Evaluation of evapotranspiration models using different LAI and meteorological forcing data from 1982 to 2017

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Abstract

We evaluated the performance of three global evapotranspiration (ET) models using the multiple sets of LAI and meteorological data from 1982 to 2017, and investigated the uncertainty in ET simulations from the model structure and forcing data. The three ET models were the Simple Terrestrial Hydrosphere model (SiTH), Priestly-Taylor Jet Propulsion Laboratory model (PT-JPL) and MODIS ET algorithm (MOD16). Comparing the observed with simulated monthly ET by the three models over 43 Fluxnet sites, we found that SiTH overestimates ET for forests, but it performed better than the other two models over short vegetation. MOD16 and PT-JPL models performed well for forests, but poorly in dryland biomes. At the catchment scale, all models perform well expect over some tropical and high latitudinal catchments. At the global scale, SiTH highly overestimated ET in tropics, while PT-JPL underestimated ET between 30°N and 60°N and MOD16 underestimated ET between 15°S and 30°S. This study also revealed that the estimated ET by PT-JPL were largely influenced by the uncertainty in meteorological data, while the estimated ET by SiTH and MOD16 were relatively non-sensitive to the forcing data sets. In addition, the results suggested that the long-term variations in estimated ET trend were greatly influenced by the uncertainty in LAI data.

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26 Abstract:

We evaluated the performance of three global evapotranspiration (ET) models 27 28 using the multiple sets of LAI and meteorological data from 1982 to 2017, and investigated the uncertainty in ET simulations from the model structure and forcing 29 30 data. The three ET models were the Simple Terrestrial Hydrosphere model (SiTH), Priestly-Taylor Jet Propulsion Laboratory model (PT-JPL) and MODIS ET algorithm 31 (MOD16). Comparing the observed with simulated monthly ET by the three models 32 over 43 Fluxnet sites, we found that SiTH overestimates ET for forests, but it 33 performed better than the other two models over short vegetation. MOD16 and 34 PT-JPL models performed well for forests, but poorly in dryland biomes. At the 35 catchment scale, all models perform well expect over some tropical and high 36 latitudinal catchments. At the global scale, SiTH highly overestimated ET in tropics, 37 while PT-JPL underestimated ET between 30°N and 60°N and MOD16 38 underestimated ET between 15°S and 30°S. This study also revealed that the 39 estimated ET by PT-JPL were largely influenced by the uncertainty in meteorological 40 data, while the estimated ET by SiTH and MOD16 were relatively non-sensitive to 41 the forcing data sets. In addition, the results suggested that the long-term variations in 42 estimated ET trend were greatly influenced by the uncertainty in LAI data. 43

44 Key words: Evapotranspiration; LAI; Uncertainty; SiTH; MOD16; PT-JPL

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1. Introducation

49	Global terrestrial evapotranspiration (ET) is an important nexus between land
50	surface, vegetation and atmosphere, and accurately estimating global land ET is of
51	great significance to study global hydrological cycle, energy exchange, carbon cycle
52	and climate change (Trenberth et al., 2009; Wang and Dickinson, 2012; Fisher et al.,
53	2008; Jung et al., 2010; Miralles et al., 2014). With the rapid developments in remote
54	sensing, numerous global ET models have been developed in recent decades (Norman
55	et al.,1995; Bastiaanssen et al., 1998; Su, 2002; Cleugh et al., 2007; Mu et al., 2007,
56	2011; Fisher et al., 2008; Leuning et al., 2008; Jung et al., 2009; Zhang et al., 2010;
57	Miralles et al., 2011; Zhu et al., 2019). In the framework of energy balance theory, the
58	majority of these models use the Penman-Monteith equation (P-M equation)
59	(Monteith, 1965) or the Priestley-Taylor approach (P-T approach) (Priestley and
60	Taylor, 1972) to estimate ET. For instance, MOD16 which is the core algorithm of
61	NASA's MODIS evapotranspiration product uses the P-M equation to simulate global
62	ET (Mu et al., 2011). Fisher et al. (2008) proposed a simple, less data-driven and
63	accurate ET model (PT-JPL) to estimate ET on basis of P-T approach. Recently, Zhu
64	et al. (2019) developed a Simple Terrestrial Hydrosphere model (SiTH) to estimate ET
65	based on the P-T approach and the groundwater-soil-plant-atmosphere continuum
66	(GSPAC) theory. These models have been widely used to study regional or global
67	hydrological cycles (Vinukollu et al., 2011a,b; Long et al., 2014; Ramoelo et al., 2014
68	Ershadi et al., 2014, 2015; Zhang et al., 2019; Hu et al., 2015; Michel et al., 2016;
69	Miralles et al., 2016).

