Flow-field fitting method and acoustic Doppler velocity measurement: a new approach and its application to the detection of leakage pathways in the concrete face rockfill dam

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Abstract

The paper is to detect the leakage inlets, determine the leakage pathways through the dam, and ensure that the amount of the leakage in the upstream and downstream is consistent, and that there is no leakage around the concrete face rockfill dam. The injection of a pseudo-random current in the water between two aluminum sheets A and B generates a current field that can be measured in the water with sensitive current sensors. When the current is channeled along leakage pathways, the flow-field fitting method can be used to detect these inlets of the leakage pathways. We first review the background equations for the seepage field and the current field in the flow-field fitting method, and we also use an approach to calculate the discharge and ensure the consistency of the upstream and downstream leakage based on the Doppler effect in physics. Moreover, to illustrate how the flow-field fitting method works, we use numerical simulation method to verify the feasibility of the flow-field fitting method. Lastly, we proceed with a case study for which the flow-field fitting method and the acoustic Doppler flow velocity measurement are used to identify and map potential leakage pathways bypassing upstream into the flow measurement weir of the downstream. The approaches proposed in this paper successfully detect three leakage areas and obtain the discharge. The results of detected in a case study provide engineering geology information for optimizing the layout of grouting holes.

1 **Flow-field fitting method and acoustic Doppler velocity measurement: a**

2 **new approach and its application to the detection of leakage pathways in**

- 3 **the concrete face rockfill dam**
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10 **Key points:**

- 11 1.The methods we proposed are first used to detect the location of the leakage inlets and
- 12 leakage pathways in the concrete face rockfill dam.
- 13 2. Numerical simulation show the seepage field can be fitted with current field, and leakage
- 14 can be effectively detected in the current field.
- 15 3. The combination of two methods formed a novel leakage and pathways detection method
- 16 in the concrete face rockfill dam.

17 **Abstract**

18 The paper is to detect the leakage inlets, determine the leakage pathways through the 19 dam, and ensure that the amount of the leakage in the upstream and downstream is 20 consistent, and that there is no leakage around the concrete face rockfill dam. The injection 21 of a pseudo-random current in the water between two aluminum sheets A and B generates 22 a current field that can be measured in the water with sensitive current sensors. When the 23 current is channeled along leakage pathways, the flow-field fitting method can be used to 24 detect these inlets of the leakage pathways. We first review the background equations for 25 the seepage field and the current field in the flow-field fitting method, and we also use an 26 approach to calculate the discharge and ensure the consistency of the upstream and 27 downstream leakage based on the Doppler effect in physics. Moreover, to illustrate how 28 the flow-field fitting method works, we use numerical simulation method to verify the 29 feasibility of the flow-field fitting method. Lastly, we proceed with a case study for which 30 the flow-field fitting method and the acoustic Doppler flow velocity measurement are used 31 to identify and map potential leakage pathways bypassing upstream into the flow 32 measurement weir of the downstream. The approaches proposed in this paper successfully 33 detect three leakage areas and obtain the discharge. The results of detected in a case study 34 provide engineering geology information for optimizing the layout of grouting holes. 35 **Keywords:** Concrete face rockfill dam, Leakage pathways, flow-field fitting method, Doppler effect,

36 Numerical simulation

37 **Plain Language Summary**

38 The approaches proposed in this paper are first used to detect leakage inlets and the 39 leakage pathways in the concrete face rockfill dam. We use numerical simulation to verify 40 the feasibility of the flow-field fitting method, and based on the Doppler effect in physics, 41 we ensure that the amount of the leakage in the upstream and downstream is consistent, 42 and that there is no leakage around the concrete face rockfill dam. We use the approaches 43 we proposed successfully detect three leakage areas and obtain the discharge in the 44 concrete face rockfill dam. The results of detected in a case study provide engineering 45 geology information for optimizing the layout of grouting holes. The methods and results 46 can be used as a reference for other similar engineering leakage problems.

