

Process-based simulations of percolation from various landfill final covers in a cold climate

Alireza Amani¹, Marie-Amélie Boucher¹, Alexander Cabral¹, Vincent Vionnet², and Étienne Gaborit²

¹Université de Sherbrooke Département de Génie Civil et de Génie du Bâtiment

²Environment and Climate Change Canada Montreal Office

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Abstract

Accurate estimation of percolation is crucial for assessing landfill final cover effectiveness, designing leachate collection/treatment systems, and many other applications, such as in agriculture. Despite the importance, percolation is seldom measured due to the high cost and maintenance of lysimeters, underlining the need for skillful simulation. Process-based numerical models, despite requiring validation and numerous parameters, present an alternative for percolation simulation, though few studies have assessed their performance. This study compares percolation measured from three fully instrumented large-scale experimental plots to simulate percolation using a new version of the Soil Vegetation and Snow (SVS) land-surface model with an active soil-freezing module. Previous research indicates numerical model performance may significantly vary based on soil-related parameter values. To account for input data and parameter uncertainty, we use an ensemble simulation strategy incorporating random perturbations. The results suggest that SVS can accurately capture the seasonal patterns of percolation, including significant events during snowmelts in spring and fall, with little to no percolation in winter and summer. The continuous ranked probability skill score values for the three plots are 0.13, -0.13, and 0.33. SVS simulates near-surface soil temperature dynamics effectively (R^2 values 0.97-0.98) but underestimates temperature and has limitations in simulating soil temperature in snow-free situations in the cold season. It also overestimates soil freezing duration, revealing discrepancies in the onset and end of freezing periods compared to observed data. This study highlights the potential of land surface models for the simulation of percolation, with potential applications in the design of systems such as leachate collection and treatment. While the SVS model already provides an interesting outlook, further research is needed to address its limitations in simulating soil temperature dynamics during soil freezing periods.

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Alireza Amani ^{*}, Marie-Amélie Boucher , Alexandre R. Cabral 

Department of Civil and Building Engineering, Université de Sherbrooke, Sherbrooke, Quebec, Canada

Vincent Vionnet , Étienne Gaborit 

Environmental Numerical Weather Prediction Research, Environment and Climate Change Canada, Dorval, Quebec, Canada

Abstract

Accurate estimation of percolation is crucial for assessing landfill final cover effectiveness, designing leachate collection/treatment systems, and many other applications, such as in agriculture. Despite the importance, percolation is seldom measured due to the high cost and maintenance of lysimeters, underlining the need for skillful simulation. Process-based numerical models, despite requiring validation and numerous parameters, present an alternative for percolation simulation, though few studies have assessed their performance. This study compares percolation measured from three fully instrumented large-scale experimental plots to simulate percolation using a new version of the Soil Vegetation and Snow (SVS) land-surface model with an active soil-freezing module. Previous research indicates numerical model performance may significantly vary based on soil-related parameter values. To account for input data and parameter uncertainty, we use an ensemble simulation strategy incorporating random perturbations. The results suggest that SVS can accurately capture the seasonal patterns of percolation, including significant events during snowmelts in spring and fall, with little to no percolation in winter and summer. The contin-

^{*}Corresponding author

Email address: alireza.amani@usherbrooke.ca (Alireza Amani )

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Keywords: land-surface model; percolation; lysimeter; soil freezing; soil moisture; soil temperature; landfill final cover; ensemble simulation;

1. Introduction

Accurate estimates of deep percolation, the net amount of water percolating below the root zone (Bethune et al., 2008), are necessary for various practical applications. In landfill engineering, precise percolation estimates are critical for assessing the effectiveness of landfill final covers to design leachate collection systems properly. Leachate, a toxic liquid produced from percolated water interacting with waste, must be treated to prevent environmental harm such as groundwater and soil pollution (Kjeldsen et al., 2002).

Percolation estimates are vitally important in agricultural water management for optimizing irrigation, i.e. minimizing percolation and maximizing transpiration (Wang et al., 2012). Percolation is also associated with nitrogen leaching from agricultural soils (Xu et al., 2017), which threatens groundwater quality and has other adverse effects such as contributing to the eutrophication of water bodies (Carpenter et al., 1998), leading to harmful algal blooms and loss of biodiversity (Abdalla et al., 2019; Ascott et al., 2017; Smith et al., 2006). In groundwater management, percolation rates are important for understanding

17 aquifer recharge and developing effective conservation and management strate-
18 gies, particularly in regions with low precipitation and high water demand where
19 unsustainable groundwater abstraction can occur (Finch, 1998a).

20 Lysimeters, such as pan lysimeters, are reliable and accurate for measuring
21 percolation directly in the field (Bethune et al., 2008; Kahale & Cabral, 2022;
22 Mijares & Khire, 2012). However, they can be expensive to install and maintain,
23 requiring specialized labor and materials, as well as regular maintenance and
24 monitoring. This renders other methods of estimating percolation appealing, in
25 particular during the pre-feasibility and feasibility phase of the design process.

26 Process-based numerical models, which consider the physical processes gov-
27 erning the transport of water through soil, could offer an alternative to costly
28 direct measurements, or complement them. These models can, for example, be
29 used to better understand the underlying processes and variables influencing
30 percolation (for instance through sensitivity analyses), as well as testing the
31 impact of different scenarios. This can for instance help applications such as
32 irrigation management and groundwater conservation. A process-based model
33 can help to quantify the response of percolation to different management prac-
34 tices (Bethune et al., 2008) and climate change scenarios (Wang et al., 2018),
35 among other sources of uncertainty.

36 However, using any particular numerical model presents at least two chal-
37 lenges. First, a large amount of field data from locations with diverse climatic
38 and physical conditions is required to validate the model. Second, a large set of
39 physical parameters is needed to describe the natural systems being modeled,
40 and this requires specialized knowledge and/or measuring equipment (Finch,
41 1998b; Bethune et al., 2008). As a result, there are relatively few studies that
42 have focused on local percolation simulations using process-based models. De-
43 spite these challenges, process-based numerical models are a potential option
44 for estimating percolation because they can be used to simulate it for example
45 at various spatial and temporal scales, under different climatic conditions, or
46 considering different management scenarios.

47 Bethune et al. (2008) reported on a lysimeter experiment in Southeastern

48 Australia aimed at measuring percolation in an irrigated pasture under various
49 conditions such as different combinations of water table depths, soil types, and
50 ponding times as a result of surface irrigation. The analysis of experimental data
51 led to the identification of influential governing variables for percolation, which
52 in turn were used to develop a conceptual model. This model was subsequently
53 tested against lysimeter and field-scale water balance data. The performance
54 of the developed model was benchmarked against both a data-driven model
55 and a calibrated process-based model, namely, artificial neural networks and
56 HYDRUS-1D (Simunek et al., 2005). The conceptual model performed bet-
57 ter than the data-driven and process-based models for most soil types while
58 requiring fewer input data compared to the artificial neural network.

59 Benson et al. (2005) evaluated the simulations of percolations from two mod-
60 els, UNSAT-H (Fayer, 2000) and VADOSE/W (Krahn, 2004), against measure-
61 ments from an instrumented experimental plot in a semi-arid climate (Cali-
62 fornia, USA). UNSAT-H overestimated surface runoff, which led to the model
63 underestimating percolation. On the contrary, VADOSE/W was able to esti-
64 mate runoff relatively accurately. However, similarly to UNSAT-H, it underes-
65 timated percolation. The authors hypothesized that this issue could be related
66 to the accuracy of saturated hydraulic conductivity as an input parameter to
67 the models.

68 Using the measured percolation/runoff quantities from the same test plot of
69 Benson et al. (2005), Bohnhoff et al. (2009) assessed and compared the perfor-
70 mance of HYDRUS, LEACHM (Hutson & Wagenet, 1995), VADOSE/W, and
71 UNSAT-H. The accuracy of all water-balance components was influenced by
72 the accuracy of the runoff prediction. Runoff was estimated more accurately
73 when precipitation was applied uniformly throughout the day, the surface layer
74 was given a larger saturated hydraulic conductivity, and Brooks-Corey functions
75 were employed to describe the hydraulic characteristics of the soils. Percolation
76 was consistently underestimated by all models. A five to ten-fold increase in
77 the laboratory-obtained saturated hydraulic conductivity of the soils improved
78 the simulation of percolation.

79 Past research focusing on percolation simulation has typically been car-
80 ried out in regions characterized by minimal annual rainfall, negligible to non-
81 existent snow accumulation, and the absence of seasonal freeze-thaw cycles.
82 This concentration of studies in such specific geographic and climatic contexts
83 means that their findings may not translate effectively to different environmental
84 conditions. For instance, in regions where snow accumulation and soil freezing
85 are prevalent, these factors can significantly influence soil hydrology (Fu et al.,
86 2018). These circumstances add complexity for numerical models.

87 Furthermore, widespread models, such as HYDRUS-1D which is often used
88 in landfill final cover assessment, do not consider factors like snow and soil freez-
89 ing. This could limit the comprehensiveness and applicability of their results
90 when dealing with diverse and more challenging environmental conditions.

91 Previous studies on simulating percolation did not account for sources of
92 uncertainty, such as meteorological input data uncertainty, and soil hydraulic
93 parameters' uncertainty, which can significantly impact the performance of mod-
94 els, as shown by Bohnhoff et al. (2009). Probabilistic approaches, like ensemble
95 simulation, can help estimate these uncertainties by generating a range of possi-
96 ble outcomes based on different input data and parameters. Ultimately, better
97 estimating these uncertainties allows for more informed decision-making.

98 Another important limitation of earlier percolation studies is that they only
99 compared total annual simulated and measured percolation volumes, rather than
100 daily or sub-daily time series (Mijares & Khire, 2012). This temporal aggrega-
101 tion restricts our ability to detect differences in the temporal patterns of perco-
102 lation. It also limits the identification of potential causes of differences between
103 simulated and measured values.

104 In this study, we use the Soil, Vegetation, and Snow (SVS) land-surface
105 model (Alavi et al., 2016; Husain et al., 2016) to simulate point-scale percolation
106 from the bottom of three large-scale experimental plots (soil enclosures). These
107 experimental plots are designed and built to evaluate the performance of three
108 different landfill final covers. They are located in Southeast Quebec (Canada),
109 a region with a warm-summer humid continental climate (Dfb), according to

110 the Köppen classification (Peel et al., 2007). Four pan lysimeters (two inside
111 one of the plots) are installed to collect percolation, which is recorded hourly
112 by data loggers.

