

Wave-induced steady currents by submerged canopy-oscillatory flow interaction

Alejandro Cáceres¹, Alejandro Orfila², Maria Maza³, and Giovanni Besio⁴

¹University of Genova

²Mediterranean Institute for Advanced Studies

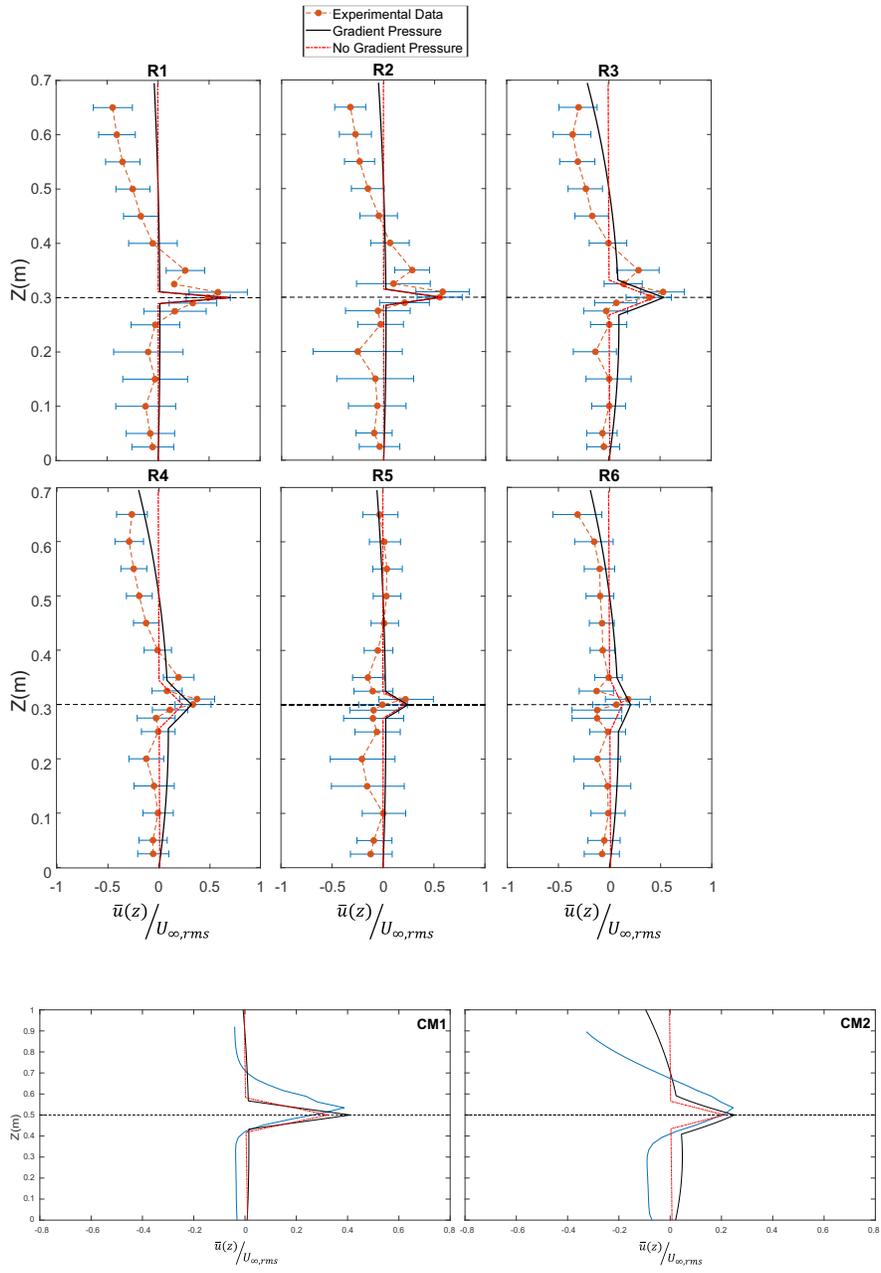
³IHCantabria, Universidad de Cantabria

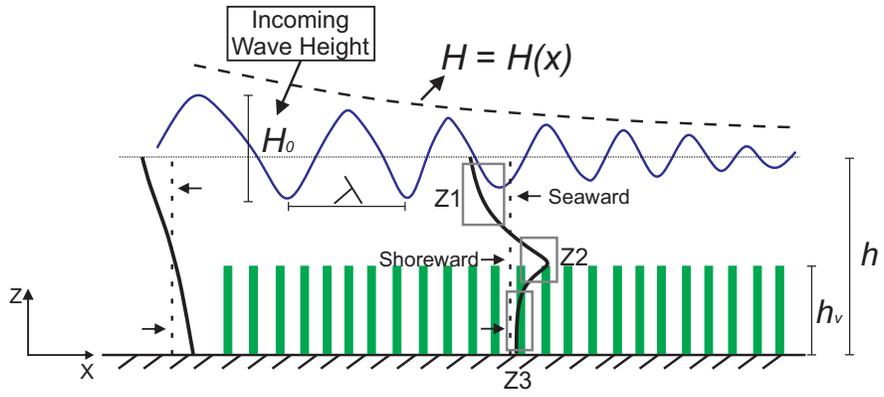
⁴University of Genoa

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Abstract

A new analytical model is presented in order to better understand the depth-dependent wave-induced steady current caused by submerged aquatic canopy-oscillatory flow interaction. The analytical model takes into account the wave and canopy properties. The model is developed by determining the dominant terms in the momentum equation by means of dimensional analysis and satisfying the mass conservation. The dimensional analysis reveals that the pressure gradient (due to wave decay) is of the same order of magnitude as the drag force, wave stress and Reynolds stress terms. In addition, the balance between the pressure gradient and mass conservation induces a seaward current above the canopy, and the presence of the pressure gradient in the momentum equation contributes to intensify the skimming flow at the top of the canopy. Finally, given that the model follows a polynomial function it can be easily implemented in large scale models such as phase average models.





