Tsunami Induced by the Strike-Slip Fault of the 2018 Palu Earthquake (Mw=7.5), Sulawesi Island, Indonesia

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Abstract

An unusual devastating tsunami occurred on 28 September 2018 after a strike-slip faulting earthquake in Sulawesi, Indonesia. The induced tsunami struck Palu city with 4-m wave height and flow depth. We performed a two-step analysis to investigate the source of the tsunami. We first conducted the teleseismic source inversion and obtained the slip distribution of the strike-slip fault. Our tsunami simulation from the coseismic deformation of the seismically-estimated strike-slip faulting produced a tsunami comparable to the leading part of the observation at Pantoloan. We then jointly utilized the tsunami waveform and Synthetic Aperture Radar (SAR) data to reconstruct the detailed slip distribution on the fault plane. Because of the lack of SAR data in the bay, the tsunami data is necessary to constrain the offshore slip distribution, which directly induces the tsunami. The inverted source model shows a strike-slip fault which consists of three segments extending from the epicenter to the south of 1.4°S with two bends and two asperities around Palu city. The joint inversion model accurately reconstructs the observed surface displacements and the leading part of the tsunami waveform. Our result exhibits the significant contribution of the strike-slip faulting to the tsunami, but it also suggests additional tsunami sources, such as landslides, for the high inundations near Palu bay. The result also indicates that regional devastating tsunamis can result from an onshore strike-slip fault with localized large dip slip.

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16	Key Points:
17 18	• The two-step analysis of teleseismic, SAR, and tsunami data retrieves an earthquake source model that explains the observed tsunami.
19 20	• A strike-slip fault with localized large dip slip of the 2018 Palu earthquake induced the devastating regional tsunami.
21 22	• Onshore strike-slip faults should also be regarded as a potential source of tsunami for regional areas.
23	
24	Abstract

24 Abstract

25 An unusual devastating tsunami occurred on 28 September 2018 after a strike-slip faulting earthquake in Sulawesi, Indonesia. The induced tsunami struck Palu city with 4-m wave 26 27 height and flow depth. We performed a two-step analysis to investigate the source of the tsunami. We first conducted the teleseismic source inversion and obtained the slip 28 29 distribution of the strike-slip fault. Our tsunami simulation from the coseismic deformation of 30 the seismically-estimated strike-slip faulting produced a tsunami comparable to the leading part of the observation at Pantoloan. We then jointly utilized the tsunami waveform and 31 32 Synthetic Aperture Radar (SAR) data to reconstruct the detailed slip distribution on the fault 33 plane. Because of the lack of SAR data in the bay, the tsunami data is necessary to constrain 34 the offshore slip distribution, which directly induces the tsunami. The inverted source model 35 shows a strike-slip fault which consists of three segments extending from the epicenter to the south of 1.4°S with two bends and two asperities around Palu city. The joint inversion model 36 37 accurately reconstructs the observed surface displacements and the leading part of the 38 tsunami waveform. Our result exhibits the significant contribution of the strike-slip faulting

to the tsunami, but it also suggests additional tsunami sources, such as landslides, for the high inundations near Palu bay. The result also indicates that regional devastating tsunamis can result from an onshore strike-slip fault with localized large dip slip.

42 Plain Language Summary

43 The Palu, Indonesia, earthquake of 28 September 2018 produced tsunami flooding and 44 damage in Palu city. Because of its strike-slip mechanism, which is not efficient to produce 45 tsunamis, multiple submarine landslides have been speculated as a tsunami source. We found that the fault model estimated by teleseismic waves (recorded globally outside Indonesia) can 46 reproduce the tsunami recorded at the Pantoloan station in Palu bay. This indicates that the 47 48 source of tsunami recoded at Pantoloan is mostly the fault motion accompanied by the 49 earthquake. We then combined the displacements measured by Synthetic Aperture Radar 50 images and the Pantoloan tsunami waveform to estimate the slip distribution on the fault. The 51 slip model shows a strike-slip fault with two large slip areas located near Palu city between 52 two bends. This model well reproduces the Pantoloan tsunami but fails to fully reproduce the 53 inundations in Palu city, suggesting that additional tsunami sources, such as landslides, 54 should be responsible for the large inundations in Palu city. Our result suggests that a strike-55 slip fault can induce a devastating local tsunami.

56 1 Introduction

57 On September 28, 2018, a devastating tsunami impacted Palu city, Sulawesi Island, 58 Indonesia (Figure 1) after an M7.5 earthquake. A moment tensor solution obtained by the 59 U.S. Geological Survey (USGS) from W phase waveforms suggests strike-slip faulting with a 60 high dip angle ($\sim 67^\circ$) at al shallow depth (~ 13 km). The estimated nodal plane strikes 61 approximately north-south (N10°W) with a rake angle of -17°, implying the presence of some 62 normal faulting component.

63 The Palu-Koro fault (Figure 1), the plate boundary between the Makassar block and 64 the North Sula block, is thought to be responsible for the Palu earthquake. Global Navigation 65 Satellite System (GNSS) monitoring shows that the relative velocity on the Palu-Koro fault 66 zone accommodates 42 mm/yr of a complex transtensive motion with a 39 mm/yr of strikeslip and 11-14 mm/yr of extension (Socquet et al., 2006). Three tsunami events associated 67 with the Palu-Koro fault zone have been reported in 1927, 1968, and 1996, of which the 1927 68 69 and 1968 earthquakes also caused destructive tsunamis in Palu bay (Prasetya et al., 2001). 70 Socquet et al. (2019) and Bao et al. (2019) pointed out that the 2018 earthquake might have 71 ruptured with a supershear velocity from the back-projection of the seismic wavefield and the 72 geodetic data.

