

# Comparison of biotite elastic properties recovered by spherical nanoindentations and atomistic simulations - influence of nano-scale defects in phyllosilicates

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## Abstract

Phyllosilicate minerals, due to their sheets structure and morphology, are known to cause anisotropy in bulk rock properties and make the bulk rock more compliant. Accurately characterizing the micromechanical behavior of phyllosilicate minerals from laboratory observations, which eventually translates to the bulk rock behavior, is still challenging due to their fine-grained nature. Recent advances in atomistic simulations open the possibility of theoretically investigating such mineral mechanical behavior. We compare the elastic properties of biotites recovered by spherical nanoindentation with those predicted from density functional theory (DFT) simulations to investigate to what extent theoretical predictions reproduce actual phyllosilicate properties. Spherical nanoindentation was conducted using schist rocks from Poorman Formation, South Dakota, USA, to recover continuous indentation stress-strain curves. Loading in the layer-normal orientation shows an average indentation modulus ( $M$ ) of about 35 GPa, while loading in the layer-parallel orientation gives a higher average of about 95 GPa. To facilitate comparison, the elastic stiffness constants ( $c_{ij}$ ) determined from DFT were converted to indentation modulus ( $M$ ) using solutions proposed in this study. The majority of the nanoindentation modulus results are below the values inferred from the simulation results representing ideal defect-free minerals. We suggest that crystal defects present at the nano-scale, potentially ripplacations, are the dominant cause of the lower indentation modulus recovered from nanoindentation compared to those inferred from DFT simulations. Results highlight the importance of acknowledging the defects that exist down to the nano-scale as it modifies the mechanical properties of phyllosilicates compared to its pure defect-free form.

1 **Comparison of biotite elastic properties recovered by spherical nanoindentations and**  
2 **atomistic simulations - influence of nano-scale defects in phyllosilicates**

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9 **Key Points:**

- 10 • Elastic modulus of cleavage-free biotites, and their anisotropy, were measured using  
11 spherical nanoindentation.
- 12 • Density functional theory (DFT) was used to calculate the elastic stiffness constants of  
13 biotite polytypes.
- 14 • Modulus from nanoindentation were persistently lower than DFT prediction suggesting  
15 the prevalence of nano-scale crystal defects.  
16

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37 mechanical properties of phyllosilicates compared to its pure defect-free form.

## 38 1 Introduction

39 As one of the most common minerals composing felsic to intermediate rocks,  
40 phyllosilicate minerals oftentimes hold an important control on the mechanical behavior of  
41 rocks. Due to their sheet structure, morphology, and the porous aggregate they form in  
42 sedimentary rocks, phyllosilicate minerals, including clays, micas, chlorites, and serpentine  
43 groups, are known to cause anisotropy in the bulk rock properties and make rocks more  
44 compliant and weaker with increasing phyllosilicate content. Phyllosilicates are also abundant in  
45 fault rocks and are believed to impose critical limits on the strength of crustal faults zones.  
46 Recently, the ductility of clay minerals in rocks is also receiving increasing attention because of  
47 its influence on productivity from hydrocarbon source rocks (e.g., shale gas, tight oil) (Dembicki  
48 and Madren, 2014), its ability to seal fractures (e.g., waste disposal) (Bock et al., 2010; Ingram  
49 and Urai, 2015), and ability to locally modify stress (Gunzberger and Cornet, 2007; Sone and  
50 Zoback, 2014b). However, studies on mechanical properties of clay minerals, or phyllosilicates  
51 minerals in general, are mostly limited to the bulk behavior of the clay-rich rocks because of the  
52 challenges in making quantitative measurements on fine-grained rocks at the grain scale. For  
53 example, with the exception of few studies on single crystal mica samples (Kronenberg et al.,  
54 1990), the micromechanics of how clay minerals promote plastic creep deformation of rocks is  
55 still described only phenomenologically (Sone and Zoback, 2014a; Trzeciak et al., 2018;  
56 Haghghat et al., 2020), and it is not understood whether inter-granular sliding or intra-granular  
57 deformation accommodates creep of clay-rich rocks. The mechanical properties of the  
58 phyllosilicates itself, as well as the micromechanics of how the mechanical behavior of  
59 phyllosilicates translates to the bulk rock behavior, is still a topic in need of further studies. Thus,  
60 reliable and quantitative techniques to observe the mechanical behaviors of clay minerals at the  
61 microscale are needed.

62 Several methods have been used to study the mechanical properties of phyllosilicate  
63 minerals, such as the acoustic method, Brillouin scattering method, multiple regression, atomistic  
64 simulation, and nanoindentation. The earliest effort can be traced back to the work of  
65 Aleksandrov and Ryzhova (1961), who derived pseudo-hexagonal or transversely isotropic (TI)  
66 stiffness constant of muscovite, biotite, and phlogopite minerals from ultrasonic techniques.  
67 Vaughan and Guggenheim (1986) measured the 13 elastic stiffness constants of muscovite by  
68 using Brillouin scattering. Militzer et al. (2011) derived a full elastic tensor of illite-smectite,  
69 muscovite, and kaolinite minerals based on density functional theory (DFT). Vyzkva et al.  
70 (2014) estimated the elastic properties of phyllosilicate minerals using multiple regression of a  
71 dataset compiled for various phyllosilicate minerals. A common aspect of these methods is that  
72 they recover moduli of the minerals at small strain magnitudes generated by acoustic waves or  
73 small perturbations in the model, which is orders less than the strain magnitude involved in static  
74 deformation of rocks relevant to various engineering settings.

75 Recent advancements of nanoindentation techniques have allowed the investigation of  
76 elastic moduli of single phyllosilicate grains at strain magnitudes relevant to static deformation.  
77 Zhang et al. (2009) used nanoindentation to study muscovite and rectorite, followed by studies  
78 on various 2:1 phyllosilicates (Zhang et al., 2010) and biotites (Lanin et al., 2019). These studies  
79 utilize the Berkovich indenter in which elastic moduli are extracted from the unloading phase of  
80 the experiment. An occasional shortcoming of the Berkovich indenter is that they introduce  
81 plastic deformation during the loading phase, before the unloading phase, which results in crack  
82 development around the indentation when working with brittle materials. Such cracking appears  
83 as the sudden increase in indentation depth without load increase in the loading phase known as  
84 pop-ins (Zhang et al., 2009; Lanin et al., 2019). These cracks can alter the effective elastic  
85 properties of the mineral volume investigated by the indenter, thus resulting in lower elastic  
86 moduli than the pure undamaged mineral (see comments from Bobko et al. 2009).

87 Meanwhile, the use of a spherical indenter helps to overcome these problems of a  
88 Berkovich indenter. Spherical indenters create less stress concentrations, thus less tendency for  
89 crack damage, and also allow the application of Hertz's contact theory (Hertz, 1881). More  
90 studies are utilizing spherical indenters to recover stress-strain data of the crack-free sample  
91 during the loading phase where deformation is purely elastic, as demonstrated by recent studies  
92 (Basu et al., 2009; Pathak and Kalidindi, 2015).

93 Another class of approach is to theoretically investigate the behavior of materials through  
94 atomistic modeling (e.g., molecular dynamic, density functional theory). These simulations allow  
95 one to study the mechanical behavior of materials that are otherwise difficult to recover due to  
96 technical and sample limitations in the laboratory. Modeling techniques are allowing us to  
97 directly study the dislocation processes, in some cases recovering estimates of activation  
98 energies for deformation (Yamakov et al., 2002; Domain and Monnet, 2005). However, careful  
99 discussion on the similarities and differences between modeled and actual materials is essential  
100 to properly extrapolate findings from the atomistic scale to the problem of interest.

101 In this study, we specifically focus on studying the behavior of biotite, as one example of  
102 a phyllosilicate, from nanoindentation tests using spherical indenter and density functional theory  
103 (DFT) simulations. Our objectives are to compare the anisotropic elastic properties of biotite  
104 measured by nanoindentation and estimated by atomistic simulations and also to understand the  
105 agreement and disagreement between the two approaches. Biotite minerals found in a low-  
106 porosity schist rock are used in the indentation study to ensure control over the orientation of the

107 minerals. We first describe the experimental materials, the nanoindentation tests conducted, and  
108 the data analysis. We then describe the method and results of the atomistic simulations. Finally,  
109 we discuss the indentation modulus parameter, comparison between experiment and simulation  
110 results, and the possible cause of those differences.