70	Despite these progresses in model developments, there are still some
71	insufficiencies in systematic inter-comparisons and evaluations of the model
72	performances. First, there is a lack of systematic assessments of the impact of forcing
73	data uncertainties on model performances. As we known, both the vegetation
74	characteristics (LAI) and meteorological variables (i.e., radiation, temperature,
75	precipitation, humidity and air pressure) may have significant influences on model
76	behaviors. For example, LAI can influence the amount of absorbed solar radiation and
77	its distributions between plant canopy and soil surface, which ultimately have
78	significant influences on plant transpiration and soil evaporation (Good et al., 2015;
79	Wang et al., 2014; Wei et al., 2017; Kala et al., 2014). The meteorological conditions
80	(i.e., temperature, humidity and wind speed) regulate the atmospheric evaporation
81	demand, which may have a significant influence on ET as the result of global change
82	(Jung et al., 2010; Zhang et al., 2016; Zeng et al., 2018). Over the past 30 years, it has
83	been well documented that there is a constant increase in LAI (Earth greening) (Chen
84	et al., 2019; Jiang et al., 2017; Zhu et al., 2016), and continuous increasing in land
85	temperature (IPCC, 2018). However, the increasing magnitude and their distributions
86	in different LAI and meteorological datasets were also large (Jiang et al., 2017; Jia et
87	al., 2018; Vinukollu et al., 2011b). Thus, it's urgently needed to evaluate the impacts
88	of the forcing data uncertainties on the estimates of ET. Second, the majority of
89	previous studies have focused on evaluating the performances of one specific model
90	over different sites or inter-comparing the performances of different models at single
91	(or a few) locations. For example, Zhang et al. (2019) evaluated the performance of

92 the PT-JPL over 43 Fluxnet sites. Ershadi et al. (2014) systemtically compared the performances of four ET models over different sites and boimes. To select the best 93 94 candidate ET model for global applications, it is needed to comprehensively evaluate and intercompare the performances of different models at different (local, regional 95 96 and global) spatial scales across different biomes and climate conditions. Third, there are still great uncertainties in the long-term changes in ET over the past few decades. 97 For instance, some studies reported that global land ET increased from 1982 to 1998 98 and then there is a sharp decline until to 2008 (Jung et al., 2010; Zhang et al., 2015; 99 100 Zhang et al., 2016; Yan et al., 2013). Others studies suggested that an upward trend is 101 observed from 1982 to 2000 and an obvious recovery in ET may have started from 2007 (Mueller et al., 2013; Miralles et al., 2014). To clearly describe the multi-decadal 102 103 trend in global terrestrial ET, we need to simulate ET using different models with multiple forcing datasets. So that we can properly assess the influences of model 104 structures and forcing data uncertainties on long-term trend of land ET. 105

106 In this study, we intercompare the performances of three process-based ET models (MOD16, PT-JPL and SiTH) at different spatial scales, and obtain a long-term 107 trend of ET based on different combinations of LAI and meteorological datasets. 108 Specifically, the goal of this study is to (i) evaluate the performance of three 109 process-based models from local to regional and global scales using different forcing 110 datasets, (ii) analyse the uncertainties due to different model structure and 111 parameterizations, and (iii) explore the uncertainty of long-term temporal ET trend in 112 response to climate change and LAI increasing. 113

114 **2. Methods and data**

115 **2.1 Models**

116 The SiTH model proposed by Zhu et al. (2019) is a relatively new satellite-based ET model at daily temporal resolution. Based on the framework of the 117 groundwater-soil-plant-atmosphere continuum (GSPAC), SiTH uses well-established 118 119 hydrological models to simulate important hydrological variables (i.e., groundwater, soil moisture, and runoff). Then, the potential evapotranspiration calculated by using 120 P-T equation was constrained down to actual ET through the plant physiological 121 factor and soil moisture conditions. In SiTH, the total ET consists of canopy 122 interception evaporation, soil evaporation and vegetation transpiration. Soil 123 evaporation is constrained to occur in the first soil layer, while plant transpiration can 124 125 use both soil water and groundwater.

The MOD16 model, which was proposed by Mu et al. (2007; 2011), estimated 126 ET based on the P-M equation to calculate potential evaporation (Penman and 127 128 Menteith, 1948). It distributes the available energy into the components of surface soil and vegetation through fractional total vegetation cover. Then, the soil evaporation 129 includes the evaporation from the saturated soil surface and the moist soil surface. 130 Furthermore, canopy water loss includes evaporation from the wet canopy surface and 131 transpiration from the dry surface. Finally, it limits potential ET to actual ET through 132 vegetation physiological factors and meteorological factors. In 133 MOD16, evapotranspiration is equal to the sum of wet canopy evaporation, vegetation 134 transpiration, and bare soil evaporation at day-time and nighttime periods. 135

PT-JPL is a relatively simple (input data and parameters are reduced), accurate 136 model for estimating actual ET (Fisher et al., 2008; Ershadi et al., 2014; Miralles et al., 137 2016; Zhang et al., 2017). First, PT-JPL estimates potential evapotranspiration based 138 on the P-T equation (Pristley and Taylor, 1972). Then, plant physiological and 139 ecological constraints (i.e., LAI, green canopy ratio, vegetation temperature and 140 vegetation moisture) are used to limit potential plant transpiration and atmospheric 141 constraints (vapour pressure deficit and relative humidity) to limit potential soil 142 evaporation to actual ET. PT-JPL divides the actual evapotranspiration into three 143 components: canopy transpiration, soil evaporation and interception evaporation. 144

145 **2.2 Input data**

The input data of the above three models includes leaf area index (LAI), net radiation (Rn), air temperature (Ta), precipitation (P), air pressure (Pa), relative humidity (RH) and land cover (LC) (Supplementary Table 1). To investigate the influences of vegetation and meteorological variables on ET estimations, three sets of LAI data and two sets of meteorological data were used in this study.

