Using Frequent, High-Resolution Remote Sensing to Identify Intermittent and Overlapping CH4 sources in Oil and Gas Development Regions

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Abstract

The oil and natural gas industry needs accurate and frequent information on methane CH4 emissions from all of their facilities globally in order to effectively reduce emissions. Here we describe the development of requirements for a constellation of satellites to provide frequent data on point source CH4 emissions from the oil and gas industry. Three types of sources were examined: isolated continuous plumes with emissions rates of 50 kg hr-1, intermittent CH4 releases from activities such as compressor start-ups, and overlapping continuous plumes. The dispersion model SCICHEM was used to simulate the dispersion of methane plumes and intermittent releases for typical meteorology in the Permian Basin, and a plume mask and integrated mass enhancement (IME) algorithm were applied to identify and quantify the emissions. The precision and ground sampling distance of the future satellite instrument were varied to determine the required precision and horizontal resolution of the satellite instrument. We find that quantifying CH4 point source emissions as small as 50 kg hr-1 by remote sensing requires a ground sampling distance of 30-60 m and a CH4 column precision of 0.5-1.0% for the range of conditions analyzed. Detecting intermittent sources is also possible with the above instrument specifications if the puff is observed within 15 min of emission. Plumes of similar source strengths more than 0.5 km apart can be separated with existing plume identification approaches but separating sources closer than that or with very different emission rates will require further development of plume identification techniques.

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1 2 3 4 5	Using Frequent, High-Resolution Remote Sensing to Identify Intermittent and Overlapping CH ₄ sources in Oil and Gas Development Regions M. J. Alvarado ¹ , A. Dayalu ¹ , D. B. Hogan ¹ , I. N. Polonsky ¹ , G. Start ² , P. Father ² , S. Aminfard ³ , F. J. Cardoso-Saldaña ³ , and C. A. Randles ^{4,5}
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14	
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16	Key Points:
17 18	• Quantifying CH ₄ point source emissions as small as 50 kg hr ⁻¹ requires a ground resolution of 30-60 m and a column precision of 0.5-1.0%.
19 20	• Detecting intermittent sources with the above specifications is possible if the puff is observed within 15 min of emission.
21 22	• Plumes of similar source strengths within less than 0.5 km of each other will be difficult to separate in remote sensing observations.

23 Abstract

24 The oil and natural gas industry needs accurate and frequent information on methane CH₄

25 emissions from all of their facilities globally in order to effectively reduce emissions. Here we

26 describe the development of requirements for a constellation of satellites to provide frequent data

on point source CH_4 emissions from the oil and gas industry. Three types of sources were

examined: isolated continuous plumes with emissions rates of 50 kg hr⁻¹, intermittent CH_4

releases from activities such as compressor start-ups, and overlapping continuous plumes. The

dispersion model SCICHEM was used to simulate the dispersion of methane plumes and
 intermittent releases for typical meteorology in the Permian Basin, and a plume mask and

intermittent releases for typical meteorology in the Permian Basin, and a plume mask and
 integrated mass enhancement (IME) algorithm were applied to identify and quantify the

emissions. The precision and ground sampling distance of the future satellite instrument were

varied to determine the required precision and horizontal resolution of the satellite instrument.

We find that quantifying CH_4 point source emissions as small as 50 kg hr⁻¹ by remote sensing

requires a ground sampling distance of 30-60 m and a CH₄ column precision of 0.5-1.0% for the

37 range of conditions analyzed. Detecting intermittent sources is also possible with the above

instrument specifications if the puff is observed within 15 min of emission. Plumes of similar

39 source strengths more than 0.5 km apart can be separated with existing plume identification

40 approaches but separating sources closer than that or with very different emission rates will

41 require further development of plume identification techniques.

