

Using ARMAX models to determine the drivers of 40-150 keV GOES electron fluxes

Laura E. Simms¹, Natalia Yu Ganushkina², Max van de Kamp², Michael W. Liemohn³, and Stepan Dubyagin²

¹Department of Physics, Augsburg University

²Finnish Meteorological Institute

³University of Michigan-Ann Arbor

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Abstract

We investigate the drivers of 40-150 keV hourly electron flux at geostationary orbit (GOES 13) using ARMAX (autoregressive moving average transfer function) models which remove the confounding effect of diurnal cyclicity and allow assessment of each parameter independently of others. By taking logs of flux and predictor variables, we create nonlinear models. While many factors show high correlation with flux (substorms, ULF waves, solar wind velocity (V), pressure (P), number density (N) and electric field (Ey), IMF Bz, Kp, and SymH), the ARMAX model identifies substorms as the dominant influence at 40-75 keV and over 20-12 MLT, with little difference seen between disturbed and quiet periods. Also over 40-75 keV, Ey has a modest effect: positive over 20-12 MLT but negative over 13-19 MLT. Pressure shows some negative influence at 150 keV. Hourly ULF waves, Kp, and SymH show little influence when other variables are included. Using path analysis, we calculate the total sum of influence, both directly and indirectly through the driving of intermediate parameters. Pressure shows a summed direct and indirect influence nearly half that of the direct substorm effect, peaking at 40 keV. N, V, and Bz, as indirect drivers, are equally influential. Neither simple correlation nor neural networks can effectively identify drivers. Instead, consideration of actual physical influences, removing cycles that artificially inflate correlations, and controlling the effects of other parameters using multiple regression (specifically, ARMAX) gives a clearer picture of which parameters are most influential in this system.

1 **Using ARMAX models to determine the drivers of**
2 **40-150 keV GOES electron fluxes**

3 **L. E. Simms^{1,2}, N. Yu. Ganushkina^{1,3}, M. van de Kamp³, M. Liemohn¹, S.**
4 **Dubyagin³**

5 ¹University of Michigan, Ann Arbor, USA

6 ²Department of Physics, Augsburg University, Minneapolis, USA

7 ³Finnish Meteorological Institute, Helsinki, Finland

8 **Key Points:**

- 9 • Substorms, as measured by *AE*, are the strongest direct influence on 40-150 keV
10 electron flux
11 • Of the possible indirect drivers *N*, *V*, *Bz* show fairly equal influence on flux
12 • An ARMAX model removes diurnal cyclicality and allows a more accurate assess-
13 ment of the correlations

Corresponding author: L. Simms, laurasim@umich.edu

14 Abstract

15 We investigate the drivers of 40-150 keV hourly electron flux at geostationary orbit (GOES 13) using ARMAX (autoregressive moving average transfer function) models which remove the confounding effect of diurnal cyclicity and allow assessment of each parameter independently of others. By taking logs of flux and predictor variables, we create nonlinear models. While many factors show high correlation with flux (substorms, ULF waves, solar wind velocity (V), pressure (P), number density (N) and electric field (E_y), IMF B_z , Kp , and $SymH$), the ARMAX model identifies substorms as the dominant influence at 40-75 keV and over 20-12 MLT, with little difference seen between disturbed and quiet periods. Also over 40-75 keV, E_y has a modest effect: positive over 20-12 MLT but negative over 13-19 MLT. Pressure shows some negative influence at 150 keV. Hourly ULF waves, Kp , and $SymH$ show little influence when other variables are included. Using path analysis, we calculate the total sum of influence, both directly and indirectly through the driving of intermediate parameters. Pressure shows a summed direct and indirect influence nearly half that of the direct substorm effect, peaking at 40 keV. N , V , and B_z , as indirect drivers, are equally influential. Neither simple correlation nor neural networks can effectively identify drivers. Instead, consideration of actual physical influences, removing cycles that artificially inflate correlations, and controlling the effects of other parameters using multiple regression (specifically, ARMAX) gives a clearer picture of which parameters are most influential in this system.

34 Plain Language Summary

35 Satellites may experience damaging surface charging due to high energy electrons present in the radiation belts. In this study, we explore the various factors that may influence these electron populations. We use an ARMAX statistical model (autoregressive moving average transfer function) that removes the confounding effect of diurnal cyclicity and allows assessment of each variable independently of others. Substorms, which inject electrons into the magnetosphere, are found to be the strongest influence, with most of their effect seen near local midnight. The electric field and pressure of the solar wind also show moderate effects. Not all variables that show high single variable correlations retain this influence in multivariate analyses. Kp and $SymH$, two indices of geomagnetic activity are highly correlated with electron levels in the magnetosphere, but show little influence in models controlling for the effects of solar wind parameters. Identifying direct, physical drivers, removing cycles that artificially inflate correlations, and controlling the effects of other parameters using multiple regression (specifically, ARMAX) gives a clearer picture of which parameters are most influential in this system.

49 1 Introduction

50 Geostationary/geosynchronous orbit (GEO) is highly populated with active satellites (<http://www.unoosa.org/oosa/osoindex/>) that can experience damaging surface charging due to high energy electrons present in the radiation belts (e.g., Lam et al., 2012; Loto'aniu et al., 2015; Koons et al., 2000; Choi et al., 2011; Matéo-Vélez et al., 2018). These and other studies suggest that surface charging is a function of factors in the space environment, including solar and geomagnetic activity, electron and ion flux magnitudes, and particle energy spectrum hardness. Charging events may also be more likely when the satellite is in the Earth's shadow (eclipse). Surface charging events often occur when there are increased electron fluxes at 10 - 50 keV (kilo electronvolt), and < 100 keV electrons may be more responsible for the most rapid surface charging events than electrons at higher energies (M. F. Thomsen et al., 2013; Matéo-Vélez et al., 2018). The abundance of these electrons fluctuates on time scales of minutes and also shows high spatial variability over the magnetosphere. For this reason, daily/orbit averaging misses much of the behavior of these electrons. Moreover, even moderate storms are not necessary for electron en-

64 hancements in this energy range, with many surface charging events detected during low
65 to moderate substorm activity and no direct dependence on substorm strength (Matéo-
66 Vélez et al., 2018; Ganushkina et al., 2021).

67 A better understanding of keV electron flux behavior is needed, including details
68 of how fluxes are driven and by what parameters. While a prediction model may hint
69 at the drivers and mechanisms, no matter how well it may forecast, it is not a valid tool
70 for effectively testing hypotheses about physical drivers. Hypothesis testing is best done
71 with statistical tools developed specifically for this. Regression is one such tool, with mul-
72 tiple regression being the more appropriate test if multiple drivers should be considered
73 simultaneously. However, as the method of regression can also just as easily be used to
74 create linear combination prediction models, there is a danger that the testing of hypothe-
75 ses will be confused with mere prediction equation production. This mistake should be
76 avoided. The ARMAX method (autoregressive moving average transfer functions), which
77 we discuss below, is a refinement of regression that allows the modelling of time series
78 behavior before the testing of input parameters. This will reduce possible spurious cor-
79 relations that can occur if both dependent and independent variable time series cycle or
80 trend simultaneously. Further, possible driving parameters to be tested should be cho-
81 sen based on theoretical considerations (i.e., what the physical relationships might be)
82 rather than just on what variables happen to have the highest correlation.

83 MeV (mega electronvolt) electron fluxes at GEO have been more extensively stud-
84 ied and may show high overall correlations with solar wind parameters when daily av-
85 eraged (e.g., Blake et al., 1997), although the hourly response may be much lower (Simms
86 et al., 2022). Solar wind speed is often cited as the most important driver (Paulikas &
87 Blake, 1979; Li et al., 2001), although the relationship is complex (Reeves et al., 2011)
88 and, for example, Lyatsky and Khazanov (2008) and Balikhin et al. (2011) have shown
89 that the solar wind density is most associated with MeV electron variations. However,
90 the direct influence of many solar wind drivers on even MeV electron flux is still unclear,
91 both because much of the solar wind influence may not be direct but instead mediated
92 by waves and electron injections following substorms (e.g., Simms et al., 2018a), and be-
93 cause simple correlations of solar wind parameters with electrons may be inflated by com-
94 mon cycles and trends if these commonalities are not removed via such methods as dif-
95 ferencing transformation or ARMAX modelling (Simms et al., 2022). For keV electrons,
96 there are even fewer simple answers as to which of the solar wind parameters drive their
97 variations.

98 Fluxes of low energy electrons have been modeled with a first principle kinetic ap-
99 proach in several ring current simulations (e.g., Harel et al., 1981; Fok et al., 2014; Ganushk-
100 ina et al., 2014; Chen et al., 2015; Jordanova et al., 2016). These models are driven by
101 different sets of solar wind, IMF (Interplanetary Magnetic Field) parameters and geo-
102 magnetic indices but the drivers are predetermined. The first principle models cannot
103 define the driving parameters themselves.

104 Empirical models can determine correlates of electron flux energies from eVs to sev-
105 eral MeVs using a variety of fitting techniques. Among them, (i) one of the earliest mod-
106 els, the NASA (National Aeronautics and Space Administration) radiation belt models
107 for electrons such as AE8 traditionally used to specify the average charged particle flux
108 for space missions (Vette, 1991), (ii) the improved AE9/SPM models (Ginet et al., 2013)
109 derived from measurements made over an extended period of time by particle detectors
110 and dosimeters on board many satellites in a variety of orbits (see Table 3 in Ginet et
111 al. (2013)), (iii) a Particle ONERA (Office National d'Etudes et de Recherches Aérospatiales/
112 French Aeronautics and Space Research Center)-LANL Electron (POLE) model (Boscher
113 et al., 2003) of energetic electron flux developed using 25 years of LANL data with in-
114 put as the year in the solar cycle, (iv) the extended POLE model known as the new In-
115 ternational Geostationary Electron model (IGE-2006) (Sicard-Piet et al., 2008) created
116 by adding the data from the Japanese spacecraft Data Relay Test Satellite (DRTS), and

117 (v) the electrons model (Roeder et al., 2005) based on Polar HYDRA (Hot Plasma An-
 118 analyzer) data proving the average flux as a function of the position in the Earth’s mag-
 119 netosphere. The models above were not parameterized on geomagnetic conditions and
 120 did not capture the MLT (Magnetic Local Time) dependence and variations on time scales
 121 of less than a day.