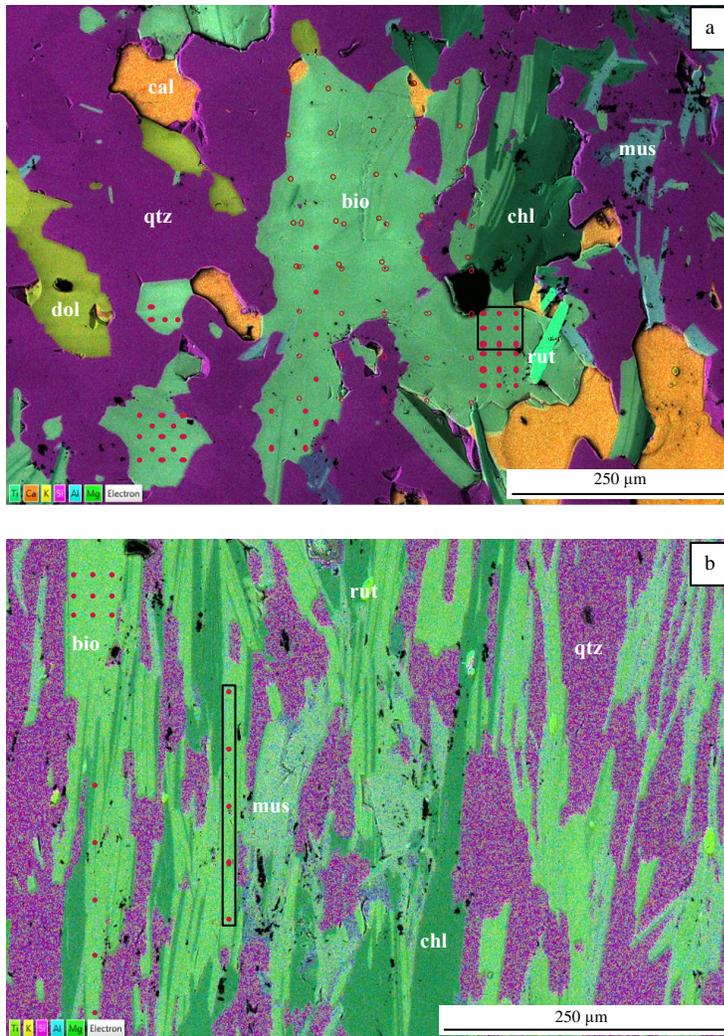
## 111 **2 Experimental materials and methods**

### 112 2.1 Materials

113 The samples used in this study were schist rocks from the Poorman Formation collected  
114 from the Sanford Underground Research Facility (SURF), South Dakota, USA, collected under  
115 the KISMET project (Oldenburg et al., 2016, 2017), same as those used by (Vigilante et al.,  
116 2017). The rocks used in this study are characterized as a biotite-quartz-carbonate phyllite to  
117 schist (Caddey et al., 1991) also including chlorite and minor amounts of muscovite and rutile.  
118 These schist rocks were chosen because of their low porosity (less than 1%) and the large biotite  
119 grains (~100 microns) in the rock that allows us to probe single crystal properties. The presence  
120 of the biotite minerals within a rigid matrix, as opposed to a compliant micro-porous matrix of a  
121 lower-grade diagenesis rock, makes these schist rocks suitable for recovering the true mechanical  
122 properties of the biotite grains. Visual observation under a scanning electron microscope (SEM)  
123 shows that the biotite grains appear to be free of visible impurities and free of cleavages parallel  
124 to the (001) plane (Figure 1). These schist rocks also exhibit a well-defined and consistent  
125 foliation fabric visible to the eye, to which the biotite grains are aligned, which made it easier to  
126 control the orientation of the exposed biotite faces to study its anisotropy.

127 Two sets of small rectangular samples were prepared, whose largest faces were oriented  
128 parallel to the foliation (layer-normal loading) and perpendicular to the foliation (layer-parallel  
129 loading), and fixed in resin. The samples were then ground using sandpaper with different grit  
130 sizes, sequentially from 180, 320, 600, to 1200 grits. The ground surfaces were then polished  
131 using abrasives of 6  $\mu\text{m}$ , 1  $\mu\text{m}$  (diamond suspension), 0.5  $\mu\text{m}$  (colloid alumina), and 0.04  $\mu\text{m}$   
132 (colloidal silica suspension) grain sizes, followed by inspections under the microscope after each  
133 polishing step to ensure no scratches were remaining from the previous polishing step. The  
134 sample preparation is completed by identifying the area of interest under an optical microscope  
135 and marking the area by giving a scratch mark. Then the exact positions of the mineral crystals  
136 of interest are identified under the SEM, as well as their relative position to the scratches so that  
137 the nanoindenter could later correctly probe the mineral crystals of interest.

138 The minerals within the area of interest were identified using Backscattered-Electron  
139 (BSE) imaging, point-shoot Energy-Dispersive X-ray Spectroscopy (EDS), EDS scanned  
140 images, and BSE-EDS stacked images. Two representative BSE-EDS images of layer-normal  
141 and layer-parallel loading samples used in the nanoindentation test are shown in Figure 1. As  
142 shown in Figure 1, the BSE-EDS image allows us to discriminate the biotite, chlorite, and  
143 muscovite layers down to the micron-scale, which are otherwise difficult to distinguish.



144

145 Figure 1 BSE-EDS stacked image of (a) layer-normal loading and (b) layer-parallel-loading.  
 146 Abbreviations denote mineral names (bio=biotite, cal=calcite, chl=chlorite, dol=dolomite,  
 147 mus=muscovite, qtz=quartz, rut=rutile). The circle markers represent the location where  
 148 nanoindentation was performed. The squares show the dataset that recovered anomalously high  
 149 and low modulus values in panel a and b, respectively.

## 150 2.2 Nanoindentation tests

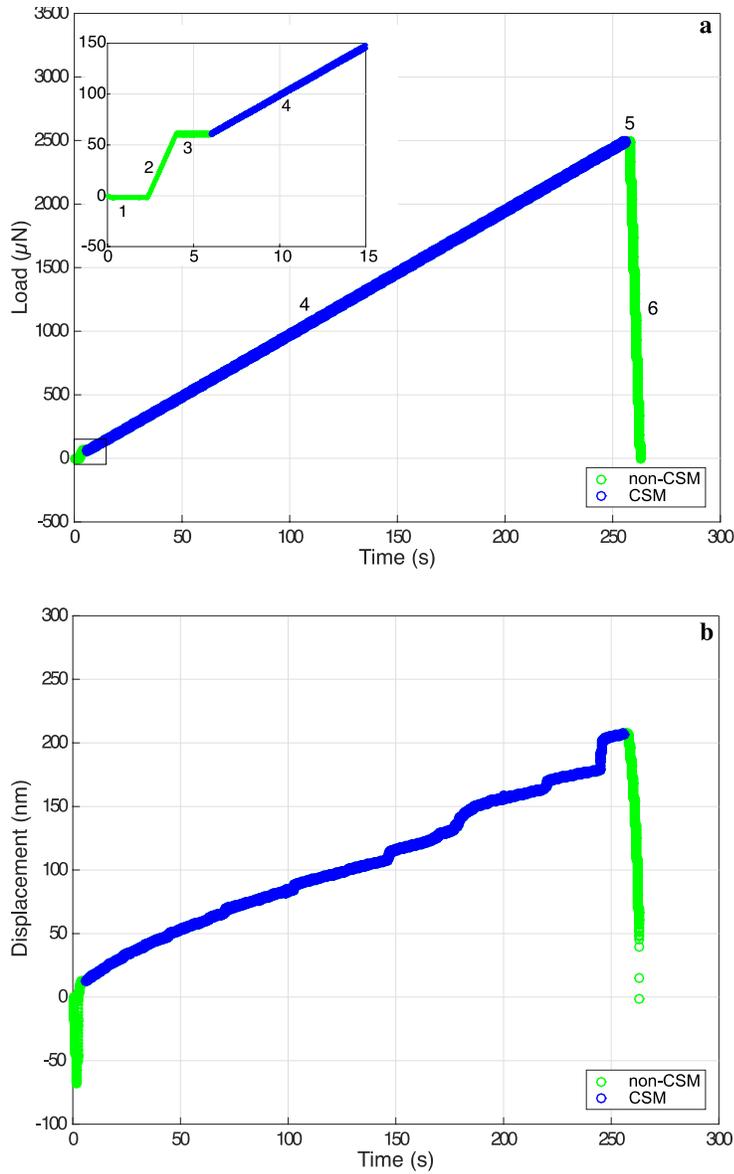
151 Nanoindentation was carried out in areas of interest identified based on observations of  
 152 the BSE-EDS image. Using the Hysitron TI-950 TriboIndenter capable of providing continuous  
 153 stiffness measurement (CSM), the tests were performed at room temperature, in load-control  
 154 mode, with maximum applied loads of 2-2.5 mN. Two diamond spherical indenters were used in  
 155 these tests, whose tip radiuses were either 1 or 5  $\mu\text{m}$ , with Young's modulus of  $1.14 \times 10^3$  GPa  
 156 and Poisson's ratio 0.007. The two tip radiuses were used to check whether one of the radii  
 157 produces a better result in recovering elastic property compare to the other. In either case, results  
 158 were screened, as explained later, so that only those recovering the proper elastic behavior is  
 159 reported. Additionally, to understand the consistency and variability in the measurement results,  
 160 indentation was performed in a grid pattern around the area of interest. To avoid interference

161 between measurements, the grid interval was chosen to be greater than the indentation effect,  
162 which is approximately 2.4 times the indenter radius (Kalidindi and Pathak, 2008).

