21st century scenario forcing increases more for CMIP6 than CMIP5 models

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Abstract

We present new estimates of the forcing for models participating in Coupled Model Intercomparison Project 6 (CMIP6) by applying the method developed in Fredriksen et al. (2021). Validating our approach, these estimates are overall consistent with the fixed-SST estimates available for a small subset of the models. We estimate forcing for experiments with abrupt changes of CO₂, 1% increase of CO₂, historical forcings, and future scenarios. Furthermore, we compare our new estimates to CMIP5 forcing, and demonstrate that CMIP6 forcing is lower than CMIP5 forcing at the end of the historical period, but grows faster than CMIP5 in the future scenarios, ending up at higher levels than CMIP5 at the end of the 21st century. The radiative efficiency of CO₂ has not changed, suggesting that the stronger future increase in CO₂ concentrations in CMIP6 compared to CMIP5 explains the forcing difference.

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Key Points:

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 Our method to estimate effective radiative forcing based on common model diagnostics is consistent with fixed-SST estimates
 We present estimates for abrupt CO₂, 1% CO₂, historical, and future scenario experiments
 Forcing estimates for the 21st century grows faster for CMIP6 than for CMIP5 models

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17 Abstract

We present new estimates of the forcing for models participating in Coupled Model In-18 tercomparison Project 6 (CMIP6) by applying the method developed in Fredriksen et 19 al. (2021). Validating our approach, these estimates are overall consistent with the fixed-20 SST estimates available for a small subset of the models. We estimate forcing for exper-21 iments with abrupt changes of CO_2 , 1% increase of CO_2 , historical forcings, and future 22 scenarios. Furthermore, we compare our new estimates to CMIP5 forcing, and demon-23 strate that CMIP6 forcing is lower than CMIP5 forcing at the end of the historical pe-24 riod, but grows faster than CMIP5 in the future scenarios, ending up at higher levels than 25 CMIP5 at the end of the 21st century. The radiative efficiency of CO_2 has not changed, 26 suggesting that the stronger future increase in CO_2 concentrations in CMIP6 compared 27 to CMIP5 explains the forcing difference. 28

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Plain Language Summary

To understand climate model responses, it is useful to separate between the drivers 30 of climate change and their responses. We present new estimates of the drivers, called 31 the effective radiative forcing, for the latest generation of climate models (CMIP6). This 32 estimates the energy input at the top of the atmosphere and is a measure of human and 33 natural influences on climate. Normally this requires additional climate model exper-34 iments to make these estimates, but since these have only been run for a few models, we 35 are here aiming to make the best alternative estimates based on existing data, follow-36 ing the method in Fredriksen et al. (2021). We show that our forcing estimates are grow-37 ing faster during the 21st century for the new CMIP6 models than for the previous gen-38 eration of models (CMIP5), and suggest this can be attributed to the higher CO₂ con-39 centrations in future scenarios for CMIP6 compared to CMIP5. 40

41 **1** Introduction

The [effective] radiative forcing (ERF) describes the energy input into the Earth system that drives climate change. As well as a common currency to compare the energetic impacts of different human and natural influences on the climate, it is used to develop scenarios characterising possible futures, for example in representative concentration pathway (RCP) and shared socioeconomic pathway (SSP) scenarios (Moss et al., 2010; O'Neill et al., 2016). However, [effective] radiative forcing is difficult to observe and complex climate models such as the general circulation models (GCMs) developed as part
 of the Coupled Model Intercomparison Project Phase 6 (CMIP6) are often the best or
 only way to determine ERF. Accurately quantifying ERF will allow us to attribute cause
 and effect in climate model behavior and better constrain climate sensitivity.

Unfortunately, only a small number of CMIP6 models—9 out of 51— provided es-52 timates of ERF, for the historical period and one scenario to 2100. These ERF estimates 53 were derived from atmosphere-only runs of CMIP6 models using pre-industrial sea-surface 54 temperatures and sea-ice distributions (Hansen et al., 2005; Forster et al., 2016), known 55 as the fixed-SST method. The experiment is a Tier 2 simulation provided by the Radia-56 tive Forcing Model Intercomparison Project (RFMIP) contribution to CMIP6 (Pincus 57 et al., 2016). To obtain estimates of ERF from more models and scenarios, we can use 58 estimates of the climate feedback parameter from each model's abrupt-4xCO2 experi-59 ment (a mandatory experiment for all CMIP6 models) obtained from a Gregory regres-60 sion, and use this to relate outputs of modelled top-of-atmosphere energy imbalance and 61 surface temperature to time-varying ERF (for a full description of this method, see Forster 62 et al. (2013)). However, this method is biased, as it is now well-known that the climate 63 feedback parameter is not constant in time (e.g. Senior & Mitchell, 2000; Winton et al., 64 2010; Armour, 2017; Rugenstein et al., 2020; Andrews et al., 2022). Comparing the two 65 methods for historical ERF shows that the bias is worse in models that show significant 66 non-stationarity in their climate feedback parameter (Smith & Forster, 2021). 67

Acknowledging that fixed-SST ERF is not yet widely available from models, we can 68 seek to improve ERF estimated from the abrupt-4xCO2 climate feedback. By calculat-69 ing ERF assuming a time-scale dependent feedback parameter with three different time 70 scales, we show in Fredriksen et al. (2021) that we can well describe the surface temper-71 ature output of the historical and RCP scenarios for the majority of CMIP5 models. In 72 this paper we extend the analysis to CMIP6 models and scenarios, with the added con-73 fidence of comparing results with fixed-SST estimates in 10 cases, and also compare ERF 74 in RCP (CMIP5) and SSP (CMIP6) scenarios with the same nominal year-2100 radia-75 tive forcing. 76

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77 **2 Data**

We study CMIP6 models that have published the four variables tas (near-surface 78 air temperature), rlut, rsut and rsdt (top of atmosphere longwave upwelling, shortwave 79 upwelling, and shortwave downwelling radiation respectively) for both the piControl and 80 the abrupt-4xCO2 experiment in March 2022. For these 51 models (listed in Table S1 81 and S2), we look at all members we could find for the experiments abrupt-2xCO2, abrupt-82 0p5xCO2, 1pctCO2, historical, hist-GHG, hist-aer, hist-nat, ssp119, ssp126, ssp245, ssp370, 83 ssp585, piClim-4xCO2, piClim-control and piClim-histall. The number of members used 84 for analysis is listed in Tables S1-S4. The piClim-* experiments are atmosphere-only sim-85 ulations using climatological SSTs and sea ice distributions from the models' pre-industrial 86 climate, and we often refer to these as fixed-SST experiments. For many models, the piClim-87 histall experiments are extended with the SSP2-4.5 scenario to year 2100. In addition 88 to the 9 publicly available piClim-histall experiments, we have included an experiment 89 done with the model MPI-ESM1-2-LR not available yet through CMIP6. In our Figure 90 3 we include also estimates presented in Fredriksen et al. (2021) for 21 CMIP5 models. 91 For each variable, we have studied the annual anomalies relative to a linear trend (com-92 puted from all piControl vears) evaluated in the corresponding period of the control run. 93

