Assessing Tropical Pacific-induced Predictability of Southern California Precipitation Using a Novel Multi-input Multi-output Autoencoder

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Abstract

We construct a novel Multi-Input Multi-Output Autoencoder-decoder (MIMO-AE) to capture the non-linear relationship of Southern California precipitation (SC-PRECIP) and tropical Pacific Ocean sea surface temperature (TP-SST). The MIMO-AE is trained on both monthly TP-SST and SC-PRECIP anomalies simultaneously. The co-variability of the two fields in the MIMO-AE shared nonlinear latent space can be condensed into an index, termed the MIMO-AE index. We use a transfer learning approach to train a MIMO-AE on the combined dataset of 100 years of output from a historical simulation with the Energy Exascale Earth Systems Model version 1 (E3SMv1) and a segment of observational data. We further use Long Short-Term Memory (LSTM) networks to assess sub-seasonal predictability of SC-PRECIP using the MIMO-AE index. We find that the MIMO-AE index provides enhanced predictability of SC-PRECIP for a lead-time of up-to four months as compared to Nino 3.4 index and the El Nino Southern Oscillation Longitudinal Index.

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Key Points:

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7	• We design a novel MIMO-AE to capture the non-linear relationships between trop-
8	ical Pacific SSTs and Southern California precipitation.
9	• We use long-short term memory models of a MIMO-AE derived index to assess
10	predictability of Southern California precipitation.
11	• MIMO-AE offers statistically significant improvement in predictive skill of South-
12	ern California precipitation on sub-seasonal scales.

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13 Abstract

We construct a novel Multi-Input Multi-Output Autoencoder-decoder (MIMO-AE) to 14 capture the non-linear relationship of Southern California precipitation (SC-PRECIP) 15 and tropical Pacific Ocean sea surface temperature (TP-SST). The MIMO-AE is trained 16 on both monthly TP-SST and SC-PRECIP anomalies simultaneously. The co-variability 17 of the two fields in the MIMO-AE shared nonlinear latent space can be condensed into 18 an index, termed the MIMO-AE index. We use a transfer learning approach to train a 19 MIMO-AE on the combined dataset of 100 years of output from a historical simulation 20 with the Energy Exascale Earth Systems Model version 1 (E3SMv1) and a segment of 21 observational data. We further use Long Short-Term Memory (LSTM) networks to as-22 sess sub-seasonal predictability of SC-PRECIP using the MIMO-AE index. We find that 23 the MIMO-AE index provides enhanced predictability of SC-PRECIP for a lead-time 24 of up-to four months as compared to Niño 3.4 index and the El Niño Southern Oscilla-25 tion Longitudinal Index. 26

27 Plain Language Summary

Traditional El Niño Southern Oscillation indices, like the Niño 3.4 index, although 28 well-predicted themselves, fail to offer reliable sub-seasonal to seasonal predictions of West-29 ern US precipitation. Here, we use a machine learning approach called a multi-input, multi-30 output autoencoder to capture the relationship between tropical Pacific and Southern 31 California precipitation and project it onto a new index, which we call MIMO-AE in-32 dex. Using machine learning based time-series predictions, we find that MIMO-AE in-33 dex offers enhanced predictability of Southern California precipitation up-to a lead time 34 of four months as compared to other ENSO indices. 35

³⁶ 1 Introduction

While El Niño-Southern Oscillation (ENSO) is a prominent predictor of precipitation over California, extracting sub-seasonal and seasonal predictability afforded from it remains a challenge (e.g. LHeureux et al., 2021; Pan et al., 2019; S. Wang et al., 2017). This was apparent during the 2015-16 Central Pacific (or Modoki) El Niño event, when California received just above average precipitation. This was in contrast to the forecast of heavy precipitation, which occurred there during the canonical (Eastern Pacific) 1982-83 and 1997-98 strong El Niño events (e.g. Cohen et al., 2017; Lee et al., 2018; LHeureux

et al., 2017). Perfect model studies with dynamical models suggest that the potential 44 predictability of Western US precipitation on sub-seasonal to seasonal timescales maybe 45 larger than the observed forecast skills of dynamical and statistical models (Becker et 46 al., 2014). Although, dynamical models capture the chaotic and non-linear nature of the 47 climate system, their predictive skill is limited by systematic model biases (largely orig-48 inating from the errors in the representation of sub-grid scale processes that grow rapidly) 49 and from complications of model initialization from sparse observations of the coupled 50 system. 51