122 The Kp (Planetary Kennziffer) index, a simple 0-9 index as compared to the
 123 more complex variations of solar wind and IMF parameters, has been used to organize
 124 keV electron fluxes (e.g., Korth et al., 1999). Using LANL satellites data in the range
 125 from 1 eV to 40 keV at GEO, Denton et al. (2015, 2016) developed a model which pre-
 126 dicted electron flux values based on energy and local time for given values of the 3-hour
 127 Kp-index and $-V_{SW}B_z$ (the electric field of the solar wind, where V_{SW} is the solar wind
 128 speed, B_z is the z-component of the IMF), under the assumption that both Kp and the
 129 solar wind electric field are correlated with magnetosphere activity (e.g., for Kp: (Freeman,
 130 1974; M. Thomsen, 2004); for $-V_{SW}B_z$: (Akasofu, 1964; Burton et al., 1975). The Kp
 131 version of the model also provides flux values for given values of the daily F10.7 index
 132 (solar radio flux at 10.7 cm). However, while the Kp index may correlate well with flux
 133 (at least in daily averaged data), it is neither the best predictive parameter, nor what
 134 we would consider to be a physical driver of electron flux variations. Kp, as it Earth-based
 135 (measured at ground magnetometers), may not represent conditions in the magnetosphere
 136 well. It is most likely a proxy measure, representing a combination of both relevant and
 137 non-relevant correlated factors, which tells us little about which specific processes drive
 138 flux. While the ease of obtaining it might offset this drawback in prediction models, it
 139 may be nearly useless in models seeking instead to explain what drives electrons. Its 3
 140 h time cadence may also make it unsuitable even for prediction models, given that elec-
 141 tron fluxes fluctuate much more rapidly. The $-V_{SW}B_z$ measure could be an improvement
 142 over Kp as it can be obtained hourly and each is a specific physical parameter rather than
 143 a possible conglomeration of generalized response (as the Kp is). However, being a com-
 144 bination of V_{SW} and IMF B_z , it combines the effects of two possible drivers rather than
 145 studying them individually. This measure also only accounts for two possible driving pa-
 146 rameters rather than studying all possible drivers.

147 Several studies have examined the response of geosynchronous keV electron flux
 148 measured at LANL satellites to solar wind parameters. For example, Shi et al. (2009)
 149 found electron flux increases due to solar wind dynamic pressure enhancements and Li
 150 et al. (2005) and Kellerman and Shprits (2012) concluded that higher solar wind speed
 151 results in higher electron fluxes. Hartley et al. (2014) have found an effect of solar wind
 152 speed on the 30-600 keV electron density, temperature and energy density from the MAGED
 153 (MAGnetospheric Electron Detector) instrument onboard GOES (Geostationary Oper-
 154 ational Environmental Satellites) 13-15.

155 Sillanpää et al. (2017), using 5 years of GOES 13 MAGED electron flux data, fit
 156 an empirical model using both solar wind and IMF B_z to predict electron fluxes at 40,
 157 75 and 150 keV energies, after concluding that the other two IMF components and solar
 158 wind density, temperature, and pressure were of less importance. This is in line with
 159 earlier studies (e.g., Li et al., 2005; Kellerman & Shprits, 2012; Ganushkina et al., 2019).
 160 The effects of multiplicative combinations of parameters (as $-V_{SW}B_z$ used in Denton et
 161 al. (2016) were not studied and it is possible that not a single parameter but the com-
 162 bined effect of multiple driving parameters that result in the observed fast variations of
 163 the keV electrons.

164 Ganushkina et al. (2021) discovered that the AE/AL (Auroral Electrojet/Auroral
 165 Lower) indices, together with solar wind speed, provide a better model of the severe en-
 166 vironments related to surface charging of satellites by keV electrons measured by LANL
 167 (1990-2005) than do IMF B_z , Kp, and solar wind number density. Based on integral elec-
 168 tron fluxes, among 400 events of worst-case severe environments (categorized based on
 169 four criteria (Matéo-Vélez et al., 2018) of the solar wind and IMF parameters and ge-

170 omagnetic indices), 100 were in one criterion based on the measured spacecraft poten-
 171 tial and 300 in the other 3 criteria based on these electron flux measurements.

172 In recent years, multivariate approaches have been explored to refine and comple-
 173 ment physical and single variable empirical models, and to determine the main driving
 174 parameters of keV electrons. Some techniques used for predictions of mainly MeV ra-
 175 diation belt electrons include linear prediction filters (e.g., Baker et al., 1990; Rigler et
 176 al., 2004; Castillo Tibocho et al., 2021), dynamic linear models (e.g., Osthus et al., 2014),
 177 conditional mutual information (Wing et al., 2022), multiple regression (e.g., Sakaguchi
 178 et al., 2013; Simms et al., 2014, 2016, 2018a, 2018b; Stepanov et al., 2021), neural net-
 179 works (e.g., Koons & Gorney, 1991; Freeman et al., 1998; Ling et al., 2010; Simms & En-
 180 gebretson, 2020), and Nonlinear AutoRegressive Moving Average with eXogenous (NAR-
 181 MAX) inputs (e.g., Balikhin et al., 2011; Boynton et al., 2015; Balikhin et al., 2016; Boyn-
 182 ton et al., 2016).

183 GOES 13-15 40 keV electron flux data were used by Boynton et al. (2019) to de-
 184 velop a model of time series of the electron flux for each of 24 MLTs employing NAR-
 185 MAX methodology. They found that the IMF factor, a combination of IMF B_y and B_z
 186 component, (Balikhin et al., 2010; Boynton et al., 2011) $B_f(t) = B_T(t) \sin^6(\theta(t)/2)$, where
 187 $B_T(t) = \sqrt{B_y(t)^2 + B_z(t)^2}$ and $\theta = \tan^{-1}(B_y(t)/B_z(t))$, controls most of the output
 188 variance. Another important variable was determined to be the solar wind velocity. The
 189 square root of the solar wind pressure and solar wind density were also chosen by the
 190 algorithm but their contributions are small. Boynton et al. (2019) stressed that the time
 191 resolution of the parameters used in the model development influences the importance
 192 of these parameters. For comparison, the earlier study by Boynton et al. (2013), in which
 193 daily averaged 10-100 keV electron fluxes measured at LANL satellites were used, the
 194 role of southward IMF was found to be insignificant.

195 In the present study, we test the influence of several possible drivers of low energy
 196 electron flux (40-150 keV) observed by GOES 13 and GOES 16 satellites: solar wind ve-
 197 locity (V), number density (N), pressure (P), and the electric field (E_y), IMF B_z , and
 198 substorms (as measured by the AE index). We use ARMAX (autoregressive moving av-
 199 erage transfer function) models both to measure the cumulative effects and to remove
 200 common cycles and trends that may inflate correlations between variables (Simms et al.,
 201 2022). These parameters may act in combination, with influence accumulating over time.
 202 It is also possible that some variables may not influence electron flux directly but indi-
 203 rectly via other parameters. For the latter case, we develop subset models showing pos-
 204 tulated direct and indirect effects.

205 Regression can be a powerful tool for testing which drivers could have a possible
 206 controlling influence on electron flux levels. However, regression on time series data, be-
 207 cause it often violates the assumption of uncorrelated errors, can result in highly inflated
 208 hypothesis test statistics, giving the impression that certain factors may be strong drivers
 209 of flux when they are only cycling or trending in common (Simms et al., 2022). While
 210 this may not be a problem if we are using a regression model to forecast flux, it will in-
 211 validate the hypothesis tests that allow us to determine if solar wind, IMF, and substorm
 212 factors are meaningfully correlated with flux. We may also find that using more of the
 213 information present in the data (i.e., the time behavior) results in more accurate pre-
 214 dictions.

215 There are several approaches to modelling the periodic behavior of a time series.
 216 We will do so with autoregressive (AR) and moving average (MA) terms (Hyndman &
 217 Athanasopoulos, 2018; Pankratz, 1991). When chosen well, these reduce the autocor-
 218 relation in the errors of the model and fully describe the cycling behavior of the series.
 219 With this behavior effectively removed (by the introduction of these terms) the remain-
 220 ing variability in the data can be tested for its response to external factors (the indepen-
 221 dent variables). This last step results in a transfer function model (X), giving the acronym

222 ARMAX. A further assumption of this type of model is a linear relationship between re-
 223 sponse and predictor variables. To achieve this linearity, we take the logs of the variables
 224 (excepting those with both positive and negative values). This allows the use of the linear
 225 model technique (regression) to be used on what is essentially a nonlinear process.
 226 Other studies have used ARMAX modelling to predict higher energy electron fluxes in
 227 geostationary orbit, and these provide further information on this approach of describ-
 228 ing the underlying cyclical behavior of flux with AR and MA terms (Balikhin et al., 2011,
 229 2016; Boynton et al., 2015, 2016; Simms & Engebretson, 2020; Simms et al., 2022). How-
 230 ever, we note that nonlinearity was introduced into the models of Balikhin et al. (2011)
 231 with polynomial terms (square and cubic terms) instead of the logs we use here. Although
 232 this appears to be a different approach, it results in a similar description of the nonlin-
 233 ear relationships. We also note that these models may sometimes be called ARIMAX
 234 models, with the additional I conveying that the data is differenced at some time step
 235 n with a $y_t - y_{t-n}$ transformation. However, as we did not find it necessary to difference
 236 the present dataset for the full models, ARMAX without the additional I is the more
 237 descriptive acronym.

238 In this study, we extend this previous work by using the ARMAX technique to deter-
 239 mine the most influential drivers of lower energy electron flux behavior. While pre-
 240 vious studies (e.g., Balikhin et al., 2011) may choose an optimal, parsimonious set of pre-
 241 dictors that describe the variance in the dataset (e.g., through the Error Reduction Ra-
 242 tio technique), using least squares regression (as applied to an ARMA model) we are able
 243 to show the statistically significant, relative contributions of each parameter rather than
 244 reducing the model to only highlight the most essential variables. In other words, we are
 245 able to test for the inutility of certain parameters in describing flux, rather than just choos-
 246 ing those parameters that have the strongest correlation. This provides more informa-
 247 tion on the additive influence of parameters, even if the influence of some is not as strong
 248 as others. This results in a deeper understanding of the ensemble effects. We also ex-
 249 plore a reduced model consisting of just those parameters we hypothesize are the direct
 250 physical drivers of flux: AE (as a measure of electron injections from substorms), pres-
 251 sure, and the solar wind electric field (E_y , or $-VB_z$).

252 The description of the data is given in Section 2. Section 3 presents the results for
 253 drivers for 40-150 keV. The findings are discussed and the conclusions are drawn in Sec-
 254 tion 4.

255 2 Data for Defining the keV Electron Drivers

256 For electron fluxes, we use hourly averaged data from the geostationary GOES-13
 257 satellite. We analyze the measurements from the MAGED instrument consisting of the
 258 nine collimated solid state telescopes (e.g., Rowland & Weigel, 2012), each with a 30°
 259 full-angle conical field of view. All nine telescopes measured the directional differential
 260 electron fluxes in units of $cm^{-2} \cdot sr^{-1} \cdot keV^{-1}$. We use the fluxes in the first three en-
 261 ergy channels where the fluxes are defined at the midpoints of the energy ranges, i.e.,
 262 at 40, 75, and 150 keV. We compute one omnidirectionally averaged flux (flight direction-
 263 integrated differential electron fluxes) for each of the energies using pitch angles calcu-
 264 lated from the GOES Magnetometer 1 data following the method presented in Sillanpää
 265 et al. (2017) and Ganushkina et al. (2019). The GOES-13 MAGED data of electron fluxes
 266 and the data for the pitch angles of each telescope with 5-min averaging are available
 267 at <https://www.ngdc.noaa.gov/stp/satellite/goes/dataaccess.html>.