163         Until recently, majority of nanoindentation tests on rock-forming minerals were carried  
164 out using Berkovich indenters (e.g., Broz et al., 2006; Whitney et al., 2007; Zhang et al., 2009,  
165 2010), with emphasis on extracting modulus and hardness values from the unloading mechanical  
166 data. However, since Berkovich indenters possess corners, nanoindentation tests using this type  
167 of indenters oftentimes result in brittle deformation almost instantaneously as soon as loading  
168 begins. Therefore, the information from the purely elastic mechanical response is not recovered,  
169 as well as the transition to the plastic regime. These problems can be mitigated using spherical  
170 indenters, where deformation at the purely elastic region and elastic-plastic transition can be  
171 observed by continuously measuring the contact stiffness and constructing the indentation stress-  
172 strain curves. Using Hertzian theory, contact stiffness measurements and the construction of  
173 indentation stress-strain curves can be carried out either with the use of multiple loading-  
174 unloading measurements (Field and Swain, 1996; Pathak et al., 2009) or with the use of the CSM  
175 technique (Herbert et al., 2001; Basu et al., 2006; Kalidindi and Pathak, 2008).

176         CSM is a technique carried out by superimposing, on top of the controlled load, a small  
177 oscillatory load with amplitudes about an order of magnitude lower than the applied load (Li and  
178 Bhushan, 2002). This technique is capable of continuously measuring the contact stiffness during  
179 a monotonic loading phase in a test without the need of carrying out multiple loading-unloading  
180 stages. On the Hysitron TI 950 Triboindenter machine, this CSM capability is referred to as the  
181 Continuous Measurement of X mode (CMX, where X is a mechanical property such as modulus,  
182 hardness, or stiffness), in the nano-Dynamic Mechanical Analysis (nano-DMA) module  
183 (Hysitron, 2014). Hereon, we will refer to the use of this CMX modes as the CSM modes as we  
184 are only interested in the mineral modulus in this study.

185         The experiments for this study were carried out with a linear load control (Linear CSM)  
186 consisting of 6 segments (Hysitron, 2014). As shown in Figure 2, segments 1-3 are the pre-  
187 loading phases, where the indenter contact with the specimen surface is established. The  
188 specimen is loaded in segment 4 using the Linear CSM mode. After the load is held for 2  
189 seconds in segment 5, the specimen is unloaded in segment 6.



190

191 Figure 2 Example of nanoindentation data. (a) load vs. time and (b) displacement vs. time.  
 192 Numbers represent the loading stages (1=hold phase, 2=initial loading phase, 3=hold phase, 4=  
 193 CSM loading phase, 5=hold phase, 6=unloading phase).

194 2.3 Experimental data analysis

195 The current data analysis methods for nanoindentation data are based on Hertz's theory  
 196 (Hertz, 1881; Johnson, 1985). According to Hertz's theory, the contact between two frictionless  
 197 isotropic surfaces can be expressed as,

198

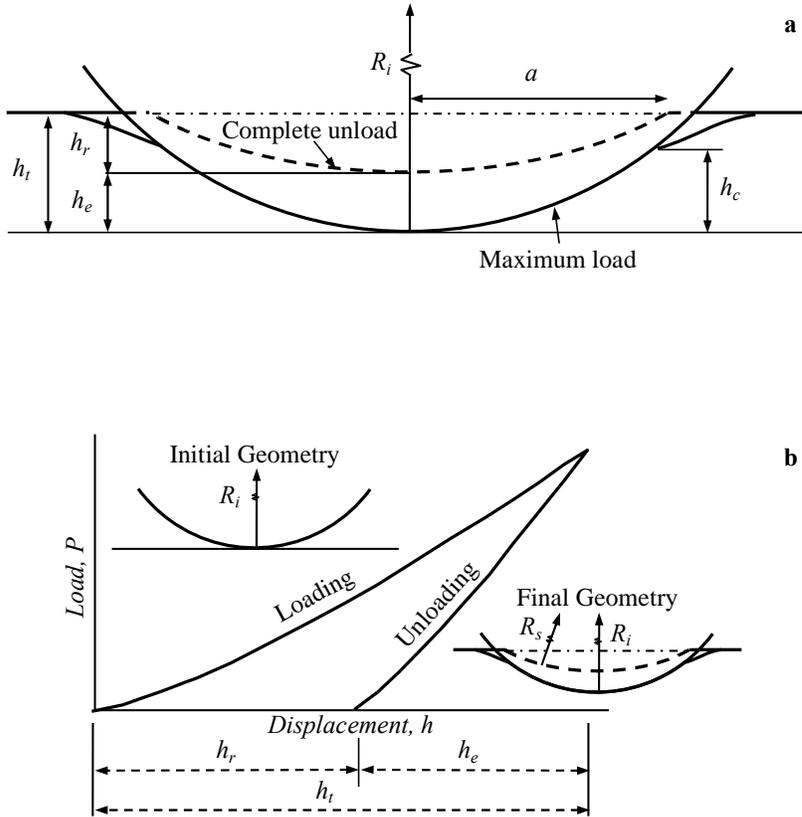
$$P = \frac{4}{3} E_r R_r^{1/2} h_t^{3/2}, \quad a = \sqrt{R_r h_e} \quad (1)$$

199 where  $a$  is the radius of the contact boundary at any given load ( $P$ ),  $h_t$  is the total indentation  
 200 depth, and  $h_e$  is the elastic indentation depth (for a schematic explanation of the parameters used

201 in this paper, please refer to Figure 3).  $E_r$  and  $R_r$  are the reduced modulus and the relative radius  
 202 of indentation curvature, respectively, defined by,  
 203

$$\frac{1}{E_r} = \frac{1 - \nu_s^2}{E_s} + \frac{1 - \nu_i^2}{E_i}, \quad \frac{1}{R_r} = \frac{1}{R_i} + \frac{1}{R_s} \quad (2)$$

204 where  $E$  and  $\nu$  are the Young's modulus and Poisson's ratio, respectively, and the subscripts  $s$   
 205 and  $i$  refer to the sample and indenter, respectively.



206

207 Figure 3 (a) Schematic of the indentation zone of spherical indenters. (b) Typical load-  
 208 displacement curve with the initial and final contact geometry (modified from Kalidindi and  
 209 Pathak, 2008). For the description of each parameter, refer to section 2.3. Experimental Data  
 210 Analysis.

211 In the commonly employed approach described in Oliver and Pharr (1994, 2004), Hertz's  
 212 model is applied to estimate Young's modulus of the tested material from the load-displacement  
 213 curve. In their method, the elastic modulus is obtained from the unloading phase (segment 6),  
 214 which is generally considered to be purely elastic. The reduced modulus is then calculated from  
 215 Eq. (1) as

216

$$E_r = \frac{\sqrt{\pi}}{2} \frac{S}{\sqrt{A}} = \frac{S}{2a}, \quad h_e = \frac{3P}{2S} \quad (3)$$

217 where  $S = dP/dh_e$  is the elastic stiffness, obtained as the slope of the unloading curve at initial  
 218 or near the peak load, and  $A = \pi a^2$  is the projected contact area. However, for reasons described  
 219 in section 2.2, the elastic modulus of the material in this study was determined from data in the  
 220 loading phase (segment 4). Referring to Pathak and Kalidindi (2015), the determination of elastic  
 221 modulus with a spherical indenter involves a two-step process, including zero-point  
 222 determination and construction of indentation stress-strain (ISS) curves.