113 SVS is a process-based model developed and used operationally by Environ-
114 ment and Climate Change Canada (ECCC), with a special focus on the rep-
115 resentation of subsurface hydrological processes. SVS explicitly considers and
116 simulates the processes related to the water and energy balance and snowpack
117 evolution. Recently, a new soil freezing module has been added to the model,
118 using the simple heat-conduction algorithm of Hayashi et al. (2007). SVS in-
119 cluding this new soil freezing scheme sets apart from other models commonly
120 used in percolation-related research, which do not account for snow and frozen
121 ground on their own and require evapotranspiration as input data and makes
122 it particularly appealing in cold climates. Previous works involving SVS have
123 mainly focused on surface energy and water balance simulations (Maheu et al.,
124 2018; Leonardini et al., 2020), and on SVS snowpack simulations (Leonardini
125 et al., 2021).

126 With this work, we aim to address the following research question: are land-
127 surface models (and in particular SVS) able to simulate percolation in a cold
128 climate where the soil undergoes seasonal freeze-thaw cycles? We hypothe-
129 size that SVS will be able to simulate percolation from our three experimental
130 plots, since it can account for the influential underlying processes, including
131 soil freezing. To provide a more stringent performance assessment, we do not
132 calibrate SVS using any field-measured data, which are typically unavailable
133 to modelers. Instead, we use an ensemble simulation approach, to account for
134 uncertainties related to meteorological input data, input parameters such as
135 soil hydraulic/thermal properties, and uncertainties related to the choice of the
136 lower-boundary condition of SVS that directly influences percolation simulation.
137 The work presented in this study is the first to evaluate the performance of SVS
138 regarding percolation simulations and soil hydrology in a cold climate. More-
139 over, it is the first study involving the newly developed soil-freezing module and
140 assessing its performance.

141 The remainder of this paper is structured as follows: In Section 3, we provide
 142 a brief description of the SVS land-surface model and the experimental setup. In
 143 Section 2 we present the case study, including a description of the experimental
 144 site and the available data. In Section 4, we present and discuss the results.
 145 Finally, in Section 5, we summarize the main findings of the study, discuss
 146 the implications and limitations of our work, and suggest directions for future
 147 research.

148 2. Case study

149 2.1. Experimental plots

150 Figure 1 shows the configuration of the three experimental plots (enclosures).
 151 The plots are constructed at the St-Nicéphore landfill site in Drummondville,
 152 Quebec (Canada), shown in Figure 2. These experimental plots are constructed
 153 as prospective landfill final covers where the main variable of interest is the
 154 percolation exiting through these covers into the waste layer.

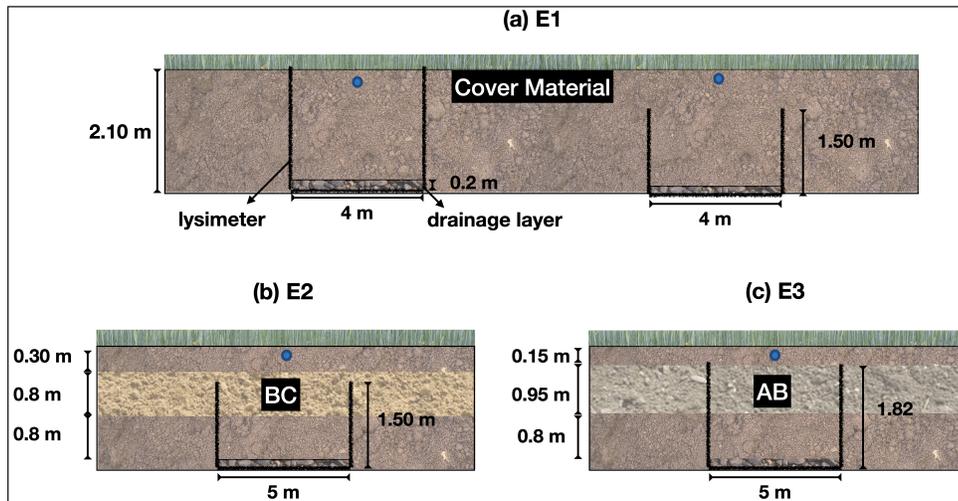


Figure 1: The different soil layers in the three experimental plots. The blue circles represent the soil moisture/temperature sensors placed at 7.5 cm depth.

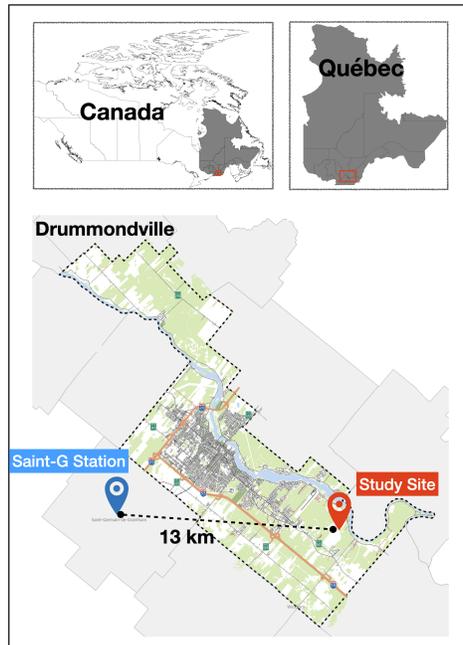


Figure 2: The location of the study site and the Saint-Germain de Grantham weather station on the map

155 The percolation from the bottom of these plots is collected using pan lysime-
156 ters and recorded hourly using tipping counters (100 ml for each tip) (Figure
157 3-a). Soil water content and soil temperature are also measured (half-hourly)
158 using dielectric sensors (5TM made by Decagon Devices Inc) depicted as blue
159 circles in Figure 1. These sensors are placed at a depth of 7.5 cm. The plots are
160 equipped with several more sensors and instruments (e.g. settlement plates),
161 not shown in the figures since they are not used in this study.

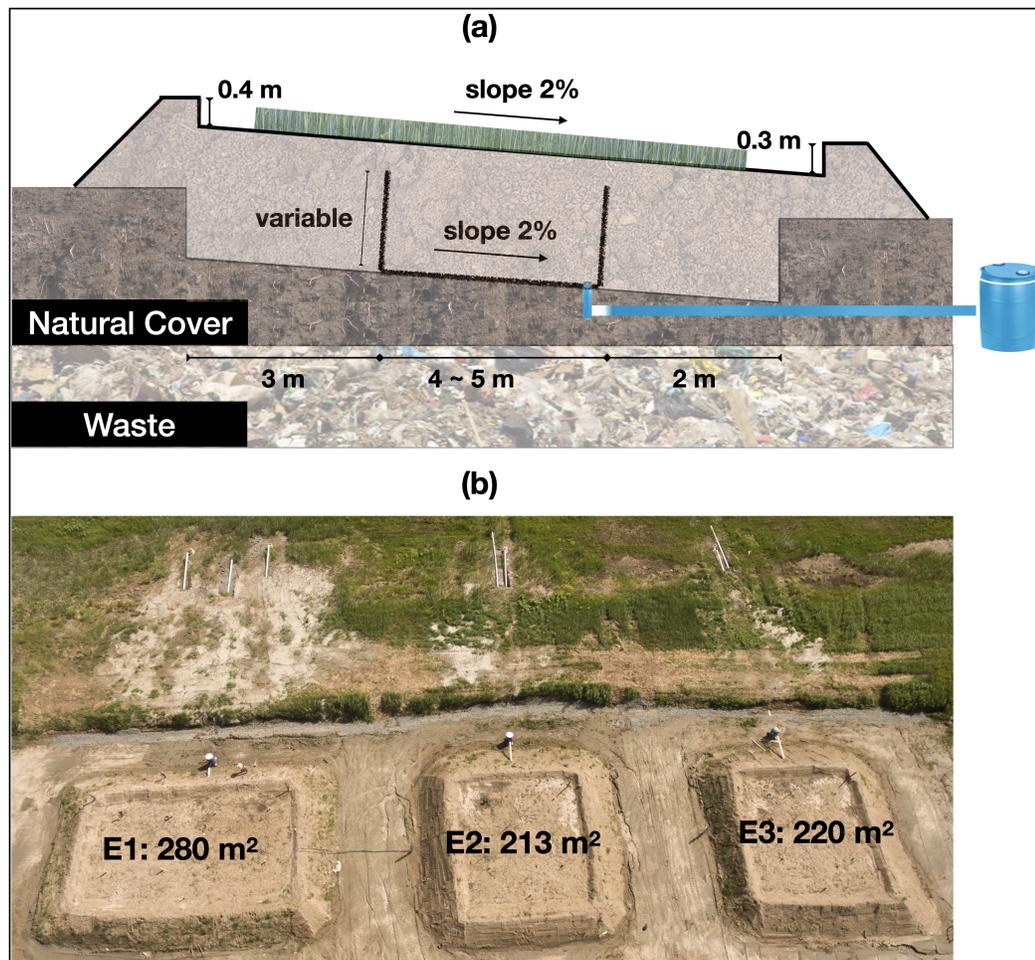


Figure 3: The cross-section view of the experimental plots (a) and the top-view of the plots in the site immediately after construction in the summer of 2018 (b)

162 Each experimental plot has a different configuration of soil layers. The E1
 163 plot 1-a contains exclusively typical cover material, a term adopted to refer to
 164 a type of soil, ranging from sandy to silty, commonly used as cover materials
 165 at St-Nicéphore landfill. The E2 plot 1-b includes a layer of BC soil and two
 166 layers of cover material, and E3 has a layer of AB soil between layers of cover
 167 material. BC and AB refer to the level of contamination according to the local
 168 legislation. At the bottom of each lysimeter, an identical 20-cm drainage layer

169 of sand and gravel is placed to facilitate the draining of the water from the
170 bottom of the lysimeters. Table 1 presents the laboratory-obtained parameters
171 for the aforementioned soils. Section 3.4 describes how these parameters were
172 measured in the laboratory.

173 2.2. Data

174 The long-term precipitation records for the study site (Drummondville) in-
175 dicate this location, on average, receives more than 1050 mm of precipitation
176 (snowfall + rainfall), including 227 cm of snowfall annually. Snow depth mea-
177 surements from 1982 to 2017 show that on average there are 109 days with more
178 than 3 cm of snow on the ground.

179 The meteorological forcing variables for SVS are obtained from the Saint-
180 Germain de Grantham (Saint-G) weather station (13 km from the study site, see
181 Figure 2), except for short-wave and long-wave radiation that is not measured
182 anywhere nearby. Radiation from the ERA5 reanalysis (Hersbach et al., 2020)
183 is used as a proxy. Specific humidity is estimated using dew point temperature
184 and atmospheric pressure. The Saint-Germain de Grantham station is equipped
185 with a double Alter Shield precipitation gauge and as suggested by Smith et al.
186 (2022) no wind-bias-adjustment is applied to the precipitation data.

