# Improved Neutral Density Predictions through Machine Learning Enabled Exospheric Temperature Model

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#### Abstract

The community has leveraged satellite accelerometer datasets in previous years to estimate neutral mass density and subsequently exospheric temperatures. We utilize derived temperature data and optimize a nonlinear machine-learned (ML) regression model to improve upon the performance of the linear EXTEMPLAR (EXospheric TEMPeratures on a PoLyherdrAl gRid) model. The newly developed EXTEMPLAR-ML model allows for exospheric temperature predictions at any location with a single model and provides performance improvements over its predecessor. We achieve a 4.2 K reduction in mean absolute error and a 3.42 K reduction in the standard deviation of the error. Like EXTEMPLAR, our model's outputs can be utilized by the Naval Research Laboratory Mass Spectrometer and Incoherent Scatter radar Extended (NRLMSISE-00) model to more closely match satellite accelerometer-derived densities. We conducted two case studies where we compare the CHAllenging Minisatellite Payload (CHAMP) and Gravity Recovery and Climate Experiment (GRACE) accelerometer-derived temperature and density estimates to NRLMSISE-00, EXTEMPLAR, and EXTEMPALR-ML during two major storm periods. The storm-time temperature comparison showed error reductions of 7-10% and 2-5% relative to NRLMSISE-00 and EXTEM-PLAR, respectively, and the density comparison showed error reductions of 20-55% and 8-12%. We use Principal Component Analysis to identify the dominant modes of variability in the model over one solar cycle. This shows the model is dominantly driven by solar activity, and there is a strong latitudinal variation related to the Summer and Winter hemispheres.

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7	Key Points:
8	• We develop a nonlinear global model for exospheric temperature prediction called
9	EXTEMPLAR-ML.
10	• We leverage Principal Component Analysis to improve our understanding of the EXTEMPLAR-
11	ML temperature formulation.
12	<ul> <li>EXTEMPLAR-ML shows increased accuracy relative to satellite observations during</li> </ul>
13	strong geomagnetic storms.

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## 14 Abstract

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# **Solution** Plain Language Summary

Density in the upper atmosphere is highly variable and difficult to model. Empirical 36 density models often rely on temperature profile predictions to determine species and mass 37 densities. One of three key parameters in determining the temperature profiles is the asymp-38 totic value at the top of the thermosphere, called the exospheric temperature. By using tem-39 peratures derived from satellite acceleration measurements, we develop a machine-learned 40 global temperature model called EXospheric TEMPeratures on a PoLyherdrAl gRid Machine 41 Learned (EXTEMPLAR-ML). We achieve a 4.2 K reduction in mean absolute error and a 42 3.42 K reduction in the standard deviation of the error relative to the model's predecessor. 43 We also look at temperatures and densities along satellite orbits during two major geomag-44 netic storms from the 21<sup>st</sup> century. In this study, we see major improvements over a signif-45 icant empirical model called NRLMSISE-00 and the linear predecessor to EXTEMPLAR-46 ML. We also use a mathematical decomposition tool on the model outputs to assess its inter-47 nal formulation. This shows that EXTEMPLAR-ML is most heavily driven by solar activity 48 and the seasons. 49

## 50 **1 Introduction**

Thermospheric mass density modeling is vital to satellite tracking and orbit prediction, 51 yet it remains a formidable task for researchers and operators. The thermosphere is highly 52 driven by external forcings, such as space weather events, and complex internal dynam-53 ics. The primary external driver to the thermosphere is solar irradiance (Qian and Solomon 54 2011). A majority of the solar irradiance energy input to the thermosphere can be captured 55 with various solar indices and proxies (Bowman and Tobiska 2006). Although, these model 56 drivers become less effective during solar minimum where other processes (e.g. composition 57 changes) become increasingly relevant (Bowman et al. 2008, Mehta et al. 2019). Other space 58 weather events, such as coronal mass ejections and solar flares, can send mass and energy towards Earth. This interacts with the magnetosphere resulting in Joule heating and particle 60 precipitation which can cause large, sudden changes in density (Fedrizzi et al. 2012, Deng 61 et al. 2013). 62