### 223 2.3.1 Zero-point determination

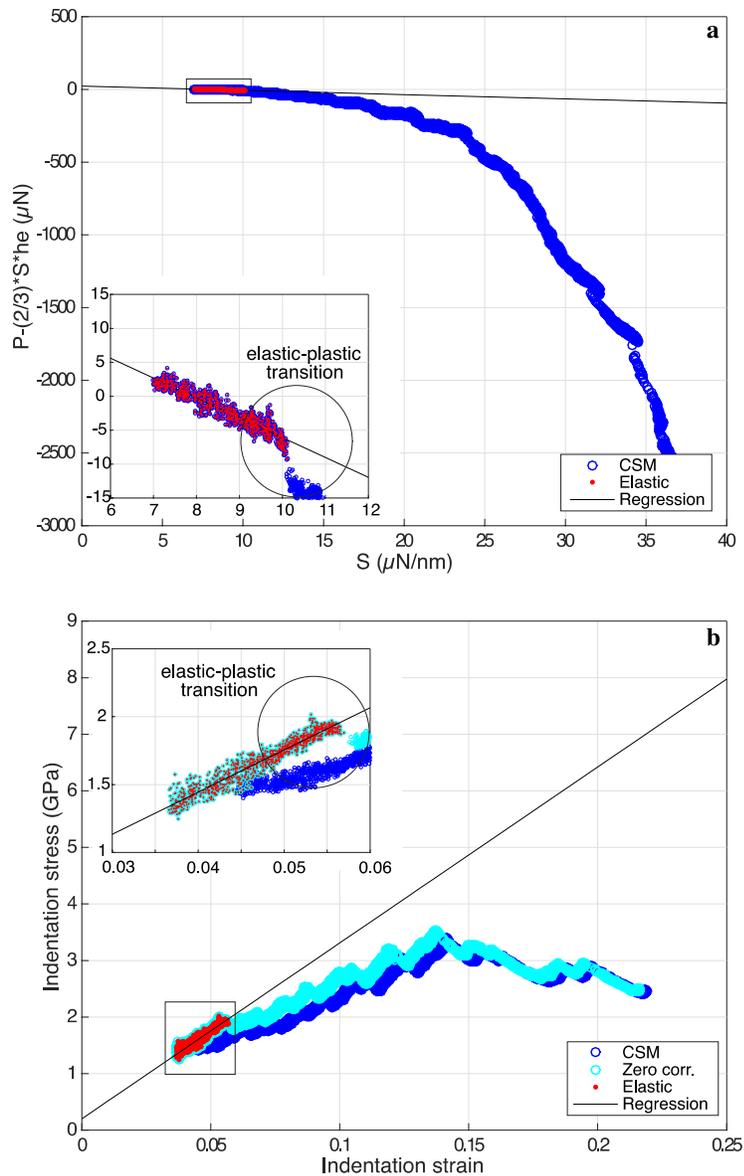
224 Due to the very subtle change in load that occurs as the indenter initially contacts the  
 225 sample (i.e. zero-point), together with other factors that falsely registers load before true contact  
 226 (e.g. vibration, non-flat surface), it is difficult to determine the zero-point from load-  
 227 displacement records. However, the correct identification of the zero-point is crucial for accurate  
 228 determination of the specimen elastic modulus because it influences the estimation of the contact  
 229 radius and the computed ISS significantly, which in turn will strongly affect the resulting elastic  
 230 modulus. Several methods have been proposed by various authors to determine the zero point of  
 231 the load-displacement curve from nanoindentation tests. Methods recently proposed for  
 232 indentation apparatuses using CSM are from Moseson et al. (2008) and Kalidindi and Pathak  
 233 (2008), whereas methods for apparatuses that do not use CSM are proposed by Pathak et al.  
 234 (2009).

235 In the present study, using a nanoindentation machine with CSM capability, the zero-  
 236 point determination was carried out by applying the Hertzian theory to Eq. (3) (Kalidindi and  
 237 Pathak, 2008).

238

$$S = \frac{3P}{2h_e} = \frac{3(P' - P^*)}{2(h_e' - h_e^*)} \quad (4)$$

239 where  $P'$ ,  $h_e'$ , and  $S$  are the measured load, displacement, and stiffness signal, respectively, from  
 240 the CSM mode.  $P^*$  and  $h_e^*$  are the load and displacement of the actual initial contact,  
 241 respectively. By rearranging Eq. (4), one can establish a linear relationship between the  
 242 quantities  $P' - \frac{2}{3}Sh_e'$  and  $S$  where the slope and y-intercept of the linear relationship represent  
 243 quantities  $-\frac{2}{3}h_e^*$  and  $P^*$ , respectively. Note that this relation only holds when the material  
 244 response is still linearly elastic. Thus, by plotting the quantity  $P' - \frac{2}{3}Sh_e'$  against  $S$  recovered  
 245 from the nanoindentation test, one can identify the initial portion of the data where the data  
 246 resembles linear elastic behavior as well as recover the values  $P^*$  and  $h_e^*$  necessary for zero-  
 247 point determination (Figure 4).



248

249 Figure 4 (a) Example of zero-point determination and (b) construction of indentation stress-  
 250 strain. The blue circles show test data before zero correction and the cyan circle after correction.  
 251 The red dots represent data of the elastic region, and the black line describes the linear  
 252 regression.

### 253 2.3.2 Indentation stress-strain (ISS) curves

254 The use of indentation stress-strain curves has been introduced since the early  
 255 development of the indentation technique by Tabor (1951). Indentation stress and strain is useful  
 256 because it allows one to characterize the average stress-strain response of the material in the  
 257 indentation zone although the stress and strain field is heterogeneous within the indentation zone.  
 258 The methodology to extract indentation stress-strain curves from spherical indenter was first  
 259 suggested by Field and Swain (1993). Currently, even though the definition of indentation stress  
 260 is commonly accepted as,

261

$$\sigma_{ind} = \frac{P}{\pi a^2} \quad (5)$$

262 as used in various studies, there are two definitions of contact radius and strain proposed in the  
 263 literature. The first definition is from Basu et al. (2006),

264

$$a = \sqrt{2R_i h_c - h_c^2}, \quad e_{ind} = \frac{4}{3\pi} \left( \frac{a}{R_i} \right) \quad (6)$$

265 which is similar to the one proposed by Herbert et al (2001), while the other definition proposed  
 266 by Kalidindi and Pathak (2008) reads

267

$$a = \left( \frac{3PR_r}{4E_r} \right)^{1/3}, \quad e_{ind} = \frac{4}{3\pi} \left( \frac{h_t}{a} \right) \quad (7)$$

268 where  $\sigma_{ind}$  and  $e_{ind}$  are indentation stress and indentation strain, respectively, and  $h_c = h_t -$   
 269  $\frac{3P}{4S} = h_t - \frac{1}{2}h_e$  is the effective contact depth.

270 The difference between the two definitions of strain and contact radius has been critically  
 271 evaluated by Donohue et al. (2012). Even though the evaluation shows a distinct difference in  
 272 the indentation stress-strain curves after the elastic-plastic transition, they show the same result  
 273 when compared within the elastic regime regardless of the definitions being used. Therefore, for  
 274 simplicity, the calculations of elastic property in this study use the definition by Basu et al.  
 275 (2006) that uses known and directly measured parameters, namely the radius of the indenter,  $R_i$ ,  
 276 and penetration depth,  $h_t$ , as shown in Figure 3.

## 277 2.4 Experimental results

278 As an initial stage in the experimental data analysis, data screening was carried out to  
 279 ensure that each data analyzed represent the elastic properties of biotite. Since the location of the  
 280 indentation could not be controlled perfectly, the indentation locations were rechecked under the  
 281 SEM to see whether the indentation were correctly placed on a biotite crystal or not. Indentation  
 282 points located in other minerals or on the boundary between biotite and other minerals were  
 283 excluded from the analysis. Additionally, further screening was conducted based on the plots of  
 284 indentation stress and strain to check that the end of the elastic region is clearly marked by the  
 285 elastic-plastic transition (Figure 4). Data with no clear elastic-plastic transition were not used in  
 286 determining the elastic properties of biotite. After screening, linear regression to the indentation  
 287 stress-strain data before the elastic-plastic transition allows us to recover the reduced modulus.

288 As a result of the screening process and validation, 48 indentation points in the layer-  
 289 normal orientation and 17 indentation points in layer-parallel orientation were used to determine  
 290 the elastic properties of biotite and the resulting values are shown in Table 1. In order to capture  
 291 the variability of the resulting elastic modulus data from different data groups, we plot each  
 292 indentation data in term of the (elastic) indentation stress and strain value at the elastic-plastic  
 293 transition such that the slope of the line connecting to the origin would resemble the reduced  
 294 modulus measured from each indentation (Figure 5).

