

Modeling snow saltation: the effect of grain size and interparticle cohesion

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Abstract

The surface of the Earth is snow-covered at least seasonally over large areas. This snow surface is highly dynamic, particularly under the influence of strong winds. The motion of snow particles driven by the wind not only changes the snow cover but has important consequences for the atmosphere in that it adds mass and moisture and extracts heat. Large scale meteorological and climatological models neglect these surface dynamics or produce conflicting results from too simplified process representation. With recent progress in the detailed understanding of the saltation process, in particular with respect to sand saltation, and the advancement of numerical models, we can systematically investigate the influence of snow properties on saltation. This contribution uses a Large Eddy Simulation (LES) model with full surface particle dynamics to investigate how snow cohesion and size distribution influence saltation dynamics and in particular the total mass flux. The model reproduces some known characteristics of the saltation system such as a focus point or a constant near surface particle speed. An interesting result is that cohesion and grain size heterogeneity can increase the overall saltation mass flux at high friction velocities. Moreover, some simplified models agree reasonably well with the simulations for given bed characteristics, while others clearly do not. These results are valid for continuous saltation while intermittent saltation, which often occurs in nature, needs further investigation. In order to successfully parameterize saltation in large scale models, progress must be made in correctly representing snow surface properties in these models, in particular cohesion.

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The surface of the Earth is snow-covered at least seasonally over large areas. This snow surface is highly dynamic, particularly under the influence of strong winds. The motion of snow particles driven by the wind not only changes the snow cover but has important consequences for the atmosphere in that it adds mass and moisture and extracts heat. Large scale meteorological and climatological models neglect these surface dynamics or produce conflicting results from too simplified process representation. With recent progress in the detailed understanding of the saltation process, in particular with respect to sand saltation, and the advancement of numerical models, we can systematically investigate the influence of snow properties on saltation. This contribution uses a Large Eddy Simulation (LES) model with full surface particle dynamics to investigate how snow cohesion and size distribution influence saltation dynamics and in particular the total mass flux. The model reproduces some known characteristics of the saltation system such as a focus point or a constant near surface particle speed. An interesting result is that cohesion and grain size heterogeneity can increase the overall saltation mass flux at high friction velocities. Moreover, some simplified models agree reasonably well with the simulations for given bed characteristics, while others clearly do not. These results are valid for continuous saltation while intermittent saltation, which often occurs in nature, needs further investigation. In order to successfully parameterize saltation in large scale models, progress must be made in correctly representing snow surface properties in these models, in particular cohesion.

1 Introduction

Wind erosion of snow covered surfaces is frequently observed in alpine and polar regions. Snow transport leads to the formation of bedforms, intensifies snow sublimation and modifies the microstructure of surface snow layers. Moreover, the interaction between the wind field and the complex topography creates regions of enhanced snow erosion and deposition, which greatly contributes to snow height heterogeneity. In alpine regions, these processes are of great importance for water management and avalanche risk assessment (Lehning et al., 2008). In Antarctica, snow transport is enhanced by the katabatic winds, dominating large areas from the inner plateau to the coast, and clouds of blowing snow particles with a height of hundreds of meters can be observed (Palm et al., 2017).

The aeolian transport of snow occurs at different heights above the ground. The terms drifting snow and blowing snow are commonly used to indicate, respectively, the movement of snow particles close to the surface (up to approximately 2 m height) and the movement of smaller snow particles transported at high elevations. In the first 10 cm above the surface, snow particles are mainly transported in saltation (Bagnold, 1941): they follow short ballistic trajectories and generally hit the ground with enough kinetic energy to hop again (rebound) or eject other particles on the bed (splash). Above the saltation layer, given by the ensemble of saltating particles, smaller grains are transported in suspension: they mainly follow the wind flow and travel great distances before being deposited on the ground or sublimate.

At low wind speeds, the mass flux in saltation is greater than the mass flux of suspended particles. At high wind speeds, snow transport in suspension becomes relevant and is currently simulated in mesoscale models by advection-diffusion equations (Lehning et al., 2008; Lenaerts et al., 2012; Vionnet et al., 2014; Amory et al., 2015). Particle concentration in the saltation layer defines the lower boundary condition for snow suspension. The saltation models commonly used in these mesoscale models rely on simple analytical equations based on the assumption of steady state saltation, that is, an equilibrium state between the grains in motion and the wind field (Pomeroy & Gray, 1990; Doorschot & Lehning, 2002; Sørensen, 2004). However, the parameters used in the referred ana-

66 lytical saltation models are highly uncertain and do not always reflect the properties of
67 the snow type. This limits the accuracy of the mass flux of particles in suspension, which
68 is either underestimated (Amory et al., 2015) or overestimated (Vionnet et al., 2014).
69 As a consequence, uncertainties arise in the rate of blowing snow sublimation and the
70 consequent increase in the atmospheric moisture content. For instance, snow sublima-
71 tion is the main mass-depleting process in some regions of the Antarctic ice sheet, but
72 the contribution of blowing snow sublimation is still largely unknown (Van Wessem et
73 al., 2018; Agosta et al., 2019). Hence, even though snow saltation is usually a sub-grid
74 process in mesoscale models, its correct modeling greatly influences the mass and energy
75 balances at a larger scale.

76 The complexity of modeling snow saltation is related to the turbulent flow features
77 and the snow particle characteristics. In contrast with sand beds, snow beds change con-
78 tinuously: soon after deposition, snow grains form interparticle ice bonds between each
79 other; the characteristics of a snow bed (for instance, particle size distribution, interpar-
80 ticle bonds and grain shape) evolve with time due to metamorphic processes; and snow
81 particle sizes change during saltation events due to fragmentation (Comola et al., 2017)
82 and sublimation (Sharma et al., 2018).

83 Detailed models of saltation are ideal to simulate both the flow and snow bed par-
84 ticularities. By explicitly solving the turbulent flow, particle trajectories and the surface
85 processes, these models can be used to improve our understanding of particle-wind in-
86 teraction and to evaluate some of the assumptions made in simple saltation models. In
87 the last two decades, Reynolds-Averaged Navier-Stokes (RANS) and Large Eddy Sim-
88 ulation (LES) flow solver techniques were used, coupled with Lagrangian models for par-
89 ticle dynamics (e.g., Shao & Li, 1999; Almeida et al., 2006; Dupont et al., 2013; Groot Zwaafink
90 et al., 2014; Okaze et al., 2018). Moreover, splash laws based on conservation principles
91 were also proposed and used to describe steady state saltation (Kok & Renno, 2009; Lämmel
92 et al., 2017; Comola & Lehning, 2017).

93 Recent theoretical and numerical advances (Comola & Lehning, 2017; Comola, Gaume,
94 et al., 2019) have shed light into the role played by granular bed properties, such as grain
95 size distribution and interparticle cohesion, in granular splash mechanisms. In addition,
96 field measurements of sand saltation (Martin & Kok, 2019) have questioned the idea of
97 modeling each grain size bin independently when assessing saltation onset over mixed-
98 sized beds. However, the effect of snow surface properties on saltation development and
99 scaling laws is still largely unknown. For example, there are no estimates on how par-
100 ticle size distribution and interparticle cohesion influence particle speed and surface fric-
101 tion velocity during saltation. Consequently, the effect of surface properties on the in-
102 tegrated mass flux is still unclear.

103 In this work, we use an LES solver coupled with a Lagrangian model to compute
104 particle-wind interactions (Comola, 2017) and the splash functions proposed by Comola
105 and Lehning (2017) to describe particle-bed interactions. The capabilities of this model
106 to simulate steady state saltation are firstly assessed. The vertical profiles of wind speed,
107 saltation mass flux, concentration and particle velocity are analyzed, as well as the vari-
108 ation of the integrated mass flux with the friction velocity. Then, a detailed study on
109 the effect of grain size and interparticle cohesion on the vertical profiles, integrated mass
110 flux and surface friction velocity is performed. To this end, the properties of the gran-
111 ular bed are varied in a systematic way in a suite of simulations, which cover a range of
112 wind velocities. The results are compared to existing saltation models and to the con-
113 clusions drawn from the latest wind tunnel and field experiments.

114 This article shows the potential of LES-based models coupled with state-of-the-art
115 splash functions to simulate steady state saltation and to improve our understanding of
116 saltation dynamics. Moreover, it sheds light onto the relative importance of grain size
117 and interparticle cohesion for snow saltation characteristics. The work presented ulti-

118 mately helps progressing towards the development of new saltation mass flux parame-
 119 terizations, which would take into account the influence of surface snow properties.

120 The model details are presented in section 2. In section 3, the numerical setup used
 121 for the simulations is presented. The results are shown and discussed in section 4 and
 122 the main conclusions are summarized in section 5.

123 2 Flow and particle dynamics

124 2.1 Flow solver

125 The tri-dimensional wind field is solved with the Large Eddy Simulation (LES) tech-
 126 nique. Turbulence features larger than the grid size are resolved by the filtered conti-
 127 nuity and Navier-Stokes equations, while the effect of smaller eddies is parameterized by
 128 a sub-grid scale (SGS) model. The LES model used along with the particles solver is named
 129 EPFL-LES. It was developed at the Ecole Polytechnique Fédérale de Lausanne and is
 130 based on the work of Albertson and Parlange (1999).

131 The LES code targets atmospheric boundary layer (ABL) flows, assumed incom-
 132 pressible and driven by a constant streamwise pressure gradient, $\partial p_\infty/\partial x$:

$$\frac{\partial p_\infty}{\partial x} = -\rho_f \frac{u_*^2}{L_z} \quad (1)$$

133 where ρ_f is the fluid density, L_z is the domain height and u_* is the desired friction ve-
 134 locity.

135 Horizontal gradients are computed with a Fourier-based pseudo-spectral approach
 136 and vertical gradients are calculated using second-order finite differences. The time deriva-
 137 tives are computed with the second-order Adams-Bashforth time advancement scheme
 138 (Canuto et al., 1988). In the present code version, the closure SGS model is given by the
 139 scale-dependent Lagrangian dynamic model (LASD) as proposed by Bou-Zeid et al. (2005).
 140 This model exhibits better dissipation characteristics than the classic Smagorinsky and
 141 the scale-invariant dynamic models.

142 Periodic boundary conditions are imposed in the vertical walls of the computational
 143 domain, as required when applying Fourier transforms, allowing for the development of
 144 a fully turbulent flow at both the inlet and outlet sections. At the top boundary, imper-
 145 meability and zero vertical gradients are assumed. At the bottom boundary, the imper-
 146 meability condition is imposed and the wall shear stress is given by the logarithmic law
 147 of the wall. The use of wall functions avoids highly discretized meshes near the surface
 148 as well as smaller time steps to guarantee numerical stability.

149 The present LES code has been used in multiple ABL studies concerning land-atmosphere
 150 interaction over complex terrains, wind-farms and urban canopy (Albertson & Parlange,
 151 1999; Bou-Zeid et al., 2005; Diebold et al., 2013; Giometto et al., 2016, 2017; Sharma
 152 et al., 2017). A detailed description of the model can be found in these works.

153 2.2 Particle dynamics

154 Particle motion is computed in a Lagrangian framework. The coupling with the
 155 LES solver was developed by Comola (2017), following the work of Groot Zwaafink et
 156 al. (2014). The model has been further developed with the contributions of Comola and
 157 Lehning (2017), Sharma et al. (2018) and Comola, Giometto, et al. (2019).

