Impact of updating vegetation information on land surface model performance

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Abstract

Vegetation plays a fundamental role in modulating the exchange of water, energy, and carbon fluxes between the land and the atmosphere. These exchanges are modelled by Land Surface Models (LSMs), which are an essential part of numerical weather prediction and data assimilation. However, most current LSMs implemented specifically in weather forecasting systems use climatological vegetation indices, and land use/land cover datasets in these models are often outdated. In this study, we update land surface data in the ECMWF land surface modelling system ECLand using Earth observation-based time varying leaf area index and land use/land cover data, and evaluate the impact of vegetation dynamics on model performance. The performance of the simulated latent heat flux and soil moisture is then evaluated against global gridded observation-based datasets. Updating the vegetation information does not always yield better model performances because the model's parameters are adapted to the previously employed land surface information. Therefore we recalibrate key soil and vegetation-related parameters at individual grid cells to adjust the model parameterizations to the new land surface information. This substantially improves model performance and demonstrates the benefits of updated vegetation information. Interestingly, we find that a regional parameter calibration outperforms a globally uniform adjustment of parameters, indicating that parameters should sufficiently reflect spatial variability in the land surface. Our results highlight that newly available Earth-observation products of vegetation dynamics and land cover changes can improve land surface model performances, which in turn can contribute to more accurate weather forecasts.

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¹⁰ Key Points:

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11	•	We find a substantial impact on the ECLand simulated latent heat flux and soil
12		moisture after updating land surface information
13	•	A regional calibration of land surface related parameters yields substantial bet-
14		ter agreement between model simulations and observations
15	•	Our results highlight the importance of representing vegetation dynamics and land
16		cover changes in land surface models

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17 Abstract

Vegetation plays a fundamental role in modulating the exchange of water, energy, and 18 carbon fluxes between the land and the atmosphere. These exchanges are modelled by 19 Land Surface Models (LSMs), which are an essential part of numerical weather predic-20 tion and data assimilation. However, most current LSMs implemented specifically in weather 21 forecasting systems use climatological vegetation indices, and land use/land cover datasets 22 in these models are often outdated. In this study, we update land surface data in the ECMWF 23 land surface modelling system ECLand using Earth observation-based time varying leaf 24 area index and land use/land cover data, and evaluate the impact of vegetation dynam-25 ics on model performance. The performance of the simulated latent heat flux and soil 26 moisture is then evaluated against global gridded observation-based datasets. Updat-27 ing the vegetation information does not always yield better model performances because 28 the model's parameters are adapted to the previously employed land surface informa-29 tion. Therefore we recalibrate key soil and vegetation-related parameters at individual 30 grid cells to adjust the model parameterizations to the new land surface information. This 31 substantially improves model performance and demonstrates the benefits of updated veg-32 etation information. Interestingly, we find that a regional parameter calibration outper-33 forms a globally uniform adjustment of parameters, indicating that parameters should 34 sufficiently reflect spatial variability in the land surface. Our results highlight that newly 35 available Earth-observation products of vegetation dynamics and land cover changes can 36 improve land surface model performances, which in turn can contribute to more accu-37 rate weather forecasts. 38

³⁹ Plain Language Summary

The accuracy of weather forecasts relies critically on the accurate modelling of the 40 exchange of water and energy between the land surface and the atmosphere. The latent 41 heat flux and the soil moisture are two important land surface variables in this exchange 42 through the net balances of water and energy. The accurate simulation of these variables 43 is challenging in most land surface models specifically used for numerical weather pre-44 diction due to i) outdated land surface cover information and/or ii) neglecting the role 45 of short-term anomalies in vegetation functioning, e.g. related to droughts. This study 46 quantifies the benefits of including up-to-date land use/land cover information and an 47 explicit consideration of the current vegetation state on the prediction of latent heat flux 48 and soil moisture. We find that model simulation performance can only benefit from up-49 dated land surface information through further adjustments to key soil and vegetation 50 related parameters in the model. Overall, we demonstrate that the new Earth observa-51 tion datasets can help to improve land surface model performance, which then contributes 52 to more accurate weather forecasts. 53

54 1 Introduction

The atmosphere is sensitive to variations in land surface processes, and such co-55 variability between the land and atmosphere states is described as the land-atmosphere 56 coupling (Santanello et al., 2009; Quillet et al., 2010; Santanello et al., 2018). The land 57 surface characteristics, e.g. vegetation state, albedo, and soil moisture, play important 58 roles in this coupling as they modulate the exchange of water, energy, and carbon be-59 tween the land surface and the atmosphere (Balsamo et al., 2011; de Rosnay et al., 2013; 60 Dirmeyer et al., 2018). Accordingly, an adequate representation of land surface proper-61 ties in the land surface models that are specifically used in numerical weather predic-62 tion (hereafter LSMs) contributes to improved forecast skills from short-range weather 63 forecasts to long-range seasonal predictions (Guo et al., 2011; Dirmeyer & Halder, 2017; 64 Nogueira et al., 2020), helping to better predict extreme events like heat waves or droughts 65 (Zhang et al., 2008; Meng et al., 2014; Hirsch et al., 2019; Miralles et al., 2019). 66

