

Searching for Subsurface Oceans on the Moons of Uranus Using Magnetic Induction

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November 21, 2022

Abstract

Icy moons around the ice giant planets may contain subsurface oceans. Their oceans could be detected and characterized using measurements of magnetic fields induced by the host planet's time-varying magnetospheric field. We explore the possibility of detecting and characterizing subsurface oceans among the five major moons of Uranus—with a particular focus on Ariel—using spacecraft magnetometry measurements. We find that the magnetic field at each moon is dominated by the synodic frequency with amplitudes ranging from ~ 4 nT at Oberon up to ~ 300 nT at Miranda. If these bodies contain oceans with sufficient thicknesses ($> \sim 6$ -100 km) and conductivities (> 2 S m^{-1}), the induced surface fields should have amplitudes exceeding the typical ~ 1 nT sensitivity of spacecraft magnetometry investigations. Furthermore, the magnetic field at the moons spans periods ranging from 1 to 10^3 h. This could enable long-term measurements to separately constrain ocean and ice thicknesses and ocean salinity.

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10 **Key Points:**

- 11 • The surfaces of the Uranian moons show evidence for resurfacing following formation
12 and therefore may contain subsurface oceans.
- 13 • Uranus's magnetic field may induce time-varying currents in these oceans that generate
14 induced magnetic fields.
- 15 • Spacecraft measurements of such induced fields could detect oceans on each of the five
16 major moons, especially Miranda and Ariel.

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19 **Keywords:**

20 Uranus, ice giants, spacecraft missions, icy moons, magnetic induction, magnetometry

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23 **Abstract**

24 Icy moons around the ice giant planets may contain subsurface oceans. Their oceans could be
25 detected and characterized using measurements of magnetic fields induced by the host planet's
26 time-varying magnetospheric field. We explore the possibility of detecting and characterizing
27 subsurface oceans among the five major moons of Uranus—with a particular focus on Ariel—
28 using spacecraft magnetometry measurements. We find that the magnetic field at each moon is
29 dominated by the synodic frequency with amplitudes ranging from ~4 nT at Oberon up to ~300
30 nT at Miranda. If these bodies contain oceans with sufficient thicknesses (>~6-100 km) and
31 conductivities (>2 S m⁻¹), the induced surface fields should have amplitudes exceeding the typical
32 ~1 nT sensitivity of spacecraft magnetometry investigations. Furthermore, the magnetic field at
33 the moons spans periods ranging from 1 to 10³ h. This could enable long-term measurements to
34 separately constrain ocean and ice thicknesses and ocean salinity.

35 **Plain Language Summary**

36 The icy moons of Uranus may harbor subsurface oceans. These oceans may be habitable
37 environments and tell us about the moon's formation and evolution of their orbits. Here we explore
38 the possibility that these oceans could be detected and characterized by magnetic field
39 measurements from a spacecraft. In particular, the time-varying magnetic field of Uranus may
40 generate currents in a salty ocean by the process of induction. These currents could then generate
41 a secondary magnetic field detectable by a spacecraft flyby. Here we explore this possibility by
42 calculating the ambient and induced magnetic fields around the five largest moons of Uranus:
43 Miranda, Ariel, Umbriel, Titania, and Oberon. We find that the spin of Uranus and the orbital
44 motion of the moons leads to strong time-varying fields at each moon. If these moons harbor thick
45 (>10 km) oceans with salinities like that of Earth's oceans, their induced fields would likely be
46 detectable by a close flyby. Longer term field measurements from a Uranus and/or dedicated icy
47 moon orbiter could likely constrain the ocean and ice thickness and ocean salinity.

48 **1 Introduction**

49 Ocean worlds, planetary bodies with large-scale liquid water layers (Nimmo & Pappalardo,
50 2016), have been discovered amongst the icy moons of Jupiter and Saturn and perhaps beyond.
51 Ocean worlds are of great interest for several reasons. Most importantly, they may be some of the
52 most common potentially habitable environments in the solar system. Second, their volatile-rich
53 interiors represent a unique end member of planetary structure. Third, they are natural laboratories
54 for studying tides and the moons' coupled orbital and thermal evolution.

55 The icy moons of the ice giants are likely to be major targets of upcoming spacecraft
56 missions [e.g., Balint et al. (2020); Elder et al. (2021); Hofstater & Simon (2017)]. Here we
57 explore the possibility of detecting and characterizing subsurface oceans on the five major moons
58 of Uranus—Miranda, Ariel, Umbriel, Titania, and Oberon—using spacecraft magnetometry
59 measurements from flybys and orbiters. Amongst the 27 known Uranian moons, these are the only
60 bodies sufficiently large to likely retain liquid water today. Furthermore, with the possible
61 exception of that of Oberon, their surfaces show geomorphological evidence for resurfacing
62 following accretion which may be a signature of past or present subsurface water. We consider the
63 approach of magnetic induction whereby a spacecraft magnetometer senses magnetic fields from
64 electrical currents in the oceans generated by Uranus's time-varying magnetic field. We focus on

65 Ariel in particular since it is the most likely amongst the major moons to have a present-day ocean
66 and because it experiences some of the strongest variations in the Uranian field.

67 This work, first presented in meeting form (Weiss et al., 2021; Weiss et al., 2020), was
68 conducted simultaneously and independently of two complementary studies (Arridge &
69 Eggington, 2021; Cochrane et al., 2021). The former focuses more on the two outermost moons
70 and incorporates the effects of magnetospheric currents (Arridge & Eggington, 2021), while the
71 latter focuses more on statistical induction forward models and the possible effects of an
72 ionosphere and current sheet (Cochrane et al., 2021). Our study uniquely considers the
73 implications of recent compositional and thermal evolution models for Ariel, including the
74 possibility of a conducting briny rocky core, for detection and characterization of its liquid interior.

75 **2 Interior Structures of the Major Moons**

76 2.1 Overview of the major moons

77 Uranus' major moons have radii ranging from 235.8 km (Miranda) to 788.9 km (Titania),
78 with their sizes generally increasing outwards with semimajor axis (with a slight decrease from
79 Titania to Oberon) (de Pater & Lissauer, 2015). Their orbits are near-circular (eccentricities 0.0011
80 to 0.0039) and largely confined to the equatorial plane of Uranus (inclinations 0.041 to 0.13°,
81 except for Miranda which is 4.3°) with semimajor axes ranging from 5.1 (Miranda) to 22.8
82 (Oberon) Uranus radii (R_U) (JPL Solar System Dynamics, 2021). They are not currently in mutual
83 mean motion resonances (Ćuk et al., 2020; Titemore, 1990).

84 The moons have mass ratios of silicate to ice ranging from ~0.5 to ~0.7 for all but Miranda,
85 which has 0.3 (Hussmann et al., 2015). Their surfaces are dominated by H₂O ice [possibly in the
86 form of methane clathrates (Schenk, 1991)], while CO₂ has also been identified on Ariel, Umbriel
87 and Titania (Grundy et al., 2006). With the possible exception of Oberon, their surfaces show
88 resurfacing, variably manifested as possible diapiric coronae, grabens, and/or cryovolcanic flows
89 (Schenk & Moore, 2020). In particular, Ariel's surface consists of lightly cratered plains with
90 viscously relaxed craters. The plains are dissected by 2-4 km deep troughs with floors covered
91 with possible cryovolcanic materials interpreted to be H₂O ice and/or NH₃-hydrates (Cartwright et
92 al., 2020; Schenk, 1991). The ages of the moons surfaces may be as young as 0.1-0.4 billion years
93 (Ga) for Ariel and Miranda (Zahnle et al., 2003).