47 **1.Introduction**

48 A concrete face rockfill dam (CFRD) is a type of dam that is widely used in water 49 conservancy and hydropower projects around the world. The concrete slab supported and 50 stabilized by the rockfill material below is connected to the toe slab through peripheral 51 joints to form an impervious system. The leakage through a dam can lead to water loss, 52 and serious leakage can reduce the project benefits and even dam failure (e.g., Gutierrez et 53 al., 2003; Howard and McLane Iii, 1988; Ferdos et al., 2018). Therefore, we need to 54 conduct leakage detection on the dam after the dam is built or a regular basis. Geophysical 55 techniques are often used to detect the anomalous areas and leakage pathways. The 56 geophysical methods used depend on the type of problem to be studied. Generally, mainly 57 include: self-potential (SP) method, Ground Penetrating Radar (GPR) method, induced 58 polarization (IP) method, electrical resistivity imaging (ERI) and so on.

59 The SP method (e.g., Rizzo et al., 2004; Jardani et al., 2006a; Jardani et al., 2008; 60 Ahmed et al., 2020) is a suitable method for large scale investigation of earth dams, and it 61 can localize seeps and determine permeability. However, for complex dam, SP method is 62 difficult to quantify, and it is difficult to distinguish whether SP anomaly is the response 63 of the leakage site, which may lead to misjudgment. The GPR method (e.g., Xu et al., 2010; 64 Prinzio et al., 2012; Antoine et al., 2015) can identify internal erosion of dams' inner 65 structure. However, GPR method has a shallow depth of detection, and this limitation limits 66 the application of this method in dams. The IP method (e.g., Revil et al. 2015; Martínez-67 Moreno et al., 2018; Abdulsamad et al., 2019) can be used to estimate water content or 68 saturation values effectively, and it is sensitive to permeability but suffer from limitations 69 regarding its resolution. The ERI method is valuable for imaging the foundations of earth 70 dams and delineating leakage zones, but it is limited by its lack of resolution (e.g., Cho and 71 Yeom,2007; Dahlin, T et al., 2008; Bolève et al., 2012; Revil, A et al.,2012). Other methods, 72 temperature field detection method and fluorescent tracer tests (e.g., Unal et al., 2007; 73 Fargier et al., 2014; Battaglia et al., 2016), which are only used as an auxiliary method in 74 leakage detection, and are usually used in combination with the other geophysical methods 75 to identify the position of leakages. However, for CFRD, the GPR and ERI method are not

76 applicable, because the surface of the CFRD is concrete. In addition, the reservoir area has 77 strong winds and waves, the SP method is also not suitable.

78 In order to detect the leakage inlets, determine the leakage pathways through the dam, 79 and ensure that the amount of the leakage in the upstream and downstream is consistent, 80 the flow-field fitting method and acoustic Doppler velocity measurement are proposed. 81 The flow-field fitting method is a means to detect the leakage distribution characteristics 82 by fitting the seepage field with the current field. In hydraulics, the seepage field will be 83 generated around the leakage inlets in dams. It is hardly to detect directly fluctuations 84 generated by the seepage field with the existing techniques, so the existence of such weak 85 seepage field can only be measured indirectly. He et al. (1999) used the flow-field fitting 86 method to detect the piping of embankment during the flood season and successfully locate 87 the leakage location. Qianwei et al. (2017) and Meng et al. (2018) used the flow-field fitting 88 method to determine the location of the leakage inlets in the concrete dam's upstream face. 89 Moore et al. (2011), Meng et al. (2018) and Ahmed et al. (2019) numerically simulated 90 leakage pathways based on current field in the structure of the dam, and it showed that 91 leakage inlets can be detected in the upstream face successfully. We did a numerical 92 simulation of the CFRD based on the seepage field and the current field, it showed that the 93 flow-field fitting method can be used to effectively detect the leakage inlets in the CFRD 94 of the study area. We inject the pseudo-random current between two aluminum sheets A 95 and B in the water which generates a current field that can be measured with sensitive 96 current sensors.

97 The acoustic Doppler velocity measurement uses acoustic signals and the Doppler 98 shift to analyze flow velocity. Flow velocity is obtained by measuring Doppler pulse shifts 99 back-scattered by particles located in water cells allocated along the instrument's 100 measurement range (Marc et al., 2020). This technology has been extensively used for flow 101 velocity and discharge analysis in natural rivers and streams (e.g., Gunawan et al., 2010; 102 Boldt and Oberg, 2015), oceans (Münchow et al., 1995) and man-made channels (e.g., 103 Oberg et al., 2007; Bahreinimotlagh et al. 2016; Klema et al. 2020). It showed that the 104 acoustic Doppler velocity measurement has an effective way in measuring flow velocity 105 and discharge. However, although the effect of the methods was demonstrated, a little 106 attention has been paid to the flow velocity and the discharge in the anomalous leakage

107 area of the CFRD. we used it for fixed-depth measurement of the flow velocity in the 108 anomalous area, and obtained the discharge to ensure the consistency of the upstream and 109 downstream leakage, and provide support for the detection results of the flow-field fitting 110 method.