42 Plain Language Summary

43 In order to reduce greenhouse gas emissions from the oil and natural gas industry, and thus

reduce near-term global warming, more frequent and accurate information on which of their

45 facilities are emitting methane is needed. Satellite observations can help due to their global

46 coverage, and recent advancements in sensor technology will make it possible to measure up to

47 80-90% of the methane emissions from the oil and gas industry. In this work we discuss

instrument requirements toward a future group of satellites that will measure methane emissions

49 from oil and gas facilities multiple times a day. We looked at small, steady sources of methane

and determined that measuring these sources would require a satellite instrument that can

51 measure methane to within 0.5-1.0% every 30-60 m horizontally. We find that detecting small, 52 unsteady sources, such as those from starting a natural gas compressor, is also possible, but only

52 unsteady sources, such as those from starting a natural gas compressor, is also possible, but only

if the source is observed within 15 minutes after the emission. Finally, we show that current

techniques can only separate neighboring sources of CH_4 if they are of similar size and at least

55 0.5 km apart.

56 **1 Introduction**

Emissions of methane (CH₄) to the atmosphere are receiving increased attention as a method to reduce greenhouse gas radiative forcing and the resulting climatic changes (e.g., Nisbet et al., 2020). Reductions of CH₄ emissions are attractive as the relatively short lifetime of CH₄ in the atmosphere (9.1 \pm 0.9 yr., Szopa et al., 2021) means that changes in CH₄ emissions could reduce climate forcing over a 10- to 20-year horizon, delaying when a given temperature threshold will be crossed and allowing for more time to address emissions of the longer-lived greenhouse gas carbon dioxide (CO₂).

64 CH₄ emissions come from a wide variety of sources, including natural sources such as 65 wetlands and wildfires and anthropogenic sources like livestock, rice cultivation, landfills, biofuel burning, and fossil fuel use (e.g., Saunois et al., 2020). Fossil fuel sources of CH₄ account for about 18% of the annual global CH₄ emissions and include emissions from coal mining (33% of fossil fuel CH₄ emissions for 2017) and the oil and natural gas industry (62% of fossil fuel CH₄ emissions for 2017, Saunois et al., 2020).

Emissions from oil and gas activities are complex as they are skewed, with a small 70 71 number of sources accounting for a large fraction of emissions (Brandt et al., 2016), and have spatiotemporal variability (Allen et al., 2017; Cusworth et al, 2021). In recent years, high CH₄ 72 emissions from oil and gas activities have been observed with aircraft and satellites in the US 73 and around the world (Cusworth et al., 2021; Cusworth et al., 2022; Lauvaux et al. 2021), and 74 they account for a disproportionate fraction of total emissions in a given region. For example, in 75 the Permian basin, close to 90% of total emissions originate from plumes larger than 50 kg/hr 76 77 (Chen et al., 2022). In order to achieve significant reductions on emissions, industry needs emission information in near-real-time for high emitter sources, such that mitigation measures 78 can be taken to address unexpected CH₄ emissions when they appear (Cardoso-Saldaña 2022). In 79 addition, the locations of emission sources need to be identified accurately to allow mitigation 80 activities to be performed, especially as different companies may have emitting equipment 81 within close proximity to each other. Finally, there is a need to detect intermittent sources of 82 CH₄, as persistent emission sources account for only 29% of oil and natural gas industry 83 84 emissions in areas like the Permian basin (Cusworth et al., 2021).

Providing the information on CH₄ emissions needed by the oil and gas industry will require a mixture of measurement approaches that combines in situ methane observations with additional information from ground-based (e.g., Pernini et al., 2022), aircraft (Duren et al., 2019; Jongaramrungruang et al., 2019; Cusworth et al., 2020), and satellite remote sensing platforms. Of these platforms, satellite observations are of particular interest due to their ability to observe methane sources globally.