The three long-term LAI products are GLOBMAP (Liu et al., 2012), GLASS (Xiao et al., 2016), and GIMMS LAI3g (Zhu et al., 2013). The GLOBMAP LAI is generated in 8 km and 16-day/8-day resolution from 1981 to 2017, produced by using Advanced Very High Resolution Radiometer (AVHRR) and Moderate Resolution Imaging Spectroradiometer (MODIS) satellite data, and it can be accessed from http://www.globalmapping.org/. The GLASS product is provided in 0.05° and 8 daily and 1 km resolution spanning from 1982 to 2000 (Xiao et al., 2016), produced by

NASA's Long Term Data Record (LTDR) project using NOAA/AVHRR surface 158 reflectance datasets (http://www.glcf.umd.edu/). The GIMMS LAI3g product (version 159 160 01) is generated at 1/12° spatial resolution from 1982 to 2011 (http://sites.bu.edu/cliveg/datacodes/; Zhu et al., 2013), based on feed-forward neural 161 162 networks.

Two sets of meteorological reanalysis data based on observational data retrieval 163 and assimilation are used in this study. The first one is the Modern-Era Retrospective 164 analysis for Research and Applications Version 2 (MERRA-2) from NASA's Global 165 166 Modeling and Assimilation Office (https://disc.sci.gsfc.nasa.gov/) (Bosilovich et al., 2016). It provides near-surface air pressure and temperature, specific humidity, 167 precipitation, and net radiation at a spatial resolution of $0.5^{\circ} \times 0.625^{\circ}$ on hourly 168 temporal resolution from 1982 to 2017. The second is the latest ERA-5 produced by 169 European Centre for Medium-Range Weather Forecast (ECMWF) 170 (https://cds.climate.copernicus.eu/). This dataset includes near-surface air pressure 171 and temperature, dew point temperature, precipitation, and net radiation spanning 172 1982 to 2017 at a spatial resolution of 31km and an hour temporal resolution 173 (Hersbach et al., 2016). In addition, we use static land cover data from MCD12C1 in 174 2001 (Friedl et al., 2010), because its changes are relatively small on a global scale 175 with time (Zhang et al., 2016). All driving data was interpolated to a 0.25°×0.25° 176 spatial resolution based on the non-linear spatial interpolation method (Zhao et al., 177 2005). A total of 18 ensembles ET products are obtained from the three ET models 178 with different combinations of inputs data (Supplementary Table 2). 179

180 **2.3 Data used for evaluation**

At the local scale, the FLUXNET 2015 (https:// fluxnet.fluxdata.org) from global 181 182 network of eddy-covariance towers was used for model evaluations (Fisher et al., 2008; Mu et al., 2007, 2011; Zhang et al., 2017; Ershadi et al., 2014). Here, a total of 183 184 43 flux sites were selected to cover a wide range of biomes with the energy closure ranging from 70% to 90%. These sites can be divided into 7 different vegetation types 185 on the basis of the IGBP classification, and included the cropland (CRO, 7 sites), 186 deciduous broad-leaved forest (DBF, 4 sites), evergreen broad-leaved forest (EBF, 5 187 188 sites), evergreen coniferous forest (ENF, 8 sites), the grass (GRA ,13 sites), the mixed forest (MF, 2sites) and open shrubland (OSH, 4 sites) (Figure 1). 189

At the catchment scale, the water balance dataset for 32 major (i.e., >200,000 km²) river catchments developed by Pan et al. (2012) was used to evaluate the model performance at regional scale (Supplementary Table 3). This dataset is considered to be the best available water budget dataset (Li et al., 2013; Zeng et al., 2015; Zhang et al., 2017), and includes monthly precipitation, ET, streamflow, and the change in water storage from 1984 to 2006.

At the global scale, the Model tree ensembles (MTE) product (Jung et al., 2009) spans from 1982-2011 at monthly temporal resolution and 0.5° spatial resolution. The MTE model integrates observed ET at the FLUXNET sites with satellite remote sensing and surface meteorological data in a machine-learning algorithm. It is widely used for the comparison and verification of model performances (Miralles et al., 2014; Zhang et al., 2016; Zhu et al., 2019). The Global Land Evaporation Amsterdam Model (GLEAM) calculates ET from satellite observations based on the P-T equation
(Miralles et al., 2011), and performed well in ET estimated (Miralles et al., 2011;
Michel et al., 2016).

205 2.4 Analysis method

The statistical measures used to evaluate model performance include the coefficient of determination (R²), slope and the Nash-Sutcliffe efficiency coefficient (NSE) (Nash and Sutcliffe, 1970; Legates and McCabe, 1999). The NSE is a normalized statistic that determines the relative magnitude of the residual variance compared to the measured data variance. It wascomputed as:

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$$NSE = 1 - \frac{\sum_{t=1}^{T} [O(t) - S(t)]^2}{\sum_{t=1}^{T} [O(t) - \overline{O}]^2} \quad (1)$$

where O(t) is the observed ET, S(t) is the simulated ET, and \overline{O} is the mean of observed values. NSE values range between $-\infty$ to 1. When the NSE values is closer to 1, the simulation is better.

