

An ensemble-based eddy and spectral analysis, with application to the Gulf Stream

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Abstract

The ‘eddy’ ocean, recognized for several decades, has been the focus of much observational and theoretical research. We here describe a generalization for the analysis of eddy energy, based on the use of ensembles, that addresses two key related issues: the definition of an ‘eddy’ and the general computation of energy spectra. An ensemble identifies eddies as the unpredictable component of the flow, and permits the scale decomposition of their energy in inhomogeneous and non-stationary settings. We present two distinct, but equally valid, spectral estimates: one is similar to classical Fourier spectra, the other reminiscent of classical EOF analysis. Both satisfy Parseval’s equality and thus can be interpreted as length-scale dependent energy decompositions. The issue of ‘tapering’ or ‘windowing’ of the data, used in traditional approaches, is also discussed. We apply the analyses to a mesoscale ‘resolving’ ($1/12^\circ$) ensemble of the separated North Atlantic Gulf Stream. Our results reveal highly anisotropic spectra in the Gulf Stream and zones of both agreement and disagreement with theoretically expected spectral shapes. In general, we find spectral slopes that fall off faster than the steepest slope expected from quasi-geostrophic theory.

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28 from quasi-geostrophic theory.

29 **Plain Language Summary**

30 The ocean displays ‘weather’ in a manner analogous to the atmosphere, even if it
31 is characterized by much different length and time scale. Such oceanographic variabil-
32 ities are referred to as ‘eddies’, and they are known to be important to the participation
33 of the ocean in climate. The oceanographic community therefore has a strong interest
34 in eddies and their physical description. Here, by using numerical simulations of the North
35 Atlantic Ocean, we describe and employ a new statistical method to define and ana-
36 lyze eddies. Among the advantages of our technique is its applicability to the normally
37 complex settings of most geophysical interest.

38 **1 Introduction**

39 That the ocean is ‘turbulent’, i.e. energetically variable in time and space, has been
40 known for several decades. A useful overview of the field circa 1980 is provided by Wunsch
41 (1981) where a discussion of several open questions about eddies at that time appears,
42 along with the recognition that the definition of an ‘eddy’ was an elusive thing. In the
43 decades since, appreciation of the dynamical significance of ocean variability has grown,

44 alongside the discovery of novel forms of variability, such as the ocean sub-mesoscale. The
45 almost impossibly large number of contributions are usefully reviewed in Hecht and Ha-
46 sumi (2008) and McWilliams (2016). Powerful new tools for the study of eddies have ap-
47 peared, such as gliders, satellites and numerical models and large organized efforts have
48 grown in order to implement them, such as the ARGO program and the various model
49 intercomparison initiatives.

50 Interest in the dynamical effects of eddies on climate projection has also invigorated
51 the study of eddy-parameterization, i.e. the restatement of feedback of ocean variabil-
52 ity on the ‘mean’ flow as a function of the resolved variables. As emphasized in several
53 publications by Berloff and collaborators, almost all eddy parameterizations appeal to
54 some form of a space-time filtering, leaving the definitions of both the mean and eddies
55 ambiguous at the level of the filtering parameters (cf. Bachman et al., 2015; Gent & McWilliams,
56 1990; Zanna et al., 2017). Berloff et al. (2021) is an interesting attempt to develop more
57 general parameterizations independent of the filtering process.

58 A traditional, perhaps ‘the’ traditional, measure of the eddy field is the kinetic en-
59 ergy spectrum, which is the distribution of the energy in the eddy field in the wavenum-
60 ber, frequency or wavenumber-frequency domain. At a basic level, a spectrum is a pow-
61 erful descriptor of the eddy field, useful for several quantitative purposes and provides
62 fundamental measures that should guide eddy parameterizations. At a deeper level, the
63 shape of the spectrum can lead to important clues about dynamical processes control-
64 ling the eddy field, with well-known examples being those for quasi-geostrophy (QG; Char-
65 ney, 1971) and surface quasi-geostrophy (SQG; Held et al., 1995; Lapeyre & Klein, 2006).
66 Indeed with the advent of global surface observations from satellites and eddy-resolving
67 models, there has been an emphasis in the physical oceanographic community on quan-
68 tifying the wavenumber spectral slopes of mesoscale eddies (Capet et al., 2008a; Callies
69 & Ferrari, 2013; Khatri et al., 2018). The general understanding has been that the en-
70 ergetic western boundary current and Antarctic Circumpolar Current (ACC) regions,
71 are a mixture of QG, mixed-layer instabilities (MLIs) and internal waves while the qui-
72 escent regions are governed by SQG and frontogenesis (Xu & Fu, 2011, 2012; Rocha, Gille,
73 et al., 2016; Vergara et al., 2019; Cao et al., 2019; Dong et al., 2020; Khatri et al., 2021).

74 The derivations of the QG and SQG spectral shapes rest on a number of assump-
75 tions that render the problem tractable. Amongst the most essential, in addition to quasi-

76 geostrophy, are those of statistical stationarity and spatial homogeneity. Implicit also
77 are the assumptions that mean fields are irrelevant and forcing is constant.

78 These are constraints which clearly do not apply to most oceanographic settings.
79 For example, the Gulf Stream possesses a very strong and structured mean flow to which
80 the eddy field is sensitive. Any Gulf Stream mean flow also almost certainly represents
81 a response to a temporally variable atmospheric forcing. Characterizations of this sort
82 are not restricted to the Gulf Stream, but can arise in virtually any part of the ocean.
83 Immediate connections to theoretical predictions are thus somewhat obscured, but one
84 hopes that the predictions represent demonstrations of general statements which have
85 been derived in special settings.

86 To test this idea requires calculations of spectra that are valid in the inhomoge-
87 neous and non-stationary regions of geophysical interest. Traditional spectra, in contrast,
88 employ assumptions of stationarity and homogeneity and process the data prior to anal-
89 ysis in ways that distort the underlying structure and thus interfere with their ultimate
90 interpretation. The results are therefore somewhat suspect in their validity. We argue an-
91 alyzing ensembles of models permits calculation of spectra in non-stationary and inho-
92 mogeneous settings. Admittedly, modeling is special in that an ensemble can be built,
93 as opposed to observations, where all that exists is the single, observed realization. A
94 lofty, long-term goal is the development of ways to view the single, observed realization
95 as a member of an ensemble, thus embedding its interpretation within an ensemble frame-
96 work.

97 This paper has two objectives. The first objective is to address the above issues
98 within the context of numerical modeling by exploiting the relatively recent methodol-
99 ogy of ocean ensemble generation. Two methods for spectral calculation are proposed
100 that provide complementary views of the eddy energy field. Both satisfy Parseval's equal-
101 ity, and therefore can be interpreted as wavenumber dependent energy spectra. The first
102 is a relatively straightforward generalization of classical spectral analysis, while the sec-
103 ond is related to empirical orthogonal function theory already widely used in oceanog-
104 raphy. The latter technique has also been employed by the turbulence community (Lumley,
105 1970; Berkooz et al., 1993; Moser, 1994). These two techniques provide complementary
106 views of the eddy energy field. The second objective is to apply the techniques to the
107 separated Gulf Stream region as a proof of concept and to comment on the local eddy

108 spectra. Accordingly, we find our results are somewhat at odds with previous spectral
109 estimates in the Gulf Stream and we find departures from theoretical power law behav-
110 iors. The results also comment on the assumptions of isotropy that are often built into
111 classical spectral analysis.

112 The next section introduces ensemble based mean and eddy definitions and reviews
113 the basics of Fourier spectral analysis. We then describe our procedures for energy spec-
114 tral computation and argue their roles as generalizations of the Fourier spectral approach
115 to inhomogeneous and non-stationary settings. The application of these procedures to
116 the separated Gulf Stream appears in Section 3 and we end with a brief summary and
117 discussion of further applications and developments.

118 **2 Fundamentals**

119 Ensemble modeling, long a practice in meteorology, has only recently gained trac-
120 tion in oceanography. A recent QJRMS special issue (Buizza, 2018) reviewed the last
121 few decades of ensemble studies, in which only one paper discussed ocean ensembles (Zanna,
122 2018). Perhaps the most widely recognized ocean ensemble is from the French OCCIPUT
123 effort (Penduff et al., 2011), consisting of 50 global ocean simulations at eddy-permitting
124 0.25° resolution. More recently, Jamet et al. (2019) and Jamet et al. (2020) analyze a
125 regional North Atlantic ensemble consisting of 60 members in various configurations at
126 an eddying $1/12^\circ$, and Aoki et al. (2020) discuss an 80-member $1/36^\circ$ eddy-resolving re-
127 gional Kuroshio model. It is clear that oceanography is still in the early stages of exploit-
128 ing ensemble methodologies, particularly at resolutions adequate to reliably host mesoscale
129 eddy dynamics.

130 **2.1 Ensemble Means Versus Classical Means**

131 As emphasized above, the idea of an ensemble is rooted in numerical simulation,
132 where collections of possible solutions of the governing equations can be analyzed. Ob-
133 servations, in contrast, are unique; no other observed ensemble members can be obtained.
134 But, if numerical simulation is to be believed, observations are composed of both mean
135 and eddy components, and represent a single realization of the dynamical state of the
136 ocean. It is here that analyzing a numerical ensemble can assist in rationally decompos-
137 ing observations into a ‘mean’ flow with superposed ‘eddies’.

138 Consider a collection of spatially and temporally variable data, $f_i(\mathbf{x}, t)$, where i
 139 notes the i^{th} member of a set of size N . Numerically, this collection will have been gen-
 140 erated by solving the equations of motion subject to specified forcing, initial and bound-
 141 ary conditions. A common procedure for ensemble generation, used in this study, involves
 142 holding forcing and boundary conditions fixed and varying initial conditions. Given the
 143 chaotic nature of the fluid equations, different initial conditions develop into different
 144 flows that, due to their adherence to the equations, are nonetheless dynamically consis-
 145 tent states.

An ensemble mean can be formed via

$$\langle f(\mathbf{x}, t) \rangle = \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x}, t), \quad (1)$$

146 representing that part of the original data present in all the members. We refer to this
 147 quantity as the ‘mean’ flow. Since the collection possesses common forcing and bound-
 148 ary conditions, we will interpret the mean as reflecting the presence of those features through-
 149 out the domain. In this sense, the ‘mean’ is the predictable, or reproducible, component
 150 of the flow.

151 The fluctuations about the mean for each member, $f'_i(\mathbf{x}, t) = f_i(\mathbf{x}, t) - \langle f(\mathbf{x}, t) \rangle$,
 152 are dynamical contributions to the data not common across the members, and arise due
 153 to the differing initial conditions. The nonlinearity in the equations essentially assures
 154 us that small initial differences lead to large differences in dynamical state over relatively
 155 short times. Defining the ‘eddies’ as f'_i identifies them as the effectively unpredictable
 156 components of the flow. Of course, both the mean and the eddies have some dependence
 157 on the ensemble size, N , but presumably converge to unique statements as N grows.