268 The time interval of this study is 10 June 2013 - 6 August 2016. There were min-
 269 imal data gaps of only several hours during these time periods. For the time-dependent
 270 analyses (ARMAX models) these gaps were filled with linear interpolation between the
 271 existing observations.

Solar wind parameters (solar wind velocity V , number density N , pressure P , IMF B_z and B_s (including only the southward component of B_z), and the electric field E_y) and magnetic indices (Kp, AE and SymH) were obtained from OMNIWeb web (<https://omniweb.gsfc219.nasa.gov/form/dx1.html>) with 1 h resolution with data time-shifted to the bow shock nose. We use an hourly ground ULF wave index (ULF) as a global ULF activity proxy reconstructed from 1-min data from the world-wide array of magnetic stations in the Northern hemisphere (data available at: <https://doi.org/10.2205/ULF-index>) (Kozyreva et al., 2007; Pilipenko et al., 2017).

Analyses based on the least squares regression methodology assume that the relationship between predictor and response variables be linear, with the residual errors (that variance unexplained by the model) being random, normally distributed, and with equal variance over the range of predicted values. This requirement applies even to such analyses as simple correlation. However, the relationship between flux and predictor parameters is often nonlinear and inspection of the residual errors of these analyses performed on non-transformed data shows this nonlinearity, as well as non-normality and an inequality of variances at different levels of the predictors. Fortunately, these problems can usually be fixed by taking the log of at least electron flux, with further improvements obtained by taking the log of transformable predictor variables as well. We therefore take \log_{10} of all variables ≥ 0 . Variables containing zero values which cannot be logged without creating missing values (i.e., Kp) were transformed by adding 1 to all values before the log transformation. B_z and E_y , as they have both positive and negative values, were not logged. Examination of residual plots of the ARMAX models (not shown) showed that this transformation fixed all three problems.

Because the dependent variable (electron flux) is log-transformed, this results in nonlinear models between flux and all the variables, a power function relationship for those predictor variables that are also log-transformed, and an exponential function relationship for those predictor variables that are not logged.

Subsequent to the log transformation, all variables were standardized by subtracting that series mean and dividing by its standard deviation. This creates unitless variables (Z-scores) for which regression coefficients (slopes) can be directly compared. Although it makes no difference to the outcome of the correlations, we also used the Z-scores for the correlation analysis for consistency. We note, however, that neither the log nor the Z-score transformation reduces either the serial autocorrelation or common cycles seen in these time series datasets. This autocorrelation inflates the simple correlations and must be further dealt with by describing/removing the autocorrelation and common trends and cycles via the introduction of AR and MA terms and/or differencing, as described below in Section 3.2 (Granger & Newbold, 1974; Simms et al., 2022).

ARMAX models were developed in IBM SPSS Statistics (formerly known as the Statistical Package for the Social Sciences), with additional statistical analysis in MATLAB.

3 Drivers of 40-150 keV Geostationary Electrons

3.1 Cross Correlations of Electron Fluxes with Solar Wind and IMF Parameters and Geomagnetic indices

Simple cross correlations of hourly measured parameters (Figure 1) show values near 0.5 for some parameters, most notably and in keeping with previous studies, V , ULF , and AE (e.g., (Li et al., 2005; Kellerman & Shprits, 2012; Hartley et al., 2014; Simms et al., 2014)). Positive correlations are shown with solid lines, negative with dashed red lines. Correlations are performed between electron flux and individual parameters from each hour (0-48 h) before the flux measurement. At higher electron energies, the AE and ULF correlations are lower, with peak correlations at earlier times. The correlation with

322 V may be somewhat higher, but there is also a tendency for its peak correlation with
 323 electron flux to occur earlier at higher energies. The correlation of flux with N is less
 324 than that with V , although it does become more prominent at 150 keV, if negative.

325 B_z and B_s correlations with flux are similar to each other. There appears to be no
 326 particular advantage to using the B_s parameter over B_z . The negative correlations of
 327 B_z and $SymH$ with flux are as expected, as each of these parameters are measured on
 328 a negative scale indicating increasing strength at more negative values. While the B_z
 329 strength shows less association with flux, $SymH$ and Kp show similar patterns of cor-
 330 relation to each other, likely because both are generalized measures of disturbance at ground
 331 magnetometers. These parameters also show an increased correlation at earlier time steps
 332 at higher flux energy.

333 P and E_y are somewhat different from the other variables in that they are math-
 334 ematical combinations of other measured parameters (V^2 and N , and V and B_z in the
 335 cases of P and E_y , respectively), but, at the same time, they may have more physical
 336 interpretability. That the P -flux correlation is similar to that of the flux correlation with
 337 V or N can be seen where the P correlation drops off in a manner similar to the N cor-
 338 relation, albeit, with some tempering of this decrease as the V correlation rises at the
 339 same point in time. The E_y -flux correlation follows the pattern of the B_z -flux correla-
 340 tion nearly exactly.

341 **3.2 Interpretation Problems with Simple Correlations: Poorly Defined** 342 **Variables, Autocorrelation, and Spurious Correlations**

343 Most of the parameters of Figure 1 show more association with flux in the few hours
 344 just prior to a flux measurement at the lower energies, but with maximum correlations
 345 at the higher energies occurring further back in time. However, it is difficult to interpret
 346 a single peak or even a rise in correlation at a given hour as a physical process that hap-
 347 pens at that particular time, given that all these parameters are strongly autocorrelated
 348 in time. A variable strongly correlated with itself in previous time steps will show a sim-
 349 ilar correlation with flux at every one of those time steps, making it impossible to de-
 350 termine the exact time of physical action from simple correlation analysis.

351 Another difficulty with simple correlation analysis is that correlations between pre-
 352 dictor variables may distort the apparent association between a predictor and flux by
 353 confounding the true relationship. The well known correlation between V and N , for ex-
 354 ample, even if it is negative, will result in both predictors showing a correlation with flux,
 355 even if only one of them has an actual association. Besides this, any co-cycling variables
 356 will show a strong correlation even when there is no association other than a similar re-
 357 sponse to time. This is a particular difficulty in space weather data where both diurnal
 358 cycles and longer cycles are common.

359 Although we find reasonable correlations of $SymH$ and Kp with flux, to justify in-
 360 cluding these in a model attempting to find the physical drivers of flux, there must be
 361 some basis for thinking there is a physical connection between these particular indices
 362 and electrons. While Kp , derived from midlatitude stations, may be sensitive to vari-
 363 ations at the inner edge of the electron plasma sheet (M. Thomsen, 2004; Freeman, 1974),
 364 there is no guarantee that this is all or even most of what Kp measures. As the mea-
 365 sure itself is merely the maximum geomagnetic disturbance recorded in a 3 h period, it
 366 may not be specific to that particular area of the magnetosphere, nor temporally fine tuned
 367 enough to be of much use. The discrete nature of the index values would also work to
 368 obscure much of the information it could carry. That there are high correlations between
 369 electron flux and Kp (see Figure 1) is not an argument in favor of its necessary inclu-
 370 sion in a meaningful physical model, but may more likely only indicate that Kp is a proxy
 371 that represents a large number of processes that we would, instead, prefer to know the
 372 effects of individually. In addition, as parameters that are averaged over longer periods

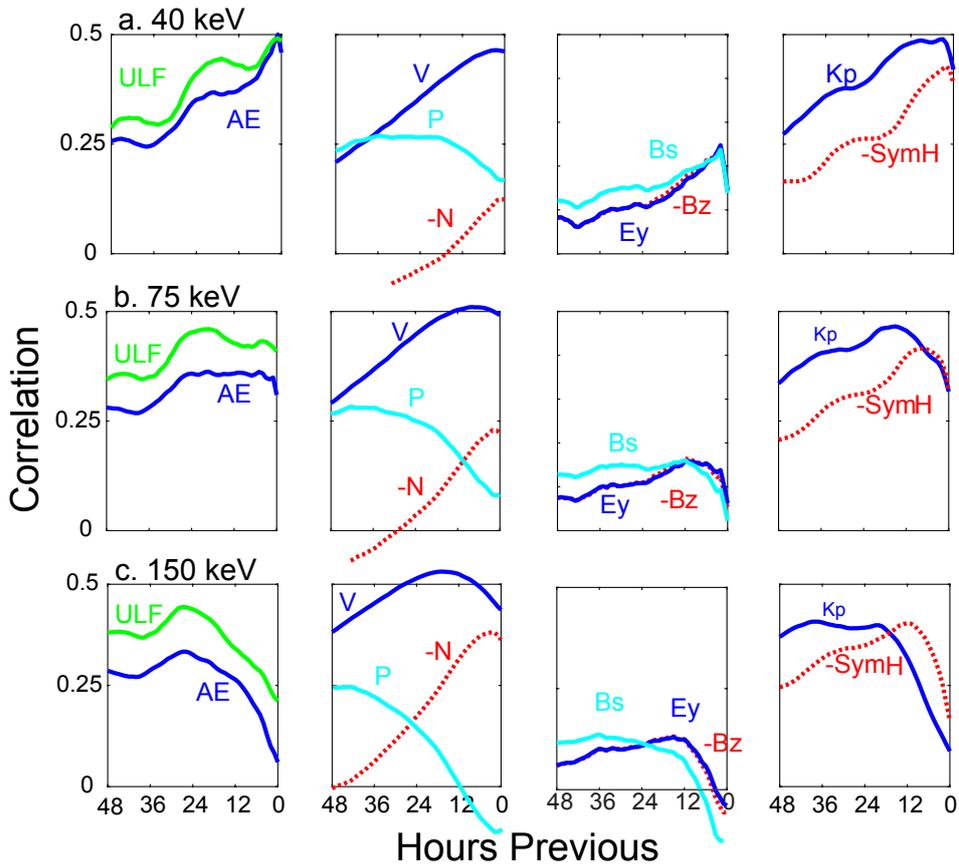


Figure 1. Cross correlations between GOES electron flux and possible drivers (hourly averages) for a. 40 keV, b. 75 keV, c. 150 keV. Solid lines are positive correlations; dashed lines are negative correlations. Note that most correlations are < 0.5 in magnitude.

373 of time tend to show higher statistical correlations without any meaningful increase in
 374 association ((Simms et al., 2022)), this alone could explain the Kp , at a 3 h cadence, hav-
 375 ing a higher correlation with flux than that of many other parameters. $SymH$ may be
 376 an indirect measure of the free energy available for local wave acceleration of keV elec-
 377 trons up to MeV energies, but is perhaps more representative of inner magnetospheric
 378 plasma pressure, about 12% of which is keV electron pressure ((Kumar et al., 2021). $SymH$
 379 may be worth testing as a representation of these processes, but the applicability to elec-
 380 tron flux in the outer radiation belts appears weak. While the AE index can be inter-
 381 preted as a measure of the substorm activity that may result in electron injections, we
 382 do not have the a similarly meaningful physical interpretation of Kp and $SymH$ other
 383 than that they measure the overall level of disturbance in the magnetosphere. But if "dis-
 384 turbance" is a meaningful concept, it is more accurately measured by such parameters
 385 as V , B_z , etc., which also have a physical meaning in the system. In previous work it
 386 has also been found that indices from magnetometers tend to correlate highly with each
 387 other, meaning that it may only be useful, or possible, to include one index in a mul-
 388 tivariate analysis without reaching problematic levels of multicollinearity that make it
 389 impossible to determine which variables are most associated with flux (Simms et al., 2016).
 390 Therefore, we need to use care in deciding which index to use and not include every one
 391 possible. Instead, we should settle on the one that best describes the physical processes
 392 we suspect are occurring.