158 Particle inertia, gravity and aerodynamic drag are related by Newton's second law.
 159 Aerodynamic drag, D_i , is given by $D_i = -1/2 C_D \rho_f A_f |U_r| U_{r,i}$, where $i = 1, 2, 3$ de-

160 notes the x (streamwise), y (crosswise) and z (vertical) directions in the Cartesian co-
 161 ordinate system. C_D is the drag coefficient, A_f is the particle frontal area, $U_{r,i}$ the par-
 162 ticle velocity relative to the local flow and $|U_r|$ its absolute value (henceforth referred
 163 to as U_r). In the current model, saltating particles are assumed spherical, with a frontal
 164 area $A_f = \pi d^2/4$, where d is the particle diameter. The drag coefficient is estimated us-
 165 ing the expression proposed by Schiller and Nauman (Clift et al., 1978) as a function of
 166 the particle Reynolds number, $Re_d = U_r d/\nu_f$, where ν_f is the fluid kinematic viscosity:

$$C_D = \frac{24}{Re_d} (1 + 0.15 Re_d^{0.687}). \quad (2)$$

167 The equation for particle trajectory yields:

$$du_{p,i} = \left[\frac{3}{4} \frac{\rho_f}{\rho_p} \frac{C_D}{d} U_r (u_i - u_{p,i}) - g \delta_{i3} \right] dt \quad (3)$$

168 where $u_{p,i}$ is the particle velocity, u_i is the instantaneous flow velocity resolved by the
 169 LES solver, ρ_p is the particle density, g is the acceleration of gravity, t is the time vari-
 170 able and δ is the Kronecker delta. Equation 3 is solved numerically with a first-order for-
 171 ward Euler method.

172 Other forces such as aerodynamic lift, electrostatic forces and those from interpar-
 173 ticle collision are expected to be smaller than weight and drag and are generally neglected
 174 when modeling saltation in air (Maxey & Riley, 1983; Anderson & Hallet, 1986). Their
 175 effect on sand saltation was studied by several authors (e.g., D. S. Schmidt et al., 1998;
 176 Kok & Renno, 2006, 2008; Huang et al., 2007; Durán et al., 2011) and further investi-
 177 gation is needed to fully assess their impact on particle trajectory (Kok et al., 2012). More-
 178 over, snow sublimation is not taken into account.

179 In previous works based on this model (Groot Zwaaftink et al., 2014; Sharma et
 180 al., 2018; Comola, Giometto, et al., 2019), the non-resolved SGS velocities were computed.
 181 Then, the instantaneous wind field was derived from the sum of the resolved wind ve-
 182 locity field, u_i , and the SGS velocities. The modeling of velocity fluctuations is impor-
 183 tant when using simple flow models, as COMSALT (Kok & Renno, 2009), or RANS solvers
 184 (Nemoto & Nishimura, 2004). In these models, turbulence is not resolved and a model
 185 for high-frequency velocity fluctuations is imperative. However, the importance of such
 186 a model is less clear for LES, as the large scale instantaneous turbulent flow is provided
 187 as a solution of the flow solver. In fact, Dupont et al. (2013) concluded that the SGS ve-
 188 locities have a negligible effect on particle trajectories. Moreover, Z. Wang et al. (2019)
 189 did not consider the SGS velocities when modeling saltation with an LES solver. The
 190 impact of SGS velocities on particle trajectories may also depend on the SGS model em-
 191 ployed, even though there are no works in the literature regarding this question. In this
 192 work, the effect of the SGS turbulence features on the resolved wind velocity field is mod-
 193 eled with one of the most advanced SGS closure schemes, the LASD (Bou-Zeid et al.,
 194 2005). Thus, the effect of the SGS velocities on particle motion is assumed to be neg-
 195 ligible and not taken into account.

196 The feedback of particle motion on flow momentum is modelled through a source
 197 term, S_i , in the Navier-Stokes equations. S_i is given by the total drag force induced by
 198 the particles, corresponding to the sum of $-D_i$, per unit volume. The contribution of
 199 each particle is linearly extrapolated to the nearest eight grid nodes where LES is resolved.

200 Periodic boundary conditions are applied to particles exiting the domain through
 201 its vertical walls. Particles that reach the top boundary are assumed to leave the domain
 202 and those impacting the bottom boundary (erodible bed) may rebound and eject other
 203 grains as described in section 2.3.

204 Different studies have been conducted with previous and current versions of this
 205 model concerning snow saltation variability (Groot Zwaaftink et al., 2014), drifting snow
 206 sublimation (Sharma et al., 2018) and preferential deposition over hills (Comola, Giometto,
 207 et al., 2019). A detailed description of the model algorithm and a comparison between
 208 simulation results and field/wind tunnel measurements can be found in these works.

209 **2.3 Surface processes**

210 The interaction between surface grains, the wind flow and particles impacting the
 211 bed is described by three main processes: aerodynamic entrainment, rebound and splash.
 212 These surface processes are modelled with statistical models based on physical princi-
 213 ples and experimental correlations, as proposed by Groot Zwaaftink et al. (2014) and
 214 further developed by Comola and Lehning (2017).

215 This approach reduces the computational cost associated with the direct numer-
 216 ical simulation of particle interactions within the granular bed. Saltation models based
 217 on the Discrete Element Method (DEM) simulate these complex interactions, but are
 218 not suitable for simulating particle transport over large computational domains (Durán
 219 et al., 2012; Pähz et al., 2015; Comola, Gaume, et al., 2019).

220 **2.3.1 Aerodynamic entrainment**

221 When a fluid flows over a granular and erodible bed, surface particles can be moved
 222 and eventually lifted by the flow. This process is called aerodynamic entrainment and
 223 occurs when the fluid surface shear stress grows above a given threshold. This thresh-
 224 old, that defines the start of wind erosion, is estimated by considering the forces applied
 225 on a grain laying on the bed and by performing a balance of angular momentum. The
 226 quantity of interest is the minimum aerodynamic force that makes the grain rotate over
 227 its leeward point of contact with the underlying grains and, eventually, leads to an up-
 228 lift of the grain.

229 In general, this threshold shear stress is modeled as a mean quantity, related to the
 230 instantaneous aerodynamic force by a parameterization. Bagnold (1941) named it the
 231 fluid threshold, τ_{ft} . Considering particle weight, buoyancy and drag, he proposed the
 232 following well known expression:

$$\tau_{ft} = A^2 (\rho_p - \rho_f) g d \quad (4)$$

233 where A is the fluid threshold coefficient, which depends on different flow and particle
 234 characteristics. Chepil (1959) deduced an expression for A , function of the turbulence
 235 intensity, particle geometry and drag coefficient, estimated by a series of experiments de-
 236 veloped with sand and soil grains. Bagnold (1941) proposed $A = 0.1$ for sand beds, af-
 237 ter a series of wind tunnel and field experiments. A higher value is expected for very small
 238 particles like dust. In this case, the granular surface is not aerodynamically rough and
 239 a thin viscous sub-layer is present close to the surface, which limits the transport of flow
 240 momentum to the bed. Different criteria have been proposed to define the onset of aero-
 241 dynamic entrainment. A summary of the latest developments can be found in Pähz et
 242 al. (2020).

243 Interparticle forces, as the van der Waals and electrostatic forces and those induced
 244 by interparticle bonds, also play a role in the aerodynamic entrainment of cohesive ma-
 245 terials as snow or moist soils (R. A. Schmidt, 1980; Shao & Lu, 2000). However, the quan-
 246 tification of such forces is still a challenge. The contribution of interparticle ice bonds
 247 in the calculation of the fluid threshold is of special interest when studying the erosion
 248 of snow covered surfaces and was firstly addressed by R. A. Schmidt (1980). However,
 249 for common interparticle bond radius, the values estimated for τ_{ft} were too large for pure

250 aerodynamic entrainment of snow particles to occur. Other authors as Lehning et al. (2000)
 251 and Clifton et al. (2006) used the same approach suggested by R. A. Schmidt (1980),
 252 but adjusted the bond properties and empirical constants to improve the agreement with
 253 wind tunnel tests performed with natural snow beds. The values for τ_{ft} obtained dur-
 254 ing wind tunnel and field experiments are lower than those deduced by R. A. Schmidt
 255 (1980), possibly because patches of loose snow grains are always present over dry snow
 256 surfaces. These grains can be easily lifted by the flow and contribute to the development
 257 of saltation by further ejecting other particles. Moreover, bed microtopography can also
 258 induce local peaks in shear stress, leading to the preferential entrainment of grains more
 259 exposed to the airflow.

260 In light of the challenges and uncertainties to correctly quantify the effect of inter-
 261 particle forces on the fluid threshold, these forces are not taken into account in this
 262 work. Hence, τ_{ft} is computed from equation 4, considering the grain mean diameter, $\langle d \rangle$.
 263 This is a simpler approach suitable to study steady state saltation, where the contribu-
 264 tion of aerodynamic entrainment is expected to be negligible (Kok et al., 2012).

265 The number of grains entrained per unit area per unit time, defined as the aero-
 266 dynamic entrainment rate, N_{ae} , is computed by the expression proposed by Anderson
 267 and Haff (1991):

$$N_{ae} = \eta(\tau_s - \tau_{ft}) \quad (5)$$

268 where η is the entrainment coefficient and τ_s is the surface shear stress. τ_s is related to
 269 the surface friction velocity, $u_{*,s}$, by its definition: $\tau_s = \rho_f u_{*,s}^2$. Similarly, we introduce
 270 the fluid threshold friction velocity, $u_{*,ft}$, related to the fluid threshold shear stress by
 271 $\tau_{ft} = \rho_f u_{*,ft}^2$. The surface friction velocity differs from the imposed friction velocity,
 272 u_* , after saltation onset and the consequent exchange of momentum from the fluid to
 273 the particles. η is computed with the expression proposed by Doorschot and Lehning (2002):

$$\eta = \frac{C_{ae}}{8\pi\langle d \rangle^2} \quad (6)$$

274 where the coefficient C_{ae} is set to 1.5 grains $\text{m}^2 \text{N}^{-1} \text{s}^{-1}$ (Groot Zwaaftink et al., 2014).

275 In the model, entrained particles start their trajectory at a height of four times the
 276 mean grain diameter. The initial velocity and vertical angle of ejection are defined ac-
 277 cording to a lognormal distribution as described in Clifton and Lehning (2008). The mean
 278 and standard deviation of the distribution are computed with the expressions presented
 279 in Table 1. The horizontal angle of ejection is given by the horizontal flow direction.

280 **2.3.2 Rebound**

281 After impacting the surface, a grain may rebound and eject other particles laying
 282 on the bed. The probability of rebound, P_r , is described by the expression proposed by
 283 Anderson and Haff (1991):

$$P_r = P_m [1 - \exp(-\gamma|u_{p,I}|)] \quad (7)$$

284 where P_m is the maximum probability of rebound, equal to 0.9 as proposed by Groot Zwaaftink
 285 et al. (2014) for snow particles, γ is a constant set to 2 s m^{-1} (Anderson & Haff, 1991)
 286 and $|u_{p,I}|$ is the particle velocity at impact.

287 The velocity of rebound, $|u_{p,R}|$, is given by $|u_{p,R}| = \sqrt{\epsilon_r}|u_{p,I}|$, where ϵ_r is the frac-
 288 tion of kinetic energy retained by the rebounding grain (restitution coefficient). Salta-

Table 1. Initial velocity of aerodynamically entrained, splashed and rebounding grains: distribution type, mean and standard deviation.