187 The precipitation’s phase discrimination in SVS is done using a zero-degree
188 threshold. However, we overwrite this by using the formula proposed by Jen-
189 nings et al. (2018) which distinguishes between rainfall and snowfall using hu-
190 midity and air temperature, as in equation 1

$$P_{snow} = \frac{1}{[1 + \exp(c_1 + (c_2 T_a) + (c_3 R_h))]} \quad (1)$$

191 where T_a is air temperature ($^{\circ}\text{C}$), R_h is the relative humidity (%), and
192 c_1, c_2, c_3 are empirical coefficients which are equal to -10.04, 1.41, 0.09, respec-
193 tively. Precipitation is recognized as snow if P_{snow} is greater than 0.5, and rain
194 otherwise.

Table 1: The laboratory-obtained properties of the soil layers inside the experimental plots

Soil	Soil Parameters								
	Sand (%)	Clay (%)	W_{sat} (m^3/m^3)	W_{fc} (m^3/m^3)	W_{wilt} (m^3/m^3)	K_{sat} (m/s)	ρ_d (g/cm^3)	ψ_a (kPa)	b (-)
Cover material	55-78	5-12	0.29-0.33	0.05-0.09	0.02-0.06	7×10^{-6} - 5.4×10^{-5}	1.46-1.69	0.26	3.9
BC	84	3	0.31	0.17	0.15	4.4×10^{-6} - 4.9×10^{-5}	1.55-1.72	0.35	7.8
AB	26	10	0.28	0.20	0.17	4×10^{-7} - 4.6×10^{-6}	1.54-1.64	0.33	11.6

195 **3. Methods**

196 *3.1. SVS land-surface model*

197 The SVS land-surface model is developed and is actively maintained by
198 ECCC (Alavi et al., 2016; Husain et al., 2016; Leonardini et al., 2021). It
199 requires seven hourly meteorological variables as input data, including air tem-
200 perature, short- and long-wave radiation, wind speed, specific humidity, atmo-
201 spheric pressure, and precipitation. To start SVS under snow-free conditions,
202 initial values for soil volumetric water content and soil temperature must be
203 provided for each defined soil layer. By default, SVS estimates soil hydraulic
204 and thermal properties using pedo-transfer functions based on the percentage
205 of sand and clay in each layer. Therefore, these two parameters are the only
206 ones that are required to fully describe the soil column in SVS.

207 Each grid cell in SVS can be divided into four tiling components: 1) bare
208 ground, 2) low/high vegetation, 3) snow over bare ground and low vegetation,
209 and 4) snow under high vegetation. For each of these four components, SVS
210 uses the force-restore approach (Bhumralkar, 1975; Blackadar, 1976) to calcu-
211 late the energy budget. SVS uses a one-layer approach for the snowpack and
212 the vegetation canopy. A detailed description of the SVS snow component is
213 presented in Leonardini et al. (2021).

214 Within the soil column, the vertical movement of water is governed by
215 Richards equation for unsaturated flow, solved by a finite difference scheme
216 (Verseghy, 1991). In SVS, the soil water retention curve (SWRC) and verti-
217 cal hydraulic conductivity (K_v) are modeled using the following two equations
218 (Clapp & Hornberger, 1978):

$$\psi(z, t) = \psi_a \left[\frac{\omega(z, t)}{\omega_{sat}} \right]^{-b} \quad (2)$$

219 and

$$K_v(z, t) = K_{v,sat} \left[\frac{\omega(z, t)}{\omega_{sat}} \right]^{2b+3} \quad (3)$$

220 where ψ (kPa) is soil suction, ω_{sat} is the saturated soil volumetric water
221 content, and $K_{v,sat}$ is the saturated vertical hydraulic conductivity of the soil.
222 In equations 2 and 3, b and ψ_a are empirical (fitting) parameters related to the
223 slope of the SWRC and air-entry value suction of the soil, respectively.

224 In SVS, by default, percolation at the bottom of the last soil layer is cal-
225 culated only when the soil volumetric water content is larger than the water
226 content at field capacity. We refer to this parameter as ω_{trig} . Furthermore, the
227 calculation of surface runoff in the model is based on the saturated fraction of
228 the surface and is generated when either the precipitation rate is larger than
229 the first layer's $K_{v,sat}$ or when soil moisture exceeds saturation.

230 The default version of SVS does not simulate soil freezing and thawing and
231 its impact on infiltration and percolation (Alavi et al., 2016). To overcome
232 this limitation, a simple soil freezing scheme has been implemented in SVS. It
233 relies on the simple heat-conduction algorithm of Hayashi et al. (2007) and is
234 described in detail in Appendix A.

235 *3.2. Experiment design*

236 *3.2.1. Research question*

237 Our research question is **are land-surface models (and in particular**
238 **SVS) able to simulate percolation in a cold climate where the soil un-**
239 **dergoes seasonal freeze-thaw cycles?** To address this question, 200-member
240 ensembles are created for each plot to account for uncertainties in the model's
241 meteorological input data, input parameters related to soil hydraulic properties,
242 and lower boundary condition related to the simulation of percolation.

243 The construction of experimental plots was concluded in the summer of 2018,
244 however, the field data (i.e. percolation + soil moisture/temperature) for the
245 first year after the construction is not used in the analysis due to the impacts of
246 experimental plot stabilization. Meteorological data for this period, July 2018
247 to July 2019, is used for model warm-up. The model evaluation period spans
248 from July 2019 to the end of June 2021. The vertical discretization of the soil
249 column inside SVS is identical for the three plots and is as follows: the first and

250 last 15 cm of the 190 cm long soil column is divided into layers of 2.5 cm, the
251 rest of the soil column is divided into layers with 5 cm depth (total of 44 layers
252 for each soil column).

253 3.2.2. Constructing the ensembles

254 To represent the uncertainty related to the model’s input parameters, a
255 sampling interval is considered for the parameters in Table 1 for which there
256 are several laboratory-estimated values. The interval is the same as the range
257 presented in the table for each parameter.

258 The interval for ω_{trig} is defined as a multiplier from 0.5 to 0.99 of ω_{sat} of the
259 corresponding soil layer, which we argue is a reasonable range considering the
260 capillary effect present at the interface between the soil covers and the drainage
261 layer (made of sand and gravel). To ensure a more evenly distributed sample,
262 we use Latin hypercube sampling (Loh, 1996) to create the ensemble members
263 rather than random sampling.

264 The ensemble of meteorological data is constructed by applying a random
265 perturbation to the variables and following the approach proposed by Charrois
266 et al. (2016), which ensures physically consistent temporal variations for the
267 data. According to this approach, a first-order autoregressive model, 4, is used
268 to compute the random perturbation for each variable (Deodatis & Shinozuka,
269 1988).

$$P_t = \phi P_{t-1} + \epsilon_t \quad (4)$$

270 In Eq. 4 P_t is the perturbation value at time t , ϕ is the parameter for
271 the autoregressive model, and ϵ is a white noise process with zero mean and
272 σ^2 variance. ϕ is obtained by fitting an AR(1) model to the time series of
273 each variable and variance σ^2 is computed using the standard deviation of the
274 residuals between the variables from the Saint-Germain de Grantham station
275 and the corresponding variable from the field stations (average of three stations)
276 following Eq. 5.

$$\sigma^2 = \sigma_{res}(1 - \phi^2) \quad (5)$$

277 An additive perturbation is applied to air temperature, dew temperature,
 278 and atmospheric pressure. A multiplicative perturbation is applied to short-
 279 wave radiation, wind speed, and relative humidity Charrois et al. (2016). The
 280 multiplicative perturbation is limited to [0.8, 1.2] to avoid extreme values.

281 Concerning longwave radiation, as there is no field measurement available, no
 282 perturbation is applied. Precipitation data is perturbed according to the World
 283 Meteorological Organization’s recommended range of uncertainty for rainfall
 284 measurements taken by automatic tipping-counter rain gauges, which is $\pm 5\%$
 285 (Lanza et al., 2005; Colli et al., 2013). The phase of precipitation is computed
 286 following the perturbation of air temperature and relative humidity data.

287 3.3. Performance assessment metrics

288 The performance of the ensembles regarding different hydrological variables,
 289 namely the soil moisture/temperature, snow depth, and percolation, is evaluated
 290 using the Continuous Ranked Probability Score (CRPS) (Bröcker & Smith,
 291 2007). The CRPS is a widely-used metric that penalizes the over or under-
 292 dispersion and bias in ensemble simulations (Clark, 2017); a low CRPS denotes
 293 better simulations, and perfect simulations would have a score of zero. The
 294 *ensverif* Python library: <https://pypi.org/project/ensverif/> is used to
 295 calculate the CRPS.

296 We use the Continuous Ranked Probability Skill Score (CRPSS) to compare
 297 the simulations produced by SVS to a benchmark. The CRPSS is calculated
 298 using Eq. 6. A positive CRPSS indicates that SVS performs better than the
 299 benchmark, a negative value means that it performs worse, and a CRPSS of
 300 zero indicates that there is no difference in performance between the two. A
 301 CRPSS of 1 signifies a perfect simulation.

$$CRPSS = 1 - \frac{CRPS_{svs}}{CRPS_{bench}} \quad (6)$$

302 To have realistic and competitive benchmarks, we linearly varied the ob-
303 served values between $\bar{y}_{obs} - \frac{s_{obs}}{4}$ and $\bar{y}_{obs} + \frac{s_{obs}}{4}$ and assigned each of them to
304 an ensemble member (200 total). Here, \bar{y}_{obs} is the average value for the obser-
305 vations of the hydrological variable, and s_{obs} is the standard deviation of the
306 observations.

307 We also use R^2 (square of Pearson’s correlation coefficient) and mean-bias-
308 error (MBE) to assess the performance of the ensemble average regarding the
309 variables of interest. MBE is calculated by subtracting the observations from
310 simulated values.

311 3.4. Laboratory methods

312 The soil water content at saturation, field capacity, and the wilting point are
313 obtained by conducting the HYPROP (HYdraulic PROPerity analyzer, Schindler
314 & Müller, 2017; Schindler et al., 2015) technique (METER Group, Inc.). This
315 technique involves measuring the pressure head, against time, at two different
316 depths within a 5-cm soil column. This is done while the water evaporates from
317 the surface. Fluxes and water contents are determined by continuous weighing
318 of the column. In the end, the measurements for pressure head, water content,
319 and evaporation fluxes are used to obtain the water retention curve which is a
320 graph that shows the relationship between the soil’s water content and the soil
321 suction (Bezerra-Coelho et al., 2018).