393 However, these arguments are somewhat moot. If we do include all 3 indices (Kp ,
 394 $SymH$, and AE in a full regression ARMAX model (see below; Table 1), Kp and $SymH$
 395 are not strong candidates, as their influence can be up to an order of magnitude below
 396 that of AE . Although Kp and $SymH$ have high simple correlations with flux, and even
 397 if we were to believe they represented physical drivers, when variables are tested simul-
 398 taneously, these two indices do not perform well. In the subset models, we therefore use
 399 the AE index both because it is representative of substorm activity and because it is a
 400 stronger correlate, at least at 40 keV. In future work, if we planned to create prediction
 401 models only, but not to identify physical drivers, this restriction would not apply and
 402 all three indices could be included (with the caveat that this did not result in overfit-
 403 ting and, therefore, poor predictive ability).

404 Although simple correlations can suggest possible drivers, further work must be done
 405 to elucidate these relationships. Below, in our ARMAX models, we address these issues,
 406 performing multivariate analyses to account for spurious simple correlations due to the
 407 confounding of variables, adding autoregressive (AR) and moving average error (MA)
 408 terms to account for serial autocorrelation and co-cycling of variables, and choosing pre-
 409 dictors that have a reasonable basis for some physical relationship with flux. In regards
 410 to this latter issue, we also choose 4 variables (AE , ULF , P , and E_y) as possible direct
 411 physical drivers of flux (direct effects) and explore their relationship with the other sol-
 412 ar wind and IMF parameters (indirect effects).

413 Additionally, below, we explore whether certain parameters are more correlated dur-
 414 ing geomagnetically disturbed periods and at different times of the day. For the former,
 415 we must use a differencing transformation ($y_t - y_{t-1}$) to reduce serial autocorrelation
 416 as, without a complete time series, we are unable to remove this with ARMA terms. To
 417 study varying influences by time of day, we add indicator variables to the ARMAX model
 418 to identify each hour (MLT: magnetic local time).

419 3.3 ARMAX models

420 As noted in the previous section, simple cross correlations of time series variables
 421 may be highly inflated by common cycles and trends often seen in time series data (Granger
 422 & Newbold, 1974). These correlations may, therefore, not say anything useful about the
 423 relationship between variables. In addition, analyzing the effect of each predictor indi-

vidually gives us no information about the relative importance of each, or the effect of each when the others are held constant. Multiple regression analysis would assess the strength of the relationship between each predictor with the effects of the other predictors eliminated. Additionally, as regression gives us the slope of the relationship between predictor and flux (the coefficients of the regression equation), there will be more information about the form of the relationship. We can further improve on a multiple regression model by introducing terms to specifically describe the cycling, trends, and autocorrelation that may be present in time series data. These terms may take the form of an autoregressive component (regressing on previous values of the dependent variable: an AR term), or a moving average component (regressing on the errors of the model at preceding time steps: an MA term). (A difference term, which subtracts a previous value from each observation, may also be used to fit an overall trend, but we found this was not needed for this full set of hourly averaged flux data.) For data that cycles “seasonally” (at a set time period) it may be helpful to also fit seasonal AR and MA terms (Hyndman & Athanasopoulos, 2018).

We fit ARMAX models, using AR and MA terms, along with “seasonal” (daily) AR and MA terms, to describe the cycling behavior of the dependent variable. We are then able to test input variables for their possible correlation separate from these common cycles. The “seasonality” we incorporate is the daily variation in flux seen as the observing satellite passes between drift shells due to the asymmetric dipole of the Earth’s magnetic field. Typically, higher energy (MeV) electron flux data collected at geosynchronous orbit shows higher levels on the dayside where the field is compressed and lower flux levels on the night side where the fields are stretched (e.g., O’Brien & McPherron, 2003; Boynton et al., 2019). For keV electrons, fluxes are highest in the morning hours and lowest in the evening hours due to their trajectories and losses (e.g., Korth et al., 1999; Sillanpää et al., 2017).

As all variables were standardized by subtracting that series mean and dividing by its standard deviation, we are able to compare these unitless regression coefficients between variables. Note that these are not correlation coefficients, but slopes. A 1 unit increase in a predictor variable is thus associated with a certain increase in the dependent variable. Taking \log_{10} of those variables for which it made sense (i.e., not B_z , for example, which has both positive and negative values) effectively creates a non-linear model, despite how we are using the linear model technique of ARMAX regression.

For each electron flux energy (40, 75, and 150 keV), we fit an AR1, MA1,2, seasonal AR1, seasonal MA1 model (abbreviated as (1,0,(1,2))(1,0,1)]. More specifically, each regression contained two flux autoregressive terms (from 1 h previous and 24 h previous) and the moving average of the errors of the model from 1,2, and 24 h previous as predictors, in addition to the exogenous AE , Kp , $SymH$, ULF , and solar wind and IMF variables. The 24 h AR and MA terms represent the “seasonality” terms that model the diurnal fluctuations in flux due to the movement of the satellite through field lines (in other words, the “seasons” are days (Table 1). This reduced all terms of the partial autocorrelation function (PACF) to non-statistically significant levels.

3.4 Full ARMAX model Including All Variables

V , N , IMF B_z , AE , ULF , P , E_y , Kp , and $SymH$ were first entered as numerator (influence) terms at 1 and 2 hour delays, with a denominator (decay) term at 1 hour (Table 1. Influence terms with p-value > 0.10 were dropped from the model. The p-value is the probability that the null hypothesis of no association is true. p-value < 0.05 is generally considered to be statistically significant, or, put another way, that the null hypothesis of no association has been rejected. Therefore, not all influence and decay terms are retained, however, at least one influence and the decay term are retained for each predictor, even if statistical significance fell above a p-value > 0.10 , in order to describe

475 the relative influence of each term. (The constant term is not significantly different from
 476 zero because all variables were standardized and therefore centered around zero. How-
 477 ever, we retain it for the small amount of explanatory value it adds to the model.) We
 478 report standardized regression coefficients which describe the slope of the relationship
 479 between predictor and response variables on a standard (unitless) scale. Due to this stan-
 480 dardization we are able to directly compare the influences of each predictor with all the
 481 others. (These are slopes, not correlation coefficients, so are not constrained to lie be-
 482 tween -1 and 1.)

483 The R^2 , or coefficient of determination, measures the percent of variation in the
 484 data that is explained by the model. (Note that the R^2 is mathematically equivalent to
 485 the prediction efficiency used by some other authors when applied to a training dataset.)
 486 The R^2 can be calculated for other models, including simple correlation, where the R^2
 487 of r , the correlation coefficient, is merely r^2 . The highest simple correlations (e.g. AE
 488 and V of Figure 1) around $r = 0.5$ would therefore have an R^2 of 25%, explaining 25%
 489 of the variation in the data. Thus, the multiple regression ARMAX models which use
 490 both ARMA terms and more than one predictor variable, explain more of the variation
 491 than any of the simple correlations. Much of the increase in R^2 is due to the introduc-
 492 tion of the ARMA terms, but the ARMAX models do also tell us which independent vari-
 493 ables are most important and how they compare in influence with each other. This ad-
 494 dition of predictor variables would also allow the ARMAX model to be used for predic-
 495 tion. If there are no exogenous (independent) variables in the model, predictions would
 496 quickly revert to the mean value of zero, the constant of the ARMAX equation.

497 The predictor coefficients can be represented with an empirical prediction equa-
 498 tion (Equation 1). For the 40 keV electrons:

$$\begin{aligned}
 499 \quad Flux_t = & -0.057 + \frac{0.632V_{t-1}}{1 - 0.270V_{t-2}} + \frac{1.087N_{t-1}}{1 - 0.126N_{t-2}} \\
 500 & + \frac{0.265Bz_{t-1}}{1 - 0.283Bz_{t-2}} + \frac{0.0170Kp_{t-1}}{1 - 0.563Kp_{t-2}} \\
 501 & + \frac{-0.028SymH_{t-1}}{1 - 0.726SymH_{t-2}} + \frac{0.170AE_{t-1}}{1 - 0.379AE_{t-2}} \\
 502 & + \frac{0.021ULF_{t-1}}{1 - 0.959ULF_{t-2}} + \frac{-0.992P_{t-1}}{1 - 0.177P_{t-2}} \\
 503 & + \frac{0.257Ey_{t-1} - 0.131Ey_{t-2}}{1 - 0.046Ey_{t-2}} \\
 504 & + 0.836 \times \hat{Y}_{t-1} + 0.999 \times \hat{Y}_{t-24} \\
 & + 0.204 \times \varepsilon_{t-1} + 0.302 \times \varepsilon_{t-2} + 0.986 \times \varepsilon_{t-24}
 \end{aligned} \tag{1}$$

506 Flux at time t is predicted by the other variables at previous times steps ($t - 1$,
 507 etc), the model predicted value of flux at $t - 1$ and $t - 24$ ("daily"), and the error be-
 508 tween model and observation (ε) at $t - 1$, $t - 2$, and $t - 24$. For clarity, we do not label
 509 the variables that have been logged (flux, V , N , Kp , AE , ULF , and P) in the empir-
 510 ical prediction equation, however, due to this transformation, this is effectively a non lin-
 511 ear model in the terms for which we have taken logs. Each influence term is represented
 512 in a numerator, with decay terms in the denominator.