94 Three main theories for the moons origin have been proposed. First, they may have
95 accreted out of material that condensed in a circumuranian nebula (Szulágyi et al., 2018). However,
96 it is uncertain if this is consistent with Uranus's 98° obliquity, which is thought to be the product
97 of giant impacts near the end of Uranus' formation (Kegerreis et al., 2018; Morbidelli et al., 2012;
98 Rogoszinski & Hamilton, 2021; Safronov, 1966). An alternative scenario is that the moons
99 accreted subsequently out of the ejecta disk (Ida et al., 2020; Rogoszinski & Hamilton, 2021;
100 Slattery et al., 1991). A third possibility is that the moons formed from tidal interactions between
101 Uranus and rings created from the disruption of cometary material [e.g., Crida & Charnoz (2012)].

102 In the circumuranian nebula formation by model by Szulágyi et al. (2018), the moons
103 formed sufficiently early that they likely contained live ²⁶Al that could have driven early volatile
104 melting and internal differentiation. Formation from an ejecta disk would likely have occurred
105 after the ²⁶Al heat source was exhausted and would have required tidally-driven heating for moon

106 interiors to partially melt. Lastly, following accretion in a first generation of rings, the moons could
 107 have been tidally heated during a period of high eccentricity orbits (Charnoz et al., 2011). In the
 108 latter scenario, the moons would have formed mostly undifferentiated and undergone partial
 109 melting. Neveu and Rhoden (2019a) suggested such bodies could sustain long-lived convection of
 110 brines in a porous rocky core (25% porosity).

111 2.2 Possible interior oceans

112 The heat responsible for the resurfacing of the moons may have been supplied by the gravitational
 113 energy of formation, radiogenic elements, and possibly tidal forcing (Hussmann et al., 2015). The
 114 relatively old surfaces and non-zero eccentricity observed at each moon suggests these bodies are
 115 not subject to significant tidal heating at present. However, the moons may have previously passed
 116 through one or more low-order mean motion resonances that may have generated substantial
 117 heating (Chen et al., 2014; Čuk et al., 2020; Tittlemore, 1990). Hence, the preservation of a deep
 118 relict ocean is mainly determined by the modalities of heat transfer since the moons emerged from
 119 past resonances. Considering the strong temperature-dependence of ice's thermal conductivity, the
 120 moons would freeze in a few hundred Ma following a melting event in the absence of a long-term
 121 heat source [following Castillo-Rogez et al. (2019)]. Clathrate hydrates in the icy shell could
 122 significantly slow freezing of the hydrosphere (Castillo-Rogez et al., 2019; Kamata et al., 2019).
 123 The porous briny core model (Neveu & Rhoden, 2019a) may not allow for the presence of deep
 124 oceans in the moons except for Ariel [preliminary results by Neveu and Rhoden (2019b)], whereas
 125 a clathrate-rich shell could likely maintain relict oceans in all the moons but Miranda [see also
 126 Hussmann et al. (2006)].

127 Given these uncertainties for the major moons, we consider a broad range of interior
 128 models consisting of two and three layers with spherical symmetry (Figure 1). The three-layer
 129 model, which represents the case of a relict ocean, consists of an innermost nonconducting rocky
 130 core of radius r_c overlain by a ocean of thickness, h and uniform conductivity, σ , and capped with
 131 a nonconducting icy shell of thickness, d [e.g., Zimmer et al. (2000)]. The two-layer model, which
 132 represents the briny core case, consists of an innermost porous briny core of thickness, h , and
 133 uniform conductivity, σ , capped with a nonconducting ice shell of thickness, d . The outermost ice
 134 layer in both models has a radius equal to mean radius of each moon, r_m . Mathematically, the two-
 135 layer model is an end-member of the three-layer case for which $r_c = 0$. Because theory and
 136 observations indicate the Uranian moons at most should have tenuous atmospheres (surface
 137 pressure < 20 nbar even around the largest moon, Titania), we have not included an additional outer
 138 conducting layer associated with a putative ionosphere (Widemann et al., 2009). Also, we have
 139 not included the contribution from a putative metallic core because its contribution to the induction
 140 signal is expected to be small [e.g., Zimmer et al. (2000)]. Analysis of these and other additional
 141 conductive layers should be the subject of future work.

142 For Ariel, we focus on two particular realizations of the relict ocean and briny core models
 143 that are motivated by the above considerations. For Ariel's relict ocean model, we consider a < 30
 144 km-thick conductive ocean underlying a 170-km thick non-conducting clathrate-rich shell. For
 145 Ariel's briny core model, we consider a solid hydrosphere overlying a briny porous rocky core
 146 (25% porosity). Both structures are consistent with Ariel's estimated ratio of rock to ice, which
 147 would indicate a total hydrosphere thickness of ~ 150 -200 km for a differentiated body. The
 148 electrical conductivities of the conducting briny layers in these two cases are based on the fact that
 149 accreted volatiles such as CO_2 , NH_3 could significantly contribute to ocean conductivity in the

150 form of bi/carbonate ions and ammonium. An average cometary composition would lead to an
151 electrical conductivity of $\sim 2 \text{ S m}^{-1}$ (0°C) prior to an increase of the salinity as a consequence of
152 freezing. For a 30-km thick relict ocean, the hypersaline waters could have a conductivity of 15 S
153 m^{-1} based on terrestrial analogs (Rebello et al., 2020) and correcting for the effect of temperature
154 (Smith, 1962). These are likely minimum values because we are not considering the effects of
155 pressure, which tends to increase electrical conductivity at the tens of MPa relevant to Ariel's
156 residual ocean (Schmidt & Manning, 2017) and because $<30 \text{ km}$ oceans would have even more
157 concentrated solute. In the case of a porous core, the electrical conductivity of the mixture
158 computed with Archie's law is of the order of $1\text{-}3 \text{ S m}^{-1}$ for 30% brine mixed with rock (with the
159 range reflecting uncertainties in brine temperature). For this study, we assume the mean value 2 S
160 m^{-1} .

161 **3 Methodology**

162 3.1 Overview of magnetic induction

163 We employ the classic technique of magnetic induction to search for conducting subsurface
164 saltwater oceans (Zimmer et al., 2000). Time-varying fields inside a conducting body generate
165 currents by Faraday's law of induction. These currents in turn generate a secondary magnetic field
166 by Ampere's Law that can be sensed by a magnetometer.

167 These driving fields can be used to probe for subsurface oceans as part of two major stages
168 of exploration. First, detection of induced fields from a small number of close (i.e., <1 moon
169 radius in altitude) flybys could identify the existence of an ocean by measuring the induction
170 response at a single frequency. However, degeneracies between the ocean thickness, ice thickness,
171 and ocean conductivity make it challenging to determine these parameters separately from single-
172 frequency sounding. This is what the Galileo mission achieved for Europa (Zimmer et al., 2000).
173 Second, repeated, long-term (e.g., lasting for tens of moon orbital periods or more) measurements
174 at a given moon could enable multi-frequency sounding data that could enable separate
175 determination of the ocean thickness, ice thickness, and ocean conductivity (Seufert et al., 2011).
176 This is the goal of the Europa Clipper mission (Raymond et al., 2015).

