# A modular model of Jupiter's magnetospheric magnetic field based on Juno data

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#### Abstract

Accurate modeling of Jupiter's magnetospheric magnetic field is important for not only scientific research but also mission planning. We develop a new empirical global model of Jupiter's magnetic field in the Juno era, including components from the planetary dynamo, Chapman-Ferraro currents, and cross-tail current sheet. The internal field is based on the JRM09 model. The shielding field is obtained by minimizing the component normal to Jupiter's magnetopause and varies due to the change of solar wind dynamic pressure. Combined with the curved magnetodisk, the high-resolution TS07 method is used for modeling Jupiter's magnetodisc and tail currents. The best-fitting results show an asymmetric magnetodisc current system in azimuthal direction with a tilted angle to Jupiter's magnetic equator. The sweep-back effects of Jupiter's magnetic fields are also reproduced by the radial current system. This new model is validated by comparing with Juno's magnetometer data in the range from 5 Rj to 60 Rj, where Rj=71492 km is the radius of Jupiter.

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5	Key Points:
6	• A Jupiter's global magnetic field model is built, including fields from the plane-
7	tary dynamo, current sheet, and magnetopause current.
8	• The magnetopause and the current on it are dynamically modeled based on so-
9	lar wind dynamic pressure.
10	• A tilted asymmetric current system on the magnetic equator is reproduced and
11	the sweep-back effect is incorporated in the current sheet model.

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#### 12 Abstract

Accurate modeling of Jupiter's magnetospheric magnetic field is important for not only 13 scientific research but also mission planning. We develop a new empirical global model 14 of Jupiter's magnetic field in the Juno era, including components from the planetary dy-15 namo, Chapman-Ferraro currents, and cross-tail current sheet. The internal field is based 16 on the JRM09 model. The shielding field is obtained by minimizing the component nor-17 mal to Jupiter's magnetopause and varies due to the change of solar wind dynamic pres-18 sure. Combined with the curved magnetodisk, the high-resolution TS07 method is used 19 for modeling Jupiter's magnetodisc and tail currents. The best-fitting results show an 20 asymmetric magnetodisc current system in azimuthal direction with a tilted angle to Jupiter's 21 magnetic equator. The sweep-back effects of Jupiter's magnetic fields are also reproduced 22 by the radial current system. This new model is validated by comparing with Juno's mag-23 netometer data in the range from 5  $R_i$  to 60  $R_i$ , where  $R_i = 71492$  km is the radius 24 of Jupiter. 25

### 26 1 Introduction

The modeling of Jupiter's magnetic field helps understand the particle dynamics, 27 magnetospheric dynamics, and coupling processes between the magnetosphere and iono-28 sphere. Jupiter's magnetosphere is highly coupled with its moon. The neutrals from Io 29 are outward and can be ionized as ions because of geologic activities (Russell et al., 2004). 30 The ions are the main sources of the dense plasma torus near the equator in the inner 31 region (<  $10R_j$ ,  $R_j = 71492$  km is the radius of Jupiter) and the torus nearly coro-32 tates with the planet due to strong magnetosphere-ionosphere-atmosphere coupling. (Bagenal, 33 1994). In the middle region  $(10-40R_i)$ , the plasma corotation with Jupiter's magne-34 tosphere gradually breaks down. The thin current sheet locates near the equator and the 35 magnetic field becomes highly stretched (Cowley et al., 2002). In the outer region (> 36  $40R_i$ ), the configuration of the magnetosphere is highly dependent on the solar wind. 37 On the dayside, the distance of magnetopause varies from  $45R_i$  to  $100R_i$  depending on 38 the solar wind dynamic pressure (Joy et al., 2002). On the nightside, the magnetotail 39 current system connects the magnetodisk current to the magnetopause current. This cur-40 rent system stretches the field line and creates a long magnetotail, which extends to the 41 orbit of Saturn (McComas et al., 2017). Furthermore, the accurate modeling of Jupiter's 42 magnetic field is also important for engineering. Energetic particles are trapped by the 43 magnetic field. The maximum energies of electrons and protons can be higher than 100 44 MeV and 1 GeV, relatively. These particles are harmful to electronics in spacecraft and 45 radiation effects caused by them are the main constraints of Jupiter mission design (Fieseler 46 et al., 2002; Wang, Zhang, et al., 2019; Wang, Ma, et al., 2019). 47