In contrast, the means that can be formed from a single realization, such as

$$\overline{f(\mathbf{x}, t)} = \frac{1}{T} \int_t^{t+T} f(\mathbf{x}, t) dt, \quad (2)$$

158 for a temporal mean, depend explicitly on the parameter T . The ‘eddies’ associated with
 159 (2) are obtained as the residuals about the mean and also reflect T . Neither the mean
 160 nor the eddies converge to unique statements as T grows. Since there is no basis for the
 161 choice of this parameter, both the mean and eddies are somewhat ambiguous. It is also
 162 common practice when analyzing observations to invoke an assumption of stationarity,
 163 or equivalently that the value of the absolute time t doesn’t matter. This is a question-
 164 able assumption for most parts of the ocean. It is possible to partially remedy any such

165 concerns by performing conditional averages, such as by averaging over the so-called *DJF*
 166 winter months for several consecutive years. But even then, the assumption is made that
 167 the value of the year is unimportant, which is again questionable given interannual vari-
 168 ability.

169 These confounding issues do not plague ensembles, leading us to our first propo-
 170 sition that (1) yields an unambiguous statement of what is meant by the mean flow and
 171 eddies. In this definition, it is recognized that any inhomogeneity or non-stationarity of
 172 the eddy field is captured.

173 2.2 Overview of Fourier spectra

174 We briefly review classical spectral analysis focussing on spatial spectra, although
 175 similar techniques apply to frequency spectra.

In any practical situation, we have spatially finite data, $u(\mathbf{x})$, over a domain A . The data can be forced into a periodic form by tapering it such that the data goes to zero at the domain edges, and then repeating the data indefinitely in space. A Fourier series representation for a purely periodic function always exists, and, calling u_w the tapered data, is

$$u_w(x, y) = \sum_{(n,m)=0}^{\infty} \hat{u}_{w;n,m} e^{-2\pi i(\frac{nx}{L_x} + \frac{my}{L_y})}, \quad (3)$$

where $\mathbf{x} = (x, y)$ and L_x, L_y are the spatial periodicities of u_w , such that

$$u_w(x, y) = u_w(x + pL_x, y + qL_y). \quad (4)$$

The quantities p, q are integers. For the remainder of the study, we only consider the eddy field (u_w, \mathbf{u}) obtained by removing the ensemble mean. The Fourier coefficients are given by

$$\hat{u}_{w;n,m} = \frac{1}{A} \int_0^{L_x} \int_0^{L_y} u_w(\mathbf{x}) e^{2\pi i(\frac{nx}{L_x} + \frac{my}{L_y})} dx dy, \quad (5)$$

176 where $A = L_x L_y$ is domain area.

We can form the product $e_{w;n,m} = \hat{u}_{w;n,m} \hat{u}_{w;n,m}^*$ where the $*$ denotes a complex conjugate. A fundamental idea behind spectral analysis is that the data u_w is random, and hence that $e_{w;n,m}$ is also random, if non-negative. Averaging is required to arrive at an estimate of the underlying spectrum. The theory behind spectral analysis assumes that an ensemble average is performed. In practice, there are several techniques that are used for averaging. Standard techniques include averaging neighboring spectral estimates,

or the original data is broken into several pieces and the spectral estimates at each wavenumber from the various areas are averaged. Note that in this process windowing necessarily impacts the domain scale spectral estimates. If the underlying fields are homogenous, the result is an estimate of an ensemble average. Denoting the average by brackets, $\langle \cdot \rangle$

$$\langle \hat{u}_{w;n,m} \hat{u}_{w;n,m}^* \rangle = \frac{1}{A^2} \int_{\mathbf{x}} \int_{\boldsymbol{\psi}} \langle u_w(\mathbf{x}) u_w(\boldsymbol{\psi}) \rangle e^{2\pi i \left(\frac{n(x-\psi)}{L_x} + \frac{m(y-\eta)}{L_y} \right)} d\boldsymbol{\psi} d\mathbf{x}, \quad (6)$$

where $\boldsymbol{\psi} = (\psi, \eta)$ denote location. At this point, the assumption of spatial homogeneity is explicitly introduced by saying that the statistics of the field depend only on separation in each of the spatial dimensions

$$\langle u_w(\mathbf{x}) u_w(\boldsymbol{\psi}) \rangle = \rho_{uu}(|x - \psi|, |y - \eta|). \quad (7)$$

The Fourier transform of the two point correlation function ρ_{uu} can now be computed and is usually written in the form

$$\langle \hat{u}_{w;n,m} \hat{u}_{w;n,m}^* \rangle = E_{uu;n,m}^w, \quad (8)$$

177 where the Fourier transform of ρ_{uu} is written $E_{uu;n,m}^w$, and interpreted as (twice) the spec-
178 tral energy density of the spatial series $u_w(\mathbf{x})$.

This interpretation comes from Parseval's theorem, i.e.

$$\sum_{(n,m)=0}^{\infty} E_{uu;n,m}^w = \frac{1}{A} \int_{\mathbf{x}} \langle u_w(\mathbf{x})^2 \rangle d\mathbf{x}, \quad (9)$$

179 as can be shown from (6), arguing that the ensemble mean energy in domain A can be
180 broken into contributions of energy $E_{uu;n,m}^w$ in the waveband n, m . An additional assump-
181 tion of isotropy is sometimes invoked, which further reduces the correlation function from
182 $\rho_{uu}(|x-\psi|, |y-\eta|)$ to $\rho_{uu}(|\mathbf{x}-\boldsymbol{\psi}|)$. Well-known issues with this classical approach are
183 that (1) in important parts of the ocean, like the separated Gulf Stream jet, the assump-
184 tions of homogeneity and isotropy are not justifiable, (2) the additional assumption of
185 stationarity in the view of seasonality and intrinsic variability is suspect and (3) the need
186 to taper the data also complicates the understanding of the results.

187 **2.3 An Ensemble Based Generalization of Spectra**

188 **2.3.1 The Classical Approach**

Perhaps the simplest and most straightforward way to use ensembles to avoid the above mentioned issues is to replace the averaging methods in (6) by an ensemble average, denoted by angle brackets $\langle \cdot \rangle$. A somewhat subtler point is that this can be done

on the Fourier transform of the original data, rather than the Fourier transform of the windowed data, where longer length scales have fewer degrees of freedom due to the windowing. (A broader discussion of the issues associated with windowing is provided in the Appendix A.) Referring to the latter as $\hat{u}_{n,m}$, the spectral energy estimate becomes

$$E_{uu;n,m}^w = \langle \hat{u}_{n,m} \hat{u}_{n,m}^* \rangle. \quad (10)$$

It is straightforward to show (10) satisfies Parseval's equality based on the original data

$$\sum_{(n,m)=0}^{\infty} E_{uu;n,m}^w = \frac{1}{A} \int_{\mathbf{x}} \langle u(\mathbf{x})^2 \rangle d\mathbf{x}, \quad (11)$$

rather than the windowed data. This permits the interpretation of $E_{uu;n,m}^w$ as the wavenumber dependent decomposition of (twice) the ensemble mean kinetic energy of the eddies. In addition, the spectra belongs to the region A ; i.e. no assumptions of homogeneity are involved and the wavenumber decomposition is that of the domain.

2.3.2 An EOF Based Approach

A different, but equally valid empirical orthogonal function (EOF) based decomposition was proposed by Moser (1994), who was interested in three-dimensional, inhomogeneous turbulence. Consider the integral equation

$$\int_{\mathbf{x}'} r_{ij}(\mathbf{x}, \mathbf{x}') \phi_j(\mathbf{x}') d\mathbf{x}' = \lambda \phi_i(\mathbf{x}) \quad (12)$$

where $r_{ij} = \langle u_i(\mathbf{x}) u_j(\mathbf{x}') \rangle$ is the two point, $(\mathbf{x}, \mathbf{x}')$, covariance matrix of a velocity field. The subscripts i, j track the velocity components, the brackets $\langle \cdot \rangle$ again denote an ensemble average and repeated indices i, j imply summation. Equation (12) defines an eigenfunction/eigenvalue $(\phi_i(\mathbf{x}), \lambda)$ problem which, as pointed out by Berkooz et al. (1993), is a classic problem in the calculus of variations. Specifically, that problem is to find the (eigen)functions ϕ_i , from the class of all functions, which are 'most similar' to the velocities, u_i^n , of all the ensemble members. The resulting decomposition into the set of functions $\phi_i(\mathbf{x})$ arises in several branches of physics. In the turbulence community, this is known as the Proper Orthogonal, or Karhunen-Loeve, decomposition (Lumley, 1970; Berkooz et al., 1993); in oceanography, the eigenmodes are equivalent to EOFs (Preisendorfer & Mobley, 1988).

First, note if r_{ij} is homogeneous, which for a finite sized observation set implies periodicity, then the choice $\phi_j = e^{2\pi i \mathbf{k} \cdot \mathbf{x}}$ satisfies (12). Note this is true for both components of the of the velocity field, hence the insensitivity of the eigenmode to the index

208 j. Equivalently, Fourier modes act as the needed eigenfunctions in that case. Further,
 209 if the eigenfunctions are Fourier modes, r_{ij} must be homogeneous (Berkooz et al., 1993),
 210 so (12) defines Fourier modes as the proper expansion basis for homogeneous flows. The
 211 novelty of the analysis we present here comes when r_{ij} is not homogeneous, in which case
 212 (12) yields a more general spatial decomposition.

For simplicity of discussion and familiarity within oceanography, the integral equation in (12) will be converted to a discrete form, where it becomes a matrix equation. Restricting the discussion from here on to two horizontal dimensions of ensemble and space, (12) can be written

$$[R][\phi] = \lambda[\phi], \quad (13)$$

where

$$\begin{bmatrix} r_{1,1} & r_{1,2} \\ r_{2,1} & r_{2,2} \end{bmatrix} = [R],$$

and

$$[\phi] = \begin{bmatrix} \phi_1 \\ \phi_2 \end{bmatrix}.$$

To fit the form of (13), the data array \mathbf{u}_{ij} composed of velocity values at spatial location (x_i, y_j) multiplied by an area-like element (to account for the spherical coordinate in a consistent manner with MITgcm’s finite volume discretization; Appendix C), is converted to a vector $\mathbf{u}_{ij} \mapsto \mathbf{u}_{i+(n_x-1)j}$ of length $n_x n_y$ where n_x and n_y are the number of observations in the zonal and meridional directions, respectively. The matrix $[R]$ is of dimension $(2n_x n_y) \times (2n_x n_y)$ and $[\phi]$ is a vector of length $2n_x n_y$, there being two velocity components. The matrix $[R]$ is also symmetric, i.e. $R_{ij} = R_{ji}$ where i, j are row and column matrix locations, and therefore basic linear algebra assures us that $[R]$, $[\phi]$, and λ possess a number of properties. Principle among these is that $[R]$ can be diagonalized, i.e.

$$[R] = [\Phi]^T [\Lambda] [\Phi], \quad (14)$$

where $[\Phi]$ is a matrix whose i^{th} column is the eigenfunction ϕ^i and $[\Lambda]$ is a diagonal matrix whose (i, i) component consists of the eigenvalue λ^i associated with ϕ^i . The notation $[\Phi]^T$ denotes the transpose of the matrix $[\Phi]$. Further the eigenfunctions are orthogonal and can be normalized

$$[\Phi]^T [\Phi] = A \mathbf{I}, \quad (15)$$

213 where \mathbf{I} is the identity matrix and A is the domain area.