A slip distribution obtained by USGS from teleseismic waveforms (United States Geological Survey, 2018) suggests an asperity with a maximum of more than 8 m slip under Palu bay. The source time function shows that most of the moment was released within 30 s after the earthquake origin time. Socquet et al. (2019) utilized horizontal offsets in SAR images to estimate the slip distribution and indicated a peak slip of more than 5 m of strikeslip and 2 m of reverse faulting dip-slip near the asperity.

Devastating tsunami inundations impacted the areas around Palu bay after the earthquake. High runups were measured by field surveys (Muhari et al., 2018; Omira et al., 2019; Yalciner et al., 2018; Paulik et al., 2019; Mikami et al., 2019). Flow depths of up to 5 m on the south coast of Palu bay (Palu City), up to 2 m observed on the east coast, and higher than 1 m on the west coast were observed. The tsunami waveform was recorded in the bay by a tide gauge at the port of Pantoloan (Figure 1). The other tide gauge located ~200 km outside
of the bay at Mamuju recorded tsunami waves from about 20 minutes after the earthquake
origin time. However, numerical simulations showed that the tsunami waves take at least 40
minutes from the source area to the Mamuju station (Heidarzadeh et al., 2019). Therefore, the
tsunami recorded at the Mamuju station is not considered to be directly originated from the
earthquake.

90 Sassa and Takagawa (2019) indicated that the earthquake caused extensive 91 liquefaction which induced liquefied sediment flows in the coastal area, resulting in the 92 devastating tsunami. Heidarzadeh et al. (2019) performed tsunami simulation using the 93 source model of USGS (United States Geological Survey, 2018). They fairly well 94 reconstructed the tsunami waveform at Pantoloan although the wave height was slightly 95 underestimated. They mentioned that a large submarine landslide may intensify the tsunami. 96 Gusman et al. (2019) focused on the vertical displacements around the narrow bay that 97 generated the tsunami. They concluded that the tsunami inundation was caused by a 98 combination of the earthquake faulting, landslides, and the high tide time of the event.

99 Ulrich et al. (2019) used a physics-based, coupled earthquake-tsunami model to 100 demonstrate that the tsunami wave and inundations were mainly generated by the earthquake deformation and suggested that landslide may not be the primary source of the tsunami. Fang 101 et al. (2019) investigated the source geometry and rupture using the SAR interferometry 102 103 (InSAR) of ALOS-2 images and regional broadband seismograms. Their rupture model shows a rupture propagated mainly southward and a major asperity located at the south of 104 105 Palu bay with a maximum slip of 6.5 m. They concluded that the offshore asperities with 106 significant normal-slip components are responsible for the tsunami.

107 Yolsal-Çevikbilen et al. (2019) inverted the teleseismic waveforms to estimate the slip 108 distribution. Their model shows an asperity concentrated in the bay area, and they suggested 109 that the normal faulting could be partially responsible for the tsunami in Palu bay. However, 100 Lee et al. (2019) expected a smaller tsunami than the observation from their inversion of 111 teleseismic waveforms. Besides coseismic effects, they suggested that other sources, such as 112 a submarine landslide, are possible to account for the local tsunami.

113 The primary tsunami source is still controversial and the contribution of the 114 earthquake fault motion to the generation of tsunami is not well clarified, although strike-slip 115 faulting is generally considered not to generate a devastating tsunami. To better understand 116 the tsunami generation by a strike-slip fault, we performed a two-step analysis that utilized 117 teleseismic, SAR, and tsunami data to examine the contribution of the fault slip to the 118 tsunami generation and estimate the slip distribution on the fault plane.

119

120 **2 Data**

121 2.1 Teleseismic Body and Surface Waveforms

122 The teleseismic records from the Global Seismograph Network (GSN) which provides 123 good azimuthal coverage for inversion (Figure S1) were utilized to estimate the slip 124 distribution of the Palu earthquake. The passbands for the body and surface waves are 1-180 s 125 and 200-500 s, respectively.

126

127 2.2 Surface Displacements from SAR Data

Sub-pixel correlation of SAR intensity images before and after an earthquake provide a high-resolution measurement of coseismic surface displacements (e.g., Michel et al., 1999). The azimuth offsets, displacements in the azimuth direction, extracted from the Sentinel-1 satellite images exhibit clear displacement offsets, from which we can constrain the geometry of the surface faulting.

133 In order to measure coseismic displacements, we used Sentinel-1 satellite images on 7 134 June 2018 and 5 October 2018 from the descending orbits, and on 13 March 2017 and 4 October 2018 from the ascending orbits. It is difficult to generate interferograms with C-band 135 images due to temporal decorrelation and large surface deformation. Therefore, we used the 136 137 two Single Look Complex (SLC) radar images, of which pixel spacing is 2.3 m and 14.1 m in 138 the range direction and azimuth direction, respectively, and we calculated the azimuth offset 139 from the correlation between two radar amplitude images by the pixel-tracking method (e.g., 140 Michel et al., 1999). The window size to measure correlations is 128 x 128 pixels and the 141 sampling spacing is 12 x 12 pixels in size to achieve a spatial resolution of 28 m in the range 142 direction (12 x 2.3 m) and 170 m in the azimuth direction (12 x 14.1 m).