As LSMs are an essential component of the models that are typically used for weather 67 forecasting systems, there have been considerable efforts in recent decades to improve 68 LSM performance (Wipfler et al., 2011; Dutra et al., 2010; Laguë et al., 2019; Fisher & 69 Koven, 2020). The constantly increasing computing power allows us to include more re-70 alistic descriptions of relevant processes and their interactions with the atmosphere, in-71 cluding soil thermodynamics, vegetation dynamics, and land cover and management (Nemunaitis-72 Berry et al., 2017; González-Rouco et al., 2021; Steinert et al., 2021). Another reason 73 for this improvement is the increasing availability of Earth observation data that allows 74 to characterise surface properties and better constrain model simulations (Ghilain et al., 75 2012; Orth et al., 2017; Balsamo et al., 2018; Hawkins et al., 2019). For LSMs that em-76 ploy data assimilation, such as the Carbon Cycle Data Assimilation System (CCDAS) 77 (Rayner et al., 2005) and ORCHIDEE (Santaren et al., 2007), Earth observation con-78 stitutes an important data source for key land surface variables including soil moisture, 79 vegetation state, albedo, and land use/land cover (Guillevic et al., 2002; Seneviratne et 80 al., 2010; Meng et al., 2014). However, exploiting these new data streams for enhanced 81 land surface model performance is not straightforward (Wulfmeyer et al., 2018). 82

Traditional LSMs used for weather forecasting incorporate the effect of vegetation 83 on simulated land surface meteorology through look-up-tables providing different param-84 eter values depending on the biome type (Boussetta et al., 2013; Johannsen et al., 2019; 85 Duveiller et al., 2022). This requires up-to-date information on land cover described through 86 the considered biome types. Furthermore, state-of-the-art LSMs use satellite-observed 87 vegetation indices such as the leaf area index (LAI) to describe vegetation greening, ma-88 turity, and senescence (Boussetta et al., 2013; Stevens et al., 2020). However, in most 89 LSMs, the vegetation state is represented only through climatological seasonality, neglect-90 ing possible impacts of anomalies in vegetation functioning on the weather (Duveiller et 91 al., 2022). Therefore, the full potential of LSMs in the face of the newly available Earth 92 observation data is not vet well exploited, resulting in opportunities for further improv-93 ing weather prediction accuracy. 94

In this study, we use the ECMWF land surface modelling system ECL and based 95 on the previous Hydrology Tiled ECMWF Surface Scheme for Exchange over Land (HT-96 ESSEL) to investigate the impact of updating vegetation and land cover information on 97 model performance (Boussetta et al., 2021). Previous studies have found that updating 98 the vegetation information in HTESSEL enhances the performance of simulated soil mois-99 ture and energy fluxes thanks to a more accurate representation of i) the soil moisture 100 uptake and *ii*) the modulation of evapotranspiration in response to soil moisture changes 101 (Boussetta et al., 2013, 2015; Orth et al., 2017; Nogueira et al., 2020; O et al., 2020; Stevens 102 et al., 2020). More recent studies that use the coupled version of HTESSEL within the 103 Integrated Forecasting System (IFS) show the subsequent effect of updated land surface 104 information on the forecast skill. For instance, Johannsen et al. (2019) showed that large 105 biases in temperature simulated by the IFS strongly relate to the outdated land cover 106 representation within HTESSEL. Further, Nogueira et al. (2021) showed that it is nec-107 essary to adapt the model to the new data, i.e., to perform a recalibration of model pa-108 rameters. This recalibration is an important step in the process of exploiting the poten-109 tial of updated land surface information since the model is well adapted to the previously 110 used data. However most existing studies overlook the importance of model recalibra-111 tion, partially due to the lack of land observations to constrain the model parameters 112 (Orth et al., 2016). 113

Even though there have been considerable efforts to exploit additional Earth observations with HTESSEL, they have never brought together all updates in one single study, nor have they performed this in combination with a parameter recalibration. Building upon the most recent HTESSEL model performance studies, we perform a comprehensive analysis with updated land surface information in ECLand as follows: *i*) we update the land use/land cover information using the ESA-CCI/C3S dataset; *ii*) we introduce interannual variability of LAI and land cover fraction from Sentinel-3 and THEA GEOV2; *iii*) we perform a recalibration of key model parameters to adjust the model parameterizations to the newly updated land cover and vegetation information. This way, we explore the contribution of near-real time land surface information and model calibration to model performance.

