# Fault-valve behavior estimated from intensive foreshock and aftershock activity in the 2017 M 5.3 Kagoshima Bay, Kyushu, southern Japan, earthquake sequence

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#### Abstract

Fluid migration and pore pressure changes within the Earth are key to understanding earthquake occurrences. In this study, we investigated the spatiotemporal characteristics of intensive foreshock and aftershock activity for the 2017 M 5.3 earthquake in Kagoshima Bay, southern Japan, to examine the physical process governing this earthquake sequence. We determined that foreshock hypocenters moved slowly on a sharply-defined steeply-dipping plane, which probably represents the same plane of the mainshock source fault. The mainshock hypocenter was located at an edge of a seismic gap formed by foreshocks along the plane, suggesting that the mainshock ruptured this seismic gap. Aftershock hypocenters, distributed along several steeply-dipping planes exhibited an overall upward migration. Aftershock activity slightly deviated from a simple mainshock-aftershock type, suggesting the existence of an aseismic process behind this earthquake sequence. We propose a hypothesis that consistently explains these observations. First, fluids rose from the deeper portion and intruded into the fault plane, reduced the fault strength and caused the foreshock sequence, as well as, possible aseismic slips. An area with a relatively high fault strength on the plane existed, where the mainshock rupture finally occurred due to a continuous decrease in the fault strength associated with increasing pore pressure and an increase in the shear stress associated with the aseismic slip and foreshocks. The change in the pore pressure associated with post-failure fluid discharge contributed to the aftershock activity, causing upward fluid migration. These observations show the importance of fluid movement at depth, when attempting to understand the earthquake cycle.

## Fault-valve behavior estimated from intensive foreshocks and aftershocks of the 2017 M 5.3 Kagoshima Bay earthquake sequence, Kyushu, southern Japan

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#### Key Points:

- Intensive foreshocks migrate via one plane.
- Aftershock hypocenters migrate toward shallower levels via several planes.
- Upward pore pressure migration explains the occurrence of the foreshock–mainshock–aftershock sequence.

#### Abstract

Determining fluid migration and pore pressure changes within the Earth is key to understanding earthquake occurrences. We investigated the spatiotemporal characteristics of intense fore- and aftershocks of the 2017 M<sub>L</sub> 5.3 earthquake in Kagoshima Bay, Kyushu, southern Japan, to examine the physical processes governing this earthquake sequence. The results show that the foreshock hypocenters moved upward on a sharply defined plane with steep dip. The mainshock hypocenter was located at the edge of a seismic gap formed by foreshocks along the plane. This spatial relationship suggests that the mainshock ruptured this seismic gap. The corner frequency of the mainshock supports this hypothesis. The aftershock hypocenters migrated upward along several steeply dipped planes. The aftershock activity slightly differs from the simple mainshock-aftershock type, suggesting that aseismic processes controlled this earthquake sequence. We established the following hypothesis: First, fluids originating from the subducting slab migrated upward and intruded into the fault plane, reducing the fault strength and causing a foreshock sequence and potentially aseismic slip. The continuous decrease in the fault strength associated with an increase in the pore pressure and the increase in shear stress associated with aseismic slip and foreshocks caused the mainshock in an area with relatively high fault strength. The change in the pore pressure associated with post-failure fluid discharge contributed to aftershocks, causing the upward migration of the earthquake. These observations demonstrate the importance of considering fluid movement at depth not only earthquake swarms but also foreshock-mainshock-aftershock sequences.

#### 1 Introduction

An earthquake is a natural phenomenon during which a high-speed rupture propagates along a fault. Two factors control the occurrence of an earthquake: an increase in the shear stress acting on the fault and a decrease in the fault strength. The results of previous studies suggested that the increase in the pore pressure plays an important role in the earthquake occurrence (e.g., Hasegawa, 2017; Hubbert & Rubey, 1959; Nur & Booker, 1972; Sibson, 1992; Rice, 1992) because it reduces the fault strength.

A well-known example of fluid-driven seismicity is the seismicity induced by fluid injection for engineering purposes (e.g., Ellsworth, 2013). There is also growing evidence that natural earthquake swarms are closely related to fluid movement at depth. In fact, the characteristics of many natural seismic swarms are similar to those of fluid injection-induced seismicity including the migration behavior of the earthquake hypocenter (e.g., Fischer and Horálek, 2003; Parotidis et al., 2003; Bianco et al., 2004; Yukutake et al., 2011; Shelly et al., 2016; Yoshida et al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). Based on the determination of the hypocenters and focal mechanisms of earthquake swarm at the 2009 Hakone volcano, the diffusion of high-pressure fluid triggered the swarm (Yukutake et al., 2011). The spatiotemporal evolution of seismic activity in the Long Valley Caldera, California, indicates that a pore pressure transient with a low-viscosity fluid initiated and sustained the swarm in 2014 (Shelly et al., 2016). It has been hypothesized that several earthquake swarms that occurred after the 2011 Tohoku-Oki earthquake were triggered by a decrease in the fault strength due to upward pore pressure migration (Terakawa et al., 2013; Okada et al., 2016; Yoshida et al., 2016a, 2019a).

Not only earthquake swarms but also foreshock-mainshock-aftershock sequences may be closely related to the fluid behavior in the Earth interior. Sibson (1992) established the fault-valve model in which the pore pressure cycle controls the earthquake cycle due to overpressurized fluids that rise from the deeper portion of the fault. In this model, fault ruptures create a transient fracture permeability within the fault zone, which acts as a valve, promoting the upward discharge of fluids from deeper portions of the crust. This model is supported by various geological and geophysical observations (Sibson, 2020). Hasegawa et al. (2005) proposed a model for the deformation process in a subduction zone based on various geophysical observations including seismic tomography data obtained for northeastern Japan. In this model, fluids expelled from the subducting slab migrate upward, reach the crust, and cause anelastic crustal deformation including earthquakes.

The migration characteristics of earthquake hypocenters can be used to infer the origin of the seismicity (e.g., Yukutake et al., 2011; Ruhl et al., 2016; Yoshida & Hasegawa, 2018a,b; De Barros et al., 2019). Pore

pressure migration and aseismic slip propagation are typical mechanisms attributed to the migration of earthquakes. In the former mechanism, the hypocenter migration is presumed to reflect the migration of fluids (e.g., Shapiro et al., 1997; Talwani et al., 2007). In the latter mechanism, the hypocenter migration is presumed to be a result of aseismic slip propagation (e.g., Lohman & McGuire, 2007; Roland & McGuire, 2009). The spatiotemporal distribution of earthquake hypocenters can be more precisely estimated than other seismological characteristics such as the three-dimensional seismic velocity structure. By examining relocated hypocenters, we may extract information on aseismic physical processes controlling earthquakes, which is crucial to understanding the earthquake generation. The results of previous studies showed that the seismic activity caused by aseismic processes differs from that of the mainshock–aftershock sequence (e.g., Hainzl & Ogata, 2005; Roland & McGuire, 2009; Kumazawa & Ogata, 2013; Yoshida & Hasegawa, 2018b). This suggests that investigations of the seismicity may provide clues about aseismic processes governing earthquakes.

The volcanic front on Kyushu Island in southern Japan formed due to the subduction of the Philippine Sea Plate. Several of the most active volcanoes in Japan are distributed along this volcanic front (e.g., Sakurajima and Aso). Kagoshima Bay is located at this volcanic front (Fig. S1), which is characterized by a low-gravity anomaly that extends from north to south. On July 11, 2017, an  $M_L$  5.3 strike-slip earthquake occurred at a depth of ~10 km in Kagoshima Bay (Fig. 1). Seismicity activity had been recorded near the mainshock hypocenter since December 2016 (Fig. 1c). In total, 1.843 foreshock events were recorded and listed in the Japan Meteorological Agency (JMA) unified seismic catalogue. The seismicity increased after the mainshock; 12.595 events are listed in the JMA catalogue. Based on the focal mechanisms of earthquakes in this region, these events were of strike-slip type with a NW–SE P-axis (Fig. 1b). Only a small coseismic step was detected by the national GNSS (Global Navigation Satellite System) network (Fig. S2). Based on the spatiotemporal variation in the b-value and the migration of the hypocenters, Nanjo et al. (2018) suggested that fluid movement caused the earthquake sequence in Kagoshima Bay, but the detailed physical process controlling this foreshock–mainshock–aftershock sequence remains unclear.



Figure 1. (a) Map showing southern Kyushu. Inverted triangles indicate the seismic stations. We used arrival time data obtained at both blue and green stations. We analyzed waveform data recorded at the green stations. The black square shows the study area. (b) Hypocenter distribution of earthquakes that occurred in Kagoshima Bay from January 1, 2003, to April 8, 2018, and their focal mechanisms. The hypocenters and focal mechanisms were extracted from the JMA unified catalog. The red square is defined as "the area surrounding the mainshock hypocenter" in this study. The numbers above the focal mechanisms indicate the JMA magnitude of each earthquake. (c) M–T diagram and cumulative number of  $M_{\rm JMA} \geq 1.0$ earthquakes that occurred in the area surrounding the mainshock. (d) Aftershock occurrence rate of events with a magnitude  $M_{\rm JMA} \geq 1.0$  (blue) and corresponding M–T diagram (gray). The inset shows the correlation between the aftershock occurrence rate and time on a log-log scale. The occurrence rate was estimated by calculating the reciprocal of the time during which 10 events with  $M_{\rm JMA} \geq 1.0$ occurred.