111 The combination of two approaches formed a novel detection method, and the 112 approaches proposed in this paper are used in CFRD for the first time. It can find out the 113 locations of the leakage area and the discharge quickly, and it can also access to the roughly 114 information of the entire leakage pathways in CFRD. The feasibility of those approaches 115 is verified in case study of the engineering practice.

116 **2. Methods**

117 **2.1 Theory of the flow-field fitting method**

118 The flow-field fitting method is a new method to find the leakage locations in CFRD, 119 and a means to detect the leakage distribution characteristics by fitting the seepage field 120 with the current field. In hydraulics, the weak seepage field will be generated around the 121 leakage inlets in CFRD. It is almost impossible to measure directly fluctuations generated 122 by the seepage field with the existing instrument, so the existence of such weak seepage 123 field can only be measured indirectly. The flow of fluid is divided into laminar flow and 124 turbulent flow in porous medium (Bear., 2013). The leakage of the CFRD can be regarded 125 as laminar flow, and the Reynolds number is not more than 1 to 10, the motion of water 126 conforms to Darcy's law (e.g., Reynolds., 1882; Bolève et al.,2007):

(1) $u = k \cdot H = -k \cdot \nabla \varphi$

128 where u denotes the flow velocity, k denotes the permeability coefficient, H denotes 129 hydraulic gradient, and φ denotes the velocity potential, and "-" indicates the direction 130 of the velocity pointing to the potential, and ∇ is the Hamilton operator.

131 In a Cartesian coordinate system, the three components along the axis are u_x , u_y and 132 u_z . Water is an incompressible fluid that satisfies continuity equations: Flow continuity 133 equation can be written as:

$$
\nabla \cdot u = 0 \tag{2}
$$

135 Differential governing equation can be written as:

 $\nabla^2 \varphi = 0$ (3)

137 where ∇^2 denotes the Laplacian.

138 On the boundary between a fluid and other object, for impermeable surface, water

139 cannot flow through the boundary, that is:

$$
\frac{\partial \varphi}{\partial n} = 0 \tag{4}
$$

141 and for permeable surface, according to the continuity equation, the normal components 142 of the velocity on the boundary should be equal.

$$
143\,
$$

143 $\frac{\partial \varphi_1}{\partial n} = \frac{\partial \varphi_2}{\partial n}$ (5)

144 where n denotes the normal components of the velocity on the boundary, and the subscripts 145 1 and 2 denote both sides of the boundary.

146 According to the tutorial (Loke., 2004), for the anomalous point or area, the current 147 vector points to that point or area, and the current density is inversely proportional to the 148 square of the anomalous point or area. For point power supplies, the direction of the current 149 density is to the point source, and the current density is inversely proportional to the square 150 of the distance of the point source. We used the MATLAB software to analyze the 151 simulation of the density curve in current field. It is obvious that the distribution of the 152 density curves is different between Fig.1(a) and Fig.1(b). In the absence of seepage, 153 leakage pathway is similar to a low resistivity object in a homogeneous half-space and 154 current vector points to the inlet of the leakage pathways.

156 **Fig. 1** Comparison of density curve in current field between leakage and no leakage (A and B denote 157 the two current electrodes)

- 158 The current field satisfies Ohms law, that is:
- 159 $i = \sigma \cdot E = -\sigma \cdot \nabla U$ (6)

160 where j denotes the current density, σ denotes the conductivity, E denotes the electric 161 gradient, and U denotes the electric potential.