Another useful result of linear algebra is that the diagonalization in (14) implies the traces of the matrices $[R]$ and $[\Lambda]$ must be identical. Noting that

$$\begin{aligned} \text{tr}([R]) &= \sum_{i=1}^{2n_x n_y} \langle \mathbf{u}_i^T \mathbf{u}_i \rangle, \\ &= \langle u_1 u_1 \rangle + \dots + \langle u_{n_x n_y} u_{n_x n_y} \rangle + \langle v_1 v_1 \rangle + \dots + \langle v_{n_x n_y} v_{n_x n_y} \rangle \end{aligned} \quad (16)$$

is twice the ensemble-mean eddy kinetic energy, the sum of the eigenvalues measures the mean energy of the samples. In more familiar EOF language, the eigenvalue represents the fraction of the observational variance captured by its associated mode. We remind the reader that while it is common to define the eddy velocity (\mathbf{u}_i) as temporal anomalies in EOF analyses (e.g. Hannachi et al., 2007), here we define it as the fluctuations about the ensemble mean.

The full set of eigenfunctions, ϕ^k , is complete, so it is possible to represent each of the original ensemble members \mathbf{u}^n using the ϕ^k as a basis

$$\mathbf{u}^n(\mathbf{x}) = \sum_{k=1}^M a^{n;k} \phi^k(\mathbf{x}) \quad (17)$$

where the superscript n denotes the ensemble index, and k is the index of EOF mode. In principle, $M = 2n_x n_y$, as the matrix R is of size $2n_x n_y \times 2n_x n_y$. However, by appealing to singular value decomposition theory, the number of significant eigenvalues is set by the ensemble size. Using the orthogonality condition

$$\frac{1}{A} \int_{\mathbf{x}} \phi^i \cdot \phi^j d\mathbf{x} = \delta_{ij}, \quad (18)$$

equivalently (15) in its discretized form,

$$\begin{aligned} a^{n;k} &= \frac{1}{A} \int_{\mathbf{x}} \mathbf{u}^n \cdot \phi^k d\mathbf{x}, \\ &\simeq \sum_{i=1}^{2n_x n_y} u_i^n \phi_i^k \end{aligned} \quad (19)$$

with the spatial integrations equivalent to summing over discretized spatial points and $A = \int_{\mathbf{x}} d\mathbf{x}$. Note, unlike the standard approach where each velocity component is transformed independently, the EOF procedure operates directly on the full velocity vector. A single set of expansion coefficients, $a^{n;k}$, along with the vector-valued basis elements, $\phi^k = (\phi_1^k, \phi_2^k)$ exactly reconstructs both components of the velocity vector in any realization; the spatial distribution of u^n comes from the first half of ϕ^k (i.e. ϕ_1^k) and that of v^n from the second half (ϕ_2^k).

Inserting the decomposition given in (17) into the definition of the ensemble-mean eddy kinetic energy and using the orthogonality of the EOF basis implies

$$\sum_k \langle \mathbf{u}_k^n \mathbf{u}_k^n \rangle = \sum_k \langle a^{n;k} a^{n;k*} \rangle = \sum_k \lambda^k. \quad (20)$$

227 In other words, the sum of the expected variance of the coefficients $a^{n;k}$ is also twice the
 228 ensemble-mean eddy kinetic energy (Moser, 1994). Inasmuch as $a^{n;k}$ in the present case
 229 plays same the role as \hat{u}_n in a standard Fourier analysis, this completes the connection
 230 between the $\{\phi\}$ and Fourier bases. The expected value of the coefficient magnitudes
 231 can be related to the sample energy as in (20), which is effectively a Parseval's equal-
 232 ity. The difference here is the expansion basis is the vector valued set $\{\phi\}$, rather than
 233 the independent complex exponentials employed by Fourier analysis. Note also that it
 234 has not been necessary to taper the data.

At this point, what remains is to assign a length scale to each member of the set $\{\phi\}$. This is important for the application of the decomposition in tests of theory, as the equations of motion relate length scales, energy levels and parameters to expectations for spectral shape, as in Kolmogorov (1941). For Fourier modes, the length scale is obvious as the inverse of the wavenumber. Note, if ϕ is a Fourier complex exponential (viz. $\phi = e^{-i\mathbf{k}\cdot\mathbf{x}}$)

$$|\mathbf{k}| = \left[\frac{\int_{\mathbf{x}} |\nabla\phi|^2 d\mathbf{x}}{\int_{\mathbf{x}} |\phi|^2 d\mathbf{x}} \right]^{1/2}. \quad (21)$$

Equation (21) can also be applied to the eigenfunction to generate a lengthscale. In this paper, we define zonal (k) and meridional (l) wavenumbers independently according to

$$|k| = \left(\frac{1}{A} \int_{\mathbf{x}} (\phi_x)^2 d\mathbf{x} \right)^{1/2}, \quad (22)$$

and

$$|l| = \left(\frac{1}{A} \int_{\mathbf{x}} (\phi_y)^2 d\mathbf{x} \right)^{1/2}, \quad (23)$$

235 (recall that $\frac{1}{A} \int_{\mathbf{x}} \phi^2 d\mathbf{x} = 1$). The subscripts x and y denote partial derivatives.

2.3.3 Connections Between the Classical and EOF Based Spectra

The two techniques described above both decompose the same domain integrated kinetic energy, and so are related. To see this, note that the velocity realizations can be expressed in terms of Fourier transforms and EOFs as

$$u_i^s(\mathbf{x}) = \sum_{n,m} \hat{u}_{i;n,m}^s e^{-2\pi i(\frac{nx}{L_x} + \frac{my}{L_y})} = \sum_p a^{s;p} \phi_i^p(\mathbf{x}). \quad (24)$$

Each $\phi_i^p(\mathbf{x})$ can be itself Fourier analyzed

$$\phi_i^p(\mathbf{x}) = \sum_{r,q} \hat{\phi}_{i;r,q}^p e^{-2\pi i(\frac{rx}{L_x} + \frac{qy}{L_y})}, \quad (25)$$

leading to the result

$$\hat{u}_{i;n,m}^s = \sum_p a^{s;p} \hat{\phi}_{i;n,m}^p. \quad (26)$$

237 By design, the EOFs produce the most compact representation possible of the ki-
 238 netic energy field. This is inherent in their derivation as a solution to a maximization
 239 problem. EOFs are also aware of the statistical connections between the velocity com-
 240 ponents u and v as they are both in the covariance matrix $[R]$. Because each of the EOFs
 241 can be reconstructed from Fourier modes, they are composed of the contributions of the
 242 variance from the various wavenumbers which are needed to meet this maximally com-
 243 pact constraint. In this sense, the EOF decomposition provides a view of the energy field
 244 that is complementary to the classical Fourier spectrum.

245 To summarize, generalizations of spectral theory to non-homogeneous settings have
 246 been described. Given an ensemble of velocity realizations, averaging can be performed
 247 directly to arrive at classical Fourier based energy spectra, or EOFs of two-point corre-
 248 lation function, $[R]$, can be estimated and used to compute an associated energy decom-
 249 position. Neither procedure requires windowing, or tapering, the data (for further de-
 250 tails, see Appendix A). Both procedures yield energy spectra satisfying Parseval's equal-
 251 ity, so the energy structure as a function of length scale can be compared with theoret-
 252 ically expected slopes.

253 **3 Application to the Separated Gulf Stream**

254 An essential element of this analysis is the use of ensembles to define both eddies
 255 and perform needed averaging. We here use 36 realizations from a North Atlantic en-
 256 semble extending from 1963 to 1967. The model consists of a $1/12^\circ$ deployment of the
 257 MITgcm (Marshall et al., 1997). The strategy used to produce the 36-member ensem-
 258 ble is described in Appendix B. We will pay particular attention to an area in the sep-
 259 arated Gulf Stream located away from any topography.

260 Figure 1 contains a plot of ensemble mean surface speed off the US east coast for
 261 12am, January 1, 1967. The mean Gulf Stream separates at Cape Hatteras and moves
 262 east northeast into the open Atlantic. Surface speeds are quite strong, in excess of 2 m s^{-1} ,

263 and evidence of persistent standing meanders are seen. The box enclosed by thick white
 264 lines is our region of focus, a $4^\circ \times 4^\circ$ square centered on (36.0N, 70.2W). The domain
 265 was chosen to focus on the separated Gulf Stream. Also, as we do not window the data
 266 prior to taking the Fourier transform (see Appendix A), we can examine the full domain
 267 size length scales. We will concentrate on the depths of 94 m and 628 m, i.e. near sur-
 268 face and mid depth zones where spectral expectations differ. Figure 2 contains plots of
 269 ensemble mean zonal and meridional velocities at these depths. The near surface zonal
 270 flow is quite strong and is accompanied by a meridional flow weaker by a factor of four.
 271 Gulf Stream baroclinicity is evident, with a reduction of mean flow to roughly 0.3 m s^{-1}
 272 in the zonal direction at 628 m, and of order 0.05 m s^{-1} in the meridional direction. These
 273 fields define the inhomogeneous environment on which the eddy field develops. The mean
 274 flows appearing in Fig. 2 are removed from all the 36 ensemble members, leaving us with
 275 effectively 35 degrees of freedom for the description of the eddy field.