In this study, we examined the physical processes that controlled the  $M_L$  5.3 Kagoshima Bay earthquake

sequence in Kyushu, southern Japan. First, we determined the hypocenters and focal mechanisms of this earthquake sequence and delineated the fault structure. We also estimated the size of the mainshock and examined its relationship with the fore- and aftershocks to obtain a comprehensive view of this foreshock–mainshock–aftershock sequence. We then examined the spatiotemporal characteristics of the intense fore- and aftershocks to extract information about the aseismic phenomena governing this earthquake sequence. Finally, by integrating the observations, we established a model that can be used to explain the occurrence and characteristics of the foreshock–aftershock sequence associated with the 2017 M5.3 Kagoshima Bay earthquake.

#### 2 Methods

#### 2.1 Hypocenter relocations

We relocated 21.102 events listed in the JMA unified catalogue for the southern Kagoshima Bay region for the period from March 1, 2003 to April 8, 2018 using the Double-Difference (DD) method (Waldhauser & Ellsworth, 2000). This relative relocation method minimizes the residuals between the observed and theoretical travel time differences for adjacent earthquake pairs at each station. We applied the DD method to differential arrival time data, which were estimated from the waveform cross-correlation, and those listed in the JMA unified catalog. The procedure was identical to that reported in Yoshida and Hasegawa (2018a, b), which can be briefly described as follows.

First, we obtained precise differential arrival time data using waveform cross-correlations. We used the waveform data observed at 20 permanent seismic stations surrounding the focal area (Fig. 1a; green stations). At each station, the ground velocity was measured using three-component short-period seismometers (natural period of 1s) and a sampling rate of 100 Hz. We applied a 5–12 Hz Butterworth filter to the waveforms of each target event. We used 2.8 and 4.3 s time windows for the P- and S-waves, respectively, starting 0.3 s before their arrival. The arrival times were obtained from the JMA unified catalogue. If arrival times were not available, they were estimated using the one-dimensional JMA2001velocity model (Ueno et al., 2002) and the hypocenters, and origin times listed in the JMA unified catalogue. We calculated the waveform cross-correlations of event pairs with hypocenters within 3 km from each other and obtained differential arrival times when the cross-correlation coefficients were greater than 0.8. In total, we acquired 17.332.318 P-wave differential arrival time data points and 27.738.043 S-wave data points. We also derived the differential arrival data from the arrival time data listed in the JMA unified catalog: 474.670 data for P-waves and 543.226 data for S-waves. For the mainshock, only data derived from the JMA unified catalog were used because of its long duration.

Second, we applied the hypo-DD algorithm (Waldhauser & Ellsworth, 2000) to the differential arrival time data. We used a spherical shell two-layer model (Aki, 1965) for the hypocenter relocation. In this model, the seismic velocities in each layer are proportional to the power of the distance from the center of the Earth (Figure S3). The medium parameters were determined for consistency with the seismic tomography results obtained in the Kyushu region (Saiga et al., 2010). We used the hypocenters listed in the JMA unified catalogue for the initial locations for the relocation. Figures 2a and 3a show the distribution of these initial hypocenters. Differential arrival time data were weighted with respect to the square root of the cross-correlation coefficient. The hypocenters were updated after 50 iterations of the relocation procedure. During the first ten iterations, a higher weight was assigned to the catalogue data to constrain the relative locations of large-scale features. In the latter 40 iterations, a higher weight was assigned to the catalogue data to the data derived by the cross-correlations to delineate shorter-scale features. We evaluated the uncertainty in the relative hypocenter locations by recalculating the hypocenters 200 times based on bootstrap resampling of differential arrival time data.



Figure 2. Maps showing the distribution of the  $(\mathbf{a})$  initial hypocenters listed in the JMA unified catalog and  $(\mathbf{b})$  relocated hypocenters based on the DD method. Blue dots indicate the locations of the hypocenters. The red lines labeled A to I indicate the locations of the vertical sections shown in Figure 3.



Figure 3. Cross-sectional views showing the distribution of the  $(\mathbf{a})$  initial hypocenters listed in the JMA unified catalog and  $(\mathbf{b})$  relocated hypocenters based on the DD method. Blue dots indicate the locations of the hypocenters. The nine figures (A–I) represent the cross-sectional views along the vertical sections indicated by the red lines in Fig. 2.

#### 2.2 Estimation of focal mechanisms

We estimated the focal mechanisms based on the amplitude ratios of the waveforms using the method of

Yoshida et al. (2019b), which is similar to that of Dahm (1996). We used six focal mechanisms determined by the JMA (Fig. 1b) to represent effects of the path and site on the waveform. We determined the focal mechanisms of 161 earthquakes with  $M_L$  [?] 2. We used displacement waveforms obtained by integrating the velocity waveforms recorded at the 20 stations (green triangles in Fig. 1a) surrounding the hypocenters. The vertical component was used for the analysis of the P-wave, whereas radial and transverse components were used for that of the S-wave. We applied a 2–5 Hz bandpass filter to the waveforms, cutting them out with time windows of 2.8 s for P-waves and 4.3 s for S-waves starting 0.3 s before their arrival.

We used waveform cross-correlations to measure the amplitude ratios between target and reference events. The amplitude ratios were obtained for pairs with absolute correlation coefficients above 0.75. We used principal component analysis (PCA) to measure the amplitude ratios.

We only estimated the mechanism solutions when amplitude ratios were obtained for more than 20 channels. We eliminated the results when the Variance Reduction (VR) was below 80:

$$\text{VR} = \left(1 - \frac{\sum_{k=1}^{n} (d_k - s_k)^2}{\sum_{k=1}^{n} d_k^2}\right) \bullet 100, (1)$$

where  $d_k$  and  $s_k$  are the observed and calculated displacement amplitude ratios, respectively, at channel k.

#### 2.3 Estimation of the size of the mainshock source

We estimated the size of the mainshock source based on the circular crack source model (e.g., Sato & Hirasawa, 1973; Madariaga, 1976). In this source model, the source radius is related to the S-wave corner frequency,  $f_c$ , as follows:

$$r = \frac{k}{f_{r}}, (2)$$

where r is the source radius, k is a constant, and  $\beta$  is the S-wave velocity close to the source. Based on a rupture velocity of  $0.9\beta$ , k is 0.44 in the model of Sato and Hirasawa (1973) and 0.32 in the model of Madariaga (1976) for P-waves (Kaneko & Shearer, 2014). Because the estimated source size depends on the source model, we computed the fault size using both models. We assumed a  $\beta$  value of 3.4 km/s.

We used the spectral ratio method (e.g., Imanishi & Ellsworth, 2006) to estimate the corner frequency of the mainshock. In this method, effects of the propagation and location on the seismic wave are empirically removed using the waveforms of an adjacent small earthquake (empirical Green's function, EGF, event). Based on the assumption that the source spectrum, that is,  $S_j(f)$ , follows the  $\omega^2$ model (Aki, 1967; Brune, 1970), the theoretical ratio between the velocity spectra of the mainshock,  $v_i(f)$ , and the EGF event,  $v_i^{\text{egf}}(f)$ , at station *i* can be calculated as follows:

$$SSR_{ij}(f) = \frac{v_i(f)}{v_i^{\text{egf}}(f)} = \frac{M_0}{M_0^{\text{egf}}} \frac{R_{\partial\varphi_i}}{M_0^{\text{egf}}}$$
$$greekR_i^{\text{egf}} \frac{1 + \left(\frac{f}{f_c^{\text{egf}}}\right)^2}{1 + \left(\frac{f}{f_c}\right)^2}, (3)$$

where  $M_0$  and  $M_0^{\text{egf}}$  are the seismic moments of the target earthquake and EGF event, respectively;  $R_{\vartheta\varphi\imath\vartheta}\alpha\imath\delta$  $R_{\vartheta\varphi\imath}^{\text{egf}}\alpha\rho\varepsilon$  the padiation patterns at station i, respectively; and  $f_c^{\text{egf}}$  is the corner frequency of the EGF event. Based on Eq. (3),  $f_c$  can be estimated from the spectral ratios.