322 Based on the HYPROP results, the soil volumetric water content at field
323 capacity (ω_{fc}) for the different types of soils is estimated to be the soil water
324 content corresponding to the 33 kPa suction. The b coefficient and ψ_a in Eq. 2
325 are obtained by fitting the equation to water content and suction measurements
326 that have been obtained using the HYPROP technique. This is done using
327 a mathematical optimization algorithm called the Levenberg-Marquardt algo-
328 rithm, which adjusts the parameters to find the best fit between the equation
329 and the measurements.

330 The saturated hydraulic conductivity (K_{sat}) was estimated using the KSAT
331 (METER Group, Inc.) device, which automatically measures K_{sat} of saturated

332 soil samples based on Darcy’s equation. In this test, a fully saturated soil sample
333 is percolated with degassed water at room temperature, perpendicular to the
334 sample’s cross-section. During the percolation, the flow rate and hydraulic
335 gradient are measured. K_{sat} ($m.s^{-1}$) is then calculated using Darcy’s equation:

$$K_{sat} = \frac{LV}{\Delta H A \Delta T} \quad (7)$$

336 where ΔT is the length of the time interval (s), V is the volume of water
337 passed through the sample (m^3), L is the length of the soil sample (m), A is the
338 soil sample cross-sectional area (m^2), and ΔH is the hydraulic head gradient
339 along the flow direction (m).

340 4. Results and discussion

341 Figure 4 presents the CRPSS, CRPS, MBE, and R^2 values obtained by
342 SVS (2019-07-01 to 2021-06-30) for the ensemble simulation of daily averaged
343 surface soil moisture/temperature and daily percolation volumes for the three
344 experimental plots. For the E1 experimental plot, the metrics values represent
345 the mean calculated from two separate sets of observations for each variable.

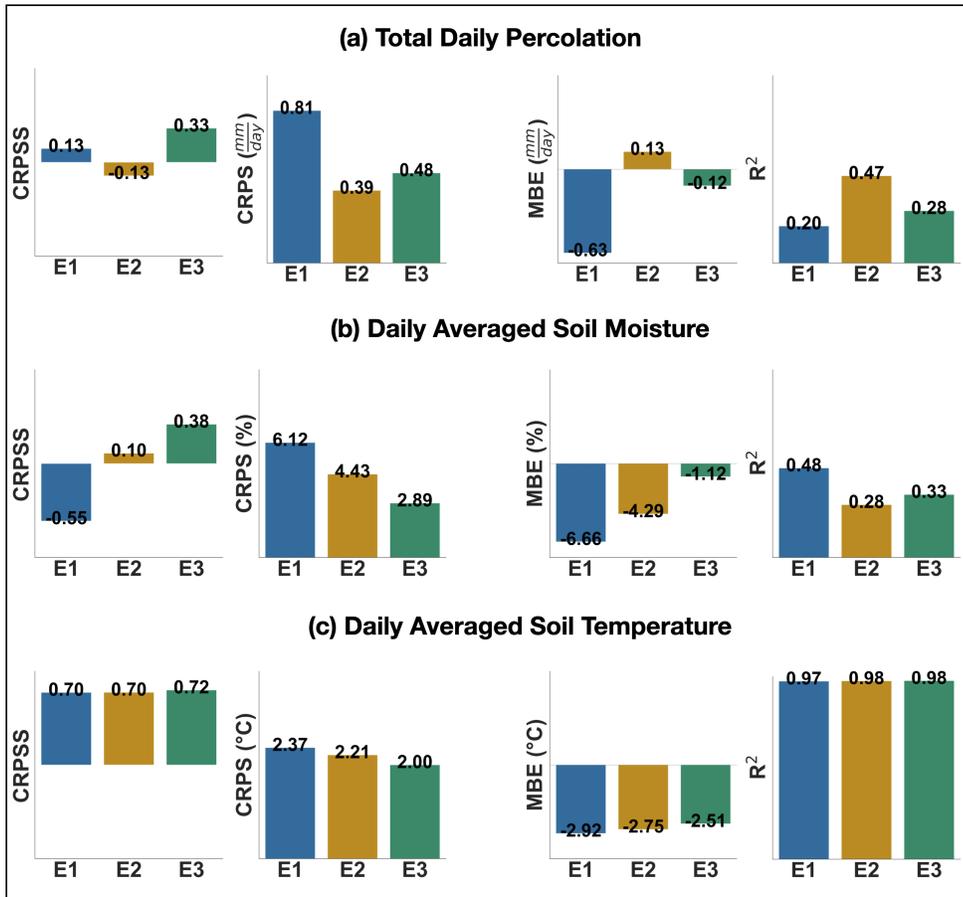


Figure 4: Performance assessment metrics for assessing the performance of SVS ensemble simulation (CRPS and CRPSS) and ensemble mean (MBE and R^2) concerning the experimental plots and soil moisture/temperature (7.5 cm) and percolation. There are two independent measurements available for E1.

346 In the following subsections, we further analyze the performance of SVS for
 347 the simulation of snow, soil temperature and soil moisture, and percolation. To
 348 gain insight into the general quality and realism of the model, its performance
 349 regarding the simulation of snow cover and soil freezing is assessed before as-
 350 sessing the quality of the simulation for percolation.

351 *4.1. Snow simulation*

352 Figure 5 shows the comparison between the snow depth measured by the
353 Saint-Germain de Grantham weather station (blue line) and the values sim-
354 ulated by SVS (in orange) for two consecutive winters (Nov-May). The blue
355 triangles represent manual on-site snow depth measurements. Each point rep-
356 resents the average of 10 samples taken on a specific day. These measurements
357 are indicative of the similarity between the snow depth at the Saint-Germain
358 de Grantham station and the actual snow cover on site.

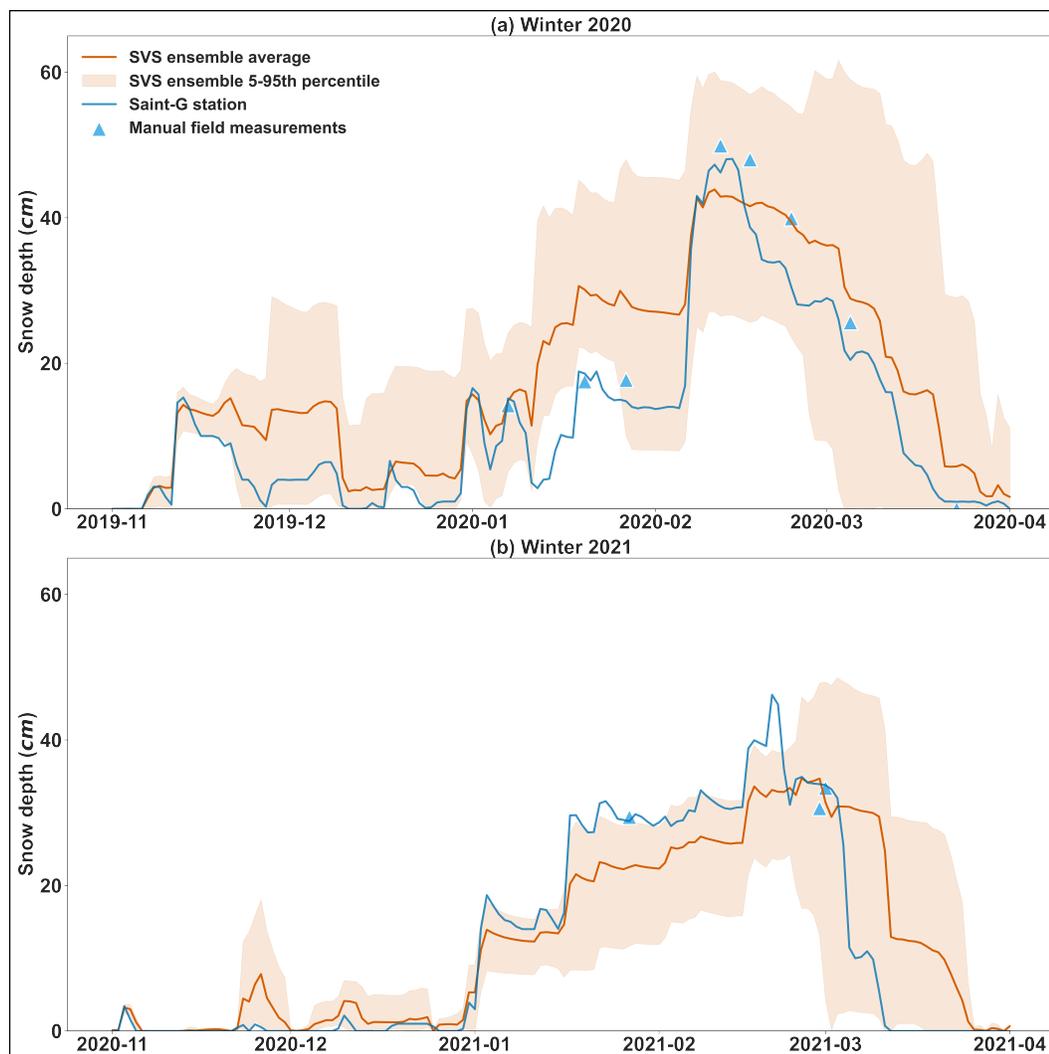


Figure 5: Snow depth values measured by the Saint-Germain de Grantham weather station (blue line) and simulated by the SVS model (shown in orange as the ensemble mean and 5-95th interpercentile range) for a) the winter of 2020 and b) the winter of 2021. The triangles are on-site manual snow measurements.

359 The simulated snow accumulation and melt during the two winter periods
 360 are generally consistent with the observations and SVS performs well in this
 361 regard, which is reflected by a CRPSS of 0.67 and R^2 of 0.82 (average over

362 two winters). The ensemble simulation can be considered reliable since the
363 observed snow depth measurements reside within the ensemble for most of the
364 two winters, denoting that ensemble simulations are successful at capturing the
365 uncertainty associated with the snow melt and accumulation process.

366 The good performance of SVS in the simulation of snow cover is vital for sim-
367 ulating snowmelt events in the spring, which can result in significant percolation
368 volumes. However, the model's ability to simulate the resulting percolation is
369 largely dependent on its simulation of the soil freeze-thaw cycle, as soil freezing
370 impacts the infiltration capacity of the soil. SVS's performance in simulating
371 near-surface soil temperature will be discussed in the following section.

372 *4.2. Soil temperature at 7.5 cm*

373 Figure 6 shows the simulated soil temperature values from SVS (in red) and
374 the temperature values recorded by sensors at a depth of 7.5 cm within the plots
375 (shown in light/dark blue).