Over California, statistical modeling suggests that tropical Pacific sea surface tem-52 peratures (TP-SSTs) offer predictability largely only for Southern California precipita-53 tion (SC-PRECIP) explaining about 20% of the variability there on seasonal to inter-54 annual timescales (e.g. Jong et al., 2016; X. Huang & Ullrich, 2017; G. Wang et al., 2021; 55 Cheng et al., 2021). However, ENSO-induced predictability of regional climate using sta-56 tistical models has largely been assessed from the linear relationship with ENSO, using 57 linear regression or singular value decomposition, ignoring the inherent non-linearity of 58 the climate system. Although, some studies have used non-linear machine learning ap-59 proaches to study ENSO associated atmospheric teleconnections (e.g. Hsieh et al., 2006; 60 Wu et al., 2005). 61

Further, traditional representations of ENSO in these linear statistical models, in-62 clude spatial averages over specific regions of the tropical Pacific like the Niño 3.4 index, 63 or use linear empirical orthogonal functions. These approaches prove to be inadequate 64 in capturing the full spectrum of spatial variability of ENSO's SST pattern and the as-65 sociated diversity of remote responses affecting regional climate predictability (e.g. Tren-66 berth & Stepaniak, 2001; Williams & Patricola, 2018). Several recent studies have ex-67 plored methods to better capture ENSO's variability, diversity and non-linearity (e.g. 68 Williams & Patricola, 2018). However, these approaches largely devise indices that rep-69 resent the oceanic or atmospheric variability over the tropical Pacific in isolation of its 70 remote teleconnections. 71

Machine learning methods, like autoencoders, allow identification of dominant non linear variability and co-variability patterns that might offer enhanced predictability. Au toencoders are artificial neural networks that regenerate the original data from efficient
 representations (encodings) of the data like principal component analysis (PCA). They,

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however, transform data to non-linear latent spaces via non-linear activation functions, 76 thus imparting the additional capability of capturing the underlying non-linear relation-77 ships within the data (e.g. Y. Wang et al., 2016; Charte et al., 2018; Masti & Bempo-78 rad, 2018). Studies show that autoencoders can better detect dominant variability pat-79 terns over other techniques, like the PCA (e.g. Y. Wang et al., 2016; Zamparo & Zhang, 80 2015; Fournier & Aloise, 2019). Some studies (e.g. Tang & Hsieh, 2003; He & Eastman, 81 2020) have also demonstrated the use of autoencoders to effectively identify modes of 82 climate variability, including those related to ENSO. 83

Further, multitask learning (MTL) solves multiple learning tasks at the same time 84 while exploiting commonalities and differences across tasks (e.g. Caruana, 1997). MTL 85 has been applied to many problems including natural language processing (Collobert & 86 Weston, 2008; Liu et al., 2017; S. Chen et al., 2021), speech recognition (Deng et al., 2013; 87 Kim et al., 2017; Toshniwal et al., 2017; Shinohara, 2016) and computer vision (Girshick, 88 2015; Devries et al., 2014; Kendall et al., 2018) to improve prediction accuracy and learn-89 ing efficiency of task-specific models. Recent studies have shown the usefulness of multi-90 input and/or multi-output networks for segmenting data and extracting useful informa-91 tion when there are multiple variables present (Raza et al., 2017; Yaguchi et al., 2020; 92 Ghifary et al., 2015). For example, Ghifary et al. (2015) used a multi-output autoencoder, 93 which they call a multi-task autoencoder (MTAE), for domain generalization. The MTAE 94 has a single input variable with multiple outputs where the input-hidden weights rep-95 resent variable shared parameters and the hidden-output weights represent domain-specific 96 parameters. MTAE learns features shared across all domains. 97