We calculated the spectral ratios by using P-wave velocity waveforms observed at the 20 stations surrounding the source area (green inverted triangles in Fig. 1b). The EGF events were earthquakes with M [?] 2 and a distance from the mainshock below 1.0 km based on the relocated hypocenters. The following procedure was performed (Yoshida et al., 2017):

(1) For the target mainshock and EGF events, the waveforms of the three components were extracted from a 2.0 s time window starting 0.3 s before the arrival of the P-wave at each station. The multitaper method (Thomson, 1982; Prieto et al., 2009) was applied to calculate the spectra. (2) For channels with EGF observation spectra with a signal-to-noise ratio > 4 at all frequencies from 0.5 to 30.0 Hz, the spectral ratio

between the main shock and EGF event was calculated. We used waveforms up to 0.3 s before the arrival of the P-waves for the noise window. (3) We calculated the geometric mean of the spectral ratios GSR (f) of all channels at each frequency for the EGF events, which satisfied the above-mentioned criterion at five or more stations: GSR  $(f) = \prod_{i=1}^{N} (\text{SR}_i(f))^{\frac{1}{N}}$ , (4) where SR<sub>i</sub>(f) is the observed spectral ratio obtained at station i and N is the number of stations. (4) By using the grid search and minimizing the evaluation function J, the corner frequencies of the main shock,  $f_c$ , and EGF event,  $f_c^{\text{egf}}$ , were determined:  $J = \sum_{k=1}^{n_{\text{freq}}} \log (\text{GSR}(f_k)) - \text{Alog} \left( \text{NSR} \left( f_k; f_c, f_c^{\text{egf}} \right) \right) |$ ,(5) where NSR  $(f; f_c, f_c^{\text{egf}}) = \frac{1+(f/f_c^{\text{egf}})^2}{1+(f/f_c)^2}, n_{\text{freq}}$  is the number of frequencies, and  $f_k$  is frequency (at 0.5 Hz intervals from 0.5 to 30 Hz). The grid search was performed for  $f_c$  and  $f_c^{\text{egf}}$  by assuming a range from 0.1 to 100 Hz at 0.1 Hz steps. The amplitude ratio, A, was estimated using the least squares method for each grid search step.

We applied the spectral ratio method to 33 EGF candidates. We obtained spectral ratios for 13 EGF events, which satisfy our S/N ratio and data criteria. Figure S4 shows the spectral ratios of the 13 EGF events.

#### 2.4 Detection of aseismic processes from seismicity

The Epidemic Type Aftershock Sequence (ETAS) model (Ogata, 1988), which is based on the superposition of the modified Omori law (Ustu, 1961), can be used to explain mainshock–aftershock seismicity. The ETAS model assumes that the seismicity rate is the sum of the background rate of independent events,  $\lambda_0$ , and aftershocks triggered by each event,  $\lambda_i(t)$ :

$$\lambda(t) = \lambda_0 + \sum_{i:t_i < t} \lambda_i(t) .(6)$$

Based on the modified Omori law, each earthquake can trigger its own aftershock sequence (Utsu et al., 1995):

$$\Lambda_i(t) = \frac{K_0}{(c+t-t_i)^p} e^{\alpha(M_i - M_{\min})}, (7)$$

where  $t_i$  is the occurrence time;  $M_i$  is the magnitude of each event, *i*, that occurred prior to time *t*;  $M_{\min}$  is the magnitude of completeness of the earthquake catalogue;  $K_0, c$ , and *p* are constants; and *t* is the time that has elapsed since the main event.

We applied the ETAS model to the seismicity observed after the mainshock in Kagoshima Bay and investigated the difference between the simulated and observed seismicity. The results show that the foreshock activity cannot be explained by the ETAS model, likely because aseismic processes mainly controlled the foreshock activity. We used the timings and magnitudes of the earthquakes listed in the JMA catalogue. The lower limit of the magnitude,  $M_C$ , was set to 1.0. Figure S4 shows the magnitude–frequency distribution. The distribution follows the Gutenberg–Richter law (Gutenberg & Richter, 1944) when  $M_{JMA}$  [?] 1.0. The SASeis2006 algorithm by Ogata (2006) was used to estimate the model parameters and calculate the residuals of the ETAS model.

#### 3 Results

#### 3.1 Fault structure and seismic gap

We obtained the relocated hypocenters of 20.347 events and the focal mechanisms of 61 events. Almost all events in the Kagoshima Bay earthquake sequence can be accurately relocated with the DD algorithm. The location data for 755 earthquakes were removed because their hypocenters were located above the ground surface or they contained outliers in the differential arrival time data. We computed the differences between the maximum and minimum values in the 95% confidence interval of the hypocenter locations (Fig. S6) estimated from the bootstrap resampling and obtained the medians as a measure of the estimation error of the relative location: 0.0013 in longitude, 0.0011 in latitude, and 0.42 km in depth.

Figures 2b and 3b show the distribution of the relocated hypocenters. Movie 1 shows the animation of the cross-sectional views of the hypocenters along various lines. Most hypocenters are located within ~5 km from the mainshock hypocenter and are distributed along several planes. These characteristics are in contrast to the distribution of the initial hypocenters (Figs 2a and 3a), which were scattered three-dimensionally, similar

to a cloud. This significant change in the hypocenter distribution is due to the improvements of the relative locations of the hypocenters in this study based on the use of many accurate differential arrival time data. Similar improvements of the relative hypocenters, from cloud-like distribution to planar structures, were previously reported for shallow earthquakes in Japan based on a similar method and data (e.g., Yoshida & Hasegawa, 2018a, b). The cloud-like distribution of the initial hypocenters reflects the errors in the hypocenter locations in the JMA unified catalog, which are due to errors in the manual selection.

Figure 4 shows the spatial distribution of the focal mechanisms. Because the reference focal mechanisms are in the northern part of the source region (Fig. 1b), newly estimated focal mechanisms are mainly located in the northern part. The figure shows that the nodal planes of most focal mechanisms are parallel to the planar structures of the hypocenters, suggesting that individual small earthquakes occurred on several macroscopic planes.



**Figure 4.** Estimated focal mechanisms plotted on the hypocenter distribution. The left figure is a map view and the nine figures (A–I) on the right are cross-sectional views along vertical sections indicated by the red lines in the left figure.

Based on Figs 2b, 3b and 4, the fault structures of the 2017 Kagoshima Bay earthquake sequence are complex, consisting of several subparallel planes. However, the distribution of the hypocenters was relatively simple before the mainshock. Figure 5 shows an enlarged view of the spatial distribution of the hypocenters of the foreshocks (red dots). Most hypocenters are evenly distributed in one plane, with a strike parallel to those of the nodal planes of the focal mechanisms of the mainshock and individual small earthquakes, suggesting that the mainshock and most of the foreshocks occurred on this plane.



Figure 5. Hypocenter distribution of the foreshocks. Red and blue circles represent the hypocenters of foreshocks and aftershocks, respectively, Blue circles represent the hypocenters of the precursory activity. (a) Map showing the hypocenters of the precursor activity and aftershocks. (b) Map showing only the hypocenters of the precursory activity. The broken ellipse indicates the location of the seismic gap. (c) Cross-sectional views along vertical sections A to I shown in (a). The yellow star indicates the hypocenter location of the mainshock.

The hypocenters of the foreshocks are not uniformly distributed in the plane, but they are distributed in form of a doughnut, that is, a seismic gap forms in the center of the plane (broken ellipse in Fig. 5b). To demonstrate this distribution, we estimated the lateral distribution of the moment release on the fault (Fig. 6a) during the foreshock sequence following Yoshida et al. (2020a). We computed the seismic moment release of each earthquake by assuming that its magnitude is equal to the moment magnitude. Subsequently, we summed the moment release values of the points that were evenly spaced every 0.04 km by using the earthquakes within the nearest grid cell. The result shown in Fig. 6b indicates that the moment release of the foreshock sequence is smaller (<  $10^{11}$  Nm) in the region corresponding to the seismic gap than in the surrounding region (>  $10^{11}$  Nm). The hypocenter of the foreshocks and aftershocks. Although aftershocks occur inside the seismic gap based on the map (Fig. 5a), they actually occur in shallower areas than the foreshocks (Fig. 5c), that is, not within the seismic gap of the foreshocks.



Figure 6. Seismic gap of earthquakes in the foreshock period projected on the dominant plane. (a) Comparison of the size of the seismic gap with the estimated sizes of the faults associated with the mainshock. Blue circles indicate the hypocenters of the precursory activity corresponding to the fault sizes by assuming stress drops of 10 MPa. The yellow star indicates the location of the mainshock hypocenter. The red circle represents the size of the fault corresponding to the mainshock estimated based on the model of Sato and Hirasawa (1973). The green circle represents the size of the fault corresponding to the mainshock estimated based on the model of Madariaga (1976). (b) Moment release amount (color scale) computed for each 0.04 km grid cell. The broken ellipse represents the seismic gap.

The median value of the estimated corner frequencies of the mainshock is 1.9 Hz (Fig. S4). The first and third quartiles are 1.8 and 2.5 Hz, respectively. Based on the median corner frequency and the models proposed by Sato and Hirasawa (1973) and Madariaga (1976), the source radius of the mainshock is 787 and 572 m, respectively. It is much smaller than the foreshock and aftershock regions but comparable to the seismic gap (Fig. 6a).

#### 3.2 Foreshock and aftershock migration

Figures 7a–c show the occurrences of the foreshocks on a color scale. In Figs 8a–c, the occurrence of each earthquake is compared with the longitude, latitude, and depth, respectively, to illustrate their migration behavior. In the longitudinal direction (Fig. 8a), the hypocenters expand nearly symmetrically in the first 230 days of foreshock activity and concentrate in the east close to the hypocenter of the mainshock during the last  $^{70}$  days. In the latitudinal direction (Fig. 8b), the hypocenters migrate from north to south. In the depth direction (Fig. 8c), the hypocenters migrate both in the shallow and deep directions, indicating that most earthquakes occurred in the deeper part surrounding the mainshock hypocenter during the last  $^{70}$  days of activity.



