly higher MI values than those obtained from observations,
304 and also reflected by regional clusters not seen in observations (e.g. Ciudad Real, Bada-
305 joz and Granada).

306 In Fig. 4b and c, we illustrate the MI biases relative to the observations for CNN-
307 MS and CNN-MSG (b1, b2), as well as for CNN-MSMG and GLM (c1, c2). We focus
308 on station pairs with MI values ≥ 0.05 in observations, thus discarding already inde-
309 pendent station pairs (blank matrix cells). Since the MI bias of the analog method is neg-
310 ligible for all station pairs, the corresponding results are shown in Appendix Appendix
311 C. The MI bias of CNN-MSMG is below the 0.05 threshold for most station pairs, with
312 a few exceptions with both positive or negative values (Fig. 4c1). CNN-MS exhibits a
313 consistent positive bias, consistently overestimating the spatial dependence of extreme
314 FWI events (Fig. 4b1). CNN-MSG, in turn, systematically underestimates these depen-
315 dencies (Fig. 4b2), yielding a lower bias magnitude than for CNN-MS. The GLM ap-
316 proach tends to overestimate these dependencies, albeit to a lesser extent than CNN-MS
317 (compare Fig. 4c2 with b1).

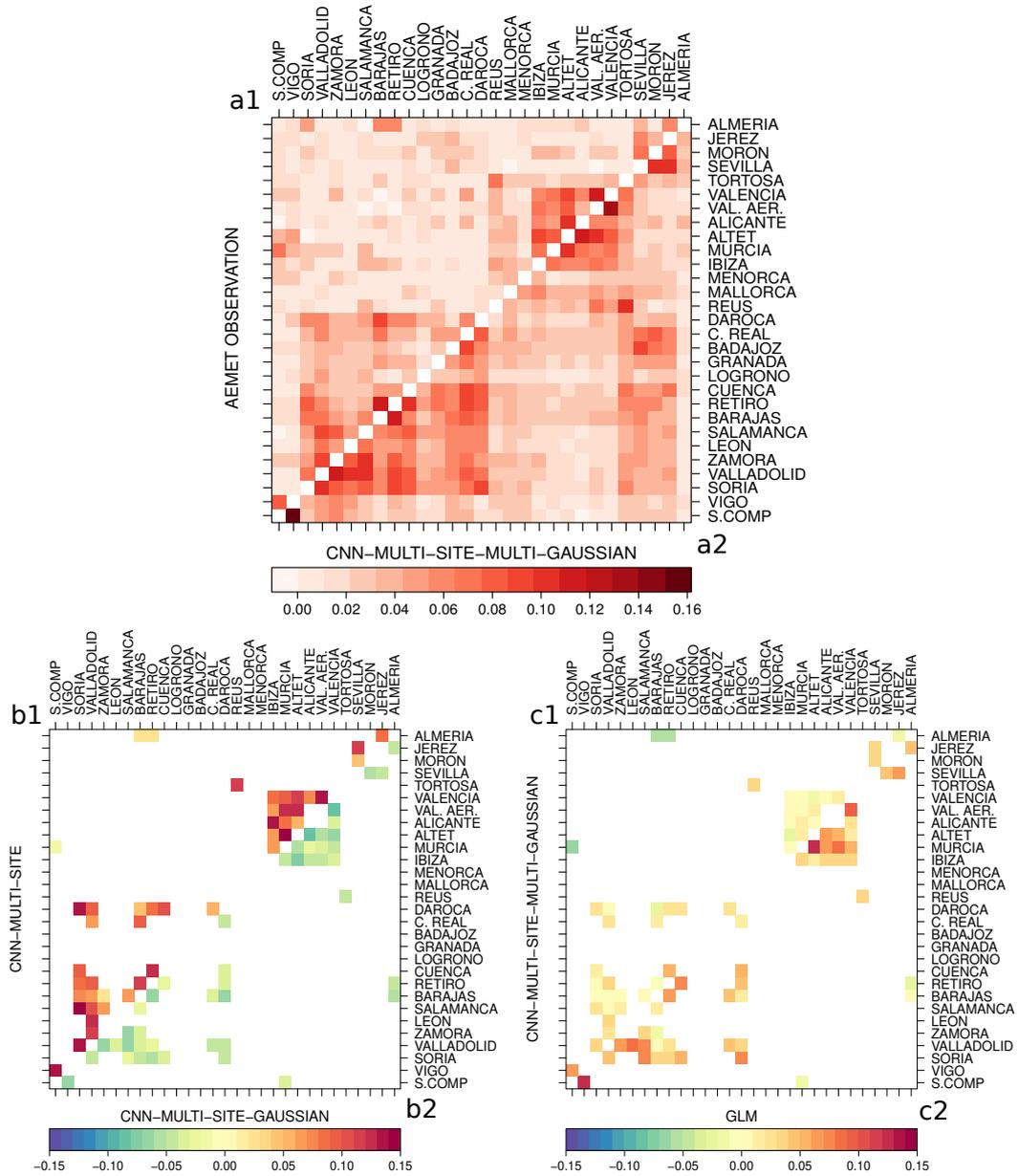


Figure 4. MI matrices for FWI90 events during the fire season (JJAS) obtained from observations (upper triangle in upper panel, a1) and from the best performing SD model (CNN-MSMG, lower triangle in upper panel, a2). Panels b and c show the MI biases for 4 remaining SD methods with respect to the observations (b1: CNN-MS, b2: CNN-MSG, c1: CNN-MSMG, c2: GLM). In b and c panels, only station pairs with $MI \geq 0.05$ in the observations are shown.

4 Conclusions

We conducted a comprehensive comparison of various Convolutional Neural Network (CNN) architectures in contrast to two established statistical downscaling (SD) methods, specifically Generalized Linear Models (GLMs) and analogs. Our assessment focused on evaluating their performance in terms of predictive accuracy, distributional congruence, and spatial coherence for Fire Weather Index (FWI) predictions across 29 locations in Spain.