Here, we expand on the MTAE approach and construct a novel multi-input multi-98 output autoencoder (MIMO-AE) to effectively extract the most prominent shared fea-99 tures between monthly TP-SSTs and SC-PRECIP anomalies and capture their under-100 lying non-linear relationship using an Earth System Model (ESM) simulation and ob-101 servational data. Our network architecture is designed to yield a temporal index of the 102 co-variability of the two variables. We further use Long Short-term Memory (LSTM) mod-103 els to predict this monthly index, which we decode to generate predicted SC-PRECIP, 104 and evaluate its predictive skill. We show that MIMO-AE can be a powerful tool to iso-105 late important teleconnections and wield enhanced sub-seasonal regional predictability. 106

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107 1.1 Model Simulations and Data

We use a 165 years-long historical simulation of the Energy Exascale Earth Sys-108 tem Model version 1 (E3SMv1) (E3SM Project, 2018), and utilize the first 100 years of 109 the simulation for training the MIMO-AE network. E3SMv1 is found to effectively cap-110 ture temporal variability of ENSO and reproduce ENSO associated spatial SST patterns 111 when compared to observational datasets (Golaz et al., 2019), although with a larger west-112 ward extent of SST anomalies during El Nino events. It also simulates the teleconnec-113 tions of ENSO to US winter season precipitation well (Mahajan et al., 2021). We use ob-114 served precipitation data from NOAA's PRECipitation REConstruction over Land (PREC/L) 115 at 1° resolution (M. Chen et al., 2002). PREC/L is a global analysis of interpolated rain 116 gauge observations from 1948 to 2020. We use observed SSTs for the same period from 117 the Hadley Centre Global Sea Ice and Sea Surface Temperature (HadISST 1.1) dataset 118 available at a 1° resolution (Rayner et al., 2003). 119

120 2 Methodology

121 2.1 Autoencoder

An autoencoder is an unsupervised neural network that is trained to learn an identity function, a function that returns the same value as its input. It aims to efficiently compress and encode data by minimizing the reconstruction error. A simple autoencoder, shown in figure 1a, contains a hidden layer h that describes a representation of important attributes of the input (e.g. Goodfellow et al., 2016). The general autoencoder consists of two parts: an encoder and a decoder. The encoder maps input x to h by a chosen activation function f(),

$$h = f(x \cdot w_e) \tag{1}$$

where w_e are the encoder weights. The decoder then maps h to the reconstruction of x, represented by x':

$$x' = f(h \cdot w_d) \tag{2}$$

where w_d are the decoder weights.

By using a linear activation function, the single hidden layer autoencoder behaves similarly to a PCA (e.g. Bourlard & Kamp, 1988; Plaut, 2018). The number of hidden layers can also be increased to create a deep autoencoder, with the middle layer often

referred to as the bottleneck layer. Tang and Hsieh (2003) used a simple autoencoder 135 to extract the leading nonlinear mode of interannual variability of upper ocean heat con-136 tent over the tropical Pacific, with a single node bottleneck hidden layer, to reveal an 137 asymmetry in the spatial pattern between characteristic El Niño and La Niña episodes. 138 For spatio-temporal data, the temporal vectors at the bottleneck nodes are analogous 139 to principal components (PC) of PCA. The value of a temporal vector at a given time 140 t results from passing the spatial data at t through the network. The non-linear activa-141 tion functions imply that the spatial pattern derived from reconstructing the data us-142 ing the decoder varies with the magnitude of the temporal vector at t, unlike PCs which 143 yield a standing spatial pattern (e.g. Tang & Hsieh, 2003). 144

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2.1.1 MIMO-AE

Figure 1b illustrates our MIMO-AE architecture designed to extract the non-linear 146 relationship between TP-SSTs and SC-PRECIP on monthly timescales. The encoder con-147 sists of two separate input temporal vectors (TP-SST and SC-PRECIP) that are passed 148 through two hidden layers before concatenating and passing through a single hidden node. 149 The input (and output) vectors represent SST anomalies at each grid box within the boxed 150 domain over tropical Pacific (20°N to 20°S, 120°E to 70°W) and precipitation anoma-151 lies over each grid box in the boxed domain over Southern California (32°N to 35°N, 120°W 152 to 114°W) (Figure 1b). The first hidden layer, consisting of 50 nodes each for the two 153 variables, can be thought of as feature extraction of the original data. The next hidden 154 layer then shrinks the data to 10 hidden nodes, again separately for the two variables, 155 in order to reduce the computational complexity of data. This data is then passed to a 156 single hidden node that is shared by the two input variables. This hidden node repre-157 sents the shared non-linear latent structure of both the SST and precipitation vectors. 158 The vectors are then split back into two from the shared hidden node and passed through 159 the decoder, which is identical in structure (with different weights) to the encoder, to 160 reconstruct back to the original shape in the output layer. We use the "tanh", or hyper-161 bolic tangent, activation function for all the hidden layers. 162