215 **3. Results**

216 **3.1 Model evaluation at local scale**

The model performances on estimating monthly ET driving by different inputs data were compared with the observations from 43 Fluxnet sites (Figure 2). The SiTH model overestimates ET when using all the forcing datasets. The linear regression slope between observed and simulated ET ranges from 1.18 to 1.25, especially for the MERRA-2 (slope=1.23~1.25). The correlation coefficients (R^2) of SiTH are highest (greater than 0.73) among the three models, suggesting that the estimated ET by SiTH

agreed better with the observed ET. When the same LAI data is used, the estimated 223 ET by SiTH using ERA-5 data is better than that using MERRA-2 data. On the 224 225 contrary, when the same meteorological data was used, there were small differences in simulated ET between different LAI datasets. Thus, it seemed that the influences of 226 the meteorological data on the performances of SiTH is larger than that of the LAI 227 data. For MOD16 model, it performed relatively well in simulating ET by using 228 different forcing data with the regression slopes close to 1 (slope=0.92~1.0). 229 Importantly, it seemed that the differences in forcing data have small influences on the 230 performances of MOD16 model. However, the correlation coefficients (R^2) between 231 observed and simulated ET by MOD16 is generally lower than the other models, 232 indicating the consistencies between estimated and observed ET were relatively low 233 for MOD16, especially using GLOBMAP LAI data ($R^2=0.55$) (Figures 2a, b). For 234 PT-JPL model, its performances using MERRA-2 (slope= $0.97 \sim 0.99$, $R^2=0.70 \sim 0.72$) 235 were much better than that using ERA-5 (slope= $0.71 \sim 0.72$, $R^2 = 0.61 \sim 0.66$), indicating 236 that meteorological data have significant influences on model performances. 237

Due to the differences in model structure and parameterization, the model performances in ET simulations varied over different land surfaces (Massman and Lee, 2002; McCabe et al., 2005; Richardson et al., 2006; Williams et al., 2009; Vinukollu et al., 2011a; Ershadi et al., 2014). Figure 3 shows the performances of the three models across the different biomes. For the forest biomes (ENF, EBF, DBF, MF), the SiTH model generally overestimated ET, while the MOD16 and PT-JPL models performed relatively well at these biomes. The MOD16 model overestimates ET at the

MF biome. However, over the short vegetation types (i.e., GRA, CRO, and OSH), 245 SiTH performs well, while the other two models underestimated ET (slope < 0.8). It 246 was also observed that the MOD16 significantly underestimate ET over the OSH 247 ecosystems (slope=0.25~0.2) (Figure 3). The simulated ET by the three models had 248 good consistency with site-observed ET over forest biomes ($R^2 > 0.4$). However, the 249 MOD16 and PT-JPL models do not capture the ET dynamics in dryland biomes (OSH) 250 (MOD16: R^2 =0.02~0.12; PT-JPL: R^2 =0.12~0.46). On the contrary, the SiTH model was 251 satisfactory across dryland biomes, with R² values ranging from 0.52 to 0.79. The 252 SiTH and MOD16 models generate negative NSE in forests (except DBF), because 253 they overestimated ET significantly. PT-JPL model has a greater NSE values (closer 254 to 1) in forests. The SiTH produces high NSE for short vegetation, and the PT-JPL, 255 256 especially MOD16 has the NSE values lower than 0 in OSH vegetation. In addition, compared with SiTH and MOD16 models, PT-JPL model showed great variations in 257 ET simulations within a specific biome. 258

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3.2 Model evaluation at catchment scale

At regional scale, SiTH tended to overestimate ET driving by different LAI and 260 meteorological data (Figure 4). The regression slope between observed and estimated 261 ET by SiTH ranged from 1.22 to 1.36. The SiTH model agreed better with WBE data 262 than MOD16 and PT-JPL (SiTH: $R^2=0.89 \sim 0.90$). The MOD16 model also slightly 263 overestimated ET with values of slope being 1.03 to 1.16, and the R^2 values were 264 lower than the other two models ($R^2=0.71\sim0.80$). The PT-JPL model performed well. 265 The regression slope between observed and PT-JPL estimated ET ranged from 0.87 to 266

1.03 with R^2 varying from 0.79 to 0.86. The estimated ET by MOD16 and SiTH models using different forcing data showed relatively little differences, suggesting that the MOD16 and SiTH models are no-sensitivity to uncertainties of the forcing data. For the PT-JPL model, the differences of estimated ET are greater when using different meteorological datasets.