94 **3** Method

The linear energy balance framework describes, to first order, the correspondence between forcing, feedbacks and global mean temperature:

$$N = F + \lambda T \tag{1}$$

where N is the top-of-the-atmosphere (TOA) net radiative downward flux (in W m⁻²), 97 λ is the climate feedback parameter (in W m⁻² K⁻¹), T is the surface air temperature 98 change (in K) relative to an unperturbed steady state where N = F = 0 and F is the 99 external radiative forcing (in $W m^{-2}$), for instance due to a change in atmospheric com-100 position. λ is often determined from idealised experiments where the CO₂ concentration 101 is abruptly quadrupled, using the Gregory method (Gregory et al., 2004). Once λ is known, 102 Eq. (1) can be rearranged to determine F(t) from any experiment where the evolution 103 of T(t) and N(t) are known (Forster et al., 2013), here referred to as the 1- λ forcing. 104

We use here the method described in detail in Fredriksen et al. (2021) to compute what we will refer to as the 3- λ forcing. This method attempts to correct the biases in the 1- λ forcing by using three different λ 's instead. We assume the global temperature responds linearly to the forcing, and can be described as

$$T(t) = \sum_{n=1}^{K} T_n(t) = \sum_{n=1}^{K} c_n \exp(-t/\tau_n) * F(t)$$
(2)

where the * denotes a convolution, and that N can be decomposed similarly, where different λ 's are associated with each component of T(t):

$$N(t) = \sum_{n=1}^{K} N_n(t) = F(t) + \sum_{n=1}^{K} \lambda_n T_n(t)$$
(3)

We determine the c_n 's and λ_n 's using abrupt-4xCO2 experiments as in Fredriksen et al. 105 (2021), except that the method is further developed to use data points from all ensem-106 ble members if several are available for a model to better constrain the estimate. Ad-107 ditional members are averaged over when computing the parameters of the temperature 108 response, and treated as extra data points when plotting T vs N to determine the λ_n 's. 109 As before, we use 150 years of data for estimation to treat all models equally. Many mod-110 els have run the experiments for longer than that, and these extra years are included in 111 the figures, allowing us to visually inspect how our fit performs at longer scales. 112

In Eqs. (2) and (3) we use K = 4, but the slowest response is assumed to be so slow, that it can be approximated as a constant heat flux $N_4 = b_4$ going into the deeper oceans without affecting the surface temperature during the first 150 years after quadrupling. Hence, we are in practice studying the 3-time scale responses $T(t) \approx \sum_{n=1}^{3} T_n(t)$ and $N(t) \approx b_4 + \sum_{n=1}^{3} N_n(t)$.

In Eq. (2), we note that we can move an arbitrary factor between the c_n and F(t)118 without changing the temperature response, so different definitions of the forcing can in 119 fact be used in a linear/impulse response model, as long as one is consistent about the 120 definition when applying the model to different experiments. Here we strive to make a 121 forcing definition that does not involve adjustments from surface temperature responses, 122 and is consistent with the fixed-SST forcing estimates. When the parameters c_n and λ_n 123 have been estimated from the abrupt-4xCO2 experiment, we have defined a separation 124 of forcing and response, which we can use to compute F(t) for other experiments by re-125 arranging Eq. (3). Since this equation needs to know the components of T(t), we need 126 to iterate until convergence between (i) performing the convolutions in Eq. (2) to find 127 the components and (ii) computing the forcing which is needed for the convolutions. 128

The method relies on a linear response model for predicting the temperature com-129 ponents, so a criterion for making good forcing estimates is that the linear model actu-130 ally predicts the temperature well. In several figures we therefore include the difference 131 between the temperature predicted by the linear model and the temperature output of 132 the GCM. A difference close to zero is considered a necessary, but not sufficient crite-133 rion that we have a good forcing estimate. More importantly, we are interested in es-134 timates that are consistent with the fixed-SST forcing (corrected for land temperature 135 responses). Hence, whenever available, our forcing estimates are compared to fixed-SST 136 estimates of the forcing. 137

As a thought experiment of why we think it is important to have a good curved 138 fit to all points in a Gregory plot to make good forcing estimates for other experiments, 139 we can consider the result of using 1- λ methods for estimating time-varying forcing for 140 abrupt-4xCO2, and test how close this is to a constant. Assuming we have a typical Gre-141 gory plot where feedbacks become less negative with time and we make a regression for 142 the first 150 years of data, the time-varying forcing $F(t) = N(t) - \lambda T(t)$ will have higher 143 values in the beginning where the values of N(t) are above the straight line. Similarly, 144 if making a regression for the first 20 years, then the later time period will get stronger 145 forcing estimates. So if these forcing estimation methods cannot reproduce the constant 146 $4xCO_2$ forcing, we would expect them to give biased time-varying forcings also for other 147 experiments. 148

149 4 Results

For the 18 models where fixed-SST forcing is available for $abrupt-4xCO_2$, we find 150 a generally good correspondence between our forcing estimates and the fixed-SST forc-151 ing (see Figure 1 and estimated parameters in Tables S6 and S7). Since the land tem-152 peratures have responded a little in the fixed-SST experiments (Andrews et al., 2021), 153 we can expect these estimates to be comparable to our curve after a few months of re-154 sponse. Several methods exist for adjusting these forcing estimates to isolate the forc-155 ing at zero temperature response, and in Figure 1 we include the ERF_trop estimates 156 from Smith et al. (2020). The light blue curves provides some insight into the uncertain-157 ties associated with our estimates, and we note that their spread varies substantially be-158 tween models. We can expect eventual over- or under-estimations of the $4xCO_2$ forcings 159 here to follow the transient forcing estimates presented in other figures. Uncertainties 160

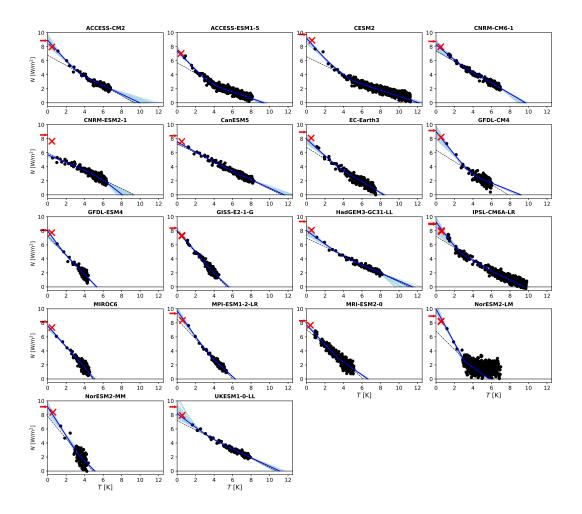


Figure 1. The top-of-the-atmosphere net radiation anomalies (N) versus the temperature anomalies (T) for the 18 models where we know the fixed-SST forcing (plotted as red crosses) for abrupt-4xCO2 simulations. The black dots are annual mean values, and all available members are included. The black dashed fit is the standard 150-year linear regression still used in the Sixth Assessment Report. The light blue curves are fits done to the first 150 years of the response with the 3- λ method for 1000 different random choices of time scales, and the dark blue curves show the best (least-squares) fit for the temperature response, as in Fredriksen et al. (2021). The red arrows show the ERF_trop forcing estimates from Smith et al. (2020).