180 **Table.1** Similarities in mathematical physics between seepage field and current field

Seepage field	Current field				
Velocity potential	Electric potential				
φ	– U				
H	Electric gradient				
Hydraulic gradient	E				
Flow velocity u	Current density $\mathbf{1}$				
Permeability coefficient	Conductivity				
k	σ				
Normal direction	Normal direction				
$\mathbf n$	$\mathbf n$				
Flow continuity equation $\nabla \cdot u = 0$	Current density continuity equation ∇ j =0				
Differential governing equation $\nabla^2 \varphi = 0$	Differential governing equation $\nabla^2 U = 0$				
Impermeable surface	Insulated surface				
$\partial \varphi / \partial n = 0$	$\partial U/\partial n=0$				
Permeable surface	Conductive surface				
$\varphi_{n1} = \varphi_{n2}$	$U_{n1} = U_{n2}$				
$\partial \varphi_1 / \partial n = \partial \varphi_2 / \partial n$	$\partial U_1/\partial n = \partial U_2/\partial n$				
Darcy law $u=k \cdot H = -k \cdot \nabla \varphi$	Ohms law $i = \sigma \cdot E = -\sigma \cdot \nabla U$				

181 According to the above method, we can place an aluminum sheet on the upstream and 182 downstream of the CFRD, respectively, and inject a pseudo-random current between two 183 aluminum sheets A and B, and measure the current density distribution in the reservoir area.

184 **2.2 Acoustic Doppler velocity measurement**

185 The acoustic Doppler velocity measurement is a common method used for the 186 measurement of velocity in natural and man-made waterways. The transducer transmits 187 acoustic pulses at a fixed frequency from transducer through the water column and using 188 the Doppler shift of the reflected acoustic energy in each beam computes water velocity 189 profile. Because the water has some suspended particles, a small amount of the sound 190 energy is reflected back (Doppler shift), most of the energy goes forward. Reflected back 191 acoustic wave is received by transducer, and after the reflection signals of different distance 192 can be analyzed (Gordon., 1989). Through tiny differences in the frequency, the velocity 193 of water flow can be calculated used the Doppler shift equation.

194

195 **Fig. 2** Layout of Doppler effect principle

196 Fig.2 illustrates the principle of Doppler shift. T denotes the acoustic source 197 (transmitting transducer), P denotes the observation target (suspended particles), TT' 198 denotes the motion vector of the acoustic source, and, **PP'** denotes the motion vector of the 199 observation target. The vector **TP** from the acoustic source T to the observation target P changes at any time. Supposing the positions of the sound source at time $t = t_0$ and $t = t_0$ 201 $t_0 + dt$ are T and T' respectively, and the phases are φ and φ' respectively, where the 202 phase increment can be written as:

$$
d\varphi = \varphi' - \varphi = 2\pi f_t dt \qquad (11)
$$

204 and P reaches P ', the phase increment can be written as:

$$
d\varphi = 2\pi f_p dt' \tag{12}
$$

206 That is:

$$
2\pi f_t dt = 2\pi f_p dt' \tag{13}
$$

208 Rewriting Eq. (13) as:

$$
\frac{dt}{dt'} = \frac{f_p}{f_t} \tag{14}
$$

210 The time is $t = t_0 + \frac{TP}{c}$, when the phase ψ propagates from the acoustic source T to 211 the position P of the observation target. The time is $t = t_0 + dt + \frac{T'P'}{c}$, when the phase 212 $\varphi + d\varphi$ propagates from the acoustic source T' to the position P' of the observation target, 213 and the difference between the two is the propagation time from P to P' can be written as:

214
$$
dt' = dt + \frac{\mathbf{T}'\mathbf{P}'}{c} - \frac{\mathbf{TP}}{c} = dt - \frac{\mathbf{TT}' + \mathbf{PP}'}{c} = dt - \frac{v_t dt + v_p dt'}{c}
$$
 (15)

215 After sorting, we get:

216
$$
\frac{dt}{dt'} = \frac{(c-v_p)}{(c+v_t)}
$$
 (16)

217 That is:

218
$$
\frac{f_p}{f_t} = \frac{(c - v_p)}{(c + v_t)}
$$
 (17)

219 Rewriting Eq. (17) as:

$$
f_t = \frac{c + v_t}{c - v_p} f_p \tag{18}
$$

221 For acoustic Doppler velocity measurement, the transceiver(observation target) and 222 transducer are inter-related. The transducer is first used as the acoustic source, and the 223 water body is the observation target, so the acoustic wave frequency received by the water 224 body can be written as:

225 $f' = \frac{c + v_p}{c - v_t} f_t$ (19)

226 Then the water body acts as the acoustic source, and the transducer acts as the 227 observation target, so the frequency of the sound wave received by the transducer can be 228 written as:

229 $f_p = \frac{c + v_t}{c - v_p} f'$ (20)

230 Then substituting Eq. (19) into Eq. (20), solving for f_p .

231 Finally, the Eq. (21) is as follows:

232
$$
f_p = \frac{(c+v_t)(c+v_p)}{(c-v_p)(c-v_t)} f_t
$$
 (21)

233 When the transmitting transducer measured this time remained stationary during the 234 measurement, then substituting $v_t = 0$ into the Eq. (21):

235
$$
f_p = \frac{(c+v_p)}{(c-v_p)} f_t
$$
 (22)

$$
v_p = \frac{f_p - f_t}{f_p + f_t} c \tag{23}
$$

237 Defining $f_a = f_p - f_t$, Eq. (23) can be rewritten as:

$$
v_p = \frac{f_d}{2f_t}c\tag{24}
$$

239 where v_p denotes the radial velocity of water relative to the transducer, f_d denotes the 240 Doppler shift, f_t denotes the frequency of the transmitting transducer, and c denotes the 241 velocity of sound in the water.

242 We used the acoustic Doppler current profiler (ADCP) for depth measurement of the 243 flow velocity in the center of the abnormal area based on Doppler effect. The data collected 244 by ADCP is substituted into equation 24, and obtained the flow velocity.

245 **3. Case study**

246 **3.1 Study area**

247 Project area is located at Luquan County, Yunnan Province, China. The upstream is 248 the Lujichang hydropower station, and the downstream is the Baihetan hydropower station 249 on the main stream of the Jinsha River. Project area is 150km away from Luquan County 250 and 220km away from Kunming Highway (Fig.3). The project area is concrete face rockfill 251 dam, and the highest height and length of the dam are 100m and 430m, respectively. Fig.4 252 shows typical profile of CFRD. The total reservoir capacity is about 185 million $m³$. After 253 the reservoir was impounded, leakage was found around the right abutment and observed 254 in the flow measurement weir of the downstream, as shown in Fig.3. The color of the 255 leakage water was turbid, and after days later became clear. The discharge was stable in 256 the range of 120L/s~140L/s. The aim of this case study is to investigate the leakage areas

257 in the reservoir area of the upstream, estimate the discharge in the leakage areas, ensure 258 that there is no other leakage around the dam and provide technical supports and solutions 259 about the layout of grouting holes to prevent or repair leakage.

261 **Fig. 3** Photographs showing geographical location of the studied dam and the leakage area

263 **Fig. 4** Typical profile of CFRD (unit of water level and elevation: m). Normal water level is 264 968.00m, downstream flow measurement weir level is 883.90m, crest elevation is 1006.00m.

265 **3.2 Numerical simulation about leakage of the CFRD**

266 The goal of this section is to study whether it is reasonable to fit the seepage field with 267 the current field in the CFRD. The main hydraulic structures of the CFRD were numerically 268 simulated according to the original layout of the CFRD body. A finite element model was 269 established to analyze the simulation of the seepage field. In hydraulics, the weak seepage 270 field will be generated around the leakage inlets in dams. The existence of such weak 271 seepage field can be observed directly based on ANSYS software. We use the commercial 272 software ANSYS Fluent 2020 R2, which is a partial differential equation solver.

273 Three-dimensional size of CFRD is built as (Fig.5a): a dam's length is 85mm, width 274 is 60mm, height is 50mm, and the dam model is symmetric about the Y axis. The reservoir 275 water is 25mm in depth, and its resistivity is 50Ω ·m. Top face of the reservoir water is 276 50mm in length, 52mm in width, and bottom face is 50mm in length, 40mm in width. The 277 leakage pathway is a cylinder with a diameter of 1mm and a length of 15mm, and the inlet 278 in the upstream face of dam, is (0mm,50mm,15mm), and the outlet in the downstream of 279 dam, is (0mm,65mm,15mm). The resistivity of the leakage pathway is 20Ω ·m.