Among the diverse CNN architectures scrutinized, CNN-MSMG demonstrated the most favorable outcomes across these validation criteria. This setup considers the multivariate nature of the predictions in the output layer yielding a predicted covariance matrix that explicitly accounts for the inter-site variability. It exhibited a notable capacity to accurately represent observed FWI distributions at both single-point and multi-site scales, closely aligning with the outcomes of the benchmarking analogs method. Notably, the analogs method, by design, upholds multisite spatial consistency without alteration, at the cost of limitations for extrapolation in climate change conditions that can be overcome by the rest of methods tested. In contrast CNN-MS (multisite CNN) and GLMs yielded poorer predictive accuracy and consistently overestimated the spatial dependence among sites. In turn, CNN-MSG (multisite Gaussian) attained good results in terms of single-site validation, but proved inefficient in modelling the spatial structure, essentially behaving like a single-site weather generator.

The results presented emphasize the importance of parameter tuning for CNN development in the context of statistical downscaling in order to produce credible predictions. In the particular case of FWI, an adequate tuning is needed in order to ensure actionable climate information for the prevention of wildfire impacts, and this study provides a methodological guidance for the successful application of CNNs to this aim.

5 Open Research

We follow the FAIR principles (Findability, Accessibility, Interoperability and Reuse, Wilkinson et al. (2016)) and publish the code (DOI: 10.5281/zenodo.8387558) and the data (DOI: 10.5281/zenodo.8381437) required to replicate the results presented in this manuscript. We build on the R based (R Core Team, 2020) framework *climate4R* (Iturbide et al., 2019) to digest, manipulate, downscale (see also Bedia et al., 2020) and visualize (Frías et al., 2018) the climate data. For the deep learning models, we lean on *downscaleR.keras*, a library that integrates *tensorflow* (Abadi et al., 2015) and *keras* (Gulli & Pal, 2017) into the *climate4R* framework (Baño-Medina et al., 2020).