	Distribution	Mean	Std.	References
Aerodynamic entrainment				
Velocity magnitude	Lognormal	$3.5u_*$	$2.5u_*$	Clifton and Lehning (2008)
Vertical angle	Lognormal	$75 - 55 \left[1 - \exp \left(-\frac{d}{175 \times 10^{-6}} \right) \right]$	15	Clifton and Lehning (2008)
Rebound				
Velocity magnitude	-	$\sqrt{\epsilon_r} u_{p,I} $	-	Kok and Renno (2009)
Vertical angle	Exponential	45	-	Kok and Renno (2009)
Splash				
Velocity magnitude	Exponential	$0.25 u_{p,I} ^{0.3}$	-	Sharma et al. (2018)
Vertical angle	Exponential	50	-	Rice et al. (1995, 1996)
Horizontal angle	Normal	Angle of impacting particle	15	Xing and He (2013)

Velocities are in units of m s^{-1} , angles are in degrees and the grain size is in meters.

289 tion models have shown to be highly sensitive to the value of ϵ_r , which greatly depends
 290 on the particle elastic properties (Kok & Renno, 2009). Experiments developed with sand
 291 showed that ϵ_r varies according to a normal distribution (D. Wang et al., 2008). Although
 292 the restitution coefficient for snow particles is more uncertain, experiments have not sug-
 293 gested a significant deviation from the values obtained for sand grains (Nalpanis et al.,
 294 1993).

295 The horizontal angle of rebound is given by the horizontal flow direction and the
 296 vertical angle is computed from an exponential distribution. Further details are presented
 297 in Table 1.

298 **2.3.3 Splash**

299 When a grain impacts the bed, it can eject several grains initially at rest. This pro-
 300 cess, named splash or ejection, is the main driver of particle motion during steady state
 301 saltation (Kok et al., 2012). As flow momentum decreases near the surface due to par-
 302 ticle drag, aerodynamic entrainment is highly compromised after the start of saltation.
 303 Particles impacting the ground become the main source of momentum as they travel from
 304 high momentum regions to the surface.

305 Numerous statistical splash functions have been proposed to estimate the number
 306 of ejected grains, N , and their initial velocity, $|u_{p,o}|$, as a function of the impacting grain
 307 velocity, $|u_{p,I}|$, and mass, m_I (e.g., Anderson & Haff, 1988; McEwan & Willetts, 1991).
 308 In this work, the number of ejected grains is computed from energy and momentum con-
 309 servation laws, as proposed by Kok and Renno (2009) and adapted by Comola and Lehning
 310 (2017) to take into account the effect of mixed-sized grains and interparticle cohe-
 311 sion.

312 The impacting grain and the bed are regarded as an isolated system, for which en-
 313 ergy and momentum conservation is applied. A fraction of the kinetic energy and mo-
 314 mentum, ϵ_r and μ_r , respectively, is kept by the impacting grain leading to its rebound.
 315 The remaining fraction is only partly transferred to the ejected grains, as a fraction of

316 the impacting energy and momentum, ϵ_f and μ_f , respectively, leads to the rearrange-
 317 ment of surface grains and, consequently, to friction related losses.

318 Both the energy and momentum conservation equations are solved for N by sta-
 319 tistically representing the kinetic energy and momentum of the ejected grains by their
 320 mean values. Only the horizontal direction of the momentum equation is taken into ac-
 321 count as the vertical component of the impact velocity is relatively small (Bagnold, 1941).
 322 Comola and Lehning (2017) arrived at the following expressions:

$$N_E = \frac{(1 - P_r \epsilon_r - \epsilon_f) m_I u_{p,I}^2}{\langle m \rangle \langle u_{p,o}^2 \rangle + r_E \sigma_m \sigma_{u_{p,o}^2} + 2\phi} \quad (8a)$$

$$N_M = \frac{(1 - P_r \mu_r - \mu_f) m_I u_{p,I} \cos \alpha_I}{\langle m \rangle \langle u_{p,o} \rangle \langle \cos \alpha \rangle \langle \cos \beta \rangle + r_M \sigma_m \sigma_{u_{p,o}}} \quad (8b)$$

323

324 where N_E and N_M denote the number of ejected grains computed by the energy and mo-
 325 mentum equations, respectively. The quantities within angle brackets represent average
 326 values, m being the mass of an ejected grain, α the vertical angle of ejection and β the
 327 horizontal angle of ejection measured from the plane of impact (in the above equations,
 328 both α and β are assumed statistically independent). σ_m , $\sigma_{u_{p,o}}$ and $\sigma_{u_{p,o}^2}$ denote the stan-
 329 dard deviation of m , $u_{p,o}$ and $u_{p,o}^2$, respectively. α_I is the vertical angle of impact, r_E
 330 and r_M are the correlation coefficients between m and $u_{p,o}^2$ and between m and $u_{p,o}$, re-
 331 spectively, and ϕ is the energy required to break the cohesive bonds between each ejected
 332 grain and the surrounding ones. The modulus symbol in both $u_{p,o}$ and $u_{p,I}$ was suppressed
 333 for simplicity.

334 The number of ejected grains is then given by the minimum value between N_E and
 335 N_M , which guarantees that neither energy nor momentum is created. The number of ejected
 336 grains is expected to be restricted by momentum conservation when the bed is consti-
 337 tuted by loose grains (Kok & Renno, 2009). However, this is not always obtained when
 338 interparticle forces are present (Shao et al., 1993; Comola & Lehning, 2017).

339 The ejection velocity is assumed to follow an exponential distribution (Anderson
 340 & Haff, 1988, 1991). The values considered for the mean ejection velocity and the ver-
 341 tical and horizontal angles of ejection are presented in Table 1. The mean and standard
 342 deviation of the mass of ejected grains are computed assuming equally-sized grains or
 343 a lognormal distribution for the grain diameter (Colbeck, 1986).

Table 2. Parameters of the splash model.

Parameter	Values used in the model	References
ϵ_r	0.25	Rice et al. (1995); D. Wang et al. (2008)
ϵ_f	$0.96(1 - P_r \epsilon_r)$	Ammi et al. (2009)
μ_r	$\sqrt{\epsilon_r}$	-
μ_f	0.4	Rice et al. (1995)
r_E	0	-
r_M	0	-
$\langle \cos \alpha \rangle$	0.75	Rice et al. (1995)
$\langle \cos \beta \rangle$	0.96	Xing and He (2013)
$\phi^{(1)}$ [J]	$10^{-10}, 5 \times 10^{-10}, 5 \times 10^{-9}$	Gauer (2001)

(1) Values obtained for ice particles. $\phi = 0$ J is considered for loose grains.

344 The parameters $\epsilon_r, \epsilon_f, \mu_r, \mu_f, r_E, r_M, \langle \cos \alpha \rangle$ and $\langle \cos \beta \rangle$ are assumed constant. ϕ
 345 is set to different figures throughout the simulations. The values used in the model are
 346 presented in Table 2. They are defined according to the range proposed in the literature
 347 (Comola & Lehning, 2017). The correlation coefficients, r_E and r_M , are set to zero in
 348 this work, as estimates of these parameters developed for snow beds are not available
 349 in the literature.

350 3 Numerical setup

351 3.1 General settings

352 The computational domain is a cube of 6.4 m side length. It models the near sur-
 353 face atmospheric flow over a flat erodible bed. The domain is relatively short in both hor-
 354 izontal directions, specially in the streamwise one. This is partially compensated by ap-
 355 plying periodic boundary conditions. However, the use of a longer domain is necessary
 356 for the consistent development of large coherent structures observed in experimental and
 357 numerical boundary layer studies (Munters et al., 2016). Even though longer domains
 358 are imperative for a proper comparison with experimental data, a cubic domain was con-
 359 sidered adequate for the study of steady state saltation developed in this paper. More-
 360 over, it greatly reduces the computational time.

361 The domain is discretized in 64 cells of equal size in the streamwise and crosswise
 362 directions. The vertical direction is discretized in 128 cells using a hyperbolic function,
 363 which guarantees a more refined mesh close to the bottom boundary. The first grid node
 364 above the surface is placed in the logarithmic sublayer.

365 The simulations are performed over a total of 350 s to allow the development of
 366 steady state saltation. The time step is set to 5×10^{-5} s. The flow is allowed to develop
 367 over 25 s prior to the start of surface erosion.

368 The initial streamwise component of the velocity field is given by a logarithmic pro-
 369 file, function of u_* and of the roughness length, z_o . The roughness length is assumed con-
 370 stant along the surface and equal to 10^{-5} m. The initial crosswise and vertical velocity
 371 components are set to zero. Noise is added to all velocity components.

372 The fluid density and kinematic viscosity are set to $\rho_f = 1.34 \text{ kg m}^{-3}$ and $\nu_f =$
 373 $1.24 \times 10^{-5} \text{ m}^2 \text{ s}^{-1}$, respectively. Particles are modelled as ice spheres with density $\rho_p =$
 374 918.4 kg m^{-3} . The top of the erodible surface is defined at a height $z = 0$ m and par-
 375 ticle size is assumed uniform or defined by a lognormal distribution, characterized by the
 376 grain mean diameter, $\langle d \rangle$, and standard deviation, σ_d . In order to reduce the computa-
 377 tional cost of the simulations, particles are not modelled individually but grouped in parcels,
 378 constituted by particles of equal size that follow the same trajectory.

379 3.2 Simulation details

380 In order to study the effect of friction velocity, mean grain size, size distribution
 381 and cohesion energy on saltation dynamics, four groups of simulations are performed -
 382 S1 to S4 - for which different values of u_* , $\langle d \rangle$, σ_d and ϕ are considered. The param-
 383 eters used in each simulation group are summarized in Table 3.

384 In simulations S1 and S2, a bed of equally-sized ($\sigma_d = 0 \mu\text{m}$) and loose grains ($\phi =$
 385 0 J) is modeled. In S1, the effect of the imposed friction velocity is studied while keep-
 386 ing the remaining parameters unchanged. In S2, different values for the grain diameter,
 387 $\langle d \rangle$, are tested. In simulations S3 and S4, a bed of mixed-sized grains is modeled by de-
 388 scribing the grain size by a lognormal distribution. In S3, the effect of the standard de-
 389 viation of the distribution, σ_d , on steady state saltation is analyzed. Finally, in S4, in-
 390 terparticle forces are assumed between surface grains and different values for the cohe-

Table 3. Simulation input parameters.

Description	u_* [m s ⁻¹]	$\langle d \rangle$ [μm]	σ_d [μm]	ϕ [J]
S1 Effect of friction velocity	0.3 - 0.8	200	0	0
S2 Effect of mean grain diameter	0.4 - 0.8	100, 300, 400	0	0
S3 Effect of size distribution	0.4 - 0.8	200	100, 200	0
S4 Effect of cohesion	0.4 - 0.8	200	100	$10^{-10}, 5 \times 10^{-10}, 5 \times 10^{-9}$

391 sion energy, ϕ , are tested. Different values for u_* are also considered in simulations S2
 392 to S4. The fluid threshold coefficient is set to $A = 0.1$ and the splash model paramete-
 393 rs are set to the values presented in Table 2.

394 3.3 Data post-processing

395 The vertical profiles of particle concentration, mean particle streamwise velocity
 396 and particle mass flux are computed by dividing the computational domain in horizon-
 397 tal layers of thickness Δz_k .

398 The particle concentration, c [kg m⁻³], is given by

$$c(z_k) = \frac{\sum_{n=1}^{N_k} m_n}{L_x L_y \Delta z_k} \quad (9)$$

399 where N_k is the number of particles in the horizontal layer with mean height z_k , m_n is
 400 the mass of the n^{th} particle, L_x is the domain length and L_y is the domain width.