Jacob et al. (2022) recently reviewed satellite methods to quantify methane emissions 91 92 from the global scale down to individual point sources. They separated methane monitoring satellites into two general categories, area flux mappers and point source imagers. Area flux 93 94 mappers are designed to observe total emissions on global or regional scales with 0.1-10 km pixel size (Jacob et al., 2022). These include the European Space Agency TROPOspheric 95 Monitoring Instrument (TROPOMI) instrument, which has been used to detect high-emitting 96 CH₄ sources in oil and gas fields with a low density of sites (Cusworth et al., 2018). Varon et al. 97 (2022) created user-friendly, cloud-based facility for quantifying CH₄ emissions with 98 $0.25^{\circ} \times 0.3125^{\circ}$ resolution by inverse analysis of satellite observations from TropOMI. 99

Point source imagers are fine-pixel (< 60 m) instruments designed to quantify individual 100 point sources by imaging the plumes (Jacob et al., 2022). For example, Varon et al. (2020) used 101 102 the GHGSat-D satellite instrument (50 m effective spatial resolution and 9–18% single-pass column precision) to quantify mean source rates for three coal mine vents (2320 to 5850 kg h^{-1}). 103 Varon et al. (2021) used data from the Sentinel-2 mission to quantify point sources down to 104 about 3 th^{-1} , with Ehret et al. (2022) using similar methods to detect and quantify more than 105 1200 CH₄ emissions from Seninel-2 data. Sánchez-García et al. (2022) used data from the 106 WorldView-3 (WV-3) satellite mission to detect point emissions over oil and gas extraction 107 fields in Algeria and Turkmenistan. 108

109 The goal of the Scepter Monitoring Mission is to provide frequent, high-resolution data 110 on multiple air pollutants to a variety of industrial and government entities. Here we focus on the development of requirements for a constellation of satellites to provide frequent data on point 111 source CH₄ emissions from the oil and gas industry. A systems engineering requirement flow-112 down process was used to determine the satellite and constellation (~14 satellites) requirements 113 to measure CH₄ leak rates of 50 kg hr⁻¹ multiple times a day, thereby meeting the needs of the oil 114 and gas industry. In this paper, we describe the first step of this process, where the dispersion 115 model SCICHEM was used to simulate the dispersion of methane plumes during a typical day in 116 the Permian Basin. The CH₄ emission rates were fixed at 50 kg hr⁻¹ for different wind speeds and 117 meteorological conditions and the resulting column enhancements $(g m^{-2})$ were calculated. A 118 noisy background of CH₄ was added to simulate the satellite observations. Then a plume mask 119 and integrated mass enhancement (IME) algorithm based on the approach of Varon et al. (2018) 120 was applied. The value of the noise and the ground sampling distance of the instrument were 121 varied to determine the required precision and horizontal resolution of the satellite instrument. 122

In addition, this paper focuses on two challenging aspects of monitoring oil and natural gas industry CH_4 emissions from satellites. First, intermittent, unintentional CH_4 releases need to be detected and quantified. Cusworth et al. (2022) showed these intermittent sources accounted for nearly half of the total CH_4 point source budget for multiple basins in the United States. To study these sources, we performed instantaneous releases in SCICHEM and applied the plume identification method of Varon et al. (2018) to the resulting puffs.

129 Second, at oil and gas facilities the plumes from multiple sources may overlap, making it more difficult to separate their emissions. This is less of a challenge for scientific studies that 130 aim at determining the total CH₄ emission in a given region, as in those studies an accurate total 131 emission rate is more important than separating the emissions among the individual sources. 132 However, for our goal of providing information to operators that allow them to quickly address 133 emissions, separating the emissions from different sources is critical to send staff to the correct 134 135 location, as well as to identify which company should respond when the facilities of different companies are near each other. To address this, we simulated different configurations of 136 overlapping plumes with the SCICHEM model, applied our plume masking algorithm, and 137 examined how difficult it would be to separate the plumes under different wind directions, 138 139 source strengths, and inter-plume distances.