We performed several iterations of the network design with different number of hidden layers, neurons and activation functions and chose the MIMO-AE architecture (described above) that exhibited a low value of the training loss function as well as explaining a large fraction of the variability of SC-PRECIP. The loss is calculated by using a

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¹⁶⁷ mean squared error (MSE) using the following equation:

$$MSE = \frac{1}{N} \sum_{i} (P_i - T_i)^2 \tag{3}$$

where P_i is the predicted value of the reconstructed data at point *i* and T_i is the true 168 value of the data at point i, which here is the original input data. The input variables 169 are scaled using a min-max scaler before training is performed. MIMO-AE was trained 170 on first 100 years of the E3SM simulation data for 100 epochs with an AdaGrad loss op-171 timizer using tensorflow on one CPU node on the National Energy Research Scientific 172 Computing Center's (NERSC) Cori super computer. The training loss for the scaled TP-173 SST reconstruction (orange) and SC-PRECIP (blue) are shown in figure 1c. We refer 174 to this MIMO-AE network as MIMO-AE-E3SM, hereafter. 175

Figure 1d and e show the R^2 values (fraction of variance explained) between the 176 reconstructions from the MIMO-AE and the original data for the 100 years of training 177 data for TP-SSTs and SC-PRECIP respectively. The MIMO-AE explains more than 80% 178 of the variability of Southern California for most grid points and about 20% of the vari-179 ability of TP-SSTs over most of the domain. The relatively weaker explained variabil-180 ity of MIMO-AE over tropical Pacific is an artefact of our network design preference. We 181 ad-hocly chose a network that explained a larger fraction of the variability of SC-PRECIP, 182 while also capturing the tele-connections to TP-SST, since our goal was largely to as-183 sess predictability of SC-PRECIP here. Likewise, a network where TP-SST variability 184 dominates can also be picked if needed. In the future, we plan to make the network de-185 sign more systematic, for example, by adding a penalizing term for explained variabil-186 ity of each field in the loss function. 187

We refer to the temporal vector of the single node bottleneck layer that represents 188 the dominant non-linear mode of co-variability of TP-SSTs and SC-PRECIP as the MIMO-189 AE index, hereafter. We apply the MIMO-AE-E3SM trained on 100 years of E3SM his-190 torical simulation on the latter 65 years of the run. As a form of transfer learning, we 191 combine the first 100 years of the E3SM simulation with 32 years of observational data 192 (1948-1979) to train another MIMO-AE network for application to remaining observa-193 tional data (1980-2020), termed MIMO-AE-OBS. Although, we find that using MIMO-194 AE-E3SM on observational data imparted similar predictability skills (Results section) 195 as MIMO-AE-OBS for observational data. Ham et al. (2019) also used a transfer learn-196 ing approach, whereby, they train a convolutional neural network (CNN) with global SST 197

and heat content data from historical simulations of 21 CMIP5 models. They retrained the network with observational data but with weights initialized from the CMIP5-trained network, which was then used to predict the observed Niño 3.4 index. While we have not investigated their approach to transfer learning in our exploratory study of MIMO-AE here, we plan to apply this and other transfer learning methods to MIMO-AE in the future.

2.2 LSTM

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To study predictability, we also train long-short term memory (LSTM) recurrent 205 neural networks as our time series prediction models. LSTMs are a special kind of re-206 current neural network that learn long term dependencies whose cells are constructed 207 with internal mechanisms called "gates" that control the flow of information through the 208 cell (Hochreiter & Schmidhuber, 1997). There are three types of gates: forget, input and 209 output. These allow for the model to learn what features in the data are important to 210 keep or throw away before passing it down the line to the next cell. LSTM models have 211 recently been shown to perform better at time series prediction over linear models for 212 Niño 3.4 index (A. Huang et al., 2019; Mu et al., 2020; Broni-Bedaiko et al., 2019; Gupta 213 et al., 2020), and we use them here to evaluate the predictability of MIMO-AE index as 214 well as SC-PRECIP. 215

