

Exploring the Potential of Long Short-Term Memory Networks for Predicting Net CO₂ Exchange Across Various Ecosystems With Multi-Source Data

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Abstract

Upscaling flux tower measurements based on machine learning (ML) algorithms is an essential approach for large-scale net ecosystem CO₂ exchange (NEE) estimation, but existing ML upscaling methods face some challenges, particularly in capturing NEE interannual variations (IAVs) that may relate to lagged effects. With the capacity of characterizing temporal memory effects, the Long Short-Term Memory (LSTM) networks are expected to help solve this problem. Here we explored the potential of LSTM for predicting NEE across various ecosystems using flux tower data over 82 sites in North America. The LSTM model with differentiated plant function types (PFTs) demonstrates the capability to explain 79.19% ($R^2 = 0.79$) of the monthly variations in NEE within the testing set, with RMSE and MAE values of 0.89 and 0.57 g C m⁻² d⁻¹ respectively ($r = 0.89$, $p < 0.001$). Moreover, the LSTM model performed robustly in predicting cross-site variability, with 67.19% of the sites that can be predicted by both LSTM models with and without distinguished PFTs showing improved predictive ability. Most importantly, the IAV of predicted NEE highly correlated with that in flux observations ($r = 0.81$, $p < 0.001$), clearly outperforming that by the random forest model ($r = -0.21$, $p = 0.011$). Among all nine PFTs, solar-induced chlorophyll fluorescence, downward shortwave radiation, and leaf area index are the most important variables for explaining NEE variations, collectively accounting for approximately 54.01% in total. This study highlights the great potential of LSTM for improving carbon flux upscaling with multi-source remote sensing data.

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2 **Exploring the Potential of Long Short-Term Memory Networks for Predicting Net**
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21 **Key Points:**

- 22 • The LSTM model with differentiated PFTs demonstrates the capability to explain 79.19%
23 of the monthly variations in NEE.
- 24 • The LSTM model exhibited clear advantages over the RF model in capturing the
25 interannual variations of NEE.
- 26 • The relative importance of feature variables for predicting monthly NEE dynamics across
27 different PFTs in North America was quantified.
- 28

29 **Abstract**

30 Upscaling flux tower measurements based on machine learning (ML) algorithms is an essential
31 approach for large-scale net ecosystem CO₂ exchange (NEE) estimation, but existing ML
32 upscaling methods face some challenges, particularly in capturing NEE interannual variations
33 (IAVs) that may relate to lagged effects. With the capacity of characterizing temporal memory
34 effects, the Long Short-Term Memory (LSTM) networks are expected to help solve this
35 problem. Here we explored the potential of LSTM for predicting NEE across various ecosystems
36 using flux tower data over 82 sites in North America. The LSTM model with differentiated plant
37 function types (PFTs) demonstrates the capability to explain 79.19% ($R^2 = 0.79$) of the monthly
38 variations in NEE within the testing set, with RMSE and MAE values of 0.89 and 0.57 g C m⁻² d⁻¹
39 respectively ($r = 0.89$, $p < 0.001$). Moreover, the LSTM model performed robustly in predicting
40 cross-site variability, with 67.19% of the sites that can be predicted by both LSTM models with
41 and without distinguished PFTs showing improved predictive ability. Most importantly, the IAV
42 of predicted NEE highly correlated with that in flux observations ($r = 0.81$, $p < 0.001$), clearly
43 outperforming that by the random forest model ($r = -0.21$, $p = 0.011$). Among all nine PFTs,
44 solar-induced chlorophyll fluorescence, downward shortwave radiation, and leaf area index are
45 the most important variables for explaining NEE variations, collectively accounting for
46 approximately 54.01% in total. This study highlights the great potential of LSTM for improving
47 carbon flux upscaling with multi-source remote sensing data.

48 **Plain Language Summary**

49 Net ecosystem exchange (NEE) of CO₂ is a crucial process that regulates carbon exchange
50 between terrestrial ecosystems and the atmosphere. Currently, the growing availability of NEE
51 measurement data, multi-source remote sensing data and meteorological data, has made machine
52 learning algorithms a popular approach for estimating large-scale NEE. Various types of NEE
53 datasets have been derived with different methods; however, the ability in representing the
54 memory effects of climate and environmental factors remains a significant source of uncertainty
55 contributed to NEE estimates. To address this issue, we constructed site-level LSTM training
56 models by plant function types in North America for improving the monthly-scale simulation of
57 NEE and its interannual variations. The established LSTM model enables the prediction of the
58 temporal variability of NEE and effectively captures the memory effects over time, showing a
59 great potential for improving carbon flux upscaling.

60 **1 Introduction**

61 The net exchange of CO₂ between terrestrial ecosystems and the atmosphere (NEE) is an
62 essential component of the global carbon cycle (Bonan, 2008; Shevliakova et al., 2013).
63 Accurately estimating NEE is an essential step towards enhancing our understanding of the
64 feedback between the terrestrial carbon cycle and climate change and better predicting future
65 climate status. Accurately quantifying terrestrial NEE is also a prerequisite for implementing net-

66 zero policies. However, estimating large-scale NEE faces great challenges due to the complex
67 relationships among the physical, chemical, and biological processes.

68 Currently, there are three main ways for large-scale NEE estimation, including top-down
69 atmospheric CO₂ inversions, terrestrial biosphere models (TBMs) and eddy flux upscaling, the
70 latter two also calls bottom-up approaches. The top-down approach infers biosphere CO₂ fluxes
71 from atmospheric CO₂ observations onboard different observation platforms, such as tall towers,
72 aircraft, ships, and satellites (Ciais et al., 2014), which utilizes atmospheric CO₂ data and a
73 transport model to deduce the spatiotemporal distribution of carbon fluxes. Atmospheric
74 inversions are particularly beneficial for constraining large-scale carbon fluxes (He et al., 2023a;
75 He et al., 2023b), but providing limited spatial information on smaller scales, as uncertainties
76 increase with spatial scale decreases. The process-based TBMs consider the physical processes
77 of energy, carbon, and water cycle regulation. Nevertheless, the complexity of the model
78 structure and the inherent assumptions of specific parameters contribute to substantial
79 discrepancies in NEE simulations among various ecosystem models (Huntzinger et al., 2012).
80 Recently, the bottom-up approach for extrapolating eddy covariance (EC) data, i.e., flux
81 upscaling, shows advantages in accurately quantifying large-scale carbon fluxes. Traditionally,
82 EC technology has been used for continuous measurements at flux sites to develop and evaluate
83 NEE models at the site level. Subsequently, by using spatial variability predominantly driven by
84 Earth observation data, the net exchange of CO₂ and energy between terrestrial ecosystems and
85 the atmosphere can be estimated through spatial extrapolation. Empirical models use statistics to
86 identify certain patterns between meteorological and satellite remote sensing observations,
87 enabling them to capture even highly nonlinear relationships among explanatory variables and
88 carbon fluxes. With the growing availability of global flux observation data and multi-source
89 remote sensing data, there is an increasing interest in encouraging machine learning (ML)
90 technology to become another promising method for NEE prediction. Data-driven ML methods
91 are simple and effective in evaluating NEE, as they are entirely adaptable to the data and do not
92 rely on assumptions about terrestrial ecosystem patterns (Peylin et al., 2013). Various ML
93 algorithms have made advancements in estimating ecosystem carbon fluxes and exchange,
94 including Artificial Neural Networks (Papale & Valentini, 2003), Model Tree Ensemble (Liang
95 et al., 2020), and Random Forest (RF; Guo et al., 2023).

96 However, despite significant progress have made in the field of empirically upscaling
97 NEE from in-situ EC measurements, various sources of uncertainty remain (Jung et al., 2020).
98 Firstly, many regions around the world only provide point measurements from sparse flux site
99 networks (Tramontana et al., 2016), which contributes to a significant uncertainty regarding NEE
100 upscaling at the regional scale. Moreover, the accuracy of ML methods for estimating carbon
101 fluxes depends heavily on the variables used as driving factors and the limited information
102 available regarding all major ecosystem features that influence carbon fluxes (Huang et al.,
103 2021). An essential aspect of data limitation is the accessibility of pertinent explanatory
104 variables, which correspond to in-situ information at the site level and corresponding global
105 networks. Additionally, predictive factors can also hinder the evaluation of NEE variability,

106 emphasizing the need for more important feature variables to enhance our understanding of NEE.
107 In addition, the upscaling method could also impact flux upscaling, since their abilities in
108 characterizing the relationship between carbon flux and feature variables vary notably
109 (Tramontana et al., 2016; Jung et al., 2020).

110 When employing ML methods for spatial estimation of different carbon and energy
111 fluxes, NEE is recognized as the most challenging flux to predict (Bodesheim et al., 2018; Jung
112 et al., 2011; Tramontana et al., 2016). Particularly, the interannual variation (IAV) of NEE has
113 not been accurately estimated (Jung et al., 2020), predominantly due to the inability to represent
114 temporal dynamics of climate and vegetation activities. Extreme climate events and human
115 disturbances exhibit memory effects in the response of NEE. These effects refer to the influence
116 of past climate and environmental conditions on current and future ecosystem responses (Ogle et
117 al., 2015). This can lead to nonnegligible interannual changes in the terrestrial carbon budget.
118 The FLUXNET and AmeriFlux networks are composed of EC flux towers, which offer long-
119 term, high-temporal resolution measurements of the site-scale NEE. Remote sensing, being a
120 potentially powerful technology, offers ecosystem observations with consistent spatial and
121 temporal coverage. Recent rapid development of deep learning (DL) technology has shed new
122 light on Earth system modeling (Irrgang et al., 2021). In particular, its capacity for mining
123 historical time-series information from multi-source ecosystem observations offers a great
124 potential for improving terrestrial carbon flux estimation (Besnard et al., 2019; Liu et al., 2023),
125 which incorporates environmental memory into flux modeling while difficult to implement in
126 state-of-the-art process models. The Long Short-Term Memory model (LSTM) is a dynamic
127 statistical method that has demonstrated excellent performance on sequence data, such as crop
128 field classification (Rußwurm & Körner, 2018). With its distinctive design, the LSTM model can
129 effectively address long-term considerations and incorporate memory effects of climate and
130 vegetation, thus aiding in the representation of interannual fluctuations in carbon fluxes (Besnard
131 et al., 2019). To support this concept, we developed and applied an LSTM model to predict site-
132 level NEE in North America. This model utilizes meteorological and flux data sets from
133 FLUXNET and AmeriFlux networks, along with multi-source remote sensing data. We use
134 continuous monthly NEE data, which represent direct samples of NEE from sites encompassing
135 diverse biological communities and climate types in North America. The predictive performance
136 of the LSTM model was assessed in combination with NEE data obtained from EC flux towers,
137 regarding spatial variability and interannual changes in monthly NEE at both site and ecosystem
138 levels. The advantage of the LSTM model to capture climate and vegetation memory effects in
139 quantifying spatiotemporal variations in NEE was analyzed.