One important source of Jupiter's magnetic field is the dynamo field, which is as-48 sociated with the metallic-hydrogen region of Jupiter's interior (Jones, 2014). The mod-49 eling attempts of the internal field started from the Jupiter flybys of Pioneer 10/11. The 50 O4 model (Acuna & Ness, 1976) adopted the data of magnetometers onboard these two 51 spacecraft and included the first three orders and degrees of the spherical harmonics. Af-52 ter including data from the Voyager 1 flyby, Connerney et al. (1982) developed the O6 53 model, which is reliable for the first three orders and matches the Ulysses observations 54 very well (Dougherty et al., 1996). This model assumed the intrinsic field was immutable 55 from the Pioneer era to the Voyager era and included the contribution of Jupiter's cur-56 rent sheet. Combining the in-situ data from Pioneer and Voyager and the observations 57 of locations of Io flux tube footprints in Jupiter's ionosphere, Connerney et al. (1998) 58 improved the previous models to a higher precision by including the fourth-order. Fur-59 thermore, Randall (1998) derived a new model that can reproduce the absorption mi-60 cro signature of the moon Amalthea. 61

Before the Juno era, Pioneer 11 provided the best description of the internal field 62 because of its retrograde orbit and high inclination. Modeling higher-order terms of Jupiter's 63 internal field is difficult because of limited datasets. Although Galileo orbited Jupiter 64 for about eight years, the limitation of its latitudinal coverage is unsuitable for improving these models. After JOI (Jupiter Orbit Insertion) in July 2016, Juno provided a global 66 coverage observation of Jupiter' magnetic field with perijove of 1.05  $R_i$  and longitudi-67 nal separation of 45° between perijoves (Bagenal et al., 2017). Based on Juno's obser-68 vations of its first nine orbits, Connerney et al. (2018) established a new model named 69 JRM09. The spherical harmonic coefficients of this model are well determined through 70 degree and order 10. JRM09 provided the detailed view of Jupiter's complex dynamo 71 and shows the hemispheric dichotomy of Jupiter's magnetic field (Moore et al., 2018). 72 The non-dipolar part of the field is confined to the northern hemisphere and the field 73 in the southern hemisphere is predominantly dipolar. This suggests the radial variations 74 in density and electrical conductivity in Jupiter's interior. 75

Another important source of Jupiter's magnetic field is the field generated from the 76 ring current near the equatorial plane and the tail current system (Alexeev & Belenkaya, 77 2005). Since the discovery of Jupiter's current sheet, many models have been created. 78 Connerney et al. (1981) modeled the azimuthal current sheet by a finite thickness and 79 became the basis of many other empirical models. This model assumed that the current 80 density is uniform within the width of the disk and is inversely proportional to the dis-81 tance from the magnetic axis. This model fits the observations of Pioneer 10 and Voy-82 ager 1/2 well within ~ 30  $R_j$ . In the Galileo era, another approach was developed by 83 Khurana (1997) and described the fields in terms of Euler potentials. This model includes 84 sweep-back effects of the magnetic field lines. In the Juno era, new current sheet mod-85 els are developed. Pensionerov, Belenkaya, et al. (2019) fitted the best optimal param-86 eters of magnetodisc using Juno's data. Furthermore, Pensionerov, Alexeev, et al. (2019) 87 incorporated models of Connerney et al. (1981) and Khurana (1997) in a piecewise fash-88 ion to more accurately model the field within ~ 95  $R_j$  and termed the model as the PCD 89 model. Based on measurements of Juno's first 24 orbits, Connerney et al. (2020) estab-90 lished a new tilted current disk model supplementing by an outward radial current sys-91 tem. 92

Besides the model of Khurana (1997), all other models are based on an assump-93 tion that equatorial current is symmetric along the azimuthal direction and could not 94 describe the sweep-back nature of Jupiter's magnetic field. However, the structure of the 95 current disk is complex and time-dependent, including asymmetries of current density 96 and thickness of the current sheet (Khurana & Schwarzl, 2005; Lorch et al., 2020). These 97 complex asymmetries arise from both internal rotational stresses and external solar wind 98 forcing on the system (Arridge et al., 2015). In recent years, techniques for modeling the qq Earth's magnetic field in its magnetosphere were developed rapidly and an overview is 100 from Tsyganenko (2013). Tsyganenko and Sitnov (2007) presented an empirical mod-101 eling method (hereafter TS07) based on large sets of data. In this method, the magnetic 102 field is expanded into a sum of orthogonal basis functions and is capable to reproduce 103 arbitrary radial and azimuthal current distribution. This method abandons the idea of 104 a predescribed equatorial current system and could reveal dynamical characteristics dur-105 ing storm time (Sitnov et al., 2008; Stephens et al., 2016). With an abundance of in-situ 106 magnetometer data from Galileo and Juno, These techniques could advance the current 107 sheet model of the Jovian system. 108

