Novel Approach to Autonomous Mosquito Habitat Detection using Satellite Imagery and Convolutional Neural Networks for Disease Risk Mapping

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Abstract

Mosquitoes are known vectors for disease transmission that cause over one million deaths globally each year. The majority of natural mosquito habitats are areas containing standing water such as ponds, lakes, and marshes. These habitats are challenging to detect using conventional ground-based technology on a macro scale. Contemporary approaches, such as drones, UAVs, and other aerial imaging technology are costly when implemented. Multispectral imaging technology such as Lidar is most accurate on a finer spatial scale whereas the proposed convolutional neural network(CNN) approach can be applied for disease risk mapping and further guide preventative efforts on a more global scale. By assessing the performance of autonomous mosquito habitat detection technology, the transmission of mosquito borne diseases can be prevented in a cost-effective manner. This approach aims to identify the spatiotemporal distribution of mosquito habitats in extensive areas that are difficult to survey using ground-based technology by employing computer vision on satellite imagery. The research presents an evaluation and the results of 3 different CNN models to determine their accuracy of predicting large-scale mosquito habitats. For this approach, a dataset was constructed utilizing Google Earth satellite imagery containing a variety of geographical features in residential neighborhoods as well as cities across the world. Larger land cover variables such as ponds/lakes, inlets, and rivers were utilized to classify mosquito habitats while minute sites such as puddles, footprints, and additional human-produced mosquito habitats were omitted for higher accuracy on a larger scale. Using the dataset, multiple CNN networks were trained and evaluated for accuracy of habitat prediction. Utilizing a CNN-based approach on readily available satellite imagery is cost-effective and scalable, unlike most aerial imaging technology. Testing revealed that YOLOv4 obtained greater accuracy in mosquito habitat detection than YOLOR or YOLOv5 for identifying large-scale mosquito habitats. YOLOv4 is found to be a viable method for global mosquito habitat detection and surveillance.

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Sriram Elango & Nandini Ramachandran Mentors: Rusty Low, Peder Nelson, Cassie Soeffing



Introduction



Results

Through analysis and experimentation utilizing the different convolutional networks and the corresponding frameworks, it was found that YOLOv4 performed with extreme accuracy and precision, identifying most mosquito habitats with extreme speed.

Ground Truth Annotation



YOLOv4



YOLOv5

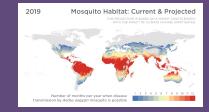


YOLOR



Conclusion

are the quickest, most efficient, and cost effective way to go, YOLOv4 performed with the highest accuracy among the 3 models with an average IoU score of 55.85%. The proposed solution can be implemented on a global scale using readily available satellite data. It can be used to aid in preventative measures of the global transmission of mosquito-borne vector map impoverished and hard to reach areas in order to determine mosquito migration patterns. Hotspots can be linked with the effects of climate change and variables such as soil moisture, temperature, and land use. There are a multitude of uses for mosquito habitat distribution data, and CNNs are a cost-



Limitation

Micro scale habitat data like smaller sites such as puddles, footprints, and tires tend to go unnoticed by this model as its scope is geared towards dealing with larger bodies of standing water. It also does not take into account nearby vegetation and weather-related data that may have an impact on breeding patterns and female oviposition. Future research could include an integration of such factors mentioned above to narrow the

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Bibliography

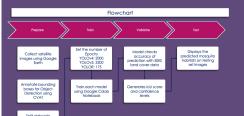
YOLOv4 (Alexey Bochkovskiy et al)

YOLOR (Chien-Yao Wang et al)

YOLOv5 (Glenn)



different CNN models (YOLOv4, YOLOv5, YOLOR). There are 4 steps involved in this process: Prepare, Train, Validate, and Test.







analyzed for accuracy of mosquito habitat detection and compared with



Mosquito habitats were classified in

the following groups: Ponds/Lakes,

River Inlets, Rivers. The annotated

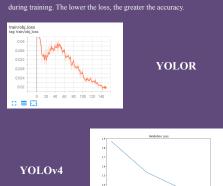
dataset of about 500 images was split ratio using Roboflow. The mages were exported using each

nodel's respective frameworks

YOLOR - TensorFlow)

 $\alpha \equiv \infty$

Training



YOLOv5