Wave-induced steady currents by submerged canopy-oscillatory flow interaction

A. Cáceres-Euse^{1,2}, A. Orfila³, M. Maza⁴, G. Besio²

¹Mediterranean Institute of Oceanography, MIO, Université de Toulon, 83041 Toulon, Cedex 9, France

²University of Genova, Department of Civil, Chemical and Environmental Engineering (DICCA),

MeteOcean Group, Italy

³Mediterranean Institute for Advanced Studies, IMEDEA (CSIC-UIB), 07190 Esporles, Spain

⁴IH Cantabria - Instituto de Hidráulica Ambiental de la Universidad de Cantabria, 39011, Santander, Spain

Key Points:

- A new analytical model is presented for wave-induced steady current by performing a dimensional analysis
- The model reveals that the wave decay (pressure gradient) contributes to wave-induced steady current
- The steady current is driven by the pressure gradient, wave-steady current interaction drag, and wave and Reynolds stress gradient terms

Corresponding author: A. Cáceres-Euse, acacere@unai.edu.co

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 19 wave-induced steady current caused by submerged aquatic canopy-oscillatory flow in-
 20 teraction. The analytical model takes into account the wave and canopy properties. The
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 23 analysis reveals that the pressure gradient (due to wave decay) is of the same order of
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 25 ance between the pressure gradient and mass conservation induces a seaward current above
 26 the canopy, and the presence of the pressure gradient in the momentum equation con-
 27 tributes to intensify the skimming flow at the top of the canopy. Finally, given that the
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30 Plain Language Summary

31 Submerged aquatic canopies are present worldwide modifying the surrounding coastal
 32 flow (such as mean onshore currents and wave orbital velocities) and dissipating incom-
 33 ing wave heights. Nonetheless, the mechanism and dominant terms in generating wave-
 34 induced steady currents under submerged canopies-wave interaction is not well under-
 35 stood. By applying dimensional analysis to 2-D momentum equation along with parametriza-
 36 tions to the wave stress gradient and pressure gradient (wave decay) terms, we observed
 37 that the wave-induced steady current can be split in three regions: above the canopy top
 38 where the steady current goes seaward, at the canopy top where the current goes shore-
 39 ward, and inside the canopy where the current is very weak compared to the previous
 40 regions (less than 10% the above-canopy orbital velocity). This simplified model can give
 41 us insights about the residence time, horizontal nutrient and sediment transport processes
 42 in coastal canopies, and can be easy to implement in large scale coastal models.

43 1 Introduction

44 Aquatic canopies cover large areas in shallow coastal waters are among the most
 45 biologically diverse and productive components of coastal systems. Canopy meadows are
 46 net sink for atmospheric CO₂ (Duarte et al., 2010) and provide a wide range of ecosys-
 47 tem services (Chen et al., 2019). From the hydrodynamic perspective, aquatic canopies
 48 are an efficient system to dissipate energy from waves and surges by increasing damp-
 49 ing thus protecting and preventing coastal shores from erosion (Maxwell et al., 2017; Foster-
 50 Martinez et al., 2018). These canopies are exposed to long waves (shallow water wave
 51 conditions) where the oscillatory flow dominates hydrodynamics and turbulent features
 52 (Abdolahpour et al., 2020).

53 The vegetation-oscillatory flow interaction begins with the dissipation of the incom-
 54 ing wave due to the work done by the canopy elements (Dalrymple et al., 1984; Kobayashi
 55 et al., 1993; Losada et al., 2016; Lei & Nepf, 2019), the wave orbital velocity attenua-
 56 tion inside the canopy due to the drag resistance by the stems against the flow (Lowe
 57 et al., 2005; Abdolahpour et al., 2016), and the generation of turbulence within the stems
 58 (wake scale) (Nepf, 2012; Tanino & Nepf, 2008; Zhang et al., 2018).

59 The reduction in the wave orbital velocity magnitude by the stems generates a strong
 60 discontinuity in the horizontal orbital velocity component (a shear layer) at the top of
 61 the submerged canopy enhancing the vertical mixing across the top of the canopy by a
 62 Kelvin-Helmholtz-type vortex instability (KH). The KH can occur if the wave excursion
 63 is much larger than the canopy drag length scale and the inertia of the flow overcomes
 64 the viscosity (Abdolahpour et al., 2016; Ghisalberti & Nepf, 2002; Ghisalberti & Schlosser,
 65 2013). This shear layer causes the discrepancy in the Stokes drift velocity at the top of

66 the canopy compared with the non-dissipative linear wave theory (Jacobsen, 2016). Re-
 67 cently, Abdolahpour et al. (2020) highlighted that the vertical mixing due to the shear
 68 layer and the advective transport by a steady current shoreward, have serious implica-
 69 tions on the residence time (i.e., the time scale of water parcels retained within the canopy),
 70 which in turn have biogeochemical implications.

71 To date, few studies have been developed regarding the steady current shoreward
 72 in aquatic canopy-wave interaction (wave-induced steady current). Experimental and field
 73 studies reported that the presence of a shear layer near the top of the coastal canopy in-
 74 duces a streaming flow (analogous to streaming flows in wave boundary layers) as func-
 75 tion of the drag forces creating a steady current shoreward (Luhar et al., 2010, 2013).
 76 Luhar et al. (2010) showed both analytically and experimentally that the work done by
 77 the stems on the flow produces a nonzero time-averaged wave stress at the top of the canopy,
 78 estimating a depth-integrated steady current. This nonzero wave stress hypothesis was
 79 later validated using a Reynolds Averaged Navier-Stokes-Volume of Fluid numerical model
 80 (RANS-VOF) in Chen et al. (2019). Nonetheless, recently, Abdolahpour et al. (2017, 2020)
 81 demonstrated that the steady current shoreward has a strong gradient along the water
 82 depth for submerged canopies with a maximum value at the top of the canopy. This max-
 83 imum value not only depends on the drag forces but also on the wave orbital excursion
 84 (wave parameter). In addition, van Rooijen et al. (2020), using a shallow water equa-
 85 tion model (SWASH), determined that along with the wave stress and the drag force,
 86 the Reynolds stress tensor plays a relevant role in the steady current generation.