¹²⁵ 2 Data and methods

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2.1 List of modelling experiments

We perform multiple uncoupled model experiments while continuously updating 127 the land and vegetation information of ECL and, as listed in Table 1. We use meteoro-128 logical forcing from ERA5 (Hersbach et al., 2020) at a reduced Gaussian grid of approx-129 imately 0.5° spatial resolution and hourly temporal resolution, from 1 January 1995 to 130 31 December 2019. The temperature, surface pressure, humidity and wind fields are in-131 stantaneous values and representative of the atmospheric layer at 10 m above the sur-132 face. The incoming shortwave and longwave radiation at the surface, rainfall and snow-133 fall are provided as hourly accumulations (Boussetta et al., 2015). We use a spin-up pe-134 riod from 1995-1999, and all results shown do not include these five years. 135

Experiment	Land cover dataset	Cover fraction dynamics	LAI dynamics	Land surface parameters
CONTROL	GLCC	Climatology	Climatology	Default
LC	ESA-CCI/C3S	Climatology	Climatology	Default
LC_COV	ESA-CCI/C3S	Interannual variability	Climatology	Default
LC_LAI	ESA-CCI/C3S	Climatology	Interannual variability	Default
LC_COV_LAI	ESA-CCI/C3S	Interannual variability	Interannual variability	Default
Global calibration	ESA-CCI/C3S	Interannual variability	Interannual variability	Spatially constant calibration
Regional calibration	ESA-CCI/C3S	Interannual variability	Interannual variability	Regionally varying calibration

 Table 1.
 Modelling experiments with ECLand

For each experiment, we update one aspect of the land surface model, i.e. land cover, 136 cover fraction, LAI or land surface parameters. We start from a baseline simulation (CON-137 TROL) which is based on an outdated land cover dataset from the USGS Global Land 138 Cover Characterization (GLCC) (Loveland et al., 2000), cover fraction and LAI clima-139 tology, and default model parameters, until we perform the LC_COV_LAI experiment 140 in which we update all aspects including the land cover dataset using information from 141 ESA-CCI/C3S (Bontemps et al., 2017), the cover fraction interannual variability and the 142 LAI interannual variability using 10-daily data from Sentinel-3 (Verger et al., 2022) and 143 THEA GEOV2 (Verger et al., 2020), but with default model parameters. The cover frac-144 tion and LAI interannual variability refers to monthly values that vary every year, in con-145 trast to climatological monthly means, based on the monthly mean calculated over the 146 period 1993-2019. 147

We additionally perform two calibration experiments (last two rows in Table 1) in 148 which we recalibrate six soil- and vegetation-related model parameters listed in Table 149 2: i) a global calibration in which we search a unique parameter set that works best over-150 all for all selected grid cells (i.e. spatially constant calibration), and ii) a regional cal-151 ibration in which we define the best parameter set individually for each grid cell (i.e. re-152 gionally varying calibration). We use Latin hypercube sampling (McKay et al., 1979) 153 to select 1000 random combinations of perturbation factors independently chosen for each 154 parameter within a specified range. The selection of the range for each parameter fol-155 lows previously used ranges in recent literature about parameter sensitivity analysis and 156

recalibration of similar parameters in HTESSEL (MacLeod et al., 2016; Orth et al., 2016,

¹⁵⁸ 2017; Johannsen et al., 2019; O et al., 2020; Stevens et al., 2020).

Tab	le 2.	Model	parameters	considered	for	$_{\mathrm{the}}$	recalibration	experiments
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Units	Range of default values	Range of perturbation factors
ms^{-1}	0.83-3.83	0.01-100.0
$ms^{-1}mbar$	0.00 - 0.03	0.25 - 4.0
sm^{-1}	80-250	0.25 - 4.0
-	-	0.25 - 4.0
cm	1-800	0.5 - 2.0
-	0.03 - 0.05	0.1 - 10.0
	Units ms ⁻¹ ms ⁻¹ mbar sm ⁻¹ - cm -	Units Range of default values ms^{-1} 0.83–3.83 $ms^{-1}mbar$ 0.00–0.03 sm^{-1} 80–250 - - cm 1–800 - 0.03–0.05

For computational efficiency, we perform the parameter calibration experiments only 159 at 230 randomly chosen grid cells across the globe (their location is shown in global maps 160 at Section 3.2.2). We only consider grid cells with a long-term mean Enhanced Vegeta-161 tion Index (EVI) greater than 0.2 to exclude regions with scarce vegetation. The EVI 162 data are derived from MODIS V6 (Didan, 2015). First, we select 30 grid cells to run the 163 1000 simulations (one for each parameter set), and we select the best 100 parameter sets 164 according to the model performance metric introduced in Section 2.2. Second, we run 165 the best 100 parameter sets in the remaining 200 grid cells and we again evaluate their 166 performance to find the best-performing parameters that work over a wider range of cli-167 mate regimes. 168