140 2 Methods

141 2.1 Satellite Instrument Performance

We assumed a future satellite instrument operating in the 2050-2400 μm band with a
 signal to noise ratio (SNR) between 100-150, a spectral resolution between 1- 5 nm, and a
 ground sampling distance between 30-120 m. These specifications are well within the limits of

- 145 current technology. We calculated the expected variance (σ) reduction due to adding a
- 146 measurement to a system described by a prior information following Rodgers (2000):

$$\sigma^{-1} = K^T \left(\frac{SNR}{y}\right)^2 K + S_a^{-1}$$

147 where y is the measured radiance, K is the Jacobian (sensitivity of the radiance to changes in the

148 CH₄ profile), *SNR* is the signal to noise ratio, and S_a is the prior covariance matrix. The

Jacobians were computed using LBLRTM v12.13 (Clough et al., 2005, Alvarado et al., 2013) based on the finite difference method using a surface albedo of 0.15, which is less than the 25th

percentile of surface albedo values in the Permian basin year-round. As we are interested in

detecting near-surface enhancements of CH₄, the prior covariance was calculated assuming that

the 1-sigma uncertainty in the CH₄ concentration in the planetary boundary layer was about 10%

154 of the total column.

For an instrument with a SNR between 100-150 and a spectral resolution between 1- 5 nm, the above procedure estimated a CH_4 column precision of between 0.3-1.0%. However, this procedure does not account for the potential impacts of errors in other retrieved species (mainly

 H_2O and surface reflectance) on the retrieved CH_4 precision. Thus, for the plume identification

and quantification studies below, we assumed a more conservative error range of 0.5-1.0%.

160 2.2 SCICHEM Dispersion Modeling

We used the SCICHEM dispersion model to simulate both continuous and instantaneous releases of CH₄. Hourly surface meteorological data were obtained from the Pine Springs, Guadalupe Mountains National Park (KGDP) weather station (31.83 °N, 104.81 °W) and upper air meteorological data was obtained from the Midland, TX station (WBAN 23023, 31.93 °N, 102.2 °W). The SCICHEM preprocessor METSCI was used to prepare the meteorological inputs, with the terrain preprocessor TERSCI used to simulate the terrain based on digital elevation model (DEM) data. Concentrations were calculated within a horizontal domain of 1 km with a spatial

resolution of 30 m, and a vertical domain between 0-3 km agl at a vertical resolution of 25 m in

the lowest 1 km and a 1 km resolution above. We determined the vertical resolution through

initial SCICHEM runs (not shown) that demonstrated that the non-buoyant CH₄ emissions

- examined here rarely extended above 1 km in altitude before leaving the 1 km horizontal $\frac{1}{2}$
- domain, but that a vertical resolution of greater than 25 m in the lowest 1 km led to > 0.1% errors in the calculated CH₄ column. We assumed a stack temperature of 30 °C and a stack exit velocity

173 in the calculated C114 column. We assumed a stack temperature of 50° C and a stack exit velocity 174 of 0.5 m s^{-1} , giving the plumes negligible buoyancy. CH₄ emissions from flares and compressor

exhaust can be buoyant, but since the satellite measures vertically integrated CH_4 columns we

expect the effects of buoyancy on our results to be minimal. We also expect most sources to be



179 Continuous release simulations were performed in the Permian for a number of different 180 wind speeds. Our simulations covered one day (March 8, 2016) with a constant release rate of 50 181 kg hr⁻¹. We simulated a release at 32.065984 °N, -103.93936 °W, which is the location of Plume 182 ID P00203 from the JPL Methane Plume Finder. SCICHEM was also used to simulate an 183 instantaneous (<< 1 min) release of 33.5 kg of CH₄ at this location and date. The total emissions 184 are roughly the median amount for a compressor blow-down and on the lower end of the range 185 for a compressor start-up (Zimmerle et al., 2022) or liquid unloadings (e.g., Allen et al., 2015).

186 2.3 Plume Identification and Quantification

187 Our approach for identifying CH_4 plumes and quantifying CH_4 emission rates followed 188 the integrated mass enhancement (IME) approach of Varon et al. (2018). The SCICHEM 189 simulated column enhancement (Figure 1b) was added to a constant CH_4 background with 0.5% 190 or 1% Gaussian noise applied (Figure 1c). The mean background column was set to 13.3 g m⁻², 191 consistent with a background surface concentration of 2000 ppbv. The background CH_4 column 192 distribution was then estimated using the up-wind quadrant of the 1 km modeling domain (Figure 193 1a).