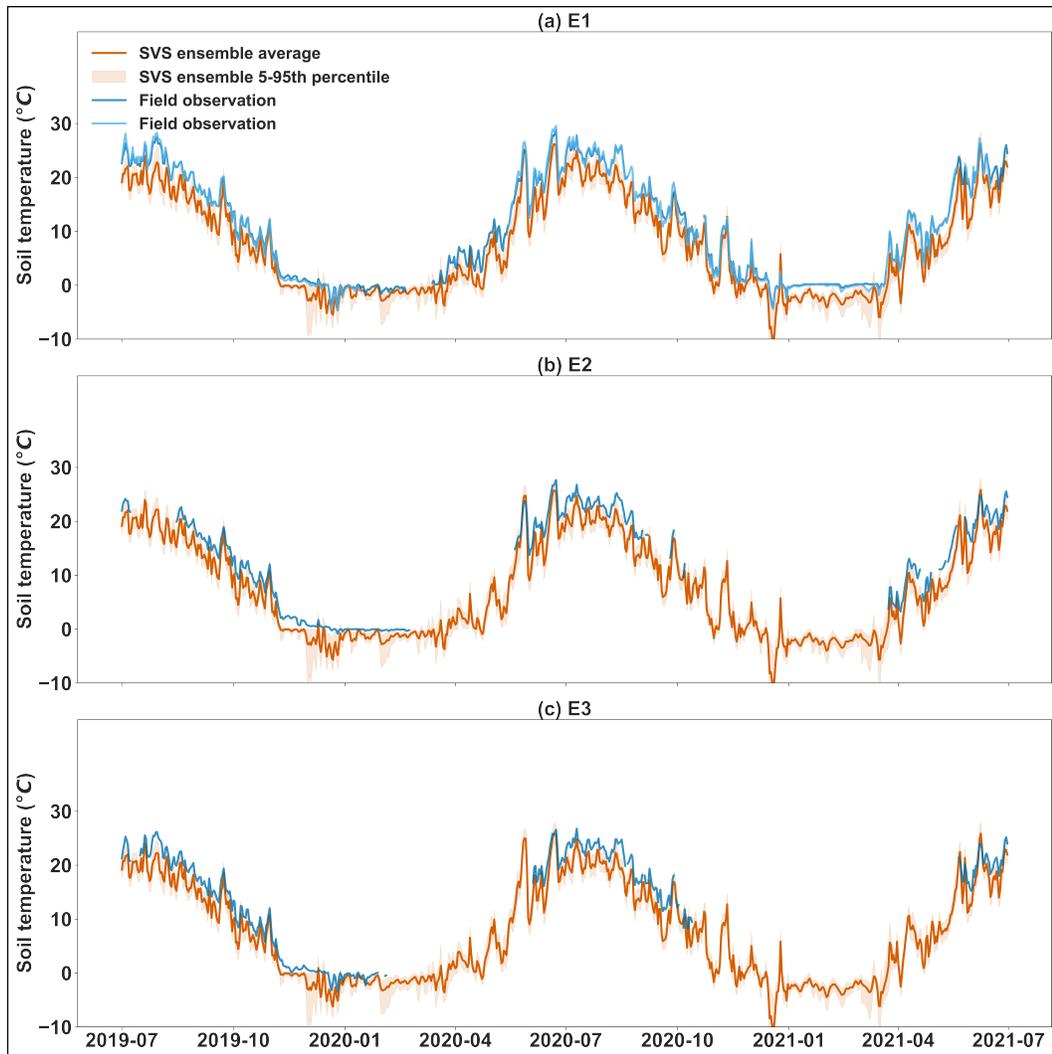


Figure 6: Daily averaged soil temperature simulation by SVS (in orange, with the ensemble mean and the 5-95th percentile range) and temperature values from a sensor (in light/dark blue) placed at 7.5 cm depth of the (a) E1, (b) E2, (c) E3 plots. Two sensors were placed inside the E1 plot

376 Figure 6 shows that SVS simulates the near-surface soil temperature rea-
 377asonably well, for all plots and throughout the year. As shown in Figure 4, the
 378ensemble has a CRPSS of around 0.70, and the ensemble average has R^2 of

379 about 0.98 for all three plots, indicating a strong agreement between the sim-
380 ulation and observations. This demonstrates the model’s ability to effectively
381 capture the seasonal dynamics of near-surface soil temperature. The similarity
382 of values for the evaluation metrics between all plots is because the near-surface
383 soil is the same for all plots, i.e. cover material (Table 1).

384 The MBE values for the ensemble mean are -2.92, -2.75, and -2.51 °C for
385 the E1, E2, and E3 plots respectively. These values indicate that SVS tends to
386 underestimate near-surface soil temperature. The underestimation issue is more
387 pronounced at a few specific periods, for instance, Dec-2020, Dec-2021, and Mar-
388 2021, as shown in Figure 6, where most or all ensemble members significantly
389 underestimate soil temperature (or overestimate frost depth).

390 Figure 6 also shows that the ensemble has a low spread, especially for non-
391 freezing temperatures. On one hand, this can indicate a robust performance by
392 SVS which exhibits low sensitivity to the perturbation concerning input data
393 and parameters (see Section 3.2.2) in the simulation of near-surface soil temper-
394 ature. On the other hand, this can indicate an overconfident ensemble, leading
395 to the underestimation of underlying uncertainty affecting the soil temperature.
396 The latter point might be related to the fact that the uncertainty concerning the
397 soil thermal parameters, such as soil (solid and dry) thermal conductivity, is not
398 directly explored in the construction of the ensemble. In the ensemble, the per-
399 turbation of soil sand/clay content, porosity, and dry density is responsible for
400 variations in the thermal properties of the soils, as SVS uses those parameters
401 to estimate soil thermal conductivity.

402 It is also important to determine how well the model simulates the onset,
403 duration, and end of soil freezing, with particular emphasis on the latter, which
404 often coincides with the melting of accumulated snow and is a major hydrological
405 event in areas with significant snow accumulation (Iwata et al., 2010). For the
406 analysis, we only use data from one of the sensors inside the E1 plot, the dark
407 blue line in Figure 6-a, since it is the source of soil temperature observations
408 for which we have the fewest number of missing values for both winters. We
409 compare the observations with the ensemble mean. It is reasonable to assume

410 that the analysis would be very similar for E2 and E3 since their near-surface
411 soil has the same type as E1 (i.e. cover material).

412 During the first winter (2019-11-01 to 2020-04-01), there are 132 days with
413 observations, with a daily-averaged observed soil temperature of 0.55 °C. The
414 simulated average soil temperature is -1.06. For this period, the soil at a depth
415 of 7.5 cm is frozen for 60 days, whereas for the ensemble mean (simulations), this
416 number is 113. The freezing period starts on 2019-12-13 according to the sensor,
417 while according to the simulations, it begins more than one month earlier, on
418 2019-11-09. It is difficult to compare the end date of the freezing period between
419 observations and simulations, as the period between 2020-02-21 and 2020-03-12
420 is missing from the observations. Nevertheless, the observations from 2020-03-
421 12 onward show positive values, while the average freezing period according to
422 the simulations ends on 2020-03-25.

423 During the second winter (2020-11-01 to 2021-04-01), there are 151 days of
424 available observations, with a daily averaged observed soil temperature of 1.42
425 °C, compared to -1.05 °C for the simulations. The observation record shows
426 that there are only 37 days where the soil is frozen at 7.5 cm. The simulation
427 shows a significantly larger number, with a total of 113 days where the soil is
428 frozen. The first subzero day according to the simulations is on 2020-11-01,
429 while for the observations it is on 2020-12-16. The last frozen day according to
430 the simulation is on 2021-03-22, while for the observations it is on 2021-03-17.

431 Examining the simulated snow depth values for the ensemble median sug-
432 gests that the severe underestimation of surface soil temperature occurs when
433 there is little to no simulated snow cover. Snow cover acts as an insulator for
434 the underlying soil and is inversely related to frost depth, an effect considered
435 in the calculation of surface layer heat flux in SVS (Appendix A). The Saint-
436 Germain de Grantham weather station’s snow depth measurements also show
437 little or no snow cover during these periods, indicating that the underestimation
438 of soil temperature is unlikely caused by an underestimation of snow cover in
439 the model.

440 This suggests that the soil freezing module of SVS may not perform well in

441 simulating soil temperature for snow-free situations and air temperatures below
442 the freezing point. This may be associated with the fact that the soil freezing
443 scheme is used as an upper boundary condition for the surface temperature from
444 the force restore scheme implemented in SVS Husain et al. (2016).

445 This scheme neglects the effects of soil freezing and thawing (latent heat
446 release) on its prognostic temperature variables. Boone et al. (2000) have shown
447 how the inclusion of these effects in a force restore scheme can improve the
448 simulation of soil temperature when the soil freezes. Neglecting this effect in
449 SVS may lead to an underestimation of the surface soil temperature during the
450 fall in snow-free conditions affecting the ground heat flux used as the upper
451 boundary conditions for the soil freezing scheme and ultimately generating an
452 overestimation of the frost depth. In addition, the soil freezing dynamic in the
453 fall depends on the liquid water content in the soil at that period (Zhao et al.,
454 1997; Kurylyk & Watanabe, 2013).

455 The next section we will specifically focus on assessing the accuracy and
456 reliability of SVS's soil moisture simulation, which is equally important for
457 understanding hydrological processes in snow-dominated areas.

458 *4.3. Soil moisture at 7.5 cm*

459 The accuracy of a model's simulated overland flow can often be assessed
460 by examining its simulated near-surface soil moisture, which can provide an
461 indirect way to evaluate the model's performance in cases where there are no
462 direct measurements of overland flow available. Figure 7 displays the simulated
463 soil moisture values from SVS (in orange) and the moisture values recorded by
464 sensors at a depth of 7.5 cm within the experimental plots in (dark/light) blue.