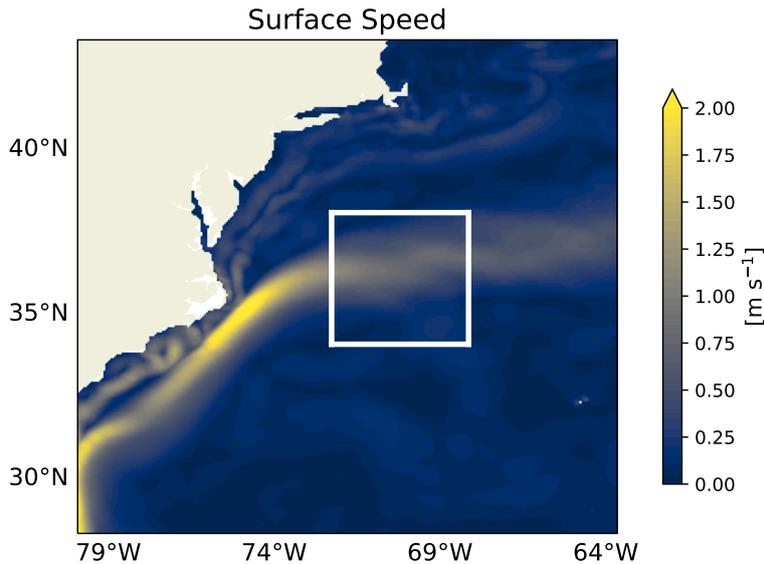


Figure 1. North Atlantic regional model domain. The contours are the ensemble-mean sea surface speed for 12a.m., January 1, 1967. The white box encloses the region studied in this paper.

276 3.1 Fourier Wavenumber Spectra

277 The result of computing the two dimensional, zonal, meridional energy spectrum
 278 according to (10), and to a detrended version of the data, appear in Figs. 3 and 4. (The

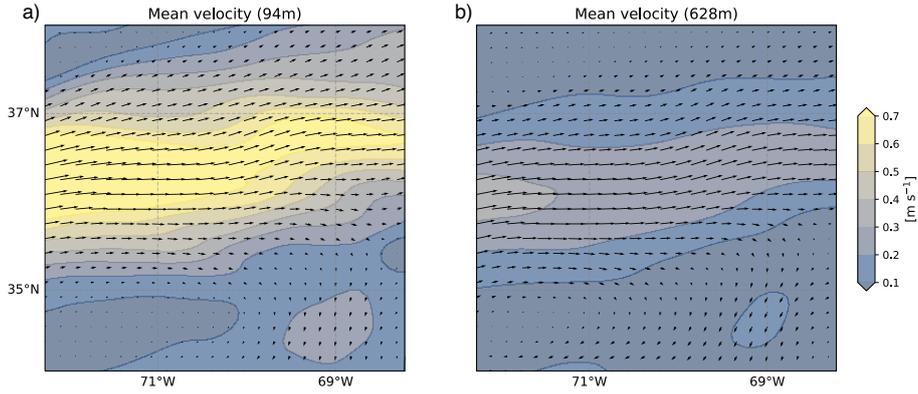


Figure 2. Ensemble mean velocities in the study domain denoted by the white box in Fig. 1. Panel **a** is from a depth of 97 m and **b** from a depth of 628 m. The colors indicate speed in $[\text{m s}^{-1}]$.

279 method of detrending is detailed in Appendix A.) Figure 3 comes from the near surface,
 280 at a depth of 94 m and Fig. 4 from 628 m, which is well within the main thermocline
 281 and away from surface influence. The left hand column shows the two dimensional spec-
 282 tra and the right hand column one-dimensional projections of the two dimensional spec-
 283 tra, along the zonal (blue) and meridional (green) directions. The upper row in both fig-
 284 ures shows the spectrum obtained from the full data, and the lower row from a detrended
 285 version of the data. The solid black line is the result of azimuthally averaging the 2-d
 286 spectrum to produce an isotropic spectral estimate. The magenta line follows the $k =$
 287 l trajectory in the wavenumber plane.

288 The left-hand column illustrates that the spectra are strongly non-isotropic, sug-
 289 gesting that Gulf Stream structure is imprinting on the eddy field. Indeed, the primary
 290 spectral amplitudes occur along the zonal and meridional directions. The right-hand col-
 291 umn shows interesting similarities and departures from the theoretically predicted spec-
 292 tral slopes of $-5/3$, -2 and -3 . These slopes appear on the right as the dot-dashed grey
 293 lines and represent the expected slope of the upscale energy cascade ($-5/3$), frontal, MLI
 294 or internal waves (-2) and the enstrophy or SQG cascades (-3) (Charney, 1971; Held
 295 et al., 1995; Rocha, Gille, et al., 2016; Vallis, 2017; Cao et al., 2019; Dong et al., 2020;
 296 Khatri et al., 2021). The overall structure of the spectra compare well between the sur-
 297 face and the main thermocline in that the relative spectral slopes from the two depths

298 are similar. The primary distinction lies in the spectral amplitudes, which are larger roughly
 299 by a factor of two near the surface, as expected.

300 The overall trend for all the one-dimensional projections is that they fall off at faster
 301 rates than the steepest -3 slope and tail off towards $-5/3$ at the largest wavenumbers,
 302 although the full data and detrended data differ in the details. For the full data, the slopes
 303 are steeper than -3 at wavenumbers smaller than $\sim 3 \times 10^{-2}$ cpkm but shoal towards
 304 $-5/3$ at larger wavenumbers. For the detrended data, the opposite is true: the slopes
 305 are steeper for wavenumbers larger than $\sim 10^{-2}$ cpkm but roll off towards $-5/3$ at smaller
 306 wavenumbers. The isotropized slope is essentially identical to the meridional projection,
 307 although it is clearly not representative of either the zonal or $k = l$ projections. All slopes
 308 are generally different from those reported in Ajayi et al. (2021), all of which assumed
 309 isotropy and all of which were more characteristically between -2.5 and -3 . Capet et
 310 al. (2008b) describe spectra with slopes of -2 in the California Current system. We note
 311 that the models examined in both of these studies were at much higher, sub-mesoscale
 312 permitting resolution, a feature which may well account for much of the difference. Our
 313 results do however question the interpretation of azimuthally averaged spectra in the Gulf
 314 Stream region of the ocean. We suspect this will be true also with sub-mesoscale reso-
 315 lutions in regions of strong mean flow.

316 The spectra appearing in the upper panels (Figs. 3a,b and 4a,b) are characterized
 317 by much larger amplitudes extending along the $k = 0$ and $l = 0$ axes relative to the
 318 lower panels (Figs. 3c,d and 4c,d). These ridges, while two to three orders of magnitude
 319 lower than the energies at low wavenumbers, are due mostly to the presence of the dis-
 320 continuities at the zonal and meridional boundaries of the domain causing the slopes to
 321 shoal towards higher wavenumbers (cf. Fig. A1). This is demonstrated by the lower plots,
 322 where spectra removing the discontinuities by means of detrending are shown. Note that
 323 the detrending has an unnoticeable effect on the energies at low wavenumbers, indicat-
 324 ing that the largest spectral amplitudes are dominated by the structure interior to the
 325 domain. Anisotropy is evident in both plots. It is generally seen that the full spectra drop
 326 off somewhat more steeply than the detrended spectra, but in all cases the slopes are greater
 327 than -3 at scales $O(100 \text{ km})$.

328 In summary, departures from theory appear in these spectral representations of the
 329 Gulf Stream eddy field. Perhaps clearest is the lack of spectral isotropy in the two-dimensional

330 spectra. Beyond that, well resolved model length scales tend to exhibit steeper slopes
 331 than are predicted by theory.

332 **3.2 An EOF-based Spectral Examination**

333 It is also possible to use the ensemble to estimate the correlation matrix from the
 334 domain in Fig. 1 and to extract its eigenvalue/eigenfunction content. We show in Fig. 5
 335 the first two velocity eigenfunctions for 94 m depth (top row) and 628 m (bottom row)
 336 and third and fourth eigenfunctions in Fig. 6. Perhaps the most prominent feature of
 337 the eigenfunctions is their similarity in structure even though separated by roughly 530m
 338 in the vertical. Beyond that, first EOF resembles a standing eddy. Given that the mean
 339 flow exhibits a standing meander in the region, this mode represents strengthening or
 340 weakening of this feature. The second mode is much more zonally elongated, and shows
 341 reversals to the north and south of the primary flow at jet center. This mode captures
 342 the broadening or narrowing of the main Gulf Stream jet. The next two modes are more
 343 spatially complex, and difficult to interpret simply in terms of their effects on the Gulf
 344 Stream. However, both are amplified in the eastern sector of the domain, suggesting an
 345 increasing tendency for the Gulf Stream to become less coherent with increasing sepa-
 346 ration from the coast.

347 We next computed the modal spectra within the $4^\circ \times 4^\circ$ square at the two depths
 348 of 94 m and 628 m. The results appear in Fig. 7 as three dimensional scatterplots. The
 349 horizontal axes are the log of the wavenumbers and the vertical axis is the log of the spec-
 350 tral amplitude. Each eigenmode is assigned a single zonal and meridional wavenumber
 351 according to (22) and (23), and the locations of those pairs are indicated by the blue dots.
 352 The spectral amplitude of the eigenmode for each wavenumber pair appears as the ma-
 353 genta crosses. The projections of the energies on the zonal and meridional axes appear
 354 as the green and red dots, respectively, and on those planes, black lines with a slope of
 355 -3 are given as reference.

356 As suggested by the solid black lines, the EOF spectra typically fall off more steeply
 357 than the -3 slope, which is consistent with the classical spectral results. There is no clear
 358 indication of the $-5/3$ slope at low wavenumbers hinted at in Figs. 3 and 4. Beyond this,
 359 there are interesting comparisons to be made with the classical results, which underscore
 360 the different philosophies behind the two spectral estimates. The assignment of single

361 zonal and meridional wavenumbers to each mode implies that the EOF spectral plot is
 362 really a single line in the three-dimensional wavenumber, energy diagram. This shows
 363 up in Fig. 7 in the blue dot distribution in the k - l plane, which are the collection of the
 364 EOF ‘wavenumbers’. The magenta dots, one per blue dot, describe a trajectory in the
 365 plot, nominally following the line described by the blue dots. Note that, although there
 366 is scatter, the spectral line is closer to an ‘isotropic’ configuration than would be indi-
 367 cated by Fig. 3. Best fit wavenumber lines suggest $l = 1.4k$ near the surface and $l =$
 368 $1.1k$ at depth. Thus there is a weak indication of compression of the variability in the
 369 across-stream direction near the surface, and less so at depth. This is seemingly in keep-
 370 ing with the stronger down stream flow found near the surface relative to that at depth.
 371 In any case, the picture emerging from these plots is much different than the anisotropic
 372 configurations seen in Figs. 3 and 4.