401 The mean particle velocity in the streamwise direction, $\langle u_{p,1} \rangle$, is given by the mass-
 402 weighted average:

$$\langle u_{p,1} \rangle(z_k) = \frac{\sum_{n=1}^{N_k} m_n u_{p,1,n}}{\sum_{n=1}^{N_k} m_n} \quad (10)$$

403 where $u_{p,1,n}$ is the streamwise velocity of the n^{th} particle in layer k .

404 The particle mass flux, q [kg m⁻² s⁻¹], is given by the product of particle concen-
 405 tration and mean particle streamwise velocity, yielding

$$q(z_k) = \frac{\sum_{n=1}^{N_k} m_n u_{p,1,n}}{L_x L_y \Delta z_k}. \quad (11)$$

406 The integrated mass flux of saltating particles, Q [kg m⁻¹ s⁻¹], is computed by in-
 407 tegrating particle mass flux, q , along the height, from the surface to 0.15 m. The last
 408 100 s of each simulation are used to compute the time-averaged values of c , $\langle u_{p,1} \rangle$, q and
 409 Q . During this time interval (250 s - 350 s), the changes in total mass of particles aloft
 410 are negligible and saltation is assumed to be in steady state.

411 The surface friction velocity, $u_{*,s}$, at each time step is obtained by averaging over
 412 the surface. The time-averaged value obtained for the last 100 s of each simulation is de-
 413 fined as the equilibrium surface friction velocity, $u_{*,eq}$.

414

4 Results and discussion

415

In this section, the results are presented and discussed. Results obtained with simulations S1 to S4 are analyzed in sections 4.1 to 4.4, respectively. Moreover, a comparison with existing saltation models and with the conclusions drawn from the latest wind tunnel and field experiments is presented.

418

419

4.1 The effect of friction velocity

420

In simulations S1, a bed of equally-sized and loose grains with a diameter of $200 \mu\text{m}$ is modelled. The streamwise wind speed profiles are presented in Figure 1. They are computed by averaging the streamwise velocity along horizontal planes. The profiles are time-averaged over the first 25 s and over the last 100 s of each simulation (before saltation onset and during steady state saltation). As expected, the resulting wind speed is lower for the latter, as the saltation layer acts on the flow as an additional sink of momentum.

426

427

A focus point can be observed at approximately 7 mm above the surface for the velocity profiles obtained during steady state saltation (inset in Figure 1). This focus point was originally observed by Bagnold (1941) and is given by the interception of velocity profiles obtained during saltation with different friction velocities. It was used as a simplifying assumption in previous saltation models (Pomeroy & Gray, 1990) and reproduced by several numerical models based on parameterizations of splash entrainment (Kok et al., 2012).

432

434

An equivalent surface roughness, characteristic of each saltation layer, can be estimated from the velocity profiles obtained during steady state saltation (Dupont et al., 2013). By extending the velocity profiles down to the wall, zero velocity is attained at greater heights as u_* increases. Hence, the equivalent surface roughness increases with u_* . This is related to an enhanced momentum exchange between the fluid flow and the particles aloft when u_* increases. Therefore, it is ultimately related to the increase in particle mass flux.

438

441

The time-averaged vertical profiles of particle mass flux, concentration and mean streamwise velocity are presented in Figures 2a-c. The average is performed over the last 100 s of each simulation. Particle mass flux decreases with height and increases with u_*

443

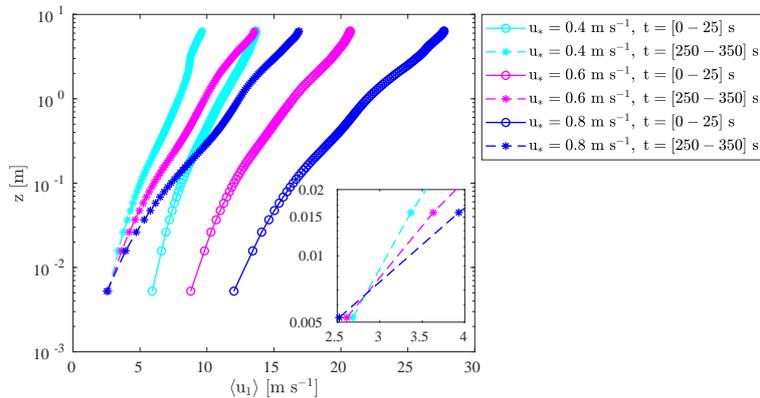


Figure 1. Vertical profiles of mean streamwise wind speed obtained before saltation onset and during steady state saltation (simulations S1). The inset is a zoom-in to the near surface region during saltation.

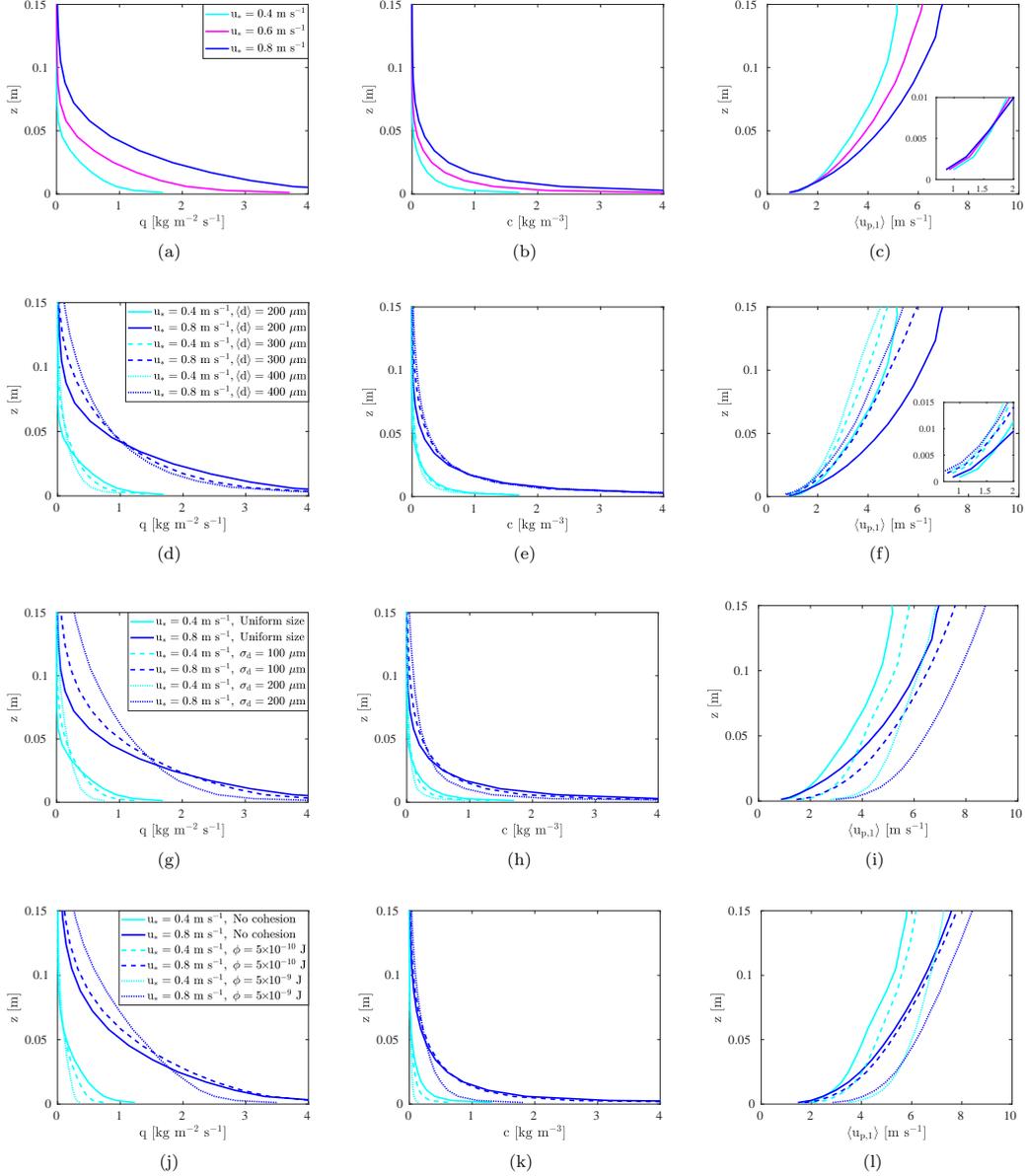


Figure 2. Vertical profiles of particle mass flux, concentration and streamwise velocity obtained with simulations S1 (a-c), S2 (d-f), S3 (g-i) and S4 (j-l). In (d-i) and (j-l) results from simulations S1 and S3 are presented for comparison, respectively. All values are obtained from surface averages and time averages over the last 100 s of each simulation. The insets in (c) and (f) are a zoom-in to the near surface region.

444 (Figure 2a), as previously observed in field measurements (Nishimura et al., 2014). A
 445 similar trend is observed for particle concentration (Figure 2b). As expected, particle
 446 streamwise velocity increases with height and u_* (and, therefore, with wind speed), as
 447 shown in Figure 2c. For heights smaller than 1 cm (approximately), the variation of particle
 448 streamwise velocity with u_* is negligible (inset in Figure 2c). This is predicted by
 449 existing saltation models (Kok & Renno, 2009) and wind tunnel measurements (Ho et
 450 al., 2011). This result is also obtained theoretically, based on the notion that steady state
 451 saltation is characterized by a mean replacement capacity equal to one (Kok et al., 2012).
 452 This means that, on average, one grain enters the saltation layer each time an impact-
 453 ing grain fails to rebound. Assuming that saltation is mainly dominated by splash, this
 454 condition is met for a given impact velocity, which completely defines the number of ejected
 455 grains and the probability of rebound for a given bed type (see equations 7 and 8). Hence,
 456 it follows that the particle speed near the surface is independent of u_* and rather varies
 457 with the bed characteristics. The near surface particle speed is closely linked to the focus
 458 point (or Bagnold’s focus) observed in the average streamwise wind speed profiles
 459 (Figure 1). Saltating particles are accelerated by the flow along their trajectories, there-
 460 fore, the near surface particle speed can only be approximately invariant with regards
 461 to u_* if the near surface wind speed is also approximately invariant with regards to the
 462 same quantity. High above the surface, the wind speed increases as u_* rises. Hence, a
 463 near surface wind speed approximately invariant with u_* is only obtained if a focus point
 464 is visible close to the surface, below which the wind speed decreases as u_* increases.