87 From this background, it is clear that the role of the dominant terms in the mo-
 88 mentum equation, involved in the wave-induced steady current, is not yet well under-
 89 stood. A first step towards this goal is the development of an analytical model able to
 90 represent the main features of the steady current profile along the water column, which
 91 could be easily applied in large scale coastal models (particularly *phase averaged models*).

92 To take a step forward in our understand of the wave induced steady current by
 93 canopy vegetation-wave interaction, the aim of this work is to answer two main ques-
 94 tions: 1) what are the dominant terms in the momentum equation involved in the wave-
 95 induced steady current under aquatic canopies-wave interaction? and 2) is it possible
 96 to develop a simplified analytical model capable to estimate the depth-dependent wave-
 97 induced steady current as a function of the wave parameters and canopy properties?

98 In this work, an analytical model for the long wave induced steady currents is de-
 99 veloped and compared against experimental data for rigid canopies, and against the nu-
 100 merical simulations from a RANS-VOF model for flexible canopies. The paper is struc-
 101 tured as follows: in Section 2 the analytical model is obtained by scaling the 2D Navier-
 102 Stokes equations, and parameterizing the wave and Reynolds stress terms. In section 3
 103 the analytical model is validated against experimental data for rigid canopies and nu-
 104 merical RANS data for flexible elements. In addition, a discussion and general overview
 105 on wave-induced steady current is presented. Finally, the conclusions and future work
 106 are highlighted in section 4.

107 **2 Development of the analytical model**

108 **2.1 Scaling the momentum equation**

109 In this section, a 1D model for wave-induced steady currents shoreward is going
 110 to be presented. Following Cáceres-Euse et al. (2020), the model assumptions are sum-
 111 marized as:

- 112 1. the cross-stream direction is negligible compared to the stream-wise (wave prop-
 113 agation axis),

- 114 2. the seagrass-oscillatory flow environment can be assumed horizontal and paral-
 115 lel, and
 116 3. the hydrostatic approximation is valid.

117 Under these hypothesis, the 2D momentum and mass conservation equations for the hor-
 118 izontal and vertical velocities and for the pressure are:

$$\frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial wu}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial z^2} \right) + F_D, \quad (1)$$

$$\frac{\partial p}{\partial z} = -\rho g, \quad (2)$$

$$\frac{\partial u}{\partial x} = -\frac{\partial w}{\partial z}, \quad (3)$$

121 where ν and g are the kinematic fluid viscosity and the gravitational acceleration, re-
 122 spectively, F_D is the canopy resistance and ρ the density of seawater.

123 To determine the dominant terms for the wave-induced steady currents in the mo-
 124 mentum equation, a scaling analysis is performed to equation (1). The reference vari-
 125 ables for the scaling are, the wavelength, λ ; the local water depth, h ; a characteris-
 126 tic time scale of several wave periods, $\beta = \alpha T$ (with $\alpha \gg 1$); the characteristic wave-induced
 127 horizontal steady current, \hat{U} ; and the characteristic vertical velocity, \hat{W} . Accordingly,
 128 the following non-dimensional variables are defined:

$$u^* = \frac{u}{\hat{U}}, \quad w^* = \frac{w}{\hat{W}}, \quad p^* = \frac{p}{\rho gh}, \quad x^* = \frac{x}{\lambda}, \quad z^* = \frac{z}{h}, \quad t^* = \frac{t}{\beta}. \quad (4)$$

129 From the mass conservation equation (3) it follows that: $\frac{\hat{U}}{\lambda} \sim \frac{\hat{W}}{h}$, and thus, the char-
 130 acteristic vertical velocity can be defined as $\hat{W} \sim \hat{U}h/\lambda$ and the momentum equation
 131 (1) reads:

$$\frac{\hat{U}}{\beta} \frac{\partial u^*}{\partial t^*} + \frac{\hat{U}^2}{\lambda} \frac{\partial u^{*2}}{\partial x^*} + \frac{\hat{U}^2}{\lambda} \frac{\partial w^* u^*}{\partial z^*} = -\frac{gh}{\lambda} \frac{\partial p^*}{\partial x^*} + \nu \left(\frac{\hat{U}}{\lambda^2} \frac{\partial^2 u^*}{\partial x^{*2}} + \frac{\hat{U}}{h^2} \frac{\partial^2 u^*}{\partial z^{*2}} \right) + F_D^*. \quad (5)$$

132 At this point we remark that $\lambda \gg h$ since we are dealing with the shallow water wave
 133 regime. The last term in equation (5) represents the canopy resistance and will be anal-
 134 ysed in detail later. From the above, $O(\beta) \sim 10^1$ to 10^2 , $O(\lambda) \sim 10^1$ to 10^2 , $O(h) \sim$
 135 10^0 , and $O(\hat{U}) \sim 10^{-1}$ to 10^0 ; thus, $O(\hat{U}/\beta) \sim O(\hat{U}/\lambda^2) \sim O(\hat{U}/h^2) \ll 1$ and the
 136 momentum equation (5), where the gradients are non-dimensional, reduces to:

$$\frac{\hat{U}^2}{\lambda} \frac{\partial u^{*2}}{\partial x^*} + \frac{\hat{U}^2}{\lambda} \frac{\partial w^* u^*}{\partial z^*} = -\frac{gh}{\lambda} \frac{\partial p^*}{\partial x^*} + F_D^*. \quad (6)$$

137 Owing to the advective terms on the left hand side of equation (6) have the same order
 138 of magnitude, they can be grouped as:

$$\frac{\hat{U}^2}{\lambda} \frac{\partial u^{*2}}{\partial x^*} + \frac{\hat{U}^2}{\lambda} \frac{\partial w^* u^*}{\partial z^*} \approx \Gamma \frac{\hat{U}^2}{\lambda} \frac{\partial w^* u^*}{\partial z^*}, \quad (7)$$

139 where $\Gamma = O(1)$ and consequently the momentum equation is:

$$\frac{\hat{U}^2}{\lambda} \frac{\partial w^* u^*}{\partial z^*} = -\frac{gh}{\lambda} \frac{\partial p^*}{\partial x^*} + F_D^*, \quad (8)$$

140 or in dimensional variables as,

$$\frac{\partial wu}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + F_D. \quad (9)$$