To filter data outside the magnetopause, shielding field from magnetopause currents (Chapman-Ferraro currents) should also be considered. Combining in-situ data and magnetohydrodynamic (MHD) simulation, Joy et al. (2002) presented probabilistic models of the Jovian magnetopause and bow shock. In the model, the size of the magnetopause is parameterized by solar wind dynamic pressure. Furthermore, statistics show a bimodal distribution of boundary positions of Jupiter's magnetopause (McComas et al., 2014; Col-



**Figure 1.** Juno trajectory plot for Perijove 1 in magnetic equatorial coordinates on 27 August (day 240) 2016. The tick marks are given every hour.

lier et al., 2020), i.e. the compressed and expanded magnetosphere. Tsyganenko (1995)
developed a magnetopause current modeling method by minimizing the normal component of the total magnetic field on the magnetopause surface. To better understand the
dynamic nature of Jupiter's magnetosphere, all these magnetic field sources should be
included to improve the current models. In this study, we attempt to build a global model
of Jupiter's magnetosphere including internal field, asymmetric equatorial current system, and magnetopause current.

#### 122 **2 Data**

We utilize the fluxgate magnetometer data of Juno mission up to the 24th perijove 123 (PJ) (Connerney et al., 2017). Juno was inserted into the polar orbit of Jupiter with a 124 perijove of ~  $1.05R_i$  and an apojove of ~  $113R_i$ . The Juno mission was designed to 125 wrap the planet in a dense net of observations using perijove passes evenly spaced in lon-126 gitude about the planet. The trajectories of Juno for PJ1 are shown in Fig. 1. The ver-127 tical axis is aligned with Jupiter's planetary dipole. Also illustrated in the plot are the 128 magnetic field lines. The spacecraft appears to wiggle up and down because of Jupiter's 129 rotation with a period of about 10 hours and the angular offset of the dipole from the 130 spin axis. In such orbits, Jupiter is globally coveraged and magnetodisk currents are sam-131 pled when Juno penetrates into and passes through the current-carrying region near the 132 magnetic equator. 133

The vector magnetic field is measured continuously and sampled at a rate of 64, 32, and 16 samples per second depending on the distance from Jupiter. In this study, we use the data that has been downsampled to 1 minute and provide a compact dataset. The data are archived and available at the PDS (Planetary Data System)<sup>1</sup>. We further average the data by 5-min interval for analysis and the time resolution is high enough for characterization of Jupiter's magnetosphere.

<sup>&</sup>lt;sup>1</sup> https://pds-ppi.igpp.ucla.edu/search/view/?f=yes&id=pds://PPI/JNO-J-3-FGM-CAL-V1.0



Figure 2. The structure of Jupiter's magnetic field modular model.

#### <sup>140</sup> **3** Model structure and results

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#### 3.1 Magnetospheric magnetic field

The total magnetic field  $B_{tot}$  in Jupiter's magnetosphere consists of contributions from internal part  $B_{int}$  and external part  $B_{ext}$ .  $B_{int}$  is the planetary field and generated by the complex dynamo mechanism.  $B_{ext}$  is associated with currents flowing inside Jupiter's magnetosphere, including fields from cross-tails current  $B_{cur}$  and that from magnetopause currents (Chapman-Ferraro currents)  $B_{sh}$ .

$$\begin{cases} B_{tot} = B_{int} + B_{ext} \\ B_{ext} = B_{cur} + B_{sh} \end{cases}$$
(1)

The model's structure is shown in Fig. 2. The inputs are Coordinated Universal Time (UTC) and the coordinate. The output is the corresponding vector magnetic field. The solar wind propagation model is used to calculate the solar wind dynamic pressure  $(P_d)$  in Jupiter's orbit at a given UTC.  $P_d$  determines the shape of the magnetopause and the corresponding scaling factors. After the magnetopause is determined,  $B_{sh}$  is obtained by shielding the internal field. Finally, we obtain the total magnetic field combining  $B_{ext}$  with the internal field.