The SAR images well exhibited the trace of the rupture on the surface. Figure 2a shows the azimuth offset from the descending images with a maximum of ~8 m relative displacement across the fault, and the ascending image in Figure 2b exhibits the relative displacement of ~5 m. The fault geometry was constrained by the trace on the surface as shown in Figure 2. The strike varies along the fault trace and the rupture can be divided into three segments by a restraining bend near 0.7°S and a releasing bend near 1.2°S. Large offsets appeared between two bends.

Although the displacements obtained from the azimuth offsets contain more noise than interferograms, this method allows us to measure large displacements where InSAR does not work; InSAR cannot provide displacements in places where the displacement coherence is low (Wright et al., 2005). In addition, the average uncertainty of pixel offset is 1/10 of the pixel size in the azimuth and range directions (Michel et al., 1999).

155

156 2.3 Tsunami Waveform

We used the tsunami record of the tide gauge at the port of Pantoloan (the location is shown in Figure 1b) maintained by the Geospatial Information Agency (Badan Informasi Geospasial, BIG) of Indonesia. The sea level is recorded every 60 s. We de-tided the raw data by removing the long period (> 3 hr) tidal constituents, but no resampling or interpolation was applied to the observed data. The Pantoloan station observed an arrival of tsunami wave about 4 min after the earthquake with a maximum wave height (trough to crest) up to 4 m (Figure 3).

An obvious waveform change appears about 8 min (after the red-shaded window in Figure 3b) after the earthquake which may result from the combination of waveforms from different sources. Thus, to ensure that only the leading tsunami wave is used, we utilized the record of the first 8 min from the origin time. Although there is only one available station with observed data, the tsunami signal provides important information on the slip offshore area where no SAR observations were available.

170

171 **3 Method**

172 3.1 Teleseismic Source Inversion

173 The location of the rupture initiation was fixed at the hypocenter determined by 174 USGS (119.846°E, 0.256°S, 20 km). A simple fault geometry of an east-dipping plane with a strike of 354° and a dip of 66° (see Aki & Richards, 2002 for angle definitions) was adopted 175 176 for the teleseismic source inversion. The modeled fault plane is rectangular with a length 177 (along the strike) of 205 km and a width (along the down-dip) of 37 km. The fault plane was divided into subfaults with a size of 5 km x 3.7 km. Variable rupture velocities between 1.5 178 179 and 4.5 km/s are allowed. To invert for the slip distribution of the Palu earthquake, we 180 computed the Green's functions for the spherically symmetric 1-D velocity model of PREM 181 (Dziewonski & Anderson, 1981) with replacing the shallow layers by the model of 182 CRUST2.0 (Bassin et al., 2000).

183 The slip distribution was estimated by the wavelet-decomposition inversion technique 184 of Ji et al. (2002). The wavelet-decomposition technique gives an optimal resolution of long-185 and short-period signals in the time domain, which corresponds to slip zones (i.e. asperities) of different scales on the fault plane. Ji et al. (2002) demonstrated that this method provides 186 relatively robust and well-resolved slip features by resolution analyses. Furthermore, the 187 188 inversion scheme solves inverse problems with a large number of free parameters based on a 189 grid-search scheme with optimization of the Simulated-Annealing algorithm (Rothman, 190 1986). Thus, the wavelet-decomposition scheme permits us to invert for the slip amplitude, 191 slip direction, rise-time, and rupture speed simultaneously and efficiently.

192 3.2 Tsunami Simulation

We computed the tsunami propagation by applying the shallow water equations (SWE), which account for tsunami arrival time and waveforms with high accuracy. Explicit finite-difference methods have been implemented to solve the SWE in numerical models. These SWE models perform fast and efficient computations and have been widely used in tsunami research (Satake et al., 2013; Ho et al., 2019). We applied the validated model JAGURS (Baba et al., 2015) to solve linear SWE for the Green's functions in the inversions and nonlinear SWE for the inundation evaluation.

200 To evaluate the dispersion effect, we computed the non-dispersive and dispersive 201 tsunami waveform at Pantoloan and compared them with each other. We first assumed a 202 tsunami source comparable to the 2018 Palu earthquake and simulated the tsunami at 203 Pantoloan by applying the linear SWE to obtain a non-dispersive tsunami waveform. We then 204 converted the non-dispersive waveform into a dispersive waveform utilizing the phase-205 correction method (Watada et al., 2014; Ho et al., 2017). In Figure S2, the dispersive 206 waveform (red dotted line) is almost identical to the non-dispersive waveform (black line). 207 Because the only tide gauge Pantoloan locates in the source area that recorded the tsunami 208 waves a few minutes after the earthquake, we confirmed that the wave dispersion effect is 209 ignorable in this study.