140 The reliability of spatial-resolved NEE estimation over large regions is constrained by the
141 predictive capability of ML- or DL- based upscaling models at the site level. Thus, it is a
142 prerequisite to address significant challenges in accurately modeling site-level NEE before
143 conducting large-scale flux estimation. The objectives of this study are to (a) investigate the
144 differences of established LSTM models with and without distinguishing PFTs in describing
145 monthly NEE variations at the plant functional type (PFTs) level, (b) analyze the variability of

146 LSTM model performances across sites, (c) evaluate the ability of the PFT-based LSTM models
147 in capturing the IAV of NEE and compare with the modeling results using widely used RF
148 models, and (d) quantify the relative importance of feature variables for predicting monthly NEE
149 dynamics across different PFTs in North America.

150 **2 Materials and Methods**

151 2.1. Dataset and Preprocessing

152 The FLUXNET is a worldwide ecosystem observational network composing observation
153 sites distributed around the globe. These sites are situated in diverse ecosystems, such as forests,
154 grasslands, cropland, etc. AmeriFlux is a network especially dedicated to monitoring terrestrial
155 ecosystems in the Americas. The observation stations affiliated with both networks utilize high-
156 precision instruments and equipment to record meteorological and ecosystem data (Baldocchi,
157 2020; Novick et al., 2018). Researchers use data from the flux networks to analyze and
158 comprehend factors related to climate change and energy and material exchange processes in
159 terrestrial ecosystems, particularly NEE and GPP (Guo et al., 2023; Xu et al., 2019). These
160 measurements are reliable, allowing for robust analysis of daily, monthly, and interannual
161 variations in the North American region.

162 When training the site-level ML algorithm for each site, we constructed a feature dataset
163 to indicate vegetation growth status. We retrieved monthly NEE and environmental variables
164 from the FLUXNET2015 (Pastorello et al., 2020) and AmeriFlux data sets (Novick et al., 2018),
165 including wind speed (WS), vapor pressure deficit (VPD), air temperature (TA), soil water
166 content (SWC), downward shortwave radiation (DSR), and precipitation (P). To gain a deeper
167 understanding of plant responses to extreme events like droughts and floods, we specifically
168 chose SWC to analyze the impact of soil moisture conditions on NEE, despite this may result in
169 a loss of some site candidates because of SWC unavailability.

170 The selected remote sensing variables included the normalized difference vegetation
171 index (NDVI), leaf area index (LAI), solar-induced chlorophyll fluorescence (SIF), and the
172 fraction of absorbed photosynthetically active radiation (FAPAR). This study utilized the Global
173 Land Surface Satellite (GLASS) LAI and FAPAR products (Liang et al., 2021). LAI represents
174 half of the total green leaf area per unit of horizontal land surface, and it is a fundamental land
175 climate variable defined by the Global Climate Observing System (GCOS) (Fang et al., 2013).
176 FAPAR is a crucial biophysical variable that directly reflects the photosynthetic activity of plants
177 (Gower et al., 1999). NDVI, which is a normalized ratio of the near-infrared (NIR) and red
178 bands, is valuable data for detecting vegetation status (Yin et al., 2022). We use the PKU Global
179 Inventory Monitoring and Modeling Studies (GIMMS) NDVI product (Li et al., 2023). During
180 the process of plant photosynthesis, leaves absorb photosynthetically active radiation (PAR) and
181 release the unused portion of the absorbed energy in the form of fluorescence, which is referred
182 to as SIF (Verrelst et al., 2016). SIF has a direct and close relationship with photosynthesis and is
183 reported to highly correlate with NEE (Shiga et al., 2018). However, previous ML predictions of

184 NEE seldom incorporated SIF as a feature variable, which may relate to its low spatial resolution
185 and spatially discontinuation in original satellite retrievals. Here we employed a high-resolution
186 (0.05°) contiguous reanalysis SIF dataset (GOSIF) (Li & Xiao, 2019), primarily derived from
187 OCO-2 SIF data, to characterize the response of NEE to climate and environment. To match the
188 site level NEE data, we utilized the monthly remote sensing observation data from GLASS LAI
189 and FAPAR products by averaging 8-day data, with a spatial resolution of $0.05^\circ \times 0.05^\circ$. For
190 remote sensing data, the pixels covering the site were used to monitor vegetation growth at the
191 site level. The values at the coordinates of each site are extracted for model training and
192 validation. Following Ukkola et al. (2021), we employed the cubic spline function to fill in the
193 blank of the monthly time series obtained, and any negative feature data was set to zero.

194 Through this approach, we created a comprehensive dataset at monthly scale. The dataset
195 comprises one label data (NEE) and 10 feature variables (WS, VPD, TA, SWC, DSR, P, NDVI,
196 LAI, SIF, and FAPAR) that are closely associated with NEE. To match the length of
197 comprehensive memory effects in each ecosystem and ensure adequate volume of data for
198 LSTM analysis, we only considered sites with at least one and a half years of NEE records. We
199 ultimately selected 7471 monthly data records from 82 sites distributed in 9 biological
200 communities in North America, covering the period from 2001 to 2020 (Figure S1 in Supporting
201 Information S1). These records encompass measurements of carbon fluxes and meteorological
202 data. The sites that were selected cover a diverse range of climatic conditions and ecosystems.
203 Following the vegetation classification scheme of the International Geosphere-Biosphere
204 Program (IGBP), those sites include 9 vegetation types: evergreen needleleaf forest (ENF; $n =$
205 22), grassland (GRA; $n = 17$), deciduous broadleaf forest (DBF; $n = 11$), open shrubland (OSH;
206 $n = 10$), cropland (CRO; $n = 9$), permanent wetland (WET; $n = 7$), closed shrubland (CSH; $n =$
207 2), mixed forest (MF; $n = 2$) and woody savanna (WSA; $n = 2$). The type of cropland/natural
208 vegetation mosaics (CVM; $n = 1$) was not used for model establishment due to limited site
209 observation data. Our analysis involved 35 sites from FLUXNET and 47 sites from AmeriFlux.
210 This analysis is based on NEE data and focuses on conducting monthly scale simulations and
211 interannual variation predictions across different PFTs and sites.

212 2.2. The LSTM-based NEE model

213 2.2.1. LSTM Algorithm

214 Recurrent Neural Networks (RNNs) can learn to recursively use internal memory states
215 to process sequential data (Thireou & Reczko, 2007). It has emerged as a valuable tool for
216 studying vegetation and climate history through time series observations (Reichstein et al.,
217 2018). By internally transmitting data, RNNs effectively encode the information seen at past
218 time-steps, enabling them to capture temporal dependencies and patterns. As an enhanced
219 variation of RNN, the Long Short-Term Memory Networks (LSTMs) adeptly model long-term
220 dependencies by regulating the information flow (Hochreiter & Schmidhuber, 1997). The
221 connections between units in the LSTM layer create a directed graph along the sequence,

222 illustrating the dynamic temporal behavior of time series in this RNN architecture. LSTM can
223 selectively store and extract information relevant to the problem at each time-step, thereby
224 enabling a better adaption to the memory effect of environmental variables on the carbon cycle
225 of terrestrial ecosystems.