177 In the following, we begin by calculating the driving field, the time-variable field of Uranus
178 as viewed by each moon. We will then use this to calculate the induced field. The spacecraft will
179 measure a superposition of the steady component of the Uranian field, the driving field, and the
180 induction field. As a metric for the feasibility of using magnetic induction to search for subsurface
181 oceans, we will compare these fields to the nominal sensitivity of a spacecraft magnetometry
182 investigation. For a typical spacecraft fluxgate magnetometer and/or gradiometer on $\geq 2 \text{ m}$ long
183 boom, magnetic field accuracies of $<1 \text{ nT}$ have been commonly achievable (Anderson et al., 2007;
184 Connerney et al., 2017; Glassmeier et al., 2010; Kiverson et al., 1992).

185

186 3.2 Driving field

187

188 Our goal is to calculate the magnetic field in the time and frequency domain of each moon.
189 At the locations of the moons orbits, Uranus's magnetic field is well described by a dipole offset
190 from Uranus' center by $\sim 0.3 R_U$ along the spin axis toward the geographic north pole and tilted by
191 59° (note that a spherical harmonic expansion using a fixed origin also has power dominated by
192 the dipole terms) (Connerney et al., 1987). The wobbling of the field due to Uranus' rotation (17.2
193 h period), combined with orbital motion due to the moon's nonzero eccentricities and inclinations
194 (periods ranging from 33.6-323 h from Miranda out to Oberon), collectively produce time variable
195 fields in the reference frames and locations of the moons.

196 We calculated the moon's motions using their orbital elements (JPL Solar System
197 Dynamics, 2021) as well as using SPICE kernels (The Navigation and Ancillary Information
198 Facility, 2021). Because we found that the frequencies of the signals with amplitudes > 1 nT (as
199 well as the amplitudes of these signals) for both approaches were essentially indistinguishable
200 given the accuracy of our discrete fast Fourier transform (FFT) implementation (see below), here
201 we report results using the orbital elements. In the moon's reference frames, x points from the
202 moon toward Uranus, y points opposite the direction of orbital motion, and z completes the right
203 handed-triad (nearly along the spin axis of Uranus).

204 For the Uranian field, we used the internal hexadecapole AH_5 magnetic field model derived
205 from Voyager 2 Magnetometer data and Ultraviolet Spectrometer observations of aurora (Herbert,
206 2009) (Figure S1) at at the epoch of the Voyager 2 flyby (1986). Given the estimated magnetopause
207 distance of $\sim 19R_U$, all of the moons with the occasional exception of Oberon and Titania should
208 spend essentially all of their time within the magnetosphere (Paty et al., 2020). Furthermore, the
209 large angle between Uranus's spin and offset dipole axes means that the moons will spend
210 relatively little time near the magnetic equator where field perturbations associated with a
211 magnetospheric plasma sheet could mask the induction signals (Cochrane et al., 2021). Because
212 we are focused on the innermost moons, we have neglected the effects of external diurnally and
213 seasonally-driven magnetospheric currents on the driving field; these are likely mainly relevant
214 for Titania and Oberon (Arridge & Eggington, 2021) and should be the subject of future work.

215 We calculated the field at each moon with a time interval of $0.01 \times$ the synodic frequency
216 over aduration of $10^7 \times$ the synodic frequency. These were chosen to minimize spectral leakage
217 and the picket fence effect (Girgis & Ham, 1980) in the FFTs in order to accurately estimate the
218 amplitudes of the synodic frequencies and their harmonics. We found that The highest amplitude
219 variation is in the x -component followed by the y -component, with both components having near-
220 zero mean and $\sim 90^\circ$ offset in phase with respect to one another (Figure 2). The z -component
221 variations are much weaker (ranging from 14% down to 3% of that of the x -component proceeding
222 outward from Miranda to Oberon) and with non-zero mean (Figure 2).

223 We find that the dominant frequency at the major moons is that of the synodic (i.e., time
224 required for a moon to return to the same longitude above Uranus's surface). The periods, T , and
225 total amplitudes, A , of the synodic variations range from ~ 35 h and ~ 330 nT at Miranda to ~ 18 h
226 and ~ 3.6 nT out at Oberon. These frequencies have skin depths of ~ 33 -46 km and ~ 91 -130 km for
227 oceans with conductivities like that expected for the relict ocean and briny core scenarios,
228 respectively. Furthermore, the moons experience a rich range of other driving frequencies at
229 harmonics of the synodic frequency, their orbital frequencies, beating between the synodic and
230 orbital frequencies, and harmonics of these frequencies (Figures 3, S3); similar results were
231 obtained by Cochrane et al. (2021) and Arridge & Eggington (2021). We find that for Miranda,
232 Ariel, and Umbriel, the first four, three and two harmonics of the synodic period, respectively have
233 amplitudes exceeding the nominal 1 nT magnetometry sensitivity threshold. Meanwhile, for

234 Titania and Oberon, only the first harmonic of the synodic period exceeds this value. The orbital
 235 frequency for all the moons are below this threshold largely due to the moons' low inclinations.

236 3.3 Induced field

237 We calculate the induced field, B_{ind} , using the two and three-layer models (Figure 1)
 238 following classic techniques in electrodynamics (Jackson, 1999; Parkinson, 1983; Srivastava,
 239 1966; Zimmer et al., 2000). Let us express Uranus's field, \vec{B}_U , as a sum of a time-independent
 240 term, \vec{B}_0 and a time-variable primary field \vec{B}_{pri} that drives induction. The primary field can be
 241 expressed as the sum $j = 1: N$ frequency components with amplitude, \vec{B}_j , frequency, $\omega_j = 2\pi/T_j$,
 242 and phase, δ_j , and oriented in the direction of unit vector \vec{b}_j so that

$$243 \vec{B}_U = \vec{B}_0 + \vec{B}_{\text{pri}} = \vec{B}_0 + \sum_{j=1}^N B_j e^{-i(\omega_j t - \delta_j)} \vec{b}_j \quad (1)$$

244 The primary field frequencies induce oscillating dipole moments $\vec{M}_j = -(4\pi/2\mu_0)A_j e^{i\varphi_j} B_j \vec{b}_j r_m^3$,
 245 with amplitudes, A_j and phase lags $+\pi + \varphi_j$ relative to that of the driving field ($\omega_j - \delta_j$); here
 246 μ_0 is the permeability of free space. The induced field is given by

$$247 \vec{B}_{\text{ind}} = \sum_{j=1}^N \frac{\mu_0}{4\pi} \frac{3(\vec{r} \cdot \vec{M}_j)\vec{r} - r^2 \vec{M}_j}{r^5}$$

$$248 = - \sum_{j=1}^N A_j e^{-i(\omega_j t - \varphi_j - \delta_j)} B_{\text{pri}} \frac{3(\vec{r} \cdot \vec{b}_j)\vec{r} - r^2 \vec{b}_j}{2r^5} r_m^3 \quad (2)$$