A nested-grid system built in JAGURS was utilized to calculate the waveforms and evaluate the inundation along the shoreline. We utilized three-level nested-layers to acquire accurate calculations where a grid size of 6" (~180 m) for Layer 1 (Figure 1a), 2" (~60 m) for Layer 2 (Figure 1b), and 2/3" (~20 m) for Layer 3 (Figure 1b) were used. The bathymetry for Layer 1 was based on the national bathymetric data of Indonesia (BATNAS) with 6" spatial resolution. For levels 2 and 3, we used the bathymetric and topographic data with a higher resolution of 0.27" obtained from the national digital elevation model of Indonesia (DEMNAS). Both BATNAS and DEMNAS were provided by the BIG of Indonesia. To
improve the inundation modeling, the DEM (digital elevation model) of Layer 2 and 3 were
further corrected by the high-resolution bathymetric contour and topographic data (see
Gusman et al., 2019). We utilized the finest grid, Layer 3, to compute the tsunami Green's
functions for our joint inversion.

We introduced a correction term for water depth change due to permanent seafloor deformation to the Green's functions in our inversion. The Pantoloan station located in the source area should be subsided by the permanent vertical seafloor deformation as shown in Gusman et al. (2019). The recorded tsunami waveform contained the sea surface variation (water wave) and the seafloor deformation. To accurately estimate the tsunami source, we applied the correction for coseismic displacement to incorporate the permanent seafloor deformation into the Green's functions.

229 3.3 Contribution of Horizontal Deformation on Tsunami Generation

We further calculated the vertical water displacement generated by horizontal deformation acting on bathymetric slopes. Although strike-slip faulting generates small vertical displacement, large horizontal deformation can induce additional vertical water displacement in the presence of bathymetric slopes, strengthening tsunamis. The vertical sea surface displacement is given by (Tanioka & Satake, 1996):

$$u_h = u_x \frac{\partial H}{\partial x} + u_y \frac{\partial H}{\partial y},$$

where u_h is the vertical displacement on the sea surface induced by the horizontal 235 deformation of the seafloor, H is the water depth and u_x and u_y are the horizontal seafloor 236 displacements. u_h is positive upward but H is positive downward (depth). The total vertical 237 displacement at the surface of the seawater is represented by $u_{z'} = u_h + u_z$, where u_z is the 238 vertical displacement of the seafloor. u_x , u_y , and u_z are calculated by applying the model of 239 Okada (1985). Figure S6 shows the vertical displacement due to horizontal deformation u_h 240 241 induced by the joint inversion model in section 4.3. Up to 0.6 m of vertical displacements 242 were generated.

243 3.4 Configuration for Joint Inversion

244 The fault was divided into three segments by a restraining bend near 0.7°S and a releasing bend near 1.2°S (Figure 2). The strike varies along the fault trace: segment 1 strikes 245 N2°W (358°) extending 50 km southward from the epicenter to the restraining bend near the 246 247 bay, where the surface displacement shows a rupture extending southwestward to the bay 248 (Figure 2). In segment 2, the strike changed to N8°W (352°) from the offshore area south of 249 the restraining bend and extended another 50 km to the releasing bend at about 1.2°S where 250 large surface displacements are presented. Segment 3 extended 20 km from the releasing bend to approximately 1.4°S with a strike N11°W (349°). 251

252 We discretized the fault plane into 4 by 29 subfaults, each of which has a size of 5 km by 5 km with an eastward dip angle of 66°. The rake angle is allowed to vary between -45° 253 and 45° where the strike-slip with normal or reverse components is incorporated. We 254 255 calculated the Green's functions of azimuth offsets and tsunami waveforms under an 256 assumption of faulting embedded in the elastic half-space theory (Okada, 1985). We then 257 projected the computed surface displacements to the azimuth direction of the SAR satellite 258 and resampled the tsunami Green's functions to match the time interval of observed tsunami 259 waveform.

We applied the nonnegative least-square method with Tikhonov regularization to acquire the slip distribution on the subfaults. In the joint inversion, the equation is given by:

262
$$\begin{bmatrix} \mathbf{B}_{S} \\ \mathbf{B}_{\tau} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} = \begin{bmatrix} \mathbf{G}_{S} \\ \mathbf{G}_{\tau} \\ \lambda \mathbf{I} \\ \gamma \mathbf{L} \end{bmatrix} \mathbf{X}^{T}$$

where $\mathbf{B}_{\mathbf{S}} = \mathbf{b}^{k}$ is the column vector of observed SAR images where k = 1 to 2 represents 263 the azimuth offsets of the descending and ascending SAR images, G_S is the matrix of azimuth 264 offsets Green's functions S_j^k , corresponding to the observation b^k , from the *j*th subfault, 265 where j = 1 to M, the number of subfaults. $\mathbf{B}_{\tau} = \beta \mathbf{p}$ is the column vector of the observed 266 tsunami waveforms p at Pantoloan weighted by $\beta = 20$. $\mathbf{G}_{\tau} = \beta \boldsymbol{\eta}_j$ is the matrix of tsunami 267 Green's functions η_i for the *j*th subfault weighted by β . $X = [x_i]$ is the unknown raw vector 268 of the amplitude for the *j*th subfault, where *j* counts for columns. The regularization factor 269 $\lambda \mathbf{I} \mathbf{X}^{T}$ stabilizes the inverse problem, where the $\lambda = 1$ and \mathbf{I} is the identity matrix. We adopted 270 Laplacian operator $\gamma LX^T = 0$ as the spatial smooth constraint, where $\gamma = 1$ is used. 271