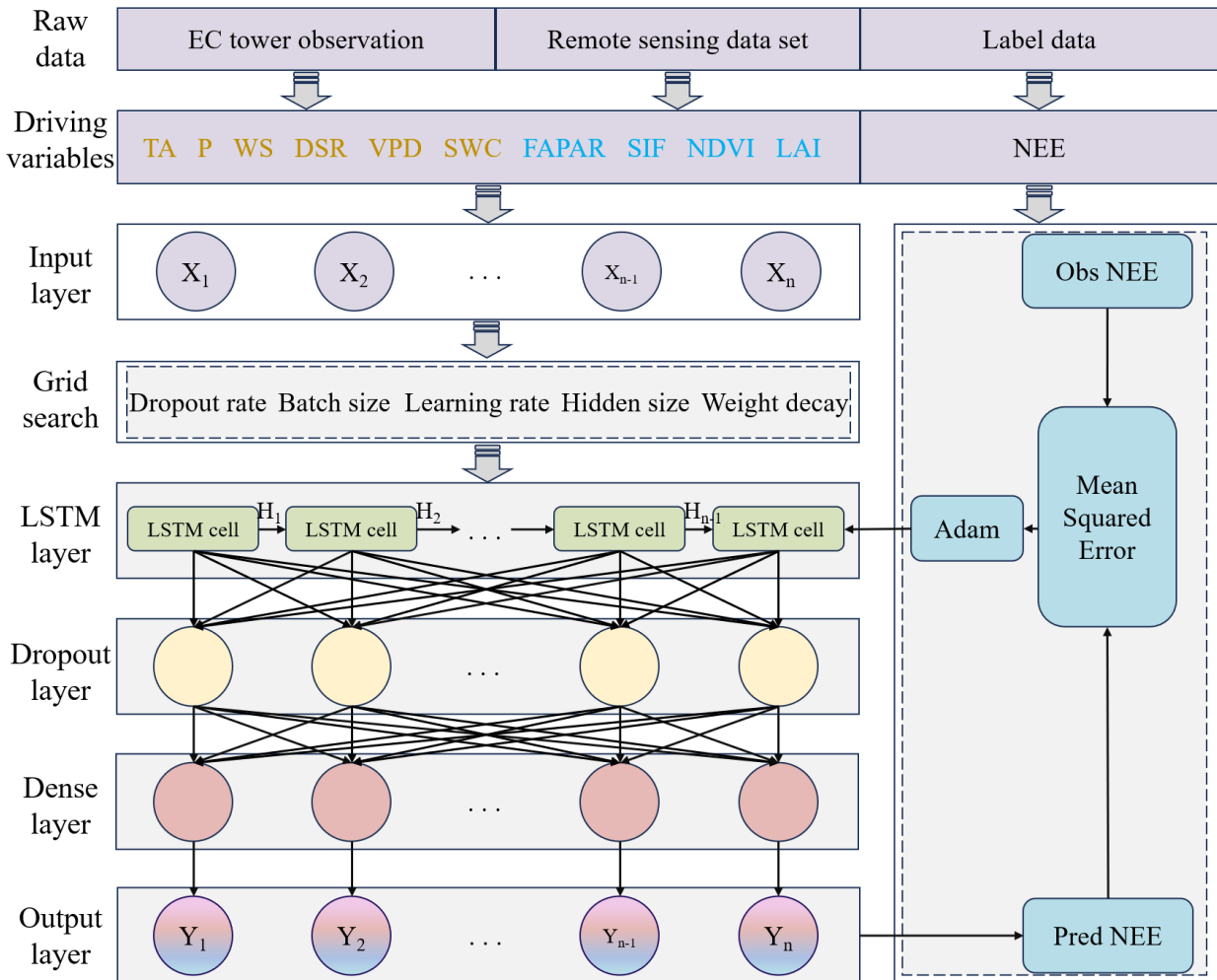
226 2.2.2. Design of NEE Prediction Model

227 Different PFTs exhibit distinct characteristics and ecological processes, leading to diverse
228 NEE responses to ecosystem carbon cycle and climate changes. To enhance the utilization of
229 existing data resources and increase model flexibility, our method directly establishes the LSTM
230 model for different PFTs to estimate NEE. NEE observations obtained from FLUXNET2015 and
231 AmeriFlux networks were used as the label data for time series prediction. The site-level inputs
232 are decomposed into 9 separate PFT groups (ENF, GRA, DBF, OSH, CRO, WET, CSH, MF,
233 and WSA). Then, we create individual LSTM model for each PFT, optimizing the model
234 parameters specifically for the PFT site being applied. Furthermore, we included all training data
235 in an LSTM model and did not consider PFTs during the model establishment process. To
236 evaluate whether distinguishing PFTs leads to improved model performance in NEE estimation,
237 we compared the accuracy of each PFT DL model with that of the model without differentiating
238 PFTs. The model that distinguishes PFTs are referred to as PFT_LSTM models, whereas the
239 latter are referred to as nonPFT_LSTM models.

240 The developed LSTM deep learning (DL) model framework is illustrated in Figure 1. It
241 employs an LSTM layer for the processing and modeling of time series data. Following the
242 LSTM layer, a dropout layer is incorporated to randomly disregard a portion of neuron outputs
243 during training, reducing the interdependence between neurons (Baldi & Sadowski, 2014). Early
244 stopping is implemented to enhance the generalization ability of the networks. The final fully
245 connected layer is responsible for mapping the output of the dropout layer to the target variable
246 NEE. We calculate the Mean Squared Error between the predicted results and the label data
247 (monthly NEE) as the loss function (Rumelhart et al., 1986). To obtain the optimal model, we
248 employ the Adam optimizer to minimize this loss function (Kingma & Ba, 2017). To achieve the
249 best model performance, a grid search was employed to determine major model parameters
250 (Bergstra & Bengio, 2012): learning rate (0.01, 0.001), number of hidden neurons (32, 64, 128,
251 256), weight decay coefficient (0.01, 0.001, 0.0001), dropout rate (0.1, 0.2, 0.3), and batch size
252 (8, 16, 32).

253 Throughout this process, we tested various parameter combinations. Thus, we selected
254 the parameter set that showed the least deviation between the observed monthly NEE data
255 provided by each PFT and the corresponding data predicted by the model. To ensure the
256 comprehensive utilization of time information, the initial 70% of both the feature data set and
257 label data set from each site served as training data to optimize the weights of networks. The
258 remaining 30% was employed as test data to assess the model performance. We conducted time
259 validation for each PFT. The training and testing data sets were used for the development and
260 evaluation of prediction models, respectively. We utilize EC tower-measured data (WS, VPD,

261 TA, DSR, SWC, and P) along with remote sensing data (NDVI, LAI, FAPAR, and SIF) to train
 262 the LSTM model and estimate site-level NEE in North America at monthly intervals.



263
 264 **Figure 1.** The architecture of the designed LSTM deep learning model.

265 2.3. Model evaluation and uncertainty assessment

266 In this study, we determined the optimal prediction by iterating the models used to fit the
 267 feature dataset. This approach allowed us to simplify, or at least quantify the empirical
 268 uncertainty caused by the random initialization of the LSTM model. We conducted 10 simulation
 269 training sessions using LSTM for each model to reflect the uncertainty in the model output
 270 (Besnard et al., 2019). Based on this training approach, 90 DL models with optimal parameters
 271 were eventually obtained. For each PFT, these models were employed to generate 10 sets of
 272 predictions for NEE. The uncertainty range of the model output was determined by the
 273 interquartile range of these 10 predicted sets, while the final estimate was derived from the
 274 median of the predicted set. We evaluated the accuracy of each model during the testing period
 275 using three indicators, coefficient of determination (R^2), Root Mean Square Error, and Mean
 276 Absolute Error (MAE). These indicators are defined as,

$$R^2 = 1 - \frac{\sum_{k=1}^N (Y_i^{obs} - Y_i^{pred})^2}{\sum_{k=1}^N (Y_i^{obs} - \bar{Y}_i^{obs})^2} \quad (1)$$

$$RMSE = \sqrt{\frac{\sum_{k=1}^N (Y_i^{obs} - Y_i^{pred})^2}{N}} \quad (2)$$

$$MAE = \frac{\sum_{k=1}^N |Y_i^{obs} - Y_i^{pred}|}{N} \quad (3)$$

where Y_i^{obs} and \bar{Y}_i^{obs} are the observation value and mean observations, and Y_i^{pred} is the model predictions.

2.4. Variable Importance Analysis

Due to the diverse nonlinear responses of ecosystems to climate conditions and environmental control, complex spatiotemporal variability in NEE exists within and across ecosystems. While traditional LSTM DL algorithms are capable of learning system modeling and capturing dynamic behavior from observations, they cannot provide explanations for the spatiotemporal variability of carbon fluxes (Perez-Suay et al., 2020). In the case of carbon fluxes, it is essential for an ML model to identify and clarify the most significant environmental driving factor. In revealing the interaction between vegetation biological characteristics and the environment, quantifying the contribution of these driving factors to monthly NEE changes poses a significant challenge. The presence of imbalanced sample data among PFT sites can hinder the effectiveness of statistical analysis, thereby limiting the reliability of traditional statistical methods in inferring the impact of variables on monthly NEE (Stoy et al., 2009).