513 The influence (numerator) and decay (denominator) terms of Equation 1 give us
 514 the tools to calculate the cumulative effects of each input variable. An influence that ap-
 515 pears at $t-1$ dissipates at a rate given by the decay term. Thus, although there may only
 516 be one hour in which a variable input appears, the exponential decay over time means
 517 influence may spread from previous time periods. The influence at a given forward time

Table 1. ARMAX standardized regression coefficients of the full models (one for each electron energy) including all variables except B_s (*: statistically significant, p-value < 0.05; †: p-value < 0.10; n.s.: not statistically significant, p-value > 0.10)

| | 40 keV | 75 keV | 150 keV |
|--------------|-----------|------------|------------|
| Intercept | -0.057n.s | -0.054n.s. | -0.036n.s. |
| AR1 | 0.836* | 0.845* | 0.855* |
| MA1 | 0.204* | 0.207* | 0.069* |
| MA2 | 0.302* | 0.217* | 0.202* |
| DailyAR1 | 0.999* | 1.000* | 1.000* |
| DailyMA1 | 0.986* | 0.993* | 0.994* |
| V lag 1 h | 0.632† | 0.888* | -0.196* |
| Decay | 0.270 | 0.822 | -0.147 |
| N lag 1 h | 1.087* | 1.358* | -0.087* |
| Decay | 0.126 | 0.811 | 0.854 |
| Bz lag 1 h | 0.265* | 0.386* | 0.306* |
| Decay | 0.283 | 0.429 | 0.673 |
| Kp lag 1 h | 0.017n.s. | 0.041* | 0.023* |
| Decay | -0.563 | 0.937 | 0.967 |
| SymH lag 1 h | -0.028* | -0.004* | 0.056* |
| Decay | 0.726 | 0.975 | -0.447 |
| AE lag 1 h | 0.170* | 0.131* | 0.019* |
| lag 2 h | – | 0.050* | 0.062* |
| Decay | 0.379* | -0.055 | 0.551 |
| ULF lag 1 h | 0.021* | 0.001n.s. | 0.003n.s. |
| Decay | 0.959 | -0.988 | 0.984 |
| P lag 1 h | -0.992* | -1.274* | 0.035n.s. |
| Decay | 0.177 | 0.813 | 0.849 |
| Ey lag 1 h | 0.257* | 0.352* | 0.263* |
| lag 2 h | -0.131 | -0.040* | – |
| Decay | -0.046 | 0.414 | 0.731 |
| R^2 | 67.4-% | 69.2-% | 78.1-% |

518 step from some time step (t) in the past will be that influence $\times(1-\text{decayfactor})^t$. Graph-
 519 ically, this results in a time delay of influence that appears similar to a cross correlation,
 520 however, the transfer function gives regression coefficients (i.e., slopes), not correlations.
 521 While a correlation can be interpreted as the strength of a relationship between two vari-
 522 ables, a regression coefficient can be interpreted as the magnitude of the impact of one
 523 variable on another. We use the predictor coefficients of Table 1 to create the cumula-
 524 tive influence bar charts of Figure 2. It should be remembered that these regression co-
 525 efficients represent the influence of each variable with the others held constant, unlike
 526 the simple correlations of Figure 1. Each panel of this figure shows the response of an
 527 electron energy (40, 75, and 150 keV) to the influence of each of the 9 exogenous vari-
 528 ables when the other 8 predictor variables are held constant. The influence of each be-
 529 gins from the hour previous to the flux measurement. The decay term describes the fall
 530 off in influence over time.

531 These ARMAX models incorporating all 9 possible predictors show little influence
 532 of Kp and $SymH$. AE has the highest influence of the geomagnetic indices, but it is weaker
 533 than the strong and lasting effects of V , N , and P , particularly at 75 keV. The V , N ,
 534 and P influences are superficially similar to those seen in the simple cross correlations
 535 (Figure 1) but the sign of influence of N and P have switched. B_z and E_y also super-
 536 ficially show the same influence as in the cross correlations, but, again, the sign of in-
 537 fluence of B_z is switched.

538 What are we to make of these losses of influence (particularly Kp and $SymH$) and
 539 the changes in sign? First, it becomes obvious that simple correlations are highly un-
 540 reliable. They should not be used, individually, to determine what drives electron flux.
 541 Each parameter is highly correlated with all the other parameters of interest, and on top
 542 of that any one of them may show a spurious correlation with electron flux due to com-
 543 mon cycling behavior. While any of the highly correlated parameters, or a set of them,
 544 might usefully be employed in a predictive model, we should not make the mistake of
 545 believing that a model that predicts well has identified the actual drivers of the system.

546 Second, geomagnetic indices (particularly Kp and $SymH$) do not even appear to
 547 influence electron flux when other variables are present. In this full model, Kp and $SymH$
 548 have little influence. However, even if they were the most "influential" parameters in these
 549 models, for the reasons mentioned above would we be justified in calling them drivers?
 550 Or are they merely correlated proxies? Is $SymH$ a predictor variable at all? Or just an-
 551 other measure of our response variable, the electron flux? These questions can only be
 552 answered from a consideration of what information these indices actually contain. As
 553 we have discussed above, while Kp and $SymH$ may roughly represent disturbance in the
 554 magnetosphere, we don't know exactly which processes and how much of each process
 555 they might represent. AE is a different case. First, AE does show more influence than
 556 the other two indices, and second, we know that this index measures substorm activity
 557 which can lead to electron injection. For this latter reason, we will retain AE in further
 558 models.

559 Both P and N act more as a pointed shock to the system with less long term in-
 560 fluence, however, the opposite sign of these two predictors, at similar magnitudes, sug-
 561 gests that there is some degree of multicollinearity occurring between these two. This
 562 is not surprising, as P , partially calculated from N , is highly correlated with N and the
 563 amount of information about the influence of each on flux is almost wholly contained in
 564 the other. Unfortunately, this can result in a pattern of presumed "influence" (as seen
 565 here) that reflects a competition for explanatory power rather than actual opposing ef-
 566 fects on flux, and the inclusion of both in the model is misleading. B_z and E_y have more
 567 modest influences on flux. Despite the high ULF -flux correlation seen in the simple cor-
 568 relations, the ULF influence on flux is very low. This is likely due to two factors. First,
 569 when other variables are included in the model any proxy correlation ULF may have rep-
 570 resented is removed from the ULF influence. Second, the high simple correlation may

571 be simply due to this ULF index and satellite-measured flux both showing a diurnal cy-
 572 cle. When this cycling is removed (via the AR and MA terms) the correlation between
 573 these variables disappears (Simms et al., 2022). (The occasional oscillating pattern of
 574 influence in several of the variables is the result of a negative decay term found by the
 575 regression. It is often unclear whether this has any real physical meaning.)

576 As these are standardized regression coefficients, we can calculate the impact of a
 577 predictor on flux. For example, as we are using standardized coefficients, a 1 standard
 578 deviation increase in $\log_{10}(AE)$ 1 h previous would result in 0.17 standard deviation in-
 579 crease in $\log_{10}(40keV flux)$, holding all the other predictors constant.

580 3.5 Choice of variables

581 Pressure (P) and number density (N) are difficult to incorporate into a model si-
 582 multaneously. As pressure is the product of the V^2 and N , the strong correlation be-
 583 tween pressure and N can lead to unexpected and puzzling behavior. In the models of
 584 Figure 2 and Table 1, there is a strong initial influence of P , and an opposing strong in-
 585 fluence of N in the same time period. As we know that P and N are highly correlated
 586 with each other, it is difficult to interpret this as each having a strong, opposing, and,
 587 most importantly, independent influence. It is more likely that these opposing effects are
 588 merely the result of the two terms acting counter to each other in an effort to explain
 589 the same small bit of variation. The same is true of E_y with V and IMF B_z , as E_y is
 590 the product of V and B_z . A more plausible model could be achieved by dropping one
 591 of either P and N , and one of E_y and IMF B_z . For example, dropping the two derived
 592 parameters (E_y and P) would allow us to more accurately see the effects of V , N , and
 593 B_z .

594 However, we may be able to do better by separating out just those parameters we
 595 believe could be influencing flux directly. These direct parameters would be AE (as a
 596 measure of substorms which inject electrons), ULF (waves in this frequency are thought
 597 to drive electrons to higher energies), E_y (with the solar wind electric field plausibly hav-
 598 ing some influence on electron behavior), and pressure (which could influence flux lev-
 599 els through acceleration, through magnetopause shadowing, and by compression of the
 600 magnetosphere at the altitude of the satellite, bringing the satellite into higher drift shells
 601 with lower electron density). The coefficients of this reduced model are presented in Ta-
 602 ble 2.

603 From the coefficients of this table, we once again calculate the cumulative effects
 604 of each variable on flux (Figure 3). At 40 keV (3a), this simpler model of the presumed
 605 direct effects alone shows a strong effect of AE , peaking at 2 hours before the flux and
 606 with influence over many hours. Pressure, E_y , and ULF , while still statistically signif-
 607 icant effects, are much lower in magnitude. The effect of pressure is negative, presuma-
 608 bly as most of its effect is due to the compression of the magnetosphere which positions
 609 the satellite into a less populated drift shell and to magnetopause shadowing. The small
 610 E_y association cycles between positive and negative. A similar pattern is seen for the
 611 75 keV electrons (3b), although the AE influence is slightly lower and the P and ULF
 612 effects somewhat stronger. The 150 keV electrons (3c) show a much lower response to
 613 AE , and, again, a somewhat stronger response to P and ULF .

614 But what of the strong influence of V we saw in the full model of Figure 2? Although
 615 our direct effects model (of Figure 3) may make more physical sense, we still would like
 616 to understand the correlation of V with flux. We can do this by using the other, indi-
 617 rect parameters to predict our set of more physically interpretable variables, decompos-
 618 ing each correlation into components. In other words, we can use N , V , and IMF B_z to
 619 predict AE , ULF , P , and E_y , which we subsequently use to predict flux.

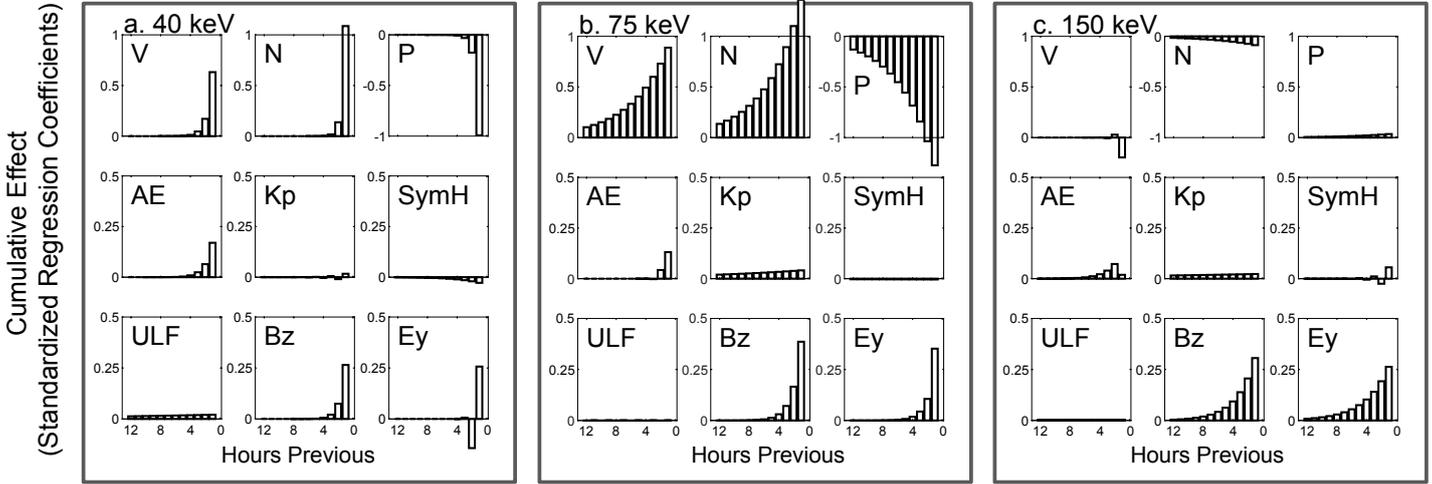


Figure 2. Cumulative effects of all possible drivers of electron flux. For each flux energy, variables are entered simultaneously into an ARMAX regression model as a predictor at a delay of 1 and 2 hours. Only statistically significant time steps are retained, along with a decay factor. Standardized regression coefficients may be compared within each model (a. 40 keV, b. 75 keV, c. 150 keV) to determine the relative influence of each variable on flux. Note that each row has the same scale, but scales vary between rows, in order to compare more effectively between the strongest associations (V , N , and P) and between the indices (AE , Kp , and $SymH$) and other variables with lower influence (ULF , B_z , and E_y).