Conventionally, different sources of fields are built on different coordinate systems. 154  $B_{int}$  is usually built on IAU standard Jupiter System III coordinates (Riddle & War-155 wick, 1976), in which the Z-axis is defined by the spin axis of Jupiter.  $B_{sh}$  is built on 156 Jupiter-Sun-Orbit (JSO) coordinates (Bagenal & Wilson, 2016), in which the X-axis is 157 aligned with the Jupiter-Sun vector and the Y-axis is antiparallel to the vector of Jupiter's 158 motion.  $B_{cur}$  is built on Jupiter magnetic coordinates, in which the Z-axis is aligned with 159 Jupiter's magnetic dipole and the Y-axis is aligned with the intersection of the magnetic 160 and geographic equator. See the Appendix section in Bagenal et al. (2017) for details 161 about these coordinate systems. In the following sections, we will discuss how to model 162 and combine each part of the fields. 163

#### <sup>164</sup> **3.2** The internal magnetic field

The internal magnetic field can be represented as the gradient of a scalar potential:  $B_{int} = -\nabla \Phi_{int}$ . So the standard solution to the Laplace's equation is used to describe the field (Connerney et al., 2017). The solution of scalar potential in the Jupiter System III coordinate is given by the sum of spherical harmonics:



**Figure 3.** Contours of the internal magnetic field magnitude at (a)  $1R_j$ , (b)  $5R_j$ , (c)  $30R_j$ , and (d)  $70R_j$  from Jupiter's center in rectangular latitude-longitude projection.

$$\Phi_{int}(r,\theta,\phi) = \sum_{n=1}^{\infty} (\frac{R_j}{r})^{n+1} \sum_{m=0}^{n} P_n^m(\cos\theta) [g_n^m \cos(m\phi) + h_n^m \sin(m\phi)]$$
(2)

where r is the distance from the planet's center,  $\theta$  and  $\phi$  are the corresponding colatitude and longitude,  $P_n^m$  is the associated Legendre polynomial function,  $g_n^m$  and  $h_n^m$  are the Schmidt coefficients of order n and degree m.

In this study, we choose the JRM09 model as the internal field model. The coef-172 ficients of this model are well determined through degree 10 and provide the most de-173 tailed view of a planetary dynamo other than the Earth. Furthermore, Stallard et al. (2018) 174 gave evidence supporting an immutable intrinsic field between the Galileo era and the 175 Juno era. Some results from the JRM09 model are shown in Fig. 3. In general,  $B_{int}$  de-176 crease very fast with increasing r. Comparing with the higher-order field, the dipole field 177 is dominant beyond 5  $R_i$  because the dipole field is proportional to  $r^{-2}$  and the quadrupole 178 field is proportional to  $r^{-4}$ , etc. So the higher-order field decreases much faster than the 179 dipole field. As a result, the subplots (b), (c), and (d) are essentially symmetric in  $\phi$  and 180  $\theta$  directions. 181

#### 3.3 Shielding magnetic field from the magnetopause

#### 183 3.3.1 Modeling method

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At Jupiter's magnetopause, the pressure balance between the external solar wind dynamic pressure and internal magnetic and plasma pressure is achieved. Joy et al. (2002) used a quasi-paraboloid model to describe the shape of Jupiter's magnetopause in JSO
 coordinates:

$$z^{2} = A(P_{d}) + B(P_{d})x + C(P_{d})x^{2} + D(P_{d})y + E(P_{d})y^{2} + F(P_{d})xy$$
(3)

where the coefficients (A-F) are functions of solar wind dynamic pressure  $P_d$ . Combining observations and MHD simulation, A-C and D-F are linear functions of  $P_d^{(-1/4)}$ and  $P_d$ , relatively.

The magnetopause carries electric currents that shield the magnetosheath from the field inside the magnetosphere. So, the magnetopause shielding field  $B_{sh}$  corresponds to a zero normal component of the total field vector at the boundary.  $B_{sh}$  is curl free and can be represented as the gradient of a scalar function:

$$\boldsymbol{B}_{sh} = -\nabla U_{sh} \tag{4}$$

where  $U_{sh}$  is the scalar function and can be represented by a series expansion of basis funtion in cylindrical coordinate system (Tsyganenko, 1995):

$$U_{sh} = \sum_{i=1}^{N} a_i J_1(\frac{\rho}{b_i}) \exp(\frac{x}{b_i}) \sin\phi$$
(5)

where  $J_1$  is Bessel function of the first kind and order 1.  $a_i$  and  $b_i$  are parameters and can be calculated by minimizing the normal component of the total magnetic field on

the magnetopause using downhill simplex algorithm (Press et al., 1992):

$$\sigma_{sh} = \sqrt{\sum_{i=1}^{N} [(\boldsymbol{B}_{int}^{(i)} - \nabla U_{sh}^{(i)}) \cdot \boldsymbol{n}^{(i)}]/N}$$
(6)

where  $B_{int}^{(i)}$  is the magnetic field from internal source to be shielded at the *i*-th location.  $n^{(i)}$  is the unit vector normal to the magnetopause surface at the *i*-th location. One example of shielding effects of magnetopause currents is shown in Fig. 4. The fitting results correspond to the situation that  $P_d = 0.045$  nPa. After adding the shielding field, the magnetic field is fully confined inside the magnetopause.