141 The drag and inertial forces included in the canopy resistance F_D can be expressed
 142 by the Morrison equation (Dalrymple et al., 1984), as

$$F_D = \frac{1}{2}C_d A_v u |u| + A_v a_v C_M \frac{\partial u}{\partial t}, \quad (10)$$

143 where a_v is the diameter of the stem, $A_v = a_v N_v$ is the frontal canopy area per unit
 144 volume with N_v the number of canopy elements per unit area and C_d and C_M the drag
 145 and inertial coefficients respectively. The nondimensional form of equation (10) is:

$$F_D^* = \frac{1}{2}C_d A_v \hat{U}^2 u^* |u^*| + C_M A_v a_v \frac{\hat{U}}{\beta} \frac{\partial u^*}{\partial t^*}, \quad (11)$$

146 with $\hat{U}^2 u^* |u^*| \gg \hat{U}/\beta(\partial u^*/\partial t^*)$ since $C_d \sim C_M$ (see for instance Lowe et al. (2005);
 147 Etminan et al. (2019)) and the dimensional momentum equation (9) ends,

$$\frac{\partial w u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + F_D, \quad F_D = \frac{1}{2}C_d A_v u |u|. \quad (12)$$

148 Equation (12) represents the dominant terms in the momentum equation involved
 149 in the steady flow generated by submerged canopies in long wave conditions. Note that
 150 the pressure gradient is of the same order of magnitude as the vertical component of the
 151 advection (as well as of the drag force) contradicting previous studies that neglected this
 152 contribution given its unclear role on the generation of the wave-induced steady currents
 153 (Luhar et al., 2010, 2013; van Rooijen et al., 2020).

154 2.2 Time averaging and analytical solution

155 In this section, a time averaging over several wave periods is performed to equa-
 156 tion (12) to determine the magnitude of the wave-induced steady currents. To calculate
 157 the wave-induced steady currents we average equation (12) over several wave periods.
 158 The horizontal and vertical velocities $\mathbf{u} = (u, w)$ are decomposed as,

$$\mathbf{u}(z, t) = \mathbf{u}_m(z, t) + \mathbf{u}'(z, t), \quad \mathbf{u}_m(z, t) = \bar{\mathbf{u}}(z, t) + \tilde{\mathbf{u}}(z, t), \quad (13)$$

159 where \mathbf{u}_m are the mean velocity components (waves plus steady currents), $\bar{\mathbf{u}}$ the time-
 160 independent mean velocity components, $\tilde{\mathbf{u}}$ the wave orbital velocity components and \mathbf{u}'
 161 the turbulent velocity components. Recall that by definition:

$$\bar{\mathbf{u}} = \frac{1}{\beta} \int_t^{t+\beta} \mathbf{u} dt \quad \text{and} \quad \bar{\tilde{\mathbf{u}}} = \bar{\mathbf{u}'} = 0. \quad (14)$$

162 Replacing equation (13) into equation (12), applying the time averaging equation
 163 (14), and stating that waves and turbulence coexist but do not correlate between each
 164 other (Bricker & Monismith, 2007), results in $\overline{w_m u'} = \overline{w' u_m} = 0$. Additionally, given
 165 that $\bar{w} \ll \bar{u}$, one obtains $\bar{w} \bar{u} \approx 0$ and, through equation (14), $\overline{\tilde{w} \tilde{u}} = \overline{\tilde{w} \bar{u}} = 0$. Thus,
 166 the time averaged left hand side of equation (12) can be expressed as:

$$\frac{\partial \overline{w u}}{\partial z} = \frac{\partial \overline{\tilde{w} \tilde{u}}}{\partial z} + \frac{\partial \overline{w' u'}}{\partial z}, \quad (15)$$

167 where $\overline{\tilde{w} \tilde{u}}$ is the time-averaged wave stress and $\overline{w' u'}$ the time-averaged Reynolds stress.

168 Now, the drag force due to the canopy elements is function of the mean flow (wave
 169 and steady currents) (Finnigan, 2000; Nepf, 2012; Luhar et al., 2013), so the turbulent
 170 fluctuations can be neglected and the averaging to F_D in equation(12) can be defined
 171 as:

$$\overline{F_D} = \frac{1}{2}C_d A_v \overline{(\bar{u} + \tilde{u}) |\bar{u} + \tilde{u}|}. \quad (16)$$

172 To simplify Eq.(16), by definition,

$$|\bar{u} + \tilde{u}| \leq |\bar{u}| + |\tilde{u}| \Rightarrow (\bar{u} + \tilde{u})|\bar{u} + \tilde{u}| \leq (\bar{u} + \tilde{u})(|\bar{u}| + |\tilde{u}|), \quad (17)$$

173 and applying the time averaging $\overline{\tilde{u}|\bar{u}|} = \overline{\tilde{u}|\tilde{u}|} = 0$, so the time-averaged momentum
174 equation reduces to

$$\frac{\partial \overline{\tilde{w}\tilde{u}}}{\partial z} + \frac{\partial \overline{w'u'}}{\partial z} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x} + \frac{1}{2} C_d A_v \left(\overline{|\bar{u}|\bar{u}|} + \overline{|\tilde{u}|\tilde{u}|} \right), \quad (18)$$

175 where $\overline{|\bar{u}|\bar{u}|} = \overline{|\bar{u}|^2} \sim O(\bar{u}^2)$ is negligible compared to the wave-steady current in-
176 teraction term $\overline{|\tilde{u}|\tilde{u}|} \sim O(\bar{u}U_\infty)$. U_∞ is the horizontal wave orbital velocity.