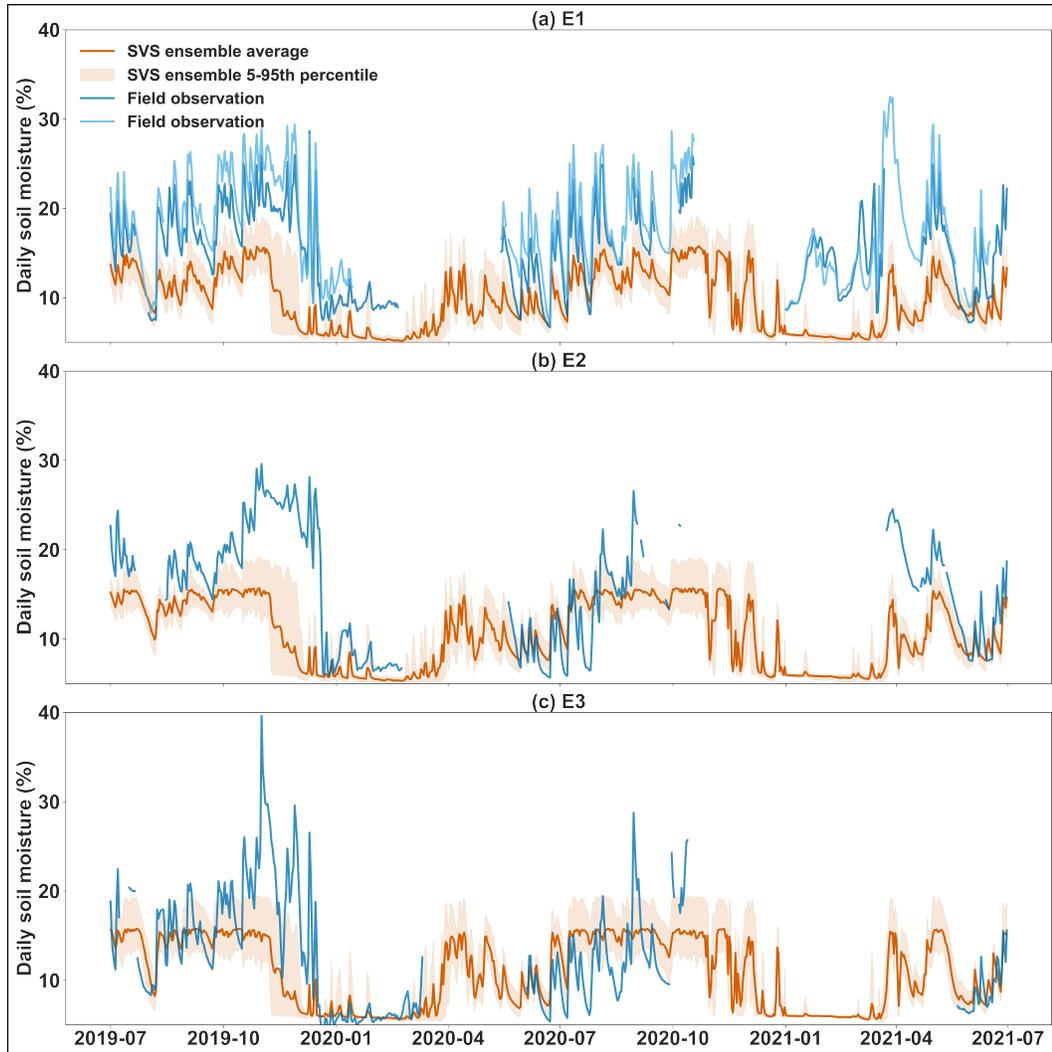


Figure 7: Daily averaged soil moisture simulation by SVS (in orange, with the ensemble mean and the 5-95th percentile range) and moisture values from sensors (in light/dark blue) placed at 7.5 cm depth of the (a) E1, (b) E2, (c) E3 plots. Two sensors were placed inside the E1 plot.

465 Concerning the E1 experimental plot, Figure 7-a shows that SVS is con-
 466 sistentlly underestimating (i.e. negative bias) soil moisture at 7.5 cm, which is
 467 more conspicuous after snowmelt events, for instance in Nov 2019, Dec 2019,

468 and Mar 2021 (see Figure 5). The mean-bias-error (MBE, simulation - obser-
469 vation) between the ensemble mean and the two sensors are -5.5 % and -7.83
470 %.

471 The negative bias is very likely the reason why SVS has negative CRPSS
472 values, -0.37 and -0.73 concerning the first and second moisture sensors, which
473 means it performs worse than the simple benchmark. This is in turn due to
474 the low reliability of the ensemble. The lack of reliability in the ensemble is
475 primarily attributed to its inability to consistently encompass the observations
476 within its range for the majority of the time steps. Using the decomposition
477 proposed by Hersbach (2000), the total CRPS of 7.2 % for SVS (concerning the
478 second sensor) can be decomposed into reliability and potential components of
479 7.07 % and 0.13 % respectively. This demonstrates the fact that most of the
480 total CRPS is due to the low reliability of the ensemble.

481 Results shown in Figure 7 highlight an underestimation of the soil liquid
482 water content in the fall that can partially explain why the soil freezes too
483 quickly in SVS. It is also possible that the issue may be exacerbated due to
484 the uncertainty present in the radiation data used to drive SVS, which directly
485 affects the soil heat transfer calculations (the shortwave and longwave radiation
486 data are obtained from the ERA5 dataset as long-term direct observations are
487 not available). Such bias in the radiation forcing may explain why the soil
488 temperature is also underestimated during the warm period.

489 The weak performance of the ensemble simulation, as measured by the
490 CRPSS, can be partially attributed to a large discrepancy between the laboratory-
491 obtained ω_{sat} of the near-surface soil, cover material, and the actual values de-
492 duced from analyzing half-hourly moisture measurements. The largest value
493 obtained in the laboratory is 33 % (see Table 1), while the two sensors inside
494 the E1 plot have recorded values around 38%. This means the actual ω_{sat} (and
495 porosity) of cover material used inside E1 can be at least 15 % larger than the
496 laboratory-obtained value. Since cover material is used for the near-surface soil
497 of all of the plots, we should expect a similar discrepancy affecting the perfor-
498 mance of SVS concerning E2 and E3. In the case of E2, the moisture sensor has

499 recorded a value of 37 %, and the sensor placed inside E3 has recorded a value
500 of 44.9 % (a storm event in Aug 2020)

501 The above-mentioned issue might be related to the fact that all laboratory
502 tests of soil hydraulic parameters were conducted during the construction phase
503 of the experimental plots. After construction (summer of 2018), these plots con-
504 tinued to experience settlement as well as soil freeze-thaw cycles, and this can
505 significantly impact soil hydraulic properties, such as porosity and saturated hy-
506 draulic conductivity. This process is disruptive and is expected to increase these
507 properties through the expansion of water in soil pores (as it freezes into ice)
508 and rearrangement of soil particles (Rooney et al., 2022; Xu et al., 2021). The
509 resulting increased porosity leads to a larger area for water flow, contributing
510 to an expected increase in saturated hydraulic conductivity.

511 SVS’s overestimation of the soil freezing period (Section 4.2), which begins
512 earlier and lasts longer than suggested by the sensor data, could be another con-
513 tributing factor to its underestimation of soil moisture. During these extended
514 periods of simulated soil freezing, water infiltration would be reduced according
515 to simulations, potentially leading to lower modeled soil moisture levels, which
516 is more critical at the beginning of the spring and during snowmelt events.

517 Concerning the E2 and E3 plots, Figure 7-b, c, shows that, despite the afore-
518 mentioned discrepancy, SVS performs better than the benchmark simulation,
519 with CRPSS values of 0.10 and 0.38, respectively. This could be partially be-
520 cause the sensors inside E2 and E3 have missing values for most of the winter
521 and spring of 2021, a period when the performance of SVS degrades, in the case
522 of the E1 plot (see Figure 7-a).

523 Despite the negative CRPSS values for SVS regarding the E1 plot, Figure
524 7-a demonstrates that SVS adequately captures the overall seasonal and sub-
525 seasonal variations in near-surface soil moisture. This trend is similarly observed
526 for the E2 and E3 plots (Figure 7-b, c). In the case of E1, this is also evident
527 in the R^2 values of around 0.48, which is moderately high considering the fact
528 that R^2 between the two adjacent soil moisture sensors inside E1 (within a
529 few meters) is 0.85. This demonstrates the inherent variability and uncertainty

530 in the observed soil moisture measurements themselves, a consideration that
531 affects the assessment of the model's performance.

532 In the next section, we examine the model's performance in simulating per-
533 colation, which is our ultimate goal.

534 *4.4. Daily percolation*

535 Figure 8 shows the simulated volumes of daily percolation (in orange) and
536 the percolation volumes collected by the pan lysimeters at the bottom of the
537 experimental plots (in light/dark blue).

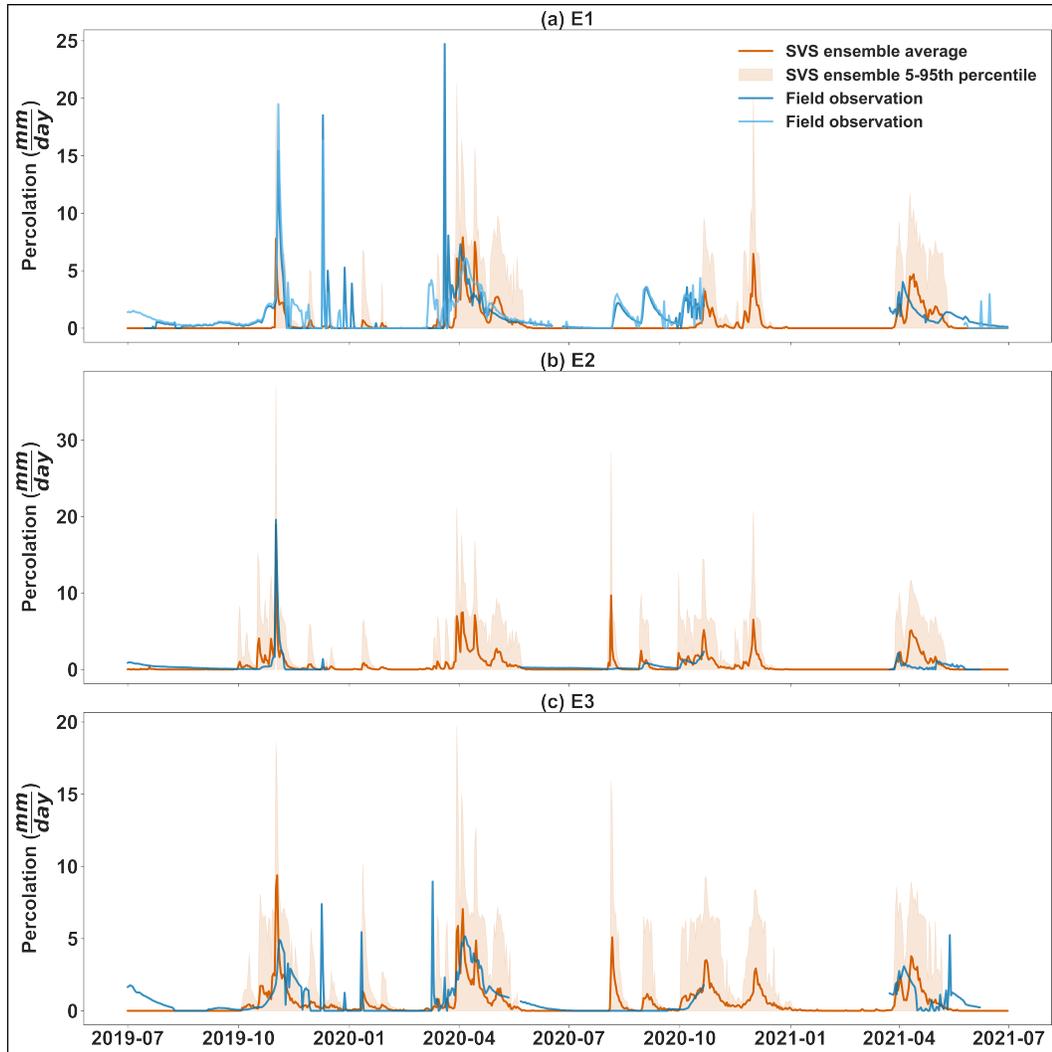


Figure 8: Total volume of daily percolation simulated by SVS (in orange, with the ensemble mean and the 5-95th percentile range) and the measured quantities from the lysimeters (light/dark blue) situated at the bottom of the (a) E1, (b) E2, and (c) E3 plots. Two lysimeters were placed inside the E1 plot.