280 Unstructured elements are used to perform the finite element mesh. The finite element 281 mesh of the water body and leakage pathway are represented in Fig.5b. Volume statistics 282 is as follows: minimum volume is 5.57×10^{-5} mm³, maximum volume is 2.05 mm³, and total 283 volume is 5.96×10^4 mm³. The direction of gravity is the Z direction, and the value is - 284 9.81m/s². Material is water-liquid, and the value of the viscous resistance and the inertial 285 resistance is the default. The porosity of leakage pathway is 0.2. For the problem of the 286 dam leakage, atmospheric pressure boundary condition was applied to the boundaries. 287 Coupled solution method was used to steady-state condition. After setting the monitoring 288 parameters, just run the calculation. The velocity distribution at or near the inlets of leakage 289 is obtained by numerical simulation.

291 **Fig.5** Three-dimensional model of CFRD and reservoir. (a) The model of dam. (b) The finite

292 element mesh of reservoir water and leakage pathway

293 As previously described, Darcy's law has its limits, the effects of the Reynolds number 294 need be taken into account. When the Reynolds number is not more than 1 to 10, the motion 295 of water conforms to Darcy's law. Fig.6 shows the range of Reynolds number, the 296 maximum is nearly 5, therefore, it is reasonable to use current field method to fit the 297 seepage field.

298

299 **Fig.6** Reynolds number diagram in YZ plane

300 Fig.7 shows three slices velocity diagrams at Y=15mm, 35mm, 49mm on the ZX plane, 301 respectively. It is not obvious in linear form, so the velocity contour color is shown in 302 logarithmic form. The distribution of the flow velocity can be observed, and it is obvious 303 that: the closer to the leakage inlet, the greater the velocity value is. Fig.8 shows that in 304 the absence of seepage, the seepage field converts to anomalous seepage field caused by 305 leakage appear. The important feature of the abnormal seepage field is that the water flow 306 velocity vector points to the leakage inlets.

308 **Fig.7** Slice velocity diagram in ZX plane (Y=15mm, 35mm, 49mm)

311 **Fig.8** Slice velocity diagram. (a) is in YZ plane (X=0mm); (b) is in XY plane (Z=15mm) 312 Fig.9(a) shows the location of three monitoring lines. Fig.9(b), (c) and (d) show a 313 comparison between flow velocity and different axes. In Fig.9(b), the red monitoring line 314 of X=0mm, Z=15mm passes from Y=0mm to Y=60mm (leakage inlet is X=0mm,Y=50mm, 315 Z=15mm), shows that with the closer to inlet, the value of flow velocity is getting bigger, 316 and velocity is biggest in the inlet. The distribution of blue monitoring line of Y=49mm, 317 Z=15mm appears symmetrical in X=0mm, just as Fig.9c as shown, and velocity emerge 318 extremums at X=0mm. In Fig.9d, the green monitoring line of X=0mm, Y=49mm passes 319 from Z=10mm to Z=35mm (leakage inlet is X=0mm,Y=50mm, Z=15mm), the trend of 320 the green monitoring line is similar to Fig.9(c), but the maximum value is close to twice 321 the blue monitoring line.

322 By contrasting and analyzing three survey lines in Fig.9, the value of velocity in Y-323 component and Z-component is nearly twice the X-component. Furthermore, the change 324 of velocity around the leakage inlet is more obvious in the Z-component comparing to the 325 Y-component. The result identifies the main component of the velocity Z responsible for 326 the flow velocity signature. Therefore, the leakage location and probable inlets can easily 327 obtain through the Z-component.

338 To get the distribution of the current density, the current is applied in the faraway 339 upstream section, and the injection electric current is set as 2A in the simulation between 340 two electrodes A and B separated by a distance of 60 mm (Fig.10a). The distribution of the 341 current density at or near the inlets of leakage is obtained by numerical simulation. 342 Fig.10(b), (c) and (d) show a comparison between current density and different axes (X-343 component, Y-component, Z-component). The distribution of three monitoring lines is 344 the same as the distribution of the three lines in Fig.9. Fig.10(b) shows that with the closer 345 to inlet, the value of current density is getting bigger. Fig.10(c) and Fig.10d show that the 346 current density at the inlet of the leakage has a positive maximum and a negative minimum. 347 By contrasting and analyzing the slope of the current density of the three survey lines at 348 the inlet of the leakage, the rate of change of the X and Z components of the current density 349 is larger than Y-component, moreover, the extremums at Z-component is nearly twice the 350 X-component. The result identifies the main component of the current density J_z 351 responsible for the current signature. Therefore, the leakage location and probable inlets 352 can also easily and quickly obtain through the Z-component of the current density.