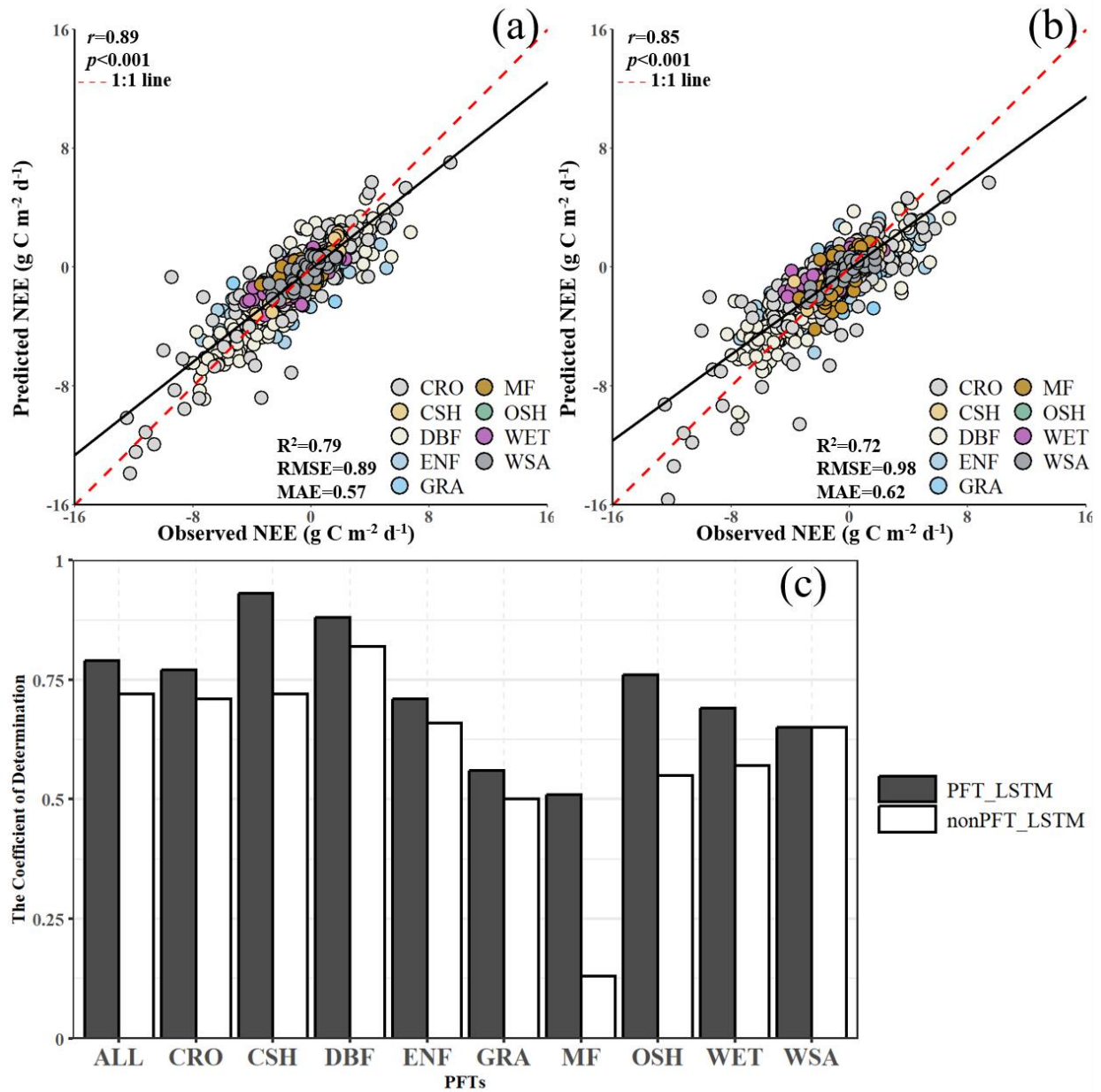
To establish a quantitative framework for quantifying the importance of control factors on NEE changes at PFT sites, we used the boosted regression trees (BRT) model (Elith et al., 2008). The BRT model is a ML method that effectively connects environmental variables with monthly scale NEE data. It is able to capture physically complex and nonlinear relationships as well as interactions among variables (Kong et al., 2022; Li et al., 2020). This advantage makes it particularly suitable for quantifying the contribution of predicted variables to monthly NEE. The BRT model can identify key features related to the target variable by evaluating the importance of each feature within the model. We used the BRT model to discern the primary plant traits and environmental factors that drive NEE changes in each PFT.

303 **3 Results**

304 3.1. Prediction Performance at the PFT Level

305 The LSTM models were used to estimate monthly NEE for various PFTs over the flux
306 sites in North America. We firstly investigated the impact of differentiating PFT to the prediction
307 accuracy. Figure 2 shows the performance comparison between the LSTM models with
308 distinguished PFT (PFT_LSTM) and the ones without differentiating PFTs (nonPFT_LSTM) for
309 monthly NEE predictions. Among all PFTs, the NEE values predicted by the PFT_LSTM model
310 highly correlated with the observations ($r = 0.89$, $p < 0.001$), slightly outperforming the
311 nonPFT_LSTM models ($r = 0.85$, $p < 0.001$). In the PFT_LSTM models, their R^2 over all PFT
312 sites increased from 0.72 to 0.79, RMSE decreased from $0.98 \text{ g C m}^{-2} \text{ d}^{-1}$ to $0.89 \text{ g C m}^{-2} \text{ d}^{-1}$, and
313 MAE decreased from $0.62 \text{ g C m}^{-2} \text{ d}^{-1}$ to $0.57 \text{ g C m}^{-2} \text{ d}^{-1}$. PFT_LSTM models demonstrated
314 higher accuracy compared to the nonPFT_LSTM models, with significantly higher R^2 and lower
315 RMSE and MAE.

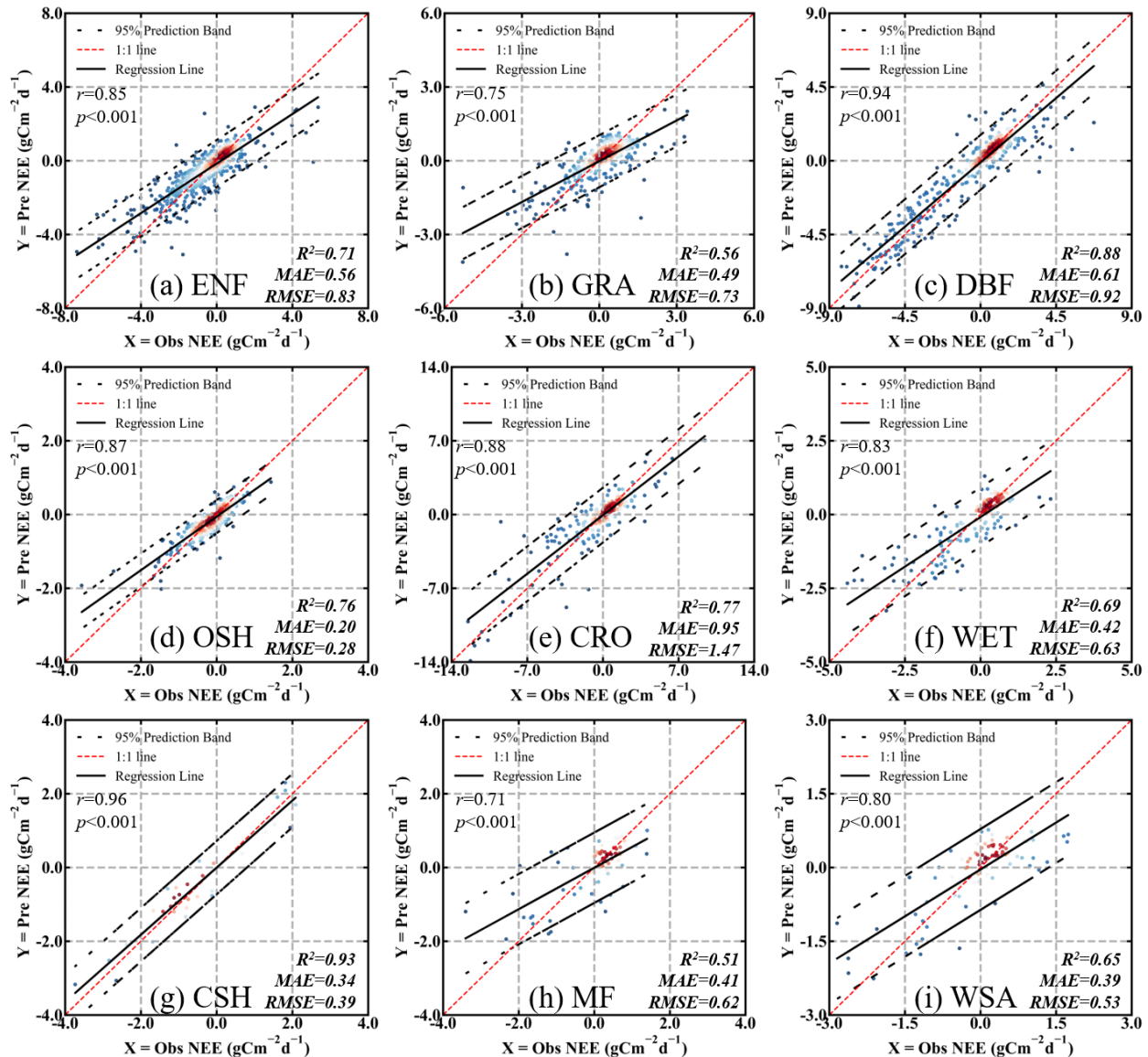
316 The performances of the LSTM models varied across PFTs (R^2 shown in Figure 2c and
317 RMSE, MAE can be found in Table S2 in Supporting Information S1). Different PFT models
318 employed various driver data and architectures, leading to slightly different performance and
319 generalization abilities of the trained LSTM model for the NEE predictions. For PFT_LSTM
320 models, the median R^2 ranged from 0.51 to 0.93 for each PFT test set, with RMSE ranging from
321 0.28 and $1.47 \text{ g C m}^{-2} \text{ d}^{-1}$, and MAE ranging from 0.20 to $0.95 \text{ g C m}^{-2} \text{ d}^{-1}$. Without
322 distinguishing PFTs, the R^2 of each PFT test set ranged from 0.13 to 0.82. The RMSE ranged
323 from 0.37 to $1.66 \text{ g C m}^{-2} \text{ d}^{-1}$, and the MAE ranged from 0.27 to $1.09 \text{ g C m}^{-2} \text{ d}^{-1}$. Among the
324 nine PFTs, except for WSA, where the R^2 remained the same, the PFT_LSTM models
325 outperformed the nonPFT_LSTM models in predicting NEE. The LSTM model performance
326 was improved in terms of R^2 , with an increase ranging from 0.05 to 0.38. The NEE estimation
327 for the MF sites showed the most significant increase in R^2 , with an improvement of 0.38. This
328 was followed by CSH, OSH and WET sites, where the increase in median R^2 exceeding 0.10.
329 Therefore, the differentiation of PFTs has improved the ability of the DL models to predict NEE.



330
 331 **Figure 2.** Comparative evaluation of the predicted monthly NEE by the LSTM models against the observed
 332 NEE. (a) The PFT_LSTM models for all PFTs; (b) The nonPFT_LSTM models for all PFTs; (c) Model
 333 performance comparison over nine different PFTs. The colors of points in (a) and (b) indicate the predominant
 334 PFT presented at respective sites (ENF: evergreen needleleaf forest, GRA: grassland, DBF: deciduous
 335 broadleaf forest, OSH: open shrubland, CRO: cropland, WET: permanent wetland, CSH: closed shrubland,
 336 MF: mixed forest, and WSA: woody savanna). Each data point corresponds to the modeled estimates derived
 337 from the median ensemble of the 10 model runs. The black line shows the best-fit line from the least-squares
 338 regression. The units of RMSE and MAE are $\text{g C m}^{-2} \text{d}^{-1}$.