#### *3.3.2* Scaling of the magnetopause

The magnetopause expands and contracts with changes to the solar wind dynamic pressure in a self-similar way. A spatial rescaling method is applied to adjust the selfsimilar behavior and the magnetopause coefficients do not need to change due to different solar wind dynamic pressure.

$$\begin{cases} [x', y', z'] = [S_x, S_y, S_z] \cdot [x, y, z] \\ B'_{sh} = S_x S_y S_z B_{sh} \end{cases}$$

$$\tag{7}$$

where  $B'_{sh}$  is the adjusted magnetic field. (x', y', z') is the adjusted location of coordinate (x, y, z).  $S_x/S_y/S_z$  is the scaling parameter in the x/y/z direction and varies with solar wind dynamic pressure. Based on the data of Table 1 in Joy et al. (2002), a logarithmic linear regression is made between pressure and magnetopause size. The results are shown in Fig. 5.  $X_{pause}$ ,  $Y_{pause}$ , and  $Z_{pause}$  are the boundary locations along the respective axes in given  $P_d$  from Joy et al. (2002). There is no surprise about the good



Figure 4. (a) Unshielded and (b) shielded magnetic field lines for dipole field.

216	results because $A-F$ in Equ. 3 are also linear functions of $P_d^{(-1/4)}$ and $P_d$ . Then the
217	scaling parameters can be obtained as a function of solar wind dynamic pressure:

$$\log_{10}(S_i) = a_i \cdot \log_{10}(P_d) + b_i, (i = x, y, z)$$
(8)

where  $a_i$  and  $b_i$  are parameters in the *i*-axis. The values of  $a_i$  and  $b_i$  are also shown in Fig. 5. In the fitting, we assume the scaling parameters for  $P_d = 0.045$  nPa are 1. An illustration of how the solar wind dynamic pressure control Jupiter's magnetospher is shown in Fig. 6. Under the premise that the magnetic field is confined in the magnetopause, the magnetosphere is expanded or compressed with the change of  $P_d$ . While  $P_d$  varies from 0.045 nPa to 0.36 nPa, the boundary of magnetopause is compressed from  $91R_j$ to  $55R_j$ .

To develop a real-time model, the solar wind dynamic pressure at any given time should be simulated. So we adopt the solar wind propagation model developed by Tao et al. (2005). This model takes observations of solar wind in near-Earth space and uses a 1-D MHD model to propagate solar wind to 10 AU. This model can simulate dynamic pressure, density, velocity, and interplanetary magnetic field in Jupiter's orbit, and the results from the model were validated by Zieger and Hansen (2008). The  $P_d$  data from the model are now available on the AMDA archive.<sup>2</sup>

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#### 3.4 Magnetic field from the current sheet

The magnetic field line is greatly distended from the planet by the dawn-to-dusk 233 current near the magnetic equator, which is responsible for the enormous size of Jupiter's 234 magnetosphere. In the previous models, the current sheet is always assumed as a sys-235 metric azimuthal (dawn-to-dusk direction) configuration while the current density de-236 creases with the distance from the planet. However, from a detailed analysis by Lorch 237 et al. (2020), the current density varies with local time and the radial current should also 238 be considered. So we employ the TS07 method (Tsyganenko & Sitnov, 2007) to construct 239 the complex morphologies of equatorial current system. This method does not impose 240

<sup>&</sup>lt;sup>2</sup> http://amda.cdpp.eu/



Figure 5. The linear regression between logarithmic solar wind pressure and magnetopause size in (a) X-axis, (b) Y-axis, and (c) Z-axis. Also shown are the fitting coefficients to scaling parameters of Equ. 8.