465 The surface friction velocity, $u_{*,s}$, as a function of time is presented in Figure 3.
 466 The fluid threshold friction velocity is also plotted as a reference. $u_{*,s}$ strongly decreases
 467 immediately after the start of surface erosion ($t = 25$ s). It tends to an equilibrium value
 468 - the equilibrium surface friction velocity, $u_{*,eq}$. A small reduction of $u_{*,eq}$ is obtained
 469 when the imposed friction velocity, u_* , increases (inset in Figure 3). The numerical model
 470 COMSALT proposed by Kok and Renno (2009) also predicts this trend for a bed with
 471 uniform grain size (Kok et al., 2012). However, they predicted a stronger reduction than
 472 that presented in the inset in Figure 3. The wind tunnel experiments performed by Walter
 473 et al. (2014) revealed a non-monotonic evolution of $u_{*,eq}$ with u_* . During the experiments,
 474 u_* was continuously increased above the fluid threshold. As a result, the measured $u_{*,eq}$
 475 firstly reduced and then increased. In general, a relatively small variation of $u_{*,eq}$ with
 476 u_* and a relatively large standard deviation of the measurements were obtained, which
 477 may be partially related to changes in the snow cover during the experiments. Based on

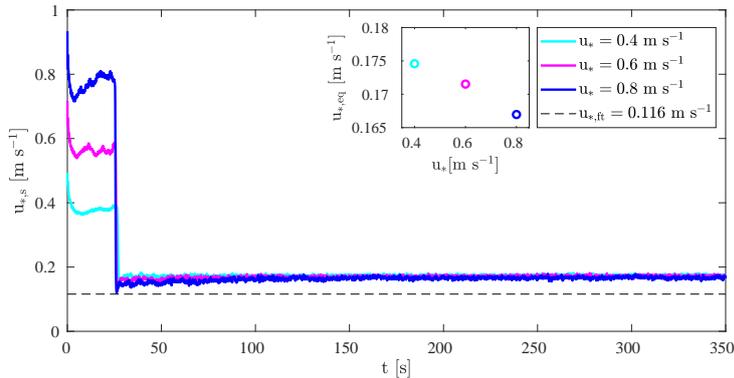


Figure 3. Surface friction velocity obtained with simulations S1. The fluid threshold friction velocity is also presented as a reference. In these simulations, saltation is allowed to develop after the first 25 seconds. The equilibrium friction velocity is presented in the inset.

478 these results, Walter et al. (2014) considered the assumption of a constant surface friction
 479 velocity (function of the grain type but invariant with the wind speed, as proposed
 480 by Owen (1964)) a reasonable first-order approximation.

481 The impact threshold, $u_{*,it}$, is generally defined as the minimum friction velocity,
 482 u_* , at which saltation can be sustained after its onset (Bagnold, 1941). In the work of
 483 Kok and Renno (2009), the impact threshold is assumed equal to the minimum value
 484 of u_* that satisfies the steady state equation. In their model, the equilibrium friction ve-
 485 locity, $u_{*,eq}$, tends to the computed impact threshold as u_* decreases (Kok et al., 2012).
 486 Taking into account these results, a simplified approach is followed in this work and $u_{*,it}$
 487 is given by the value of $u_{*,eq}$ obtained when u_* is set to 0.4 m s^{-1} (the minimum friction
 488 velocity common to all simulation groups). This approach is considered appropriate
 489 taking into account the small variation of $u_{*,eq}$ with u_* obtained for most simula-
 490 tions. A more accurate estimation of the impact threshold needs further investigation,
 491 in particular, a set of simulations at low friction velocities (near the impact and fluid thresh-
 492 olds) and the analysis of the transition from intermittent to steady state saltation.

493 The mass of particles aloft per unit surface area varies with time, as presented in
 494 Figure 4. The vertical mass flux of particles leaving the surface either through aerody-
 495 namic entrainment or splash and the vertical mass flux of particles deposited due to fail-
 496 ure of rebound are also presented. The results were obtained for $u_* = 0.4 \text{ m s}^{-1}$. The
 497 evolution shown is representative of all the simulations performed. At $t = 25 \text{ s}$, salta-
 498 tion starts due to aerodynamic entrainment. A sudden increase in the mass of particles
 499 aloft is observed, which is consistent with the strong decrease in surface friction ve-
 500 locity presented in Figure 3. The overshoot in particle mass is justified by the surge in the
 501 vertical mass flux of particles entering saltation via splash, that overcomes the vertical
 502 mass flux of particles leaving the saltation layer through deposition (Figure 4b). The im-
 503 balance between the vertical mass flux of splash and deposition drives the variation of
 504 mass of particles aloft. When saltation reaches steady state, a dynamic equilibrium be-
 505 tween the vertical mass flux of splash and deposition is obtained. Aerodynamic entrain-
 506 ment is much smaller than splash: the vertical mass flux reaches a maximum at salta-
 507 tion onset and then decreases to a steady state value, which is one order of magnitude
 508 lower than the vertical mass flux of splash and deposition. In the simulations performed,
 509 aerodynamic entrainment occurs during steady state saltation because the surface fric-
 510 tion velocity is greater than the specified fluid threshold (Figure 3). However, taking into

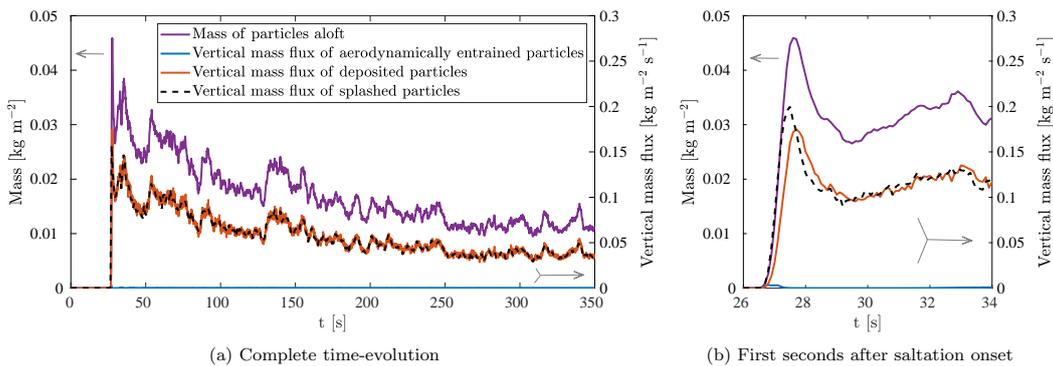


Figure 4. Time-evolution of the mass of particles aloft per unit area (purple line). The time-
 evolution of the vertical mass flux of particles leaving the surface either through aerodynamic
 entrainment or splash and the vertical mass flux of particles deposited are presented in blue,
 dashed black and orange, respectively. Results obtained from simulation S1 with $u_* = 0.4 \text{ m s}^{-1}$.
 The arrows indicate the y-axis corresponding to each curve.

511 account the relatively small contribution of aerodynamic entrainment to the mass of par-
 512 ticles aloft, the correct assessment of the fluid threshold is expected to have a negligi-
 513 ble effect on steady state saltation for friction velocities significantly greater than the fluid
 514 threshold. These results are in agreement with the well-established notion that steady
 515 state saltation is dominated by splash and that an equilibrium between splash and fail-
 516 ure of rebound should be attained (Kok et al., 2012).

517 The time-averaged integrated mass flux and the corresponding standard deviation
 518 are presented in Figure 5. In Figure 5a, the fit between the mean values and a quadratic
 519 function is presented, as well as between the mean values and a cubic function. In Fig-
 520 ure 5b, the results are compared to saltation models proposed by several authors (Bagnold,
 521 1941; Pomeroy & Gray, 1990; Doorschot & Lehning, 2002; Sørensen, 2004; Durán et al.,
 522 2011). The results from Doorschot and Lehning (2002) were obtained from the numer-
 523 ical algorithm proposed by the authors. The remaining curves are computed from the
 524 equations presented in Table 4.

525 Equations used to compute the integrated mass flux (as those presented in Table
 526 4) are obtained from the balance of horizontal momentum applied to the saltating par-
 527 ticles. The total horizontal force per unit area applied on these particles is equal to the
 528 excess shear stress, $\tau - \tau_s = \rho_f (u_*^2 - u_{*,s}^2)$, where $\tau = \rho_f u_*^2$ is the surface shear stress
 529 before saltation onset. In addition, if particle trajectories are characterized by a repre-
 530 sentative hop, with length L , in which particles undergo a mean variation of horizontal
 531 velocity, Δu_{ph} , between lift off and impact with the bed, the integrated mass flux is com-
 532 puted from $Q = \rho_f (u_*^2 - u_{*,s}^2) L / \Delta u_{ph}$ (e.g., Kok et al., 2012). Different models arise
 533 from different assumptions regarding the evolution of $u_{*,s}$ and $L / \Delta u_{ph}$. Following Owen’s
 534 hypothesis (Owen, 1964), the surface friction velocity, $u_{*,s}$, is generally assumed invari-
 535 ant with respect to u_* and equal to the impact threshold, $u_{*,it}$. Even though there is no
 536 full consensus on the validity of this hypothesis and its implications on saltation dynam-
 537 ics (see, for instance, Kok et al. (2012) and Walter et al. (2014)), the fact that the gen-
 538 eral equation yields $Q = 0$ when u_* equals $u_{*,s}$ favours the use of this simplifying as-
 539 sumption. The quadratic growth of Q with u_* is predicted theoretically when both the
 540 particle velocity near the surface (and, consequently, Δu_{ph}) and the representative hop
 541 length are considered invariant with u_* (Ungar & Haff, 1987; Durán et al., 2011). This
 542 yields an expression for Q of the form $au_*^2 + b$, which is corroborated by recent field ex-
 543 periments (e.g., Martin & Kok, 2017). The increase of Q with u_*^3 was early proposed by

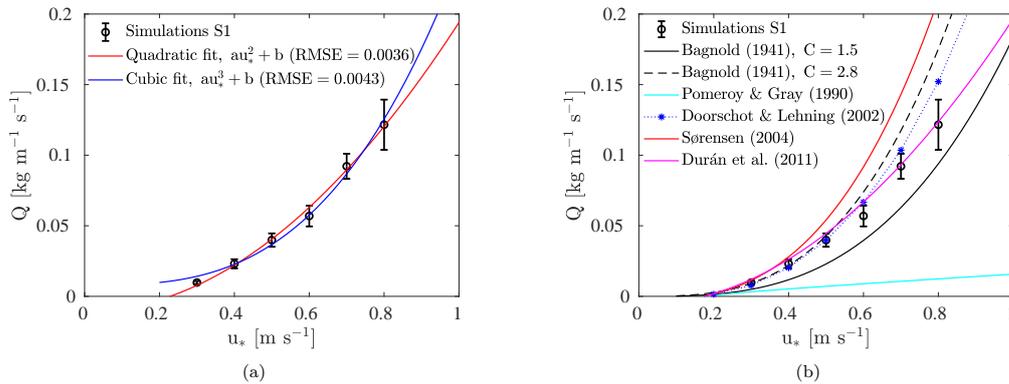


Figure 5. Integrated mass flux obtained with simulations S1. The error bar is twice the standard deviation of the results. (a) Fit of simulation results to quadratic and cubic functions (RMSE is the root mean square error of the fit). (b) Comparison with saltation models.

Table 4. Saltation models for the integrated mass flux, Q .

Integrated mass flux	Constant parameters	References
$Q_{Bag} = C \sqrt{\frac{\langle d \rangle}{d_R}} \frac{\rho_f}{g} u_*^3$	$C = 1.5$ (uniform grains) $C = 2.8$ (highly non-uniform grains)	Bagnold (1941)
$Q_{P\&G} = C \frac{\rho_f}{g} u_{*,it} u_* \left(1 - \frac{u_{*,it}^2}{u_*^2} \right)$	$C = 0.68$	Pomeroy and Gray (1990)
$Q_{S\phi} = \frac{\rho_f}{g} u_*^3 \left(1 - \frac{u_{*,it}^2}{u_*^2} \right) \left(\alpha + \beta \frac{u_{*,it}^2}{u_*^2} + \gamma \frac{u_{*,it}}{u_*} \right)$	$\alpha = 2.6, \beta = 2.5, \gamma = 2.0$ ⁽¹⁾	Sørensen (2004)
$Q_{Dur} = C \frac{\rho_f}{g} u_{*,it} u_*^2 \left(1 - \frac{u_{*,it}^2}{u_*^2} \right)$	$C = 8.5$ ⁽²⁾	Durán et al. (2011)

d_R is a reference diameter, $d_R = 250 \mu\text{m}$.