339 Overall, the PFT_LSTM models demonstrated a satisfactory performance in predicting
 340 monthly NEE across various PFTs (Figure 3). The model performed best for CSH and DBF, with
 341 the median R^2 of 0.93 and 0.88, respectively. In contrast, the predictive ability for MF is

342 relatively poor, with the median R^2 close to 0.50. This can be explained by multiple factors,
 343 including the limited number of sites ($n = 2$), limited observation data (only 253 site months of
 344 NEE), and limited variation of NEE between these investigated sites. These factors collectively
 345 constrain the performance of the LSTM models. The PFT_LSTM models performed relatively
 346 well in ENF, DBF, OSH, CRO, WET, CSH, and WSA, with R^2 greater than 0.65. In comparison,
 347 the nonPFT_LSTM models performed best at DBF sites, with the R^2 of 0.82, while they
 348 performed the worst at the MF sites, with the R^2 of only 0.13.

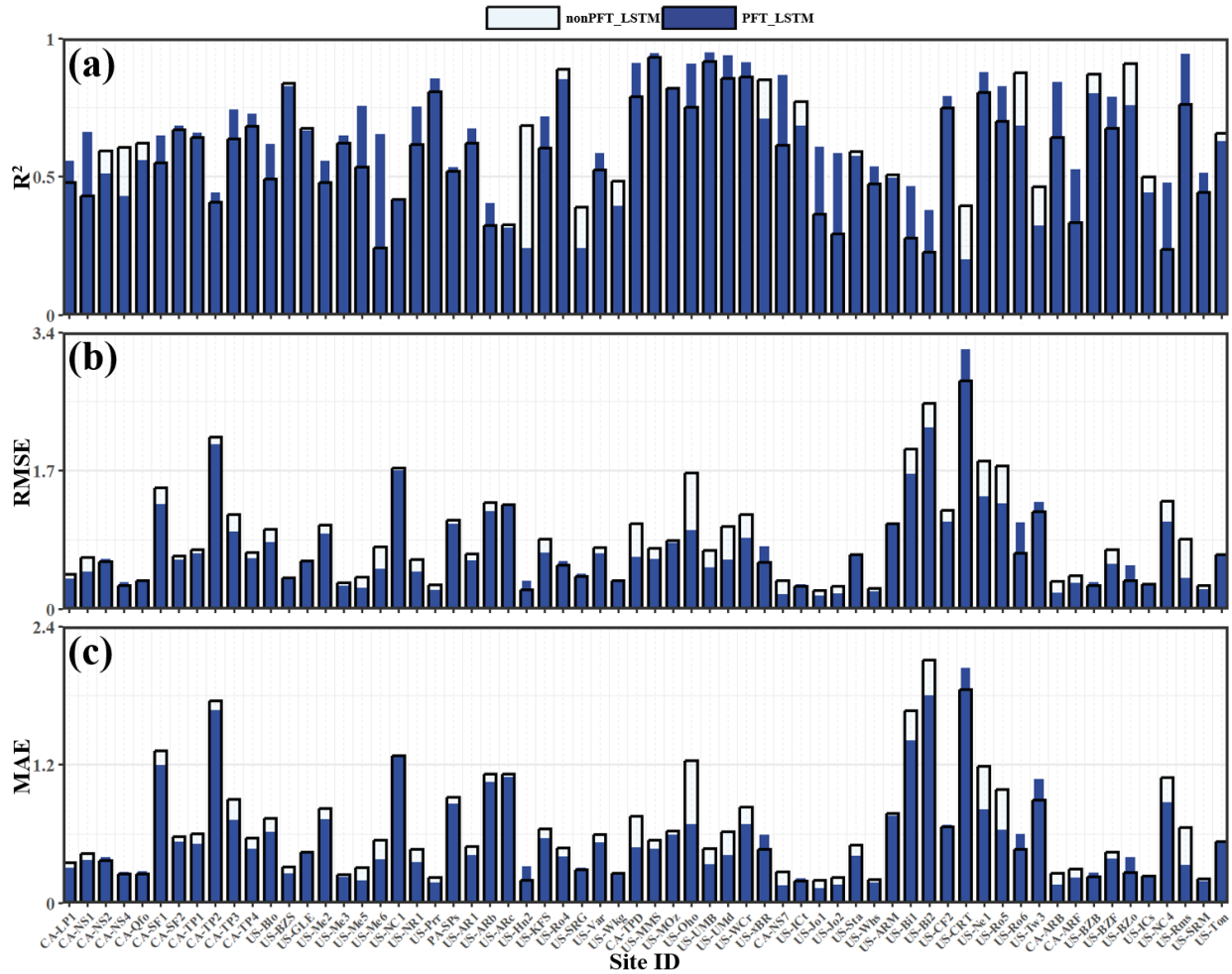


349
 350 **Figure 3.** Scatter plots of the predicted NEE by the PFT_LSTM models against the observed NEE across
 351 various PFTs. The color in the scatter density thermogram indicates data density. The range covered by the
 352 black dashed line is the 95% prediction band of the models. The units of RMSE and MAE are $\text{g C m}^{-2} \text{d}^{-1}$.

353 3.2. Across-Site Variability Estimation

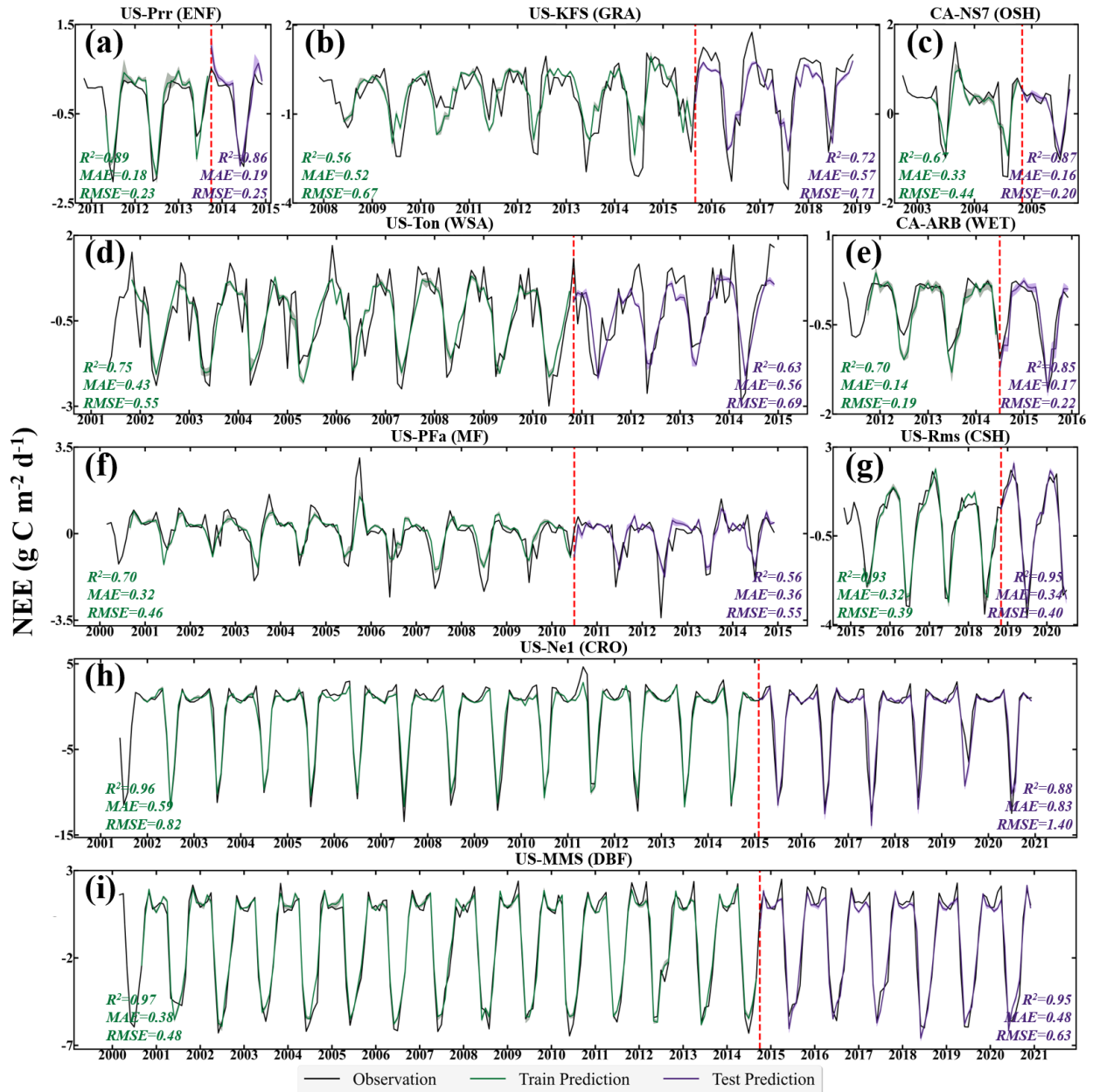
354 We further evaluated the prediction accuracy of the LSTM models at the site level. In the
355 across-site study, we employed trained PFT_LSTM and nonPFT_LSTM models to generate the
356 simulated data specially for each site during the testing phase. The validation analysis reveals
357 that the PFT_LSTM models demonstrated a good performance in capturing cross-site variability,
358 with R^2 exceeding 0.2 for 74 sites, which accounts for 90.24% of the total amount of tested sites.
359 However, the performance of the PFT_LSTM models was unsatisfactory at 8 sites, e.g., $R^2 =$
360 0.06 at the US-KS2 site (Figure S2a in Supporting Information S1). In comparison, for the
361 nonPFT_LSTM models, only 66 sites achieved an R^2 above 0.2, representing 80.49% of the total
362 participated sites. Meanwhile, the nonPFT_LSTM models showed poor prediction at 16 sites,
363 e.g., $R^2 = 0.01$ at the CA-NS6 site (Figure S2b in Supporting Information S1).