Appendix A Input Data

Table A1 is a summary of the AEMET weather station database. We also indicate their corresponding climatic zone, according to the spatial aggregation summarizing the results in Sec. 3.1 of the main text. The *Short name* column indicates the abbreviated labels used throughout the article figures.

Station name	Short name	Lon	Lat	Altitude	Climatic region
REUS–AEROPUERTO	REUS	1.18	41.15	71	COASM
SANTIAGO DE COMPOSTELA–LABACOLLA	S.COMP	-8.41	42.89	370	ATL
VIGO–PEINADOR	VIGO	-8.62	42.24	261	ATL
SORIA	SORIA	-2.48	41.77	1082	CONTM
VALLADOLID	VALLADOLID	-4.75	41.64	735	CONTM
ZAMORA	ZAMORA	-5.73	41.52	656	CONTM
LEÓN–VIRGEN DEL CAMINO	LEÓN	-5.65	42.59	916	CONTM
SALAMANCA–MATACÁN	SALAMANCA	-5.50	40.96	790	CONTM
MADRID–BARAJAS	BARAJAS	-3.56	40.47	609	CONTM
MADRID–RETIRO	RETIRO	-3.68	40.41	667	CONTM
CIUDAD REAL	C. REAL	-3.92	38.99	628	CONTM
BADAJOS–TALAVERA LA REAL	BADAJOS	-6.81	38.88	185	CONTM
GRANADA–AEROPUERTO	GRANADA	-3.79	37.19	567	CONTM
SEVILLA–SAN PABLO	SEVILLA	-5.88	37.42	34	COASM
MORÓN DE LA FRONTERA	MORÓN	-5.61	37.16	87	COASM
JEREZ DE LA FRONTERA–AEROPUERTO	JEREZ	-6.06	36.75	27	COASM
ALMERÍA–AEROPUERTO	ALMERÍA	-2.36	36.85	21	COASM
MURCIA–SAN JAVIER	MURCIA	-0.80	37.79	4	COASM
ALICANTE–EL ALTET	ALTET	-0.57	38.28	43	COASM
ALICANTE	ALICANTE	-0.49	38.37	81	COASM
CUENCA	CUENCA	-2.14	40.07	945	CONTM
VALENCIA–AEROPUERTO	VAL. AER.	-0.47	39.49	69	COASM
VALENCIA	VALENCIA	-0.37	39.48	11	COASM
LOGROÑO–AGONCILLO	LOGROÑO	-2.33	42.45	353	CONTM
DAROCA	DAROCA	-1.41	41.11	779	CONTM
TORTOSA	TORTOSA	0.49	40.82	44	COASM
PALMA DE MALLORCA–SON SAN JUAN	MALLORCA	2.74	39.56	8	COASM
MENORCA–MAÓ	MENORCA	4.22	39.85	91	COASM
IBIZA/ES CODOLA	IBIZA	1.38	38.88	6	COASM

Table A1. Selected stations of the Spanish AEMET network, indicating their position in decimal degrees and meters above sea level (Datum WGS-84). The abbreviations corresponding to the climatic regions in the column are as follows: ATL for Atlantic, COASM for Coastal Mediterranean, and CONTM for Continental Mediterranean.

Table A2 provides a summary of the reanalysis fields used as predictors in this study. The predictor set has been chosen following the methodology for FWI downscaling presented by Bedia et al. (2013), but replacing relative humidity by specific humidity, the former being not directly available in some model simulation databases. The spatial extent of these fields covers a bounding box centered over the Iberian Peninsula, limited by the geographical coordinates $-10^{\circ}/15^{\circ}\text{E}$, $35^{\circ}/45^{\circ}\text{N}$.