272 4 Results of Two-step Analysis

273 4.1 Teleseismic Source Inversion

274 Figure 4 compares observed and synthetic waveforms of 44 body-waves and 41 275 surface-waves, respectively, indicating that the synthetic waveforms fit well the observed 276 body and surface waves. Figure 5 shows the estimated slip distribution, which presents a 277 single distinct region of slip concentration. This slip distribution suggests that the center of 278 asperity is located at about 50 km south of the hypocenter. The surface projection of asperity 279 is right in the bay, which might account for the induced large tsunami height. The maximum 280 slip in the asperity is about 4.85 m with less slip to the north and below the hypocenter on the fault plane. The spatial slip distribution and its rupture time suggest that a strike-slip rupture 281 282 propagates obliquely from the hypocenter to the south as a unilateral rupture with an average rupture velocity ~3 km/s. Figure S3 shows the moment rate function of the inversion. The 283 estimated seismic moment is 2.78×10^{20} Nm, which is equivalent to M_w 7.56. 284

The inverted source model was used to compute the tsunami waveform. Figure 6a shows the computed tsunami waveform compared with the observed tsunami at Pantoloan. The coseismic vertical deformation is shown in Figure S5. The computed tsunami waveform is similar to the observed waveform with a slight phase shift and a smaller amplitude. The fact that the observed tsunami waveforms are explained by the computed one from the slip distribution estimated from teleseismic waveforms implies that the observed tsunami was induced directly by the fault slip.

292 The teleseismic inversion model (Figure 5) reconstructs the teleseismic body and 293 surface waves with a main asperity concentrating near the bay area. However, no asperity 294 was inverted between 1.0°S to 1.4°S where large offsets were observed by SAR. Contrary to 295 slip distribution inverted from SAR images that are well constrained in a shallow depth, the 296 slip distribution obtained from teleseismic waveforms exhibits a general rupture pattern on 297 the whole fault plane. Because we considered wave propagation in the 1-D velocity model and used long-period waves (e.g., 1-180 s for body wave and 200-500 s for surface wave) in 298 299 our inversion which correspond to wavelengths of hundreds of kilometers, the inversion 300 result reflects an overall response of the fault plane. Thus, the south asperity might not be 301 revealed by the teleseismic inversion.

302

303 4.2 SAR-only Inversion

304 We then estimated the fault slip distribution with only SAR data, which consists of two horizontal-direction displacement fields (N20°W and S20°W). The estimated slip 305 distribution in Figure 7a shows the inverted slip distribution, which was decomposed into 306 dip-slip and strike-slip components presented in Figure 8. The inverted source model exhibits 307 a peak slip of up to 9 m at 1.1°S north of the releasing bend and an asperity with about 7 m 308 309 slip in Palu bay south of the restraining bend. A smaller asperity with about 5 m slip is located south of the epicenter. Large strike-slip was retrieved at a shallow depth of ~10 km. 310 The dip-slip component is generally small. The maximum dip-slip is located at the south of 311 312 the epicenter with ~3 m normal slip. Very weak oblique slip was found near the releasing 313 bend, where shows a normal slip up 1.6 m. Weak oblique slip with reverse-slip of about -1.7 m was retrieved in the restraining bend area. Large normal slip was retrieved at ~1.0°S to 314 315 explain the surface offsets by SAR images (Figure 2).

Figure 6b shows the computed tsunami waveform from the inverted slip model compared with the observation at Pantoloan. The coseismic vertical deformation is shown in Figure S5. The computed tsunami waveform underestimates the observation and fails to match the phase of the first wave. We calculated the characteristic focal mechanism of the fault plane by averaging the moment tensor of all subfaults. The nodal plane strike/dip/rake was 352°/65°/-9°.

322

323 4.3 Joint Inversion

To circumvent the poor capability of reconstructing offshore fault slip by SAR images, we performed the joint inversion utilizing the tsunami and SAR data. Because SAR images only provide coseismic surface displacements on land, the derived offshore slip distribution is less constrained than that on land. Tsunami generation is mainly controlled by offshore fault slip; therefore, tsunami data provides good constraint and more information on offshore slip.

The joint inversion (Figure 7b) exhibits a slip distribution similar to the one obtained 329 330 by the SAR-only inversion (Figure 7a), but the slip is noticeably different in the bay area 331 between 0.65°S and 0.9°S. We decomposed the slip into dip-slip and strike-slip components shown in Figure 9. Compared to the weak oblique slip in the restraining bend estimated by 332 333 the SAR-only inversion, the joint inversion retrieved strike-slip faulting in the bend area. 334 Very weak oblique slip was again retrieved in the releasing bend area at 1.2°S as retrieved by 335 SAR-only inversion. Large dip-slip normal components of 2-4 m appear in the bay area after 336 we added tsunami data to the inversion. This offshore area is less constrained by the SAR 337 images, and the normal components are required to explain the observed tsunami waves.

The slip amount along the rupture in Figure 9c exhibits two main asperities with slip larger than 9 m between two bends, one at ~1.1°S north of the releasing bend, which was also retrieved by SAR-only inversion, and another in the southern bay area, which was constrained by tsunami data. A small asperity at the south of the epicenter is also presented to explain the surface offsets. The inversion also well reconstructs the observed azimuth offsets in the descending and ascending SAR images. Figure S4 shows the misfits of the azimuth offsets, where the misfits are smaller than 1 m in most of the source area.