Figure 6. The change of the magnetospheric configurations due to different solar wind dynamic pressures. The thin and thick lines represent the magnetic field lines and the configuration of magnetopause, respectively.

a predefined azimuthal or radial current sheet. After fitting in-situ data, TS07 can describe any distribution of current in the equatorial sheet (tail and ring systems) with finite sheet thickness by a regular expansion into series of basis functions:

$$\boldsymbol{B}_{cur}(\rho,\phi,z) = \sum_{n=1}^{N} a_n^{(s)} \boldsymbol{B}_n^{(s)} + \sum_{m=1}^{M} \sum_{n=1}^{N} a_{mn}^{(o)} \boldsymbol{B}_{mn}^{(o)} + \sum_{m=1}^{M} \sum_{n=1}^{N} a_{mn}^{(e)} \boldsymbol{B}_{mn}^{(e)}$$
(9)

where  $B_{curr}$  is the field from equatorial current system represented by the TS07D model. 244  $B_{\alpha\beta}^{(\gamma)}$  is the basis function and  $a_{\alpha\beta}^{(\gamma)}$  is the weight from the fitting procedure. M and N 245 are parameters, which determine the number of expansion terms. The formula of  $B_{\alpha\beta}^{(\gamma)}$ 246 can be found in Tsyganenko and Sitnov (2007). The solution is combined by azimuthally 247 symmetric modes denoted by the index (s) and asymmetric modes denoted by the in-248 dex (o) and (e), corresponding to odd and even components with respect to the plane 249 y = 0, relatively. The spatial resolution of the equatorial current sheet is determined 250 by (M, N) and can be increased to the desired value by increasing the values of M and 251 N. However, a model with too many degrees of freedom will be subject to overfitting, 252 whereas an underfit model will not fully capture the breadth of information contained 253 in the data. In this study, we choose (M, N) = (10, 10) by trial and error. 254

To fit the current distribution in Jupiter magnetic coordinate, the optimal values for coefficients  $a_{\alpha\beta}^{(\gamma)}$  are searched out by using the downhill simplex algorithm and minimizing the error:

$$\sigma_{cur} = \sqrt{\sum_{i=1}^{N} (\boldsymbol{B}_{ts07}^{(i)} - \boldsymbol{B}_{juno}^{(i)})^2 / N}$$
(10)

where  $B_{ts07}^{(i)}$  are magnetic fields from Equ. 9.  $B_{juno}^{(i)}$  are the corresponding values from in-situ magnetometer data of the Juno spacecraft. N is the total number of the data. This criterion provides the best approximation to  $a_{\alpha\beta}^{(\gamma)}$  and provide the best estimation of the magnetic field from the equatorial current system. In the TS07 method, the electric current flow direction is strictly parallel to Jupiter's magnetic equator. However, this premise limits the use of the TS07 method. We assume that the current sheet could be rotated by a tilt angle and an azimuthal angle, separately. So the values of the two angles are also included in the downhill simplex algorithm.

Furthermore, we consider the curvature of the current sheet. Due to the rotating tilted dipole and effects of the solar wind flow, the current sheet deviates from equatorial plane. So we adopt a nonrigid current sheet model (Khurana, 1997) by replacing zby  $z-z_{cs}$ , where  $z_{cs}$  is the z coordinate of the current sheet center and defines the bowl structure of Jupiter's current sheet:

$$z_{cs} = \rho \tan(\Phi_0) \left[ \frac{x_0}{x_{jso}} \tanh(\frac{x_{jso}}{x_0}) \cos(\phi - \delta) + \cos\phi \right]$$
(11)

where  $\Phi_0$  is the tilt angle of the dipole axis from the rotation axis.  $x_0$  and  $\delta$  are parameters and their values can be found in Khurana (1997).  $\rho$  and  $\phi$  are in Jupiter's magnetic coordinates.  $x_{jso}$  is the distance along the Jupiter-Sun axis.

In the current sheet modeling, we only use Juno's in-situ data from PJ0 to PJ20. Data beyond PJ20 are used for validation of the model. In addition, data in regions  $< 5R_j$  or  $> 60R_j$  are excluded. Because the influence of the currents on the magnetopause is significant beyond 60  $R_j$  and the field within 5  $R_j$  is dominated by the planetary field that is so strong (>1600 nT). After iterations, the best values of  $a_{\alpha\beta}^{(\gamma)}$  are obtained and



**Figure 7.** Observed and modeled fields from the current sheet in cylindrical components for Juno perijove 17. The observed field is the data of the magnetometer with the JRM09 internal field subtracted. The fields are plotted versus spherical radial distance with inbound data shown on the left and outbound data on the right.

are provided in the Appendix section. In addition, the best-fitting results show that the
optimized current sheet is tilted by 0.85 ° from the magnetic equator and rotated by 8.81
° in the azimuthal direction.