The plume identification algorithm starts by performing a t-test to determine if the distribution of CH_4 columns in the 5x5 neighborhood of pixels around a given pixel is significantly different (95% confidence) from the background distribution. If so, the center pixel is tentatively marked as a plume pixel (Figure 1d). A median 3x3 filter is then applied to the resulting t-test mask to remove isolated pixels (Figure 1e), and then a Gaussian filter is applied to





Figure 1. (a) Quadrant used to calculate mean and standard deviation of the background distribution. (b) Simulated plume from a point source of CH₄ with an emission rate of 50 kg hr⁻¹. (c) Addition of noisy background (13.3 g m⁻² \pm 0.5%). (d) Result of t-test plume identification. (e) Result of applying the median filter on (d). (f) Result of applying the Gaussian filter on (e).

Once the plume pixels have been identified, the *IME* (g CH₄) is defined as the areaweighted sum of the column enhancement of methane above background (Figure 2), following the equation

$$IME = \sum_{pixel=1}^{N_{pixel}} (\Omega_{CH4,pixel} - \Omega_b) A_{pixel} \qquad (1)$$

210 where

209

- 211 $\Omega_{CH4,pixel}$ is the measured methane column for a single pixel from the Level 2 212 product converted to units of g m⁻²
- Ω_b is the background methane column in units of g m⁻² estimated as discussed below
- A_{pixel} is the area of the pixel in units of m²
- N_{pixel} is the number of pixels in a single plume

217 The IME is combined with the effective plume length:

218
$$L_{eff} = \sqrt{A_{plume}} = \sqrt{\sum_{pixel=1}^{Npixel} A_{pixel}} \quad (2)$$

and an effective wind speed U_{eff} (m/s) to estimate the emission rate (Q, g/s) via the equation:

220
$$Q = \frac{U_{eff}}{L_{eff}} IME \quad (3)$$

221 U_{eff} is calculated from the 10-m wind speed U_{10} using an equation of the form (Varon et 222 al., 2018):

 $U_{eff} = a \log U_{10} + b \quad (4)$

Varon et al. (2018) used a = 0.9 and b = 0.6 m s⁻¹, and we use the same values for our continuous release tests.



- Figure 2. (a) Simulated plume from a point source of CH₄ with an emission rate of 50 kg hr⁻¹ and U_{10} wind speed of 2.6 m s⁻¹ at 16 UTC on March 8, 2016. (b) Addition of noisy background (13.3 g m⁻² ± 0.5%). (c) Final plume mask and estimated emission rate.

230 2.4 Overlapping Continuous Sources

To simulate overlapping continuous sources, we took the simulation shown in Figure 2 231 and added a second source to the east at distances of 0.25, 0.5, and 0.75 km. The wind direction 232 for the two plumes were rotated, such that a wind direction of 0° simulated the wind being 233 perpendicular to the line connecting the point sources and thus has the least overlap, while a 234 wind direction of 90° has the wind parallel to the line connecting the sources and thus has the 235 most overlap. We also simulated the intermediate case of 45°. Two cases were simulated for 236 emission rates, one where both sources had an emission rate of 50 kg hr⁻¹, and one where the 237 western source has a much larger release rate of 500 kg hr⁻¹ while the eastern source remains at 238 50 kg hr^{-1} . 239

240 **3 Results**

241 3.1 Continuous Sources

Figure 2 shows the plume mask results for a fairly dispersive plume under low wind speed conditions (2.6 m s^{-1}) and an instrument precision of 0.5%. The plume mask for this case does identify the central core of the plume but is too conservative to identify the full extent of the plume. This suggests that there is room for improvement in the plume identification algorithm.