Figure 7. Spatiotemporal evolution of the hypocenters  $(\mathbf{a})-(\mathbf{c})$  before and  $(\mathbf{d})-(\mathbf{f})$  after the mainshock. (a) Projection of the hypocenters,  $(\mathbf{d})$  map view,  $(\mathbf{b})$  and  $(\mathbf{e})$  east-west cross section, and  $(\mathbf{c})$  and  $(\mathbf{f})$  north-south cross section. The symbol sizes corresponds to the JMA magnitude. The hypocenters are colored according to their occurrence time measured relative to that of the mainshock, that is, the mainshock occurred at time 0 and negative and positive numbers denote the days before and after the mainshock, respectively.



Figure 8. Temporal evolution of hypocenters in the  $(\mathbf{a})$  latitude,  $(\mathbf{b})$  longitude, and  $(\mathbf{c})$  depth directions. (d) Temporal evolution of the aftershock hypocenters in the depth direction. The red crosses and yellow curve in (d) indicate the depth above which the shallowest 10% of the hypocenters are located (D10) for every bin with 400 events based on the occurrence time. The circle size corresponds to the JMA magnitude. The yellow star indicates the hypocenter of the mainshock.

Figures 7d–f show the distribution of aftershock hypocenters colored based on the occurrence time of each event. Figure 8d shows the temporal evolution of the aftershock hypocenters as a function of the depth. The temporal evolution of the aftershock hypocenters in both the latitudinal and longitudinal directions is shown in Fig. S7. Because the spatial distribution of the aftershocks is complex, the spatiotemporal features of the aftershocks are more difficult to determine than those of the foreshocks. Overall, the aftershock hypocenters move upward with time, as shown in Fig. 8d, which depicts the depths above which the shallowest 10% of the hypocenters are located (D10) for each bin containing 400 events, as denoted by the red curve. Although earthquakes occur in a relatively deep region immediately after the mainshock, the upper limit of the seismic depth (D10) gradually moves in the shallow direction, that is, the hypocenters gradually move to the shallower part with time after the mainshock.

#### 3.3 Deviation of the seismicity from Omori's law

We investigated the seismicity rate of the Kagoshima Bay earthquake sequence after the mainshock. Figure 1d shows the seismicity rates of the  $M_{JMA}$  [?]1.0 events in the area surrounding the hypocenter of the mainshock (red frame in Fig. 1b). The seismic rate was obtained by calculating the reciprocal of the time required to generate ten earthquakes that were arranged in chronological order. Based on Fig. 1d, the seismicity rate decreases by the power of the elapsed time immediately after the mainshock, as described by the modified Omori law (Utsu, 1961). The seismicity rate abruptly increases ~44 days after the mainshock, which corresponds to the occurrence of the largest aftershock ( $M_L$  4.4), suggesting that the increase is due to secondary aftershocks. A period with a high seismicity rate started approximately 20 to 40 days after the mainshock; the seismic activity was temporarily strong despite the absence of large aftershocks.

Based on maximum likelihood estimation, we obtained the following parameters for the ETAS model:  $K_0 = 34.205, c = 1.3163 \times 10^{-2}, p = 1.0685, \alpha = 1.5078, \text{and}\mu = 2.9603 \times 10^{-2}$ . Based on Ogata (1992), the range of  $\alpha$ -values is 0.35–0.85 for swarm seismicity and 1.2–3.1 for non-swarm seismicity. The  $\alpha$  value estimated for the seismic activity in Kagoshima Bay is within the latter range.

In Fig. 9, the cumulative number of earthquakes simulated using the estimated model parameters is compared with the observations. Overall, the number predicted based on the ETAS model matches the observations. However, the simulated number of earthquakes is lower than the observed number 20–40 days after the mainshock. To quantitatively examine the magnitude of the discrepancy between the model and observations, we performed residual analysis using the transformed time, similar to Ogata (1988). Figure 9c shows that the discrepancy between the model and observations is high at a transformed time between 1.000 and 1.500, corresponding to the period of 20–40 days after the mainshock. This deviation is significant at the 95% significance level based on the assumption of a uniform distribution.



Figure 9. (a) M–T diagram. (b) Observed cumulative number of aftershocks with  $M_L \geq 1.0$  (red solid line) and predicted number based on the estimated ETAS parameters (blue solid line). Each curve represents the cumulative numbers starting 0.1 days after the mainshock. (c) Results of the residual analysis, where the blue solid line shows the observed events with respect to the transformed time on the horizontal axis and cumulative number of observed  $M_L \geq 1.0$  earthquakes on the vertical axis. The black dotted line represents the transformed time at which the assumed model fully matches the observation. The red solid and red broken lines indicate the two-sided 95% and 99% error bounds of the Kolmogorov–Smirnov statistic, respectively. The gray zone in (c) shows the range of the transformed time corresponding to the period of 20–44 days after the mainshock highlighted in gray in (b).

The large discrepancy between the predicted and observed seismicity rates 20–40 days ( $^{-1.000-1.500}$  in Fig. 9c) after the mainshock can be explained by a temporary increase in the background seismicity, which was assumed to be constant over the entire period of this analysis in the model. The transient increase in the background seismicity rate suggests that the Kagoshima Bay earthquake sequence may have been affected by physical processes other than earthquake-to-earthquake interactions, especially during this period (20–40 days) and that an aseismic process may have led to the largest aftershock ( $M_L$  4.4) that occurred 44 days after the mainshock. Contrarily, most aftershocks can be explained as general mainshock–aftershock seismic activity, suggesting that stress changes caused by the mainshock resulted in numerous aftershocks.

#### **4** Discussion

Our results show that: (1) the foreshocks of the 2017 M5.3 Kagoshima Bay earthquake sequence occurred on a single plane with a steep dip to the east, whereas aftershocks occurred on several more complex planar structures, (2) the foreshock hypocenters formed a seismic gap, and (3) the foreshock and aftershock hypocenters exhibit clear migration behaviors. In this section, we integrated these observations and propose a simple model that can explain the occurrence of the foreshock–mainshock–aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake based on the upward fluid movement, which is similar to the fault-valve model proposed by Sibson (1992).

#### 4.1 Migration of foreshock activity along a plane

The clear hypocenter migration observed for the foreshock sequence suggests that aseismic physical processes controlled this sequence. In fact, the seismicity rate of the foreshock sequence could not be reproduced by the ETAS model, suggesting that the earthquake-to-earthquake interaction cannot explain this sequence. Thus, the foreshock sequence must be understood as temporary increase in the background seismicity rate, similar to that of the earthquake swarm.

In Fig. 10, the distances of the foreshock hypocenters from the mean location of the first three events are plotted against time. The expansion front of the pore pressure diffusion model reported in Shapiro et al. (1997) is also shown, which can be expressed by the following equation including various diffusion coefficients  $D_h$ :

$$r = \sqrt{4\pi D_h t}, \# (9)$$

where r is the distance from the point pressure source and t is the time. In this study, we set the initiation time to 220 days before the mainshock because the seismicity rate significantly increased at this time (Fig. 1c). We also show the propagation fronts of the linear spread model that has been used for aseismic slip propagation in the past (e.g., Vidale & Shearer, 2006).



Figure 10. Temporal evolution of the distances between the foreshocks and initial hypocenter. Blue circles represent the hypocenters expressed by the size corresponding to the JMA magnitude. The black curves show the fluid diffusion models with  $D_h = 0.01$ , 0.03, and 0.05 m<sup>2</sup>/s. Gray straight lines show the linear spread model with migration speeds of d = 0.001, 0.003, and 0.005 km/h.

The pore pressure diffusion model with a hydraulic diffusion coefficient of  $^{0.05}$  m<sup>2</sup>/s matches the observations better than the linear spread model. In previous studies, it has been estimated that the hydraulic diffusion coefficient in the crust ranges from  $^{0.01-10}$  m<sup>2</sup>/s (e.g., Talwani et al., 2007; Shelly et al., 2016; Yoshida & Hasegawa, 2018a), which is similar to the foreshock migration speed of the M5.3 Kagoshima Bay earthquake sequence. Based on the linear spread model, the propagation velocity is  $^{0.001-0.005}$  km/h. Based on previous studies, the migration speed of aseismic slip propagation ranges from 0.1–1.0 km/h (e.g., Lohman & McGuire, 2007; Kato et al., 2016), which is significantly higher than the migration speed of the present foreshock activity. If we advance the initiation timing of propagation, the propagation speed decreases. Thus, according to the migration speed and spatiotemporal pattern of the foreshocks, the pore pressure diffusion model better explains the overall migration of the foreshock hypocenters.