Nitroc oxide (NO) is a cooling mechanism responsible for long-term cooling trends
 present during solar minimum (*Kockarts* 1980), and short-term temperature decreases fol lowing large geomagnetic storms (*Mlynczak et al.* 2003, *Knipp et al.* 2017). Lei et al (2012a)
 found that for the 2003 Halloween storm, temperature and density post-storm were appre ciably lower than pre-storm levels. Many empirical models do not model this phenomena
 well and predict higher density in the recovery phase of major storms relative to observations
 (*Oliveira and Zesta* 2019, *Licata et al.* 2021b)

The Naval Research Laboratory Mass Spectrometer and Incoherent Scatter radar Ex-70 tended (NRLMSISE-00 but referred to in this paper as MSIS) is a commonly used empir-71 ical thermospheric density model (Picone et al. 2002). As with many models (e.g. DTM 72 (Bruinsma 2015) and JB2008 (Bowman et al. 2008)), MSIS heavily relies on temperature 73 profiles to determine species densities and therefore mass density throughout the thermo-74 sphere. A key parameter in predicting the temperature profile is the exospheric temperature 75  $(T_{\infty})$  which is the asymptotic value that the temperature profile approaches at the top of the 76 thermosphere, or thermopause (Bates 1959, Jacchia 1965). MSIS uses the Bates-Walker 77 temperature profile (Walker 1965). 78

The availability of accelerometer-derived density estimates, from satellite such as 79 CHAllenging Minisatellite Payload (CHAMP) and Gravity Recovery and Climate Experi-80 ment (GRACE), has been advantageous for model development and assessment (Luhr et al. 81 2002, Bettadpur 2012). Over the lifetime of satellites with onboard accelerometers, we ac-82 cumulate measurements over an abundance of locations and space weather conditions. Re-83 searchers have used these measurements to derive density estimates by removing accelera-84 tions from other sources (Sutton 2008, Doornbos 2012, Calabia and Jin 2016, Mehta et al. 85 2017). Weimer et al. (2016) used the density estimates from Mehta et al. (2017) to approxi-86 mate exospheric temperatures by varying the parameter in MSIS using the bisection method 87 until the model density closely matched that of the satellite. Weng et al. (2017) followed this 88 methodology and used Sutton's CHAMP density estimates to create an exospheric tempera-89 ture model. 90

Weimer et al. (2020) had used the derived exospheric temperatures to fit 1,620 lin ear models to make predictions on a polyhedral grid as a function of different space weather
 conditions over time. The model is called EXTEMPLAR (EXospheric TEMPeratures on a
 PoLyherdrAl gRid). In this work, we develop an improved exospheric temperature model by
 using a single nonlinear artificial neural network (ANN) to make predictions at any location.
 This global model is called EXTEMPLAR Machine Learned (EXTEMPLAR-ML).

Principal Component Analysis (PCA), also referred to as Empirical Orthogonal Func-97 tion (EOF) analysis or Proper Orthogonal Decomposition (POD), is used in this work to in-98 vestigate the most dominant modes of variability in EXTEMPLAR-ML. PCA has been used to analyze thermospheric density datasets previously and is often used in the development of 100 reduced-order models (Mehta and Linares 2017, Mehta et al. 2018, Gondelach and Linares 101 2020). PCA has also been used to study satellite accelerometer datasets (Matsuo and Forbes 102 2010, Lei et al. 2012b, Calabia and Jin 2016). Sutton et al. (2012) used PCA to produce ba-103 sis functions that represented the variability of temperature parameters used in an empirical 104 Jacchia family model to improve its nominal density formulation (Jacchia 1970). Ruan et 105 al. (2018) used CHAMP density estimates and a physics-based density model to develop an 106 exospheric temperature model based in PCA. ML models tend to be ambiguous in nature, so we utilize PCA only to improve our understanding of the physical processes that drive 108 EXTEMPLAR-ML, not for model development. 109

The paper is organized as follows, we start by detailing the model development. Then, we discuss the methodology for temperature and density prediction using the model. After, we look at a baseline global temperature map to compare to the preceding model. We then investigate the dominant modes and PCA coefficients across one solar cycle. As a case study, we compare the temperature and density predictions of MSIS, EXTEMPLAR and
 EXTEMPLAR-ML to CHAMP and GRACE-A during two major geomagnetic storms.