The performances of the three models over each basin were compared in Figure 272 5. Both MOD16 and SiTH models overestimated ET over the majority of the 273 catchments, while PT-JPL performs relatively well in most catchments. The estimated 274 ET by three models (especially SiTH) shows high consistency with water balance ET, 275 with the R^2 greater than 0.8. But the values of R^2 in three models are very low in 276 several basins (Amazon, Congo, Mekong, MOD16 in Aral, Indus, Murray and 277 Olenek). The PT-JPL model has better NSE (closer to 1) in most catchments than the 278 other two models. Generally, the three models performed poorly over catchments in 279 the tropical rainforest areas (Amazon, Congo, and Mekong). In addition, MOD16 also 280 performed poorly in high latitudes regions (Indigirk, Olenek and Yukon), and 281 Zhujiang region. This may be due to large discrepancies in LAI and meteorological 282 data sets (Jiang et al., 2017; Jia et al., 2018), or lack of a robust description of snow 283 and ice evaporation at high latitudes. 284

3.3 Evaluation of ET at global scales

At global scale, we calculated the annual average ET during 1982-2011 using these models forced by six different combinations of inputs (Figure 6). The spatial pattern of simulated ET by the three models were very similar. The highest annual ET

289	was found over the amazon basin, the Congo rainforest and the southeast Asia near
290	the equator, while the lowest annual ET were in the north Africa, most areas of central
291	Asia, the southwestern United States, the Central and western Australia and some
292	parts of high latitude. The average total annual ET from 1982 to 2011 were
293	(76.87 ± 2.98) × 10 ³ km ³ , (71.68 ±2.82) × 10 ³ km ³ , and (61.25±1.92) × 10 ³ km ³ for
294	SiTH, MOD16, and PT-JPL model, respectively. These values fell in the ranges from
295	54.9×10^3 km ³ to 85×10^3 km ³ reported by previous studies (Oki and Kanae, 2006;
296	Jung et al., 2010; Wang-Erlandsson et al., 2014; Miralles et al., 2016). In addition, the
297	mean annual global land ET calculated from MET and GLEAM during the same
298	period were 63.34 \times 10 3 km 3 and 65.7 $\times 10^3$ km 3 , respectively. These values were
299	slightly lower than that estimated by SiTH and MOD16 model, but very close to that
300	estimated by PT-JPL model. The latitudinal average of ET simulated by the three
301	model during 1982-2011 were also presented Figure 6, and showed similar latitudinal
302	pattern. Relative high ET values were observed near the equator area and near 20°N.
303	However, the estimated ET in tropical regions by SiTH model was higher than that
304	estimated by the other two models. The PT-JPL estimated ET was relatively low for
305	the latitudes $30^{\circ}N$ - $60^{\circ}N$, and estimated ET by MOD16 was low for the latitudes
306	between 15°S and 30°S (Vinukollu et al., 2011b).

Figure 7 shows the ensembles of multi-decadal ET anomalies (1982-2017) using three process-based ET models forced by the six different combinations of inputs. Generally, the range of the ensembles of global ET anomalies shows large fluctuations, and the median of long-term global ET ensembles agreed better with the global ET trend by MET (Figure 7a). There were two peaks in the median of global ET ensembles in 1998 (median ET anomalies =17.17 mm/year) and 2010 (median ET anomalies =14.79 mm/year), respectively. Both 1998 and 2010 were El Niño years. There was an increasing trend from 1982 to 1998, and a decreasing trend from 1998 to 2008. After 2008, the ET reached its second summit in 2010. Since the summit in 2010, the global ET fluctuantly declined but reached high positive anomaly in 2016 (mean ET anomalies = 12.56 mm/year).

To evaluate the impact of LAI and meteorological data uncertainties on 318 long-term ET trend, we classified 18 sets of ET products in Supplementary Table 2 319 into two categories: (1) the estimates of ET from three LAI datasets with different 320 combinations of models and meteorological datasets, which were mainly used to 321 322 investigate the influences of different LAI datasets on the ET estimations (Figure 7b); and (2) the estimates of ET from two meteorological datasets with different 323 combinations of models and LAI datasets, which were mainly used to investigate the 324 influences of different meteorological datasets on ET estimations (Figure 7c). In 325 Figure 7b, the estimates of ET using the GLASS dataset deviated from those using the 326 GLOBMAP and GIMMS datasets. The estimated ET using the GLASS dataset were 327 lower than those by the other two LAI datasets during 1988-1993 period, while the 328 estimated ET using the GLASS dataset were higher than those by the other two LAI 329 datasets during 1999-2004 period. In Figure 7c, the estimates of ET using the 330 MERRA-2 dataset were very similar to that using the ERA5 data, and their 331 inter-quartile range of ET overlapped greatly and varied synchronously. Also, the 332

median values of ensembles ET using the ERA5 and MERRA-2 datasets were consistent with the ET value estimated by MET. This indicated that the influences of LAI datasets on the estimated long-term variations in global ET were higher than those of meteorological datasets.