295

296

Table 1 Summary of experimental reduced modulus ( $E_r$ ) and indentation modulus ( $M$ )

Orientation	Indenter Radius ( $\mu\text{m}$ )	ID	Number of data		$E_r$ (GPa)		$M$ (GPa)	
			Indentation	Screened	Mean	Sdev	Mean	Sdev
Normal	1	N1-1	9	9	32.8	3.1	33.8	3.3
		N1-2	3	3	31.5	5.3	32.4	5.6
		N1-3	1	1	30.9		31.8	
		N1-4	9	9	32.3	2.3	33.3	2.5
		N1-5	4	4	29.7	2.1	30.5	2.3
		N1-6	4	4	33.0	4.8	34.0	5.1
		N1-7	9	7	51.4	6.1	53.9	6.7
	5	N5-1	9	3	33.6	12.8	34.7	13.6
		N5-2	5	4	31.5	5.4	32.4	5.7
		N5-3	4	4	30.8	7.1	31.7	7.4

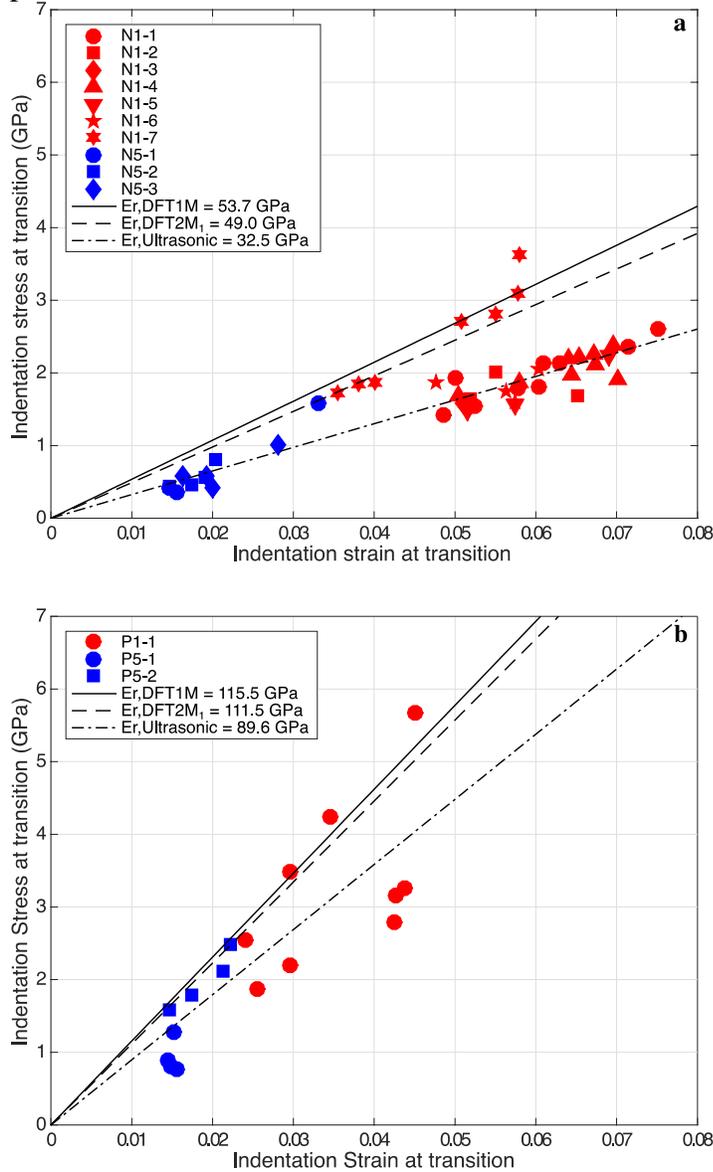
Orientation	Indenter Radius ( $\mu\text{m}$ )	ID	Number of data		$E_r$ (GPa)		$M_s$ (GPa)	
			Indentation	Screened	Mean	Sdev	Mean	Sdev
Parallel	1	P1-1	9	9	92.6	24.8	101.4	29.6
	5	P5-1	5	4	62.4	15.1	66.2	17.1
		P5-2	5	4	105.8	5.2	116.6	6.3

297 For layer-normal loading, both 1  $\mu\text{m}$  and 5  $\mu\text{m}$  indenters showed a fairly consistent  $E_r$   
 298 value of about 32 +/- 5 GPa, except for the N1-7 dataset, which gave an average  $E_r$  of 51 +/- 6  
 299 GPa. Observation of the BSE-EDS image shows that there are no anomalous compositional  
 300 variations seen under this N1-7 dataset, marked with a black box in Figure 1a. The N1-7 dataset  
 301 was obtained close to the mineral boundary that transitions into a chlorite crystal and also  
 302 surrounded by rutile and calcite minerals. Judging from how biotite and chlorite minerals are  
 303 interlayered in Figure 1b, it is possible to speculate that the biotite was thinning towards this  
 304 mineral boundary and potentially reflecting the stiffness of a stiffer underlying mineral  
 305 continuing from the surrounding phases. Whether the anomalously high reduced modulus in N1-  
 306 7 reflects the actual biotite property is unknown from available information.

307 Meanwhile, for the layer-parallel indentations, two datasets show a reduced modulus of  
 308 about 96 +/- 21 GPa while another dataset (P5-1) gives an average of about 62 +/- 15 GPa. BSE-  
 309 EDS image observations were also carried out to look for possible explanations of anomalies in  
 310 this dataset, marked by the black box in Figure 1b. The BSE-EDS image shows that P5-1 is one  
 311 of the two arrays of 5 indentation points which were placed within a thin biotite layer where fine  
 312 inter-layering of biotite and chlorite occurs. A possible speculation is that weak mineral  
 313 boundaries or cleavages unresolved in the BSE-EDS image may have influenced the results  
 314 towards a low elastic modulus, but the reason is unknown from available information.

315 We observe consistently that the elastic limit for the 5  $\mu\text{m}$  indenter data comes at a lower  
 316 indentation stress and strain values compared to the 1  $\mu\text{m}$  indenter data. We interpret this to be  
 317 the result of the larger mineral volume that is probed by the larger indenter. For a given  
 318 indentation strain value, the volume of investigation below the indenter will scale with the cube  
 319 of the indenter tip diameter. Thus, there are greater chances for the 5  $\mu\text{m}$  indenter to encounter

320 pre-existing flaws in the mineral structure, if any, which leads to an earlier onset of plastic  
 321 deformation and pop-ins. However, as long as we properly identify the elastic limit in the  
 322 mechanical data, the reduced moduli values we recover at the elastic limit should not depend on  
 323 the indenter tip radius assuming homogeneous mineral properties. Consistency between results  
 324 from different indenter tip radius confirms that we were able to correctly identify the elastic  
 325 plastic transition in the data.



326

327 Figure 5 Indentation stress and indentation strain values at elastic-plastic transition for (a) layer-  
 328 normal loading and (b) layer-parallel loading. Data from the tests using indenter with a radius of  
 329  $5\ \mu\text{m}$  is represented by a blue marker and  $1\ \mu\text{m}$  by a red marker. The different marker shapes  
 330 depict different dataset groups. The lines describe stress-strain relations predicted by DFT and  
 331 ultrasonic velocity measurements of Aleksandrov and Ryzhova (1961).

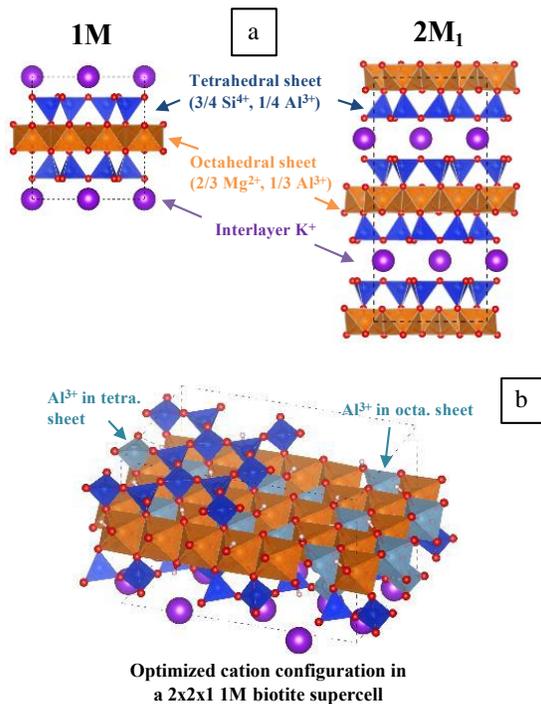
332 Apart from biotite, to check the validity of the method used, analyses were also carried  
 333 out on indentations that fell in quartz minerals. These serve as a quality control for our analysis

334 considering that quartz minerals have nearly isotropic mechanical properties and their physical  
 335 characteristics are widely known from previous studies. The 36 indentations located in quartz  
 336 minerals give an average  $E_r$  value of 83.3 +/- 18.3 GPa. Based on Eq. (2), assuming that the  
 337 Poisson's ratio of quartz is 0.07 (Mavko et al., 2009), this results in an average Young's modulus  
 338 of 89.6 +/- 19.7 GPa. Considering that the Young's modulus of quartz is known to be about 94.5  
 339 GPa (Mavko et al., 2009), our method correctly recovers the known properties of quartz albeit  
 340 with a large standard deviation.