⁽¹⁾ Constant parameters proposed by Vionnet et al. (2014) to model snow saltation.

⁽²⁾ C estimated from Figure 27 in Durán et al. (2011), assuming a packing fraction of the bed, ϕ_b , equal to 0.95.

544 Bagnold (1941) based on the assumptions that L is proportional to u_*^2 and that the near
 545 surface particle velocity increases linearly with u_* . This yields an expression for Q of the
 546 form $au_*^3 + b$. A cubic expression for the integrated mass flux can also be obtained by
 547 assuming that particle velocity near the surface is invariant with u_* , but considering a
 548 linear increase of L with u_* (Sørensen, 1991, 2004). However, experiments show that a
 549 cubic increase of Q with u_* is only likely to happen when saltation develops over rigid
 550 beds (Ho et al., 2011).

551 In Figure 5a, a good agreement is obtained for both polynomial functions, although
 552 the quadratic fit is slightly better (root mean square error, RMSE, equal to 0.0036 in-
 553 stead of 0.0043). In fact, for the range of studied friction velocities, small differences be-
 554 tween the two functions are obtained.

555 In Figure 5b, the comparison between simulation results and saltation models is
 556 made by assuming an impact threshold of 0.175 m s^{-1} (the value of $u_{*,eq}$ obtained for
 557 $u_* = 0.4 \text{ m s}^{-1}$, as previously discussed). In the models proposed by Pomeroy and Gray
 558 (1990), Sørensen (2004) and Durán et al. (2011), the impact threshold is a parameter
 559 in the integrated mass flux equations which characterizes the erodible bed (Table 4). For
 560 friction velocities lower than 0.6 m s^{-1} , a good agreement is seen between simulation re-
 561 sults and the saltation model proposed by Doorschot and Lehning (2002). At higher fric-
 562 tion velocities, the model proposed by Doorschot and Lehning (2002) predicts greater
 563 values for Q and a better agreement is obtained with the expression proposed by Durán
 564 et al. (2011). Q_{Dur} scales with u_*^2 , which is supported by the current simulation results.
 565 However, this equation is highly sensitive to the value of the impact threshold and the
 566 observed agreement is greatly compromised for different values of $u_{*,it}$. Bagnold (1941)
 567 and Sørensen (2004) proposed expressions for Q proportional to u_*^3 . When using the co-
 568 efficients proposed by Vionnet et al. (2014), a greater mass flux is obtained with Sørensen's
 569 expression in comparison with the simulation results. Conversely, the expression proposed
 570 by Bagnold (1941) to describe saltation over uniform grains ($C = 1.5$) predicts lower
 571 values for Q . For friction velocities lower than 0.6 m s^{-1} , the simulation results agree
 572 well with the model proposed by Bagnold (1941) if the constant parameter C is increased
 573 to 2.8. However, the curve obtained with $C = 2.8$ is only expected to describe salta-
 574 tion over a bed of mixed-sized grains. The expression proposed by Pomeroy and Gray
 575 (1990) underestimates the integrated mass flux in comparison with the remaining mod-
 576 els and the simulation results. This is partly justified by the authors assumption of a rel-
 577 atively shallow saltation layer (saltation layer height varying from 7 mm to 5 cm for u_*

578 varying from 0.3 to 0.8 m s⁻¹). However, even by adjusting the height of integration from
 579 15 cm to the proposed values, the integrated mass flux obtained with the current numer-
 580 ical model is significantly greater than the evolution proposed by Pomeroy and Gray (1990).
 581 Hence, the deviation between $Q_{P\&G}$ and the remaining models and simulation results
 582 is mainly related to the erroneous scaling of the integrated mass flux with u_* .

583 4.2 The effect of mean grain diameter

584 In this section, we continue the analysis of saltation over a bed of equally-sized grains.
 585 The effect of grain size is studied by comparing the results presented in the previous sec-
 586 tion (S1, $\langle d \rangle = 200 \mu\text{m}$) with those from simulations S2, obtained for different grain
 587 sizes.

588 The vertical profiles of particle mass flux, concentration and mean streamwise ve-
 589 locity obtained for grain diameters ranging from 200 to 400 μm are presented in Figures
 590 2d-f. It can be observed that particle streamwise velocity decreases when the grain size
 591 increases (Figure 2f). This is due to the fact that aerodynamic drag applied to the saltat-
 592 ing particles increases approximately with d^2 , but particle mass increases with d^3 . Hence,
 593 the ability of the flow to accelerate the saltating grains reduces with particle mass. The
 594 near surface particle velocity also decreases with the grain diameter (inset in Figure 2f).
 595 Although the near surface particle velocity does not vary significantly with u_* , it clearly
 596 varies with the grain size.

597 As the grain size increases, the particle mass flux decreases near the surface and
 598 increases at higher elevations of the saltation layer (Figure 2d). Near the surface, this
 599 trend is justified by the decrease in particle streamwise velocity as $\langle d \rangle$ increases (Figure
 600 2f). Above approximately 4 cm, the increase in particle mass flux as the grain size in-
 601 creases is due to the rise in particle concentration (Figure 2e), which is related to both
 602 an increase in particle mass and the number of particles aloft. The vertical profiles of
 603 particle mass flux obtained for $u_* = 0.4 \text{ m s}^{-1}$ are also presented in logarithmic scale
 604 in Figure 6a. The results obtained with $\langle d \rangle = 100 \mu\text{m}$ are added for comparison. An
 605 exponential decay along the saltation layer is clear for the greater grain sizes ($\langle d \rangle$ between
 606 200 and 400 μm), which is in agreement with field measurements (Martin & Kok, 2017).
 607 The vertical profile obtained with the smallest grain size ($\langle d \rangle = 100 \mu\text{m}$) differs signifi-
 608 cantly from the others. A similar trend inside the saltation layer is visible up to 1 cm
 609 height. However, at greater heights, the profile assumes a different shape suggesting tran-
 610 sition from saltation to suspension. In fact, for the smallest grain size, particles can be

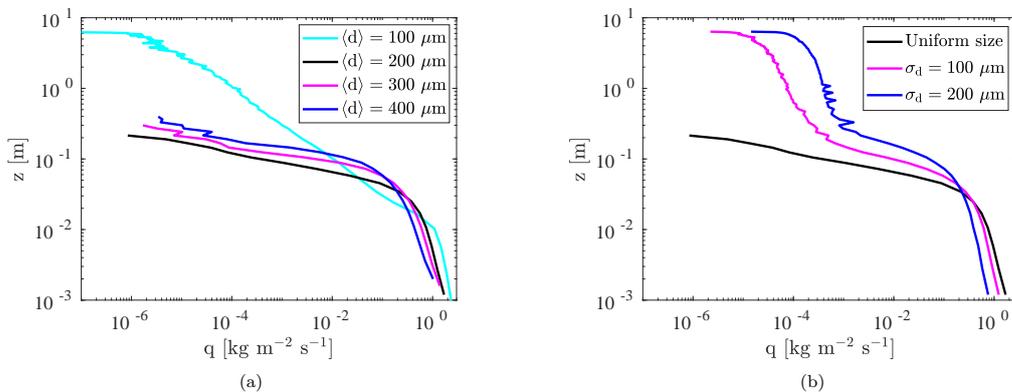


Figure 6. Vertical profiles of particle mass flux obtained with simulations S2 (a) and S3 (b) for $u_* = 0.4 \text{ m s}^{-1}$. Results from simulations S1 are presented for comparison.

611 observed up to the top of the domain, while for greater grain sizes, aeolian transport seems
 612 to occur via saltation only as the mass flux profiles follow an exponential decay up to
 613 the maximum height reached by the particles (14 cm, approximately).

614 The integrated mass flux is presented in Figure 7a along with the expression pro-
 615 posed by Bagnold (1941) and the numerical results from Doorschot and Lehning (2002)
 616 for varying mean grain diameters and friction velocities. Bagnold’s expression establishes
 617 that Q is proportional to $\langle d \rangle^{\frac{1}{2}}$. The numerical model of Doorschot and Lehning (2002)
 618 also predicts an increase in the integrated mass flux with the grain diameter. In contrast,
 619 a negligible variation is obtained with our model for grain diameters ranging from 200
 620 to 400 μm : the reduction in mass flux near the surface and its increase at higher eleva-
 621 tions for increasingly bigger grains (Figure 2d) counterbalance each other. In fact, other
 622 saltation models do not predict an explicit variation of Q with particle mean diameter
 623 (e.g., Sørensen, 2004; Durán et al., 2011). The wind tunnel measurements carried out
 624 by Dong et al. (2003) revealed a reduction in the integrated mass flux with the grain di-
 625 ameter. However, the comparison between sand beds is performed considering the same
 626 wind speed at a given reference height. Hence, it is observed that for the same wind speed
 627 at the chosen reference height, the integrated mass flux decreases as the grain size in-
 628 creases. In the simulations performed, the imposed friction velocity is kept constant when
 629 varying the grain size, which implies different velocities at a given reference height, de-
 630 pending on the mass flux of saltating particles and the respective momentum transfer.
 631 The negligible variation of the integrated mass flux with $\langle d \rangle$ obtained with our model
 632 goes along with an increase in the wind speed at all heights as the grain size increases.
 633 When analyzing the experiments of Dong et al. (2003) performed with different grain
 634 sizes but yielding similar integrated mass fluxes, a greater wind speed is also obtained
 635 for greater grain sizes.

636 When considering a uniform bed with grains of 100 μm , a greater integrated mass flux
 637 is obtained. However, as previously discussed, particles between 1 and 15 cm height
 638 might not be in saltation but rather in suspension. When modeling particles smaller than

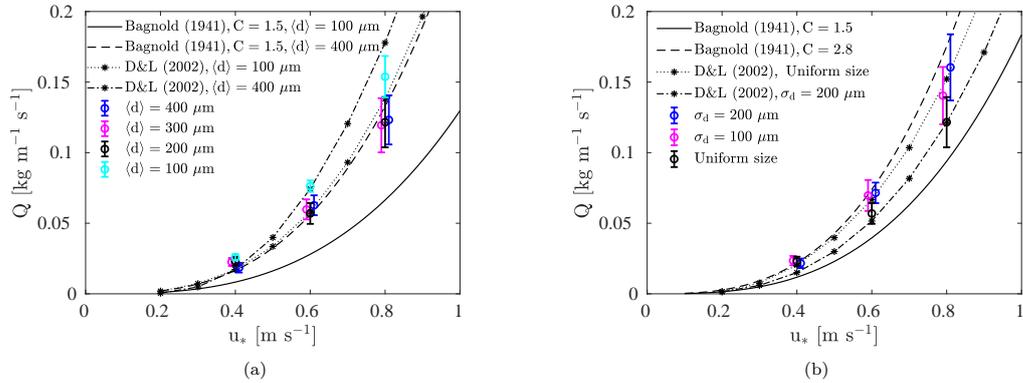


Figure 7. Integrated mass flux obtained with simulations S2 (a) and S3 (b) for u_* equal to 0.4, 0.6 and 0.8 m s^{-1} . Results from simulations S1 obtained with the same u_* are also presented for comparison. To improve readability, some data points are slightly shifted in the u_* axis. The error bar is twice the standard deviation of the results. The curves are obtained from Bagnold’s model (Q_{Bag} in Table 4) and from the numerical model proposed by Doorschot and Lehning (2002) (D&L). In (a), the curves are computed considering a uniform bed characterized by different grain diameters. In (b), both a uniform and a mixed-sized bed with a mean grain diameter of 200 μm are considered.