### 116 **2 Methodology**

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### 2.1 Model Development

We had access to over 81 million exospheric temperature estimates from Weimer et al. 118 (2020), the associated polyhedral grid locations, and different space weather indices/proxies 119 as potential drivers. The best linear model from previous work used  $S_{10}$ ,  $\sqrt{M_{10}}$ , Poynting 120 flux totals ( $S_N$  and  $S_S$ ), a temperature perturbation term ( $\Delta T$ ), day of year (doy), and univer-121 sal time (UT). The cooling effect of Nitric Oxide emissions was simulated in the calculation 122 of  $\Delta T$ . We set out to use only operational indices for EXTEMPLAR-ML so that it could be 123 used in real time. Therefore, we use  $S_{10}$ ,  $M_{10}$ ,  $S_N$ ,  $S_S$ , local solar time (LST), geodetic lati-124 tude, doy, and UT. The  $S_{10}$  and  $M_{10}$  indices are representative of solar activity and are part of 125 Space Environment Technologies' (SET) SOLAR2000 algorithm (Tobiska et al. 2000) which 126 has been recently benchmarked by Licata et al. (2020b). Descriptions of these indices are 127 thoroughly explained by Tobiska et al. (2008). The Poynting flux values are calculated us-128 ing an electrodynamics model (referred to as the W05 model) described by Weimer (2005a, 129 2005b). For doy and UT, the model uses sine and cosine functions of the fractional doy and 130 UT, generating four temporal inputs  $(t_1-t_4)$ , see Equation 1. 131

$$t_1 = \sin\left(\frac{2\pi doy}{365.25}\right)$$
  $t_2 = \cos\left(\frac{2\pi doy}{365.25}\right)$   $t_3 = \sin\left(\frac{2\pi UT}{24}\right)$   $t_4 = \cos\left(\frac{2\pi UT}{24}\right)$  (1)

<sup>132</sup> Upon having set up the data into inputs (described above) and labels (associated  $\log_{10}T_{\infty}$ ), <sup>133</sup> we leverage a tool called Keras Tuner (*O'Malley et al.* 2019). This allows us to provide a <sup>134</sup> range of hyperparameters upon which the tuner searches to find the best architecture/model <sup>135</sup> through a Bayesian optimization scheme. The tuner settings are shown in Table 1. The tuner <sup>136</sup> is provided 1 million random training samples and 200,000 validation samples.

Parameter	Choices
Number of Hidden Layers	1 – 10
Neurons	min = 64, max = 1024, step = 4
Activations	relu, softplus, tanh, sigmoid, softsign, selu, elu, linear
Dropout	min = 0.01, max = 0.50, step = 0.01
Optimizer	RMSprop, Adam, Adadelta, Nadam

Table 1. Hyperparameter search space for EXTEMPLAR-ML tuner.

Once complete, the tuner returns the ten best models, which we evaluate on indepen-138 dent data to confirm model performance. The best architecture to come out of the tuner is 139 displayed in Table 2. This model was trained further using 60 million random samples, with 140 the remaining 21 million used as validation/test data. Once the final model is developed, 141 we test its validity by first comparing its global temperature maps to that of its predecessor. 142 This is to check for anomalies in the temperature distributions for a given condition. While 143 EXTEMPLAR-ML is not restricted to prediction at the polyhedral grid locations, it still con-144 tains the name EXTEMPLAR, because it is trained on temperatures that are binned to those 145 locations. 146

- Table 2. Model architecture for the best model from the EXTEMPLAR-ML tuner.
- <sup>148</sup> There are 10 inputs for Layer 1.