### 341 **3 Atomistic simulation methods and results**

342 To offer a comparison with the nanoindentation measurements, the elastic properties of  
 343 two common biotite polytypes, 1M and 2M<sub>1</sub>, were calculated from density functional theory  
 344 (DFT) simulations. The atomic models of the two polytypes were constructed based on their  
 345 crystal structures determined from X-ray diffraction experiments (Brigatti et al., 2000). As  
 346 shown in Figure 6, the two polytypes have similar clay sheets separated by interlayer K<sup>+</sup>, but  
 347 with different stacking arrangements. In both polytypes, the clay sheets consist of an octahedral  
 348 layer sandwiched between two tetrahedral layers. Diffraction experiments (Brigatti et al., 2000)  
 349 have observed partial cation occupancies in both the octahedral and tetrahedral layers. Based on  
 350 the experimental site occupancies, an ideal chemical composition of K(Mg<sub>2</sub>Al)(Si<sub>3</sub>Al)O<sub>10</sub>(OH)<sub>2</sub>  
 351 was adopted in this study. It should be noted, however, that substitution of Mg by Fe, Ti, Mn,  
 352 etc. can exist in real samples to various degrees.

353



354

355 Figure 6 (a) Biotite polytypes and (b) optimized cation configuration in a 2x2x1 1M biotite  
 356 supercell.

357

## 358           3.1 Simulation method

359           Although diffraction experiments suggested cation distributions in the clay sheets are  
360 disordered, explicit cation configurations were needed for computing elastic properties from  
361 DFT simulations. To this end, the cation arrangements in the clay sheets were first optimized in  
362 classical simulations. This was conducted using General Utility Lattice Program (GULP) (Gale,  
363 1997) and ClayFF (Cygan et al., 2004), a classical force field that has been widely used for clay  
364 mineral simulations. Structural optimizations were performed for randomly generated cation  
365 arrangements in supercells of 1M and 2M<sub>1</sub> polytype structures until no configuration with a  
366 lower energy can be found. Models with the most energetically favorable cation configurations,  
367 found in 2×2×1 and 2×1×1 supercells respectively for 1M and 2M<sub>1</sub>, were used for elastic  
368 property calculations. It should be noted that, although classical simulations using ClayFF offer  
369 accurate predictions for clay structures and energetics, they have been shown to overestimate the  
370 moduli of mica family clays by ~25% (Teich-McGoldrick et al., 2012). As such, the elastic  
371 properties were calculated from DFT simulations, using the atomic models of biotite with  
372 optimized cation arrangement.

373           The DFT simulations were conducted using the Vienna *ab initio* simulation (VASP)  
374 package with the projector-augmented wave pseudopotential of Blöchl (Blöchl, 1994; Kresse and  
375 Furthmüller, 1996). The generalized gradient approximation of Perdew-Burke-Ernzerhof was  
376 employed for the exchange-correlation functional (Perdew et al., 1996). Corrections for the van  
377 der Waals interactions were made with the DFT-D3 method with Becke-Johnson damping  
378 (Grimme et al., 2010, 2011). In all the calculations, the electronic wave function was expanded  
379 using a plane wave basis up to an energy cutoff of 520 eV. K-space meshes were set to ensure  $a$   
380  $\times n_k > 20 \text{ \AA}$ , where  $a$  is the lattice parameter and  $n_k$  is the number of k points along  $2\pi/a$  in the  
381 reciprocal space. This results in a mesh of 2×1×2 for the 221 supercell of 1M. All lattice  
382 parameters and ionic positions were fully relaxed before mechanical property calculations. The  
383 convergence criteria for the energy during self-consistent field calculations and the force  
384 during structural relaxation were set as  $10^{-6}$  eV and 0.005 eV/Å, respectively. The elastic  
385 constants were calculated from the strain-stress relationship determined by relaxing the atomic  
386 positions under finite lattice distortions.

## 387           3.2 Simulation results

388           The elastic properties calculated from DFT simulations are listed in Table 2 together with  
389 those determined from ultrasonic measurements by Aleksandrov and Ryzhova (1961). Due to the  
390 explicit cation arrangements used in the atomic model, the structures deviate slightly from  
391 transverse isotropy. As such, small differences exist for both polytypes between simulated C11  
392 and C22 and related properties. Nonetheless, the elastic properties from DFT simulations are in  
393 good agreement with ultrasonic measurements overall.  
394

395 Table 2 Summary of elastic properties from simulation results and ultrasonic measurements.

Parameters	Density Functional Theory (DFT)		Ultrasonic measurements*
	Biotite 1M	Biotite 2M <sub>1</sub>	Unknown Polytype
C11/C22	189/203	184/186	186
C33	60	56	54
C12	56	30	32.4
C13/C23	24/22	16/19	11.6
C44/C55	18/17	10/8	5.8
C66	71	100	76.8
E11/E22	167/182	204/233	178.6
E33	55	59	52.8
v <sub>12</sub> /v <sub>21</sub>	0.25/0.27	0.08/0.09	0.16
v <sub>13</sub> /v <sub>23</sub>	0.32/0.25	0.18/0.21	0.18
v <sub>31</sub> /v <sub>32</sub>	0.10/0.08	0.05/0.05	0.05

396 \*Aleksandrov and Ryzhova (1961).

397 **4 Discussion**398 4.1 Indentation modulus ( $M$ ) for frictionless spherical indenters

399 Using the two-steps process as described in the data analysis section, the elastic modulus  
400 can be obtained in the form of a reduced modulus ( $E_r$ ). However, because the Poisson's ratio of  
401 the samples ( $\nu_s$ ) is not measured by indentation, the reduced modulus ( $E_r$ ) cannot be converted  
402 to Young's modulus of the sample ( $E_s$ ) using Eq. (2), but only reported as indentation modulus  
403 ( $M$ ). For an isotropic material, the general relation between Young's modulus ( $E$ ) and Poisson's  
404 ratio ( $\nu$ ) with indentation modulus ( $M$ ) is described as  
405

$$M = \frac{E}{1 - \nu^2} \quad (8)$$

406 For anisotropic materials, however, the relationship between indentation modulus and  
407 Young's moduli is more complicated. Several methods have been proposed to determine the  
408 indentation modulus ( $M$ ) for anisotropic materials. The effort started by the work of Willis  
409 (1966) who evaluated the problem for parabolic indenters using the contour integral. The  
410 simplified solution using the surface Green's function (Barnett and Lothe, 1975) was proposed  
411 by Vlassak and Nix (1993) for a flat circular punch, by Vlassak and Nix (1994) for Berkovich  
412 indenters, by Swadener and Phar (2001) and later refined by Vlassak et al. (2003) for conical and  
413 spherical indenters. The central concept in these methods involves deriving the indentation load-  
414 displacement function by integrating the material's Green's function over the contact area.  
415 However, it is generally difficult to obtain the exact forms of Green's function and contact area.  
416 Vlassak et al. (2003) provided a solution for indenters of arbitrary shape assuming the contact  
417 area is elliptical. For spherical indenter, the contact area is exactly elliptical, and the solution can  
418 be obtained using a Fourier expansion of the material's Green's function. Delafargue and Ulm  
419 (2004) further proposed a first-order approximation of the Green's function for indentations

420 along or perpendicular to the axis of symmetry on a transversely isotropic solid. They derived  
 421 solutions for conical indenters and demonstrated that the approximation yielded accurate results.  
 422 The method was then, due to similarity of the sharp tip, used by the subsequent researcher (e.g.,  
 423 Ahmadov, 2011) to estimate the indentation modulus ( $M$ ) for Berkovich indenter.

424 In our present study, the indentation modulus ( $M$ ) is calculated based on the works of  
 425 Vlassak, et al. (2003) and Delafargue and Ulm (2004). For a frictionless spherical indenter, the  
 426 indentation modulus can be calculated based on Vlassak, et al. (2003) by:  
 427

$$M = \frac{1}{\alpha(e)(1 - e^2)^{\frac{1}{4}}} \quad (9)$$

428 where:  
 429

$$\alpha(e) = \int_0^\pi \frac{H(\theta + \frac{\pi}{2})}{\sqrt{1 - e^2 \cos^2 \theta}} \quad (10)$$

430 It is worth noting that both  $\alpha(e)$  and the eccentricity  $e$  are related to the Green's function of the  
 431 material, which can be written as:  
 432

$$H(\theta) = H_0 + H_{c1} \cos(2\theta) \quad (11)$$

433 where the two terms including  $H_0$  and  $H_{c1}$  respectively represent the isotropic and anisotropic  
 434 portions of the Green's function.