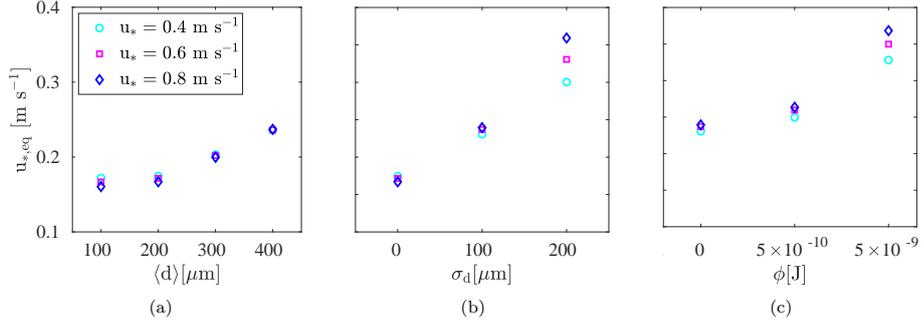


Figure 8. Equilibrium friction velocity obtained with simulations S2 (a), S3 (b) and S4 (c). In (a) and (b), results from simulations S1 are presented for comparison. In (c), results from simulations S3 are presented for comparison.

639 200 μm , a rigorous definition of the saltation layer height is needed to fully assess the
 640 impact of the mean diameter on the integrated mass flux in saltation.

641 The equilibrium surface friction velocity varies considerably with the mean grain
 642 size. In Figure 8a, an increase of $u_{*,eq}$ is observed when $\langle d \rangle$ increases for values greater
 643 than 200 μm , which is consistent with the results of Kok and Renno (2009). For a given
 644 u_* , the total momentum transfer from the fluid to the particles decreases for greater grain
 645 diameters. This is partly due to a smaller number of particles aloft, which overcomes the
 646 increase in drag applied on each grain.

647 4.3 The effect of mixed-sized grains

648 In order to model saltation over a bed of mixed-sized grains, the size distribution
 649 of surface grains is described by a lognormal distribution. In this section, the results from
 650 simulations S3, obtained with different standard deviations of the grain diameter, are
 651 presented and compared with those from simulations S1, obtained with a uniform grain
 652 size.

653 The vertical profiles of particle mass flux, concentration and mean streamwise ve-
 654 locity are presented in Figures 2g-i. Grain size heterogeneity leads to a greater mean par-
 655 ticle streamwise velocity, both near the surface and at higher elevations (Figure 2i). This
 656 is due to an increase in the number of smaller particles aloft, which are easily accel-
 657 erated by the fluid flow. Similarly to Figure 2f (simulations S2), the variation of particle
 658 speed close to the surface with u_* is negligible; however, a clear variation with the bed
 659 characteristics is observed.

660 Figures 2g and 2h show that grain size heterogeneity decreases particle mass flux
 661 and concentration close to the surface but leads to greater values at higher elevations
 662 of the saltation layer. The vertical profiles of particle mass flux obtained for $u_* = 0.4 \text{ m s}^{-1}$
 663 are presented in logarithmic scale in Figure 6b. As expected, close to the surface, an ex-
 664ponential decay across the saltation layer is observed. At higher elevations, a cloud of
 665suspended grains forms above the saltation layer of mixed-sized beds and a second dis-
 666tinct exponential decay of the mass flux along the height is observed. The transition from
 667saltation to suspension occurs at approximately 12 cm and is characterized by the change
 668in gradient of the mass flux profiles. This trend was previously observed in field mea-
 669surements (Gordon et al., 2009) and other numerical models (e.g., Nemoto & Nishimura,
 6702004).

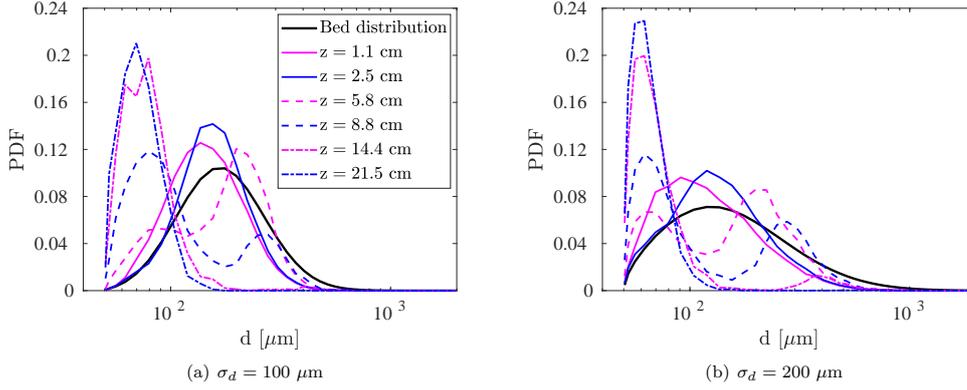


Figure 9. Probability density function (PDF) of particle size at the bed and at different heights obtained from simulations S3 considering $u_* = 0.4 \text{ m s}^{-1}$.

671 The probability density function (PDF) of particle size at different heights is pre-
 672 sented in Figure 9 for $u_* = 0.4 \text{ m s}^{-1}$ and both size distributions (σ_d of 100 and 200
 673 μm). The PDF of particle size at the bed is also presented for comparison (the left tail
 674 of the distribution is not obtained, as a minimum grain size of $50 \mu\text{m}$ is specified in the
 675 simulations). Below approximately 3 cm height, the size distribution of particles aloft
 676 is reasonably well approximated by a lognormal distribution. It is similar to the PDF
 677 at the bed, but skewed towards smaller grain sizes. From 5 to 10 cm height, a bi-lognormal
 678 distribution is visible in both simulations. In this region, for progressively greater heights,
 679 the probability density of smaller grains increases and the probability density of bigger
 680 grains decreases. Finally, above approximately 14 cm, a new lognormal distribution arises,
 681 characterized by grains smaller than $100 \mu\text{m}$. The presented variation of particle size dis-
 682 tribution with height agrees well with the results of Nemoto and Nishimura (2004) and
 683 is related to the saltation-suspension transition observed in Figure 6b.

684 Figure 9b shows that a wider lognormal bed size distribution leads to smaller grain
 685 sizes in the first centimeters above the surface. Smaller grains and less particles aloft jus-
 686 tify the decrease in mass flux close to the surface observed in Figure 6b. Moreover, the
 687 fraction of grains within the range 200 to $500 \mu\text{m}$ present between 8 and 15 cm height
 688 is greater. Considering that these particles are transported in saltation, this is in agree-
 689 ment with the increase in saltation layer height observed in Figure 6b.

690 The integrated mass flux is presented in Figure 7b. The simulation results are com-
 691 pared with Bagnold’s model, considering different values for the parameter C (Bagnold,
 692 1941), and with the results of the numerical model proposed by Doorschot and Lehning
 693 (2002). In the latter, particle size is assumed uniform ($\langle d \rangle = 200 \mu\text{m}$) or defined
 694 by a lognormal distribution ($\langle d \rangle = 200 \mu\text{m}$, $\sigma_d = 200 \mu\text{m}$). In general, the integrated
 695 mass flux obtained with the current model increases with bed heterogeneity. This trend
 696 is also predicted by Bagnold (1941). However, it contrasts with the evolution obtained
 697 with the model of Doorschot and Lehning (2002), in which Q decreases when the bed
 698 heterogeneity increases. The effect of bed size distribution on the integrated mass flux
 699 underlines the importance of correctly describing particle size when estimating snow salta-
 700 tion mass flux. According to the simulation results, this is particularly relevant when u_*
 701 is greater than 0.4 m s^{-1} . Even though a rigorous definition of the saltation layer height
 702 is not taken in this work, similar trends are obtained when the integration height is lim-
 703 ited to the first 10 cm. Moreover, the effect of bed heterogeneity on the computed in-
 704 tegrated mass flux is even more significant if the suspension layer is taken into account.
 705 The integrated mass flux obtained for a uniform bed of grains with $100 \mu\text{m}$ in diame-

706 ter is closer to the values obtained for the studied mixed-sized beds, compared to the other
 707 uniform beds with larger grains (Figure 7a). However, over the uniform bed with grains
 708 of 100 μm , particles above 1 cm height seem to be transported in suspension (Figure 6a).
 709 Taking also into account that an increase in the mean particle diameter from 200 to 400
 710 μm leads to a negligible variation of Q (Figure 7a), it is in general not possible to cor-
 711 rectly model saltation over a mixed-size bed considering a representative diameter and
 712 equally-sized grains.

713 An increase in bed heterogeneity also leads to an increase in the equilibrium sur-
 714 face friction velocity, $u_{*,eq}$ (Figure 8b). In contrast with the simulations performed over
 715 equally-sized grains, $u_{*,eq}$ slightly increases with u_* . This trend is specially visible for
 716 the results obtained with $\sigma_d = 200 \mu\text{m}$. For a given u_* , the total exchange of momen-
 717 tum from the fluid to the particles decreases for greater standard deviations of the size
 718 distribution. Taking into account that the drag applied on each grain is approximately
 719 proportional to d^2 and that the number of particles aloft does not vary in a monotonous
 720 way with σ_d , the decrease in the momentum exchange is explained by the presence of
 721 particles with diameters smaller than the mean value ($\langle d \rangle = 200 \mu\text{m}$).

722 4.4 The effect of interparticle cohesion

723 We complete the analysis of mixed-sized bed saltation by studying the effect of in-
 724 terparticle cohesion. In this section, the results obtained with simulations S4 are pre-
 725 sented. A bed of mixed-sized grains characterized by a lognormal distribution with $\langle d \rangle =$
 726 200 μm and $\sigma_d = 100 \mu\text{m}$ is considered. The results are compared with those from sim-
 727 ulation S3, that were performed with the same particle size distribution but neglecting
 728 interparticle cohesion.

729 The vertical profiles of particle mass flux, concentration and mean streamwise ve-
 730 locity are presented in Figures 2j-l. As cohesion energy increases, the mass flux and par-
 731 ticle concentration decrease close to the surface and increase at higher regions of the salta-
 732 tion layer (Figures 2j,k). Particle mean streamwise velocity increases with cohesion en-
 733 ergy at all heights (Figure 2l). As expected, close to the surface, a negligible variation
 734 of particle streamwise velocity is obtained for different u_* ; however, a clear variation with
 735 interparticle cohesion is seen. Hence, the decrease in mass flux near the surface is due
 736 to a strong reduction in the number of particles there and its increase at higher eleva-
 737 tions is justified by the rise of both the number of particles aloft and the particle stream-
 738 wise velocity.

739 The equilibrium friction velocity, $u_{*,eq}$, is presented in Figure 8c. It is expected to
 740 vary with the bed type, and therefore, with the strength of the interparticle bonds. In
 741 fact, $u_{*,eq}$ increases with the cohesion energy, which was also obtained by Comola, Gaume,
 742 et al. (2019).