249 for radial position from the center of the moon, \vec{r} , and where

$$250 A_j e^{i\varphi_j} = \left(\frac{r_0}{r_m}\right)^3 \frac{R_j J_{5/2}[(r_m - d)k_j] - J_{-5/2}[(r_m - d)k_j]}{R_j J_{1/2}[(r_m - d)k_j] - J_{-1/2}[(r_m - d)k_j]} \quad (3)$$

251 with

$$252 R_j = \frac{[(r_m - d - h)k_j]k_j J_{-5/2}[(r_m - d - h)k_j]}{3J_{3/2}[(r_m - d - h)k_j] - [(r_m - d - h)k_j]k_j J_{1/2}[(r_m - d - h)k_j]} \quad (4)$$

253 Here, J_m are Bessel functions of the first kind and order m and $k_j = \sqrt{i\omega_j \mu_0 \sigma}$. For the three-layer
 254 sphere (i.e., $r_m - d - h > 0$), R_j is in general nonzero, whereas for the two-layer sphere (i.e., $r_m -$
 255 $d - h = 0$), $R_j = 0$.

264 The skin depth, the depth at which the primary field declines by a factor of $1/e$ for a semi-
 265 infinite conducting half space, is given by $s = \sqrt{2/\omega_j \mu_0 \sigma}$. The induction amplitude grows and the
 266 phase delay shrinks as the ocean gets thicker (i.e., h increases) and/or more conductive (σ
 267 increases). When the skin depth approaches the ocean thickness (i.e., $h \approx s$), the amplitude and
 268 phase dependence pass through a local minimum (i.e., decrease and then increase over a limited
 269 range of h and σ) (Hand & Chyba, 2007). Eventually, as these two parameters increase further, a
 270 saturated state is reached with $A_j = 1$ and $\varphi_j = 0$. For thin oceans (i.e., $h \ll r_m$), equations (3)
 271 and (4) reduce to

$$272 \quad A_j \approx \frac{2r_m h}{3s^2} = \frac{\mu_0 r_m h \omega_j \sigma}{6} \quad (5)$$

273
 274 Therefore, all other parameters being fixed, larger moons and higher frequency driving fields
 275 produce higher amplitude induced fields.
 276

277 Forward modeling the induction field [equation (2)] consists of choosing values for h , σ ,
 278 and d and computing A_j and φ_j using equations (3) and (4). The inverse problem of solving for
 279 the three parameters h , σ , and d from the two observations A_j and φ_j at a single frequency is
 280 clearly nonunique. This is illustrated by the fact that a thick, low conductivity ocean will produce
 281 a similar amplitude induction field as a thin, conductive ocean (Khurana et al., 2009; Seufert et al.,
 282 2011). Furthermore, a thick ice shell and thick ocean will have a similar amplitude induction field
 283 as that of a thin ice and thin ocean (although the phase lag for the latter will be greater). The
 284 nonuniqueness can be broken by sounding at multiple frequencies, provided that the ocean is near
 285 saturation (i.e., $h \approx s$) for at least one of the frequencies.
 286

287 4. Results

288 Because most of the variation at the synodic frequency at each moon occurs in the x - and
 289 y -components, the induction poles for these frequencies lie within $\pm \sim 4^\circ$ of the equators of all
 290 moons but that of Miranda (for which it lies with $\pm \sim 6^\circ$). The induction poles sweep across the
 291 moons with the associated induced moments oscillating in magnitude at their respective
 292 frequencies. This means that spacecraft flybys with closest approaches near the equatorial regions
 293 of the moons and that sample a widely distributed range of phases will enable the most sensitive
 294 induction studies.

295 The amplitude of induced fields depend on σ , d , and h while the phase depends on σ , d .
 296 The response exhibits a degeneracy in which a given measured amplitude and phase are each
 297 consistent with a wide range of combinations of σ and h (Figure 4A). The amplitude grows and
 298 the phase lag approaches 0 with increasing h (as more fluid can participate in the induction
 299 process) and increasing σ (as a given ocean approaches saturation) (Figure 4B, C). Following
 300 equation (5), the minimum ocean conductivity and thickness required to generate a 1-nT amplitude
 301 induction field at the surface induction pole grows monotonically with the moons' distance from
 302 Uranus (and therefore with the amplitude of Uranus' field), with the exception that the order of
 303 Ariel and Miranda are reversed because of Ariel's $2.5\times$ larger radius (Figure 4A).

304 We first consider the case of ocean detection. We see that for the estimated conductivities
 305 of a relict ocean and briny core, surface measurements could detect conducting layers with

306 minimum thicknesses as low as ~ 0.3 and ~ 2 km (for Miranda) and ranging up to ~ 5 and ~ 50 km
307 (for Oberon), respectively under a nominal 50-km thick ice shell (Figure 4A). By comparison,
308 oceans $\ll 1$ km are detectable at Europa; this is much smaller than that of the Uranian moons
309 mainly because of Europa's large radius (twice that of Titania) and because it experiences a large
310 synodic amplitude approaching that of Miranda (Figure 4A). Furthermore, for a single flyby of
311 Ariel within 200 km of its surface [e.g., that proposed for insertion of a flagship mission into orbit
312 around Uranus (Hofstadter & Simon, 2017)], we find that induced fields for relict oceans of
313 thickness of just a few km as well as from the briny core structure should have amplitudes
314 detectable with a typical magnetometry investigation (Figure S4). Likewise, Cochrane et al. (2021)
315 have shown that even in the presence of a model ionosphere, a relict ocean with just 2 S m^{-1}
316 conductivity and thickness of < 10 km could be detectable.

317 With respect to ocean characterization, we find that multi-frequency sounding is likely
318 readily achievable at least at Miranda and Ariel. In particular, for Ariel, separate determination of
319 ocean thickness, ice thickness and ocean conductivity may be possible for conductivities $> \sim 1 \text{ S}$
320 m^{-1} and ocean thicknesses $> \sim 20$ km (Figure 4B, C). More generally, this investigation could be
321 enabled by multiple (≥ 10 -20) flybys of each moon and/or dedicated moon orbiters or landers.

322 **5 Conclusions**

323 The five major moons of Uranus may harbor relict oceans and/or briny cores underneath
324 their ice shells. The time-variable Uranian magnetospheric field of Uranus could produce
325 substantial induced magnetic fields in the liquid layers of these moons, dominantly at the synodic
326 frequency and its harmonics. For a nominal 50-km thick ice layer, relict oceans layers with
327 conductivities of 15 S m^{-1} and thicknesses of < 7 km could be detected on the major moons by a
328 close flyby of a typical spacecraft magnetometry experiment. Multi-frequency sounding from
329 flybys could in principle characterize the ocean thickness and conductivity for at least Miranda
330 and Ariel. As such, searching for subsurface oceans on the major moons using magnetic induction
331 should be a key science objective of a future mission to the Uranian system.

332 **Data Availability Statement**

333 The internal magnetic field coefficients of Herbert (2009) were used to model Uranus's driving
334 field. No data were created for this research.