As an example, the fitted results of PJ17 data are shown in Fig. 7. The TS07 method 282 based model fits the Juno data very well for  $B_{\rho}$  and  $B_z$ . The fluctuation of inbound  $B_{\phi}$ 283 and the sudden decrease of outbound  $B_{\phi}$  near 40  $R_j$  could not be reproduced by this 284 model perfectly. In general, the error  $(\sigma_{cur})$  of this model is 4.61 nT, which is good enough 285 for use. Comparing with other Juno-data-based models, Pensionerov, Alexeev, et al. (2019) 286 did not compare the results of the PCD model with  $B_{\phi}$  data. In the model from Pensionerov, 287 Belenkaya, et al. (2019),  $B_{\phi}$  component was not adequately described because radial cur-288 rents in magnetodisk are not included. So the inclusion of an asymmetric magnetodisc 289 current system and radial current makes our model a more reasonable one. 290

Fig. 8 shows a cross-section of magnetic field lines of the current sheet model combined with the JRM09 internal model. Due to the current sheet, the field lines are stretched outward along the magnetic equator. Also shown is the color-coded azimuthal current density, which is calculated numerically from curl  $B_{cur}$ . The thickness of the current sheet is assumed as  $5R_j$ . The current density increase with  $\rho$  if  $\rho < 11R_j$  and decrease if  $\rho >$  $11R_j$ .

One advantage of the TS07 method is that the direction and symmetry of the current sheet are not assumed in advance. So a radial current system is included in our model.



Figure 8. Cross-section of the field lines from the equatorial current system combined with the JRM09 internal field in the  $\phi = 0$  meridian plane.

As a result, the sweep-back effects of the field lines are also incorporated self-consistently. This effect is a unique feature of Jupiter's magnetosphere, as shown in Fig. 9. The spiral configurations of the field lines on the dusk and dawn sectors are illustrated in the JSO coordinate system. Also shown is the magnetopause with  $P_d = 0.045$  nPa.

#### 3.5 Model validation

In this section, we will compare the results from our model with in-situ observa-304 tions. To validate the applicability of our model, the data beyond PJ20 are used. These 305 data are not used for model construction and one example of PJ21 data is shown in Fig. 306 10. The blue lines represent the original 1-min averaged Juno data from PDS in System 307 III coordinates. The red lines are results from our model, including magnetic fields from 308 the planetary dynamo, the current sheet, and the magnetopause current. The results are 309 only shown from 5  $R_j$  to 60  $R_j$  for visualization reasons. Our model corresponds well 310 with the in-situ data. So this model is suitable for magnetic field prediction in Jupiter's 311 magnetosphere. 312

#### 313 4 Conclusions

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In this study, we attempt to develop a new global magnetic field model of Jupiter based on in-situ Juno data from PJ0 to PJ20. This modular model features a planetary dynamo, a variable magnetopause, and a cross-tail current sheet. The internal field is based on the JRM09 model, which is well determined through degree and order 10. The magnetopause shielding field is provided by minimizing the residual magnetic field component normal to the magnetopause. The variation of solar wind dynamic pressure is used to characterize the shape and currents on Jupiter's magnetopause.

In the modeling of Jupiter's current sheet, we use the TS07 method to construct 321 an asymmetric current system, which is more reasonable comparing to the previous mod-322 els. The curvature of the magnetodisk due to the solar wind effect is also incorporated 323 in the model. As a verification, the overall error of this model for PJ17 data is 4.61 nT 324 in the range from 5  $R_i$  to 60  $R_j$ . Furthermore, after minimizing the residual field com-325 ponent between in-situ data and the current sheet model, it is found that the magne-326 to disc normal is tilted from the magnetic axis by 0.85 °. The azimuthal current density 327 peaks at  $\rho \sim 11R_i$  and magnetic field lines are stretched outward along the magnetic 328 equator. After the inclusion of the radial with currents along the current sheet, the sweep-329



Figure 9. The view of some arbitrarily chosen field lines as seen from a point high above Jupiter.



Figure 10. Comparison of the observed and the modeled vector magnetic fields for PJ21.