in the forcing estimates are often larger if the model's surface temperature responds quickly, 161 as there will be fewer points close to the y-axis to constrain the intercept. Similarly, if 162 a model is still far from equilibrium after 150 years we can expect a larger spread in the 163 estimated climate sensitivity (as derived from the intercept with the x-axis). Internal vari-164 ability in T and N also plays a role in determining the uncertainty of the fit. 165

One exception from the good correspondence happens for the model CNRM-ESM2-166 1, because the model did not use an abrupt concentration change of $4 \times CO_2$ through-167 out the whole atmosphere, instead adjusting the surface emissions of CO_2 to maintain 168 $4 \times CO_2$ in the lowest atmospheric layer and allowing CO_2 to percolate throughout the 169 atmosphere, which takes around 15 years to reach a uniform $4 \times CO_2$ concentration (Smith 170 et al., 2020). This results in regression estimates being biased low compared to the fixed-171 SST estimates. These "effective" lower estimates actually work well in predicting tem-172 perature responses with our linear model, but since the forcing has been specified dif-173 ferently to other CMIP6 models we have not included this model in further analyses. 174

We show similar figures for the 33 models without fixed-SST forcing estimates in 175 the supporting information (Figures S1 and S2), and for the 12 models with abrupt-2xCO2 176 and the 9 models with abrupt-0p5xCO2 experiments in Figures S3 and S4, respectively. 177 Our curved fit through the points appears to be a generally better fit than straight lines, 178 so we expect to find reasonable forcing estimates (i.e. relative to fixed-SST forcing es-179 timates) also for these experiments. Forcing estimates for the abrupt-2xCO2 and abrupt-180 0p5xCO2 experiments are given in Table S8. We find that $4 \times CO_2$ forcing is on average 181 2.11 times stronger than the $2 \times CO_2$ forcing, and the absolute value of the $0.5 \times CO_2$ forc-182 ing is a little weaker than the $2 \times CO_2$ forcing for most models, consistent with a radia-183 tive forcing depending superlogarithmically on the CO₂ concentration (Etminan et al., 184 2016). However, the smaller signal-to-noise ratio makes these lower forcing estimates more 185 uncertain. We note this in particular for the $0p5xCO_2$ experiments, where a few esti-186 mates in the high end of the uncertainty range cause the mean absolute forcing to be 187 slightly stronger than for $2 \times CO_2$. 188

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All abrupt CO₂ experiments could in principle have been used for estimating the 3 λ 's, but many more models have published 4xCO₂ experiments than abrupt 2× and 190 $0.5 \times \text{CO}_2$ experiments. The higher signal-to-noise ratio of the abrupt-4xCO₂ experiments 191 is also an advantage. However, the stronger the response, the stronger the effect of state-192

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dependent feedbacks or other parameters may be, which violates our linear response assumption (Bloch-Johnson et al., 2021). Finding a way to tell how much of the feedback change is due to state-dependence (inconsistent with linear response) or due to pattern effect/time-scale dependence (can be consistent with linear response) will be important in future work.

The historical and SSP2-4.5 3- λ forcing is consistent with the fixed-SST forcing for 198 most of the 10 models where this is available and always better than or as good as the 199 1- λ forcing estimates (Figure 2). Hence we expect the 3- λ ERF to be a good approxi-200 mation also for the many models and experiments that lack fixed-SST forcing. The black 201 curves in the right column show that land temperatures have not responded much in these 202 fixed-SST experiments compared to abrupt-4xCO2 experiments, so these forcing esti-203 mates probably do not need to be corrected for land responses to the same degree. For 204 models with little curvatures in Figure 1, the $1-\lambda$ forcing is as expected very similar to 205 the 3- λ forcing. For IPSL-CM6A-LR the fixed-SST forcing falls in the middle of the 1-206 λ and 3- λ forcing, suggesting that both the 3- λ and 1- λ forcings are slightly biased in 207 different directions. From Figure 1 we note that our $3-\lambda$ IPSL-CM6A-LR forcing esti-208 mate is in the higher end of a large uncertainty range. 209

In addition to the comparison with fixed-SST forcing, the ability to predict the GCM 210 temperature also serves as a measure of how good the forcing estimate is, therefore we 211 have included in the right column of Figure 2 the difference between the temperature 212 predicted from our 3- λ forcing and linear response model and the output of the complex 213 model. For positive differences, the forcing is probably overestimated, and vice versa. 214 Temperature differences are typically within a $\pm 0.5^{\circ}$ C interval, suggesting that our com-215 bination of forcing and linear response can generally well describe global mean temper-216 atures. Our smaller temperature emulation error for some models compared to Jackson 217 et al. (2022) (which can e.g. be up to 0.5° C for IPSL-CM6A-LR) is probably explained 218 by our different forcing definition, in particular related to its correction for land temper-219 ature responses. 220

Figure 3 shows the multi-model mean $3-\lambda$ forcing from all available models for 7 different experiments (left column), and the corresponding global mean temperature difference between the linear responses and the GCMs (right column). The large ensembles of temperature differences show that temperature responses are on average slightly

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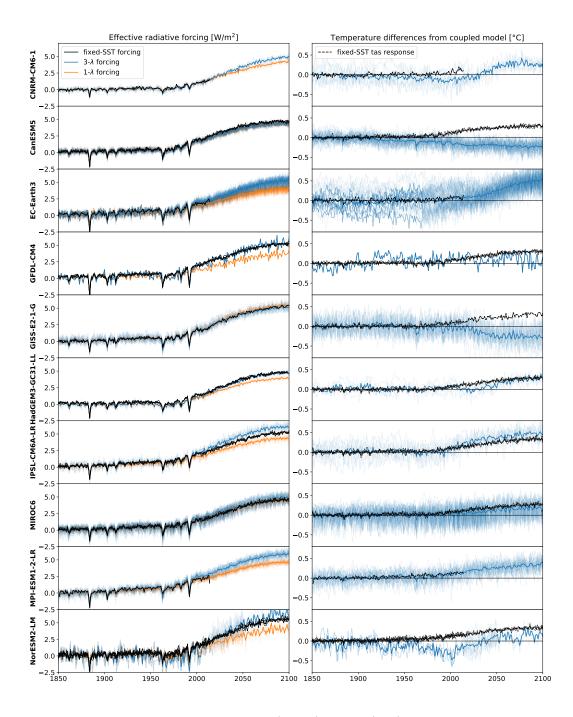


Figure 2. Left column: comparison of 1- λ (orange) and 3- λ (blue) forcing estimates to the fixed-SST (black) forcing estimates, for the models where transient fixed-SST estimates are available (10 models). Some models have run these experiments for the historical period, and some have extended it for the SSP2-4.5 scenario. Thin lines are estimates from single members, and thicker lines are ensemble means. Right column: the surface air temperature differences between the output of the coupled model and the estimated response to the 3- λ forcing (blue). In addition, we have included the change in surface air temperature from the fixed-SST runs, which should give the fixed-SST forcing a tiny negative bias when the temperature response grows (black).