Appendix B Benchmarking SD methods

We next provide further methodological details on the standard SD methods used as benchmarks in this study. Both are implemented in the R package `downscaleR` (Bedia et al., 2020), part of the `climate4R` framework for climate data analysis and visualization (Iturbide et al., 2019, <https://github.com/SantanderMetGroup/climate4R>).

Code	Name	units
T2M	Air Temperature at surface	K
T850	Air Temperature at 850 hPa	K
HUS850	Specific humidity at 850 hPa	$g\ kg^{-1}$
UA850	U-wind at 850 hPa	$m\ s^{-1}$
VA850	V-wind at 850 hPa	$m\ s^{-1}$

Table A2. Predictor variables used in this study, selected from the predictor combination proposed for statistical downscaling of FWI in Bedia et al. (2013). Note that for convenience, relative humidity at 850 hPa has been replaced by specific humidity, more commonly available in GCM datasets. All fields are daily mean values.

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B1 Generalized lineal models

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GLMs (Nelder & Wedderburn, 1972) are an extension of the classical linear regression that models the expected value of a random predictand variable for different types of probability distributions and link functions. This makes them a versatile tool for modeling a wide range of data types and situations, and therefore extensively used in SD applications (see e.g.: Chandler & Wheeler, 2002; Gutiérrez et al., 2019). Here, the response variable is assumed to follow a Gaussian distribution. The relationship between the linear predictor $g(\mu)$ and the expected value of FWI is defined by the identity link function, so the linear predictor directly models the mean FWI, where $g(\mu)$ is defined as $g(\mu) = \mathbf{X}\beta$, where \mathbf{X} is the design matrix containing the predictor variables (Sec. 2.1), and β is the vector of coefficients, estimated by maximum likelihood based on the probability density function of the Gaussian distribution using a least-squares iterative algorithm implemented in the R package `stats` (R Core Team, 2020). Furthermore, predictor configuration is such that only local information is used for training at each site. Here, an optimal number of 16 closest grid-points to each predictand point-location are retained to construct the local predictor set (Bedia et al., 2020), after testing different neighbourhood sizes using cross-validation (Sec. 2.3).

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B2 Analogs

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The analog method is a simple yet powerful downscaling technique which assumes that similar (or analog) atmospheric patterns (predictor set \mathbf{X}) over a region originates similar local meteorological outcomes (daily FWI) for a particular location or set of locations (Sec. 2.2). In this study, we use the standard deterministic nearest neighbor method analog technique based on the Euclidean distance, considering the complete fields to compute distances and only the first closest nearest closest analog for prediction (San-Martín et al., 2016), similar to the standard ‘ANALOG’ method of the VALUE intercomparison experiment (described in Gutiérrez et al., 2019, A.2), and considering the implementation described in Bedia et al. (2020). Note that using the complete fields as predictors ensures the maximum spatial coherence of the predictions among stations, since the same analog dates are chosen in each case for every point-location (see e.g. Widmann et al., 2019).

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Appendix C Results

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This section contains additional results as indicated in the figure captions.