The retrieved emissions for the true 50 kg hr^{-1} rate vary between 25-200 kg hr^{-1} for the 24 246 hours (and thus 24 meteorological conditions) simulated. Figure 3 shows the mean estimated 247 source rates for daytime hours (yellow bars), all hours (grey bars), and only hours with wind 248 speed less than 5 m s⁻¹ (blue bars) when 0.5% or 1.0% noise is added to the CH₄ background 249 column. When data from all hours are averaged, the IME approach used here returns estimates 250 with small positive biases (5-20 kg hr⁻¹). However, our assumed satellite instrument will only be 251 able to make measurements in the daytime. Looking at only daytime hours leads to a positive 252 bias of 25-50 kg hr⁻¹. The difference between the all-hours cases and the daylight-hours cases is 253 that the all-hours cases include more cases with a stable atmosphere, suppressing vertical mixing. 254

Somewhat surprisingly, the higher noise case tends to have a lower positive bias. We believe this is a case of compensating errors: the positive bias comes from our U_{eff} parameterization, but the higher noise level leads to an underestimate of the plume extent, and

thus IME, reducing the high noise bias.

The positive bias increases further (50-75 kg hr⁻¹) if only hours with wind speeds below 5 m s⁻¹ are considered. As the plume mask tends to miss plume pixels, it is unlikely that the source

of this bias is the plume mask or the IME calculation, which suggested that addressing these

biases requires further refinement of the U_{eff} parameterization, potentially to include other

263 meteorological inputs than just U_{10} wind speed.

Retrieved Source Rate Q (kg/hr) at two noise levels relative to original Q=50kg/hr on 20160308



264

Figure 3. Mean and 95% confidence interval of the retrieved emission rates for the 50 kg hr-1 continuous releases. Solid bars (left) are for 0.5% Gaussian noise in the background, while the hatched bars (right) are for 1.0% Gaussian noise.

Figure 4 shows the plume simulation and masking results for a case with 4 m s⁻¹ wind 268 speed. The top row shows the results for the native 30 m horizontal resolution of the simulations, 269 corresponding to a satellite ground sample distance of 30 m. We then degraded the resolution to 270 60 m, 90 m, and 120 m by averaging the original 30 m pixels and then applied the plume 271 identification algorithm. Only at the 30 m resolution was the plume mask able to retain the shape 272 273 of the simulated plume, with the other resolution only identifying enhanced blobs 0.25 - 0.75 km downwind from the original source. This again suggest that improvements are needed to the 274 plume identification algorithm, as the plume can be clearly identified by eye at 60 m resolution, 275 and somewhat at 90 m resolution. However, at 120 m resolution most of the plume enhancement 276 has been lost in the background, suggesting that even an improved plume identification 277 algorithm would not be able to identify a 50 kg hr⁻¹ leak at this spatial resolution. 278



Figure 4. Impact of different horizontal resolutions on the plume identification algorithm.

From top to bottom, the rows show the results at 30 m, 60 m, 90 m, and 120 m horizontal

resolution. Left column is the simulated column enhancement for the plume, middle

- column is after a background with 0.5% noise is added, and right column is the resulting
- plume mask. All simulations are for a release rate of 50 kg hr⁻¹ and a wind speed of 4.2 m s
- ²⁸⁵ ¹ (20 UTC on March 8, 2016).
- 286 3.2 Intermittent Sources

Figure 5 shows the results for the instantaneous release at 5 min (top row), 10 min (middle row) and 15 min (bottom row) after release for a 0.5% noisy background. The

- identification is very time dependent, as the instantaneous release results in a puff that is
- dispersing along both horizontal axes, resulting in concentrations that fall off more rapidly. The

291 maximum CH₄ column enhancement drops from 8 g m⁻² at release start to 0.025 g m⁻² 20 minutes

downwind.