373 These very different spectral impressions can be understood by appealing to their
 374 derivations. The EOF spectra emerge from an examination of the two-point correlation
 375 function, (12), which in turn contains information about statistical relationships between
 376 zonal and meridional velocity. In contrast, all such information is lost in the classical Fourier
 377 spectra, which consider the two velocity components independently. The spectra of the
 378 individual zonal and meridional velocity components from the detrended data appears
 379 in Fig. 8, where the top row is from 94 m and the bottom row is from 628 m. The left
 380 column is the zonal velocity spectrum and the right column the meridional velocity spec-
 381 trum. The sum of each row yields the full spectrum seen in the bottom rows of Figs. 3
 382 and 4. The zonal flow tends to contribute variance to the total near to the $k = 0$ axis,
 383 meaning this component of the flow exhibits long downstream lengthscales, and pronounced
 384 cross-stream structure. The opposite is true for the meridional velocity, which contributes
 385 heavily near to the $l = 0$ axis, indicative of the downstream structure of the cross-Gulf
 386 Stream eddy flow. When added, the spectrum that emerges is the anisotropic version
 387 observed in Figs. 3 and 4. These various structures however, are not statistically inde-
 388 pendent, and when this is accounted for, by analyzing $R(\mathbf{x}, \mathbf{x}')$, the spectral represen-
 389 tation falls along a line much closer to $k = l$. Recall that both energetic decomposi-
 390 tions completely reconstruct the total kinetic energy in the domain, so both are equally
 391 valid descriptions. The EOF spectra, by combing through the wavenumber plane to com-
 392 bine the coherent variance at each wavenumber as determined by the statistics, provides
 393 a view of the eddies in a manner complementary to the classical spectra.

394 The statistical dependence of the u and v fields plays an important role in describ-
395 ing the regional variability. It is possible to partially reconstruct the velocity fields of the
396 realizations by adding the contributions of the first few modes to the ensemble mean flow.
397 Doing so demonstrates that the role played by the first few EOFs is to mimic the sin-
398 uous motion of the Gulf Stream within the jet. This is shown in Fig. 9. Figure 9a is the
399 94 m velocity field of one of the ensemble members. Figure 9b is the ensemble mean ve-
400 locity field. Clearly, the realization differs markedly from the ensemble mean, and so pos-
401 sesses a strong eddy field. On the other hand, it is clear the structure of the realization
402 is dominated by the coherent Gulf Stream jet. The lower two rows (Fig. 9c,d) show the
403 effect of adding the first and second EOFs multiplied by the appropriate projection co-
404 efficient, respectively, to the ensemble mean. The comparison demonstrates that this par-
405 tial reconstruction brings the fields much closer to the realization. Of course, this should
406 be the result of adding the EOFs to the mean, but the comparison serves to illustrate
407 that the regional variability is dominated by the vacillations of a highly coherent feature,
408 and that the underlying regularity of the velocity field is captured by the EOFs. This
409 statistical relationship between the velocity components is lost in the classical EOF en-
410 ergy spectrum.

411 **4 Discussion and Summary**

412 We illustrate the use of ensembles to compute ocean kinetic energy spectra, from
413 the perspective of emphasizing how they readily permit the examination of spectra in
414 the non-stationary, inhomogeneous and anisotropic settings of most oceanically inter-
415 esting settings. This is primarily because the development of the ensemble permits the
416 straightforward application of ensemble averaging to compute the mean fields, the ‘ed-
417 dies’ and the averages needed to obtain robust results. Amongst their advantages are
418 an ability to define ‘parameter’ free mean and eddy fields. It is also not necessary to in-
419 voke the assumptions normally used to generate spectra. We have also discussed vari-
420 ants on the normal spectral theme. In addition to the classical Fourier based decom-
421 position which has seen wide-spread usage in oceanography, we have adopted a technique
422 used in the turbulence literature for the study of inhomogeneous settings. In order to
423 capture the inhomogeneous nature of oceanic flows, Sadek and Aluie (2018) recently de-
424 veloped a method where they spatially decompose the kinetic energy using a coarse-graining
425 approach. Here, we have instead effectively migrated EOF analysis to energy by exam-

426 ining the two-point correlation matrix of the velocity field. The modal eigenvalues from
427 the analysis play the role of the spectral amplitudes, but now describe the contribution
428 of the EOF to the total energy, rather than that of a given complex exponential. The
429 assignment of length scales to the energy is made via the gradients of the eigenmodes,
430 a procedure that is itself a generalization of the Fourier technique. We also do not ta-
431 per or window the data prior to analyzing it.

432 We apply the methods to the eddies to a section of the separated Gulf Stream, a
433 strongly inhomogeneous and eddy rich area of the world ocean. The classical spectra ar-
434 gue strongly that the region is anisotropic, with energy predominantly found in the low
435 velocity modes (Fig. 8). The slopes of the spectra, when viewed from various one-dimensional
436 perspectives, exhibit a number of novel characters. There is a suggestion at the lowest
437 resolved wavenumbers of the $-5/3$ slope expected from inverse energy cascade arguments
438 (Fig. 3). Moving towards higher wavenumbers, however, the slopes fall off more steeply
439 than the steepest (-3) slope expected from QG theory. This result differs from other
440 analyses employing standard methods. We suggest these differences are at least partly
441 due to the unique separation between mean and eddies that an ensemble permits.

442 We examine surface and mid-thermocline depths, finding the spectral structures
443 strongly resemble each other. This appears in the similarity of the spatial EOFs as well
444 as the distributions of the classical spectra. The energy levels are, of course, different,
445 with the deeper level less energetic. The deeper level is, according to the EOF spectra,
446 slightly less anisotropic than the surface, a result consistent with the weaker mean flow
447 structure at depth.

448 The big distinction between the spectral views is in the apparent change between
449 the highly anisotropic conditions suggested by the classical spectra and the much more
450 isotropic looking spectral structure associated with the EOFs. Both techniques yield valid
451 decompositions of the regional energy and each possesses its own strengths. Fourier anal-
452 ysis unambiguously assigns lengths scales to the spectral amplitudes and therefore can
453 readily be used to investigate spectral slopes for comparison with theory. On the other
454 hand, complex exponentials experience some degree of contamination due to the non-
455 periodicity inherent in geophysical data. Length scales can also be assigned to EOFs via
456 the procedure outlined in this paper, but the results tend to be less regular due to the
457 complex spatial EOF structure. Testing for spectral slopes becomes much more subtle.

458 The new information available to the EOFs, however, is found in the velocity cross-correlations
459 (as opposed to in classical kinetic energy spectrum where such information is lost), which
460 results in spatial structures reflecting the preferred modes of the data. These structures
461 are well suited to the finite domain size and inhomogeneity of the data. In effect, the pro-
462 cedure illustrates how the energy is assigned across statistically coherent structures. Al-
463 though this seems a valuable extension of classical Fourier analysis, in view of the broad
464 usage of Fourier spectra in oceanography, we suggest the three views including the coarse-
465 graining approach (Sadek & Aluie, 2018) provide complementary energy views.

466 Given these ensemble techniques, and with nesting technology their capacity for
467 resolving the full time and space evolution of spectra, there are a dizzying number of av-
468 enues to pursue. We are particularly interested in comparing and contrasting the eddy
469 fields of the ocean interior with those from the separated Gulf Stream. The latter is, as
470 emphasized above, strongly inhomogeneous while the former region is more likely to meet
471 conditions of isotropy. The regions are also starkly different in terms of their eddy en-
472 ergies. In view of these contrasts, we anticipate spectral distinctions will arise, with the
473 interior likely to exhibit spectral structures like those anticipated from theory. We are
474 also interested in exploring the departures of the Gulf Stream spectra from classical re-
475 sults. The presence of the mean flow and the departure of the region from quasi-geostrophic
476 character are possible explanations, but which of these, if either, is dominant is not clear.

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484 ~qjamet/share/data/Uchida2021/](http://ocean.fsu.edu/~qjamet/share/data/Uchida2021/)). We also acknowledge Edward Peirce and Kelly Hi-
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486 spectra were calculated using the `xrft` Python package (Uchida et al., 2021). The Mat-
487 lab scripts and Jupyter notebook used for analysis are available on Github with the DOI:
488 10.5281/zenodo.5563893.

489 Appendix A Windowing Considerations

490 It is standard practice when working with data of a finite extent, as is always the
 491 case, to window or taper the data, to avoid contaminating the spectra with edge effects.
 492 Literally, this implies multiplying the original data by a function that tapers the bound-
 493 ary values to zero so that the underlying data structure is consistent with the spatial pe-
 494 riodicity of the Fourier functions, as used in Arbic et al. (2014), Uchida et al. (2017) and
 495 Ajayi et al. (2021). We note that this is not necessary for our EOF spectral analysis: the
 496 two point correlation function can be computed for all points within the domain, and
 497 the eigenfunctions extracted, without further manipulating the data. We also note that
 498 in classical spectra, tapering distorts the underlying data thus effecting the outcomes of
 499 the computation. We do not taper, or window, the data in the classical way. The ratio-
 500 nal for that decision is discussed here.

501 Tapering is usually invoked to minimize edge effects occurring, for example, when
 502 an open ocean section of the Gulf Stream section is examined. Tapering the data to ze-
 503 ros at the domain edge then seamlessly permits the Fourier transforming of the data as
 504 if it were a purely periodic signal. In addition, it helps to control edge effects as an ef-
 505 fect on averaging, a problem that we do not encounter as our averaging is a true ensem-
 506 ble averaging.

A well known result of Fourier theory is that the transform of the tapered data is
 a convolution, i.e. if the windowed data is

$$u_w(\mathbf{x}) = u(\mathbf{x})w(\mathbf{x}), \quad (\text{A1})$$

the transformed data is

$$\hat{u}_w(\mathbf{k}) = \int_{\mathbf{p}} \hat{u}(\mathbf{p})\hat{w}(\mathbf{p} - \mathbf{k})d\mathbf{p}, \quad (\text{A2})$$

507 where \hat{w} is the Fourier transform of the window. The windowed transform, \hat{u}_w , is a weighted
 508 average of the underlying ‘true’ transform. The artistry of window construction revolves
 509 around designing w such that its transform is reasonably narrow band, and dies off quickly
 510 with distance from the origin. It is impossible to avoid side lobes in \hat{w} , but a well-designed
 511 window hopefully minimizes the distortion of the underlying spectrum.

While accepting this premise, we point out two views, one mathematical and one
 conceptual, that suggest for many applications, windowing can usefully be avoided. First,
 one reason to taper is to avoid contamination from edge effects, a contamination that

often falls under the title of Gibbs phenomena. This is a well-known problem with Fourier representations of discontinuous data that manifests in the unavoidable appearance of noise in the vicinity of the discontinuity. We do not dispute the reality of Gibbs phenomenon, but also point out that a discrete Fourier transform is entirely invertible. This implies that the discrete Fourier transform of a data stream of length N consists of a sequence of $N/2$ complex values whose inverse discrete Fourier transform returns the original data set to machine accuracy. If

$$\hat{u}_n = \sum_p u_p e^{2\pi i \frac{pn}{N}}, \quad (\text{A3})$$

then

$$u_p = \frac{1}{N} \sum_n \hat{u}_n e^{-2\pi i \frac{pn}{N}}, \quad (\text{A4})$$

512 and no information is lost in the forward/backward transformation. An example appears
 513 in Fig. A1, where the original data, appearing in the left panel, consists of a straight line,
 514 and thus possesses a large discontinuity at the edge. This input is forward and backward
 515 discrete Fourier transformed. The result appears in the lower left panel, and the differ-
 516 ence of the two appears on the lower right. The difference is machine precision zero, which
 517 simply reflects the above argument.