335 **Acknowledgments**

336 We thank Marc Neveu for helpful discussions. We thank the NASA Jet Propulsion Laboratory
337 (consulting services agreement #1662407), the NASA Europa Clipper project (University of
338 Michigan/JPL SUBK00011438), the MIT Undergraduate Research Opportunities Program and the
339 MIT Department of Earth, Atmospheric and Planetary sciences for support. Part of this work was
340 carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract
341 with the National Aeronautics and Space Administration (80NM0018D0004). B. P. W. and J. B.

342 B. conceived the project, B. P. W. supervised the project, and all authors conducted calculations
 343 were involved in writing the manuscript. The authors declare no competing interests.

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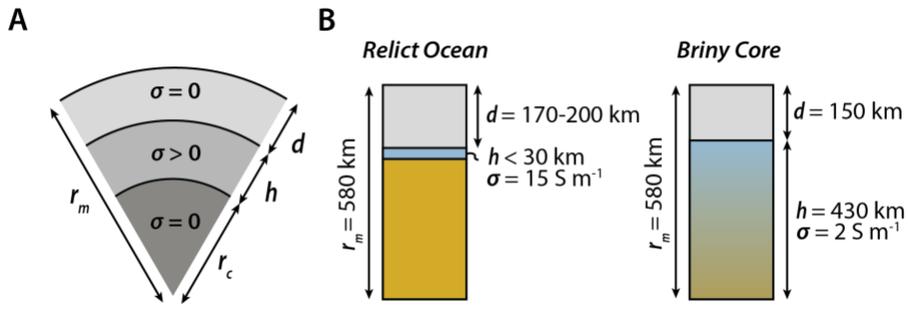
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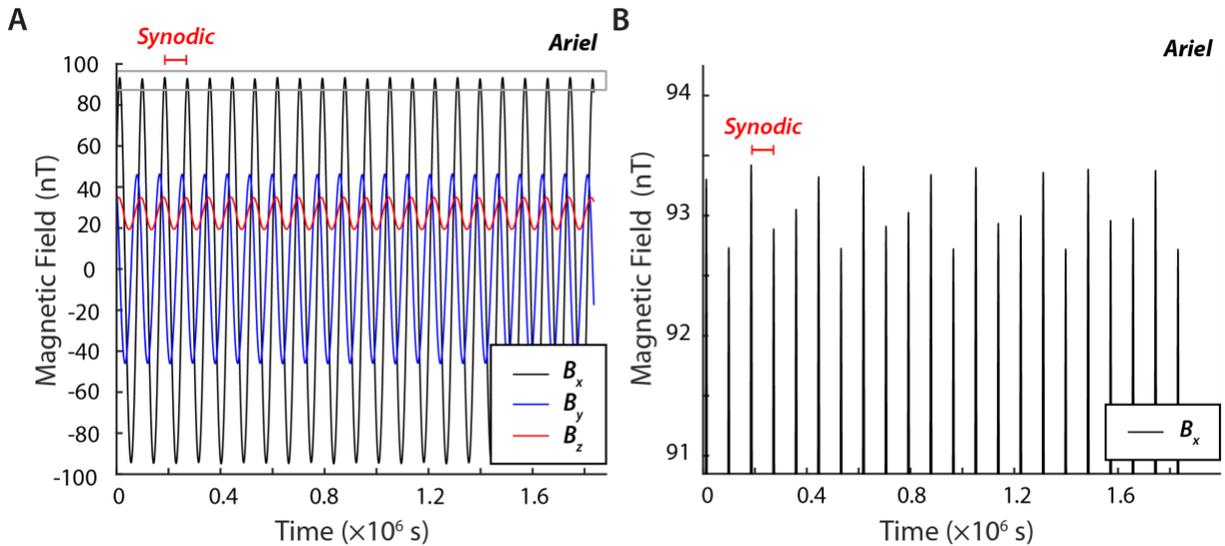
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471 **Figure 1.** Assumed Moon interior models. (A) General model for all the moons, consisting of
 472 three-layer spherical body with a nonconducting rock ice core of radius r_c , overlain by a
 473 conducting layer of thickness, h , and conductivity, σ , which is in turn overlain by a nonconducting
 474 ice shell of thickness, d . (B) Two end-member spherically-layered models for Ariel. Left: relict
 475 ocean, consisting of <30 km-thick ocean with conductivity of up to 15 S m^{-1} . Right: briny core,
 476 consisting of 430 km-thick porous, rocky mantle with conductivity of 2 S m^{-1} .

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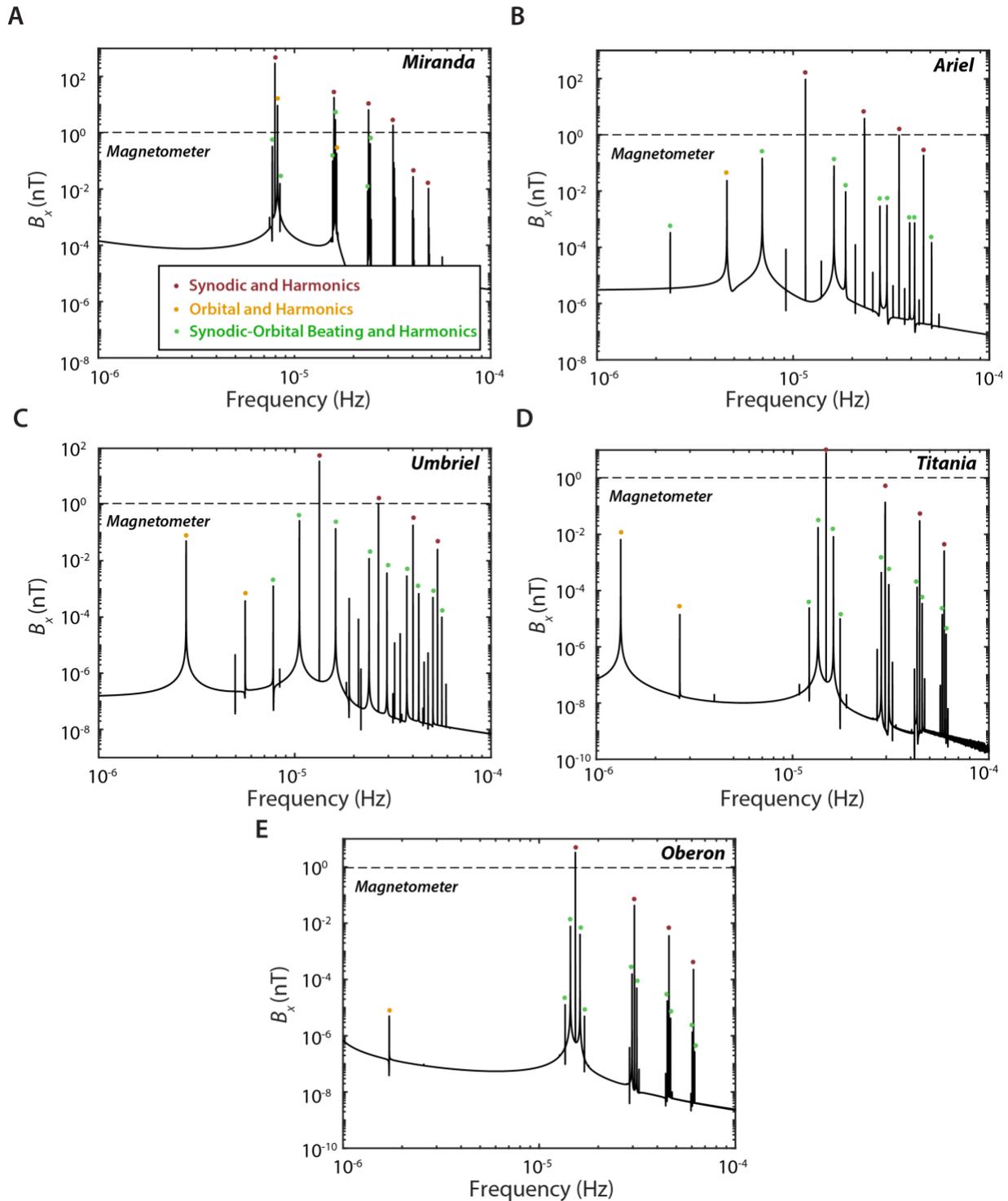