353 **3.3 Leakage detection based on the flow-field fitting method**

354 The field work took approximately one day to complete. The detection method is 355 shown in Fig. 11. To best characterize the leakage pathways, the energizing aluminum 356 sheets A and B must be strategically placed upstream and downstream. The upstream 357 aluminum sheet is far away from the water outlet to ensure the current field of measurement 358 area not affected by each other. We regard the distance between aluminum sheet A and 359 aluminum sheet B to be as far as possible, and no less than five times the length of the 360 overall detecting area, just as shown in Fig.11. We proposed to use aluminum sheets instead 361 of electrodes. Compared with electrodes, aluminum sheets can better generate and receive 362 current signals in the long-distance transmission. According to the above-mentioned 363 physical facts and the result of numerical simulation, the probe 's Z component was used 364 to detect changes in current density in the reservoir area.

365 An DC electric current with a pseudo-random signal was applied to the paired (A, B) 366 aluminum sheets. The electric current flowing between the aluminum sheets (A, B) 367 generates a current field. We used the transmitter to supply pseudorandom signal to the 368 two aluminum sheets linked to cable. Lastly, we put the probe linked to the receiver into 369 the water, and by controlling the travel route of the boat, we use music monitoring and 370 meter display to find the seepage area, and we use a differential GPS for positioning at a 371 certain distance. The detected current density value is converted to voltage value, which is 372 reflected in the way of sound. The greater the voltage, the louder the sound, and results 373 indicated the possible presence of leakage.

374

389

377 We can determine the leakage locations by analyzing the distribution of the voltage 378 section in the horizontal plane. Measured values have varied degrees of response at the site 379 of leakage. The background values of potential difference are about 0-30 mV (Fig.12), 380 therefore we took the values between 0-30 mV as the normal areas, and regard values 381 higher than it as anomalous areas. Thus, by the analysis of the detection data of each survey 382 line and measuring point (with a differential GPS), three anomalous areas were found on 383 the right bank of the reservoir area (the detected locations were significantly higher than 384 the background value of the nearby area).

385 The chromatogram of the flow-field fitting method was shown in Fig.12. The three 386 anomalous areas were presumed to be leakage inlets, and the others indicated no leakage. 387 – Among them, the area of No.1 anomalous area was about $2000m^2$, the area of No.2 was 388 about $80m^2$, and No.3 was about $120m^2$.

390 **Fig. 12** Chromatogram of potential difference about reservoir area ("×" denotes a differential GPS 391 measuring point)

392 **3.4 Velocity analysis based on the acoustic doppler effect**

393 The acoustic doppler velocity profiler (ADCP) has been extensively used for velocity 394 analysis in natural rivers and streams. ADCP was used to measure the velocity near the 395 center of the No.1 to No.3 anomalous area in the reservoir area, and the results of radial 396 velocity distribution varying with depth were obtained. We used it for fixed-depth 397 measurement of the flow velocity at the center of the anomalous area (see Fig.13).

398 According to the actual depth of the leakage area in the dam, 600kHz working 399 frequency of the transducer was used. Working technical specifications of the acoustic 400 Doppler velocity profiler in China is shown in Table.2.

401 **Table 2** Working parameter list of the ADCP

Frequency of operation /kHz	38	75	150	300	600	1200
Initiative measured depth /m	16.0	80	40	2.0		
Maximal measured depth /m	700	350	180	100	50	20

402 The transducer transmits acoustic pulses at a fixed frequency from transducer through 403 the water column and using the Doppler shift of the reflected acoustic energy in each beam 404 computes water velocity profile. the velocity can be calculated used the Doppler shift 405 equation 24.