518 It is also sometimes argued that the presence of the discontinuity will force the pres-
 519 ence of high wavenumber content into the transform that is clearly not present. The top
 520 right panel shows the log plot of the transform of the original data, where it is seen that
 521 spectral variance is present throughout the wavenumber band, but that after the first
 522 few wavenumbers, the spectral amplitudes drop by four orders of magnitude. While this
 523 is the introduction of high wavenumber variance in what clearly is a very smooth func-
 524 tion, the contamination by high wavenumbers is small.

525 A conceptual issue we raise with windowing is in its resultant filtered connection
 526 to the so-called underlying ‘true’ spectrum. Indeed, the aim of window design is to give
 527 as pure a view of that spectrum as is possible with finite data. The issue as we see it here
 528 is that we are focussing, in a broad sense, on the ocean. The true underlying velocity
 529 transform in that case, brushing aside questions of domain irregularities and the like, would
 530 be the transform of the global ocean velocity field. This of course mixes the momentum
 531 of Pacific waters with those of the Indian and Southern oceans all together, which then
 532 presents one with the problem of interpreting what the results mean; a local signal in
 533 space is global in the wavenumber domain and visa versa.

534 If we move away from this rather abstract example to our present case of the North
 535 Atlantic, provided that we could somehow adequately isolate the North Atlantic and ex-
 536 tract a Fourier transform of its velocity field, we would then be looking at the results of
 537 simultaneously considering all the differing regimes of the North Atlantic in a single trans-
 538 form. But the North Atlantic, by itself, still houses dramatically distinct dynamic regimes,
 539 from the chaotic and eddy rich Gulf Stream extension to the much more quiescent in-
 540 terior westward drift to the Loop Current dominated Gulf of Mexico (Jamet et al., 2021).
 541 In this case, the ‘true’ underlying transform mixes all these various regions together to
 542 provide a single value for an amplitude at a given wavenumber.

543 If we consider the fundamental question driving our investigation in this paper, it
 544 is to study the spectral representation of the eddy field in the Gulf Stream extension,
 545 a region notable for its extraordinary behavior when compared to any other sector of the
 546 North Atlantic, and indeed to essentially all of the worlds oceans. One can rightly ask
 547 of what value is it when pursuing this question to extract from the regional data a look
 548 at the underlying ‘true’ spectrum. In a sense this question is avoided if the transform
 549 of the raw, unwindowed data is used. In view of the invertibility of the Fourier trans-
 550 form, all of the wavenumber content of the regional data is perfectly contained in the
 551 raw transform, and full information about how that energy is structured in wavenum-
 552 ber space is available. In addition, it provides a product that is comparable and com-
 553 patible to the EOF based decomposition which, by design, involves no windowing.

554 It is evident in Figs. 3 and 4 that the energy lying along the k and l axes is one
 555 of the major anisotropic features of those spectra, even if their amplitudes are orders of
 556 magnitude smaller than the dominant spectral amplitudes at lower wavenumbers. In view
 557 of the contribution of the edge discontinuities to high wavenumbers inherent in Fig. A1,
 558 it is fair to ask if the perception of anisotropy survives if the effects of the discontinu-
 559 ities are removed. We have therefore computed the regional spectra of so-called ‘detrended’
 560 data, where the detrending is carried out as described below.

561 **A1 Detrending**

First, consider the finite Fourier transform of a line,

$$\hat{x}(k) = \int_0^L x e^{2\pi i k x} dx, \quad (\text{A5})$$

with the inverse transform

$$x = \int_{-\infty}^{\infty} \hat{x} e^{-2\pi i k x} dk. \quad (\text{A6})$$

Equation (A5) can be written

$$\hat{x} = \frac{1}{2\pi i} \int_0^L \frac{d}{dk} e^{2\pi i k x} dx = \frac{1}{2\pi i} \frac{d}{dk} \int_0^L e^{2\pi i k x} dx, \quad (\text{A7})$$

leading eventually to

$$\hat{x} = \frac{1}{4\pi^2 k^2} (e^{2\pi i k L} - 1) - \frac{iL}{2\pi k} e^{2\pi i k L}. \quad (\text{A8})$$

Given a non-periodic field $f(\mathbf{x})$ inside a finite, square domain of zonal length L_x and meridional length L_y , we define a second field periodic in x , f_1 , according to

$$f(\mathbf{x}) = f_1(\mathbf{x}) + \frac{(f(L_x, y) - f(0, y))x}{L_x}. \quad (\text{A9})$$

It is easily shown that

$$f_1(0, y) = f_1(L_x, y) = f(0, y). \quad (\text{A10})$$

Next, we define a field $f_2(\mathbf{x})$ according to

$$f_1(\mathbf{x}) = f_2(\mathbf{x}) + \frac{(f_1(x, L_y) - f_1(x, 0))y}{L_y}. \quad (\text{A11})$$

It is easily shown that

$$f_2(x, 0) = f_2(x, L_y) = f_1(x, 0). \quad (\text{A12})$$

562 Eliminating f_1 from (A11) using (A9) yields eventually

$$f(\mathbf{x}) = f_2(\mathbf{x}) + \frac{(f(x, L_y) - f(x, 0))y}{L_y} + \frac{(f(L_x, y) - f(0, y))x}{L_x} + \frac{(f(L_x, 0) - f(0, 0) - f(L_x, L_y) + f(0, L_y))xy}{L_x L_y}, \quad (\text{A13})$$

from which it can be shown that

$$f_2(0, y) = f_2(L_x, y), \quad (\text{A14})$$

and

$$f_2(x, 0) = f_2(x, L_y), \quad (\text{A15})$$

563 so f_2 is a periodic function both zonally and meridionally. It is the spectra of the result-
 564 ing f_2 field that we present in Figs. 3 and 4. If one is interested in the total energy, one
 565 only needs to add the spectra of the other terms on the right-hand side of (A13).

566 **Appendix B Macro and micro initial conditions**

567 Our 36-member ensemble is composed of 24 members run with ‘micro’ Initial Con-
 568 ditions (ICs; Jamet et al., 2019), and 12 other members run with ‘macro’ ICs. ‘Micro’
 569 ICs are meant to reflect the growth of dynamically consistent ocean perturbations in re-
 570 sponse to infinitesimally small perturbations of the ocean state. Here, they are gener-
 571 ated as follow: 24 oceanic states separated 48 hours each were taken during an initial
 572 month-long integration beginning December 8, 1962, upon which 24 simulations were run
 573 using these as the initial conditions under a yearly repeating atmospheric and bound-
 574 ary condition of 1963. We have verified that the spread so generated is consistent with
 575 another strategy found in the literature (Germe et al., 2017), where Gaussian white noise
 576 with a standard deviation of 3.5×10^{-3} K is applied to the 3-dimensional temperature
 577 oceanic field. The 12 next realizations were initialized with ‘macro’ ICs. These ICs are
 578 meant to more strongly involve decorrelated lower, interannual frequency ocean intrin-
 579 sic variability. They have been constructed here through a 50-year long run exposed to
 580 yearly repeating forcing, from which the January 1 model states separated by 4 years
 581 have been used. The interested reader is referred to Stainforth et al. (2007) for a broader
 582 description of these different initialisation strategies.

583 **Appendix C EOF analyses on a sphere**

The eigenvalue problem governing the EOFs is

$$\int_{\mathbf{x}'} R_{ij}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' = \lambda \phi_i(\mathbf{x}), \quad (\text{C1})$$

where $R_{ij} = \langle u_i(\mathbf{x}) u_j(\mathbf{x}') \rangle$. The volume element on a sphere is

$$d\mathbf{x} = a^2 \cos \theta d\theta d\varphi, \quad (\text{C2})$$

584 where a is the Earth radius and θ, φ are latitude and longitude, respectively. The vari-
 585 able volume element is an issue with simply forming the covariance matrix and extract-
 586 ing the EOFs, as the various elements in equation (C1) are weighted differently accord-
 587 ing to the latitude. What follows is a proposed fix for this issue.

We will use the notation

$$\mathbf{x} \rightarrow (\theta, \varphi) \quad (\text{C3})$$

588 with the same for \mathbf{x}' .

Breaking up the $\cos \theta'$ into the product of square roots and multiplying equation (C1) by $\sqrt{\cos \theta}$, we get

$$\int_{\mathbf{x}'} \sqrt{\cos \theta} \langle u_i(\mathbf{x}) u_j(\mathbf{x}') \rangle \sqrt{\cos \theta'} \sqrt{\cos \theta'} \phi_j(\mathbf{x}') a^2 d\theta' d\varphi' = \lambda \sqrt{\cos \theta} \phi_i(\mathbf{x}). \quad (\text{C4})$$

Now, defining $\sqrt{\cos \theta} \phi_i(\mathbf{x}) = \Phi_i(\mathbf{x})$, equation (C4) becomes

$$\int_{\mathbf{x}'} \rho_{ij}(\mathbf{x}, \mathbf{x}') \Phi_j(\mathbf{x}') a^2 d\theta' d\varphi' = \lambda \Phi_i(\mathbf{x}) \quad (\text{C5})$$

with

$$\rho_{ij}(\mathbf{x}, \mathbf{x}') = \langle \sqrt{\cos \theta} u_i(\theta, \varphi) \sqrt{\cos \theta'} u_j(\theta', \varphi') \rangle. \quad (\text{C6})$$

589 The form of equation (C5) is the same as that of (C1) except that the weightings given
 590 all elements are the same. We can now form the new covariance matrix $\rho_{ij} a^2 d\theta d\varphi$ and
 591 extract its eigenvalues. We note that such consideration for varying latitude is often dis-
 592 carded in Fourier spectral analysis which assumes a local Cartesian plane.