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482 **Figure 2.** Uranus's time variable magnetic field as experienced by Ariel. (A) Three field
 483 components, where the x points toward Uranus, y points opposite the orbital velocity of the moon,
 484 and z completes the triad. The synodic period is labeled. (B) Zoom-in to grey boxed region in (A),
 485 showing the presence of additional frequencies modulating and interfering with the synodic
 486 frequency.

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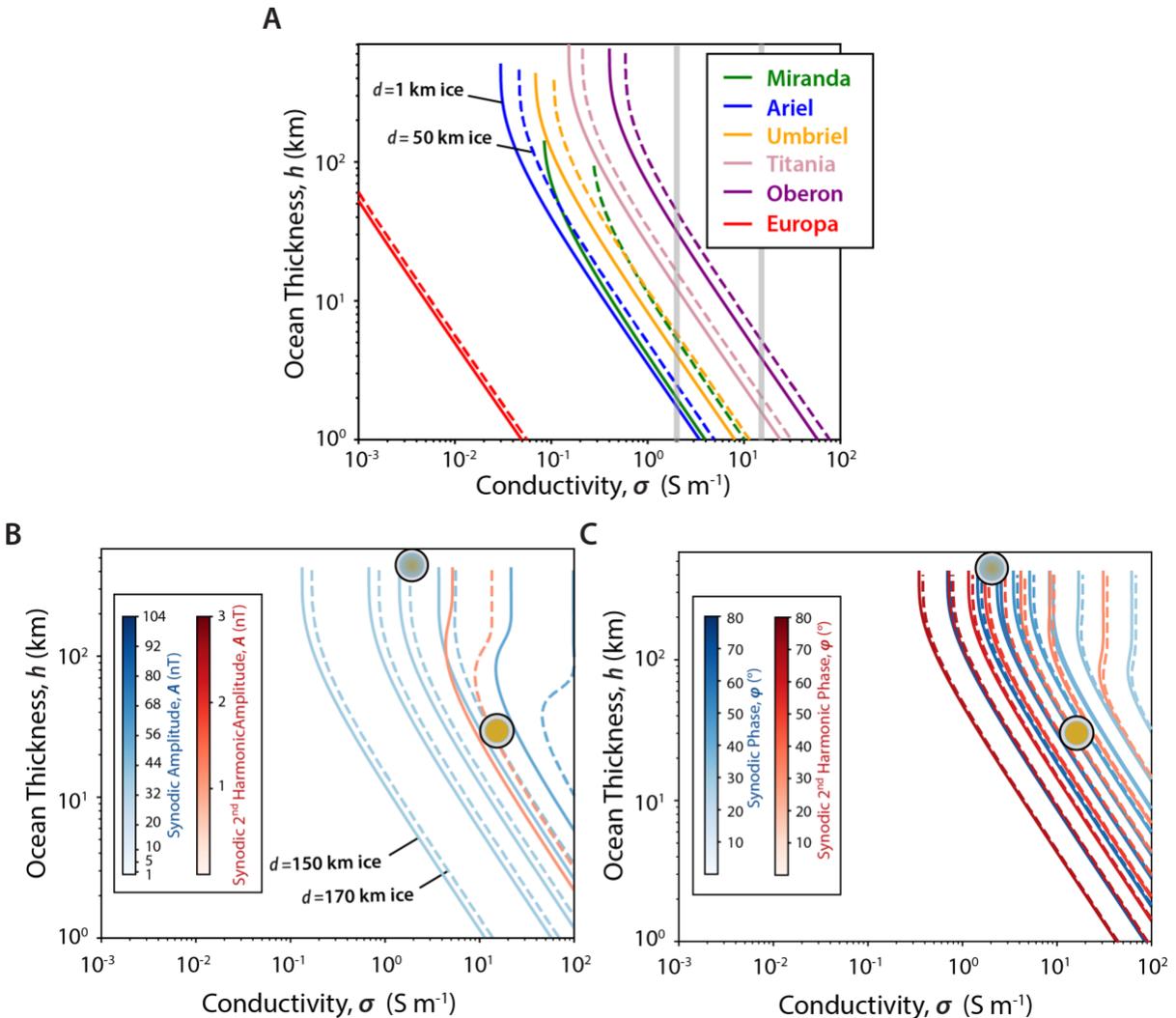


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489 **Figure 3.** Periodogram of the x -component of Uranus’s magnetic field as experienced by the major
 490 moons. There is a rich spectrum of frequencies including the synodic and its harmonics (red), the
 491 orbital frequency and its harmonics (orange), and beats between the synodic and orbital frequency

492 harmonics (green). Dashed lines denote 1 nT sensitivity of typical spacecraft magnetometry
 493 investigations. (A) Miranda. (B) Ariel. (C) Umbriel. (D) Titania. (E) Oberon.

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496 **Figure 4.** Induction fields at the synodic frequencies of the major moons and the Jovian moon
 497 Europa at the surface induction pole. (A) Combinations of ocean thickness and conductivity for
 498 producing a 1 nT amplitude. Solid and dashed curves are for ice thicknesses of 1 km (solid lines)
 499 and 50 km (dashed lines). Shown are conditions for Miranda (green), Ariel (blue), Umbriel
 500 (orange), Titania (pink), Oberon (purple), and Europa (red). Vertical grey bars denote
 501 conductivities for briny mantle (left) and relict (ocean). (B, C) Amplitude and phase of the
 502 response of the induced field for Ariel as function of ocean thickness and conductivity compared
 503 to two expected interior structures. Dashed curves denote end-member relict ocean, consisting of
 504 30 km-thick ocean with conductivity of $15\ S\ m^{-1}$, overlain by a 170-km thick ice shell. Solid curves
 505 denote briny mantle, consisting of 430 km-thick porous, conducting mantle with conductivity of 2
 506 $S\ m^{-1}$ overlain by 150-km thick ice shell. Shown is the response to the first (red) and second (blue)

507 harmonics of the synodic frequency. Numerical values of contours correspond to labeled values
508 on colorbars. Two colored circles denote briny ocean (top) (Fig. 1B) and 30-km thick relict ocean
509 (bottom) (Fig. 1C). Note that electrical conductivities greater than 20 S m^{-1} are not expected even
510 for hypersaline solutions due to interactions between ions and the low eutectic temperature of
511 relevant solutions.