177 The first term on the right hand side of equation (18) is formulated based on its
178 maximum value, given its relevant role at the wavelength scale λ ,

$$\frac{\partial \bar{p}}{\partial x} = \rho g \frac{\partial a}{\partial x}, \quad (19)$$

179 where a is the wave amplitude and can be expressed as a function of x (Dalrymple et
180 al., 1984; Losada et al., 2016; Luhar et al., 2017):

$$a(x) = \frac{a_0}{1 + \xi x}, \quad (20)$$

181 here ξ is a wave decay parameter (Dalrymple et al., 1984), and C_d is estimated based
182 on Maza et al. (2013). Thus, the pressure gradient can be approximated within the meadow
183 by using the effective vegetation length scale L_e as:

$$\frac{\partial \bar{p}}{\partial x} \approx -\frac{\rho g \xi a_0}{(1 + \xi L_e)^2}, \quad (21)$$

184 being $L_e = (V - V_m)/A_v$, V a control volume, and V_m the volume of vegetation in-
185 side the control volume (Mazda et al., 1997). Thus, equation (18) can be finally stated
186 as:

$$\frac{\partial \overline{\tilde{w}\tilde{u}}}{\partial z} + \frac{\partial \overline{w'u'}}{\partial z} = \frac{g \xi a_0}{(1 + \xi L_e)^2} + \frac{1}{2} C_d A_v \overline{|\tilde{u}|\tilde{u}|}, \quad (22)$$

187 which is the time-averaged momentum equation dealing with the dominant terms involved
188 in the wave-induced steady current released by aquatic canopy-oscillatory flow environ-
189 ments. This analytically developed equation, is similar to the numerical one presented
190 by van Rooijen et al. (2020), but including the pressure gradient, the Reynolds stress,
191 and the wave-steady current drag force effects. In the next, additional simplifications will
192 be performed in order to find an analytical solution.

193 2.3 Analytical solution and parameterization

194 The Reynolds stress is (Rodi, 1993):

$$\overline{w'u'} = -\nu_t \frac{\partial \bar{u}}{\partial z}, \quad (23)$$

195 where ν_t is the eddy viscosity. Regarding the wave stress term, numerical experiments
196 demonstrated a maximum value at the top of the canopy and zero elsewhere (Chen et
197 al., 2019; van Rooijen et al., 2020). Thus, wave stress gradients at the top of the canopy,
198 $z=h_v$, and Reynolds stress can be respectively simplified as:

$$\left(\frac{\partial \overline{\tilde{w}\tilde{u}}}{\partial z} \right)_{z=h_v} \approx \frac{\overline{\tilde{w}\tilde{u}}}{\delta} \approx \frac{\overline{\tilde{w}\tilde{u}}}{0.2A_w}, \quad \frac{\partial \overline{w'u'}}{\partial z} = -\nu_t \frac{\partial^2 \bar{u}}{\partial z^2}, \quad (24)$$

199 where $\delta \approx 0.2A_w$ being A_w the horizontal wave orbital excursion and δ is the shear layer
 200 thickness (Cáceres-Euse et al., 2020). $A_w = U_\infty T / (2\pi)$ and U_∞ comes from the lin-
 201 ear wave theory. The definition for ν_t is presented in the appendix section. Addition-
 202 ally, applying a skin friction formulation on a rough surface leads (Lowe et al., 2005; Jensen
 203 et al., 1989; Infantes et al., 2012; Foster-Martinez et al., 2018):

$$\frac{\overline{\tilde{w}\tilde{u}}}{\delta} \approx -\frac{f_w U_{\infty, rms}^2}{2\delta} \approx -\frac{f_w U_{\infty, rms}^2}{0.4A_w}, \quad (25)$$

204 where $U_{\infty, rms}$ is the root mean square of the horizontal wave orbital velocity far from
 205 the canopy effect and f_w the friction factor coefficient (Nielsen, 1992) see appendix). Re-
 206 placing equation (24) into equation (22) results in:

$$\frac{\partial^2 \bar{u}}{\partial z^2} = \frac{1}{\nu_t} \left(-\frac{ga_0\xi}{(1 + \xi L_e)^2} + \left(\frac{\partial \overline{\tilde{w}\tilde{u}}}{\partial z} \right)_{z=h_v} - \frac{1}{2} C_d A_v \overline{|\tilde{u}|} \right). \quad (26)$$

207 Integrating vertically twice equation (26), and assuming that the wave-steady cur-
 208 rent interaction term can be simplified as $\bar{u} \ll |\tilde{u}|$ (always below the top of the canopy),
 209 leads to $\overline{|\tilde{u}|} \approx U_c |\tilde{u}|$ and $|\tilde{u}| \leq U_h^{rms}$ where U_h^{rms} is the root mean square of the
 210 horizontal wave orbital velocity inside the canopy and U_c the steady current at the bot-
 211 tom. Additionally, $U_h^{rms} = \phi U_{\infty, rms}$ with $\phi < 1$ is the attenuation parameter (Lowe
 212 et al., 2005). The time averaged momentum equation (equation 26) can be finally writ-
 213 ten as:

$$\overline{u(z)} = \frac{z^2}{2\nu_t} \left(-\frac{ga_0\xi}{(1 + \xi L_e)^2} + \left(\frac{\partial \overline{\tilde{w}\tilde{u}}}{\partial z} \right)_{z=h_v} - \frac{1}{2} C_d A_v \phi U_c U_{\infty, rms} \right) + C_1 z + C_2, \quad (27)$$

214 with C_1 and C_2 integration constants and with $\overline{u(z)}$ satisfying the mass conservation:

$$\int_0^h \overline{u(z)} dz \approx 0. \quad (28)$$

215 Finally, applying the boundary condition at the bottom, *i.e.* $\overline{u(0)} = U_c$ we can write:

$$\overline{u(z)} = \left(\frac{3z^2 - 2zh}{6\nu_t} \right) \left(\frac{-ga_0\xi}{(1 + \xi L_e)^2} + f(z) \left(\frac{\overline{\tilde{w}\tilde{u}}}{0.2A_w} \right) - \frac{\epsilon}{2} C_d A_v \phi U_c U_{\infty, rms} \right) + U_c \left(1 - \frac{2z}{h} \right), \quad (29)$$

216 where $\epsilon = 1$ for $z \leq h_v$ and $\epsilon = 0$ for $z > h_v$, and,

$$f(z) = \begin{cases} 1 - \frac{1}{\delta} |h_v - z|, & z \in [h_v - \delta, h_v + \delta] \\ 0, & z \leq h_v - \delta \wedge z \geq h_v + \delta, \end{cases} \quad (30)$$

217 a delta function included to activate or deactivate the effect of the wave stress at the top
 218 of the canopy. Finally, the steady current at the bottom can be estimated assuming that
 219 drag coefficients for waves and current are comparable (Luhar et al., 2010), so that,

$$U_c = \sqrt{\frac{4}{3\pi} \frac{k}{\sigma} U_b^3}, \quad U_b = \frac{3}{4} \frac{a^2 \sigma k}{\sinh^2(kh)}, \quad (31)$$

220 where k , and σ are the wavenumber and angular frequency, and U_b the steady current
 221 in absence of canopy (Longuet-Higgins, 1953).