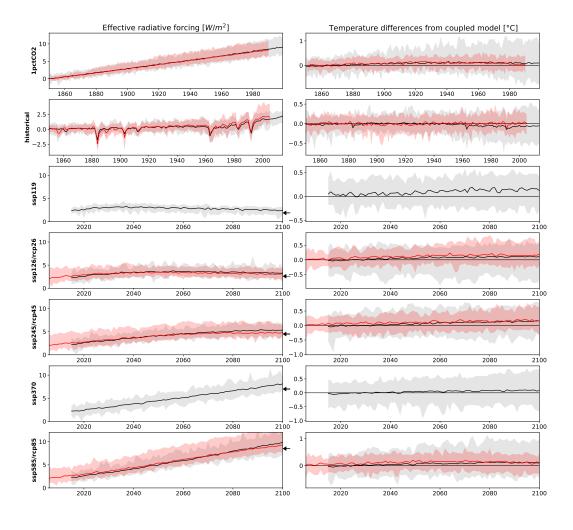


Figure 3. Left column: Effective radiative forcing estimates using the 3- λ method from up to 50 models from CMIP6 (gray/black) and up to 21 models from CMIP5 (red). The shading shows the min and max values of the member mean forcing for each year, and the red/black curves the mean of all models. Each row shows an experiment denoted by the y-axis label. The black arrows denote the forcing levels 1.9, 2.6, 4.5, 7.0 and 8.5 W m⁻² in year 2100. Right: The difference between the temperature predicted by the linear temperature response and the global mean temperature from the coupled model.

overestimated for the 1pctCO2 and future scenario experiments, and hence the forcings
in the left column are probably slightly overestimated too. We hypothesize this could
be due to state-dependencies in the feedback parameters. We include also the CMIP5
estimates from Fredriksen et al. (2021) in this figure for comparison, and note that for
the 1pctCO2 experiment (top row) the average forcing estimates are remarkably similar for CMIP5 and CMIP6.

For the last decades of the historical experiment, we find the CMIP6 forcing to be 231 lower than the CMIP5 forcing, but maybe slightly underestimated, as evidenced by the 232 comparison between our estimated temperatures and those from the GCMs. For the fu-233 ture comparable scenarios however (SSP1-2.6, SSP2-4.5 and SSP5-8.5 for CMIP6; RCP2.6, 234 RCP4.5 and RCP8.5 for CMIP5), the CMIP6 forcing grows more than the CMIP5 forc-235 ing, and ends up at higher values than CMIP5 at the end of the 21st century with no 236 clear difference in the bias in temperatures compared to CMIP5 models. This suggests 237 that CMIP6 ERF is higher than equivalent nominal scenarios in CMIP5. The multi-model 238 mean difference in year 2100 is 0.18, 0.46, and 0.55 Wm^{-2} for RCP2.6/SSP1-2.6, RCP4.5/SSP2-239 4.5, RCP8.5/SSP5-8.5, respectively. 240

A closer look at the historical period (Figure 4) shows that our 3- λ total forcing for around 1995 onwards is a little stronger than the 1- λ forcing, as used in Smith and Forster (2021). Studying the components separately, we find that the greenhouse gas forcing becomes more positive, and the aerosol forcing becomes more negative when using the 3- λ method. In general, the different forcing definitions give more different results the stronger the temperature response is.

The small underestimation of the CMIP6 linear temperature responses for the his-247 torical period seems to stem mainly from the response to aerosol forcing in some of the 248 models (not shown). One reason for this could be a similar (possible state-dependence) 249 effect for this negative forcing as we have with the small overestimation for the positive 250 forcing. Or it could be that the more spatially inhomogeneous aerosol forcing triggers 251 more localised responses (for instance land temperatures may respond much faster and 252 stronger than ocean temperatures), resulting in a global mean response to aerosols that 253 differ from the global mean response to CO_2 . This may lead to small errors in the lin-254 ear response assumption, which could cause small errors in the global mean forcing es-255

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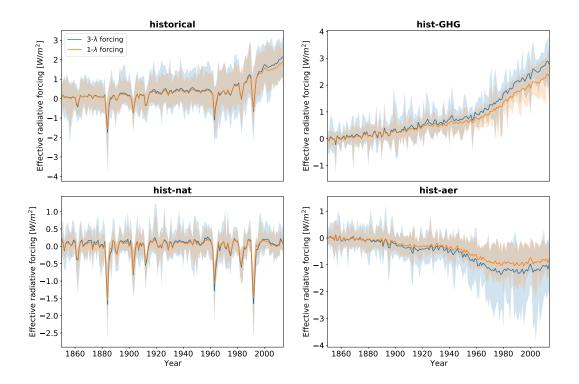


Figure 4. The effective radiative forcing for the historical, hist-GHG, hist-nat and hist-aer experiments, computed using both the $1-\lambda$ (orange) and the $3-\lambda$ method (blue). The shading shows the min and max values of the model ensemble, and the solid curves the model means.

timates too. Hence we cannot rule out that efficacy factors (Hansen et al., 2005) differ-

²⁵⁷ ent from 1 could be needed for this forcing.

258 5 Discussion

Future temperature projections from CMIP6 show stronger warming than the cor-259 responding projections from CMIP5 (Tebaldi et al., 2021). The CMIP5 RCP scenarios 260 have a different composition of greenhouse gases, aerosols and other forcers than the CMIP6 261 SSP scenarios, but they are designed such that they should reach approximately the same 262 forcing levels by the end of the 21st century (Gidden et al., 2019). However, Wyser et 263 al. (2020) shows that at least half of the temperature increase from CMIP5 to CMIP6 264 for the model EC-Earth3-Veg is due to the increase in the ERF, and in particular the 265 greenhouse gas concentrations. Chapter 4 of the IPCC's Sixth Assessment Report Work-266 ing Group 1 (Lee et al., 2021) shows that ERF is substantially higher for CMIP6 SSPs 267 that are nominally the same forcing as CMIP5 RCPs (SSP1-2.6 versus RCP2.6 for ex-268 ample), and comes to a similar conclusion, namely that the increase in forcing contributes 269 to about half of the temperature increase in CMIP6 models compared to CMIP5 mod-270 els with the other half attributed to the increase in climate sensitivity. 271

Our results confirm that the ERF is indeed increasing more for CMIP6 than for CMIP5 during the 21st century. From the 1pctCO2 experiment we note that given the same increase in CO₂ concentrations, the ERF is similar in CMIP5 and CMIP6 models, so the radiative efficiency of CO₂ has not changed between the model generations. This suggests that the higher year-2100 CO₂ concentrations in CMIP6 compared to similar CMIP5 scenarios (Meinshausen et al., 2020) explains the increase in ERF.