743 Cohesion energy has a direct effect on the number of ejected grains computed from
 744 energy conservation, N_E (see equation 8a). If N_E becomes smaller than N_M , the num-
 745 ber of ejected grains is restricted by energy conservation and it decreases for increasing
 746 values of ϕ . Hence, for the same impact velocity and impacting grain diameter, the num-
 747 ber of splashed grains reduces with cohesion energy (Comola & Lehning, 2017). Our re-
 748 sults suggest that this leads to a global decrease in the number of particles aloft. As a
 749 result, for greater values of cohesion energy, the total momentum transfer from the fluid
 750 to the particles is smaller (Figure 8c), as well as the consequent decrease in streamwise
 751 wind speed. This leads to a general increase in particle speed. The initial velocity at which
 752 the splashed grains are ejected from the bed does not vary directly with interparticle co-
 753hesion (see distribution characteristics presented in Table 1). However, greater impact
 754 velocities lead to higher ejection velocities.

755 The integrated mass flux is presented in Figure 10. The results obtained with the
 756 saltation models proposed by Pomeroy and Gray (1990), Doorschot and Lehning (2002)
 757 and Sørensen (2004) are also presented for comparison. These models are currently used
 758 in atmospheric models, such as RACMO (Lenaerts et al., 2012), MAR (Amory et al.,
 759 2015), Alpine3D (Lehning et al., 2008) and Meso-NH (Vionnet et al., 2014), to estimate
 760 snow saltation mass flux. The expressions proposed by Pomeroy and Gray (1990) and
 761 Sørensen (2004) are plotted for two limiting values of the impact threshold: obtained with
 762 simulation S3, $\sigma_d = 100 \mu\text{m}$ (non-cohesive bed) and with simulation S4, $\phi = 5 \times 10^{-9}$
 763 J. As previously explained, in this work, the impact threshold is assumed equal to the
 764 equilibrium friction velocity at the lowest value of u_* that was studied ($u_* = 0.4 \text{ m s}^{-1}$).
 765 The results obtained with the model developed by Doorschot and Lehning (2002) are
 766 derived considering a lognormal bed size distribution with $\langle d \rangle = 200 \mu\text{m}$ and $\sigma_d = 100 \mu\text{m}$.

767 The simulation results indicate that Q varies significantly with the cohesion energy.
 768 In general, it decreases with ϕ for lower friction velocities and increases with ϕ for greater
 769 values of u_* . This is due to the reduction of particle mass flux close to the surface and
 770 to its increase at higher elevations as cohesion energy increases (Figure 2j). At low fric-
 771 tion velocities ($u_* = 0.4 \text{ m s}^{-1}$), the reduction of particle mass flux close to the sur-
 772 face prevails, while at greater u_* , the rise in mass flux at higher elevations becomes more
 773 significant, leading to a global growth of the integrated mass flux. A better agreement
 774 between the expression proposed by Sørensen (2004), using the parameters proposed by
 775 Vionnet et al. (2014), and the simulation results is obtained when interparticle cohesion
 776 and a lognormal size distribution are considered. This is, when considering a more real-
 777 istic snow bed. Nonetheless, greater values for Q are predicted with $Q_{S\phi}$. An overes-
 778 timation of the integrated mass flux in saltation is consistent with the overestimation
 779 of blowing snow particles obtained by Vionnet et al. (2014). The effect of the impact thresh-
 780 old on $Q_{S\phi}$ is mainly visible at lower friction velocities. At $u_* = 0.4 \text{ m s}^{-1}$, the adjust-
 781 ment of the impact threshold improves the agreement between model and simulation re-
 782 sults obtained with different values for cohesion energy. The results obtained with the
 783 numerical model of Doorschot and Lehning (2002) agree well with the simulation results
 784 obtained with mixed-sized and cohesionless grains or $\phi = 10^{-10} \text{ J}$, over the whole range

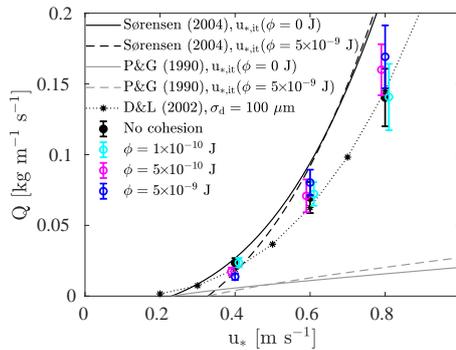


Figure 10. Integrated mass flux obtained with simulations S4 for u_* equal to 0.4, 0.6 and 0.8 m s^{-1} . Results from simulations S3 obtained with the same size distribution and u_* are also presented for comparison. To improve readability, some data points are slightly shifted in the u_* axis. The error bar is twice the standard deviation of the results. The expressions proposed by Sørensen (2004) and Pomeroy and Gray (1990) (P&G) are plotted for comparison considering different values of the impact threshold. The results from Doorschot and Lehning (2002) (D&L) are obtained for a bed characterized by a lognormal distribution with $\langle d \rangle = 200 \mu\text{m}$ and $\sigma_d = 100 \mu\text{m}$.

785 of the studied friction velocities. Even though a good agreement is also obtained over
 786 a bed of uniform grains for $u_* < 0.6 \text{ m s}^{-1}$ (Figure 5b), the effect of mean grain diam-
 787 eter and bed heterogeneity on the integrated mass flux predicted by Doorschot and Lehn-
 788 ing (2002) is not consistent with the evolution obtained by the present model (Figure
 789 7). The expression proposed by Pomeroy and Gray (1990) considerably underestimates
 790 the integrated mass flux in comparison with the simulation results and remaining mod-
 791 els, independently of the assumed values for the impact threshold. The underestimation
 792 of the saltation mass flux might be one of the causes for the underestimation of blow-
 793 ing snow mass flux obtained by Amory et al. (2015).

794 5 Conclusions

795 The modeling of snow saltation is particularly challenging due to the metamorphic
 796 nature of snow. Depending on the meteorological conditions, snow grains can have mul-
 797 tiple shapes and sizes and form interparticle ice bonds between them. During snow trans-
 798 port, the interparticle bonds break and snow particles shape and size change due to frag-
 799 mentation and sublimation. However, snow saltation models used in mesoscale models
 800 generally neglect these particularities, leading to uncertainties in the estimated mass flux
 801 that are difficult to quantify. In this work, an LES-based model coupled with state-of-
 802 the-art splash functions is used to simulate the complex particle-wind-bed interactions.
 803 This approach allows the modeling of steady state saltation over a variety of bed types
 804 and the analysis of the effect of grain size and interparticle cohesion on saltation dynam-
 805 ics.

806 The numerical model is able to simulate the main saltation characteristics observed
 807 in previous models and experiments: the focus point in the average streamwise wind pro-
 808 files, an average streamwise particle speed close to the surface invariant with respect to
 809 the friction velocity, the exponential decay of particle mass flux with increasing height,
 810 and the scaling of the integrated mass flux with the square of the friction velocity. More-
 811 over, as expected, for friction velocities sufficiently greater than the fluid threshold, the
 812 resulting steady state is characterized by a dynamic equilibrium between splash and de-
 813 position. Over mixed-sized beds, different particle size distributions are obtained depend-
 814 ing on the distance to the snow surface, as expected when transition from saltation to
 815 suspension occurs.

816 The relative importance of snow bed characteristics on saltation dynamics is an-
 817 alyzed by varying the particle size distribution and interparticle bond strength in a sys-
 818 tematic way. Bed characteristics, as grain size and interparticle cohesion, significantly
 819 influence saltation dynamics, in particular, particle speed, surface friction velocity and
 820 integrated mass flux. Particle speed close to the surface is approximately invariant with
 821 respect to the friction velocity for all beds that were considered; however, it varies with
 822 the bed type. This is relevant for the development of simple saltation models, which are
 823 usually based on an assumption for the near surface particle speed. The average surface
 824 friction velocity during steady state saltation, defined here as the equilibrium friction ve-
 825 locity, increases for greater values of the mean grain diameter, standard deviation of the
 826 size distribution and interparticle cohesion. The equilibrium friction velocity is tightly
 827 correlated with the impact threshold, which is an important parameter to estimate salta-
 828 tion mass flux. Over uniform beds, a negligible variation of the integrated mass flux with
 829 particle size is obtained for particles ranging between 200 and 400 μm . When consid-
 830 ering a mixed-sized bed characterized by a lognormal distribution, an increase in the in-
 831 tegrated mass flux is seen due to an average increase in particle speed and concentra-
 832 tion. The results presented highlight that the integrated mass flux over mixed-sized beds
 833 can be hardly reproduced by an equally-sized bed with a representative mean diameter
 834 - a tempting assumption in simple saltation models. The integrated mass flux also varies
 835 with interparticle cohesion, but in a non-monotonous way: it decreases with the strength
 836 of interparticle bonds for lower friction velocities and it increases for higher friction ve-

837 locities. Overall, greater values of cohesion lead to a reduction in the number of parti-
838 cles aloft which, at high wind speeds, is balanced by an increase in particle speed. In gen-
839 eral, the greater the friction velocity, the greater the effect of bed properties on salta-
840 tion characteristics. High wind speed events might be rare in some regions. However,
841 they are responsible for major modifications of the snow cover.

842 The agreement between simulation results and the saltation models typically used
843 in large scale atmospheric models depends on the bed characteristics. For specific bed
844 types, a relatively good agreement can be obtained with the models of Sørensen (2004),
845 using the parameters proposed by Vionnet et al. (2014), and Doorschot and Lehning (2002).
846 However, these models either consider fixed parameters, which are not adjustable to the
847 snow type, or predict a different variation of the integrated mass flux with the mean grain
848 size and bed heterogeneity. A systematic underestimation and overestimation of the in-
849 tegrated mass flux is obtained with the expression proposed by Pomeroy and Gray (1990)
850 and Sørensen (2004), respectively. This might partly justify the underestimation and over-
851 estimation of blowing snow mass flux presented, respectively, by Amory et al. (2015) and
852 Vionnet et al. (2014).

853 Further efforts must be made to fully model the effect of bed characteristics on snow
854 saltation. For example, interparticle cohesion is also expected to influence particle ejection
855 velocity during splash and the fluid threshold for the onset of aerodynamic entrainment
856 (Comola et al., 2021). Moreover, the strength of interparticle bonds between grains
857 that did not leave the surface and between those that failed to rebound might not be the
858 same. From the experimental work side, a correlation between interparticle cohesion and
859 meteorological conditions or measurable snow properties like snow density or snow hard-
860 ness is still needed. In addition, exhaustive direct comparisons between simulation re-
861 sults and experimental measurements of snow saltation must be performed to complete
862 model validation. In order to better access the model inner parameters, further studies
863 of the splash process over natural snow beds are required, as well as detailed field mea-
864 surements characterizing both the wind speed, the snow bed and the particles in salta-
865 tion.

866 Simple and computationally inexpensive saltation models are much needed in mesoscale
867 models. However, the in depth study of snow saltation is necessary to fully understand
868 the implications of the simplifying assumptions that are used and to estimate the errors
869 they might introduce. This article shows the capabilities of an LES-based model to sim-
870 ulate snow saltation, presents the effect of bed properties on saltation dynamics and mo-
871 tivates further studies in this field. It highlights the limitations of the snow saltation mod-
872 els currently employed in mesoscale models and the need for improved ones that take
873 into account the effect of snow surface characteristics. Without accurate estimations for
874 the mass flux in saltation, climatological models do not reasonably estimate blowing snow
875 transport and sublimation. Hence, their effect on large scale mass and energy balances
876 is highly compromised.

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884 <https://enacshare.epfl.ch/djzTaD3YGc9HBkdqA2MCt> in csv format. The results will
885 be uploaded to the repository www.envidat.ch before acceptance.

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