293



Figure 5. Plume identification results for an instantaneous release of 33.5 kg from a

compressor blow-down at noon local time (UTC-7h) on March 8, 2016. From top to

bottom, the rows show the results for 5, 10, and 15 minutes after emission. Left column is

297 the simulated column enhancement for the plume, middle column is after a background 298 with 0.5% noise is added, and right column is the resulting plume mask.

At 5 minutes, the puff is clearly identifiable by eye against the noisy background (Figure 299 5), and the plume identification algorithm successfully identifies the puff, although a spurious 300 plume identification is also made to the northeast. At 10 min, it becomes difficult to identify the 301 puff visually. While the plume identification algorithm does identify the puff location, it also 302 classifies a large number of background locations as plume. At 15 min, it is difficult to identify 303 the plume by eye, and the plume identification algorithm only identifies the central core of the 304 plume, and after 15 min the puff is no longer detectable. This suggests an increased probability 305 of detection of short duration events with higher frequency (hourly or less) observations. 306

307 3.3 Overlapping Continuous Sources

For cases with equal source strength of 50 kg hr⁻¹ and a background column precision of 50 kg hr^{-1}

- 309 0.5%, the plume identification algorithm is generally able to separate the two overlapping
- sources if they are 0.5 km apart or more, regardless of the wind direction, but is not able to
- separate them if they are only 0.25 km apart. Figure 6 shows the most challenging case, where
- the wind is parallel with the line connecting the sources and so the upwind plume covers the
- downwind one (90-degree wind rotation from the original case in Figure 2). When the sources
- are only 0.25 km apart (top row), the plumes are merged in the plume mask. However, at 0.5 km (middle row) and 0.75 km (bottom row), the plume identification algorithm is able to distinguish
- the two plumes. Note that the horizontally dispersive case chosen here likely contributes to the
- ability to separate these plumes, as the centerline concentrations of the upwind plume have fallen
- to background levels before the second source is reached. Results for winds perpendicular to the
- 319 line connecting the sources (zero-degree wind rotation) and the 45-degree rotation case, are
- 320 shown in Supplemental Figures S1 and S2, respectively. The perpendicular shows two separate
- 321 plumes when they are spaced 0.5 km and 0.75 km apart. At 0.25 km the two plumes merge into a
- single feature, with a small near-source bifurcation in the plume mask being the only indication
- 323 of overlapping sources.

If the strength of the western source is increased to 500 kg hr⁻¹, the downwind plume is no longer separable from the upwind plume if the wind is parallel to the line connecting the sources (Supplemental Figure S3). This is true even if the locations of the sources are reversed



(not shown). Figure 7 shows the results if the wind is perpendicular. At 0.25 km, the second
source is only identifiable as a small tendril disrupting the overall symmetry of the larger plume.
At 0.5 km the tendril is more pronounced, and at 0.75 km we clearly see two distinct, if

- At 0.5 km the tendril is more pronounced, and at 0.75 km we clearly see two distinct, if eventually overlapping, plumes. These plumes are in principle separable, but the plume
- identification algorithm would have to be refined to fully separate the two plumes. The 45-
- degree rotated case (Supplemental Figure S4) gives similar results to the perpendicular case in
- 333 Figure 7.

334

- Figure 6. Plume identification results for two sources emitting 50 kg hr⁻¹ of CH₄ when the
- 336 winds are parallel to the line connecting the two sources. From top to bottom, the rows
- 337 show the results for when the sources are 0.25 km, 0.5 km, and 0.75 km apart. Left column
- is the simulated column enhancement for the plume, middle column is after a background
- 339 with 0.5% noise is added, and right column is the resulting plume mask.
- 340



Figure 7. Plume identification results for two sources, the western one emitting 500 kg hr⁻¹ of CH₄ and the eastern one emitting 50 kg hr⁻¹ of CH₄ when the winds are perpendicular to the line connecting the two sources. From top to bottom, the rows show the results for when the sources are 0.25 km, 0.5 km, and 0.75 km apart. Left column is the simulated column enhancement for the plume, middle column is after a background with 0.5% noise is