593 Appendix D Confidence interval for spectrum

In formulating the spectrum (E), we are averaging squared quantities where the quantity being squared has zero mean and are independent from one another. The zero mean is guaranteed as we have subtracted out the ensemble mean and non-linearity of the system ensures decorrelation amongst ensemble members. The distribution of the squared quantities, therefore, follows approximately a χ^2 distribution (Rocha, Chereskin, et al., 2016; Menke & Menke, 2016; Uchida et al., 2017). Under such distribution, the probability of our spectral estimate (E^{est}) falling close to the unknown ‘true’ spectrum (E^{true}) is

$$P\left(\chi_{N,1-\alpha/2}^2 < N \frac{E^{\text{est}}}{E^{\text{true}}} < \chi_{N,\alpha/2}^2\right) = 1 - \alpha, \quad (\text{D1})$$

where $N = 35$ is the degrees of freedom and $1 - \alpha = 0.95$ the significance level. After some equation manipulation, this yields

$$P\left(\frac{N}{\chi_{N,\alpha/2}^2} < \frac{E^{\text{true}}}{E^{\text{est}}} < \frac{N}{\chi_{N,1-\alpha/2}^2}\right) = 1 - \alpha. \quad (\text{D2})$$

In other words, we can reject the null hypothesis that the true spectrum doesn’t lie within the range of

$$\frac{N}{\chi_{N,\alpha/2}^2} E^{\text{est}} < E^{\text{true}} < \frac{N}{\chi_{N,1-\alpha/2}^2} E^{\text{est}}, \quad (\text{D3})$$

594 with a $1 - \alpha$ significance level.

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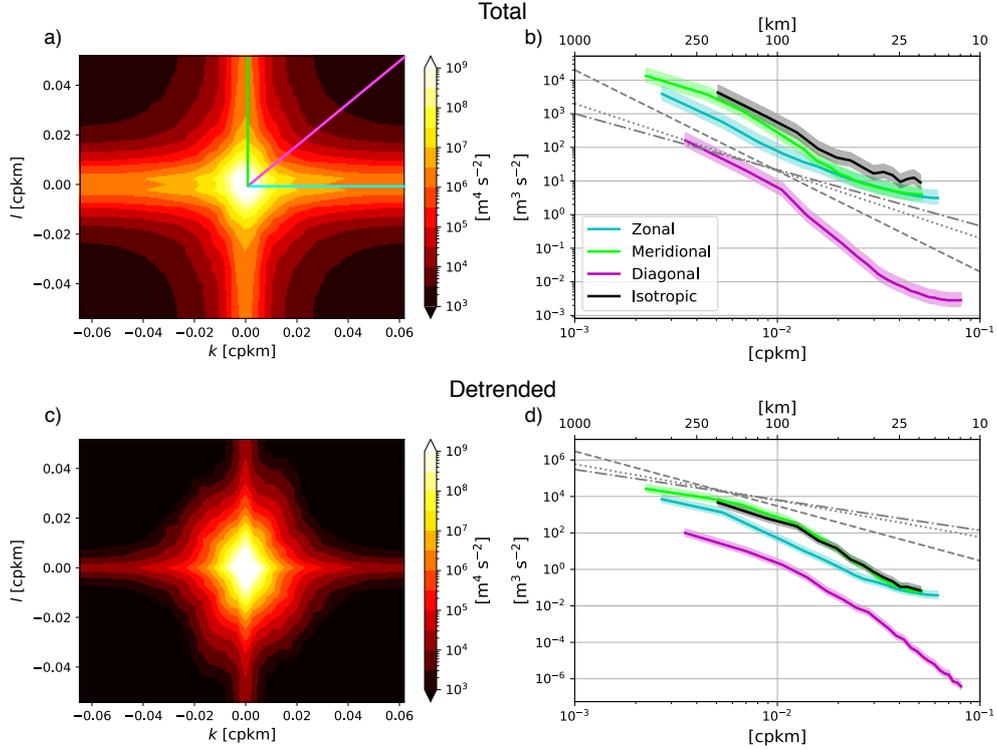


Figure 3. Classical Fourier spectra based on ensemble averaging. Both rows portray data from 94 m. The upper row shows Fourier spectra without any windowing, and the lower row uses detrended data, as discussed in Appendix A. The left column are two-dimensional plots of the log of the spectra as a function of the zonal and meridional wavenumbers. The right column are plots of one-dimensional cuts through the wavenumber plane along the straight lines appearing in the upper left plot. Note the units of spectra are all in spectral density. The 95% confidence intervals are shown in the colored shadings (see Appendix D for details). The dot-dashed grey lines on the right are slopes of $-5/3$, -2 and -3 , which are the upscale energy, frontal and enstrophy or SQG cascade slopes expected from QG theory. The solid black line is the azimuthally averaged slope extracted from the two-dimensional spectra. The left column shows the spectra are highly anisotropic.

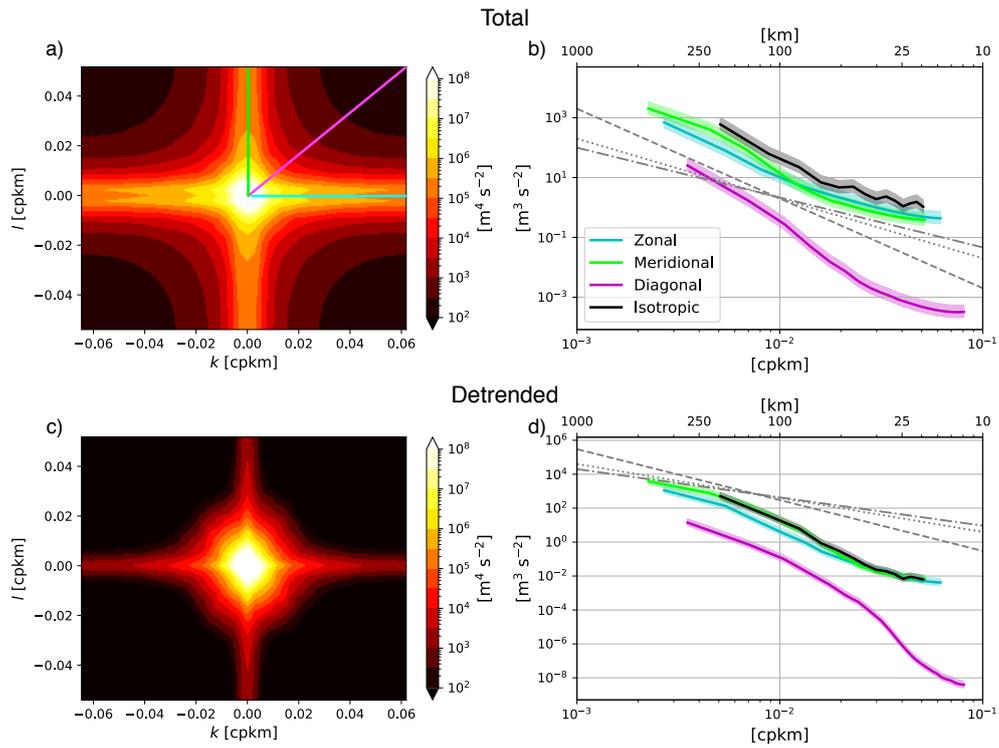


Figure 4. Same as Fig 3, except at 628 m.

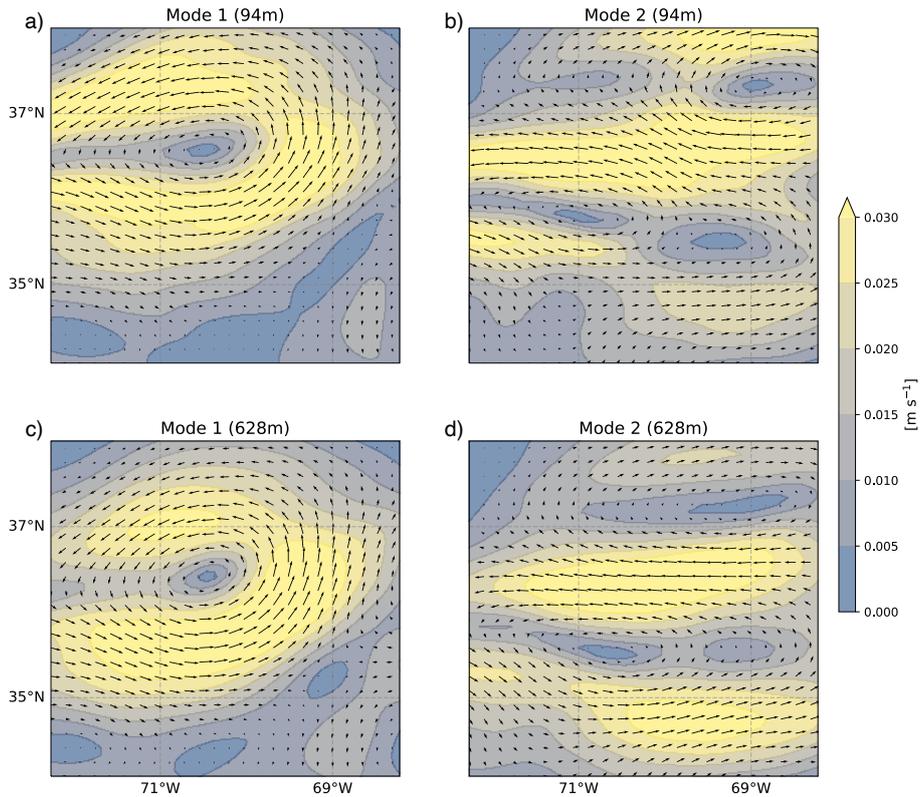


Figure 5. First and second EOF of the velocity fields (EOF 1 left and EOF 2 right, 94 m top and 628 m bottom) shown as vectors, from the square in Fig. 1. The colors indicate speed.

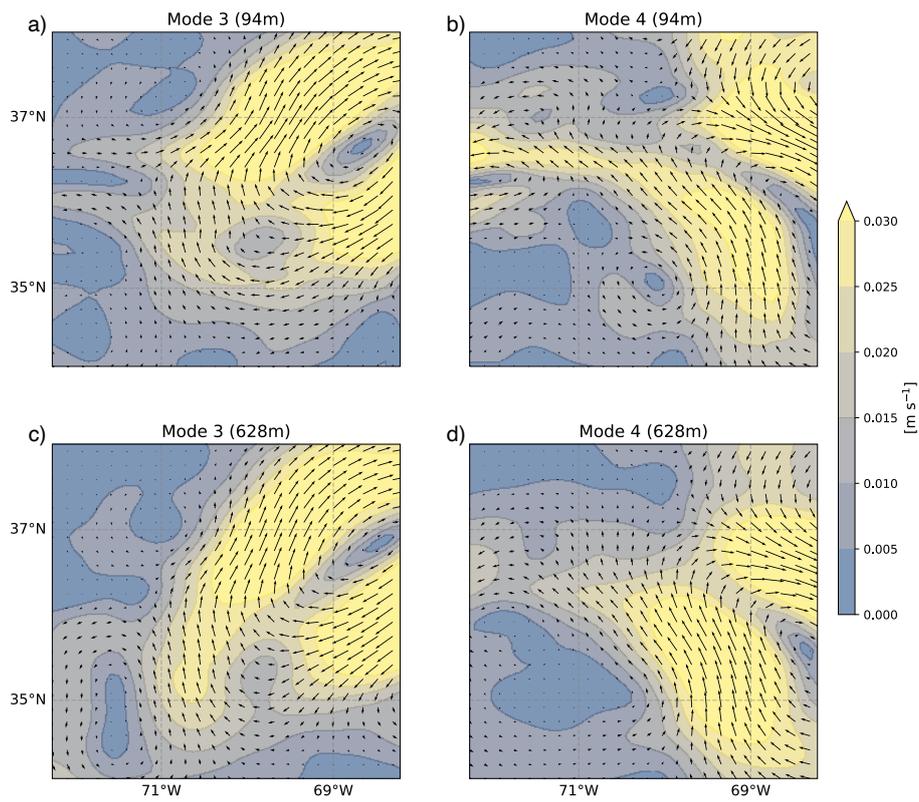


Figure 6. Same as Fig. 5, but for the third and fourth EOF.