337 **4. Discussion**

4.1 Analyzing the performance of models

The three models with different structural complexity 339 and process parameterizations have been developed to predict global ET. Hence, these models are 340 341 expected to present various performance in estimating ET (Vinukollu et al., 2011a; Mueller et al., 2013). In this study, we found that the SiTH model overestimated ET 342 over some specific biomes (i.e., forest) and in the tropical regions. However, this 343 344 model exhibited relatively high consistency with the observations ($R^2=0.6\sim0.88$). In this model, the P-T coefficient α is a dimensionless factor associated with the Bowen 345 ratio to limit evaporation, and its value of 1.26 is derived from the data of daily fluxes 346 347 at saturated land sites and open water (Priestley and Taylor, 1972). Many studies revealed that the value of α for forests may be below 1.26. For examples, Komatsu et 348 al. (2005) reported that the value of α is 0.83 ± 0.15 at deciduous forests and α =0.63 349 \pm 0.2 at coniferous forests. Cho et al. (2012) discovered that the mean value of α for 350 deciduous forests is 1.01 and for the coniferous forests is only 0.75. Sanches et al. 351 (2010) found that α values for forests are around 0.65. Therefore, the overestimates of 352 ET by SiTH is due to the high α value used in this model for forest ecosystems. On 353 the contrary, SiTH has a good performance over short vegetation ecosystems (i.e., 354

grassland, cropland and shrubland). For the well-watered short vegetations, the value 355 of α =1.26 is confirmed in the literature (Priestley and Taylor, 1972). Pereira et al. 356 357 (2007) reported that the value of α at the irrigated croplands ranged from 1.17 to 1.35. Some researchers found that the value of α close to the 1.26 over shrublands (Owe 358 and Van de Griend, 1990; Caylor et al., 2005). So, the SiTH performed relatively well 359 over short vegetation ecosystems (i.e., grassland, cropland and shrubland) (Figure 4). 360 Notice that the α value may systematically vary on the daily and seasonal cycles 361 (Tongwane et al., 2017; Assouline et al., 2016; Komatsu et al., 2005). So, it should 362 363 take this variation into account in the future studies and optimize the value of α in SiTH for forests to improve its accuracy in ET simulations. 364

We also found that both PT-JPL and MOD16 performed poor in dryland biomes 365 366 (OSH), which is consistent with the previous studies (Zhu et al., 2016a; Garcia et al., 2013; Zhang et al, 2017; Vinukollu et al., 2011b; Sun et al., 2012; Velpuri et al., 2013; 367 Michel et al., 2016; Zhang et al, 2019; Ershadi et al., 2014). In arid areas, soil 368 moisture is the main factor to that influences ET processes. However, the PT-JPL and 369 MOD16 models used the atmospheric moisture conditions (i.e., air temperature, RH 370 371 and VPD) to reflect soil moisture constraints on ET (Fisher et al., 2008; Mu et al., 2007, 2011), rather than directly using the soil moisture to constrain the ET. Recently, 372 Novick et al. (2016) reported that atmospheric moisture conditions may be 373 significantly correlated with soil moisture at month to year time scales, but they 374 tended to be nearly decoupled at the daily and hourly time scales. Thus, the PT-JPL 375 and MOD16 models using the atmospheric moisture conditions to limit soil moisture 376

may not properly describe the restricts of soil moisture on ET in arid regions. 377 Furthermore, the soil moisture constraint was calculated as $RH^{VPD/\beta}$ in MOD16 and 378 379 PT-JPL models. The parameter β is the sensitivity of soil moisture constraint to VPD, and plays an important role in accurate estimation of soil evaporation (Fisher et al., 380 2008; García et al., 2013; McCabe et al., 2016; Zhu et al., 2016a; Zhang et al., 2017). 381 Zhang et al. (2017; 2019) found that β was the most sensitive parameter and its values 382 in arid area were lower than that in humid regions, resulting in low soil evaporation 383 due to soil moisture stress. On the contrary, the SiTH model directly uses soil water 384 385 content to describe soil moisture limitation, and performs relatively well in arid areas (Zhu et al., 2019). Finally, plants have deep roots in arid regions (Fan et al., 2013, 386 2017) and can utilize deeper soil moisture or even groundwater to maintain growth 387 388 (Thompson et al., 2011). However, only SiTH among the three models took the influences of groundwater into account during ET modeling. 389

4.2 Impact of the uncertainties of forcing data on ET

391 Models tend to exhibit different behavior when forced with different input data (Vinukollu et al., 2011b; Ferguson et al., 2010; Ershadi et al., 2014). From the 392 evaluation of monthly estimated ET by the three models using different combinations 393 of forcing datasets at local and catchment scales (Figure 2 and Figure 4), the SiTH 394 model overestimated ET with all forcing datasets. The differences of simulated ET by 395 SiTH model are relatively small by using different forcing data, although a slight 396 improvement in performances were observed by using ERA5 meteorological dataset. 397 The MOD16 model performed well and robust using different combinations of the 398

399 forcing datasets, especially using the MERRA-2 meteorological data. Then, it seemed that MOD16 model is relatively non-sensitive and stable to the forcing datasets. On 400 401 the contrary, the differences in ET estimated by PT-JPL model are large when using different meteorological forcing datasets. The PT-JPL performs well when using the 402 ERA5 meteorological datasets. Generally, the forcing data had relatively little 403 influence on the estimated ET in the SiTH and MOD16 models. But the 404 meteorological data has more influence on the estimated ET at monthly scale than 405 LAI data in PT-JPL model. 406