222 3 Validation and discussion of the analytical model

223 The vertical profile for steady current obtained with the analytical model is tested
 224 in this section for rigid vegetation using experimental data from van Rooijen et al. (2020)

Table 1. Experimental and numerical parameters. U_r the Ursell, Re Reynolds and KC Keulegan-Carpenter numbers.

Van Rooijen et al. 2020					
ID	$H(m)$	$T(s)$	Re	KC	U_r
$R1$	0.14	2	1043	51	4.19
$R2$	0.10	3	1009	74	7.86
$R3$	0.21	3	1845	135	16.51
$R4$	0.20	4	1722	169	29.45
$R5$	0.09	5	1182	144	21.22
$R6$	0.21	5	1887	230	49.42
Maza et al. 2013					
ID	$H(m)$	$T(s)$	$N(m^{-2})$	$h(m)$	U_r
$CM1$	0.44	3.5	180	2.4	6.91
$CM2$	0.49	4	360	1.8	20.26

225 and for flexible vegetation with numerical experiments from Maza et al. (2013). van Rooi-
 226 jen et al. (2020) performed experiments considering a rigid canopy under 6 different wave
 227 conditions. The tests were done in a 35 m long, 1.2 m deep, and 1.2 m wide wave flume.
 228 A Nortek Vectrino ADV measuring at 25Hz was placed at the midpoint of the canopy.
 229 The canopy was constructed as an staggered dowels array of 6.4 mm diameter, 30 cm
 230 high, approximately 3100 units per m^2 density, and 2.5 m long. Water depth was equal
 231 to 75 cm, wave heights ranged from 9 to 21 cm and wave periods from 2 to 5 s (see Ta-
 232 ble 1).

233 Regarding the numerical data for a flexible canopy, Maza et al. (2013) performed
 234 numerical simulations using a RANS-VOF model, including the stem flexibility and the
 235 relative displacement between the stems and the surrounding oscillatory flow. Two canopy
 236 density values were tested, 180 units per m^2 and 360 units per m^2 . The stems were 55cm
 237 high (including their base), 1mm thick and 1cm width, and the material used to built
 238 them had a Young's modulus equal to 2.9 GPa. Wave height, water depth and wave pe-
 239 riod were defined according to Table 1.

240 3.1 Rigid canopy

241 Figure 1 displays the comparison of the normalized steady current of the exper-
 242 imental data and the analytical model for rigid canopies. The 95% confidence interval
 243 of the experimental data, estimated by using the interquartile and bootstrapping meth-
 244 ods, is also shown in the figure. Results show that for all cases tested, the steady cur-
 245 rent obtained by using the analytical model is always inside the confidence interval of
 246 the experimental data from the bottom to the canopy top. Below the top of the canopy
 247 the steady current is around 10% the horizontal wave orbital velocity. At the top of the
 248 canopy the steady current goes shoreward. This behaviour was already reported exper-
 249 imentally and numerically by Luhar et al. (2013, 2010); van Rooijen et al. (2020); Ab-
 250 dolahpour et al. (2017). Additionally, the skimming flow at the top of the canopy is well
 251 reproduced, and the current inside the canopy is basically depth-uniform. From the top
 252 of the canopy to the free surface, a seaward current is observed. This seaward current
 253 is identified by the model in agreement with van Rooijen et al. (2020); Luhar et al. (2010).
 254 Nonetheless, for $R1$ and $R2$ the analytical model presents the largest deviation with re-
 255 spect to the experimental data. Two possible sources of error are attributed to these dis-
 256 crepancies: 1) the wave height decay formulation used in the present model assumes a

257 linear wave theory, so the pressure gradient is being underestimated; and 2) the last term
 258 on the right hand side of Eq.(29) is a linear function dependent of the water depth and
 259 proportional to U_c . In addition, the seaward current above the top of the canopy is depth-
 260 dependent and follows a parabolic profile as demonstrated in Eq.(29). Finally, the lower
 261 the KC number (KC in Table 1) the least the effect by the pressure gradient on the sea-
 262 ward current in the analytical model (as observed in Figure 1).

263 3.2 Flexible canopy

264 To test the analytical model for the steady current induced in flexible canopies, the
 265 canopy frontal area has been modified by an stem-effective length to account for the bi-
 266 ased position induced by the streaming. Following Luhar et al. (2013, 2017) this length
 267 is function of the Cauchy (Ca) and Buoyancy (B) numbers. In addition, for the RANS
 268 model velocity, possible departures from the steady current due to turbulent fluctuations
 269 or systematic errors are not possible to be assessed by confidence intervals.

270 The normalized wave induced steady currents in flexible canopies are shown in Fig-
 271 ure 2 showing a good performance at the top of the canopy (the shoreward current) for
 272 both wave conditions. Above the canopy, the seaward current from the analytical for-
 273 mulation and RANS model are in agreement for $CM1$, but not for $CM2$ where the an-
 274 alytical model presents a lower value. For flexible canopy scenarios it seems that the wave
 275 non-linearity influences the seaward current estimation. The higher the Ur the bigger
 276 the difference between the RANS and the analytical model. So, the pressure gradient
 277 is being underestimated for non-linear wave conditions.