Despite the higher temperature increase in the future scenarios, the historical tem-278 perature increase is less in CMIP6 than in CMIP5 (Flynn & Mauritsen, 2020; Smith & 279 Forster, 2021). Smith and Forster (2021) explain this as a combination of stronger feed-280 backs and lower historical forcing, from both aerosols and greenhouse gases (GHGs). Our 281 new 3- λ historical forcing estimates diverge from the 1- λ forcing used in Smith and Forster 282 (2021) only after 1995, and is hence not changing their conclusions. However, our find-283 ing that similar CO_2 concentrations lead to similar forcing, should also imply that the 284 similar global annual mean historical CO_2 concentrations (Meinshausen et al., 2017) lead 285 to similar CO₂ forcing in CMIP5 and CMIP6, though differences in the latitudinal and 286

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seasonal variations in concentrations or the effective forcing from other greenhouse gases
may also affect the resulting GHG forcing. The similar CO₂ forcing may suggest that
the stronger aerosol forcing plays a larger role in explaining the lower historical forcing
in CMIP6.

The higher temperature increase for CMIP6 during the 21st century is also partly 291 explained by the increase in climate sensitivity, as evidenced by less negative global feed-292 backs, increased equilibrium climate sensitivity (ECS) and transient climate response (TCR) 293 (Flynn & Mauritsen, 2020; Zelinka et al., 2020). The climate sensitivity does not tell the 294 full story of how much warming we can expect at all times, and an increased sensitiv-295 ity may not necessarily contribute to increased temperature responses during the his-296 torical period. In addition to forcing differences, the pattern of warming also matters, 297 as some regions more effectively radiate out excess energy than others, hence modulat-298 ing the effective global climate sensitivity with time (the *pattern effect*). During the late 299 20th century, the warming pattern in the tropical Equatorial Pacific has led to lower es-300 timates of the effective climate sensitivity, (e.g. Zhou et al., 2016; Andrews et al., 2018, 301 2022). This pattern is not expected to persist in the future, likely causing the effective 302 climate sensitivity to increase in the near future. 303

Normalizing the abrupt-4xCO2 responses by our estimated forcing yields also a measure of the model sensitivity per unit forcing, which may be helpful for understanding if temperature responses are stronger because of a high climate sensitivity or a higher forcing. We find that CMIP6 models have an average response slightly stronger than CMIP5 models, and a larger model spread (Figure S5). Hence our results confirm that CMIP6 models are overall more sensitive, but the relative role of the climate sensitivity for explaining higher temperature responses is highly model dependent.

6 Open research

The original CMIP6 datasets are available at https://esgf-node.llnl.gov/projects/ cmip6/. Processed data and code will be permanently stored in zenodo (link will be made and inserted here when paper is accepted. In the meantime, data and code can be accessed through github: https://github.com/Hegebf/CMIP6-forcing, which was made public just before submission)

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317 Acknowledgments

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Supporting Information for "21st century scenario forcing increases more for CMIP6 than CMIP5 models"

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- 2. Table S1-S8

Introduction

We present tables with an overview of the data included in this study, and estimated parameters from the abrupt $4xCO_2$ experiments, in addition to forcing estimates from $2xCO_2$ and $0p5xCO_2$ experiments.

We show also results from abrupt- $4xCO_2$ experiments similar to those in Figure 1 in the main manuscript, but where no fixed-SST estimates are available. And similar plots for abrupt- $2xCO_2$ and abrupt- $0p5xCO_2$ experiments.

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We note also that for many models the branch information found in the metadata contains errors. We have done our best in trying to correct obvious mistakes, but cannot rule out more branch time errors, which could have small impacts on the computed anomalies.

	abrupt-4xCO2	abrupt-2xCO2	abrupt-0p5xCO2
ACCESS-CM2	1	-	-
ACCESS-ESM1-5	2	-	-
AWI-CM-1-1-MR	1	-	-
BCC-CSM2-MR	1	-	-
BCC-ESM1	1	-	-
CAMS-CSM1-0	2	-	-
CESM2	1	1	1
CESM2-FV2	1	-	-
CESM2-WACCM	1	-	-
CESM2-WACCM-FV2	1	-	-
CMCC-CM2-SR5	1	-	-
CMCC-ESM2	1	-	-
CNRM-CM6-1	6	1	1
CNRM-CM6-1-HR	1	-	-
CNRM-ESM2-1	3	-	-
CanESM5	2	1	1
E3SM-1-0	1	-	-
EC-Earth3	2	-	-
EC-Earth3-AerChem	1	-	-
EC-Earth3-CC	1	-	-
EC-Earth3-Veg	1	-	-
FGOALS-f3-L	3	-	-
FGOALS-g3	1	-	-

Table S1. Number of abrupt-4xCO2, abrupt-2xCO2 and abrupt-0p5xCO2 members used in

this study, part I.

	1	1	
	abrupt-4xCO2	abrupt-2xCO2	abrupt-0p5xCO2
GFDL-CM4	1	-	-
GFDL-ESM4	1	-	-
GISS-E2-1-G	4	4	1
GISS-E2-1-H	3	2	-
GISS-E2-2-G	1	1	-
GISS-E2-2-H	1	1	-
HadGEM3-GC31-LL	1	1	1
HadGEM3-GC31-MM	1	-	-
ICON-ESM-LR	1	-	-
IITM-ESM	1	-	-
INM-CM4-8	1	-	-
INM-CM5-0	1	-	-
IPSL-CM5A2-INCA	1	-	-
IPSL-CM6A-LR	12	1	1
KIOST-ESM	1	-	-
MIROC-ES2L	1	-	-
MIROC6	1	1	1
MPI-ESM-1-2-HAM	1	-	-
MPI-ESM1-2-HR	1	-	-
MPI-ESM1-2-LR	1	-	-
MRI-ESM2-0	14	1	1
NESM3	1	-	-
NorCPM1	1	-	-
NorESM2-LM	1	-	-
NorESM2-MM	1	-	-
SAM0-UNICON	1	-	-
TaiESM1	1	1	1
UKESM1-0-LL	1	-	-
Number of models	51	12	9

Table S2.	Number of abrupt-4xCO2, abrupt-2xCO2 and abrupt-0p5xCO2 member	ers used in
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this study, part II.