LSTM models are constructed individually for each of the time series of MIMO-216 AE index, Niño 3.4 index, ELI and regionally averaged SC-PRECIP anomalies using the 217 first 100 years of the E3SM data. We train separate LSTMs for the above listed time se-218 ries using the first 32 year segment (1948-1979) of observational dataset used. Given a 219 predicted value of MIMO-AE index, predicted SC-PRECIP (and TP-SSTs) can be con-220 structed by passing the index through the decoder of MIMO-AE. We optimize the LSTM 221 architecture by choosing the number of hidden nodes that maintains a low training loss 222 for all indices, found to be 100 nodes. We train separate LSTMs for each of the forecast 223 lead times ranging from 1 to 12 months and evaluate their predictive skill on the remain-224 ing 65 years of E3SM data and the 41 years of observational data. 225

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226 3 Results

227 **3.1 MIMO-AE**

Figure 2a shows the three-month moving average of the standardized MIMO-228 AE index time-series for a segment (last 40 years, 1974-2013) of the 65 years of the E3SM 229 testing data. MIMO-AE index was generated by passing the TP-SST and SC-PRECIP 230 data through the MIMO-AE network trained on the prior 100 years of simulation. Also, 231 shown are the three-month moving average time series of standardized Niño 3.4 index, 232 ELI and domain averaged SC-PRECIP. The correlations of each time-series against do-233 main averaged SC-PRECIP is also listed for the smoothed data. Fig. 2b shows the same 234 but for a segment of the observational data (1980-2019) using MIMO-AE-OBS. To re-235 iterate, MIMO-AE index for observations is computed by passing the observed data through 236 the MIMO-AE-OBS network. 237

For both E3SM and observations, the correlation between SC-PRECIP and MIMO-238 AE index is higher than that between SC-PRECIP and Niño 3.4 index or ELI, given that 239 precipitation data is fed in the generation of MIMO-AE index and MIMO-AE explains 240 a large fraction of the SC-PRECIP variability. The correlation between MIMO-AE and 241 both Niño 3.4 index and ELI is weak both for E3SM (0.35 and 0.27 respectively) and 242 observational data (0.43 and 0.39 respectively). However, the correlation between MIMO-243 AE and Niño 3.4 is higher than the correlation between SC-PRECIP and Niño 3.4. The 244 above correlations are indicative of the shared variability captured by MIMO-AE. Fur-245 ther, in observational data, all indices spike during the 1982-83 and 1996-97 El Niño events, 246 but only the Niño 3.4 peaks during the 2015-16 El Niño event. Thus, MIMO-AE also 247 categorizes the 2015/2016 event weaker than the Niño 3.4, similar to the ELI index (Williams 248 & Patricola, 2018). 249

Fig. 2c and d show the probability density functions of the Niño 3.4, ELI, MIMO-250 AE index and domain averaged SC-PRECIP for E3SM testing data and observations. 251 While the Niño 3.4 index tends to be symmetric, the ELI is skewed towards the left (west-252 wards), both for E3SM data and observations as noted by Williams and Patricola (2018), 253 with a thicker right tail (eastwards). ELI is a non-linear SST-based index and represents 254 the average longitude of deep convective activity over the tropical Pacific governing the 255 Rossby wave trains originating from there. MIMO-AE which represents the shared co-256 variability between the TP-SSTs and SC-PRECIP also shows a leftwards skewed distri-257

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bution with a larger number of strong positive events than strong negative events. The 258 leftwards skewness may follow from the density function of precipitation that is natu-259 rally skewed leftwards, even for monthly average data (e.g. Mahajan et al., 2012). But, 260 it could also be reflective of the skewed relationship between TP-SSTs and SC-PRECIP, 261 with some events over the tropical Pacific triggering extreme positive anomalous events 262 in SC-PRECIP. While, co-variability between the two remains weaker during strong neg-263 ative SC-PRECIP anomalous events. The skewness of MIMO-AE index is noted to be 264 stronger in E3SM than in observations. 265