278 3.3 General discussions

279 Concerning the steady current at mid-canopy, the profile can be split in three re-
 280 gions (see Figure 3). $Z1$, above the canopy top, shows a parabolic seaward current as
 281 the result of the balance between pressure gradient and mass conservation restriction (the
 282 linear function on the last term of the right hand side of equation (29)). $Z2$, at the canopy
 283 top, presents a skimming flow shoreward where the pressure gradient, the wave stress,
 284 steady current-wave drag force, and mass conservation restriction are involved. $Z3$, be-
 285 low the canopy top, presents a very low velocity magnitude where the momentum bal-
 286 ance is between the pressure gradient, the steady current-wave interaction drag force,
 287 and mass conservation restriction. Below the top of the canopy, the steady current given
 288 by the analytical model predicts a shoreward current while the RANS simulations and
 289 experimental data show a seaward current, but, \bar{u} is less than 10% $U_{\infty,rms}$ for all sce-
 290 narios. Nonetheless, ADV experimental data in Abdolahpour et al. (2017) and Particle
 291 Image Velocimetry data in van Veelen et al. (2020) reported some shoreward currents
 292 scenarios.

293 Finally, Figure 1 and Figure 2 show an analytical solution neglecting the pressure
 294 gradient term where is possible to observed how this term contributes to the seaward cur-
 295 rent above the canopy top and intensifies the skimming flow at the top of the canopy (sce-
 296 narios where the pressure gradient is included). In addition, the steady current over a
 297 flat bottom and no canopy (upstream the canopy) (see Figure 3) presents a similar be-
 298 havior to a mean flow in Longuet-Higgins (1953), where a wave height decay is produced
 299 by the viscous dissipation when the wave interacts with the bottom (Luhar et al., 2010).
 300 In this region, the first term (pressure gradient) and the last term on the right hand side
 301 of equation (29) define the steady current profile. This result is in agreement with the
 302 experimental work in Luhar et al. (2010); Abdolahpour et al. (2017).

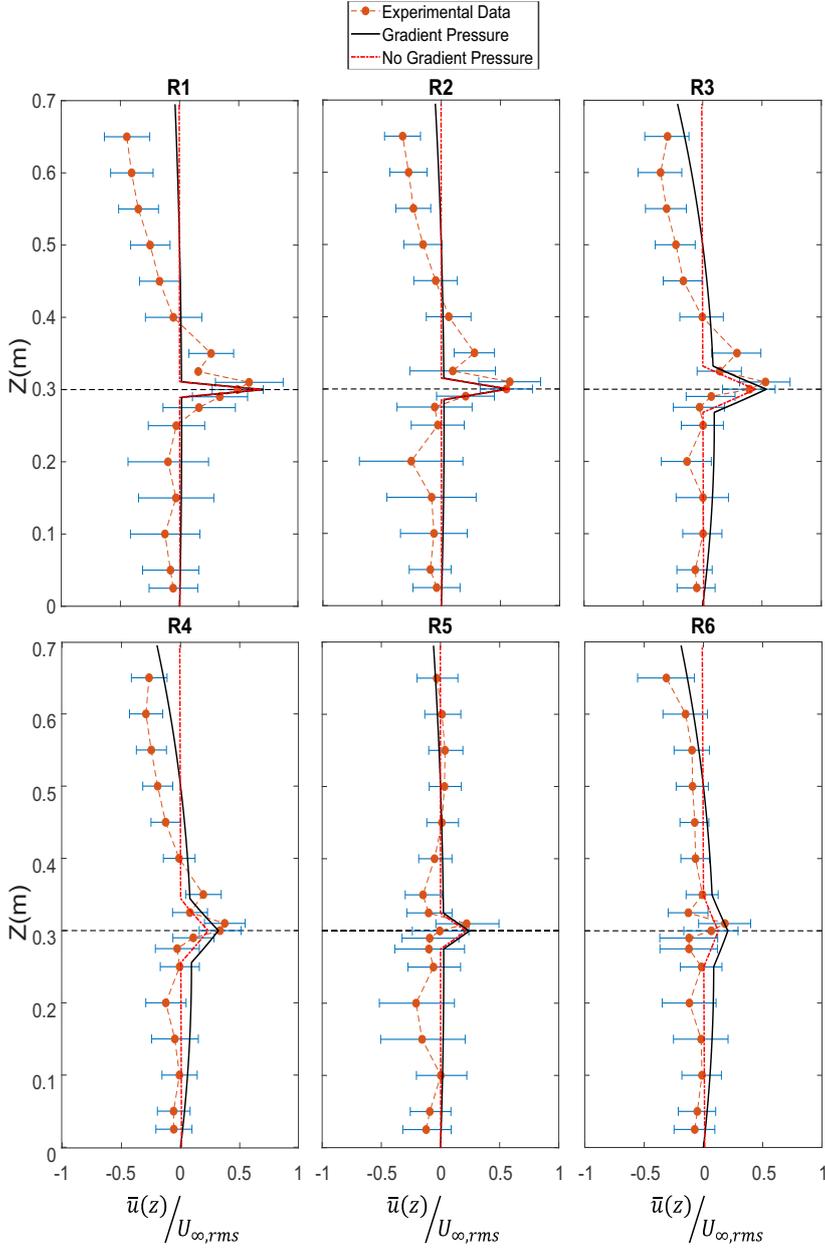


Figure 1. Normalized wave-induced steady current, $\overline{u(z)}$. $U_{\infty,rms}$ is the horizontal root mean square wave orbital velocity far from canopy effects. Orange dot-dashed line is the experimental data, blue line the confidence interval. The continuous black and red dashed lines are the analytical model including the pressure gradients and neglecting the pressure gradient, respectively. The horizontal dashed line indicates the canopy top.