¹⁶⁹ 2.2 Model evaluation

For each model experiment, we compare simulated latent heat flux and soil mois-170 ture with respective global gridded observation-based datasets listed in Table 3. While 171 we use absolute values for latent heat flux, for near-surface and deep soil moisture we 172 analyze normalized anomalies to account for different systematic errors in ECLand and 173 in each reference dataset. To compute normalized anomalies for each soil moisture vari-174 able and dataset i) we subtract the linear long-term trend from the time series, ii) we 175 remove the mean seasonal cycle calculated at daily time steps over the period 2000-2019, 176 and *iii*) we divide by the standard deviation of the resulting time series. 177

Output variable	Reference dataset	Source of information
Near-surface soi lmoisture normalized anomalies	SoMo.ml 0-10 cm soil layer (upscaled in situ observations)	O and Orth (2021)
	GLEAM 0-10 cm soil layer (physical-based model)	Martens et al. (2017)
	MERRA-2 0-5 cm soil layer (reanalysis)	Gelaro et al. (2017)
Deep soil moisture normalized anomalies	SoMo.ml 10-50 cm soil layer (upscaled in situ observations)	O and Orth (2021)
*	GLEAM 10-100 cm soil layer (physical-based model)	Martens et al. (2017)
	MERRA-2 0-100 cm soil layer (reanalysis)	Gelaro et al. (2017)
Surface latent heat flux	FLUXCOM RS V6 (upscaled in situ observations)	Jung et al. (2019)
	GLEAM (physical-based model)	Martens et al. (2017)
	MERRA-2 (reanalysis)	Gelaro et al. (2017)

Table 3. Reference datasets for model performance evaluation

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We use censored RMSE (cenRMSE) as a performance metric, which is based on modified root mean squared error (RMSE) to account for uncertainties in the observational data. The term "censored" refers to a value that occurs outside the range of a measuring instrument (Fridley & Dixon, 2007). We compute the cenRMSE as follows:

$$cenRMSE = \sqrt{\sum_{i=1}^{n} dy_i^2} \tag{1}$$

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$$dy_i = min(|\hat{y}_i - y_{i,r}|), r = 1, 2, 3 \tag{2}$$

 \hat{y}_i is the model value in time step *i* and $y_{i,r}$ is the reference data for the three refrescale erences $(y_{i,1}, y_{i,2}, y_{i,3})$. $dy_i = 0$ if \hat{y}_i is in the interval defined by the range of the refrescale erence values, otherwise the minimum is taken to compute the cenRMSE. The cenRMSE behaves like RMSE outside the interval and is 0 if all predictions are within the range of reference values.

Specifically for the parameter calibration experiments, we combine the cenRMSE
 performance metric of the three target variables (i.e. near-surface soil moisture, deep soil
 moisture and surface latent heat flux). We rank the 1000 perturbation factors individ ually for each variable and then we add the individual ranks up. The lowest (highest)
 sums constitute the best (poorest) perturbation factors in terms of model performance.

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2.3 Spatial variability of regional parameters

We extend our analysis to the spatial features of calibrated model parameters (Ta-195 ble 2). We employ random forest models (Breiman, 2001; Molnar, 2020) (hereafter RF) 196 to predict each of the six calibrated parameter values across grid pixels (six RF mod-197 els are used). As predictor variables we use i long-term mean climatic and land surface 198 characteristics such as aridity, temperature and EVI, ii) differences in high and low veg-199 etation cover between the two land cover datasets used in the modelling experiments (ESA-200 CCI/C3S and GLCC) (Boussetta et al., 2021), and *iii*) the values of the remaining five 201 parameters (other than the target parameter). This allows us to determine if there is a 202 spatial pattern of the newly defined model parameters and, if so, to quantify factors in-203 fluencing the spatial patterns. 204

We use information from the 230 grid cells for the RF training. We assess the performance of the RF models by computing the R^2 between the predicted and the observed target variables for out-of-bag (OOB) data that was not used for training (hereafter referred to as estimate of R^2) (Li et al., 2021). We infer the relative importance of each predictor variable from SHapley Additive exPlanations (SHAP) feature importance which is based on the average marginal contribution of each predictor to the modelled target variable (Lundberg & Lee, 2017; Sundararajan & Najmi, 2020).

We note a potential caveat in our approach with the RF due to existing relationships among our selected set of predictors. Accordingly, we compute individual Spearman correlations (Wilks, 2011) among the predictors to account for the magnitude of these associations and to identify the most affected variables.