364 For cross-site validation, we viewed that the model failed to predict NEE changes at that
365 site if the R^2 was lower than 0.2. These failed predictions can be attributed to limited input data,
366 the choice of feature variables, and the limitation of the model design. Uncertain factors may
367 obscure the relationship between the target variable and the predictors. Among the sites that can
368 be predicted by LSTM models, when using PFT_LSTM models for prediction, the median R^2
369 across sites was greater than 0.65, including CSH, DBF, WET, and ENF sites. Especially,
370 PFT_LSTM models can effectively explain monthly NEE variations at DBF sites, with a median
371 R^2 of 0.92 for site-level predictions, $RMSE = 0.66 \text{ g C m}^{-2} \text{ d}^{-1}$, and $MAE = 0.5 \text{ g C m}^{-2} \text{ d}^{-1}$. In
372 addition, for all PFTs except CRO and GRA, the fitting accuracy of PFT_LSTM models for
373 cross-site monthly NEE was higher than that of nonPFT_LSTM models. We compared the
374 model performance at the sites that can be predicted by both PFT_LSTM models and
375 nonPFT_LSTM models (Figure 4). 43 out of these 64 sites exhibited an improvement in R^2 along
376 with obvious reductions in RMSE and MAE, indicating that 67.19% of the sites have enhanced
377 the performance of LSTM models.



378
 379 **Figure 4.** Model performance comparison between the PFT_LSTM models and the nonPFT_LSTM models
 380 across different sites. (a) R^2 , (b) RMSE and (c) MAE. The unit for RMSE and MAE is $\text{g C m}^{-2} \text{d}^{-1}$.

381 Cross-site validation analyses consistently demonstrated that the DBF and CSH sites
 382 exhibit the best predictive capability, which aligns with the performance evaluations at the PTF
 383 level. The PFT_LSTM models demonstrated the ability to predict monthly NEE spatiotemporal
 384 variability at more than 90% of EC tower sites in North America, with satisfactory performance
 385 (i.e., $R^2 > 0.6$) at over 50% of the sites. Therefore, distinguishing PFTs in predicting terrestrial
 386 ecosystem carbon fluxes is pretty crucial. Figure 5 illustrates the time series of the monthly NEE
 387 simulations by the PFT_LSTM models at typical sites within each PFT. The PFT_LSTM models
 388 can effectively capture the seasonal variations of terrestrial NEE during both the training period
 389 and the testing period.



390

391 **Figure 5.** Fitting of the predicted NEE by the PFT_LSTM models against the observed NEE across various
 392 representative sites for each PFT. The shaded bands around the lines indicate the uncertainty ranges of the
 393 prediction ensemble members. The red dashed line indicates the start of the site testing period. Note that we
 394 use the previous 6 months of input data to predict NEE, thus no NEE predictions were made for the initial 6
 395 months. The unit for RMSE and MAE is $\text{g C m}^{-2} \text{d}^{-1}$.

396

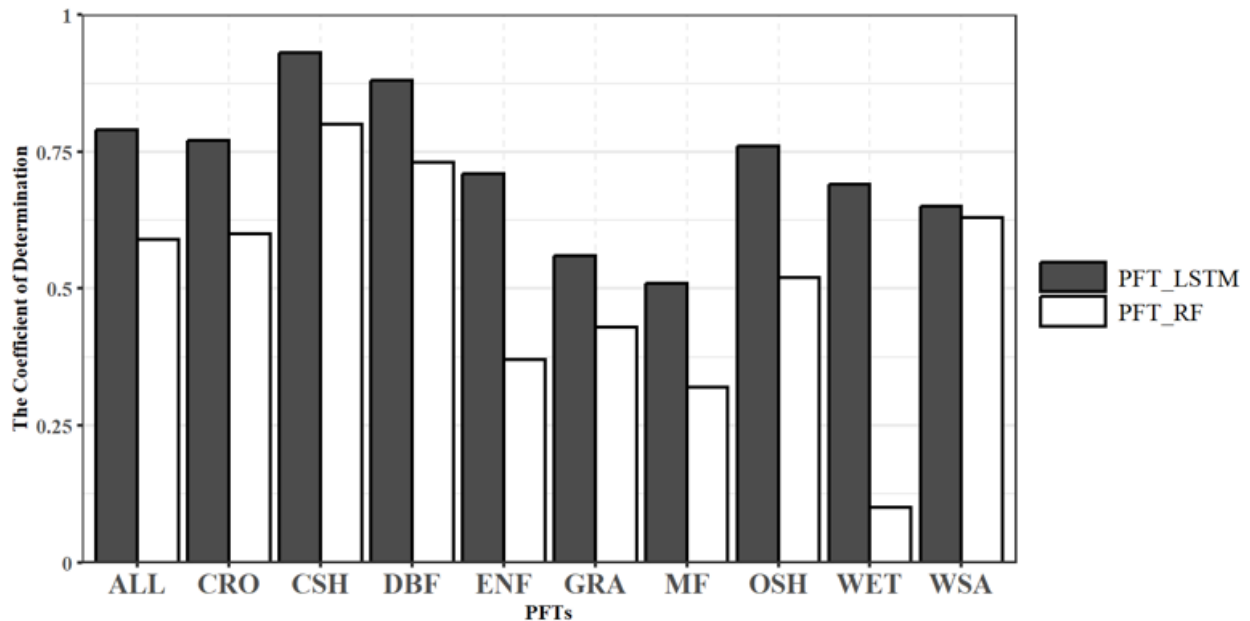
3.3. Advantages of LSTM over RF in Predicting NEE and its IAV

397

398 Random Forest (RF) is a widely recognized ML algorithm that performs well in handling
 399 complex datasets and features by constructing multiple decision trees for prediction (Belgiu &
 400 Drăguț, 2016). It has been successfully employed to predict NEE variability at the site level
 401 (Huang et al., 2021), as well as in various endeavors aiming to upscale carbon fluxes to
 continental or global scales (Kondo et al., 2015; Reitz et al., 2021). RF and LSTM are two

402 representatives ML or DL models with different theoretical and algorithmic implementations.
 403 For each PFT, we established an RF model and labeled them as PFT_RF Model. During the
 404 training phase of the RF models, we employed a tenfold cross-validation process to conduct a
 405 grid search to determine the optimal parameter set. Subsequently, a prediction model was built
 406 using the training data, and its performance was evaluated using test data. Similar to the LSTM
 407 model, each PFT model run 10 times, and the median estimate from these results was considered
 408 the best prediction.

409 The performance on predicting monthly NEE was compared between the RF model and
 410 the LSTM model (R^2 shown in Figure 6 and RMSE, MAE can be found in Table S2 in
 411 Supporting Information S1). It showed that the RF models provided monthly NEE estimations
 412 with $R^2=0.59$, RMSE= $1.19 \text{ g C m}^{-2} \text{ d}^{-1}$, and MAE= $0.70 \text{ g C m}^{-2} \text{ d}^{-1}$. PFT_RF models also
 413 exhibited acceptable performance in predicting NEE for 9 PFTs, with R^2 ranging from 0.1 to 0.8.
 414 Both the RF and LSTM models displayed consistent predictive abilities, with the best
 415 performance observed for the PFTs of CSH and DBF, with the R^2 of 0.80 and 0.73, respectively.
 416 Notably, the RF model performed poorly for the PFT of WET, with the R^2 value close to 0.1.
 417 The PFT_LSTM models demonstrated better predictive ability compared to the RF models
 418 across all PFTs.