	Neurons	Activation		<b>Dropout Rate</b>
Layer 1	780	elu		0.23
Layer 2	584	tanh		0.13
Layer 3	336	softplus		0.13
Output	1	linear		0.00

#### 149 **2.2 Principal Component Analysis**

Principal Component Analysis is an eigendecomposition technique that determines 150 uncorrelated linear combinations of the data that maximize variance (F.R.S. 1901, Hotelling 151 1933). As mentioned in the Introduction, PCA is widely used in thermospheric density and 152 exospheric temperature studies as both a modeling and analytical tool. We use PCA to get 153 insight into EXTEMPLAR-ML, which requires predictions covering a vast array of condi-154 tions. To accomplish this, we evaluated the model at all 1,620 EXTEMPLAR grid locations 155 between the solar maximums of solar cycle 23 and 24 (~2002-2014) at a three hour cadence. 156 These predictions provide the global evolution of exospheric temperatures spannig a solar 157 cycle. We perform PCA on the spatiotemporal temperature maps to obtain the U,  $\Sigma$ , and V 158 matrices. PCA decomposes the data and separates spatial and temporal variations such that: 159

$$\mathbf{x}(\mathbf{s},t) = \sum_{i=1}^{r} \alpha_i(t) U_i(s)$$
(2)

where  $\mathbf{x} \in \mathbb{R}^n$  is the model output state (full 2D temperature maps), r is the choice of order truncation,  $\alpha_i$  are temporal coefficients, and  $U_i$  are orthogonal modes or basis functions. The modes are the first r columns of the left singular vector derived by performing PCA on an ensemble of model output solutions such that:

$$\mathbf{X} = \begin{bmatrix} | & | & | & | \\ \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 & \dots & \mathbf{x}_m \\ | & | & | & | & | \end{bmatrix} \text{ and } \mathbf{X} = U\Sigma V^T$$
(3)

In Equation 3, *m* represents the ensemble size (one solar cycle). The temperature data is denoted by **X**. *U* is the left unitary matrix, and it is made of orthogonal vectors that represent the modes of variation.  $\Sigma$  is a diagonal matrix consisting of the squares of the eigenvalues that correspond to the vectors in *U*. We can extract temporal coefficients by performing matrix multiplication between  $\Sigma$  and  $V^T$ . Therefore, the signs of the modes and coefficients are important in the analysis phase.

#### 2.3 Geomagnetic Storm Case Study

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We look at a 48 hour period between 12:00 UT on July 26, 2004 to 12:00 UT on July 171 28, 2004. This encompasses a day-long geomagnetic storm with  $a_p$  peaking at 300 2nT. We 172 predict exospheric temperatures along the orbits of CHAMP and GRACE-A and compare it 173 to the satellite-derived temperatures, MSIS, and the best linear EXTEMPLAR model. We 174 perform a similar comparison across the three-day period of October 29-31, 2003. This was 175 one of the most significant geomagnetic storms of the  $21^{st}$  century, with  $a_p$  reaching 400 176 2nT on two separate occasions. We then look at the CHAMP and GRACE-A densities plot-177 ted against MSIS, MSIS + EXTEMPLAR, and MSIS + EXTEMPLAR-ML for the same two 178 periods. The density values for EXTEMPLAR and EXTEMPLAR-ML are obtained from 179 MSIS while bypassing the normal  $T_{\infty}$  calculation within MSIS, using the models' tempera-180 ture outputs instead, as described by Weimer et al. (2020). 181

# 182 **3 Results**

<sup>183</sup> Once we obtained the model described in Section 2.1, we evaluated it on all training <sup>184</sup> and validation data. This is shown in Figure 1. The top panel shows the original and pre-<sup>185</sup> dicted  $T_{\infty}$  values in a scatter plot with a background contour showing the absolute error. The <sup>186</sup> bottom panel shows the error distributions for training and validation samples.



Figure 1. Comparison of observed and predicted  $T_{\infty}$  for training (green) and validation (yellow) sets. The background contour shows mean absolute percent error for that temperature combination. The bottom panel shows histograms of error for both sets.