538 There are periods when measurements are not available due to issues with
 539 data loggers and drainage pipes. However, it is still possible to compare the
 540 simulated percolation volumes from SVS with the measured values. Figure 8

541 shows that most percolation is collected in spring after the snow melts or in fall.

542 In winter, the surface soil freezes, as indicated by sensors placed at 7.5 cm
543 recording subzero temperatures, thereby reducing the amount of percolation
544 collected from the experimental plots due to limited water infiltration. Data on
545 percolation and near-surface soil temperature for the experimental plots from
546 2019-07 to 2021-07 reveals that, on average, only 2 % of the total percolation
547 volume was collected during frozen periods. This underlines the necessity for
548 accurate simulation of soil freeze-thaw cycles. Factors such as the reduced infil-
549 tration capacity of frozen ground (Heinze, 2021), the contraction of pore space
550 and decrease in unsaturated hydraulic conductivity due to frozen trapped pore
551 water, and the inverse correlation between water temperature and its dynamic
552 viscosity, can partially account for the observed effect.

553 As shown in Figure 8, the percolation during fall is significantly higher than
554 in summer, despite the average monthly total rainfall being roughly the same
555 throughout both seasons (Jun to Nov, with an average of 94 mm per month).
556 This may be attributed to evapotranspiration loss in summer (June to August),
557 which can account for 65% of the total annual evapotranspiration on average in
558 Canada, while the loss in the colder months (including October and November)
559 can be less than 10 mm per month Wang et al. (2013).

560 The seasonality of percolation at the study location suggests that missing
561 data in the fall or spring likely include significant percolation. For instance, the
562 first period of missing data in the E2 experimental plot (Figure 8-c) includes
563 spring 2020, when large volumes of percolation occurred in the other experi-
564 mental plots. It is reasonable to assume that similar percolation events also
565 occurred in the E2 plot.

566 Figure 8 shows that SVS accurately matches the timing of major percola-
567 tion events. In addition, the simulation accurately shows little or no percolation
568 during winter and summer, consistent with observed patterns of percolation at
569 the study location. However, Figure 8-a shows the model does not simulate per-
570 colation at all for two significant rainfall events in Aug 2020, which is collected
571 by the lysimeter inside E1. While this highlights the need for further refinement

572 of the SVS model, overall it demonstrates its ability to capture the seasonal and
573 sub-seasonal patterns of percolation dynamics in the study area.

574 The CRPSS values for percolation from the plots, shown in Figure 4, are 0.13,
575 -0.13, and 0.33. According to these values, SVS has acceptable performance
576 for E1 and E3, while it performs worse than the benchmark for the E2 plot.
577 However, this poor performance must be considered in light of the fact that
578 major percolation volumes were not recorded in the spring of 2020 for the E2
579 plot, where SVS has simulated a significant amount of percolation.

580 The R^2 between the ensemble average and the daily percolation collected
581 by the two lysimeters inside E1 is 0.15 and 0.24. Considering the fact that
582 R^2 between the collected percolation by these two lysimeters is 0.56, it would
583 not be unreasonable to consider the model's performance moderately successful.
584 Concerning the E2 and E3 plots, the R^2 values are 0.46 and 0.28, which indicates
585 the simulated percolation has a considerably higher correlation with observed
586 values, compared to the case of E1. Assuming the same inherent variability for
587 percolation from E2 and E3, as demonstrated by the fact that R^2 between two
588 adjacent lysimeters can be as low as 0.56, we can argue that SVS has a good
589 performance concerning E2 and E3, in terms of correlation.

590 Figure 8 shows that, for all plots, there is a large variability in the timing of
591 the simulated percolation between the members of each ensemble. It is highly
592 likely that the main source of variation in this regard is the wide sampling
593 space for the ω_{trig} parameter, which is 50-99 % of ω_{sat} of cover material. This
594 suggests that further refinement of the sampling space could potentially improve
595 the performance of the ensemble simulations.

596 **5. Conclusion**

597 Reliable estimation of percolation is crucial for various applications, includ-
598 ing landfill engineering, irrigation management, and groundwater management.
599 Land-surface models offer a valuable tool for simulating percolation and en-
600 hancing our understanding of the complex interactions between soil properties,

601 hydrological processes, and environmental factors.

602 We evaluate the ability of the SVS land-surface model to simulate percolation
603 from the bottom of three experimental plots (soil covers) equipped with pan
604 lysimeters, soil moisture, and temperature sensors. These plots are constructed
605 at a landfill site in the vicinity of Drummondville, Quebec (Canada), with a
606 warm-summer humid continental climate. The site receives a significant amount
607 of snowfall during the cold months (Nov-Apr) and undergoes seasonal soil freeze-
608 thaw cycles. This presents an opportunity to assess the performance of the newly
609 developed soil-freezing module of SVS.

610 The main research question is the following: **are land-surface models**
611 **(and in particular SVS) able to simulate percolation in a cold cli-**
612 **mate where the soil undergoes seasonal freeze-thaw cycles?** To address
613 this, 200-member ensemble simulations are created for each plot, considering
614 uncertainties in meteorological input data, soil hydraulic properties, and lower
615 boundary condition associated with percolation simulations (i.e. trigger mois-
616 ture). The simulation period spans from July 2018 to June 2021 (inclusively),
617 with the first year used only for model warm-up.

618 To represent uncertainty in model input parameters, sampling intervals are
619 created (by considering the ranges presented in Table 1) for each parameter with
620 multiple laboratory-estimated values. For trigger moisture (ω_{trig}), an interval
621 ranging from 0.5 to 0.99 of the corresponding soil layer’s saturated water content
622 (ω_{sat}) is defined. Meteorological data ensembles are constructed by applying a
623 random perturbation to variables using a first-order autoregressive model (AR1)
624 for physically consistent temporal variations.

625 The results demonstrate the ability of the SVS model to capture the seasonal
626 and sub-seasonal patterns of percolation dynamics in the study area. The model
627 accurately matches the timing of major percolation events due to snowmelt in
628 spring and in fall and shows little or no percolation during winter and summer.
629 The CRPSS values for the E1 and E3 plots indicate an acceptable model per-
630 formance, while the performance for the E2 plot is worse than the benchmark.
631 The R^2 values between the ensemble average and the daily percolation show a

632 moderately successful to good model performance for the E1, E2, and E3 plots.
633 It is worth noting that the correlation in percolation data between two closely
634 located lysimeters is only around 0.56. This highlights the spatial variability
635 and complexity of percolation processes in the field.

636 While SVS shows promise in its ability to simulate percolation dynamics,
637 it also highlights certain shortcomings that need to be addressed. Specifically,
638 inaccuracies in simulating soil freezing and soil moisture potentially contribute
639 to percolation simulation errors. Overestimation of soil freezing duration by the
640 model impacts the accurate simulation of water infiltration, thereby leading to
641 an underestimation of soil moisture levels. An underestimation of soil mois-
642 ture can translate into a reduced simulation of percolation. This is particularly
643 consequential during critical periods of high infiltration such as snowmelt. Fur-
644 thermore, discrepancies between the laboratory measurements of soil hydraulic
645 parameters and their actual field values could also be contributing to the model's
646 underestimation of soil moisture, thus affecting the prediction of percolation.

647 SVS simulates near-surface soil temperature dynamics reasonably well with
648 CRPSS values of approximately 0.70 and R^2 values of approximately 0.98 for all
649 three plots. However, the model may underestimate near-surface soil tempera-
650 ture and has limitations in simulating soil temperature for snow-free situations
651 and air temperatures below the freezing point. There are large discrepancies
652 between the onset, duration, and end of simulated and observed soil freezing
653 periods, where SVS largely overestimates the duration of the freezing period.
654 These dynamics are critical in simulating percolation and overland flow due to
655 snowmelt events in spring. Therefore, further efforts are necessary to improve
656 the model's accuracy in simulating soil freezing periods and their impacts on
657 hydrological processes in snow-dominated regions.

658 Our findings underscore the SVS model's value and potential while empha-
659 sizing areas that require further improvement. Moving forward, future studies
660 could consider using multiple models for soil water retention curves which may
661 help account for uncertainty in the model's structure. Additionally, we can ex-
662 plore the applicability of the model to different geographical regions or climatic

663 conditions.

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671 **CONFLICT OF INTEREST STATEMENT**

672 The authors declare no conflicts of interest.

673 **DATA AVAILABILITY STATEMENT**

674 All the codes required to reproduce the ensemble simulations, the evalua-
675 tions, and figures, along with the SVS source code, are hosted at the following
676 GitHub repository: https://github.com/Alireza-Amani/SVS_percolation.
677 The datasets presented in this study are publicly available in the Zenodo repos-
678 itory and can be accessed at Cabral (2023). The repository contains daily
679 percolation volumes and soil moisture and temperature measurements collected
680 from experimental plots between July 1, 2018, and June 30, 2021. Readers are
681 encouraged to utilize these data in their research with appropriate attribution.

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874 **Appendix A. Soil freezing module in SVS**

875 SVS uses a hybrid approach that combines Force Restore schemes to compute
876 the surface energy budget of bare ground, vegetation, and snow (Husain et al.,
877 2016) with a multi-layer hydrological module solving the Richards equations for
878 unsaturated flow in a porous media Alavi et al. (2016). This hybrid approach
879 initially prevented the simulation of soil freezing and thawing by the model. To
880 overcome this limitation a new module has been developed.