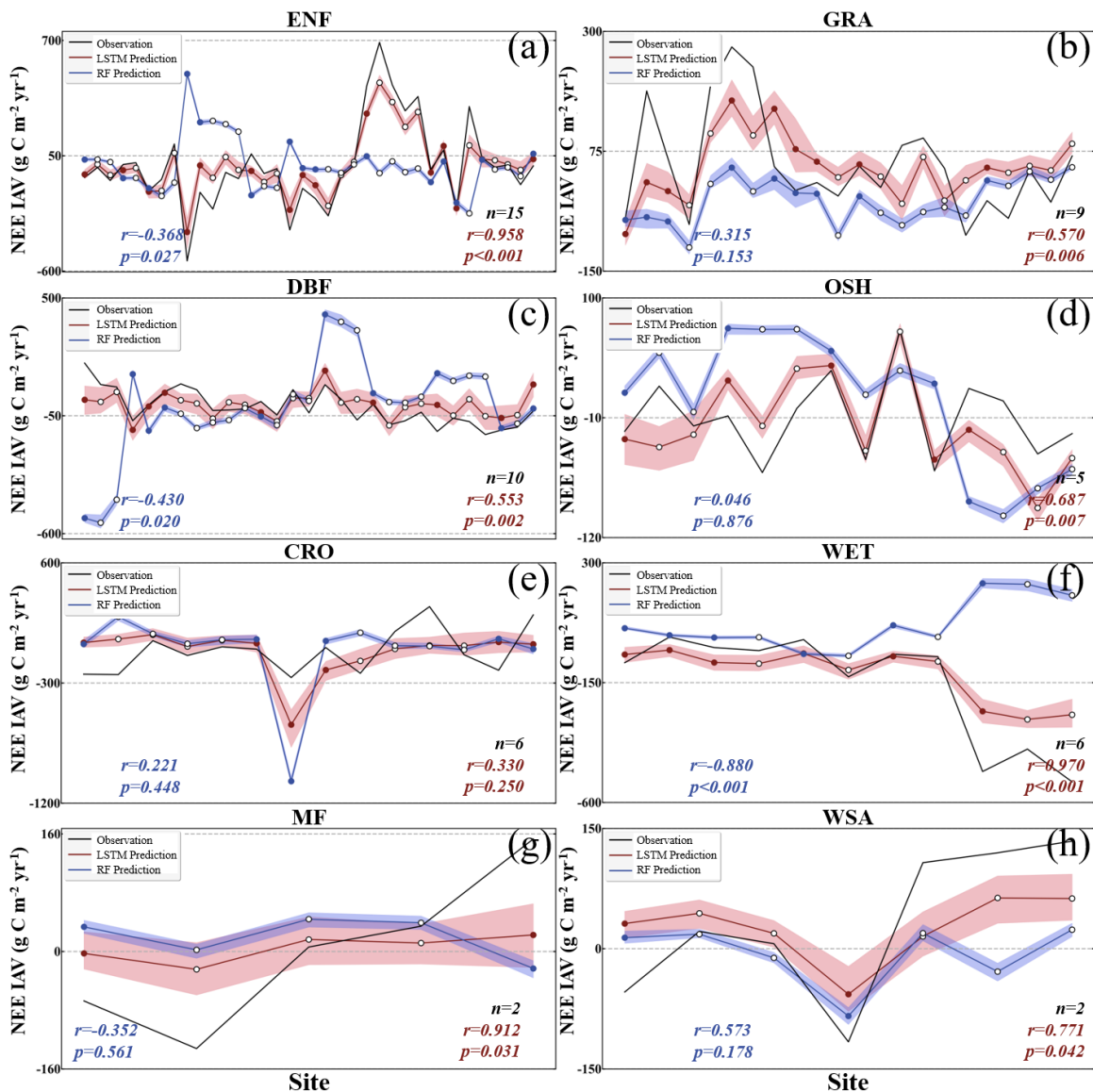
419

420 **Figure 6.** Model performance comparison between the LSTM model and the RF model over nine PFTs.

421

422 We further made comparative evaluations on the predictive capacities of NEE IAV by the
 423 PFT_LSTM models and PFT_RF models against flux tower observations over various PFTs. For
 424 each EC tower, we filtered the data to ensure only NEE data with sufficient 12 months per year
 425 is included, and calculated the annual NEE ($\text{g C m}^{-2} \text{ yr}^{-1}$) from these monthly NEE data. This
 426 allowed us to obtain both annual NEE observations and model predictions. The evaluation was

427 based on the analysis of annual anomalies. NEE IAV was calculated as the difference between
428 yearly NEE during the testing period and the average value over the entire observation period.
429 The results indicate that PFT_LSTM models reasonably captured the IAV of NEE in North
430 America, showing a significant positive correlation between the observations and the model
431 predictions in the IAV of NEE ($r = 0.81$, $p < 0.001$). By contrast, the PFT_RF models generally
432 failed to predict the NEE IAV, with a low correlation coefficient $r = -0.21$ ($p = 0.011$). Figure 7
433 shows the combined time series of NEE IAV predicted by the LSTM and RF models by PFTs.
434 The LSTM models performed relatively well in representing the IAV of NEE for ENF, WET,
435 MF, and WSA, with the r exceeding 0.75, among which the WET performed the best ($r = 0.970$,
436 $p < 0.001$). The CRO had strong IAV of NEE, ranging from $-783.52 \text{ g C m}^{-2} \text{ yr}^{-1}$ to 271.93 g C
437 $\text{m}^{-2} \text{ yr}^{-1}$. Consequently, LSTM models predicted NEE IAV poorly for CRO, with $r = 0.330$ ($p =$
438 0.250). In terms of indicating NEE IAV, the RF models performed clearly less effectively
439 compared to the LSTM models at the PFT level.



440
 441 **Figure 7.** Evaluation of combined time series of NEE IAV predicted by the LSTM and RF models against flux
 442 tower observations at the PFT level. The shaded bands around the lines indicate the uncertainty ranges of the
 443 prediction ensemble members. Each scatter represents a site-year, while a solid scatter represents the start of
 444 the site testing period. n represents the number of sites available for estimating NEE IAVs across each PFT.
 445 Note that the IAV predictions for CSH are not included in the plots due to the limited availability of complete
 446 observational data; only two full years of observations were available for CSH during the testing period.

447 Furthermore, we investigated the performance of the LSTM and RF models to predict the
 448 IAV of NEE at the site level (Figure 8). These selected sites typically cover at least four
 449 complete years of flux observations during the testing period, ensuring sufficient data for
 450 conducting analysis. The LSTM models exhibited a much stronger correlation with the observed
 451 NEE IAVs at these sites than the RF models did, e.g., at US-GLE and US-Me2.

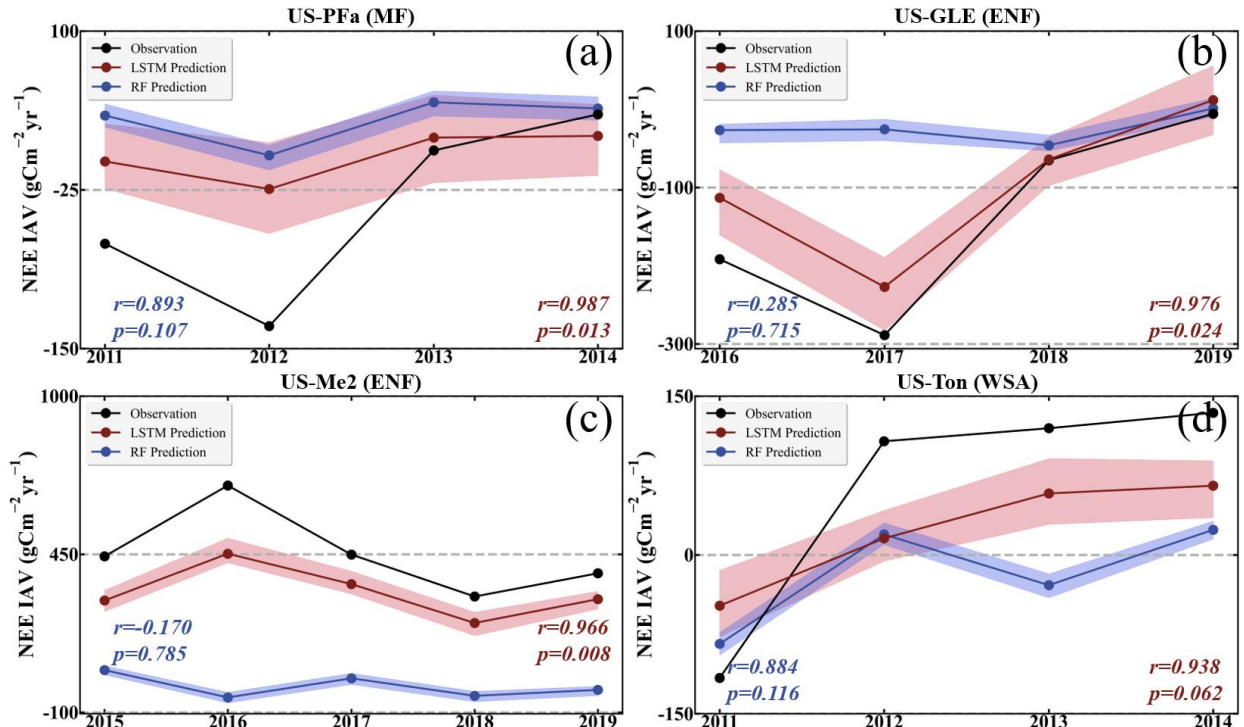


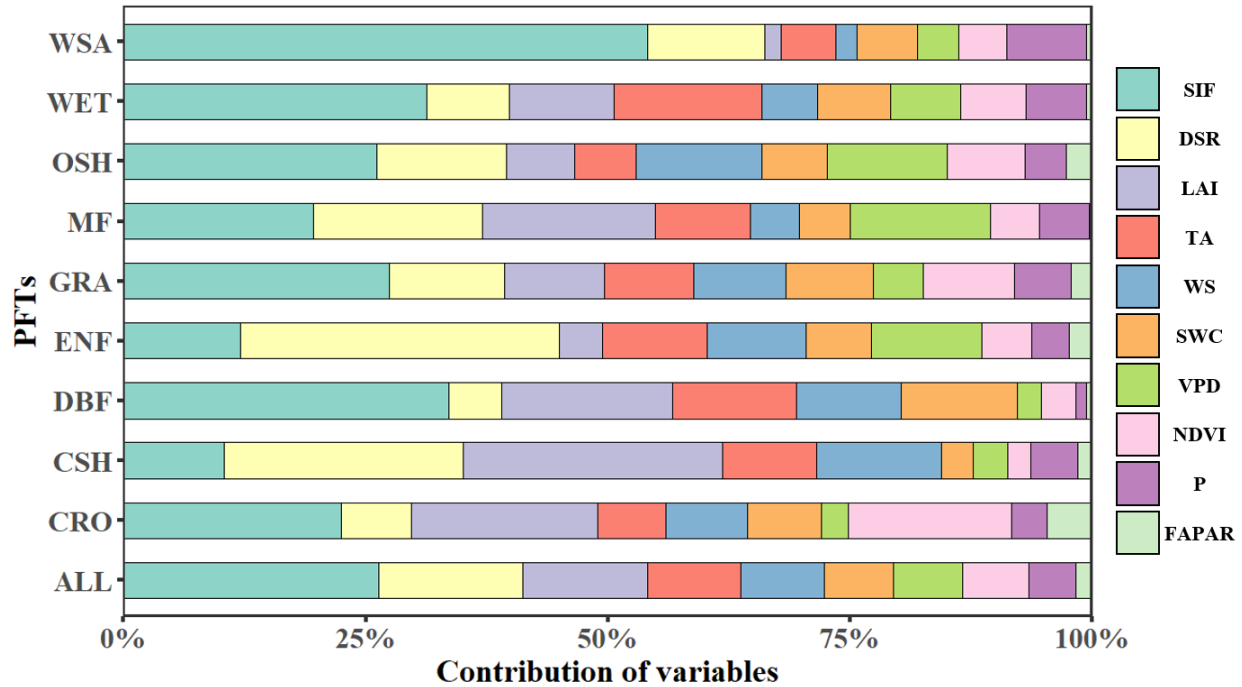
Figure 8. Evaluation of time series of NEE IAV predicted by the LSTM and RF models against flux tower observations at the site level. The shaded bands around the lines indicate the uncertainty ranges of the prediction ensemble members.