Fig. 2e and f show the composite of reconstructions of TP-SST and SC-PRECIP 266 during the strongest 10 positive and negative monthly MIMO-AE index values for both 267 the E3SM testing data. Strong (negative) SC-PRECIP anomalies during those events 268 are associated with strong positive (negative) anomalies in central tropical Pacific and 269 northeast tropical Pacific and weak positive (negative) anomalies in the Eastern trop-270 ical Pacific. Similar patterns are noted for the strongest positive and negative MIMO-271 index values for reconstructions of TP-SST when observation data is passed through the 272 MIMO-AE network (Fig. 2f). 273

Fig. 2g shows the December to February average reconstructions for the three strongest 274 El-Niño events (1981-82, 1997-98, 2015-16) in observations. It is apparent that the spa-275 tial patterns of these reconstructions are not standing - more clearly here than the com-276 posite plots (Fig. 2e,f) - with varying contour patterns of SST anomalies for each of the 277 three events. The 2015-16 El Niño events is associated with weak positive anomalies in 278 the MIMO-AE latent space for SC-PRECIP and TP-SST over much of tropical Pacific. 279 In contrast, the 1981-82 and 1997-98 events are associated with strong positive anoma-280 lies both in SC-PRECIP and TP-SST, with the stronger 1997-98 SC-PRECIP anoma-281 lies associated with stronger TP-SST anomalies and varied contour delineations. When 282 a separate MIMO-AE network is trained on all of the observation data (1948-2020) and 283 with no E3SM data, the spatial pattern of the TP-SST during 1981-82 and 1997-98 ex-284 hibits a narrow band of strong anomalies over equatorial Pacific including coastal East-285 ern Pacific (not shown), illustrating the influence of E3SM model bias in MIMO-AE-OBS. 286 We plan to explore ways to reduce the influence of model bias in MIMO-AE-OBS, for 287 example by appropriately weighing the observational data used during training in the 288 future. 289

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3.2 Predictability of MIMO-AE Index

We use LSTM models to predict the MIMO-AE index for lead times of 1 to 12 months. 291 Figure 3a shows the predictive skill of the LSTMs to predict the MIMO-AE index for 292 the 65 years of E3SM testing data. The predictive skill is computed as the correlation 293 between the LSTM predicted value and the true value of the MIMO-AE index when data 294 is passed through the network. The predictive skill of Niño 3.4 index and ELI index us-295 ing LSTMs are also shown. One standard deviation spread, computed using the Fisher 296 transformation, are shown as color shadings. The MIMO-AE index exhibits a lower pre-297 dictive skill than both the Niño 3.4 and the ELI index at all lead times longer than two 298 months. This is likely due to the presence of noisy precipitation data in MIMO-AE, which 299 demonstrates poor temporal auto-correlations on these time scales (e.g. Mahajan et al., 300 2012), offering little predictive skill. 301

This is evident in the Figure 3a, which also shows the predictive skill of domain 302 averaged SC-PRECIP using LSTMs, and serves as a baseline for evaluation of predic-303 tive skill. Precipitation shows a high skill at a lead time of one month like the other in-304 dices, but offers poor predictive skill at longer lead times. MIMO-AE index provides more 305 predictive skill than precipitation itself for two and three month lead times, likely due 306 to the inclusion of TP-SSTs, which have higher predictive skill due to the thermal in-307 ertia of the oceanic mixed layer. But, MIMO-AE index provides poor skill for longer lead 308 times. Figure 3b shows the LSTM skills as a function of the calendar month when the 309 prediction is initialized for all indices and generally reflect Fig. 3a, while also showing 310 the well-known spring predictability barrier associated with Nino3.4 and ELI. 311

The above results hold for the observational data too, with the the MIMO-AE in-312 dex exhibiting poorer predictive skill when compared to Niño 3.4 index and ELI on these 313 monthly time scales. Similar to E3SM data, MIMO-AE index demonstrates weaker skill 314 at 2-months lead times and longer, while precipitation time series exhibits no skill at lead 315 times longer than one month irrespective of the initial month of predictions (Figure 3d). 316 Although, the skill of predicting MIMO-AE index is substantially higher than that of 317 predicting SC-PRECIP. 318

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3.3 SC-PRECIP Predictability from MIMO-AE Index