Table S3. Number c	Number of members	where we have computed	have com	puted trans	transient forcing time ser	ing time		es, part I.		
	1pctCO2	historical	hist-nat	hist-GHG	hist-aer	ssp119	ssp126	27	ssp370	ssp585
ACCESS-CM2	<u>ш</u>	υ	ω	ယ	ω	I	υ	თ	თ	υ
ACCESS-ESM1-5	<u>—</u>	40	ω	ယ	ω	I	40	40	40	40
AWI-CM-1-1-MR	щ	υ	I	I	I	I	щ	<u>س</u>	თ	<u> </u>
BCC-CSM2-MR	щ	లు	ω	ယ	ω	I	щ	<u>ш</u>	щ	⊢
BCC-ESM1	щ	లు	I	I	I	I	I	I	ယ	I
CAMS-CSM1-0	2	ట	I	I	I	2	2	2	2	2
CESM2	1	11	ω	ယ	2	I	ယ	ယ	ယ	ယ
CESM2-FV2	щ	లు	I	I	I	I	I	I	I	I
CESM2-WACCM	щ	లు	I	I	I	I	щ	თ	ယ	υ
CESM2-WACCM-FV2	щ	లు	I	I	I	I	I	I	I	I
CMCC-CM2-SR5	щ	7	ı	I	I	I	щ	щ	щ	щ
CMCC-ESM2	щ	щ	I	I	I	I	щ	щ	щ	щ
CNRM-CM6-1	щ	29	10	10	10	ı	6	10	6	9
CNRM-CM6-1-HR	Ц	Ц	ı	I	ı	ı	1	1	1	1
CNRM-ESM2-1	10	11	ı	I	ı	ы	υī	10	თ	ы
CanESM5	6	65	50	50	30	50	50	50	50	50
E3SM-1-0	1	τυ	ı	I	ı	ı	ı	ı	ı	ı
EC-Earth3	щ	72	ı	I	ı	51	57	71	57	57
EC-Earth3-AerChem	щ	2	ı	I	ı	ı	ı	ı	2	ı
EC-Earth3-CC	щ	щ	I	I	ı	ı	I	щ	I	1
EC-Earth3-Veg	щ	9	I	I	ı	ယ	7	∞	6	x
FGOALS-f3-L	లు	లు	ı	I	ı	ı	Ц	Ц	1	щ
FGOALS-g3	లు	6	ယ	ω	ω	Т	4	4	υ	4

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Table S4. Number of members where we have computed transient forcing time series, part II	of members	•		2112		1	1)		1
	1pctCO2	historical	hist-nat	hist-GHG	hist-aer	ssp119	ssp126	ssp245	ssp370	ssp585
GFDL-CM4		1	က	I	ı	ı	ı		ı	-
GFDL-ESM4		1	ŝ	1			Ļ		Ļ	
GISS-E2-1-G	ы	46	20	10	15	7	12	31	27	11
GISS-E2-1-H		25	ı	I	I	2	ю	10	9	υ
GISS-E2-2-G		ı	ı	I	I	I	I	ı	I	I
GISS-E2-2-H	H	ю	ı	I	ı	ı	ı	ı	ı	ı
HadGEM3-GC31-LL	4	Ŋ	10	ъ	ស	I	1	ഹ	I	4
HadGEM3-GC31-MM	Η	4	ı	I	ı	ı	1	I	ı	4
ICON-ESM-LR		ю	ı	I	ı	ı	ı	I	ı	ı
IITM-ESM	Н	1	I	I	I	I	1	Ц	1	1
INM-CM4-8		1	I	I	I	I	-	Ц		
INM-CM5-0		10	I	I	I	I	1	Η	S	1
IPSL-CM5A2-INCA		1	ı	I	I	I	Ļ	I	Ļ	I
IPSL-CM6A-LR	Ξ	33	10	10	10	9	9	11	11	2
KIOST-ESM		1	I	I	I	I	-	Ц	ı	
MIROC-ES2L	,	26	ı	ı	I	10	10	25	10	10
MIROC6	1	50	50	က	10	, 1	50	50	က	50
MPI-ESM-1-2-HAM	1	က	ı	I	ı	ı	ı	ı	က	ı
MPI-ESM1-2-HR	1	10	ı	I	ı	ı	2	2	10	2
MPI-ESM1-2-LR	1	30	ı	I	ı	30	30	30	30	30
MRI-ESM2-0	2	12	5 C	0 Q	5	ŋ	5	10	5	9
NESM3	1	ю	ı	I	ı	ı	2	2	ı	2
NorCPM1	1	30	ı	I	ı	ı	ı	ı	ı	ı
NorESM2-LM	1	c,	က	က	c,	ı	1	13	c:	, - 1
NorESM2-MM	1	က	ı	I	ı	ı	1	2		, _
SAM0-UNICON	1	1	ı	I	I	I	ı	I	ı	ı
TaiESM1	1	2	ı	I	ı	I	, -	H	, _	, _ 1
UKESM1-0-LL	4	19	ı	ı	ı	ю	16	17	16	ю
Number of models	51	50	15	14	14	15	38	38	37	39

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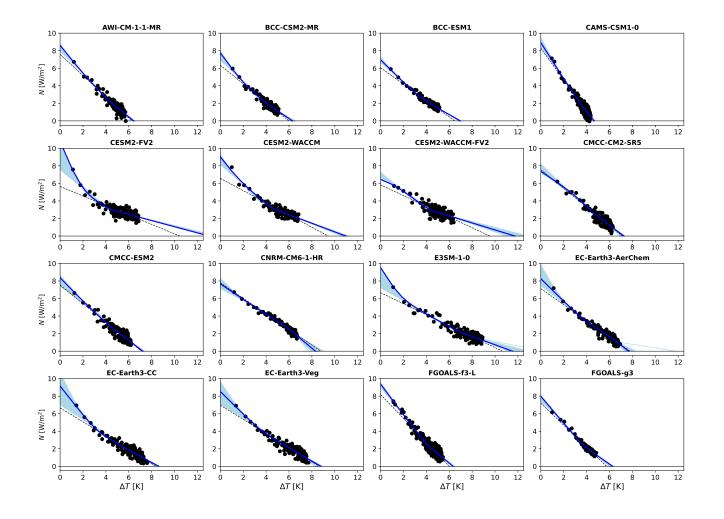
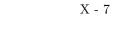


Figure S1. As Figure 1, but for models without fixed-SST forcing. Part I.



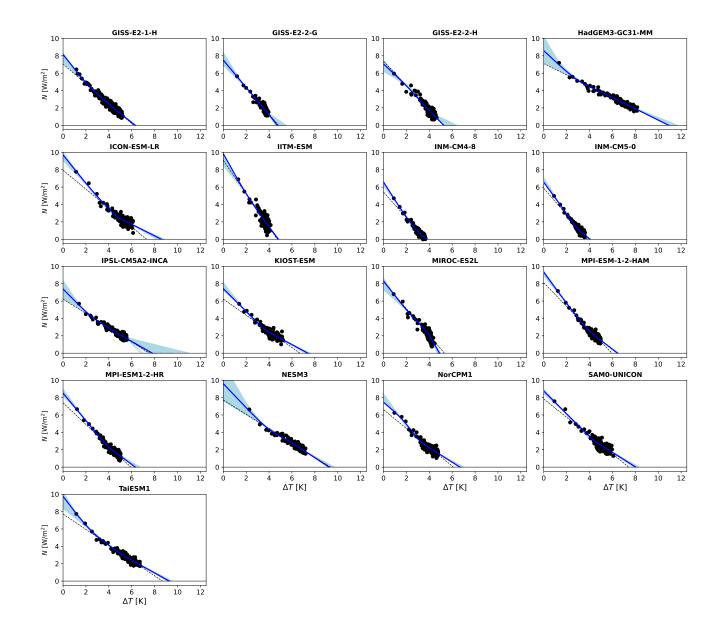


Figure S2. As Figure 1, but for models without fixed-SST forcing. Part II.