Table 2. ARMAX standardized regression coefficients of the three reduced models using *AE*, *ULF*, *P*, and *Ey* as predictors (*: statistically significant, p-value < 0.05; n.s.: not statistically significant)

| | Log 40 keV flux | Log 75 keV flux | Log 150 keV flux |
|-----------------|-----------------|-----------------|------------------|
| Constant | -0.090n.s. | -0.093n.s. | -0.056n.s. |
| AR1 | 0.825* | 0.843* | 0.86* |
| MA1 | 0.197* | 0.195* | 0.055* |
| MA2 | 0.293* | 0.212* | 0.201* |
| Daily AR1 | 0.998* | 0.998* | 0.999* |
| Daily MA1 | 0.981* | 0.987* | 0.993* |
| Log(AE) 1h lag | 0.216* | 0.130* | 0.004n.s. |
| 2h lag | 0.154* | 0.091* | |
| Decay 1h | 0.882 | 0.542 | 0.053 |
| Decay 2 h | | 0.349 | |
| Log(ULF) 1h lag | 0.017* | 0.021* | 0.03* |
| Decay 1h | 0.965 | 0.969 | 0.97 |
| Log(P) 1h lag | -0.025* | -0.039* | -0.055* |
| Decay 1h | 0.717 | 0.728 | 0.801 |
| Ey 1h lag | -0.018* | -0.014* | -0.03* |
| 2h lag | — | -0.022 | — |
| Decay 1h | -0.763 | -0.381 | 0.412 |
| | | | |
| R^2 | 67.10% | 68.50% | 76.90% |

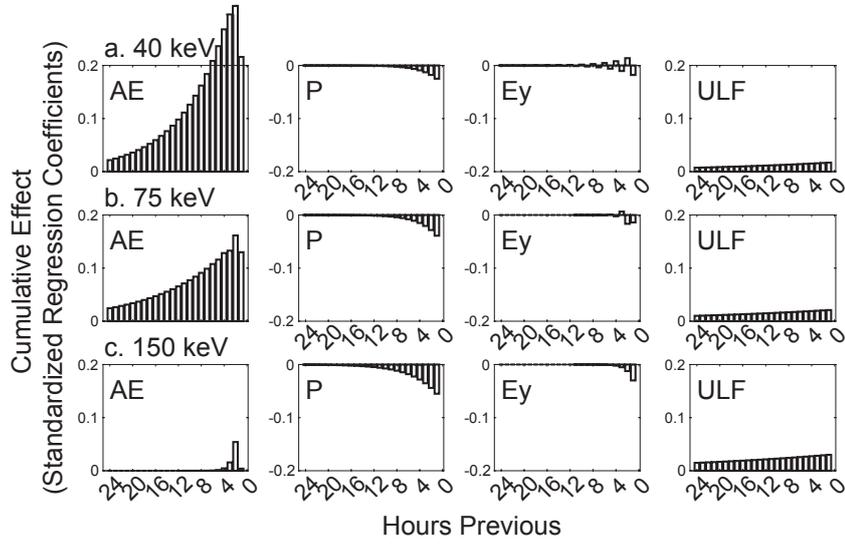


Figure 3. Cumulative effects of the possible direct drivers of electron flux. For each flux energy, AE , P , E_y , and ULF are simultaneously entered into an ARMAX regression model as predictors at 1 and 2 hours, but only significant time steps are retained, along with a decay factor. Standardized partial regression coefficients may be compared within each model to determine the relative influence of each variable on flux: a. 40 keV, b. 75 keV, c. 150 keV.

620 To accomplish this, we presume a causal model (Figure 4) and run a series of
 621 regressions to determine the coefficients of the paths. In this figure, we present the stan-
 622 dardized regression coefficients obtained by predicting 40 keV flux from *AE*, *ULF*, *P*,
 623 and *E_y*. We then predict both *AE* and *ULF* using *P*, *E_y*, *N*, *V*, and IMF *B_z* from one
 624 hour previous. (These models are not shown explicitly as the input parameter coefficients
 625 are all that we need here, but these are simply the exogenous coefficients from an AR-
 626 MAX model also incorporating AR and MA terms. For this particular model, we use only
 627 a lag 1 h influence term and no decay term to simplify the effects of each input variable.)
 628 Similarly, we show the exogenous variable coefficients for predicting *P* from *N* and *V*,
 629 and *E_y* from *V* and *B_z*, using *N*, *V*, and *B_z*, but from the same hour as *P* and *E_y*. (There
 630 are not paths from *V* to either *ULF* or *AE* because it was not a statistically significant
 631 direct influence on either.) In this figure, green arrows run to and from *AE*, gold arrows
 632 to and from *ULF*, and blue arrows to and from *P* and *E_y*.

633 These standardized regression coefficients from this series of regression models are
 634 known as path coefficients (Wright, 1934). The path coefficients can be multiplied (through
 635 connecting arrows, or paths), then summed to show the full cumulative effect of each of
 636 the indirect drivers (*V*, *N*, and *B_z*) on the direct drivers (*AE*, *ULF*, *P*, and *E_y*) and,
 637 subsequently, on flux.

638 The maximum direct effect of each variable is shown by arrows leading directly to
 639 flux. Simple correlations between the exogenous, or indirect, variables (*N*, *V*, and *B_z*)
 640 are shown (in black curved arrows). This decomposition allows the correlation between
 641 a pair of variables to be broken down into direct effects, indirect effects, and spurious
 642 correlation due to associations between the exogenous variables. We are interested in the
 643 direct and indirect effects and will ignore spurious correlations due to the associations
 644 between *N*, *V* and *B_z*. For example, the direct effect of pressure on flux is represented
 645 by the arrow from pressure to flux (-0.04 coefficient). This is rather low, but to this we
 646 can add the indirect effect of pressure: the path from *P* through *AE* to flux (coefficients
 647 0.52 and 0.25). This indirect effect of *P* via its influence on *AE* (which subsequently in-
 648 fluences flux) is the product of the steps in the path: $0.52 \times 0.25 = 0.13$. The contri-
 649 bution of several indirect paths can be calculated by summing these products (Table 3).
 650 In the first column of this table, we show the direct effect of *AE*, *ULF*, *P*, and *E_y* on
 651 flux (coefficients on the arrows leading directly to flux of Figure 4). In the second col-
 652 umn we show the results of the calculations for the indirect effects of each variable through
 653 *AE*, in the third column, these indirect effects through *ULF*, in the fourth, indirect ef-
 654 fects through *P*, and in the fifth column, these indirect effects through *E_y*. (Details of
 655 example calculations are given in the footnote.) The last column is the sum of the first
 656 5 columns, showing the total influence of each variable, both through its direct influence
 657 (if any) and its indirect influence via other parameters.

658 The result of these calculations are that we can now see a clearer picture of which
 659 variables are most influential on flux and through which processes that influence is medi-
 660 ated (given this particular, hypothesized, causal structure). Predictors not postulated
 661 to directly influence flux, such as *V*, still show an overall moderate degree of influence
 662 when paths connecting it indirectly to flux are considered (mainly, in this case, via *P*).
 663 However, *N*, which has a moderate (if negative) simple correlation with 40 keV flux, has
 664 less influence than *V* when all influences are added. *N* appears to drive several compet-
 665 ing processes: reducing *AE* and *ULF* while simultaneously (through *P*) increasing flux.
 666 Thus, the lower correlation of *N* with flux is not an indication that it does not influence
 667 flux, but that it does so through several opposing processes that cancel out each other's
 668 effects in an overall correlation.

669 Certain parameters, such as *ULF*, which show a strong simple correlation with flux
 670 (Figure 1), are not influential. So why does the simple correlation appear so high in com-
 671 parison? This is due to several factors which we have now accounted for: inflated cor-
 672 relations due to common cycles and trends (accounted for by the AR and MA terms of

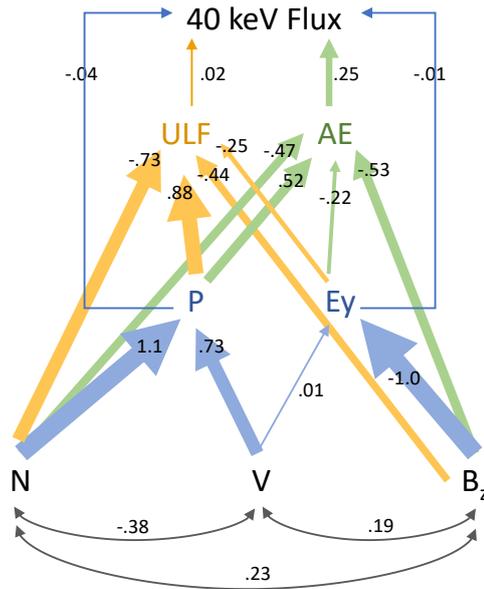


Figure 4. Postulated direct drivers of 40 keV GOES electron flux (green arrows to and from *AE*, gold arrows to and from *ULF*, blue arrows to and from *P* and *E_y*) may be influenced by solar wind and IMF parameters (*V*, *N*, and *B_z*). Standardized coefficients of the influence of *AE*, *ULF*, *P*, and *E_y* on flux (from an the ARMAX model with predictors measured 1 h before flux) are given. *ULF* and *AE* are postulated to be driven by *P*, *E_y*, *V*, *N*, and *B_z* (coefficients from ARMAX models with predictors measured 1 h before). *P* and *E_y*, being mathematically dependent on *N*, *V*, and *B_z*, are predicted from ARMAX models with all variables measured at the same hour. Influences of *V*, *N*, and *B_z* on *P* and *E_y* are from the same hour. These paths break down the overall correlations into components, attributable to the various associations between variables. Only statistically significant links between variables are retained. As a consequence, there is no direct link from *V* to either *ULF* or *AE*.

Table 3. Calculating the sum of direct and indirect influences on 40 keV flux.

| | Direct | via AE | via ULF | Via P | Via Ey | Sum Direct + Indirect Influence |
|-----|--------|-------------------|---------|-------------------|---------|------------------------------------|
| AE | 0.25 | --- | --- | --- | --- | 0.25 |
| ULF | 0.02 | --- | --- | --- | --- | 0.02 |
| P | -0.04 | 0.13 ¹ | 0.018 | --- | --- | 0.11 |
| Ey | -0.01 | -0.055 | -0.005 | --- | --- | -0.070 |
| N | --- | -0.12 | -0.015 | 0.12 ² | --- | -0.014 |
| V | --- | 0 | 0 | 0.137 | -0.0007 | -0.024 |
| Bz | --- | -0.13 | -0.0088 | --- | 0.070 | -0.071 |

¹As an example, the indirect path of P influence through $AE = (\text{effect of P on AE}) \times (\text{effect of AE on flux}) = 0.52 \times 0.25 = 0.13$, using coefficients from the paths in Figure 4.