Aseismic creep related to the nucleation process of the mainshock might be involved in the migration of the foreshocks. In fact, physical simulations indicate interseismic creep in seismogenic patches from external stable-slip regions before the occurrence of unstable slip (Tse & Rice, 1986). Such an expansion of quasi-static slip prior to the mainshock may explain the current migration of the foreshocks (e.g., Dodge et al., 1996; Yabe & Ide, 2018). However, the source of the mainshock is smaller than the foreshock area (Fig. 6a), which contradicts the hypothesis because the mainshock rupture zone should include the nucleation area. Note that the size of the source of the mainshock was estimated based on source models assuming a constant rupture velocity (subshear rupture propagation). If the assumptions differ from reality (e.g., supershear rupture propagation), the source size may differ from our estimation, explaining this contradiction. However, the aftershocks migrate upward on multiple planes (Fig. 8d), which can be explained with the foreshock sequence if the pore pressure migration model is adopted. Thus, we prefer the hypothesis that pore pressure migration is primarily responsible for the generation of the 2017 M5.3 Kagoshima Bay earthquake sequence. The heterogeneity in the permeability and/or pore pressure along the fault may explain the up- and downward movement of the hypocenter along the plane (Fig. 8c).

However, recent observations of fluid injection-induced seismicity and natural earthquake swarms suggest that an increase in the pore pressure can cause aseismic slip (Cornet et al., 1997; Guglielmi et al., 2015;

Ruhl et al., 2016; Yoshida & Hasegawa, 2018a; De Barros et al., 2020). In the presence of fluids, the effective normal stress decreases and the critical nucleation size increases; thus, the occurrence of aseismic slip is likely (e.g., Scholz, 1998). The increase in the pore pressure also accelerates creep in the stable-slip segment of the fault. Both aseismic slip and fluid movement may have contributed to the occurrence of foreshocks. Furthermore, the poroelastic effects associated with pore pressure migration (Segall, 1989; Goebel et al., 2018) and the earthquake-to-earthquake interaction (Helmstetter, 2002) may contribute to the occurrence of earthquakes.

#### 4.2 Seismic gap of the foreshock and aftershock sequence in the mainshock fault plane

The doughnut-like pattern of the foreshocks (Fig. 6) is similar to the "Mogi doughnut" (Mogi, 1969). It has been reported that aftershocks do not occur in the mainshock region (e.g., Mendoza & Hartzell, 1988; Das & Henry, 2003; Woessner et al., 2006; Asano et al., 2011; Ebel & Chambers, 2016; Yoshida et al., 2016b and 2020a; Ross, 2017b, 2018; Wetzler et al., 2018), which is likely because the shear stress was released during the mainshock. In Figure 6a, the size of the seismic gap is compared with the estimated size of the fault related to the mainshock. Because the centroid location of the mainshock was not determined, we assumed the centroid is located by a few hundred meters into the shallower region such that the mainshock centroid is located in the center of the seismic gap shown in the figure. The fault size of the mainshock is similar to that of the seismic gap. This is consistent with the hypothesis that the mainshock rupture occurred in the seismic gap of the foreshock and aftershock activities. A similar spatial separation of the mainshock and fore- and aftershocks in the rupture area was also reported for a recent M5.2 intraplate earthquake that occurred in Akita, NE Japan (Yoshida et al., 2020).

The seismic gap in the foreshock activity may originate from the spatial heterogeneities in the frictional and material properties along the fault plane. The fault strength of the mainshock rupture area may have been higher than that of the surrounding area, as proposed in the asperity model of Lay & Kanamori (1981). Foreshocks can be understood as failures of small seismogenic patches in the surrounding stable area. Alternatively, the area may have been covered by an impermeable medium, hindering fluid intrusion. The occurrences of foreshocks and aseismic slip increased the shear stress in the future source region of the mainshock rupture. The mainshock occurred in this region due to the gradually increasing pore pressure and shear stress.

#### 4.3 Upward migration of the aftershocks along several planes

The aftershock sequence of the Kagoshima Bay earthquake sequence follows Omori's law (Fig. 1d), suggesting that this sequence was triggered by the M5.3 mainshock. However, the aftershock sequence slightly deviates from the prediction based on the ETAS model (Figs 9b–c). The transient increase in the background seismicity rate suggests that the Kagoshima Bay earthquake sequence may have been affected by physical processes other than earthquake-to-earthquake interactions, especially during this period (20 to 40 days) and that these aseismic processes may have led to the largest aftershock (M<sub>L</sub> 4.4) that occurred 44 days after the mainshock. Based on the model simulations of fluid injection-induced seismicity, Hainzl and Ogata (2005) pointed out that the background seismicity rate of the ETAS model is sensitive to the amount of injected water. In previous studies, similar observations were made for fluid injection-induced seismicity and natural earthquake sequences (Llenos & Michael, 2013; Yoshida & Hasegawa, 2018b; Kumazawa et al., 2019).

Our results indicate that the aftershock hypocenters migrated toward the shallower portion on multiple planes. Such upward movements of hypocenters have been previously reported for earthquake swarms following nearby large earthquakes and it has been concluded that they reflect the upward pore pressure migration associated with the fault-valve behavior (Shelly et al., 2015; Ruhl et al., 2016; Yoshida & Hasegawa, 2018a, b). Examples are the earthquake swarms that occurred in northeastern Japan following the 2011 Tohoku-Oki earthquake (Yoshida et al., 2016a; Yoshida & Hasegawa, 2018a, b). The earthquake swarms might originate from the pore pressure increase because (1) they occurred in the stress shadow of the 2011 Tohoku-Oki earthquake with a time delay of a few weeks despite the reduction in the shear stress, (2) they are located beneath the caldera structures that are believed to host shallow igneous bodies, with hydrothermal fluids immediately below, (3) they are located a few kilometers above S-wave reflectors and the low-velocity zone including fluids, and (4) their hypocenters migrate upward (Yoshida & Hasegawa, 2018a; Yoshida et al., 2019a). The Kagoshima Bay swarm was also located beneath an ancient caldera and involved the upward migration of aftershocks, which can be explained by an increase in the pore pressure. Fluid paths in the crust may have expanded due to the deformation and shaking associated with the mainshock. Pore pressure migration may explain deviations in the seismicity rate from Omori's law. These observations are consistent with the prediction based on the fault-valve model proposed in Sibson (1992), that is, upward fluid discharge after the mainshock. In recent geodetic studies, a porosity wave associated with the fault-valve action was detected (Rossi et al., 2016 and 2018).

We presume that the subducting Philippine Sea Plate is the source of fluids, similar to the model reported in Hasegawa et al. (2005), which is based on the geophysical and geological observations in northeastern Japan. This hypothesis is supported by seismic data obtained in Kyushu using tomography, which indicate that the existence of an inclined low-velocity layer continuously distributed in the mantle wedge and reaching right below the volcanic front as northeastern Japan (Zhao et al., 2012). The low-velocity zone is considered to represent the ascending flow portion of the secondary convection within the mantle wedge and therefore contains fluids from the slab and resultant melts (Hasegawa et al., 2005). The buoyancy facilitated the upward migration of the fluids, as shown in simulations (e.g., Iwamori, 1998; Wada et al., 2015; Horiuchi et al., 2016), and the fluids reached the source region of the Kagoshima Bay sequence.

#### 4.4 Comprehensive interpretation of the seismic activity in Kagoshima Bay

Here, we summarize our simple model that comprehensively explains the observed results of the foreshockmainshock-aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake.

First, fluids that have infiltrated the mainshock fault plane caused the foreshock activity. The hypocenter migration of the foreshock activity can be interpreted considered to be a reflection of fluid movement and possibly triggered aseismic slip on the plane. Second, the occurrences of foreshocks and aseismic slip increased the shear stress in the future source region of the mainshock (seismic gap in Fig. 6). The mainshock finally occurred in this region due to the gradually increasing pore pressure and shear stress. Third, the change in the stress associated with the occurrence of the mainshock primarily triggered aftershocks in the area surrounding the mainshock including regions outside the mainshock fault plane. Fluids started to move upward due to the deformation and shaking associated with the mainshock. Together with the fluids, the aftershock hypocenters moved to shallower regions. Thus, the overall sequence of the 2017 M5.3 Kagoshima Bay earthquake can be explained by consistent upward fluid movement.

#### 4.5 Implications to the foreshock-mainshock-aftershock sequence

The results of previous studies suggested that many earthquake swarms are caused by the movements of crustal fluids (e.g., Mogi, 1989; Italiano et al., 2001; Fischer and Horálek, 2003; Parotidis et al., 2003; Bianco et al., 2004; Yukutake et al., 2011; Shelly et al., 2016; Yoshida et al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). The results of the present study suggest that the generation mechanism of the foreshock activity is the same as that of earthquake swarms, that is, a temporary increase in background seismicity rate due to increasing pore pressure and aseismic slip. The whole sequence of the Kagoshima Bay seismicity can be understood as the transition from swarm activity to the mainshock–aftershock sequence.