Moreover, the differences were found in estimated global ET anomalies by 407 three models using different combination of forcing datasets, but the ensemble median 408 of global ET anomalies agreed well with the MTE-estimated global land ET 409 410 anomalies (Figure 7a). It indicates that ensemble-model method can well capture the uncertainties in ET estimates (Ershadi et al., 2014; Zhang et al., 2016; Vinukollu et al., 411 2011b; Mueller et al., 2013). Generally, the global ET shows an increasing trend from 412 1982 to 1998. After the summit in 1998, global ET shows a decreasing trend from 413 1998 to 2008. (Figure 7a). This agrees well with the results of previous studies (Jung 414 et al., 2010; Yan et al., 2013; Zhang et al., 2015; Zhang et al., 2016). Some authors 415 thought that the decline in global ET from 1998 to 2008 was caused by 416 ENSO-induced anomalous dry conditions and consequent limited moisture supply, 417 especially in the Southern Hemisphere (Jung et al., 2010; Yan et al., 2013). However, 418 the decline of ET was transient, and global land ET reached another summit in 2010 419 (Figure 7a). It demonstrated a transition from El Niño phase to the La Niña phase in 420

2010 with high precipitation (Poulter et al., 2014), leading to a high ET (Yan et al.,
2013). Thus, the decline of ET after 1998 was a transient variation but not a constant
decline signal.

Comparing the global ET anomalies at annual scale under different forcing 424 425 datasets, we found that the influences of LAI datasets on the estimated long-term variations in global ET were higher than those of meteorological datasets (Figure 7b 426 and c). This result was consistent with previous studies which found that vegetation 427 greening is main driver to the multi-decadal ET trend since 1980s (Zhang et al., 2015; 428 Zhang et al., 2016; Zeng et al., 2018; Forzieri et al., 2020; Piao et al., 2020). The 429 different meteorological variables (i.e., net radiation, temperature, precipitation and 430 relative humidity) have opposite or negative effects on ET process, which may blur 431 432 the capabilities of ET to identify climate trends at the annual scale (Zhang et al., 2015). In Figure 7b, the estimates of ET anomalies using the GLASS dataset showed large 433 inconsistency with those using the GIMMS and GLOBMAP LAI datasets. Comparing 434 the four long-term LAI products, Jiang et al. (2017) found that interannual 435 variabilities of GLASS LAI products shows large differences with other LAI products. 436 The differences of estimated ET anomalies using the different meteorological datasets 437 is relatively small. The ensemble median values of global ET using ERA5 and 438 MERRA-2 datasets are in agreement with the MTE-estimated global land ET 439 anomalies. Thus, it seemed that the influences of meteorological datasets on global ET 440 estimates can be ignored partially due to their relatively good qualities. 441

443 **5.** Conclusions

In this study, we evaluated the performances of three process-based ET models in 444 445 ET simulations at multiple scales by using variuos LAI and meteorological forcing datasets. The results showed that SiTH simulated well in dryland short vegetation 446 447 ecosystems, but overestimated ET in forest ecosystems because the P-T coefficient (α) may be set too high in this model. The PT-JPL and MOD16 models performed well in 448 forests, but poorly in dryland biomes due to their improper description of soil 449 moisture stress based on atmospheric moisture conditions. Similar model 450 451 performances were observed at both catchment and global scales. To obtain proper long-term global ET estimates, the multi-model ensemble approach is a proper choice. 452 We found that the ensembles median of global ET anomalies from different models 453 454 and forcing datasets showed good consistency with that obtained by the MTE method. Generally, the LAI datasets have larger influences on the global ET estimates than the 455 meteorological datasets. In further studies, we will pay more attentions in optimizing 456 the P-T coefficient (α) over different vegetation types for SiTH to improve its 457 accuracy in ET simulations over forest ecosystems. Finally, more studies are need to 458 quantify the contributions of different driving factors to the variations in global ET, 459 and to figure out the mechanisms in controlling global ET changes. 460

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Figure lists

Figure 1. Location of the 43 FLUXNET sites. The biomes types are identified based 755 on the International Geosphere-Biosphere Programme (IGBP) biome classification. 756

Figure 2. Scatter plots of the simulated ET of three models using different forcing 757 datasets versus measured ET at 43 flux sites. On the left panels, the same 758 meteorological dataset of ERA5 and LAI datasets of (a) GLOBMAP, (c) GLASS, 759 and (e) GIMMS was used to simulate ET, respectively. On the right panels, the same 760 meteorological dataset of MERRA-2 and LAI datasets of (b) GLOBMAP, (d) GLASS, 761 and (f) GIMMS was used to estimate ET, respectively. The black dotted line 762 represents the 1:1 line. 763

Figure 3. Comparison of the simulated ET by three models using different forcing 764 datasets versus observed ET at different biomes. Boxplots show the slope, R² and 765 NSE statistical significance of simulated ET. The central solid line of each box shows 766 the the median. The bottom and top of boxes represent the 25th and 75th percentiles. 767 respectively. The lower and upper whiskers indicate the minimum and maximum 768 values, respectively. The circles represent outliers. 769

Figure 4. Scatter plots of the simulated ET by three models using different forcing 770 datasets versus measured ET at 32 catchments. On the left panels, the same 771 meteorological datasets of ERA5 and different LAI datasets of (a) GLOBMAP, (c) 772

GLASS, and (e) GIMMS was used to estimate ET, respectively. On the right panels,

the same meteorological datasets of MERRA-2 and different LAI datasets of (b)

GLOBMAP, (d) GLASS, and (f) GIMMS was used to estimate ET, respectively. The

black dotted line represents the 1:1 line.