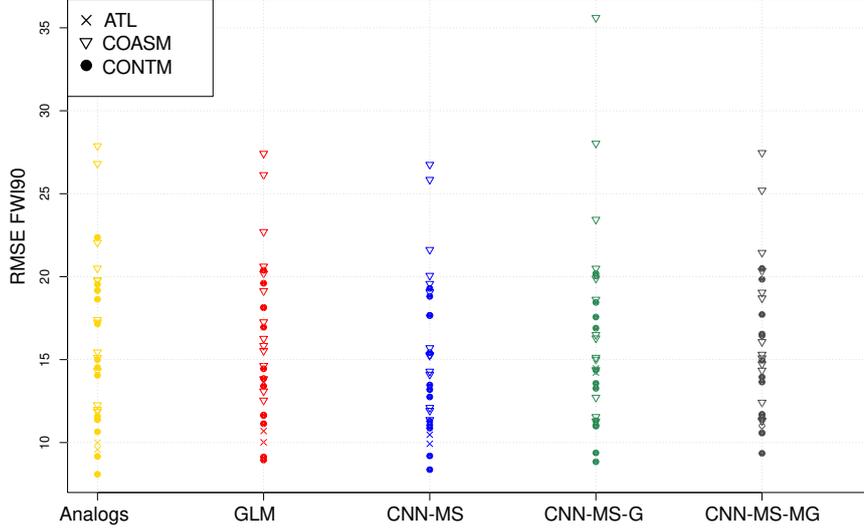


Figure C1. RMSE for the simulated FWI90 per station and method distinguishing the regions by symbols.

	CL	MIL	CL Bias	MIL Bias
AEMET_13UTC_FWI	208.30	168.22		
Analogs			11.68	-2.45
CNN-MS			285.91	259.81
CNN-MSG			<i>NA</i>	<i>NA</i>
CNN-MSMG			68.63	119.67
GLM			211.37	146.92

Table C1. The columns display the CL and MIL values for the reference observations, as well as the CL and MIL biases for the models, measured in kilometers (km). The lowest CL and MIL biases (excluding the benchmarking analogs method) are highlighted in boldface.

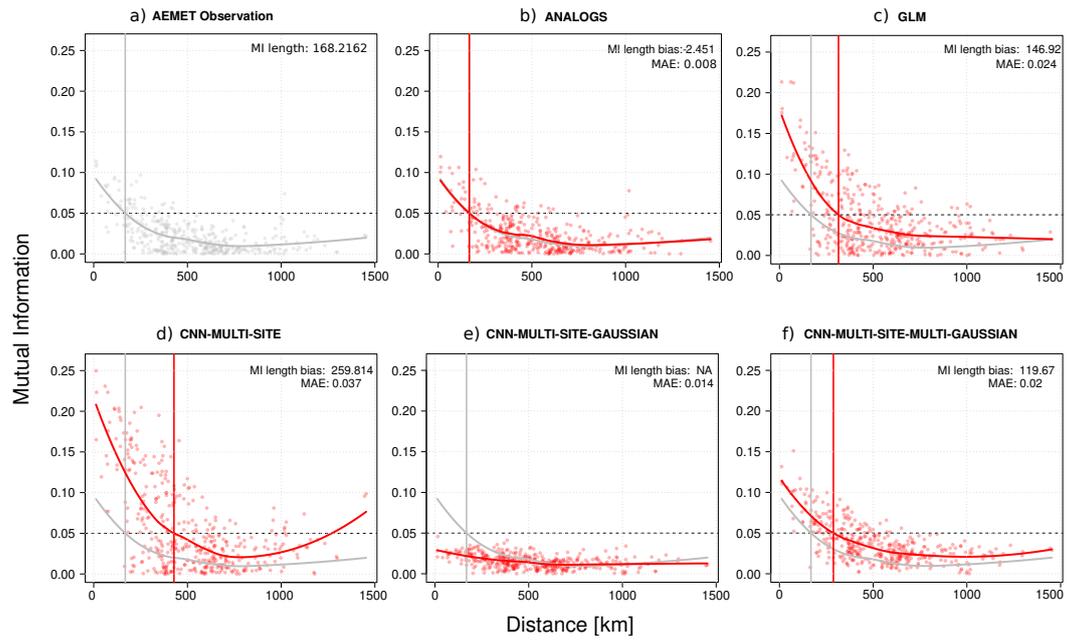


Figure C2. Mutual Information diagrams for FWI90 for fire season (JJAS) showing the mutual information of the FWI90 time series for each pair of stations against their geographical distances. The MI and MI length for the reference observations are shown in the upper left panel. In the rest of the panels, the MI length bias and the MAE are indicated at the top right of the panel.

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