²The more complicated paths of N through P are summed: $(N \text{ on } P) \times (P \text{ on flux}) + (N \text{ on } P) \times (P \text{ on } AE) \times (AE \text{ on flux}) + (N \text{ on } P) \times (P \text{ on } ULF) \times (ULF \text{ on flux}) = 1.1 \times (-0.04) + 1.1 \times 0.52 \times 0.25 + 1.1 \times 0.88 \times 0.02 = 0.12$.

Table 4. Summed direct and indirect influences on 40, 75, and 150 keV flux.

| | a. AE | b. ULF | c. P | d. Ey | e. N | f. V | g. Bz |
|---------|--------|--------|--------|--------|--------|--------|--------|
| 40 keV | 0.25 | 0.020 | 0.11 | -0.070 | -0.014 | -0.024 | -0.071 |
| 75 keV | 0.15 | 0.005 | 0.021 | -0.052 | -0.051 | -0.049 | -0.029 |
| 150 keV | -0.001 | -0.008 | -0.090 | -0.023 | -0.092 | -0.065 | 0.027 |

673 the ARMAX regression), correlations with confounding variables (now accounted for by
 674 the use of multivariate regression instead of single correlations), and the possibility that
 675 ULF over the short term (hourly, in this case) has little influence.

676 For parameters such as V and N , influence has been diminished by their relegation
 677 to indirect driver status in the path analysis. This is a choice made based on the
 678 hypothesis that neither is postulated to have the physical ability to directly drive elec-
 679 tron flux. If there were reason to believe they did, these could be moved up the hierar-
 680 chy in the path analysis, allowing them to have more influence in that correlational struc-
 681 ture.

682 We can do these calculations for each of the electron energies, giving the summed
 683 influence of each parameter on flux (Table 4). AE appears only as a direct effect, and
 684 is thus comparable directly between electron energies, with the strongest effect at 40 keV
 685 (0.25) but a lower effect above this range (-0.001 - 0.15). The summed influence of P is
 686 generally larger and positive compared to its weak negative direct effect, particularly at
 687 40 keV. The summed E_y effect is similar in magnitude to P . The summed effects of V ,
 688 N , and B_z are all somewhat equal to each other, with somewhat more effect of V at 40
 689 keV and a higher influence of N at 150 keV. For the most part, these three indirect drivers
 690 are negative in influence overall.

691 3.6 MLT dependence of 40-150 keV electron flux response to AE , ULF , 692 P , and E_y

693 Electrons at geostationary orbit show different flux levels at different magnetic local
 694 times (MLT) (Boynnton et al., 2019). With geostationary satellites, which orbit syn-
 695 chronously with MLT, it is unclear whether these are spatial or temporal variations, how-
 696 ever, electron injection has been observed in the hours around local midnight (M. F. Thom-
 697 sen et al., 2001; Birn et al., 1997). Using ARMAX models, we investigate not only whether

698 flux differs at varying MLT, but also whether the identified drivers show different influ-
 699 ences (i.e., a different coefficient slope) at each MLT. We do not subset the data into MLT
 700 bins and analyze them separately, but identify each MLT in the dataset and calculate
 701 a different slope coefficient for each. This is done by creating a set of 23 indicator vari-
 702 ables spanning the MLT hours: each is set to 1 for a different, particular MLT and 0 at
 703 all other times. The interaction term between each of these indicator variables and each
 704 predictor variable (obtained by multiplying each indicator variable by each predictor)
 705 gives the slope of the relationship between flux and predictor at each MLT ((Neter et
 706 al., 1990). By not splitting the dataset by MLT (i.e., by identifying MLT by indicator
 707 variables instead), we are able to analyse the dataset as a continual ARMA process. We
 708 report these slopes (standardized regression coefficients) for each MLT (Figure 5).

709 At 40 and 75 keV, AE is the most influential parameter, but it is most effective
 710 over 3-11 MLT (40 keV) and 6-17 MLT (75 keV). Not only is the flux higher at these
 711 times (Boynnton et al., 2019), but the effect of the strongest driver (AE) is also at its high-
 712 est level.

713 The other direct drivers (ULF , P , and E_y) are, as demonstrated above, less influ-
 714 ential, but there are MLT differences in their effects. ULF has somewhat more effect at
 715 19-0 MLT on the 40 keV electrons. P shows a stronger negative effect over 16-4 MLT,
 716 with the most effect being seen at 150 keV. E_y , at 40 and 75 keV, shows a positive ef-
 717 fect over 23-8 MLT, with a negative effect over 9-22 MLT. The E_y switch in influence
 718 from positive to negative likely accounts for its overall lack of effect in the analyses above
 719 that are not broken down by MLT. Although less dramatic, the switch in ULF from pos-
 720 itive to slightly negative or near zero also results in an overall lack of influence when MLT
 721 is not considered, even though ULF does show a modest positive influence at some times.

722 3.7 Disturbed vs. quiet response

723 To produce an ARMAX model, a continuous time series is needed. This means that
 724 disturbed and quiet periods must be combined in the same analysis. However, it may
 725 be that the flux response to each predictor varies depending on conditions. A simpler
 726 multiple regression model could be used to explore the response between quiet and dis-
 727 turbed periods, however, this can result in spurious correlations if variables are cycling
 728 together (for example, a diurnal cycle) or show a common trend (Simms et al., 2022).
 729 A regression model that accounts for these co-occurring cycles and trends can be produced
 730 by differencing the data: subtracting the previous value from each observation ($y_t - y_{t-1}$).
 731 This results in regression coefficients that describe the change in flux as predicted by the
 732 change in the independent variables, rather than in the original units, but tests of sig-
 733 nificant influence and comparisons of relative influence can still be made.

734 We assemble a subset of "disturbed" data by taking those periods a day before and
 735 a week following each Dst dip to -100 nT. We create a "quiet" set by finding periods >
 736 2 weeks after a Dst dip below -30 nT. A third subset ("recovery") are the disturbed pe-
 737 riods with the Dst drop removed (i.e., with the main phase of the storm removed). By
 738 doing this, we hope to pinpoint those periods when these predictors may have different
 739 influence on electron flux due to geomagnetic conditions. We first perform a multiple re-
 740 gression on the differenced data with AE , ULF , P , and E_y as predictors in order to com-
 741 pare their relative effects via the standardized regression coefficients (Figure 6). We then
 742 compare this to the same analyses performed on undifferenced data to show the effect
 743 of removing spurious correlations that are the result of common cycles and trends.

744 With differenced data (Figure 6.1), the AE effect is consistent over these three pe-
 745 riods (strongest effect on the 40 keV flux, least effect on 150 keV flux). No matter the
 746 geomagnetic conditions, substorms (as measured by AE) show a statistically significant
 747 positive influence on flux, with the most effect at the lower electron energies. P does not
 748 contribute significantly at most periods or energy levels (the exception being at 150 keV

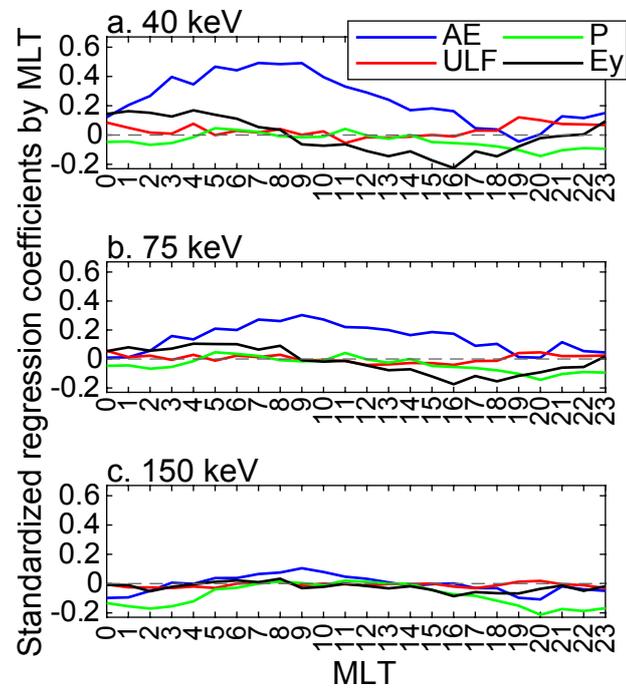


Figure 5. Varying effects of AE , ULF , P , and E_y over magnetic local time. Each variable is entered into an ARMAX regression model as a predictor at 1 h. a. 40 keV, b. 75 keV, c. 150 keV.

during disturbed periods). E_y shows a negative effect in the quiet periods but a positive effect in recovery. ULF has little or a negative influence, even when periods are selected that would be expected to show a strong effect such as recovery following storms.

We present an analysis of undifferenced data in this figure (6.2) to show the danger of correlating variables with common diurnal cycles. In the undifferenced data, we do find the "expected" strong ULF effect (Figure 6.2; note the larger scale compared to the differenced data), but this is only a demonstration of the spurious nature of this high correlation. High correlations between ULF wave activity and electron flux in hourly data are likely only describing a common diurnal cycle and say little about physical driving mechanisms (Simms et al., 2022). ULF waves may be a more long term driver of flux, with positive influences only appearing after 24 h (Simms et al., 2021). The other predictors also show stronger effects when not differenced (Figure 6.2), likely also due to common diurnal cycles in the data.

4 Discussion and Conclusions

A number of variables show high simple (single variable) correlations with keV electron flux, but by using an ARMAX analysis which removes the confounding effect of diurnal cyclicity and allows assessment of each parameter independently, we show more definitively that substorms (measured by AE) are the most influential process at 40 and 75 keV. This accords with previous work that found substorms to be an important correlate with both keV (Ganushkina et al., 2021) and MeV electrons (Simms et al., 2018a).

There is a somewhat lesser effect of E_y (calculated as $-V_{SW}B_z$) in contrast to previous single-variable studies (Denton et al., 2016). P is more influential at 150 keV, acting to decrease electron flux. The contrast to previous findings, where pressure increased flux (Shi et al., 2009), is due to our present study incorporating more predictors at one time. Pressure, as shown in Figure 1, does correlate positively with flux when it is the only tested predictor at the lower electron flux energies, but appears negative in influence when other variables are included. ULF shows little influence on keV electrons in these hourly, fuller variable models, despite its influence on MeV electrons (Simms et al., 2021, 2018a, 2018b) and its strong positive correlation when it is the only predictor (Figure 1).

In addition to these variables that we label direct, physical drivers of flux, we consider several other parameters as possible indirect drivers (solar wind N and V and IMF B_z) which show fairly equivalent influences on flux via their effects on the direct drivers. This supports previous findings concerning these three solar wind and IMF influences (Sillanpää et al., 2017; Li et al., 2005; Kellerman & Shprits, 2012; Ganushkina et al., 2019; Hartley et al., 2014). Stepanov et al. (2021) when controlling for other variables, also found solar wind velocity and a magnetospheric convection variable (the dayside merging electric field, somewhat similar to the E_y we use) to be the strongest influences on keV flux near the plasmashet midplane. A similar multiplicative variable, the IMF factor (Balikhin et al., 2010; Boynton et al., 2011) and solar wind velocity appear to control hourly averaged 40 keV electrons. However, these last studies did not include a test of AE influence.