(m,n)	1	2	3	4	5	6	7	8	9	10
1	1.17e2	-2.1e2	-2.4e2	4.9e2	-7.6e1	-2.6e2	-9.3e0	2.1e2	4.0e1	-1.2e2
2	-5.4e2	3.1e2	-3.2e0	-7.9e1	-3.5e1	$4.9\mathrm{e1}$	5.6e1	-1.8e1	-7.7e1	$3.3\mathrm{e1}$
3	5.6e2	-2.3e2	-4.0e0	$5.3\mathrm{e1}$	$2.7\mathrm{e1}$	-2.9e1	-4.1e1	2.1e1	$6.2\mathrm{e1}$	-5.7e1
4	4.5e3	-5.1e2	-4.1e1	$1.9\mathrm{e1}$	$2.3\mathrm{e1}$	1.0e1	-8.4e0	-1.1e1	5.8e0	8.8e0
5	-2.8e4	1.1e3	1.4e2	1.8e1	-1.3e1	-2.3e1	-1.6e1	1.2e1	3.1e1	-3.0e1
6	6.3e4	-2.3e3	-2.6e1	$3.5\mathrm{e1}$	$2.0\mathrm{e1}$	7.3e0	-4.1e0	-1.2e1	-6.9e0	1.6e1
7	1.3e6	-6.8e3	-6.9e2	-1.1e2	-1.7e1	5.7e0	1.1e1	1.1e1	$3.9\mathrm{e0}$	-1.5e1
8	-2.4e7	1.1e5	3.0e3	1.1e2	-2.5e1	-2.0e1	-1.1e1	-6.5e0	-2.0e0	6.3e0
9	1.8e8	-3.2e5	-9.1e3	-6.0e2	-3.5e1	1.6e1	1.6e1	1.1e1	4.5e0	-6.3e0
10	6.3e9	-6.2e6	$-9.7\mathrm{e4}$	-3.7e3	-1.7e1	1.1e2	$6.7\mathrm{e}1$	$3.3\mathrm{e1}$	8.4e0	-1.7e1

**Table A1.** Values of  $a_{mn}^{o}$  in Equ. 9. The row number corresponds with *m*-index and the column number corresponds with *n*-index.

**Table A2.** Values of  $a_{mn}^e$  in Equ. 9. The row number corresponds with *m*-index and the column number corresponds with *n*-index.

(m,n)	1	2	3	4	5	6	7	8	9	10
1	-3.7e2	4.0e2	-1.7e2	-1.3e2	8.4e1	9.7e1	-6.1e1	-8.2e1	7.3e1	-2.5e1
2	1.3e2	-8.1e1	2.2e1	2.8e1	5.4e0	-1.8e1	-1.8e1	3.3e0	2.7e1	-1.2e1
3	-3.6e2	1.9e2	-1.8e1	-3.4e1	-8.7e0	1.8e1	1.3e1	-1.2e1	-1.0e1	1.0e1
4	-6.9e3	7.3e2	6.4e1	-2.2e1	-2.8e1	-1.1e1	1.0e1	8.2e0	-1.2e1	$6.0\mathrm{e0}$
5	2.3e4	-1.2e3	-1.2e2	-7.5e0	$1.4\mathrm{e1}$	1.8e1	1.1e1	-9.8e0	-2.4e1	$1.4\mathrm{e1}$
6	2.5e5	-7.3e3	-3.0e2	$3.7\mathrm{e1}$	$4.2\mathrm{e1}$	$2.4\mathrm{e1}$	1.6e0	-2.2e1	-2.5e1	$3.4\mathrm{e1}$
7	1.1e6	-2.0e4	-3.3e2	9.5e1	4.8e1	1.4e1	-4.9e0	-1.6e1	-1.2e1	$2.4\mathrm{e1}$
8	7.8e6	-9.4e4	-1.1e3	1.5e2	$6.4\mathrm{e1}$	$1.9\mathrm{e1}$	4.0e0	-1.1e0	-1.6e0	-2.2e0
9	-4.8e8	9.8e5	2.4e4	1.2e3	1.8e0	-7.2e1	-5.3e1	-3.0e1	-7.7e0	$2.4\mathrm{e1}$
10	-5.5e9	5.9e6	9.4e4	3.8e3	$3.3\mathrm{e}1$	-1.2e2	-7.7e1	-3.8e1	-8.7e0	2.4e1

**Table A3.** Values of  $a_n^s$  in Equ. 9.

n	1	2	3	4	5	6	7	8	9	10
	5.0e2	-1.3e2	1.2e3	2.3e2	-3.3e2	5.1e2	5.8e2	-7.4e1	-4.7e2	6.9e2

back effects of Jupiter's magnetic field can also be illustrated by this model. Incorpo-

rating different parts of the modular model, we also compare the model with Juno's PJ21 data. The regults show that the model can repredive the charmenting mult

data. The results show that the model can reproduce the observations well.

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These coefficients can be found in the supporting information of Connerney et al. (2018).

#### <sup>339</sup> Appendix A Fitting coefficients of TS07 method

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