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Supporting Information for:

Searching for Subsurface Oceans on the Moons of Uranus Using Magnetic Induction

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Submitted to: *Geophysical Research Letters*

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Figures S1 to S4

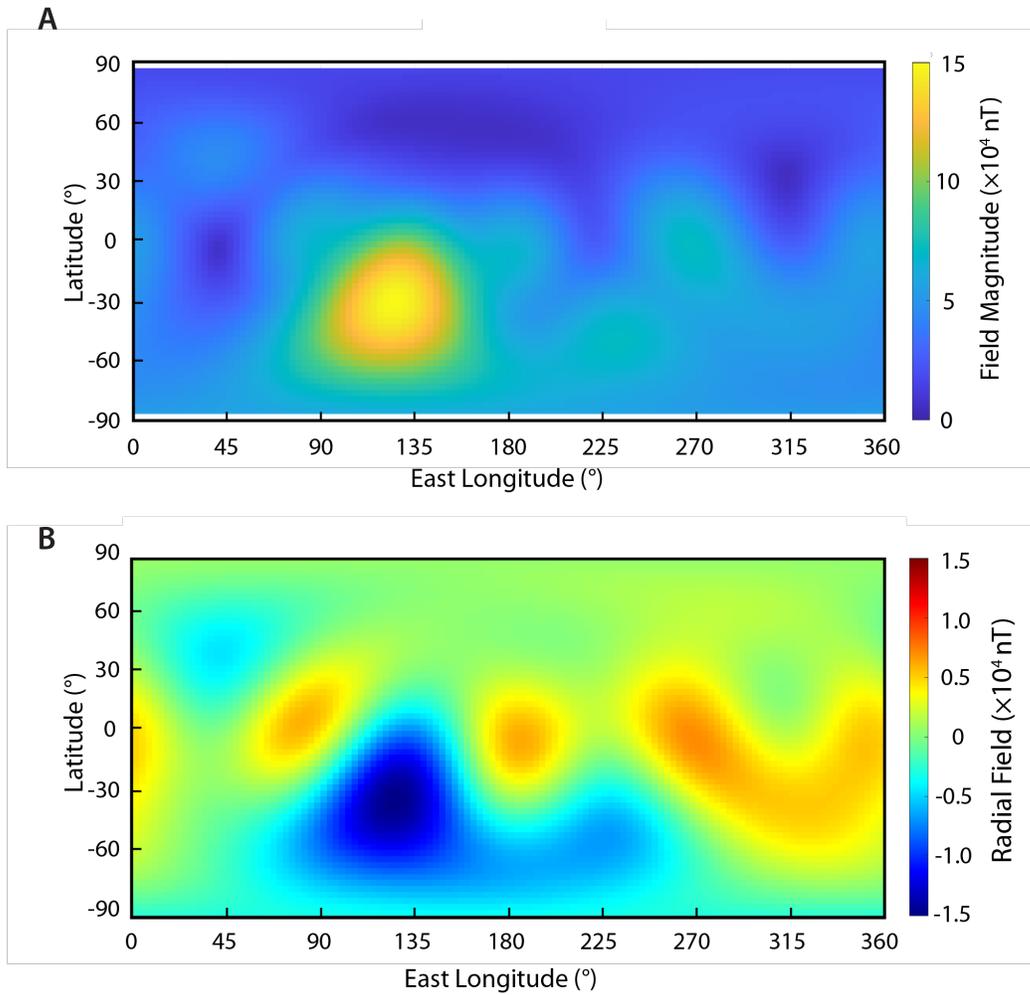


Figure S1. Uranus' magnetic field as measured by Voyager 2. Shown is the AH₅ hexadecapole model of Herbert (2009). (A) Field magnitude. (B) Radial field.

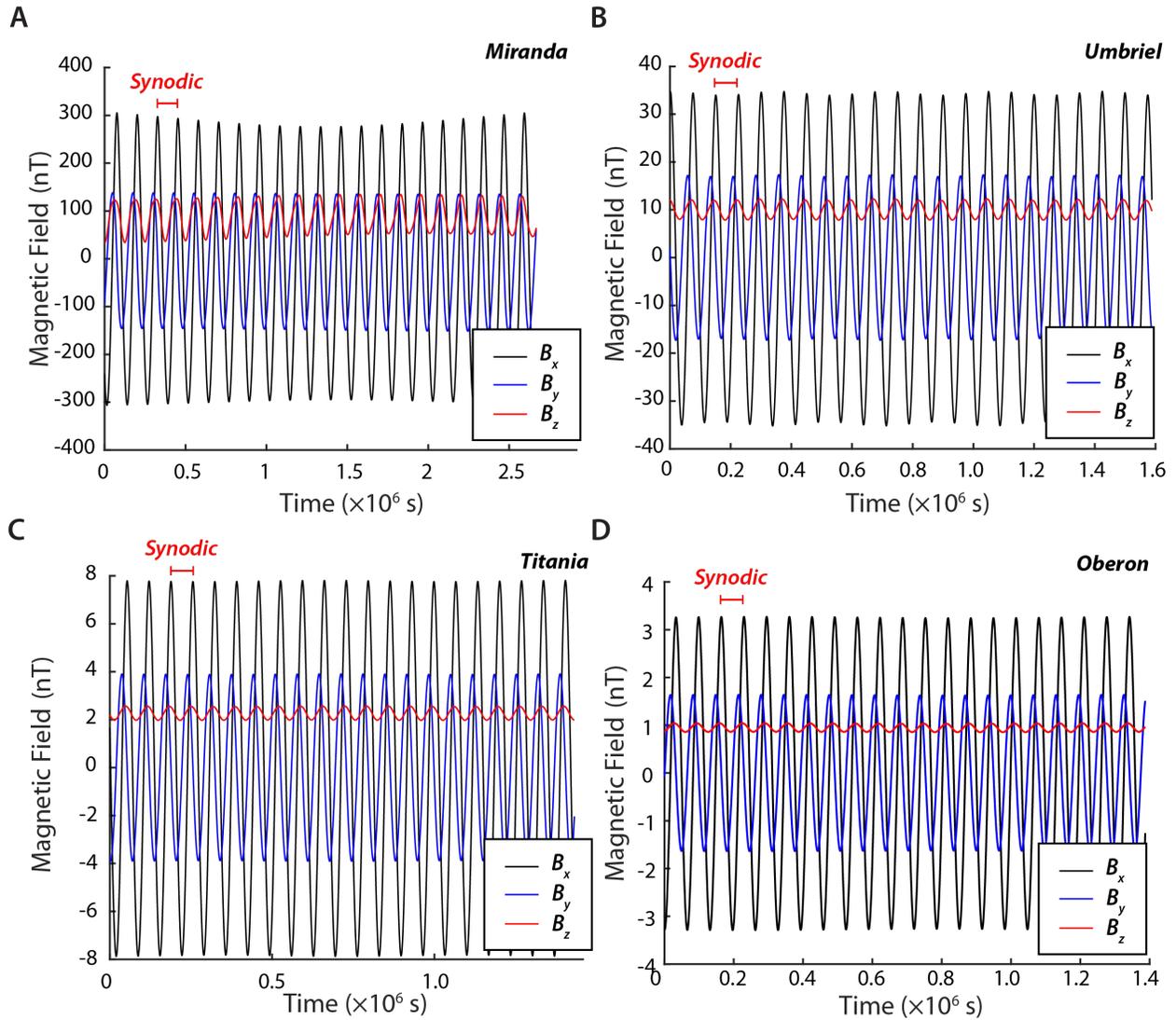


Figure S2. Uranus’s time variable magnetic field as experienced by the other major moons. (A) Three field components, where the x points toward Uranus, y points opposite the orbital velocity of the moon, and z completes the triad. The synodic period is labeled. (A) Miranda. (B) Umbriel. (C) Titania. (D) Oberon.