The  $T_{\infty}$  scatter plot is fairly centered on the 1:1 line, which indicates a zero-error pre-190 diction. There is a skew towards underprediction at very high temperatures. However, some 191 of these exospheric temperatures are not physical, due to some instances where an abnor-192 mally high temperature needs to be input to MSIS to obtain a match with the measured den-193 sity. A distinguishing feature in the top panel is the similarity between training and valida-194 tion performance. This indicates that the model is well-generalized and performs well on in-195 dependent/new data. The bottom panel of Figure 1 shows that the error distributions have 196 close to zero-mean, and over 98% of training and validation samples have less than 10% 197 error. The mean absolute error for training and validation are both 2.81%, confirming the 198

- generalized behavior of the model. Table 3 shows the mean absolute error and standard de-
- viation of the error for EXTEMPLAR-ML and the best linear EXTEMPLAR model from
- <sup>201</sup> Weimer et al. (2020), in Kelvin.

202	Table 3.	Model statistics for linear EXTEMPLAR (version 6) and EXTEMPLAR-ML.

Model	Mean Absolute Error	Standard Deviation
EXTEMPLAR v6	27.92 K	37.53 K
EXTEMPLAR-ML	23.72 K	34.12 K

EXTEMPLAR-ML achieves an absolute error reduction of over 4 K, and a reduction in the error standard deviation of over 3 K. As previously mentioned, the EXTEMPLAR-ML drivers are only a subset of the EXTEMPLAR version 6 (v6) drivers, in an effort to make the model operation-capable, which makes the performance improvement significant. Next, we evaluate EXTEMPLAR-ML for a global grid to compare Figure 2 (below) with Figure 4 from Weimer et al. (2020).



209	Figure 2. Global $T_{\infty}$ map with following inputs: $S_{10}=M_{10}=120$ sfu, $S_N=S_S=50$ GW, doy = 80,
210	and UT = 15 hours for EXTEMPLAR v6 (left) and EXTEMPLAR-ML (right). The black triangle
211	and square refer to the maximum and minimum temperature locations, respectively.

The global map has no clear defects and shows strong similarities to the EXTEMPLAR v6 map for the same conditions. The locations of maximum and minimum temperatures are also similar to the previous model. The main difference is in the low temperature region in the western hemisphere, where there is a larger region of < 834 K for EXTEMPLAR-ML. As there are only point estimates along orbits, there is no way to validate the global temperature maps, so we cannot confidently say which map is more accurate. However, we attribute this difference to the nonlinear temperature formulation by EXTEMPLAR-ML.

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# 3.1 Principal Component Analysis

With the extensive EXTEMPLAR-ML prediction set described in Section 2.2, we can investigate the most dominant modes of variability and their associated PCA coefficients.

- <sup>222</sup> This is shown in Figure 3. It is important to note that the data was not centered prior to per-
- forming PCA, so the first mode is representative of the mean temperature distribution over
- this period. The longitudinal coordinates are local solar time scaled to longitude values with

local noon being at  $0^{\circ}$ .



**Figure 3.** First three modes (left) and corresponding PCA coefficients (right) for the exospheric temperatures between November 1, 2001 and April 1, 2014. The most highly correlated drivers are plotted against the coefficients for comparison with the Pearson correlation coefficient shown in the title (*Schober et al.* 2018).

The first mode is representative of solar EUV heating denoted by the diurnal tempera-229 ture map and strong correlation with  $S_{10}$ . This mode accounts for over 80% of the system's 230 variance. Mode 2 represents a latitudinal Summer-Winter variation. There is a linear pro-231 gression of the mode with latitude and  $\alpha_2$  oscillated about zero with a period of 365 days. It 232 has an inverse relationship to  $t_2$ , described in Equation 1, and its amplitude is a function of 233 the solar activity. Mode 3 resembles a map of the magnetic field with the low latitude band 234 following the magnetic equator. There are also peaks in the poles, and  $\alpha_3$  most strongly cor-235 relates with the Poynting flux totals (~0.64 with  $S_N$  and  $S_S$ ). We suspect this mode corre-236 sponds to the effects of high latitude heating from either Joule heating or electron precipita-237 tion. 238

# 3.2 Modeled vs Observed Temperature Along Orbits

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In an effort to compare model performance between other temperature models and the observations, we evaluate the MSIS (unmodified), EXTEMPLAR v6, and EXTEMPLAR-ML exospheric temperature values along CHAMP and GRACE-A orbits for two storm periods. The first is the 48 hour period between 12:00 UT on July 26, 2004 to 12:00 UT on July 28, 2004. The results are shown in Figure 4.