3.4. Relative Contributions of Environmental Controls to Monthly NEE Variations Across PFTs

We quantified the importance of the 10 predictive variables (WS, VPD, TA, SWC, DSR, P, NDVI, LAI, SIF, and FAPAR) on predicting monthly NEE using the BRT model (Figure 9). Since different PFTs exhibit distinct responses to NEE, individual BRT models were established for the 9 PFTs. Overall, among all PFTs, SIF was the most powerful predictor for monthly NEE variability, with an average contribution of 26.32%, followed by DSR and LAI. The combined contributions of SIF, DSR, and LAI to monthly NEE variability accounted for approximately 52.02%. Compared with SIF, DSR, and LAI, other variables showed much weaker controls over monthly NEE, with an average contribution of less than 10%. This analysis is in line with the findings of a previous study (Kong et al., 2022), which identified DSR and LAI as the primary environmental controls of daily NEE changes for most PFTs, while the contributions of TA, SWC, and other variables were relatively small. It is worth noting that Kong et al.'s study did not include the SIF variable.

The relative importance of predictive variables in driving NEE changes diverged among PFTs. For most PFTs, including GRA, DBF, OSH, WET, CRO, MF, and WSA, SIF is the most powerful predictor for monthly NEE variability. Particularly, for DBF, WET, and WSA, SIF contributed for more than 30% of monthly NEE variability. For WSA, SIF even contributed for more than 50% of monthly NEE variations. In contrast, SIF played a much weaker role for ENF

475 and CSH, where DSR emerged as the most critical predictor for ENF, and LAI additionally made
476 a remarkable contribution for CSH.



477 **Figure 9.** The relative contributions of downward shortwave radiation (DSR), solar-induced chlorophyll
478 fluorescence (SIF), air temperature (TA), normalized difference vegetation index (NDVI), leaf area index
479 (LAI), wind speed (WS), vapor pressure deficit (VPD), soil water content (SWC), precipitation (P) and
480 fraction of absorbed photosynthetically active radiation (FAPAR) to monthly net ecosystem exchange of CO₂
481 from the BRT method across all North American vegetation types.
482

483 4 Discussion

484 4.1. Advantages of LSTM in Predicting NEE and Its IAV

485 The proposed LSTM models in this study exhibited a satisfactory performance in
486 predicting the temporal dynamics and cross-site variability of monthly NEE, and clearly superior
487 performance over the traditional ML models (e.g., RF investigated in this study) that doesn't
488 consider temporal memory effect.

489 Extreme climate events and disturbances can affect the development, structure, and
490 function of terrestrial ecosystems (S. Liu et al., 2011; Williams et al., 2012). Due to the complex
491 carbon cycling process between terrestrial ecosystems and the atmosphere, these impacts
492 typically persist for a long period (Frank et al., 2015). This memory effect results in a delayed
493 IAV in the growth rate of atmospheric CO₂ concentration, which hinders the accurate prediction
494 of long-term changes in the terrestrial carbon budget under climate change and human influence.
495 Capturing this impact on NEE was quite challenging in a long past period. The widely used ML-
496 based NEE dataset (FLUXCOM NEE) is an upscaling of remote sensing data and meteorological
497 reanalysis data to the flux towers data. However, FLUXCOM fails to accurately reproduce the

498 long-term trends and IAV of NEE (Piao et al., 2020), which could largely associate with
499 characterizing memory effect. The memory effect is important factor in controlling the IAV of
500 NEE (Bloom et al., 2020), but has not been considered in FLUXCOM. Recent researches
501 demonstrated the potential of considering memory effects in improving terrestrial carbon flux
502 simulations (Besnard et al., 2019; Liu et al., 2023).

503 In terms of representing NEE IAV, the LSTM DL algorithm outperforms the widely used
504 RF ML model when using the same input data and model configuration. The LSTM algorithm is
505 able to dynamically incorporate temporal information into the estimation of CO₂ fluxes, allowing
506 for the characterization of the memory effect caused by disturbances and climate change on
507 NEE. The strong long-term dependency modeling abilities of LSTM make it suitable for
508 characterizing memory effect relationships in sequence data, leading to more realistic estimations
509 of NEE dynamics (Schmidhuber, 2015). By capturing the memory effects of climate and
510 vegetation, we can enhance our understanding and predictive ability of regional C budgets. We
511 anticipate that PFT_LSTM models will deliver enhanced performance in future carbon flux
512 upscaling research.

513 4.2. Uncertainties and Prospects

514 While LSTM can generally fit monthly NEE from North American sites well, avoiding
515 prediction bias is also challenging due to imbalanced input sampling caused by spatial and
516 temporal differences in NEE data. In the model training process, the model is more frequently
517 exposed to sites with spatial correlation and longer observation data, enabling better learning of
518 the NEE variability of these specific sites (He et al., 2015). However, if certain spatiotemporal
519 changes in the training samples are not adequately represented, the model may not accurately
520 predict or adapt to those changes, resulting in significant bias and uncertainty. Although the
521 LSTM model was specifically designed for PFT, there are still 8 sites scattered across three PFTs
522 in North America that are not predictable by LSTM (GRA; n = 5, DBF; n = 2, and CSH; n = 1).

523 Furthermore, despite PFT_LSTM models performed better than nonPFT_LSTM models
524 for the PFT level of CRO and GRA, their performances were slightly weaker than
525 nonPFT_LSTM models in predicting across-site variability, with the median R² reduced by 0.01
526 for CRO and 0.09 for GRA, respectively. This is attributed to the challenge of identifying similar
527 trends, patterns, or relationships between CRO and GRA sites, along with the substantial
528 influence of human management on croplands (Marcolla et al., 2017). Thus, the integration of
529 more observations could be crucial for ML algorithms to accurately capture monthly NEE
530 changes at CRO and GRA sites. The Unbalanced sampling leads to a lack of representativeness
531 in the data, which may be the primary factor contributing to uncertainty in the NEE simulation
532 for these sites. Adding more observations is crucial for improving the ability to fit the NEE
533 variability at these sites.

534 We notice that the time length of memory effect could influence the modeling power for
535 different PFTs and sites. In this study, we used 6 months for all PFTs. In fact, for different PFTs,

536 the memory length could be different (Aubinet et al., 2018; Zhang et al., 2022). In the study by
537 Liu et al., (2023), they found the optimal memory effect lengths diverged across PFTs. From
538 their study, 6 months are proper for most PFTs. In the future, in order to achieve a more reliable
539 upscaling, designing different memory effect lengths for different PFTs could be helpful.

540 With LSTM models, the NEE fluxes in the context of global climate change are expected
541 to be more accurately predicted. Using LSTM DL algorithms to upscale carbon estimation at the
542 regional, continental, and even global scales would emerge as a popular approach for future NEE
543 modeling. The investment and use of more flux towers will provide a substantial volume of high-
544 quality continuous observation data for future studies. Enhancing the representativeness of flux
545 tower data and the availability of predictive variables is an important undertaking in accurately
546 estimating future carbon fluxes.

547 **5 Conclusions**

548 This study explored the potential of LSTM models in predicting monthly NEE over 82
549 sites in North America based on FLUXNET 2015 and the AmeriFlux datasets and multiple
550 satellite land surface products. After distinguishing PFTs, the overall R^2 of monthly NEE
551 increased by 9.72%, RMSE decreased by $0.09 \text{ g C m}^{-2} \text{ d}^{-1}$, and MAE decreased by 0.05 g C m^{-2}
552 d^{-1} . The model performance of each PFT has been improved, highlighting the importance of
553 differentiating PFTs during model training. The use of time series data as model inputs allows
554 the LSTM algorithm to effectively capture the memory effect of climate and environmental
555 factors on the time scale. A significant positive correlation exists between the observation of
556 NEE IAV and the model prediction results ($r = 0.81$, $p < 0.001$). While commonly used non-
557 temporal dynamic statistical RF ML algorithms demonstrate acceptable performance in
558 predicting monthly NEE, their ability to predict IAV is very poor. Among the selected predictive
559 variables, SIF exhibits the strongest correlation with monthly NEE changes, contributing an
560 average of 26.32%, followed by DSR (14.83%) and LAI (12.87%). Including these variables into
561 ML or DL models is critical for predicting monthly NEE. Overall, the combination of LSTM and
562 PFTs classification shows potential in predicting the temporal variability of NEE and correcting
563 for NEE IAVs. This study provides a reference for modeling terrestrial carbon cycle, especially
564 for upscaling in-situ carbon flux observations to larger scales.

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570 the PKU GIMMIS NDVI dataset. We also sincerely acknowledge Shunlin Liang's group for
571 sharing GLASS LAI and FAPAR data.

572 **Data Availability Statement**

573 The data sets used in this paper are available from open resources. Eddy covariance data
 574 for the 35 FLUXNET sites utilized in this study are available from the FLUXNET2015 data set
 575 (Pastorello et al., 2020). Eddy covariance data for the remaining 47 sites are attained from the
 576 AmeriFlux website (Novick et al., 2018). The GLASS LAI and FAPAR products are available
 577 on the official website for the GLASS project (Liang et al., 2021). The PKU GIMMS NDVI data
 578 is publicly available in the Zenodo repository (Li et al., 2023b). GOSIF is available in the Global
 579 Ecology Group’s data repository (Li & Xiao, 2023).

580

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