²¹⁶ 3 Results and discussion

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3.1 Impact of updated land surface information on model performance

Figure 1 shows ECLand's model performance in the CONTROL experiment. In general, the model performance varies considerably across regions. For near-surface and deep soil moisture (Figure 1 a and b), we see relatively good performance in the midlatitudes of Europe, North America and southern South America. On the contrary, the model performs poorly in high-latitude regions, possibly due to high uncertainty in soil

moisture-related processes, e.g., soil freeze/thaw cycles (Dutra et al., 2010, 2011; Diro et 223 al., 2018). In some regions, the model performance for deep soil moisture is slightly poorer 224 than for near-surface soil moisture. This can be due to the high uncertainty among the 225 reference datasets for deep soil moisture values as a consequence of sparse observations 226 (Denissen et al., 2020; Koster et al., 2020; Li et al., 2021). For the surface latent heat 227 flux (Figure 1 c) the cenRMSE is relatively good in central and eastern Europe and North 228 America, which might be related to the high density of observations that can support 229 model development and parameter calibration dedicated to these regions (Stegehuis et 230 al., 2013). 231



Figure 1. cenRMSE performance metric of CONTROL simulation for a) near-surface soil moisture, b) deep soil moisture and c) surface latent heat flux. cenRMSE is computed based on absolute values for latent heat flux, while normalized anomalies are used for soil moisture. Numbers in the textboxes represent the global median. Gray areas are masked as their long-term mean EVI is lower than 0.2.

Figure 2 shows the performance of the experiment with the most updated land in-232 formation (LC_COV_LAI) compared to the performance of the CONTROL experiment. 233 We find a general deterioration of model performance (red color) for all three variables 234 considered which is related to the high sensitivity of the RMSE-based metrics to out-235 liers. Recomputing the cenRMSE without the 10% largest disagreements between LC_COV_LAI 236 and CONTROL simulation confirms that the percentage difference in cenRMSE improves 237 in most regions (not shown). Therefore, on average, an update of the land surface in-238 formation in ECL and has positive impacts on the prediction of surface latent heat flux 239 and near-surface and deep soil moisture. 240



Figure 2. Similar to Figure 1, but for percentage differences in performance: LC_COV_LAI minus CONTROL divided by CONTROL.

The updated land surface information has a much clearer impact on the simula-241 tion of latent heat flux compared to soil moisture, as indicated by a larger magnitude 242 of percentage changes in surface latent heat flux. Also, the spatial patterns of improve-243 ment/deterioration are not always consistent between latent heat flux and soil moisture; 244 for instance, in southern South America there is improvement in most areas for surface 245 latent heat flux but for both near-surface and deep soil moisture we find deterioration. 246 This points to possible weaknesses in the representation of the coupling between latent 247 heat flux and soil moisture in the model, as also stated in other studies (Zhang et al., 248 2008; Santanello et al., 2009; Quillet et al., 2010; Meng et al., 2014; Dirmeyer & Halder, 249 2017; Wulfmeyer et al., 2018; Fairbairn et al., 2019). 250

We also look at the model performance of each individual experiment in terms of the three considered output variables (Figures S1, S2 and S3). In general, the spatial patterns of improvement and deterioration are similar to the results in Figure 2. Comparing the magnitudes of the changes we find that the strongest effect on the model performance is exerted by the land cover type update, which is present in all experiments. The LAI interannual variability update has the second strongest effect on the model performance (Boussetta et al., 2013, 2015; Stevens et al., 2020; Duveiller et al., 2022).

3.2 Effect of recalibration of model parameters

3.2.1 Ranks of the parameter sets

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We rank the 1000 model simulations with perturbed parameter values according to the cenRMSE performance metric of the three target variables (see Section 2.2), and relate the ranking to individual parameter perturbations in Figure 3 in order to assess their individual contribution. Table S1 shows the individual optimal perturbation factors for the model parameters. Hydraulic conductivity and minimum stomatal resistance show the strongest systematic influence on model performance, similar to the results from Orth et al. (2016) and Orth et al. (2017).



Figure 3. Relating model performance to perturbations in the considered individual ECLand parameters: a) hydraulic conductivity, b) humidity stress function, c) minimum stomatal resistance, d) soil moisture stress function, e) total soil depth and f) transmission of net solar radiation through vegetation. Red dots indicate the performance of the default parameterizations (i.e. no perturbation). A rank value of 1 (1000) in the Y-axis indicates the best (poorest) perturbation factor in model performance.

Hydraulic conductivity governs the water transport in the soil and is therefore directly linked to soil moisture and evapotranspiration (latent heat flux). We find that a substantial reduction of the hydraulic conductivity from its default value improves model performance. This reduces percolation of infiltrated water and therefore increases nearsurface soil moisture and ultimately latent heat flux (O et al., 2020). If the model with the new land surface information displays a general dry bias in soil moisture, a lower hydraulic conductivity would help in retaining more water into the soil matrix.

In the case of the minimum stomatal resistance it strongly relates to evapotranspiration as it modulates the exchange of moisture from vegetated surfaces (Orth et al., 2016). Our results suggest that there is an optimum perturbation value for the minimum stomatal resistance between 1 and 2, i.e. close to the default parameterization, thus, modifying it has little potential to improve the model. The increase in stomata resistance should be related to an excess of evapotranspiration with the new land surface information, for instance, with an increase of LAI, compared to the CONTROL experiment.