The joint inversion model reconstructs well the observed waveform as shown in Figure 6c, which is significantly improved than the SAR-only inversion. The synthetic tsunami matches well the phase and amplitude of the leading part in the observation. The unusual waveform appeared from 8 to 15 minutes after the earthquake with a 3-m wave (Figure 6c) could be a result of the reflection or nonlinear effects of the bay. The simulated tsunami is much smaller than that observed at Mamuju (Figure S7), where the tsunami may come from another source. Other than the earthquake, a landslide was also considered as a secondary or main source (Carvajal et al. 2019; Gusman et al., 2019; Sassa & Takagawa, 2019). The coseismic vertical deformation is shown in Figure S5.

354 The nodal plane strike/dip/rake calculated from the joint inversion slip distribution 355 was 352°/64°/-13°, which is very close to the one by SAR-only inversion and compatible with the plane by the Global CMT solution of 348°/57°/-15° (Dziewonski et al., 1981; 356 Ekström et al., 2012) and the USGS W-phase Moment Tensor solution of 350°/67°/-17° by 357 358 the United States Geological Survey (2018). Although the characteristic focal mechanism 359 shows strike-slip faulting on the fault plane, the local dip-slip components are still able to generate a regional devastating tsunami in Palu bay. The finite-fault parameters of the joint 360 361 inversion model are provided in Supporting Information.

362

363 4.4 Tsunami Inundation

364 To evaluate the tsunami inundation, we applied the nonlinear SWE to the finest grids Layer 3, which covered the entire coast of Palu bay, as noted in section 3.2. We adopted the 365 366 slip model inverted by the joint inversion (Figure 7b) as the initial condition. According to 367 the tide prediction of BIG, the tsunami occurred during the high tide, so we considered the 368 sea-level rise for 1 m when computing the flow depth. We divided the coast of Palu bay into 369 three parts by the west, south, and east coasts. The Palu city is located on the south coast. The overall impacts to the coastal communities along the west and east coasts were less severe 370 than the south coast because of the steep topography in those areas on the west and east 371 372 coasts.

Figure 10a, 11a, and 12a show the estimated flow depth for the south coast (Layer 374 3-4), west coast (Layer 3-5 to 3-7), and east coast (Layer 3-1 to 3-3), respectively. The estimated flow depth was also compared to the field measurements (Mikami et al., 2019; Paulik et al., 2019) in Figure 10b, 11b, and 12b. We also computed the maximum flow depth on the coastline represented by blue blocks in Figure 10b, 11b, and 12b.

378 On the south coast, high flow depths were measured near the mouth of Palu River and 379 decreased westward and eastward. Up to 4-m-high flow depths were measured at the two 380 sides of the mouth of Palu River, where we partially reproduced the flow depth by about 1-2 381 m height at the measuring positions. The measured flow depths reduce to smaller than 2 m on 382 the area further east of the river mouth. We had a good estimation near 119.865°E with ~1 m flow depth. On the west side of the river mouth, we reproduced the flow depths on the coast 383 between 119.84°E and 119.85°E. Further west of 119.84°E, the flow depth increased to up to 384 385 5 m, but the estimated flow depth decreased to only 0-2 m high.

Figure 11 shows the result for the west coast. Our model caused up to 5 m flow depth on the coastline, but the inundation distance was so short and we could not reproduce the flow depth at the measured locations. On the east coast shown in Figure 12, we estimated flow depths of higher than 5 m on the coastline between 0.75°S and 0.85°S. Our model induced higher flow depth and longer inundation distance on the east coast than the west coast. The estimated inundation shows a general pattern similar to the observation that the inundation is stronger on the south coast and weaker on the east and west coasts. Our model reproduces the flow depths in some places on the south coast but underestimates the inundations on the west and east coasts and some parts of the south coast. This result suggests that the general pattern of the tsunami source is reproduced and implies a secondary source to account for the local high flow depths, such as a landslide.

398

399 **5 Discussion**

400 In the teleseismic source inversion, a simple rectangular fault geometry is applicable. 401 Koketsu et al. (2011) and Yokota et al. (2011) have performed separate and joint inversions 402 utilizing teleseismic, strong motion, geodetic, and/or tsunami data to estimate the source of 403 the 2011 Tohoku earthquake. They exhibited checkerboard resolution tests and real case 404 inversions and pointed out that teleseismic-data-only inversions show limited spatial 405 resolution. Our teleseismic source inversion utilizes low-frequency body and surface waves. 406 The result resolves a characteristic source mechanism with a general slip distribution rather than the details such as small asperities. Thus, a simple rectangular fault geometry is 407 408 applicable for the teleseismic source inversion. In other words, because teleseismic-data-only 409 inversion is not sensitive to subtle slip variations but resolves a smooth slip model, we can 410 expect a similar inverted slip model if we apply a complex geometry with the same method. However, the induced tsunami by the slip model is controlled by local offshore slip, so a 411 412 similar slip distribution could induce very different tsunami waves. The source model estimated by the teleseismic source inversion located the major asperity at shallow depth in 413 414 the bay area and the computed tsunami implied that the observed tsunami waveform can be 415 explained by fault rupture. We then carried out the joint inversion of SAR and tsunami data to estimate the detailed slip distribution. 416