The 2008 Mogul earthquake swarm, Nevada, may be a similar example. This sequence was also initiated by swarm activity but shifted to a mainshock–aftershock sequence after the occurrence of the M4.9 mainshock. The upward migration of the earthquakes suggests that fault-valve behavior is involved in the occurrence of this earthquake sequence (Ruhl et al., 2016). The aftershock activities of the 2014  $M_L$  4.8, Ubaye earthquake, France (De Barros et al., 2019), and the foreshock and aftershock activities of the 2017 M5.2 Akita-Daisen event can also be understood as transitions from swarm activity to mainshock–aftershock sequences (Yoshida et al., 2020b). Similarly, aseismic slip may have caused the foreshocks and mainshock of the 2011 M9 Tohoku-Oki earthquake (Kato et al., 2012); 2014 Iquique Mw 8.1 earthquake, Chile (Kato & Nakagawa, 2014); and 2009 M6.3 L'Aquila earthquake (Borghi et al., 2016). It is likely that pore pressure migration and aseismic slip propagation occasionally coexist (Waite & Smith, 2002; Ross et al., 2017a; Yoshida & Hasegawa, 2018; De Barros et al., 2020) and contribute to the increase in the background seismicity rate. Such aseismic processes may also cause mainshock–aftershock activity without notable foreshocks. The 2019 M6.7 Yamagata-Oki earthquake, NE Japan, may be an example. The earthquake occurred in the stress shadow of the 2011 Tohoku-Oki earthquake and exhibited an upward aftershock migration (Yoshida et al., 2020b). These observations suggest that the monitoring of aseismic processes is crucial to understanding the seismic activity.

#### 5 Conclusions

The results of previous studies suggested that many earthquake swarms have been caused by the movement of crustal fluids (e.g., Mogi, 1989; Fischer and Horálek, 2003; Parotidis et al., 2003; Bianco et al., 2004; Yukutake et al., 2011; Chen et al., 2012; Shelly et al., 2016; Yoshida et al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). In the present study, the intense foreshock-mainshock-aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake was examined. The results show that the whole sequence can be explained by upward fluid movement: (1) most foreshocks were located on a single plane with a steep dip to the east and migrated along the plane. This foreshock migration can be interpreted as a reflection of fluid movement and possibly triggered aseismic slip on the plane; (2) The hypocenter of the mainshock was located at the edge of a seismic gap with a size comparable to that of the source of the mainshock rupture. This suggests that the mainshock rupture was due to the slip of this seismic gap and the seismic gap was a large seismogenic patch with higher fault strength, which finally ruptured due to the increase in the pore pressure and aseismic slip in the surrounding areas; and (3) Aftershocks occurred on several planes with a steep dip to the east and moved from deeper to shallower regions. The upward migration can be interpreted as a reflection of post-failure fluid discharge. Thus, the overall sequence of the 2017 M5.3 Kagoshima Bay earthquake can be explained by upward fluid movement, as presumed by the fault-valve model (Sibson, 1992).

The whole sequence of the Kagoshima Bay seismicity can be understood as the transition from swarm activity to a mainshock–aftershock sequence. The results of the present study suggest that the generation mechanism of the foreshock activity is the same as that of the earthquake swarms, that is, a temporary increase in the background seismicity rate due to increasing pore pressure and aseismic slip. Aseismic processes sometimes cause a large earthquakes that is followed by numerous aftershocks; the foreshock–mainshock–aftershock sequence may such a sequence.

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1	Fault-valve behavior estimated from intensive foreshocks and aftershocks of
T	raut-varve benavior estimated if our intensive foreshocks and after shocks of
2	the 2017 M 5.3 Kagoshima Bay earthquake sequence, Kyushu, southern
3	Japan
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15	Key Points:
16	• Intensive foreshocks migrate via one plane.
17	• Aftershock hypocenters migrate toward shallower levels via several planes.
18	• Upward pore pressure migration explains the occurrence of the foreshock-mainshock-
19	aftershock sequence.

#### 5 6

### 20 Abstract

Determining fluid migration and pore pressure changes within the Earth is key to understanding 21 earthquake occurrences. We investigated the spatiotemporal characteristics of intense fore- and 22 aftershocks of the 2017 M<sub>L</sub> 5.3 earthquake in Kagoshima Bay, Kyushu, southern Japan, to 23 examine the physical processes governing this earthquake sequence. The results show that the 24 foreshock hypocenters moved upward on a sharply defined plane with steep dip. The mainshock 25 26 hypocenter was located at the edge of a seismic gap formed by foreshocks along the plane. This spatial relationship suggests that the mainshock ruptured this seismic gap. The corner frequency 27 of the mainshock supports this hypothesis. The aftershock hypocenters migrated upward along 28 29 several steeply dipped planes. The aftershock activity slightly differs from the simple 30 mainshock–aftershock type, suggesting that aseismic processes controlled this earthquake sequence. We established the following hypothesis: First, fluids originating from the subducting 31 slab migrated upward and intruded into the fault plane, reducing the fault strength and causing a 32 33 foreshock sequence and potentially aseismic slip. The continuous decrease in the fault strength 34 associated with an increase in the pore pressure and the increase in shear stress associated with aseismic slip and foreshocks caused the mainshock in an area with relatively high fault strength. 35 The change in the pore pressure associated with post-failure fluid discharge contributed to 36 37 aftershocks, causing the upward migration of the earthquake. These observations demonstrate the importance of considering fluid movement at depth not only earthquake swarms but also 38 foreshock--mainshock-aftershock sequences. 39

#### **1** Introduction 40

An earthquake is a natural phenomenon during which a high-speed rupture propagates along a 41 fault. Two factors control the occurrence of an earthquake: an increase in the shear stress acting 42 on the fault and a decrease in the fault strength. The results of previous studies suggested that the 43 increase in the pore pressure plays an important role in the earthquake occurrence (e.g., 44 Hasegawa, 2017; Hubbert & Rubey, 1959; Nur & Booker, 1972; Sibson, 1992; Rice, 1992) 45 because it reduces the fault strength.

A well-known example of fluid-driven seismicity is the seismicity induced by fluid 47 injection for engineering purposes (e.g., Ellsworth, 2013). There is also growing evidence that 48 natural earthquake swarms are closely related to fluid movement at depth. In fact, the 49 characteristics of many natural seismic swarms are similar to those of fluid injection-induced 50 seismicity including the migration behavior of the earthquake hypocenter (e.g., Fischer and 51 Horálek, 2003; Parotidis et al., 2003; Bianco et al., 2004; Yukutake et al., 2011; Shelly et al., 52 2016; Yoshida et al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). Based on the 53 determination of the hypocenters and focal mechanisms of earthquake swarm at the 2009 54 Hakone volcano, the diffusion of high-pressure fluid triggered the swarm (Yukutake et al., 2011). 55 The spatiotemporal evolution of seismic activity in the Long Valley Caldera, California, indicates 56 that a pore pressure transient with a low-viscosity fluid initiated and sustained the swarm in 2014 57 (Shelly et al., 2016). It has been hypothesized that several earthquake swarms that occurred after 58 the 2011 Tohoku-Oki earthquake were triggered by a decrease in the fault strength due to upward 59 pore pressure migration (Terakawa et al., 2013; Okada et al., 2016; Yoshida et al., 2016a, 2019a). 60 Not only earthquake swarms but also foreshock-mainshock-aftershock sequences may be 61 62 closely related to the fluid behavior in the Earth interior. Sibson (1992) established the fault-

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valve model in which the pore pressure cycle controls the earthquake cycle due to 63 overpressurized fluids that rise from the deeper portion of the fault. In this model, fault ruptures 64 create a transient fracture permeability within the fault zone, which acts as a valve, promoting 65 66 the upward discharge of fluids from deeper portions of the crust. This model is supported by various geological and geophysical observations (Sibson, 2020). Hasegawa et al. (2005) 67 proposed a model for the deformation process in a subduction zone based on various geophysical 68 observations including seismic tomography data obtained for northeastern Japan. In this model, 69 fluids expelled from the subducting slab migrate upward, reach the crust, and cause anelastic 70 crustal deformation including earthquakes. 71 The migration characteristics of earthquake hypocenters can be used to infer the origin of 72 the seismicity (e.g., Yukutake et al., 2011; Ruhl et al., 2016; Yoshida & Hasegawa, 2018a,b; De 73 74 Barros et al., 2019). Pore pressure migration and aseismic slip propagation are typical mechanisms attributed to the migration of earthquakes. In the former mechanism, the hypocenter 75 migration is presumed to reflect the migration of fluids (e.g., Shapiro et al., 1997; Talwani et al., 76 2007). In the latter mechanism, the hypocenter migration is presumed to be a result of aseismic 77 slip propagation (e.g., Lohman & McGuire, 2007; Roland & McGuire, 2009). The 78 spatiotemporal distribution of earthquake hypocenters can be more precisely estimated than other 79 seismological characteristics such as the three-dimensional seismic velocity structure. By 80 examining relocated hypocenters, we may extract information on aseismic physical processes 81 controlling earthquakes, which is crucial to understanding the earthquake generation. The results 82 of previous studies showed that the seismic activity caused by aseismic processes differs from 83 that of the mainshock-aftershock sequence (e.g., Hainzl & Ogata, 2005; Roland & McGuire, 84 85 2009; Kumazawa & Ogata, 2013; Yoshida & Hasegawa, 2018b). This suggests that

investigations of the seismicity may provide clues about aseismic processes governingearthquakes.