We also analyze the influence of parameter perturbations on model performance 281 in terms of the considered individual variables (Figures S4, S5 and S6). The clear pat-282 tern of better model performance in the case of lower hydraulic conductivity found in 283 Figure 3 is mainly related to an improvement of the soil moisture performance, especially for the near-surface layer (Figure S4). For the minimum stomatal resistance the pattern 285 found in Figure 3 is related to variations in the simulation performance of latent heat 286 flux (Figure S6). Additionally, the total soil depth is relevant for the simulation perfor-287 mance of deep soil moisture, (Figure S5) as also found in a similar study by Hawkins et 288 al. (2019). This illustrates that different parameters matter for different land surface vari-289 ables, as well as that different observational datasets are needed to constrain different 290 parameters. 291

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3.2.2 Model performance in parameter calibration experiments

Figures 4 and 5 show the model performance changes relative to CONTROL af-293 ter the global and the regional recalibration across 230 grid cells, respectively. Gener-294 ally, for the global calibration (Figure 4) we find inconsistent results with improved or 295 deteriorated model performance depending on the grid cell. This suggests that there is 296 no one(calibration)-fits-all(regions) solution, probably related to the spatial heterogeneity in climate along with different land surface characteristics, or its insufficient repre-298 sentation in the current default values in the model (like for specific vegetation types, 299 soil textures, etc.) (Laguë et al., 2019; Nogueira et al., 2021), as can be seen from the 300 spatial distribution of the calibrated parameter values in Figure S7. After the global cal-301 ibration we already see an improvement in both soil moisture variables but it is not al-302 ways the case for the surface latent heat flux, probably due to compensation in model 303 performance between variables (McCabe et al., 2005). This is expected as the newly applied datastreams are related to land cover and vegetation structure. Specifically, the 305 model performance in the grid cells in northern Asia always degrades from a global cal-306 ibration, whereas for the other regions we see mixed results. 307

After the regional calibration, we find substantial improvement in model perfor-308 mance for all three variables as shown in Figure 5. See also Figure S8 for comparisons 309 of model performance between the regional and global calibrations. In a similar study 310 for another LSM, Xie et al. (2007) found an improvement in model performance after 311 a regional calibration of model parameters. This suggests that parameters should suf-312 ficiently reflect land surface heterogeneity, different climate zones, different biome types, 313 etc. The regional calibration leads to better model performance for most grid pixels, ex-314 cept for high latitudes in Northern Asia, possibly due to high uncertainty in the repre-315 sentation of soil freeze processes, as found in other studies (Dutra et al., 2010, 2011; Diro 316 et al., 2018). 317

To aggregate our main findings, Figure 6 shows the median global change in model 318 performance for each experiment and variable. Most of the experiments do not show clear 319 model performance improvement with regards to the CONTROL simulation before re-320 calibration. Only the regional calibration experiment shows improvement in all output 321 variables, which calls for parameter recalibration after updating land surface informa-322 tion on LSMs to exploit the benefits of Earth observation developments (Nogueira et al., 323 2021). This is specifically the case for a regional (spatially varying) as opposed to the 324 global (spatially constant) calibration as this can better account for spatial heterogeneities, 325 and compensate for potentially related shortcomings in the model structure (Xie et al., 326 2007). The variability of the experiments (represented by the error bars in Figure 6) for 327 the surface latent heat flux is higher than for the two soil moisture variables. We attribute 328 this to a direct effect on latent heat flux from the perturbation of the selected param-329 eters because these are mostly related with evapotranspiration, whereas they have an 330 indirect effect on soil moisture (Jefferson et al., 2017; Montzka et al., 2017). 331



Figure 4. Similar to Figure 1, but for percentage differences in performance: Global calibration minus CONTROL divided by CONTROL.

In a final step, we study model performance changes in wet vs. dry regions by pro-332 ducing Figure 6 for such regions separately (Figure S9). The effect of updating land sur-333 face information in ECL and on model performance is generally stronger in dry grid cells 334 than in wet grid cells. This is expected since vegetation plays a more important role for 335 modulating the exchange of water and energy in dry-to-transitional regions, whereas the 336 role of the vegetation and relevant land processes in comparison to the effect of atmo-337 spheric dynamics is less prominent in wet regions (Seneviratne et al., 2010; Miralles et 338 al., 2019; Denissen et al., 2020). 339

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3.3 Attribution analysis of spatial patterns of regional parameter calibration