881 The representation of soil freezing in SVS relies on the soil freezing/thawing
882 module available in the Versatile Soil Budget Model (VSMB Mohammed et al.,
883 2013). This module is based on the simple heat-conduction algorithm of Hayashi
884 et al. (2007) and simulates the evolution of soil temperature and associated phase
885 changes without the computationally expensive iterative solution of coupled
886 non-linear equations. In SVS, soil temperature, and phase changes are solved
887 on the same vertical grid as the hydrological processes using upper boundary
888 conditions provided by the force restore schemes solving the multiple energy
889 budgets at the surface (Husain et al., 2016).

890 *Appendix A.1. Heat conduction algorithm*

891 In the soil temperature algorithm, the heat conduction between two adjacent
892 soil layers (upper to lower) is given by:

$$q_h = -\lambda_s \frac{\Delta_z T}{\Delta z} \quad (\text{A.1})$$

893 where q_h is the soil heat flux (W m^{-2}), $\Delta_z T$ is the difference in soil tem-
894 perature between adjacent layers (lower minus upper) (K), Δz is the distance
895 between the centers of the (m) and λ_s is the bulk thermal conductivity given by

896 the thickness-weighted harmonic mean conductivity of the two layers (W K⁻¹
 897 m⁻¹).

898 For a given soil layer j , the net heat flux ($\Delta_z q_{h,j}$) is then computed as:

$$\Delta_z q_{h,j} = q_{h,j-1} - q_{h,j} \quad (\text{A.2})$$

899 The soil temperature algorithm assumes then that the change in net heat
 900 flux corresponds to a change in heat stored as sensible and latent heat in layer
 901 j :

$$\Delta_z q_{h,j} = (\Delta_t T_j c_{s,j} + \Delta_t w_{i,j} \rho_w L_f) d_j \quad (\text{A.3})$$

902 where $\Delta_t T_j$ (K) and $\Delta_t w_{i,j}$ (kg kg⁻¹) are the changes in soil temperature
 903 and liquid equivalent ice content of layer j , respectively, with time, ρ_w is the
 904 density of water (kg m⁻³), L_f is the latent heat of fusion (J kg⁻¹), d_j is the
 905 layer thickness (m), and $c_{s,j}$ is the volumetric heat capacity of the soil layer (J
 906 m⁻³ K⁻¹).

907 The VSMB soil freezing scheme assumes that water in soil pores freezes at
 908 $T_{ref} = 273.15$ K and ignores the freezing-point depression (Kurylyk & Watan-
 909 abe, 2013). It accounts for the presence of unfrozen water that remains in the
 910 soil at sub-zero temperatures and co-exists with ice. The default VSMB algo-
 911 rithm assumes that the residual unfrozen water content, $w_{l,r}$, is constant and
 912 equals 0.06. This option has been used in the work since it corresponds well to
 913 local observations of residual liquid water content in frozen conditions. Another
 914 option in SVS allows the unfrozen residual water content to depend on the soil
 915 texture based on Niu & Yang (2006). If a soil layer j is completely thawed
 916 or frozen with no liquid water above the residual frozen water content (i.e.,
 917 $T_j \neq T_{ref}$), $\Delta_z q_{h,j}$ is converted to sensible heat until T_j reaches T_{ref} and any
 918 residual is converted to latent heat (melting of freezing). If the soil is already
 919 frozen ($T_j = T_{ref}$), $\Delta_z q_{h,j}$ is first used for phase change of all available liquid
 920 water above $w_{l,r}$ and any residual is converted to sensible heat. Calculations
 921 are performed sequentially from the top to the lowest soil layer.

922 The thermal heat capacity, c_s , and thermal conductivity, λ_s , of the soil
 923 layers are parameterized following Peters-Lidard et al. (1998) as functions of
 924 soil moisture and texture (percentage of sand and clay) and account for the
 925 effect frozen soils as described in Boone et al. (2000). The dry soil thermal
 926 conductivity and soil thermal conductivity are taken from He et al. (2021) and
 927 Johansen (1975), respectively.

928 *Appendix A.2. Lower boundary condition*

The heat flux at the bottom of the lowest soil layer is specified using an
 annual mean deep soil temperature, T_{btm} , and an appropriate scaling depth,
 z_{btm} . It is written as:

$$q_{h,N} = \lambda_{s,N} \frac{T_N - T_{btm}}{(z_{btm} - z_N)} \quad (\text{A.4})$$

929 where N corresponds to the deepest soil layer. In this study, T_{btm} was set to
 930 7.5 (°C) and z_{btm} set to 5 m.

931 *Appendix A.3. Upper boundary condition*

932 The upper boundary condition accounts for the surface tiling use in SVS and
 933 includes the contribution from: (i) snow-free bare ground, (ii) snow-free low and
 934 high vegetation, (iii) snow over bare ground and low vegetation, and (iv) snow
 935 below high vegetation. The heat flux at the top of the superficial soil layer is
 936 written as:

$$q_{h,0} = (1 - f_{veg}) [(1 - f_{snw}) H_{grnd} + f_{snw} H_{snw}] + f_{veg} [(1 - f_{snwv}) H_{veg} + f_{snwv} H_{snwv}] \quad (\text{A.5})$$

937 Where f_{veg} , f_{snw} and f_{snwv} are the fractions of the grid cell covered by high
 938 vegetation, the fraction of low vegetation and the bare ground covered by snow,
 939 and the fraction of soil under high-vegetation covered by snow, respectively.
 940 H_{grnd} , H_{veg} , H_{snw} and H_{snwv} are the heat flux (W m^{-2}) from snow-free bare
 941 ground, snow-free vegetation, snow over bare ground and low vegetation and
 942 snow below high vegetation.

For bare ground, the heat flux depends on the difference between the skin-temperature T_{gs} simulated by the force-restore approach for bare ground and the temperature of the upper soil layer ($j=1$). It is written as:

$$H_{grnd} = \frac{T_{gs} - T_1}{R_g} \text{ with } R_g = \frac{d_1}{2\lambda_{s,1}} \quad (\text{A.6})$$

943 In its current version, the soil freezing scheme has no feedback on the force
 944 restore scheme used for bare ground. Therefore, the prognostic temperature
 945 variables of the force restore scheme used for bare ground lack the effect of
 946 latent heat release due to soil freezing and thawing. This can lead to an under-
 947 estimation of soil temperature during soil freezing and an overestimation of soil
 948 temperature during soil thawing.

949 SVS does not simulate the evolution of the surface soil temperature below
 950 the low and high vegetation. This limits the ability to compute accurately the
 951 heat flux below the vegetation tile. For this reason, without more information
 952 available, the heat flux from the vegetation tile is assumed to be the same as
 953 the heat flux from the bare ground tile: $H_{veg} = H_{grnd}$.

The force restore schemes used for the snowpack over bare ground and low
 vegetation and the snowpack below high vegetation do not provide information
 on the temperature at the interface between the ground and the snow. There-
 fore, the deep snow temperature, $T_{snw,d}$, from the force restore scheme is used
 to estimate the heat flux between the superficial soil layer and the snow. It is
 written as:

$$H_{snw} = \frac{T_{snw,d} - T_1}{R_{snw}} \text{ with } R_{snw} = \frac{h_{therm}}{\lambda_{snw}} + \frac{d_1}{2\lambda_{s,1}} \quad (\text{A.7})$$

954 where λ_{snw} is the snow thermal conductivity ($\text{W m}^{-1} \text{K}^{-1}$) and h_{therm} the
 955 thickness used to compute the thermal exchanges between the snowpack and
 956 the ground (m). h_{therm} depends on the snow damping depth, d_{snw} , used to
 957 characterize the diurnal variation of temperature close to the snow surface in the
 958 Force Restore scheme (Leonardini et al., 2021). h_{therm} is computed as $h_{therm} =$
 959 $\max/(h_{snw}/2, h_{snw} - d_{snw})$ where h_{snw} is the total snow depth. The heat
 960 flux between the superficial soil layer and the snowpack below high vegetation,

961 H_{snowv} , is derived in the same way as H_{snow} using the simulated information for
 962 the snowpack below high vegetation.

An accurate estimation of the fraction of the soil covered by snow is an important component of the soil freezing scheme. Indeed, it affects the estimation of the surface heat flux and strongly controls soil freezing in the fall and soil thawing in springtime. Two approaches can be used for snow cover fraction in the soil freezing scheme. For the first option, the fraction is computed as $f_{snow} = \max/(1., \frac{\rho_{snow} h_{snow}}{W_{cr}})$ with $W_{cr} = 1 \text{ kg m}^{-2}$. The same formulation is used for f_{snowv} . With this formulation, the snow cover fraction reaches the value of 1 as soon as the snow is present on the ground. Such formulation is mainly suitable for point-scale applications of the soil freezing scheme and was used in the study. A second option, recommended for gridded simulations, relies on the formulation of Niu & Yang (2007):

$$f_{snow} = f_{snowv} = \tanh / \left(\frac{h_{snow}}{2.5z_0 \left(\frac{\rho_{snow}}{\rho_{ref}} \right)^m} \right) \quad (\text{A.8})$$

963 where $\rho_{ref} = 100 \text{ kg m}^{-3}$ and $m = 1.6$ are the default values from Niu & Yang
 964 (2007). In the soil freezing scheme, z_0 is set to 0.01 m to preserve a rapid
 965 increase of the snow cover fraction with snow depth. The term $\left(\frac{\rho_{snow}}{\rho_{ref}} \right)^m$ in the
 966 denominator aims at roughly representing the hysteresis associated with the
 967 snow cover fraction (Niu & Yang, 2007).

968 *Appendix A.4. Hydrological impact*

The presence of frozen soil ($w_i > 0$) modifies the hydraulic conductivity at saturation and the soil porosity in the SVS soil hydrology scheme. The saturated hydraulic conductivity in the presence of frozen soil is written as $k_{satc} = f_{ice} k_{sat}$ where k_{sat} is the hydraulic conductivity at saturation that depends on soil texture. f_{ice} is a parameter that aims at reducing k_{sat} in presence of frozen water in the soil (e.g., Kurylyk & Watanabe, 2013). It is computed as in the CLASS land surface scheme (Ganji et al., 2017):

$$f_{ice} = \left[1 - \max / \left(0, \min / \left(\frac{w_{sat} - 0.001}{w_{sat}}, \frac{w_i}{w_{sat}} \right) \right) \right]^2 \quad (\text{A.9})$$

969 where w_{sat} is the saturated volumetric water content.

The volumetric liquid water content at saturation is also reduced assuming that frozen water becomes part of the soil matrix (Zhao et al., 1997):

$$w_{satc} = \max/(0.001, w_{sat} - w_i) \quad (\text{A.10})$$

970 Evapotranspiration is also indirectly impacted due to the change in the liquid
971 water content when freezing and thawing occur.