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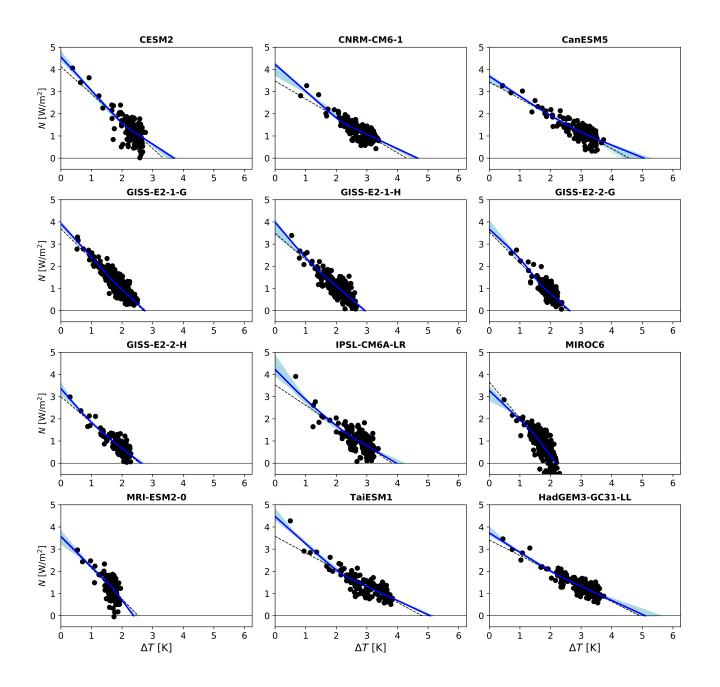


Figure S3. Similar figure as above, but using the abrupt-2xCO2 experiment.



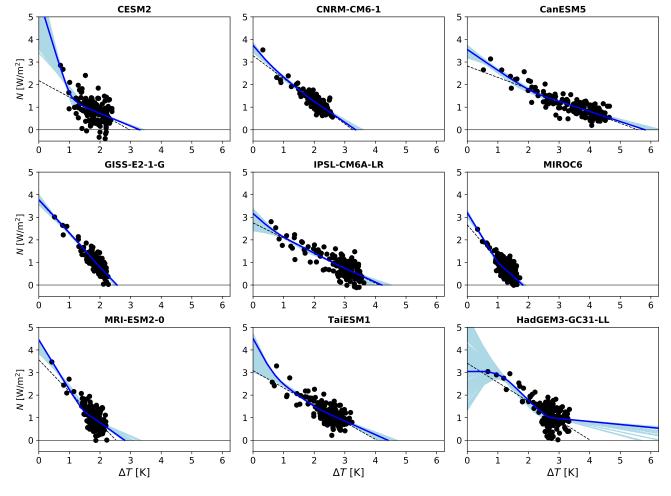


Figure S4. Similar figure as above, but using the abrupt-0p5xCO2 experiment. This experiment has negative responses, but the signs are flipped when performing the estimation and plotting.

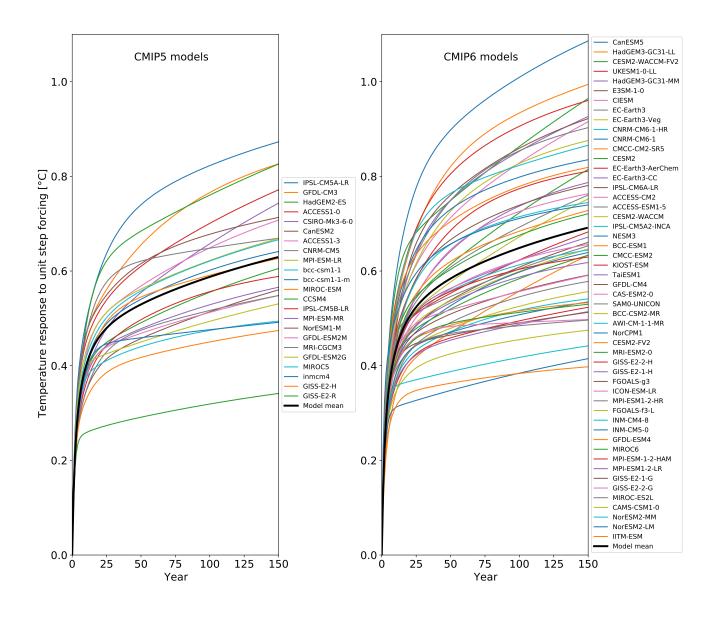


Figure S5. Temperature responses to unit-step forcing. Legend is sorted by the response in year 150. If the temperature responses are strong (weak) it may be because they compensate for weak (strong) forcing estimates.

niClim_4xCO2	niClim_histall
*	proministan
1	-
1	-
1	-
1	1
1	-
1	3
1	1
1	3
1	-
2	3
1	3
5	3
1	3
1	1
1	-
2	6
1	-
1	-
18	10
	$ \begin{array}{c} 1 \\ 1 \\ 1 \\ 2 \\ 1 \\ 5 \\ 1 \\ 1 \\ 2 \\ 1 \\ 1 \\ 2 \\ 1 \\ $

 Table S5.
 Number of members used in this study to compute fixed-SST forcing.