417 To estimate a detailed slip distribution, we applied a complex fault geometry for the joint inversion and the SAR-only inversion. The offsets in different directions recorded by 418 419 SAR images revealed a clear rupture trace that allowed us to determine a complex fault 420 geometry, which was appropriate for the SAR-only inversion and joint inversion to retrieve a 421 detailed slip distribution. Due to the clear boundary of offsets of different directions, if we 422 apply a simple geometry to the SAR-only or joint inversion, we will fail to fit the offsets 423 somewhere, e.g., the bend areas. The SAR images have no contribution to the bay (sea) area, 424 where the offshore slip is only constrained by the adjacent land offset records in SAR-only 425 inversion. In contrast, tsunami waves, which are induced by offshore displacement, provide 426 good constraints for the offshore area. By adding tsunami data to the inversion, we can 427 retrieve the slip distribution that generates the observed tsunami waveform. Although the 428 SAR images dominated the joint inversion because they recorded the land offsets of most of 429 the rupture area, the tsunami data still provide an important contribution to the offshore slip. 430 Figure 7 exhibits noticeable slip differences in the bay area that indicates the indispensable 431 contribution of tsunami data to the joint inversion.

Our inversion results are comparable to other studies in some parts. Our SAR-only inverted model exhibits weak oblique slip near the retraining and releasing bends, which is comparable to the results of Socquet et al. (2019) and He et al. (2019). Socquet et al. (2019) estimated oblique slip with comparable strike-slip and dip-slip components in the bay area and the releasing bend at 1.2°S and 0.2°S. He et al. (2019) had a similar source model on their onshore segments. The restraining bend area is located in the bay area, where different slip was retrieved. Our joint inversion model retrieved normal slip near the bay, which were also estimated by Ulrich et al. (2019), who addressed a regional releasing beneath the bay and
retrieved 2-m normal slip in the bay area, and Fang et al. (2019) also estimated normal slip up
to 2 m in Palu bay. Lee et al. (2019) estimated an oblique-to-normal slip from the epicenter to
the bay at a ~15 km depth.

An offshore normal fault based on the bathymetry was added by Song et al. (2019) and He et al. (2019). According to Song et al. (2019), the additional normal fault improved the misfit of InSAR data for the northwest island further north of 0.3°S. The inverted slip distribution is identical to the one without an additional segment in the area further south of 0.5°S. Although they claimed that the normal fault may be the source of the tsunami, the northwest offshore segment is too far to be the source for the leading tsunami wave. However, the predicted tsunami at Mamuju may be improved by an offshore segment.

450 The observed tsunami wave was neither explained by the strike-slip displacement (Lee et al., 2019), the oblique slip (Socquet et al., 2019), nor an additional offshore normal-451 faulting segment (Song et al. 2019). Ulrich et al. (2019) retrieved normal slip in the bay area 452 453 and their model reproduced the magnitude of the tsunami wave. Our joint inversion source 454 model reconstructed the tsunami waveform at Pantoloan and the flow depths in some areas on the south coast, but failed to reproduce the local high flow depth in other places. The 455 underestimation can be contributed by some factors, for example, the precision of measuring 456 457 positions, accuracy of topographic data, the inverted model, and additional sources. The error 458 of measuring position can result from device error and inherent positioning error of different 459 signal conditions, but it can only explain some specific positions.

460 The accuracy and precision of the topographic data can be discussed separately. The topographic data, which was provided by BIG, should be accurate for tsunami inundation 461 computation, but the DEM does not include the urban land cover, e.g., buildings and streets, 462 463 which could generate estimation errors. According to the study of Ali et al. (2015), DEMs in different resolutions did not show significant differences in flood assessment. The quality and 464 465 accuracy of a DEM are more important than the resolution and precision. Savage et al. (2016) demonstrated that the performance of deterministic simulations degrades as resolution coarser 466 than 50 m, and has little improvement when resolution finer than 50 m. We applied the high-467 resolution bathymetric contour and topographic data from BIG to construct our Layer 2 and 468 Layer 3, where the Layer 3 has the finest resolution of 20 m (east-west direction) by 13 m 469 470 (north-south direction). Although the buildings and streets are not included on top of the 471 topography in the DEM, the resolution should be applicable to approximately estimate the inundation for source assessment. Future work to explore the detailed flood in the city should 472 473 consider the urban land cover.

474 Since we reconstructed well the tsunami wave at Pantoloan and partially reproduced 475 the flow depth of the south coast, the characteristic pattern of the tsunami should be retrieved 476 by our source model. A secondary source is a reasonable explanation for the local high flow 477 depths. Although landslide events were suggested by previous studies (Carvajal et al., 2019; 478 Gusman et al., 2019; Sassa & Takagawa, 2019), the precise location and dimension are still 479 controversial. Future investigation and exploration will provide more evidence and uncover 480 the puzzle.