As electron flux is log-transformed in our analyses, all the relationships we find here are nonlinear even though they are tested with the linear model method of ARMAX regression. As B_z and E_y are not log-transformed, they show an exponential relationship with electron flux. All other predictors, which are log-transformed, are described by a power function relationship.

Although all three geomagnetic indices (Kp , $SymH$, and AE) show high simple (single variable) correlations with electron flux, the influences of Kp and $SymH$ disappear in a full regression model where other variables are included. It is likely that these

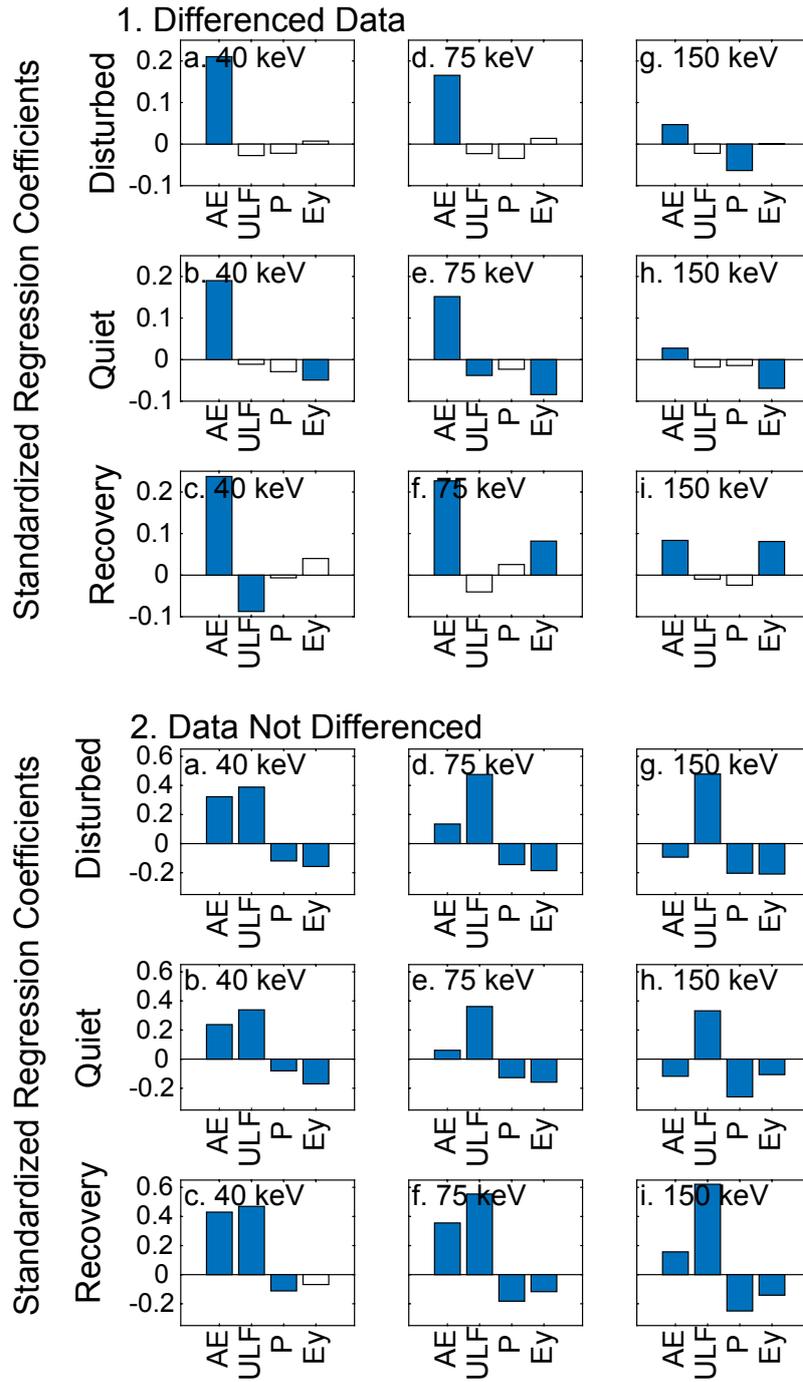


Figure 6. Standardized regression coefficients (AE , ULF , P , and E_y) from multiple regression (not ARMAX) models. 1. All data differenced by subtracting the previous hour's observation: during disturbed periods (a,d,g), quiet periods (b,e,h), and storm recovery periods (c,f,i). 2. The same for undifferenced data. Note the difference in scale between 1. and 2. Significant effects (p-value < 0.05) are shown in blue.

799 two indices mostly measure generalized disturbance in the magnetosphere which is bet-
 800 ter described using solar wind and IMF variables. The AE index, as it is better posi-
 801 tioned to measure substorms and subsequent electron injections, is more representative
 802 of the physical processes that drive flux.

803 The response of electron flux to our identified possible direct drivers (AE , ULF ,
 804 P , and E_y) varies only somewhat between disturbed, quiet, and storm recovery periods.
 805 AE is a stronger influence during recovery, for example, than during quiet or disturbed
 806 periods.

807 While there are sizable simple correlations of some parameters with electron flux,
 808 single variable correlations can misrepresent the actual relationships. If neither common
 809 cycles and trends, nor confounding variables are accounted for, simple correlational anal-
 810 ysis may show large associations between variables that have no physical relationship.
 811 This has been demonstrated before, where removal of common cycles results in either
 812 a complete elimination of a correlation between some space weather parameters (e.g.,
 813 the commonly observed ULF wave correlation with solar wind velocity or with electron
 814 flux (Simms et al., 2022)) or a reduction in correlation (Simms et al., 2021). An ARMAX
 815 model, used in this study, can account for common cycles in time series data (and trends,
 816 if necessary) by the use of AR and MA terms (and differencing, if needed). Entering sev-
 817 eral predictor variables into the same analysis then allows each variable’s influence to
 818 be calculated while the others are held constant.

819 However, adding all possible explanatory variables to a model may not correctly
 820 identify the most important physical parameters but only those that correlate best, for
 821 whatever reason. While a reasonable predictive model may be achieved by throwing all
 822 available variables into a regression or neural network, leaving an algorithm to choose
 823 the model with the highest validation correlation, this is unlikely to identify actual drivers
 824 in the system. This approach, instead, can lead to several problems: 1. ”opposing” vari-
 825 ables may appear extremely influential as they compete to explain the same small bit
 826 of variation, 2. theoretical considerations of physical influence tend to be ignored in fa-
 827 vor of factors that happen to correlate well, 3. coefficient estimates may be biased if ex-
 828 traneous variables are included or if important variables are excluded (Smith, 2018; Whit-
 829 tingham et al., 2006). In the worst case, a model may report that factors that cannot
 830 physically influence the dependent variable are the only factors that have any effect at
 831 all. For this reason, to determine whether a factor has an actual driving influence, care
 832 must be taken to choose only those for which a likely physical effect can be postulated
 833 and not just all that are available. This is why we have chosen to do further analyses
 834 on a set of presumed direct drivers (substorms, ULF waves, pressure, and electric field),
 835 as well analyses that show the relative correlations of all possible variables.

836 Using the ARMAX method on such a reduced model, we find that the influence
 837 of substorms (AE) on hourly electron flux remains substantial over the 40-75 keV range
 838 at geostationary orbit (approximately L6) although of less importance at 150 keV. This
 839 influence is strongest after midnight into the mid-morning hours MLT. The AE influ-
 840 ence is slightly higher during storm recovery periods than during either disturbed or quiet
 841 periods. Substorms, therefore, are the dominant driver within our postulated ”direct driver”
 842 set (substorms, ULF waves, solar wind pressure, and electric field) and presumably show
 843 the influx of electrons injected from the magnetotail.

844 The hourly E_y parameter (electric field of the solar wind) shows little influence when
 845 MLT is ignored. However, introducing MLT into the model results in a positive effect
 846 of E_y over 20-8 MLT, with a mostly negative effect at other times of day. These oppos-
 847 ing influences cancel each other out in a model that does not account for variations over
 848 MLT. The E_y influence also varies by geomagnetic conditions, with no influence during
 849 disturbed periods, a negative influence during quiet periods, and a positive influence dur-
 850 ing recovery after storms.

851 Overall, P shows a moderately negative direct effect on flux. When the analysis
852 accounts for MLT, this negative influence is strongest over 20-12 MLT.

853 ULF waves, thought to accelerate electrons to higher energies, show little imme-
854 diate (hourly) influence. A strong correlation of ULF waves with high energy electron
855 flux (> 1.5 MeV) found in previous studies may be a consequence of correlating two vari-
856 ables with a common diurnal cycle, or a reflection of only long term (at least day long)
857 physical driving (with no short term influence), or both. We find here that any signif-
858 icant short term driving of 40-75 keV electrons by *ULF* appears to be negative and only
859 during quiet or recovery periods, while there is little short term effect at 150 keV.

860 At 150 keV, there is the least response of hourly averaged flux to the presumed phys-
861 ical drivers. This may represent the longer time frame of action required from these pro-
862 cesses to bring electrons to higher energies. Even the cross correlations (Figure 1) show
863 higher effects from 24-48 hours previous, with *ULF* and *AE* showing their least influ-
864 ence in the 12 h preceding a flux measurement and the E_y influence peaking at 12 h.

865 We are able to compare effects of the other correlates by summing their indirect
866 influence through the presumed physical drivers. We are able to calculate that at 40 keV,
867 P shows a summed influence (both direct and indirect) nearly half that of the most in-
868 fluential parameter, *AE*, with E_y having about a fourth the influence of *AE*. Of the pos-
869 tulated indirect drivers, N , B_z , and V show nearly equal effects. The N and V influ-
870 ences are negative, while the B_z influence switches sign above 75 keV.

871 We compare our approach to finding the physical drivers of electron flux (using the
872 ARMAX model framework) to that of some other empirical models that seek instead to
873 predict flux. If the purpose of a model is accurate prediction, then a simple validation
874 correlation of observation with prediction on a withheld test set is the statistic of inter-
875 est. In this case, predictor variables can be chosen simply on the basis of availability and
876 ability to correlate well with the response. Alternatively, the ARMAX-regression mod-
877 els we present here address the question of what parameters drive flux changes. We use
878 hypothesis testing within the ARMAX-regression framework to determine whether cer-
879 tain parameters show an association with electron flux. As our questions concern the sci-
880 ence of the system (i.e., which variables are drivers), we consider, first, which variables
881 most justifiably have a physical association with flux and which are only highly corre-
882 lated because they are proxies. A model such as this, developed for determining the ac-
883 tual relationships, should test the slope of association with flux for each identified vari-
884 able. The validation correlation, of predictions with test set observations, is of much less
885 importance.

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891 The GOES-13 MAGED data and GOES Magnetometer 1 data used in the present
892 study are available at <https://www.ngdc.noaa.gov/stp/satellite/goes/dataaccess.html>.
893 Solar wind parameters and magnetic indices were obtained from OMNIWeb (<https://omniweb.gsfc>
894 [219 .nasa.gov/form/dx1.html](https://omniweb.gsfc.nasa.gov/form/dx1.html)).

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