407 **Fig. 13** Simple diagram showing the arrangement of the flow velocity measurement in leakage area 408 According to the curves of depth-flow velocity (Fig.14), and there was a water flow 409 of 0.012~0.093m/s in the No.1 anomalous area, there was a water flow with a velocity of 410 0.021~0.072m/s in the No.2 anomalous area, and a water flow with a velocity of

411 0.014~0.073m/s in the No.3 anomalous area. See Fig.14 for details. Taking into account 412 the wind and waves on the day of the measurement, the measured flow velocity is within 413 the depth range of 5m-30m. The average flow velocity of the three abnormal areas were 414 0.064m/s, 0.052m/s, and 0.054m/s, respectively. In addition, the estimated area of No.1 415 anomalous area was 2000m^2 , the area of No.2 was 80m^2 , and No.3 was 120m^2 , respectively. 416 We used the index velocity method (e.g., Le Coz et al., 2008; Levesque et al., 2012) 417 to predict the discharge from the ADCP, and based on previous engineering experience 418 (e.g., Nord et al., 2014; Kästner et al., 2018), the discharge in the No. 1 to No. 3 abnormal 419 areas was estimated to be 95 L/s, 15 L/s and 20 L/s, respectively. The calculated total 420 discharge (130L/s) was in agreement with the flow measurement weir of the downstream 421 (120L/s~140L/s).

423 **Fig.14** Curves of Depth-Flow velocity

422

425 **Fig. 15** Detection results in investigation area

426 **3.5 Final result**

427 The numerical simulation results showed that the seepage field can be fitted with the 428 current field, and the leakage location and probable inlets can easily and quickly obtain 429 through the Z-component of the current field. According to the actual situation in the study 430 area, and from the profile of results provided by the flow-field fitting method, it is capable 431 to identify the leakage locations and the scale of leakage area. In addition, acoustic Doppler 432 velocity measurement determines the flow velocity in the upstream, and roughly calculates 433 the discharge, and it is basically the same as the discharge measured in the measuring weir 434 of the downstream. As shown in Fig.12, three anomalous areas were detected, and 435 comparing the calculated leakage with the flow measurement weir of the downstream (see 436 Fig.14), it shows that there are no other leakage areas around the dam. Based on the on-site 437 investigation results (see Fig.15), there are roughly three leakage pathways and no other 438 leakage pathways in the reservoir area. This type of information can be used to take 439 effective decisions concerning how to further monitor and remediate ground water 440 bypassing upstream into the flow measurement weir of the downstream.

441 **4. Discussions**

442 As shown in the previous sections, the flow-field fitting method and acoustic Doppler 443 velocity measurement can be used to determine leakage inlets and conductive pathways, 444 which can be interpreted, under specific circumstances, to preferential leakage pathways 445 of ground water. These leakage inlets can be hardly detected using other techniques. The 446 correspondence between electrical and hydraulic flow is only apparent and works only in 447 some cases. In addition, electrical resistivity imaging is limited by its lack of resolution 448 and the inability to place electrodes on the concrete surface. Induced polarization is 449 sensitive to permeability but suffer from the same limitations than electrical resistivity 450 tomography regarding its resolution. The self-potential is sensitive to the mineralization of 451 the pore water and highly mineralized ground water implies low self-potential signals.

452 Another point worth to be discussed is the fact that the flow-field fitting method is 453 widely used in china, but it is rarely mentioned abroad. In addition, one may wonder about 454 the validity of the fitting method used in this paper while we use it to detect leakage inlets 455 in the CFRD. In this paper, we have neglected the case where the Reynolds number is 456 greater than 10. We will need however to check in future publications if this assumption is 457 always valid, especially for the current field distribution in the non-Darcy. The use of three 458 component current density sensors should be considered in future research, and it should 459 be able to improve the accuracy of detection.

460 Our methods can be used to access to the roughly information of the entire leakage 461 pathways, and this technique works well when we know where the leakage pathways start 462 or end, and it has the advantage of taking measurements in the water, without requiring 463 contact with the surface of the CFRD. This is an interesting research topic in itself.

464 **5. Conclusions**

465 The flow-field fitting method and the acoustic Doppler velocity measurement appear 466 as a novel method for leakage investigation of CFRD compared with conventional 467 geophysical methods. In our case study, the two methods showed an enormous potential 468 for large-scale leakage detection of CFRD. Three leakage pathways have been found, and 469 there is no leakage around the dam. It is the key point of dam foundation reinforcement

- 470 project to determine the best position of grouting borehole according to the results. By
- 471 optimizing the layout of grouting holes through geophysical investigation, the number of
- 472 drilling holes can be reduced and the engineering cost can be saved. The flow-field fitting
- 473 method can also be combined with other geophysical methods to detect leakage pathways
- 474 in CFRD. When the CFRD is at low water level, appropriate anti-seepage materials and
- 475 seepage grouting can be used to repair or block the leakage area.

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