481 6 Conclusions

To examine if the tsunami can be induced by the rupture displacements, we performed a two-step analysis of the 2018 Palu earthquake by performing two inversion methods with two different data sets: step one, the teleseismic source inversion, and step two, the SAR-only inversion and the joint inversion of SAR and tsunami data. 486 Our teleseismic source inversion indicated that a strike-slip rupture propagated from 487 the hypocenter to the south, with the major asperity located at about 50 km south of the hypocenter in the shallow part. The observed tsunami waveform at Pantoloan was explained 488 489 by the slip distribution, suggesting that the strike-slip faulting with localized dip-slip was the 490 major cause of the tsunami. We then estimated the fault slip distribution with only SAR data, 491 but the computed tsunami could not reproduce the observed tsunami waveform, because the 492 offshore slip was not well resolved. The joint inversion of SAR and tsunami data shows a 493 strike-slip fault which consists of three segments extending from the epicenter to the south of 1.4°S with two bends and two asperities around Palu city. The tsunami data provides 494 495 necessary information to reconstruct the slip distribution inside the bay that reproduces well 496 the observed tsunami waveform at Pantoloan and part of inundations in Palu city. However, 497 to fully explain the high inundations near Palu bay, additional sources, such as landslides, are 498 also suggested. We provide the parameters for the finite faults of the joint inversion in the 499 supporting information Dataset S1.

500 Finally, this study points out that local devastating tsunamis can result from a strike-501 slip fault. This suggests that offshore and/or onshore strike-slip faults should be considered in 502 tsunami hazard assessment to account for regional tsunamis.

503

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- 644 645

646 Figure 1. The three layers for computing the tsunami waveforms and inundations. (a) The 647 entire computational domain of Layer 1 and the region of Layer 2. The Red star indicates the 648 epicenter, and the white circles show the aftershocks of M4.0 to M5.9 within two months after the mainshock provided by the USGS Earthquake Catalog. (b) The domain of Layer 2 649 and the seven black rectangles indicate the areas of Layer 3 where the numbers from 1 to 7 at 650 651 the southeast corner represent the Layer 3-1 to 3-7. The blue inverted triangle indicates the tide gauge at Pantoloan. The magenta dots show the locations of inundation/flow depth 652 653 observations.

654

Figure 2. Azimuth offsets from (a) descending (S20°W) and (b) ascending (N20°W) images observed by Sentinel-1. The red stars show the epicenter of the earthquake. The black and green arrows indicate the azimuth and range directions, respectively.

658

Figure 3. The tsunami waveform recorded by the Pantoloan tide gauge. (a) shows the raw data, (b) is the de-tided waveform. The red-shaded window shows the signals used in the inversions.

662

Figure 4. Waveform comparisons between observed (black) and synthetic (red) (a) teleseismic body waves and (b) teleseismic surface waves. In each panel, station and phase IDs are labeled on the left. Phase IDs are abbreviated as follows: 'P' for P wave, 'SH' for SH wave, 'RA' for Rayleigh wave, and 'LO' for Love wave, respectively. The numbers above and below the beginning of each trace indicate azimuth relative to the source and epicentral distance, both in degrees. The observed peak ground displacement in micrometers is shown at the end of each trace.

670

Figure 5. The slip distribution of the Palu earthquake in (a) map view and (b) cross-section. The gray star denotes the hypocenter. In (a) and (b), the background color on the fault plane indicates the amount of slip. In (b), the rake angle is indicated by the arrow at each subfault center. The contours represent the elapsed time the rupture from its onset in seconds with a contour interval of 5 s.

676

677 **Figure 6.** Waveform comparisons between the observed and calculated waveforms by (a) the 678 teleseismic inversion, (b) the SAR-only inversion, and (c) the joint inversion model. The 679 blue-shaded windows indicate the data used in our inversion.

680

Figure 7. Slip distributions derived from (a) the source inversions with only SAR images and
(b) the joint inversion with SAR and tsunami data. Color and arrows indicate the slip
amplitude and the rake angle, respectively. The star denotes the epicenter.

684

Figure 8. Slip distribution of (a) dip-slip and (b) strike-slip components, and (c) slip amount
estimated by SAR-only inversion. Negative indicates the reverse-faulting component in (a).
S-Bend represents the releasing bend and N-bend indicates the restraining bend. The star
indicates the hypocenter.

689

Figure 9. Slip distribution of (a) dip-slip and (b) strike-slip components, and (c) slip amountestimated by joint inversion.

692

Figure 10. The estimated flow depth on the south coast of Palu bay in Layer 3-4. (a) The computed flow depth is shown in color. Dark crosses indicate the measuring positions of field surveys. (b) The observed (dark crosses) and computed (red circles) flow depth at measuring positions of field surveys. The blue blocks represent the computed maximum flow depths on the coastline.

698

Figure 11. The estimated flow depth on the west coast of Palu bay for Layer 3-5 to 3-7. (a)Dark crosses indicate the measuring positions of field surveys. (b) The dark crosses show the

- 701 observed flow depth at measuring positions of field surveys. The blue blocks represent the computed maximum flow depths on the coastline. 702
- 703
- 704 Figure 12. The estimated flow depth on the east coast of Palu bay for Layer 3-1 to 3-3. (a)
- Dark crosses indicate the measuring positions of field surveys. (b) The dark crosses show the 705 observed flow depth at measuring positions of field surveys. The blue blocks represent the
- 706
- 707 computed maximum flow depths on the coastline.

708

Figure 1.





(a)

Figure 2.



(a)

Figure 3.







Figure 4.









Figure 5.





Figure 6.



Figure 7.



Figure 8.



Figure 9.



Figure 10.

(a)



Figure 11.





Figure 12.