Figure 5. Comparison of the simulated ET of three models versus water balance ET at

32 catchments. The bottom, middle, and top panels represent the slope, R^2 , and NSE,

respectively. The dots are the median of simulated ET under different forcing datasets.

780 Error bar illustrates the mean ± 1 s.d.

781 Figure 6. Spatial patterns of annual mean land evapotranspiration for the SiTH,

MOD16, PT-JPL, MTE, and GLEAM from 1982 to 2011. The right panel shows the
latitudinal profiles of ET from each models between 55°S and 80°N.

784 Figure 7. Global land ET anomalies. (a). Ensembles of global ET anomalies from 1982 to 2017 under all models and the forcing datasets. (b). The estimates of ET 785 anomalies from three LAI datasets with different combinations of models and 786 meteorological datasets. The green line (GIMMS), blue line (GLASS) and red line 787 (GLOBMAP) represent the median of ET ensembles using the GIMMS, GLASS and 788 GLOBMAP LAI datasets, respectively. (c). The estimates of ET anomalies from two 789 meteorological datasets with different combinations of models and LAI datasets. The 790 blue line (MERRA-2) and pink line (ERA5) is the median of ET ensembles using the 791 MERRA-2 and ERA5, respectively. The shading area indicates the inter-quartile of 792 ET ensembles using different LAI and meteorological datasets. 793

Supplementary

Madala	Leaf Area		Meteoro	logical va	riables		- Land Carren
Widdels	Index	Та	Р	Pa	RH	Rn	- Land Cover
SiTH	\checkmark	\checkmark		\checkmark		\checkmark	\checkmark
MOD16	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark
PT-JPL	\checkmark				\checkmark	\checkmark	\checkmark

Table 1. Variables used as input to derive ET in three models.

 Table 2. Details of the input datasets combinations for each ensemble members.

M. 1.1.	Ensemble	Meteorolo	Meteorological datasets		Leaf Area Index datasets		
Models	No.	ERA5	MERRA2	GLOBMAP	GLASS	GIMMS	period
	el	\checkmark		\checkmark			1982-2017
	e2				\checkmark		1982-2015
C:TH	e3					\checkmark	1982-2011
511H	e4		\checkmark	\checkmark			1982-2017
	e5		\checkmark				1982-2015
	e6		\checkmark			\checkmark	1982-2011
	e7			\checkmark			1982-2017
	e8	\checkmark			\checkmark		1982-2015
MODIC	e9						1982-2011
MOD16	e10		\checkmark	\checkmark			1982-2017
	e11		\checkmark		\checkmark		1982-2015
	e12		\checkmark				1982-2011
	e13			\checkmark			1982-2017
	e14	\checkmark			\checkmark		1982-2015
	e15					\checkmark	1982-2011
Υ I-JYL	e16		\checkmark	\checkmark			1982-2017
	e17		\checkmark		\checkmark		1982-2015
	e18		\checkmark				1982-2011

Number	Basin	Location	Area (km ²)	KG Climate	
1	Amazon	South America	5,854,000	Af	
2	Congo	Africa	3,699,000	Af/Aw	
3	Mekong	Asia	759,000	Aw	
4	Aral	Asia	2,148,000	Bwk	
5	Columbia	North America	732,000	Bsk	
6	Indus	Asia	1,143,000	Bwh	
7	Limpopo	Africa	420,000	Bsh	
8	Murray	Oceania	1,032,000	Bsk	
9	Niger	Africa	2,240,000	Bwh	
10	Nile	Africa	3,826,000	Bwh	
11	Senegal	Africa	847,000	Bwh	
12	Changjiang	Asia	1,794,000	Cfa	
13	Danube	Europe	788,000	Cfb	
14	Huang	Asia	795,000	Cwa	
15	Mississippi	North America	3,203,000	Cfa	
16	Parana	South America	2,664,000	Cfa	
17	Zhujiang	Asia	450,000	Cfa	
18	Amur	Asia	1,755,000	Dwa	
19	Dnieper	Europe	500,000	Dfb	
20	Don	Asia	500,000	Dfa	
21	Indigirk	Asia	334,000	Dfd	
22	Kolyma	Asia	666,000	Dfc	
23	Lena	Asia	2,442,000	Dfc	
24	MacKenz	North America	1,695,000	Dfc	
25	Ndavina	Asia	288,000	Dfc	
26	Ob	Asia	3,026,000	Dfb	
27	Olenek	Asia	223,000	Dfd	
28	Pechora	Asia	314,000	Dfc	
29	Ural	Asia	296,000	Dfb	
30	Volga	Europe	1,476,000	Dfb	
31	Yenisei	Asia	2,579,000	Dfc	
32	Yukon	North America	856,000	Dfc	

Table 3. Details of 32 river catchments.