- 347 added, and right column is the resulting plume mask.
- 348

349 4 Conclusions

To help with the development of an operationally focused satellite constellation to detect 350 351 CH_4 emissions for the oil and gas industry, we applied a plume identification and quantification method based on Varon et al. (2018) to three types of sources. First, isolated continuous sources 352 with source strength of 50 kg hr⁻¹ were simulated as 80-90% of methane sources from oil and gas 353 are this size or larger. Second, an isolated instantaneous source of 33.5 kg was used to simulate 354 an intermittent release from a compressor blowdown. Third, overlapping continuous sources 355 were simulated for different distances, wind directions, and source strengths. A retrieved column 356 precision of 0.5%-1.0% was assumed for these cases, based on a future satellite instrument 357 operating in the 2050-2400 µm band with a signal to noise ratio (SNR) between 100-150 and a 358 spectral resolution between 1- 5 nm. 359

For the isolated continuous sources, the retrieved emissions varied between 25-200 kg hr⁻¹, with the daytime cases showing a mean bias of 25-50 kg hr⁻¹. As the plume identification algorithm tends to be overly conservative in identifying pixels as within the plume, this positive

bias suggests the need for improvements in the U_{eff} parameterization used in the IME method. 363 The plume mask performed the best at a horizontal resolution of 30-60 m, with the performance

364 degrading significantly at horizontal resolution greater than 90 m. 365

As the instantaneous releases disperse in both horizontal directions, the CH₄ columns fall 366 off as the square of distance/time downwind, rather than the linear decrease seen with continuous 367 releases. This limits the time downwind that a puff from an instantaneous release is visible. With 368 a 0.5% CH₄ column precision, a 33.5 kg CH₄ release is visible for 15 minutes after release. Thus, 369 the typical compressor start-up, compressor blow-down, and liquid unloading with a plunger lift 370 (7-200 kg, Allen et al., 2015) would have to be observed shortly after release to be detected by 371 satellite. Liquid unloadings without plunger lifts tend to have larger releases (400-700 kg, Allen 372 et al., 2015, Pacsi et al., 2020), and so may be visible for up to one hour after release. Thus, the 373 releases larger than 50 kg/hr would be detected by satellite. Oil well completions tend to be a 374 factor of 10 smaller (e.g., Cardoso-Saldaña and Allen, 2021), and so only the largest emitters 375 376 would be detected.

377 Overlapping plumes of similar small source strength were difficult to separate if they were only 0.25 km apart but were separable by the plume identification algorithm if they were 378 379 0.5 km apart or more. This result was independent of whether the wind was perpendicular or parallel to the line connecting the two sources. However, when one source was much larger than 380 381 the other, the resulting plumes tended to merge together downwind, although the sources were generally separable near the source. This suggests that a modified plume identification algorithm 382 383 could be able to better separate these plumes.

384 Future work will focus on further refinement of the plume identification algorithm to better identify the full plume and to better separate overlapping plumes from neighboring 385 sources. Further work is also needed to separate the puffs from intermittent sources from 386 statistical fluctuations in the retrieved background columns. In addition, improvements in the 387 parameterization of U_{eff} , potentially incorporating additional data beyond the U_{10} wind speed, 388 should be explored. 389

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Open Research 394

V3.3 of the SCICHEM model used for the dispersion modeling studies performed in this 395 work is publicly available at https://github.com/epri-dev/SCICHEM/tree/3.3 from the Electric 396 397 Power Research Institute. V12.13 of LBLRTM, used for calculating the Jacobians to estimate the precision of the retrieved methane columns for different assumptions of instrument resolution 398 and SNR, is publicly available at https://github.com/AER-RC/LBLRTM from Verisk 399 400 Atmospheric and Environmental Research. The LBLRTM license is free for all non-commercial

research uses. 401

The input (meteorological and terrain) and output data (raw concentration output,
calculated methane columns) from SCICHEM used in this study are available at zenodo via DOI
10.5281/zenodo.7757810 under a Creative Commons Attribution 4.0 International license.

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