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	$ au_1$	$ au_2$	$ au_3$	$-\lambda_1$	$-\lambda_2$	$-\lambda_3$	b_4	F4x	T4x
ACCESS-CM2	2.57	25.28	139.03	1.58	0.60	0.62	1.63	8.93	9.98
ACCESS-ESM1-5	2.63	14.26	324.14	1.41	1.02	0.46	0.37	7.42	9.40
AWI-CM-1-1-MR	1.17	5.99	87.70	1.72	1.38	1.07	0.58	8.62	6.42
BCC-CSM2-MR	1.11	7.18	184.44	1.93	1.25	0.88	0.11	7.74	6.30
BCC-ESM1	2.72	19.25	337.09	1.32	0.94	0.75	0.02	6.96	6.96
CAMS-CSM1-0	1.87	10.32	131.09	2.07	1.91	1.61	0.09	8.92	4.67
CAS-ESM2-0	1.43	8.93	81.05	2.06	1.07	0.85	0.87	8.81	7.11
CESM2	1.38	6.93	291.55	1.80	1.11	0.44	0.06	9.22	12.15
CESM2-FV2	1.15	6.14	381.16	4.43	0.93	0.35	0.12	10.78	13.02
CESM2-WACCM	1.13	5.75	287.90	2.11	1.17	0.49	0.20	9.01	10.97
CESM2-WACCM-FV2	1.03	5.54	427.24	-0.00	1.00	0.40	0.10	6.45	11.74
CIESM	2.80	16.64	257.81	1.05	0.91	0.51	0.34	9.12	12.63
CMCC-CM2-SR5	1.40	8.28	80.47	0.79	1.33	0.98	0.90	7.37	7.26
CMCC-ESM2	1.25	6.40	105.71	1.39	1.21	1.00	0.59	8.37	7.22
CNRM-CM6-1	1.78	14.26	96.73	1.15	0.66	0.78	1.88	8.29	9.67
CNRM-CM6-1-HR	1.76	12.73	274.71	0.92	0.79	1.09	0.06	7.67	8.31
CNRM-ESM2-1	4.14	40.76	93.08	0.52	0.65	1.04	1.77	5.71	8.09
CanESM5	2.19	13.37	179.44	0.74	0.68	0.60	1.01	7.57	11.62
E3SM-1-0	1.06	9.80	114.58	2.86	0.79	0.48	0.83	9.51	11.52
EC-Earth3	2.66	26.33	107.27	1.24	0.72	0.81	0.52	7.94	8.38
EC-Earth3-AerChem	2.84	28.13	103.24	1.34	0.78	1.03	0.59	8.26	7.67
EC-Earth3-CC	1.71	12.46	80.03	1.78	0.85	0.71	0.67	9.15	8.63
EC-Earth3-Veg	2.27	20.38	88.11	1.35	0.77	0.75	0.63	8.52	8.80
FGOALS-f3-L	1.15	6.13	122.70	1.78	1.71	1.08	0.61	9.38	6.33
FGOALS-g3	2.82	15.44	154.88	1.51		0.97	0.81	7.92	6.17

 Table S6.
 Parameters estimated from abrupt-4xCO2 experiments, part I.

	$ au_1$	$ au_2$	$ au_3$	$-\lambda_1$	$-\lambda_2$	$-\lambda_3$	b_4	F4x	T4x
GFDL-CM4	1.96	10.47	175.61	1.72	1.15	0.53	1.02	9.03	9.20
GFDL-ESM4	1.14	5.75	82.88	2.05	1.30	1.36	1.26	8.01	5.32
GISS-E2-1-G	1.16	5.95	341.47	1.45	1.64	1.27	0.44	8.01	5.55
GISS-E2-1-H	1.04	7.26	84.97	1.79	1.23	1.06	1.04	8.16	6.29
GISS-E2-2-G	1.42	10.42	431.60	1.60	1.53	1.68	1.13	7.51	4.72
GISS-E2-2-H	1.33	7.51	83.07	1.16	1.47	1.36	0.85	7.06	5.26
HadGEM3-GC31-LL	2.97	26.13	357.17	1.03	0.57	0.58	0.50	8.03	11.47
HadGEM3-GC31-MM	1.53	15.15	239.48	1.35	0.60	0.65	0.18	8.59	10.92
ICON-ESM-LR	1.31	7.15	397.08	1.73	1.38	0.66	0.29	9.71	8.59
IITM-ESM	1.05	5.37	126.92	2.49	1.92	1.76	1.13	9.85	4.82
INM-CM4-8	1.17	6.53	80.86	2.12	1.89	1.21	0.01	6.58	3.75
INM-CM5-0	1.06	6.38	161.14	1.78	1.92	1.12	0.03	6.56	4.03
IPSL-CM5A2-INCA	1.37	13.05	83.13	1.43	0.84	0.75	1.59	7.39	7.80
IPSL-CM6A-LR	1.08	10.73	93.40	2.07	0.80	0.64	1.17	9.28	9.54
KIOST-ESM	1.05	5.75	285.83	1.30	1.37	0.71	0.02	7.43	7.39
MIROC-ES2L	1.59	9.32	209.35	1.81	1.29	2.29	0.99	8.32	4.89
MIROC6	1.96	13.05	297.24	1.53	1.31	1.77	0.39	7.61	4.94
MPI-ESM-1-2-HAM	1.45	9.67	245.61	1.85	1.59	1.02	0.42	9.33	6.45
MPI-ESM1-2-HR	2.12	10.75	98.71	1.57	1.95	0.99	1.00	8.52	6.31
MPI-ESM1-2-LR	1.87	10.23	257.28	1.92	1.47	1.19	0.10	9.74	6.30
MRI-ESM2-0	1.00	5.26	190.72	1.41	1.41	0.91	0.46	7.71	6.64
NESM3	1.18	11.56	80.78	1.46	0.67	0.87	1.64	9.61	9.24
NorCPM1	1.00	5.02	89.10	0.77	1.83	0.83	1.30	7.46	6.68
NorESM2-LM	1.95	18.67	280.80	2.45	nan	0.94	0.05	9.98	5.76
NorESM2-MM	2.13	12.92	255.69	2.06	nan	1.33	0.03	9.15	5.10
SAM0-UNICON	3.80	26.08	278.66	1.33	nan	0.83	0.12	8.76	8.04
TaiESM1	1.29	8.44	291.73	2.04	0.99	0.73	0.12	9.76	9.28
UKESM1-0-LL	2.03	15.28	96.48	1.04	0.69	0.61	1.64	8.20	11.10
Model mean	1.74	12.20	192.98	1.61	1.17	0.93	0.65	8.36	7.86
		-							

Table S7.Parameters estimated from abrupt-4xCO2 experiments, part II.

F2x	F0p5x	F4x	F4x/F2x	F4x/F0p5x
4.56	-5.82	9.22	2.02	-1.58
4.23	-3.74	8.29	1.96	-2.22
3.69	-3.55	7.57	2.05	-2.13
3.92	-3.78	8.01	2.04	-2.12
3.98	nan	8.16	2.05	nan
3.67	nan	7.51	2.05	nan
3.36	nan	7.06	2.10	nan
3.73	-3.04	8.03	2.15	-2.64
4.23	-3.17	9.28	2.19	-2.93
3.27	-3.20	7.61	2.32	-2.38
	$\begin{array}{r} 4.56 \\ 4.23 \\ 3.69 \\ 3.92 \\ 3.98 \\ 3.67 \\ 3.36 \\ 3.73 \\ 4.23 \end{array}$	$\begin{array}{rrrr} 4.56 & -5.82 \\ 4.23 & -3.74 \\ 3.69 & -3.55 \\ 3.92 & -3.78 \\ 3.98 & nan \\ 3.67 & nan \\ 3.36 & nan \\ 3.73 & -3.04 \\ 4.23 & -3.17 \end{array}$	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

3.57

4.48

-4.45

-4.51

7.71

9.76

2.16

2.18

-1.73

-2.17

-2.21

:

Model mean3.89-3.928.182.11-4Table S8.Forcing estimates for 2x, 0.5x, 4x CO2, and forcing ratios.

MRI-ESM2-0

TaiESM1