In a final step, we analyze the spatial patterns of the optimal parameter pertur-342 bations determined in the grid cell-wise model calibration shown in Figure S7. In order 343 to explain the spatial pattern of each parameter we consider several predictors includ-344 ing climate and vegetation characteristics, as well as the calibrated values of the other 345 considered parameters. This attribution analysis is done separately for each parameter 346 (target in the regional calibration). Figure 7 shows that overall we see that for each of 347 the modelled parameters, the remaining parameters are the best factors to predict the 348 values of the target. Only for the humidity stress function (Figure 7 b) and for the trans-349 mission of net solar radiation through vegetation (Figure 7 f) the difference in vegeta-350 tion type and the temperature are important predictors (other than the remaining model 351 parameters) in the RF models, respectively. We attribute this to an equifinality prob-352 lem in the model and accept it as a caveat in our analysis: we select only the best pa-353



Figure 5. Similar to Figure 1, but for percentage differences in performance: Regional calibration minus CONTROL divided by CONTROL.

rameter sets while other sets might perform almost as good as the best set (Williams et al., 2009).

The RF models have in general a good model performance (Figure S10), meaning that the considered factors can explain the spatial patterns of model parameters. The hydraulic conductivity calibration has the best RF model performance due to the clear systematic pattern in the parameter set ranks (Figure 3 a), specially given by the dependence of the near-surface soil moisture model performance on this parameter (Figure S4).

The relative importance is analyzed here for correlation and not causation. We acknowledge that some of the selected factors are highly correlated (Figure S11) and their actual relative importance might be reduced by the collinearities (Ghosh & Maiti, 2021). The most cross-correlated ones are: hydraulic conductivity and total soil depth; minimum stomatal resistance and soil moisture stress function; EVI and aridity; EVI and temperature; and the differences in high and low vegetation cover. However, most pairs of factors show correlation lower than 0.2.

³⁶⁹ 4 Summary and conclusion

Recent studies performed substantial efforts for exploiting additional Earth observations in ECLand model validation (Boussetta et al., 2013, 2015; Orth et al., 2017; Nogueira et al., 2020; O et al., 2020; Stevens et al., 2020). However these experiments have never



Figure 6. Summary of ECLand performance for each experiment compared to the CON-TROL simulation. Medians of percentage change of cenRMSE across 230 grid cells are shown. The error bars represent the 25th and 75th percentile.

included all updates in one single study. Neither have they performed a follow-up recalibration of the model to exploit the benefits of including more accurate land surface information. Here we make a step in this direction with our comprehensive modelling experiments (Gupta et al., 1999), not only updating land cover type but also including interannual variability of LAI and cover fraction.

We find a substantial impact of updating land and vegetation information from newly 378 available Earth observations on the simulated surface latent heat flux and near-surface 379 and deep soil moisture. However, these modifications do not always show positive im-380 pacts on the model performance. The changes in model performance vary between re-381 gions and considered variables, indicating the need for model evaluation based on mul-382 tivariable analysis to make conclusive remarks on model performance (McCabe et al., 383 2005). Further, this shows that ingesting novel Earth observation data streams into cur-384 rent LSMs is not automatically leading to improved model performance as the model pa-385 rameterizations need to be adapted to these updates (Nogueira et al., 2021). By consid-386 ering several reference datasets, we benefit from the growing suite of global observational 387 products, and manage to incorporate the uncertainty between these products into our 388 evaluation of model performance. 389

As a further step we also recalibrate the model to adapt it to the new conditions. For the model recalibration we follow two approaches: global calibration and regional calibration (Xie et al., 2007). We find that the regional calibration yields substantial better agreement between model simulations and reference datasets, suggesting it may be beneficial to revise the spatial variability of model parameters which so far is based on soil and vegetation types (i.e. look-up tables). An update of those look-up tables and/or



Figure 7. Relative importance (SHAP values) of multiple factors to explain the spatial patterns of regionally calibrated model parameters for a) hydraulic conductivity, b) humidity stress function, c) Minimum stomatal resistance, d) soil moisture stress function, e) total soil depth and f) transmission of net solar radiation through vegetation. Note that the Y-axes have different ranges.

the consideration of more aspects of spatial heterogeneity may be a way forward in this context. This would allow that future calibrations can be done globally only.

We suggest that one reason for the lack of improvement in the model performance after updating land surface information with state-of-the-art observations is attributed to the then outdated model parameters. The model shows substantial improvement when adjusting parameters, particularly through the regional calibration, indicating that land information updates in the model cannot be treated independently from model parameterization. Future work should consider the impact of the improved and calibrated ECLand performance within a coupled model system.

405 Open Research Section

The meteorological forcing for ECLand from ERA5 is available at https://cds.climate.copernicus.eu/ (ECMWF & Service, 2018). The EVI data from MODIS are available through NASA's data catalogue at https://lpdaac.usgs.gov/products/mod13c1v006/ (EOSDIS, 2015). Both the evaporative fraction data from FLUXCOM and the soil moisture data from SoMo.ml are available at the Data Portal of the Max Planck Institute for Biogeochemistry at https://www.bgcjena.mpg.de/geodb/projects/Data.php (for Biogeochemistry, 2019, 2021). The output data from the ECLand modelling experiments are available in the Zenodo repository at

413 https://doi.org/10.5281/zenodo.7823893.