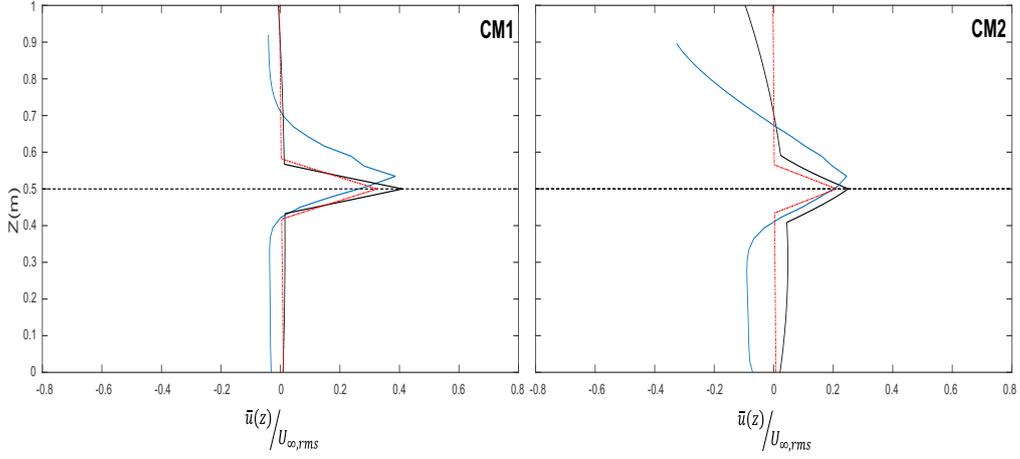


Figure 2. Normalized wave-induced steady current. $U_{\infty,rms}$ is the horizontal wave orbital velocity far from canopy effects. The blue corresponds to the *RANS – VOF* model by Maza et al. (2013), and the continuous black and red dashed lines are the analytical model with and without the pressure gradient, respectively.

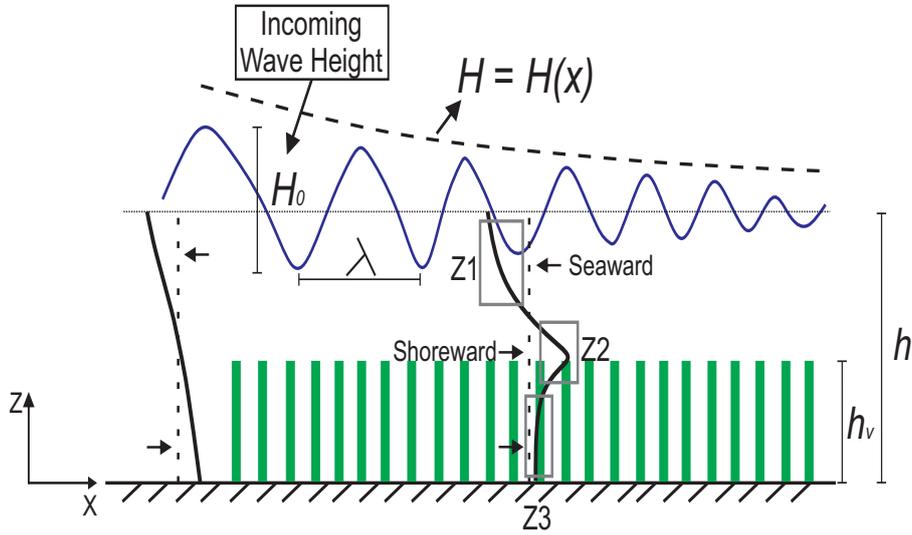


Figure 3. Qualitative scheme for the wave-induced steady current. Dashed line represents the vertical axis of the velocity profile. Upstream is the steady current profile with no canopy. Mid-canopy represents the steady current vertical profile under aquatic vegetation-wave interaction.

4 Conclusions

In this work we provide a step forward to a better understanding of the mechanisms involved in the wave-induced steady current under wave-canopy interaction by formulating a simple analytical model. The development is performed by a dimensional analysis to the momentum equation satisfying the mass conservation. The model, expressed by a polynomial function, can be easily implemented in large scale phase averaged coastal models in order to include the wave-induced steady current created by aquatic canopies-wave interaction.

The development of the analytical model revealed the dominant terms driving the wave-induced steady current. Some of the terms discussed in this work were introduced in previous studies by using numerical simulations, however, this is the first approach from analytical departure solving a depth-dependent wave-induced steady current. Additionally, the influence by the wave decay (pressure gradient) on inducing the seaward current above the canopy and its contribution to the skimming flow at the top of the canopy was also revealed in this work.

The highest discrepancies between the analytical model and experimental/RANS data are observed above the canopy top, the seaward direction. These differences are attributable to the underestimation in the pressure gradient since we assumed a linear wave decay. Thus, the development of wave decay statements based on nonlinear wave theory is further needed.

The wave-induced steady current can be split in three regions. Above the canopy top (a balance between the mass conservation restriction and pressure gradient) a seaward current is observed. At the top of the canopy a shoreward current is realised and intensified when including the pressure gradient term. Inside the canopy where the steady flow is weak compared with the other two regions. Additionally, in the present study a parametrization to the wave stress term is defined, however, investigations to the wave stress gradient term is needed in order to improve the steady current calculations.

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5 Appendix

The parameters used to calculate the wave-induced steady currents are defined as follows,

$$C_d = 0.87 + \left(\frac{2200}{Re_d} \right)^{0.88}, \quad Re_d = \frac{a_v U_\infty}{\nu}$$

$$f_w = \exp \left[5.123 \left(\frac{K_b}{A_w} \right)^{0.1944} - 5.977 \right]$$

$$\xi = \frac{2ka_v C_d}{9\pi} \left[\frac{9\sinh(kh_v) + \sinh(3kh_v)}{\sinh(kh)(\sinh(2kh) + 2kh)} \right]$$

342 where K_b is the hydraulic roughness and given that the inertial term in the canopy resistance is negligible ϕ can be defined based on Lowe et al. (2005),
343

$$\phi = \sqrt{\frac{C_f(1 - \lambda_p)}{C_d \lambda_f}}$$

344 where the empirical friction coefficient is assumed $C_f \sim 0.01$, however, future improvements to the model can include a parametrization as function of the flow condition.
345

346 To solved the Reynolds stress in Equation (29) a formulation based on Prantdl mixing-length hypothesis in Cáceres-Euse et al. (2021) has been used,
347

$$\overline{u'w'} = -\nu_t \frac{\partial \bar{u}}{\partial z} \Rightarrow u_*^2 \sim \nu_t \frac{U_{\infty, rms}}{\delta}$$

348 and assuming $u_* \sim 0.1U_{\infty, rms}$ (Lowe et al., 2005),

$$\nu_t \sim \frac{\delta U_{\infty, rms}}{100}$$

349 For simplicity, ν_t has been assumed constant and dependent on the wave properties and
350 canopy drag.

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