To evaluate the predictability of SC-PRECIP using the MIMO-AE index, we pass 320 the predicted MIMO-AE index values through the decoder part of the MIMO-AE to con-321 struct spatio-temporal predictions of SC-PRECIP anomalies. Figure 3e shows the skill 322 of predicted SC-PRECIP. The predicted spatial pattern of the SC-PRECIP constructed 323 by the MIMO-AE decoder is domain averaged to compute predictive skill. For the Niño 324 3.4 and ELI, we predict domain average SC-PRECIP from LSTM predicted values of the 325 indices by using linear regression models (also shown). The linear regression models were 326 constructed using the training data for E3SM and observations separately. MIMO-AE 327 generated predicted precipitation exhibits stronger skill than other indices for lead times 328 of up to 3-months. 329

However, MIMO-AE index's skills at lead times of one to three months are statis-330 tically indistinguishable from that of SC-PRECIP index at the 95% confidence level based 331 on a two-tailed Student's t-test of the Fisher transformations of the correlations. To ac-332 count for the auto-correlation in the time-series', we use effective sample size for the null 333 hypothesis tests. We calculate this effective sample size using the following equation $N_{effective} =$ 334 $\frac{N}{1+2\sum_{i}^{N}\gamma_{i}^{2}}$ where γ_{i} is the auto-correlation of our SC-PRECIP time series at lag *i* and 335 N is our total number of samples (Livezey & Chen, 1983). Although, the improved skill 336 is a significant improvement over that of Niño 3.4 index and ELI. MIMO-AE skills are 337 weaker and also indistinguishable from that of SC-PRECIP for longer lags, and become 338 statistically indifferent from zero at a lead time of 6-months and longer. The skill of Niño 339 3.4 and ELI is statistically insignificant at all lead times on these monthly scales. The 340 enhanced predictive skill of precipitation from MIMO-AE up to a lead time of 3 months 341 is noted for almost all initialization calendar months of the year as compared to other 342 indices (Figure 3f). 343

Enhanced predictive skill of MIMO-AE of SC-PRECIP is also noted for the 41 years of observation testing data (Figure 3g). The improvement in MIMO-AE skill as compared to other indicies is statistically significant at two to four months lead times at the 95% confidence level. The high skill at 1-month lead time is statistically indifferent from that of SC-PRECIP. And, the skills are statistically zero for 6-months lead time and longer. Also, the enhanced skill of MIMO-AE is noted for almost all initialization calendar months of the year (Figure 3h). Similar to E3SM, the Niño 3.4 index and ELI demonstrate weak

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skill at all lead month lengths on monthly scales, although they are statistically differ-351 ent from zero for 1-month and 2-month lead times. This is consistent with other stud-352 ies (e.g. LHeureux et al., 2021; Pan et al., 2019; S. Wang et al., 2017) that find poor skill 353 from ENSO on noisier sub-seasonal time scales over Western US - largely due to atmo-354 spheric noise - in spite of significant correlations between SC-PRECIP and Niño 3.4 in-355 dex on smoother seasonal and inter-annual time scales in observational data (e.g. Jong 356 et al., 2016; X. Huang & Ullrich, 2017; G. Wang et al., 2021; Cheng et al., 2021, also Fig. 357 2b). 358

359 4 Summary and Discussion

In a novel approach, we apply MIMO-AE to extract the non-linear relationships 360 between TP-SST and SC-PRECIP on monthly scales and find it to be a powerful tool 361 to enhance sub-seasonal regional predictability. We design the network to yield a tem-362 poral index of the projection of these two data sets on the inherent non-linear space of 363 the network. We use LSTMs of the MIMO-AE index to assess the predictability of SC-364 PRECIP afforded by MIMO-AE on monthly time scales. LSTM-predicted values of MIMO-365 AE index are decoded using the MIMO-AE decoder to yield predicted SC-PRECIP. We 366 find that the MIMO-AE index offers statistically significant improvements in predictive 367 skill of SC-PRECIP up to a lead time of up to four months for both E3SM and obser-368 vations, as compared to that imparted by both Niño 3.4 and ELI. 369