435 Since the indentations on the biotite samples were conducted either along or  
 436 perpendicular to the axis of symmetry, we applied the first order approximation to the Green's  
 437 function derived by Delafargue and Ulm (2004):  
 438

$$H_0 = \frac{H_2 + H_3}{2}, \quad H_{c1} = \frac{H_2 - H_3}{2} \quad (12)$$

439 where  $H_2$  and  $H_3$  can be directly calculated from the elastic constants ( $c_{ij}$ ):  
 440

$$H_2 = \frac{1}{2\pi} \sqrt{\frac{C_{3333}}{C_{11}C_{33} - C_{1133}^2} \left( \frac{1}{C_{1313}} + \frac{2}{\sqrt{C_{11}C_{33} + C_{1133}}} \right)}, \quad H_3 = \frac{C_{1111}}{\pi(C_{1111}^2 - C_{1122}^2)} \quad (13)$$

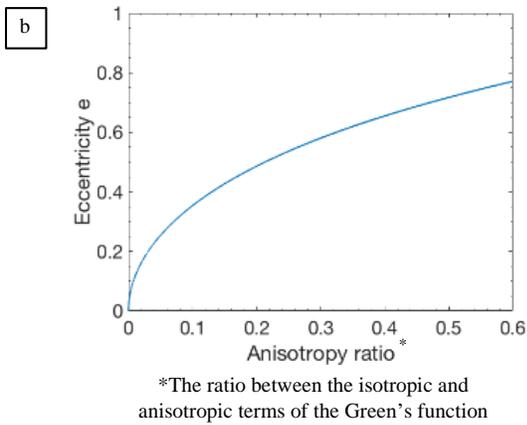
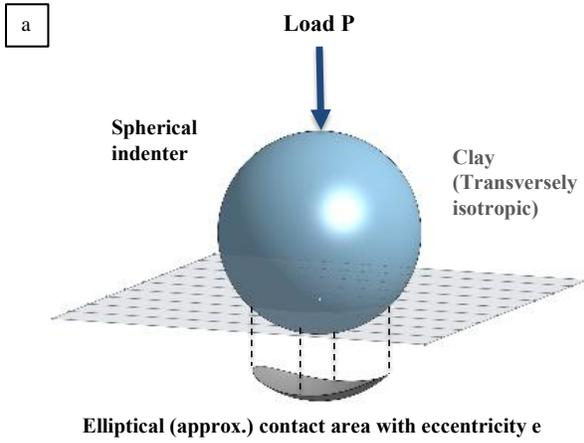
441 From here, the eccentricity of the contact area  $e$  and  $\alpha(e)$  can be computed utilizing their  
 442 relationship with the anisotropic ratio  $H_{c1}/H_0$ :  
 443

$$\frac{H_{c1}}{H_0} = \frac{(\partial/\partial e)(\alpha_0(e)\sqrt{2 - e^2})}{(\partial/\partial e)(\alpha_2(e)\sqrt{2 - e^2})} \quad (14)$$

444 where:  
 445

$$\alpha_0 = \int_0^\pi \frac{d\theta}{\sqrt{1 - e^2 \cos^2 \theta}}, \quad \alpha_2 = \int_0^\pi \frac{\cos(2\theta)d\theta}{\sqrt{1 - e^2 \cos^2 \theta}} \quad (15)$$

446 The eccentricity as a function of anisotropic ratio for spherical indenter is plotted in Figure 7.  
 447 Once the eccentricity is determined based on biotite's elastic constants, the indentation modulus  
 448 can then be calculated using Eq. (9-11).  
 449



450

451 Figure 7 (a) Illustration of spherical indenter and (b) the relationship between eccentricity ( $e$ )  
 452 with anisotropy ratio.

453 Based on these formulations, the elastic constant ( $c_{ij}$ ) from DFT and ultrasonic method  
 454 (Table 2) can be converted to indentation modulus ( $M$ ) as presented in Table 3. Finally, the  
 455 reduced modulus ( $E_r$ ) is also calculated based on Eq. (2) from the indentation modulus ( $M$ ) using  
 456 the elastic properties of the diamond indenter tips.

457 Table 3 Indentation modulus ( $M$ ) of DFT and ultrasonic measurements.

Method	Polytype	Indentation Modulus (GPa)		Reduced Modulus <sup>a</sup> (GPa)	
		Layer-normal	Layer-parallel	Layer-normal	Layer-parallel
Density Functional Theory (DFT)	1M	56.3	128.4	53.7	115.5
	2M1	51.2	123.4	49.0	111.5
Ultrasonic measurements <sup>b</sup>	Unknown	33.5	97.2	32.5	89.6

458 <sup>a</sup>Reduced modulus calculated from indentation modulus using diamond indenter properties of  
459 Young's modulus  $1.14 \times 10^3$  GPa and Poisson's ratio 0.007. <sup>b</sup>Aleksandrov and Ryzhova (1961).

#### 460 4.2 Comparison of experiments with simulation results

461 The elastic behaviors predicted by DFT and ultrasonic measurements are compared with  
462 experimental result in Figure 5 by drawing linear stress-strain relations whose slopes are  
463 determined by the reduced moduli calculated in the previous section (Table 3). We observe that  
464 nearly all experimental data plot on or below the DFT-simulated trends for both 1  $\mu\text{m}$  and 5  $\mu\text{m}$   
465 diameter indenters. Thus the DFT prediction marks an upper bound to the elastic reduced moduli  
466 recovered from nanoindentation. The DFT predictions are slightly different between the two  
467 polytypes, 1M and 2M<sub>1</sub>, but the difference is small compared to the overall variation in  
468 experimental results. This suggests that the variability in experimental results are not explained  
469 by differences in polytypes.

470 Stress-strain relation predicted from the ultrasonic measurements by Aleksandrov and  
471 Ryzhova (1961) plot lower than those from the simulation reduced moduli, an obvious  
472 consequence of the lower indentation moduli recovered from the ultrasonic data. For the layer-  
473 normal loading dataset (Figure 5a), there appears to be a population of lower-moduli data that  
474 clusters along the ultrasonic-based trend, but not below. This may suggest that the ultrasonic-  
475 based modulus is the most compliant member when compared with DFT and nanoindentation  
476 results. For the layer-parallel loading dataset, there are less data points to confirm, but there is a  
477 population of nanoindentation results that plot below the ultrasonic-based trend therefore  
478 ultrasonic-based modulus does not appear to be the most compliant compared to DFT and  
479 nanoindentation results.

#### 480 4.3 Causes of differences in simulation and experimental results

481 As reported above, in general, the reduced modulus ( $E_r$ ) derived from nanoindentations  
482 distribute between those predicted from DFT simulations and the ultrasonic measurements by  
483 Aleksandrov and Ryzhova (1961), in both normal and parallel orientation. We suggest that these  
484 differences could be related to several causes, namely chemical impurities, cleavages, crystal  
485 defects, and scale dependence.

##### 486 *Chemical Impurities*

487 The DFN simulations were carried out using the ideal chemical composition of a biotite  
488 ( $\text{K}(\text{Mg}_2\text{Al})(\text{Si}_3\text{Al})\text{O}_{10}(\text{OH})_2$ ), whereas biotite is known to be a continuous solid solution of Mg  
489 (magnesium) and Fe (iron), of which phlogopite is the Mg end-member and annite is the Fe end-  
490 member. The presence of Fe in the chemical composition of natural biotites may be responsible  
491 for the differences between the simulated and measured results. However, since Fe and Mg have  
492 the same number of cations (<sup>+2</sup>) and bonding type, including Fe in the chemical composition of  
493 biotite is not expected to significantly change its mechanical properties. For comparison, Young  
494 modulus of biotite and phlogopite inferred from the ultrasonic velocities (Aleksandrov and  
495 Ryzhova, 1961) were 178.6 GPa and 169.8 GPa, respectively, in the layer-parallel direction, and  
496 52.8 GPa and 48.8 GPa, respectively, in the layer-normal direction. We also did not observe a  
497 significant Fe peak compared to the Mg peak in the point-shoot EDS pattern recovered from  
498 biotite grains (1 cps/eV for Fe and 20 cps/eV for Mg). Therefore, chemical impurities are not

499 expected to be the main cause of the discrepancy between the predicted and observed indentation  
500 moduli.