Figure 4.  $T_{\infty}$  for MSIS, EXTEMPLAR v6, EXTEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for a July 2004 geomagnetic storm.

In the pre-storm period (top panel), both EXTEMPLAR models adequately track the 247 satellites while MSIS overpredicts. During the early phase of the storm, both EXTEMPLAR 248 models still track the observations well, but the linear model becomes more sporadic around 249 10:00 UT on July 27th. Both models far outperform MSIS in the second panel. The third 250 panel shows the storm recovery where EXTEMPLAR-ML tracks the observations most 251 closely, and EXTEMPLAR v6 overpredicts. In the last twelve hours, both EXTEMPLAR 252 models do well, and MSIS overpredicts. The mean absolute error for EXTEMPLAR-ML is 253 5.84% and 4.85% with respect to CHAMP and GRACE-A. For EXTEMPLAR v6, the mean 254 absolute error is 8.55% and 7.46% with respect to CHAMP and GRACE-A. MSIS has the 255 highest errors with 15.05% and 12.86% with respect to CHAMP and GRACE-A. Figure 5 256 shows a similar comparison for a 72-hour period encompassing the 2003 Halloween storm. 257

EXTEMPLAR-ML tracks the trends in both satellites for all 12-hour windows. Like 260 the other two models, it has a more general response and does not track the abrupt peaks that 261 are likely a result of imperfections in data processing. EXTEMPLAR struggles for brief pe-262 riods and MSIS has a mixed response with respect to accuracy. The mean absolute error for 263 EXTEMPLAR-ML is 6.26% and 5.64% with respect to CHAMP and GRACE-A. For EX-264 TEMPLAR v6, the mean absolute error is 10.89% and 9.98% with respect to CHAMP and 265 GRACE-A. MSIS has the highest errors with 15.91% and 13.03% with respect to CHAMP 266 and GRACE-A. 267

## **3.3 Modeled vs Observed Density Along Orbits**

We input the exospheric temperatures from Figures 4 and 5 into MSIS in order to obtain the associated mass density values along the CHAMP and GRACE-A orbits. Figure 6



Figure 5.  $T_{\infty}$  for MSIS, EXTEMPLAR v6, EXTEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for the 2003 Halloween Storm.

- shows the modeled densities, including the unmodified MSIS values, along with the satellite
   density estimates for the July 2004 storm.
- The overprediction of exospheric temperature by MSIS in the first 12 hours, seen in 275 Figure 4, causes its modeled density to be notably higher than the observed values. Both 276 EXTEMPLAR models provide similar accuracy pre-storm, but EXTEMPALR-ML more 277 closely matches the CHAMP and GRACE-A estimates during the storm. In the recovery 278 phase, EXTEMPLAR-ML densities are more similar to GRACE-A than to CHAMP. The 279 mean absolute error for EXTEMPLAR-ML is 19.13% and 20.81% with respect to CHAMP 280 and GRACE-A. For EXTEMPLAR v6, the mean absolute error is 27.78% and 32.33% with 281 respect to CHAMP and GRACE-A. MSIS has the highest errors with 62.32% and 75.38% 282 with respect to CHAMP and GRACE-A. Figure 7 shows the density variations resulting from 283 the temperatures in Figure 5. 284



Figure 6. Density for MSIS, EXTEMPLAR v6, EXTEMPLAR-ML plotted alongside CHAMP (left) and
 GRACE-A (right) for a July 2004 geomagnetic storm.