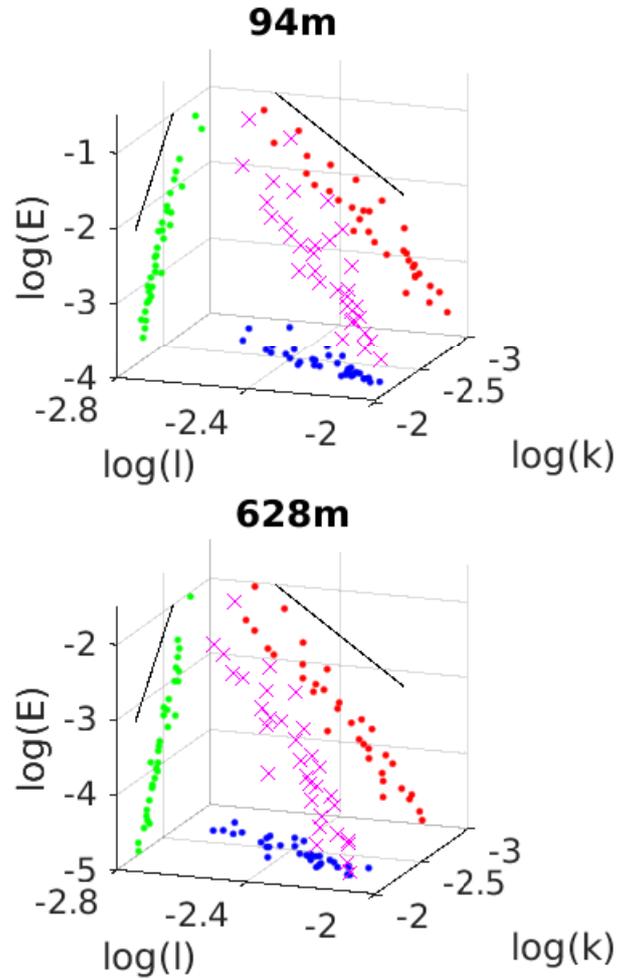


Figure 7. Modal spectra for depths 94 m and 628 m shown as scatterplots. The horizontal axes are the logs of zonal and meridional wavenumbers and the vertical axis is log of spectral amplitude in $[\text{m}^2 \text{s}^{-2}]$. The magenta crosses are the EOF eigenvalues for the 35 modes, which follow the trajectory through the wavenumber plane painted by the blue dots. Projections on the zonal and meridional plane of the eigenvalues appears as the green and red dots. The solid black lines both have slopes of -3 .

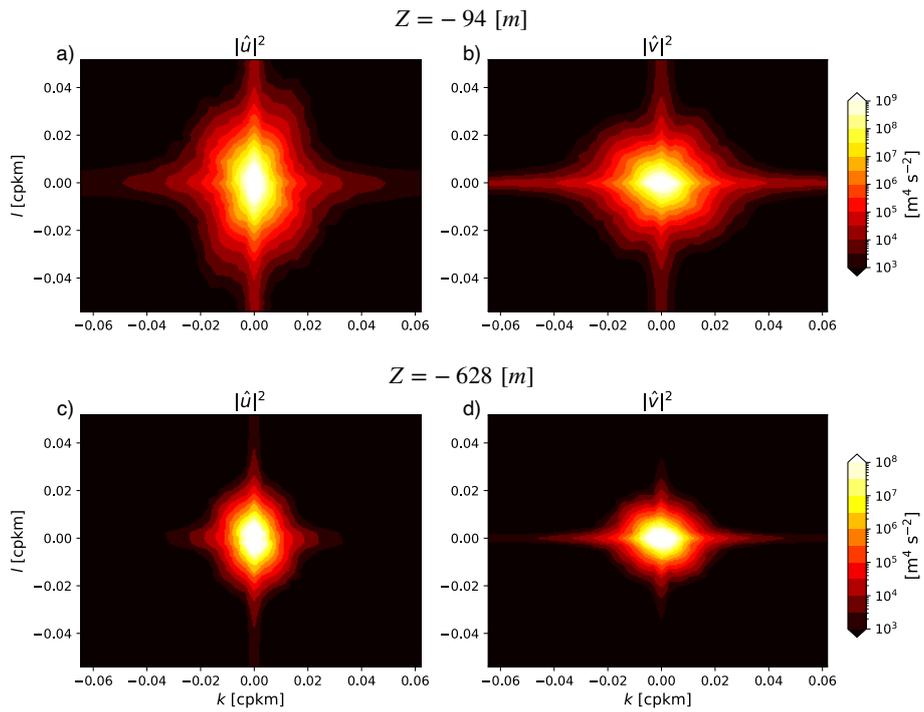


Figure 8. Zonal (left) and meridional (right) Fourier spectra, shown independently from $z = 94$ m (top) and $z = 628$ m (bottom).

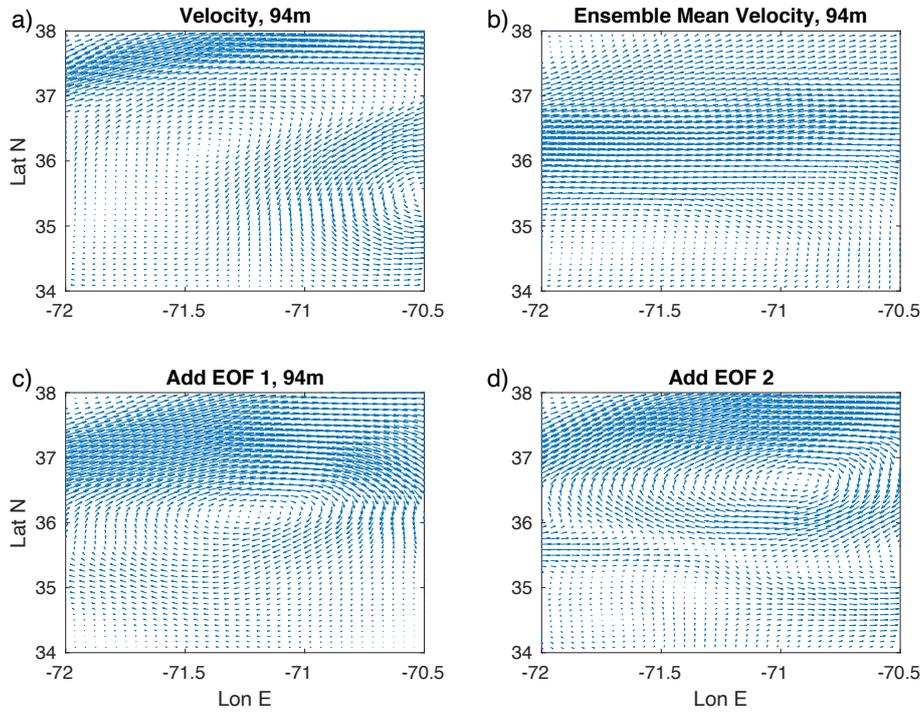


Figure 9. The velocity field arising from one of the ensemble members appears on the upper left. The ensemble mean velocity field is on the upper right. The result of sequentially adding the first and second EOFs to the mean field appear in the lower left and right panels, respectively. This difference between the upper two plots defines the ‘eddies’ in this realization, which clearly relates the eddies to the variations of the coherent Gulf Stream jet. The reconstruction illustrates the role played by the EOFs in correcting the ensemble mean towards the realized jet. This reconstruction heavily involves the coherent patterns of the zonal and meridional velocities.

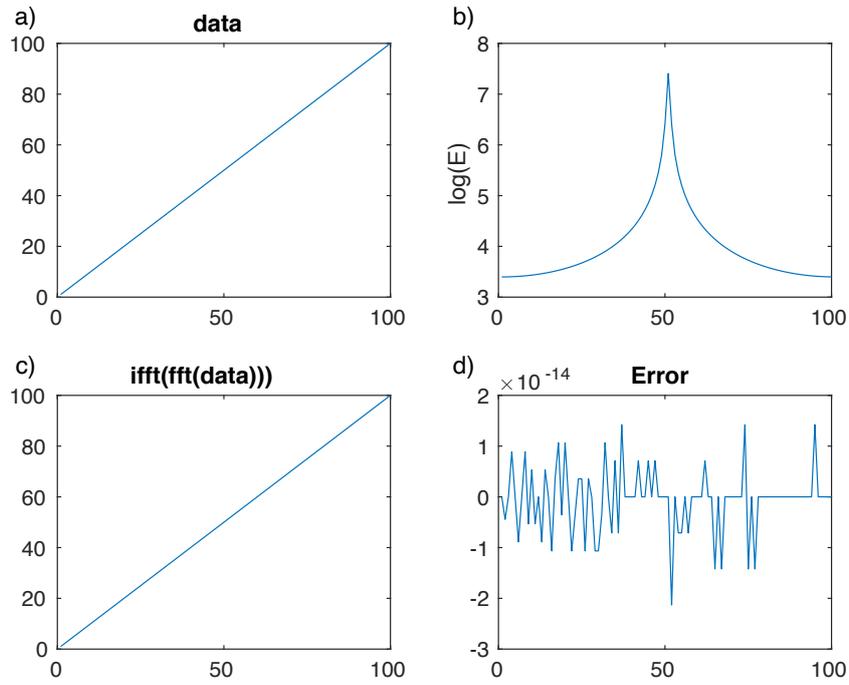


Figure A1. An example of Fourier transform invertibility. The upper left panel shows the original data, characterized by an edge discontinuity. The lower left panel shows the result of forward and backward transforming that data and the lower right panel shows the difference between the two. The difference is clearly machine precision zero. The upper right panel shows the spectrum of the transform of the original data. High wavenumbers, representing small scale contributions to the transform, are orders of magnitude smaller than the amplitudes of the primary low wavenumbers.