### 501 *Closing of Cleavages*

502 Because cleavages along the (001) basal plane are known to be prevalent in mica  
503 minerals, even in single crystal specimens, it is possible that the compliance observed in the  
504 ultrasonic and nanoindentation results are caused by the closing of the cleavage planes.  
505 However, this is unlikely the case at least for the nanoindentation data because: (1) no open  
506 cleavage planes were seen under the SEM in the biotite grains tightly embedded in the schist  
507 matrix, (2) closure of cleavages result in mineral stiffening but the linearity between the  
508 indentation stress and strain suggests no such stiffening, (3) closing of cleavage planes would not  
509 explain the low moduli also observed during layer-parallel loading. For the ultrasonic velocity  
510 measurement by Aleksandrov and Ryzhova (1961), Aleksandrov and Prodaivoda (1993)  
511 describes that the measurement was affected by cleavage planes. This may explain why  
512 ultrasonic-based reduced modulus for the layer-normal direction places at the lower-end of the  
513 range of reduced modulus exhibited by the nanoindentation results. We note that cleavages do  
514 not affect layer-parallel loading tests, so the low reduced modulus calculated from ultrasonic  
515 measurement compared to the DFT predictions requires a separate explanation.

### 516 *Crystal Defects - Ripplcation*

517 For the reduced modulus recovered from nanoindentation experiments, a more probable  
518 cause for the lower modulus compared to DFT results is the presence of defects in the crystal  
519 structures of biotite. The crystal structure used in the DFT simulations are of the ideal form of  
520 the polytypes 1M and 2M<sub>1</sub>, whereas the biotite samples used in the laboratory measurements,  
521 both ultrasonic velocity and nanoindentation, come from naturally occurring rocks. Naturally  
522 occurring minerals contain various defects known as vacancies and dislocations, which are  
523 critical ingredients for crystal plastic deformation of minerals at high temperatures (Poirier,  
524 1985; Karato, 2008). Traditionally, the dominant mode of crystal defects in biotites have been  
525 thought to be dislocations parallel to the (001) basal plane, either along the biotite interlayer  
526 (Bell and Wilson, 1986; Kronenberg et al., 1990) or the within the oxygen layer between the  
527 octahedral and tetrahedral sheets (Noe and Veblen, 1999). But such dislocation do not  
528 accommodate out of plane movement of atoms, not plausible as an explanation for layer-normal  
529 compliance.

530 Recently, a new type of crystal defect in layered minerals, *ripplocation*, has been  
531 introduced by Kushima et al. (2015), which takes the form of atomic-scale ripple-like defects in  
532 the basal layer. Aslin et al. (2019) reports the abundance of nano-scale ripplocations in biotites  
533 found in a mylonite rock, as well as in an undeformed granite, observed under the TEM.  
534 Although we have not confirmed the presence of such defect features in the biotites we studied,  
535 we suggest that the low nanoindentation modulus is an evidence of the presence of ripplocations.  
536 The exact effect of such mineral defects on the elastic moduli of minerals is not known. But it is  
537 plausible that ripplocations reduce the stiffness of biotites in both layer-normal and layer-parallel  
538 direction because ripplocations can accommodate layer-normal expansion and layer-parallel  
539 shortening, similar to kink bands found in biotites (Aslin et al., 2019). Ripplocations would also  
540 explain the low reduced modulus in the layer-parallel direction estimated from ultrasonic  
541 measurements in the absence of cleavages.

542 *Scale Dependence*

543 With the notion that the crystallographic defects are enhancing the compliance of biotite  
544 minerals, the relationship between the simulation, nanoindentation, and ultrasonic modulus can  
545 be understood as a result of scale-dependence. Wavelengths of ultrasonic waves at a megahertz  
546 frequency passing through minerals are typically on the order of few millimeters to a centimeter,  
547 which indicates that the indentation modulus based on ultrasonic measurements by Aleksandrov  
548 and Ryzhova (1961) represent the effective properties of biotites at such length scales. It is easy  
549 to perceive that a single crystal of few millimeters size contains defects, including cleavages, and  
550 the apparent stiffness of the crystal is lowered by those structural impurities. On the other hand,  
551 the mineral volume probed by the nanoindenter tips are at most several factors larger than the  
552 diameter of the indenter tip, approximately several  $\mu\text{m}$  for the 1  $\mu\text{m}$  indenter, likely smaller than  
553 cleavage openings. However, because nanoindentation modulus is still consistently lower than  
554 the theoretical value of the defect-free mineral, this suggests that crystal defects are still  
555 prevalent and abundant features of the mineral influencing its mechanical properties at the sub-  
556 micron length scale.

## 557 4.4 Implications for deformation mechanisms in phyllosilicates

558 Dislocation glide along the (001) basal plane as a mechanism for creep in biotites have  
559 been studied extensively (Kronenberg et al., 1990; Christoffersen and Kronenberg, 1993), and  
560 Kronenberg et al. (1990) also determined the activation energies for two types of creep  
561 constitutive laws (i.e. exponential and power-law). However, dislocation glide does not  
562 accommodate any strain component parallel to the c-axis of the crystal structure, and what  
563 accommodates off-basal-plane plastic strain have remained ambiguous (Aslin et al., 2019). On  
564 the other hand, ripplocation as a ubiquitous deformation mechanism for layered solids (Barsoum  
565 et al., 2019) may also occur in phyllosilicates, allowing plastic deformation with a greater degree  
566 of freedom without fracturing the mineral by brittle deformation. This is because ripples in the  
567 basal layers give ripplocation a component strain parallel to the c-axis that is absent in basal  
568 dislocations (Aslin, 2019).

569 While plastic deformation of phyllosilicates by ripplocations have not been directly  
570 observed, whether such mechanism can accommodate the creep deformation of clay-minerals is  
571 of particular interest in crustal settings. It is known that clay-rich sedimentary rocks (e.g., shales)  
572 exhibit some time-dependent plastic deformational behavior even at low temperatures (Chang  
573 and Zoback, 2009; Sone and Zoback 2013, 2014a; Trzeciak et al., 2018). The importance of such  
574 creep behavior in characterizing the long-term behavior of subsurface reservoirs (Alramahi and  
575 Sundberg, 2012) and understanding origins of in-situ stress states in the crust is well-recognized  
576 (Warpinski, 1989; Gunzburger and Cornet, 2007; Sone and Zoback 2014b), but the exact  
577 physical mechanism causing the rock to creep is not clearly understood. Pore volume loss  
578 facilitated by grain sliding (i.e., compaction) is suggested to be an important mechanism for  
579 creep (Sone and Zoback, 2013, 2014a), but it is still undetermined if plastic deformation of the  
580 phyllosilicates minerals itself also contributes to the bulk rock creep behavior.

581 Deformation facilitated by ripplocations and its mechanical data, however, is still  
582 difficult to recover from mechanical testing at the scale of a single cleavage-free phyllosilicate  
583 crystal at the micron scale. If atomistic simulations therefore becomes an important technique in  
584 evaluating the potential for ripplocations to accommodate crystal plastic deformation, it will be  
585 crucial to properly incorporate the appropriate type and number of crystal defects in the models.

586 To this end, results from this study provide a benchmark for calibrating future atomistic models  
587 for phyllosilicate minerals.

## 588 **5 Summary**

589 We studied the elastic modulus of biotites using spherical nanoindentation and atomistic  
590 simulations. Our study uniquely reports the measured elastic properties of biotite using  
591 nanoindentation in two directions (layer-parallel and layer-normal loading). We also provide  
592 theoretical predictions of biotite elastic constants using density functional theory (DFT) not  
593 reported in the literature. We also propose a solution to estimate the indentation modulus (M) for  
594 spherical indentation from stiffness constants in an anisotropic material. Indentation modulus  
595 recovered from our nanoindentation results are generally equal to or higher than those recovered  
596 from dynamic ultrasonic measurements (Aleksandrov and Ryzhova, 1961), but lower than those  
597 predicted from the ideal defect-free DFT model. These differences highlight the presence of  
598 defects down to the nano-scale within naturally occurring phyllosilicates minerals, which may be  
599 important for understanding plastic deformation mechanism of phyllosilicates. Our results  
600 provide measured evidence that nano-scale defects affect the mechanical properties of  
601 phyllosilicate minerals.

## 602 **Acknowledgments**

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604 Endowment Fund for Education (LPDP). We thank Connor Acker for the support in preparing  
605 the polished samples used in this study.

## 606 **Data Availability Statement**

607 Nanoindentation datasets for this research will be archived in MINDS@UW repository  
608 and are underway. Ultrasonic datasets for this research are included in Aleksandrov and Ryzhova  
609 (1961).

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