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Supporting information for "Impact of updating vegetation information on land surface model performance"

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Introduction

The present document contains additional material (Table and Figures) that supports the discussion in the study "Impact of updating vegetation information on land surface model performance". This material is not included in the main text because it is not essential to the main scientific conclusins other than providing additional information.

 Table S1.
 Optimal perturbation factors for the model parameters after global calibration

Model parameter	Optimal perturbation factors
Hydraulic conductivity	0.09766
Humidity stress function	0.83900
Minimum stomatal resistance	1.27800
Soil moisture stress function	1.47000
Total soil depth	1.06044
Transmission of net solar radiation through vegetation	0.13652



Figure S1. Percentage differences in cenRMSE model performance for near-surface soil moisture in a) LC, b) LC_COV, c) LC_LAI, d) LC_COV_LAI, e) Global calibration and f) Regional calibration simulations with regards to CONTROL simulation. Numbers in the textboxes represent the global median.



Figure S2. Similar to Figure S1, but for deep soil moisture.



Figure S3. Similar to Figure S1, but for surface latent heat flux.



Figure S4. Rankings of 1001 random perturbation factors for near-surface soil moisture for a) hydraulic conductivity, b) humidity stress function, c) minimum stomatal resistance, d) soil moisture stress function, e) total soil depth and f) transmission of net solar radiation through vegetation. Red dots indicate the performance of the default parameterizations (i.e. no perturbation).



Figure S5. Similar to Figure S4, but for deep soil moisture.



Figure S6. Similar to Figure S4, but for surface latent heat flux.



Figure S7. Spatial distribution of the calibrated parameter values in the regional calibration experiment for a) hydraulic conductivity, b) humidity stress function, c) minimum stomatal resistance, d) soil moisture stress function, e) total soil depth and f) transmission of net solar radiation through vegetation.



Figure S8. Model performance of the global parameter calibration experiment (left column) and reduction in cenRMSE of the regional parameter calibration experiment with regards to the global calibration experiment (right column) for a) near-surface soil moisture, b) deep soil moisture and c) surface latent heat flux.



a) Dry grid cells

Figure S9. Summary of ECLand performance for each experiment compared to the CONTROL simulation only considering a) dry (\leq first quartile of soil moisture) and b) wet (\geq third quartile of soil moisture) grid cells. The error bars represent the 25th and 75th percentile.



Figure S10. Model performance (OOB estimate of R^2) in the trained RF for the considered six soil and vegetation related model parameters. Higher OOB means the RF can well explain the spatial pattern of model parameters.

Hydraulic conductivity -	1.00	0.04	0.22	0.24	-0.51	-0.02	0.21	0.20	-0.02	0.03	0.05
Parameter in humidity stress function -	0.04	1.00	-0.33	0.14	0.05	0.02	0.05	-0.06	-0.00	-0.21	0.11
Minimum stomatal resistance -	0.22	-0.33	1.00	-0.43	-0.23	-0.13	-0.02	0.16	0.23	0.08	0.04
Soil moisture stress function -	0.24	0.14	-0.43	1.00	0.05	0.23	0.27	0.11	-0.25	-0.02	-0.06
Total soil depth -	-0.51	0.05	-0.23	0.05	1.00	-0.09	-0.21	-0.11	0.16	-0.03	0.00
Transmission of net solar _ radiation through vegetation	-0.02	0.02	-0.13	0.23	-0.09	1.00	-0.05	-0.15	-0.19	-0.09	0.11
Aridity -	0.21	0.05	-0.02	0.27	-0.21	-0.05	1.00	0.17	-0.49	0.01	-0.13
Temperature -	0.20	-0.06	0.16	0.11	-0.11	-0.15	0.17	1.00	0.43	0.20	-0.11
EVI -	-0.02	-0.00	0.23	-0.25	0.16	-0.19	-0.49	0.43	1.00	0.03	0.17
Differences in high vegetation cover	0.03	-0.21	0.08	-0.02	-0.03	-0.09	0.01	0.20	0.03	1.00	-0.60
Differences in low _ vegetation cover	0.05	0.11	0.04	-0.06	0.00	0.11	-0.13	-0.11	0.17	-0.60	1.00
	Hydraulic conductivity -	Parameter in humidity stress function -	Minimum stomatal resistance -	Soil moisture stress function -	Total soil depth -	Transmission of net solar radiation through vegetation	Aridity -	Temperature -	EVI -	Differences in high vegetation cover	Differences in low vegetation cover

Figure S11. Spearman cross-correlation matrix among the 11 predictors used in the RF models to predict the calibrated parameter values.