The volcanic front on Kyushu Island in southern Japan formed due to the subduction of the 88 Philippine Sea Plate. Several of the most active volcanoes in Japan are distributed along this 89 volcanic front (e.g., Sakurajima and Aso). Kagoshima Bay is located at this volcanic front (Fig. 90 S1), which is characterized by a low-gravity anomaly that extends from north to south. On July 91 11, 2017, an M<sub>L</sub> 5.3 strike-slip earthquake occurred at a depth of ~10 km in Kagoshima Bay (Fig. 92 1). Seismicity activity had been recorded near the mainshock hypocenter since December 2016 93 (Fig. 1c). In total, 1.843 foreshock events were recorded and listed in the Japan Meteorological 94 Agency (JMA) unified seismic catalogue. The seismicity increased after the mainshock; 12.595 95 events are listed in the JMA catalogue. Based on the focal mechanisms of earthquakes in this 96 region, these events were of strike-slip type with a NW-SE P-axis (Fig. 1b). Only a small 97 coseismic step was detected by the national GNSS (Global Navigation Satellite System) network 98 (Fig. S2). Based on the spatiotemporal variation in the b-value and the migration of the 99 hypocenters, Nanjo et al. (2018) suggested that fluid movement caused the earthquake sequence 100 in Kagoshima Bay, but the detailed physical process controlling this foreshock-mainshock-101 aftershock sequence remains unclear. 102

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Figure 1. (a) Map showing southern Kyushu. Inverted triangles indicate the seismic stations. We 106 used arrival time data obtained at both blue and green stations. We analyzed waveform data 107 recorded at the green stations. The black square shows the study area. (b) Hypocenter 108 distribution of earthquakes that occurred in Kagoshima Bay from January 1, 2003, to April 8, 109 110 2018, and their focal mechanisms. The hypocenters and focal mechanisms were extracted from the JMA unified catalog. The red square is defined as "the area surrounding the mainshock 111 hypocenter" in this study. The numbers above the focal mechanisms indicate the JMA magnitude 112 of each earthquake. (c) M–T diagram and cumulative number of  $M_{JMA} \ge 1.0$  earthquakes that 113 occurred in the area surrounding the mainshock hypocenter (i.e., red square in Fig. 1b) prior to 114

the mainshock. The vertical red line denotes the mainshock. (d) Aftershock occurrence rate of events with a magnitude  $M_{JMA} \ge 1.0$  (blue) and corresponding M–T diagram (gray). The inset shows the correlation between the aftershock occurrence rate and time on a log-log scale. The occurrence rate was estimated by calculating the reciprocal of the time during which 10 events with  $M_{JMA} \ge 1.0$  occurred.

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In this study, we examined the physical processes that controlled the  $M_L$  5.3 Kagoshima 121 Bay earthquake sequence in Kyushu, southern Japan. First, we determined the hypocenters and 122 focal mechanisms of this earthquake sequence and delineated the fault structure. We also 123 estimated the size of the mainshock and examined its relationship with the fore- and aftershocks 124 to obtain a comprehensive view of this foreshock-mainshock-aftershock sequence. We then 125 examined the spatiotemporal characteristics of the intense fore- and aftershocks to extract 126 information about the aseismic phenomena governing this earthquake sequence. Finally, by 127 integrating the observations, we established a model that can be used to explain the occurrence 128 and characteristics of the foreshock-mainshock-aftershock sequence associated with the 2017 129 M5.3 Kagoshima Bay earthquake. 130

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#### 132 2 Methods

#### 133 2.1 Hypocenter relocations

We relocated 21.102 events listed in the JMA unified catalogue for the southern Kagoshima Bay 134 region for the period from March 1, 2003 to April 8, 2018 using the Double-Difference (DD) 135 method (Waldhauser & Ellsworth, 2000). This relative relocation method minimizes the residuals 136 between the observed and theoretical travel time differences for adjacent earthquake pairs at each 137 station. We applied the DD method to differential arrival time data, which were estimated from 138 the waveform cross-correlation, and those listed in the JMA unified catalog. The procedure was 139 identical to that reported in Yoshida and Hasegawa (2018a, b), which can be briefly described as 140 follows. 141

First, we obtained precise differential arrival time data using waveform cross-correlations. 142 We used the waveform data observed at 20 permanent seismic stations surrounding the focal area 143 (Fig. 1a; green stations). At each station, the ground velocity was measured using three-144 component short-period seismometers (natural period of 1s) and a sampling rate of 100 Hz. We 145 applied a 5-12 Hz Butterworth filter to the waveforms of each target event. We used 2.8 and 4.3 146 s time windows for the P- and S-waves, respectively, starting 0.3 s before their arrival. The 147 arrival times were obtained from the JMA unified catalogue. If arrival times were not available, 148 they were estimated using the one-dimensional JMA2001 velocity model (Ueno et al., 2002) and 149 the hypocenters, and origin times listed in the JMA unified catalogue. We calculated the 150 waveform cross-correlations of event pairs with hypocenters within 3 km from each other and 151 obtained differential arrival times when the cross-correlation coefficients were greater than 0.8. 152 In total, we acquired 17.332.318 P-wave differential arrival time data points and 27.738.043 S-153 154 wave data points. We also derived the differential arrival data from the arrival time data listed in

the JMA unified catalog: 474.670 data for P-waves and 543.226 data for S-waves. For the
mainshock, only data derived from the JMA unified catalog were used because of its long
duration.

Second, we applied the hypo-DD algorithm (Waldhauser & Ellsworth, 2000) to the 158 differential arrival time data. We used a spherical shell two-layer model (Aki, 1965) for the 159 hypocenter relocation. In this model, the seismic velocities in each layer are proportional to the 160 power of the distance from the center of the Earth (Figure S3). The medium parameters were 161 determined for consistency with the seismic tomography results obtained in the Kyushu region 162 (Saiga et al., 2010). We used the hypocenters listed in the JMA unified catalogue for the initial 163 locations for the relocation. Figures 2a and 3a show the distribution of these initial hypocenters. 164 Differential arrival time data were weighted with respect to the square root of the cross-165 correlation coefficient. The hypocenters were updated after 50 iterations of the relocation 166 procedure. During the first ten iterations, a higher weight was assigned to the catalogue data to 167 constrain the relative locations of large-scale features. In the latter 40 iterations, a higher weight 168 was assigned to the data derived by the cross-correlations to delineate shorter-scale features. We 169 evaluated the uncertainty in the relative hypocenter locations by recalculating the hypocenters 170 200 times based on bootstrap resampling of differential arrival time data. 171

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Figure 2. Maps showing the distribution of the (a) initial hypocenters listed in the JMA unified
catalog and (b) relocated hypocenters based on the DD method. Blue dots indicate the locations
of the hypocenters. The red lines labeled A to I indicate the locations of the vertical sections
shown in Figure 3.



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Figure 3. Cross-sectional views showing the distribution of the (a) initial hypocenters listed in the JMA unified catalog and (b) relocated hypocenters based on the DD method. Blue dots indicate the locations of the hypocenters. The nine figures (A–I) represent the cross-sectional views along the vertical sections indicated by the red lines in Fig. 2.
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#### 189 **2.2 Estimation of focal mechanisms**

We estimated the focal mechanisms based on the amplitude ratios of the waveforms using the 190 method of Yoshida et al. (2019b), which is similar to that of Dahm (1996). We used six focal 191 mechanisms determined by the JMA (Fig. 1b) to represent effects of the path and site on the 192 waveform. We determined the focal mechanisms of 161 earthquakes with  $M_L \ge 2$ . We used 193 displacement waveforms obtained by integrating the velocity waveforms recorded at the 20 194 stations (green triangles in Fig. 1a) surrounding the hypocenters. The vertical component was 195 used for the analysis of the P-wave, whereas radial and transverse components were used for that 196 of the S-wave. We applied a 2–5 Hz bandpass filter to the waveforms, cutting them out with time 197 windows of 2.8 s for P-waves and 4.3 s for S-waves starting 0.3 s before their arrival. 198 We used waveform cross-correlations to measure the amplitude ratios between target and 199 reference events. The amplitude ratios were obtained for pairs with absolute correlation 200 coefficients above 0.75. We used principal component analysis (PCA) to measure the amplitude 201 ratios. 202

We only estimated the mechanism solutions when amplitude ratios were obtained for more than 20 channels. We eliminated the results when the Variance Reduction (VR) was below 80:

$$VR = \left(1 - \frac{\sum_{k=1}^{n} (d_k - s_k)^2}{\sum_{k=1}^{n} d_k^2}\right) \cdot 100, \qquad (1)$$

where  $d_k$  and  $s_k$  are the observed and calculated displacement amplitude ratios, respectively, at channel *k*.