Studies (e.g. LHeureux et al., 2021; S. Wang et al., 2017; G. Wang et al., 2021; Cheng 370 et al., 2021) suggest enhanced sub-seasonal and seasonal predictability of Western US 371 precipitation from atmospheric variables; like geopotential heights, upper level zonal winds, 372 moisture transport, etc.; as well as Northern Pacific SSTs. While we have only utilized 373 TP-SST here for demonstrating the use of multi-task learning for enhanced predictive 374 skills, we plan to incorporate additional variables in the future within the MIMO-AE frame-375 work. Further, atmospheric noise is often associated with poor predictability of regional 376 climate induced by modes of climate variability on seasonal timescales (e.g. S. Wang et 377 al., 2017; Cheng et al., 2021). We plan to explore techniques, like de-noising autoencoders, 378 that account for the presence of noise in data and the modeled system and may allow 379 for the extraction of predictability through the atmospheric noise on seasonal and longer 380 time scales. Also, we train our MIMO-AE here using a historical simulation from E3SMv1, 381 which inherits E3SM's model bias. In the future, we plan to use multi-model simulations 382

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from the CMIP6 archive and use Bayesian and other transfer learning approaches to weight the available observations appropriately while training network architectures. We also plan to condense the MIMO-AE and LSTMs into one combined MIMO-AE-LSTM network to account for spatial and temporal variability simultaneously to assess predictability in a more coherent manner.

Our results demonstrate the promise of multi-task learning to enhance predictabil-388 ity afforded by remote teleconnections, supporting a focused exploration of other per-389 tinent multi-task and multi-modal methods, like multi-task CNNs for such purposes. Dy-390 namical models exhibit more skill at predicting tropical SSTs than precipitation. It would 391 be interesting to explore hybrid models that utilize dynamical models predicted trop-392 ical SSTs with MIMO-AE-like networks that extract non-linear remote teleconnections 393 to make regional climate predictions. Further, machine learning models have demonstrated 394 significantly more skill at seasonal and multi-annual predictions of tropical SSTs than 395 dynamical models (e.g. Ham et al., 2019). Combining such networks with multi-task learn-396 ing methods provides the potential to further enhance predictability of regional climate. 397

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5.1 Data Availability Statement

The E3SMv1 data used in this study is freely available through the Earth System Grid Federation (ESGF) distributed archives via https://doi.org/10.1029/2018MS001603 and is available through the ESGF interface https://esgf-node.llnl.gov/projects/ e3sm/ (E3SM Project, 2018).

- ⁴¹⁷ Observational SST data from the HadISST 1.1 dataset (Rayner et al., 2003) can
- 418 be downloaded from the web at https://www.metoffice.gov.uk/hadobs/hadisst/.
- ⁴¹⁹ Observed precipitation data from NOAA's PREC/L (M. Chen et al., 2002) can also be
- found open access at https://psl.noaa.gov/data/gridded/data.precl.html.

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Figure 1. Network architecture. A simple autoencoder architecture (a), MIMO-AE architecture (b), training losses for MIMO-AE over 100 epochs using scaled data (c), and the average R^2 between the MIMO-AE reconstructed and original input data for Southern California precipitation (d) and Tropical Pacific SST (e). We note that the connections between neurons in (b) are shown selectively for clarity and in actuality all neurons are connected with every neuron in the adjacent layers.



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from domain average SC-PRECIP, MIMO-AE index, ELI and Niño 3.4 index for E3SM testing data (f); and observational testing data (h). Cross markings indicate tion of the correlation coefficients. Predictive skill of LSTMs as a function of initialization calendar month and forecast lead time from domain average SC-PRECIP, SC-PRECIP (black) at forecast lead times of 1 to 12 months for E3SM testing data (a); and observational testing data (c). Shading represents one standard deviaconfidence level. Predictability of SC-PRECIP using MIMO-AE. Predictive skill of MIMO-AE index (blue), Niño 3.4 index (orange) and ELI (green) at predicting Predictability of MIMO-AE index. Predictive skill of LSTMs of MIMO-AE index (blue), Niño 3.4 index (orange), ELI (green) and domain averaged domain averaged SC-PRECIP at forecast lead times of 1 to 12 months for E3SM testing data (e); and observational testing data (g) Shading represents one standard deviation of the correlation coefficients. Predictive skill of domain average SC-PRECIP as a function of initialization calendar month and forecast lead time MIMO-AE index, ELI and Niño 3.4 index for E3SM testing data (b); and observational testing data (d). Cross markings indicate values significant at the 95% values significant at the 95% confidence level. Figure 3.

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