EXTEMPLAR-ML tracks the satellite densities well for the entire three-day period. 287 The performance enhancement is most notable in the recovery phase (bottom panel) where 288 the other two models tend to overpredict. The ability to capture the anomalously low temper-289 ature and density from enhanced NO production following a shock-led geomagnetic storm is 290 highly desired as this prolonged period of lower than expected density can result in substan-291 tially different satellite positions in the context of conjunction analyses (Oliveira and Zesta 292 2019). The mean absolute error for EXTEMPLAR-ML is 14.43% and 15.94% with respect 293 to CHAMP and GRACE-A. For EXTEMPLAR v6, the mean absolute error is 24.62% and 294 25.34% with respect to CHAMP and GRACE-A. MSIS has the highest errors with 35.39% 295 and 35.97% with respect to CHAMP and GRACE-A. 296

#### <sup>297</sup> 4 Summary

In this work, we developed and optimized a machine learned nonlinear regression 298 model to predict exospheric temperatures given a set of operational Space Weather and tem-299 poral drivers. This model, called EXTEMPLAR-ML, has nearly identical training and vali-300 dation/test performance with 2.81% mean absolute error across 81 million available samples. 301 This is an extension of a linear EXTEMPLAR model developed by Weimer et al. (2020). 302 Using fewer drivers, EXTEMPLAR-ML outperforms EXTEMPLAR with a 4.20 K decrease 303 in absolute error and a 3.41 K decrease in the error standard deviation. An advantage of 304 EXTEMPLAR-ML is that the single model can provide temperature predictions at any lo-305 cation, which was a limitation of its predecessor. The use of PCA provided insight to the 306 temperature formulation within the "black-box" ML model. The first mode represented the 307 effects of solar EUV heating and accounted for 81% of the system's variance. Latitudinal 308 variations accounted for the next 4.75% of the variance and were still a function of solar ac-309



Figure 7. Density for MSIS, EXTEMPLAR v6, EXTEMPLAR-ML plotted alongside CHAMP (left) and GRACE-A (right) for the 2003 Halloween Storm.

tivity. The last mode we looked at only accounted for 1.28% of the variance but described the effects of high latitude heating caused by geomagnetic storms.

We performed two case studies where EXTEMPLAR-ML along with EXTEMPLAR 312 v6 and MSIS predicted  $T_{\infty}$  along CHAMP and GRACE-A orbits during two major geo-313 magnetic storms. In the July 2004 storm, EXTEMPLAR-ML achieved error reductions 314 along both CHAMP and GRACE-A's orbits ranging from 2.07-9.35% compared to EXTEM-315 PLAR v6 and MSIS. In the 2003 Halloween storm, EXTEMPLAR v6 struggled during pe-316 riods, leading to a higher error reduction of 4.57% and 3.97% with respect to CHAMP and 317 GRACE-A. When these temperatures were used for density prediction, the relative accuracy 318 of EXTEMPLAR-ML became more pronounced. The error reduction from EXTEMPLAR 319 in terms of the resulting density ranged from 8-11% and 9-12% with respect to CHAMP and 320 GRACE-A, respectively for the two storms. In the future, we plan to incorporate model un-321 certainty into EXTEMPLAR-ML (Licata et al. 2020a, Licata and Mehta 2021, Licata et al. 322 2021a). We plan to develop a newer model using temperatures derived with NRLMSIS 2.0 323

(*Emmert et al.* 2021). With the successive model, we also plan to use the exact observation locations to reduce errors associated with binning measurements to the polyhedral grid.

# 326 Data Availability Statement

CHAMP and GRACE density estimates from (*Mehta et al.* 2017) can be found at http://tinyurl.com/densitysets. A data archive containing the supplemental graphs of neutral density predictions can be accessed online (at https://doi.org/10.5281/ zenodo.3525166). Also contained here are the adjustments to the NRLMSISE-00 model supplied by J. Emmert; the total Poynting flux into both Northern and Southern Hemispheres from the Weimer 2005 model, for years 2002–2017; the derived  $\Delta$ T values; and EXTEM-PLAR model code with the required files.

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