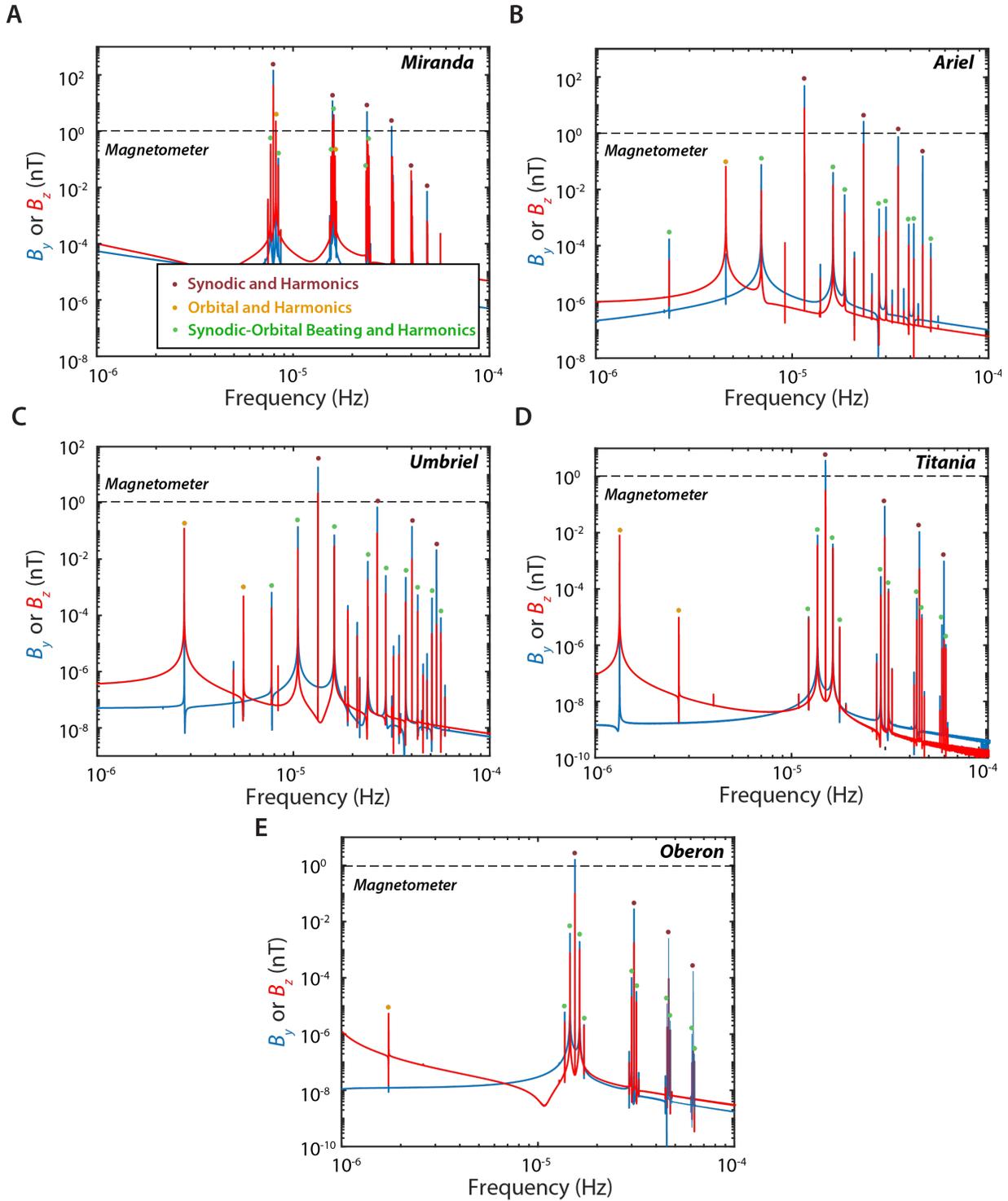


Figure S3. Periodograms of the y - and z -components of Uranus's magnetic field as experienced by the major moons. As with the x -components (Figure 3), there is a rich spectrum of frequencies including the synodic and its harmonics (red), the orbital frequency (orange), beats between the synodic and orbital frequency and harmonics of these beats (green). Dashed line denotes 1 nT sensitivity of typical spacecraft magnetometry investigations. Red boxes denote synodic frequencies and their harmonics. (A, B) y - (red) and z - (blue) components for Miranda. (C, D) y -

(red) and z- (blue) components for Ariel. (E, F) y- (red) and z- (blue) components for Umbriel. (G, H) y- (red) and z- (blue) components for Titania. (I, J) y- (red) and z- (blue) components for Oberon.

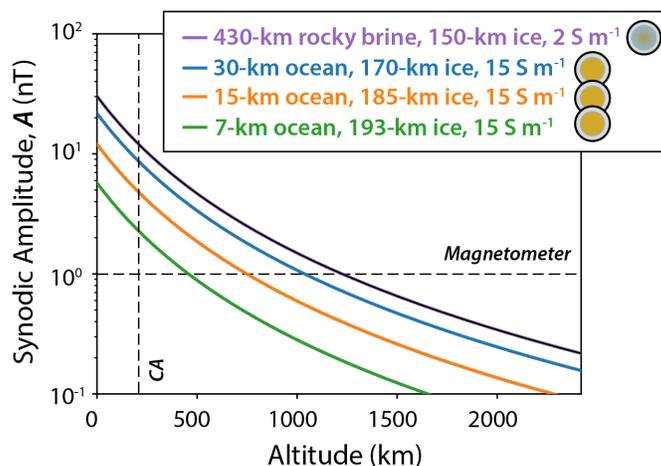


Figure S4. Amplitude of the induction signal at Ariel as a function of altitude above the surface induction pole. Shown is the response for four assumed interior structures. Purple curve denotes induced field for 430 km rocky brine with conductivity of 2 S m^{-1} overlain by 150-km thick ice layer. Blue, orange, and green curves denote induced fields for water oceans with conductivities of 15 S m^{-1} and fixed H_2O thickness of 200 km: 30-km ocean overlain by 170-km thick ice (blue), 15-km ocean overlain by 185-km thick ice (orange), and 7-km ocean overlain by 193-km thick ice (green). Horizontal and vertical dashed lines denote spacecraft magnetometry threshold and 200-km closest approach (CA) of an Ariel flyby from Hofstdater & Simon (2017).