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#### 2.3 Estimation of the size of the mainshock source 209

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We estimated the size of the mainshock source based on the circular crack source model (e.g., 210 Sato & Hirasawa, 1973; Madariaga, 1976). In this source model, the source radius is related to 211 the S-wave corner frequency,  $f_c$ , as follows: 212

$$r = \frac{k\beta}{f_c},\tag{2}$$

where r is the source radius, k is a constant, and  $\beta$  is the S-wave velocity close to the source. 214 Based on a rupture velocity of  $0.9\beta$ , k is 0.44 in the model of Sato and Hirasawa (1973) and 0.32 215 in the model of Madariaga (1976) for P-waves (Kaneko & Shearer, 2014). Because the estimated 216 source size depends on the source model, we computed the fault size using both models. We 217 assumed a  $\beta$  value of 3.4 km/s. 218

We used the spectral ratio method (e.g., Imanishi & Ellsworth, 2006) to estimate the corner 219 220 frequency of the mainshock. In this method, effects of the propagation and location on the seismic wave are empirically removed using the waveforms of an adjacent small earthquake 221 (empirical Green's function, EGF, event). Based on the assumption that the source spectrum, that 222 is,  $S_i(f)$ , follows the  $\omega^2$  model (Aki, 1967; Brune, 1970), the theoretical ratio between the 223 velocity spectra of the mainshock,  $v_i(f)$ , and the EGF event,  $v_i^{egf}(f)$ , at station *i* can be calculated 224 as follows: 225

226 
$$SSR_{ij}(f) = \frac{v_i(f)}{v_i^{egf}(f)} = \frac{M_0}{M_0^{egf}} \frac{R_{\theta\varphi i}}{R_{\theta\varphi i}^{egf}} \frac{1 + \left(\frac{f}{f_c^{egf}}\right)^2}{1 + \left(\frac{f}{f_c}\right)^2},$$
(3)

where  $M_0$  and  $M_0^{egf}$  are the seismic moments of the target earthquake and EGF event, 227 respectively;  $R_{\theta\phi ij}$  and  $R_{\theta\phi i}^{egf}$  are their radiation patterns at station*i*, respectively; and  $f_c^{egf}$  is the 228

- 51
- 52

229	corner frequency of the EGF event. Based on Eq. (3), $f_c$ can be estimated from the spectral
230	ratios.
231	We calculated the spectral ratios by using P-wave velocity waveforms observed at the 20
232	stations surrounding the source area (green inverted triangles in Fig. 1b). The EGF events were
233	earthquakes with $M \ge 2$ and a distance from the mainshock below 1.0 km based on the relocated
234	hypocenters. The following procedure was performed (Yoshida et al., 2017):
235	(1) For the target mainshock and EGF events, the waveforms of the three components were
236	extracted from a 2.0 s time window starting 0.3 s before the arrival of the P-wave at each
237	station. The multitaper method (Thomson, 1982; Prieto et al., 2009) was applied to
238	calculate the spectra.
239	
240	(2) For channels with EGF observation spectra with a signal-to-noise ratio $> 4$ at all
241	frequencies from 0.5 to 30.0 Hz, the spectral ratio between the mainshock and EGF event
242	was calculated. We used waveforms up to 0.3 s before the arrival of the P-waves for the
243	noise window.
244	
245	(3) We calculated the geometric mean of the spectral ratios $GSR(f)$ of all channels at each
246	frequency for the EGF events, which satisfied the above-mentioned criterion at five or
247	more stations:
248	$GSR(f) = \prod_{i=1}^{N} \left( SR_i(f) \right)^{\frac{1}{N}}, \tag{4}$
249	where $SR_i(f)$ is the observed spectral ratio obtained at station <i>i</i> and <i>N</i> is the number of
250	stations.

- 56

(4) By using the grid search and minimizing the evaluation function J, the corner

frequencies of the mainshock,  $f_c$ , and EGF event,  $f_c^{egf}$ , were determined:

$$J = \sum_{k=1}^{n_{freq}} \left| \log \left( GSR(f_k) \right) - A \log \left( NSR(f_k; f_c, f_c^{egf}) \right) \right|, \tag{5}$$

where 
$$NSR(f; f_c, f_c^{egf}) = \frac{1 + (f/f_c^{egf})^2}{1 + (f/f_c)^2}$$
,  $n_{freq}$  is the number of frequencies, and  $f_k$  is frequency

(at 0.5 Hz intervals from 0.5 to 30 Hz). The grid search was performed for  $f_c$  and  $f_c^{egf}$  by assuming a range from 0.1 to 100 Hz at 0.1 Hz steps. The amplitude ratio, *A*, was estimated using the least squares method for each grid search step.

259

We applied the spectral ratio method to 33 EGF candidates. We obtained spectral ratios for 13 EGF events, which satisfy our S/N ratio and data criteria. Figure S4 shows the spectral ratios of the 13 EGF events.

263

### 264 **2.4 Detection of aseismic processes from seismicity**

The Epidemic Type Aftershock Sequence (ETAS) model (Ogata, 1988), which is based on the superposition of the modified Omori law (Ustu, 1961), can be used to explain mainshock– aftershock seismicity. The ETAS model assumes that the seismicity rate is the sum of the background rate of independent events,  $\lambda_0$ , and aftershocks triggered by each event,  $\lambda_i(t)$ :

$$\lambda(t) = \lambda_0 + \sum_{i:t_i < t} \lambda_i(t).$$
(6)

Based on the modified Omori law, each earthquake can trigger its own aftershock sequence(Utsu et al., 1995):

272 
$$\Lambda_i(t) = \frac{K_0}{\left(c + t - t_i\right)^p} e^{\alpha (M_i - M_{min})}, \qquad (7)$$

where  $t_i$  is the occurrence time;  $M_i$  is the magnitude of each event, *i*, that occurred prior to time *t* ;  $M_{min}$  is the magnitude of completeness of the earthquake catalogue;  $K_0$ , *c*, and *p* are constants; and *t* is the time that has elapsed since the main event.

276 We applied the ETAS model to the seismicity observed after the mainshock in Kagoshima Bay and investigated the difference between the simulated and observed seismicity. The results 277 show that the foreshock activity cannot be explained by the ETAS model, likely because 278 aseismic processes mainly controlled the foreshock activity. We used the timings and magnitudes 279 of the earthquakes listed in the JMA catalogue. The lower limit of the magnitude, M<sub>c</sub>, was set to 280 1.0. Figure S4 shows the magnitude-frequency distribution. The distribution follows the 281 Gutenberg–Richter law (Gutenberg & Richter, 1944) when  $M_{JMA} \ge 1.0$ . The SASeis2006 282 algorithm by Ogata (2006) was used to estimate the model parameters and calculate the residuals 283

of the ETAS model.

285

#### 286 **3 Results**

#### 287 3.1 Fault structure and seismic gap

We obtained the relocated hypocenters of 20.347 events and the focal mechanisms of 61 events. Almost all events in the Kagoshima Bay earthquake sequence can be accurately relocated with the DD algorithm. The location data for 755 earthquakes were removed because their hypocenters were located above the ground surface or they contained outliers in the differential arrival time data. We computed the differences between the maximum and minimum values in the 95% confidence interval of the hypocenter locations (Fig. S6) estimated from the bootstrap resampling and obtained the medians as a measure of the estimation error of the relative location:
0.0013 ° in longitude, 0.0011° in latitude, and 0.42 km in depth.

Figures 2b and 3b show the distribution of the relocated hypocenters. Movie 1 shows the 296 animation of the cross-sectional views of the hypocenters along various lines. Most hypocenters 297 are located within ~5 km from the mainshock hypocenter and are distributed along several 298 planes. These characteristics are in contrast to the distribution of the initial hypocenters (Figs 2a 299 and 3a), which were scattered three-dimensionally, similar to a cloud. This significant change in 300 the hypocenter distribution is due to the improvements of the relative locations of the 301 hypocenters in this study based on the use of many accurate differential arrival time data. Similar 302 improvements of the relative hypocenters, from cloud-like distribution to planar structures, were 303 previously reported for shallow earthquakes in Japan based on a similar method and data (e.g., 304 Yoshida & Hasegawa, 2018a, b). The cloud-like distribution of the initial hypocenters reflects the 305 errors in the hypocenter locations in the JMA unified catalog, which are due to errors in the 306 manual selection. 307

Figure 4 shows the spatial distribution of the focal mechanisms. Because the reference focal mechanisms are in the northern part of the source region (Fig. 1b), newly estimated focal mechanisms are mainly located in the northern part. The figure shows that the nodal planes of most focal mechanisms are parallel to the planar structures of the hypocenters, suggesting that individual small earthquakes occurred on several macroscopic planes.

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Figure 4. Estimated focal mechanisms plotted on the hypocenter distribution. The left figure is a map view and the nine figures (A–I) on the right are cross-sectional views along vertical sections indicated by the red lines in the left figure.

Based on Figs 2b, 3b and 4, the fault structures of the 2017 Kagoshima Bay earthquake sequence are complex, consisting of several subparallel planes. However, the distribution of the hypocenters was relatively simple before the mainshock. Figure 5 shows an enlarged view of the spatial distribution of the hypocenters of the foreshocks (red dots). Most hypocenters are evenly distributed in one plane, with a strike parallel to those of the nodal planes of the focal mechanisms of the mainshock and individual small earthquakes, suggesting that the mainshock and most of the foreshocks occurred on this plane.



Figure 5. Hypocenter distribution of the foreshocks. Red and blue circles represent the hypocenters of foreshocks and aftershocks, respectively, Blue circles represent the hypocenters of the precursory activity. (a) Map showing the hypocenters of the precursor activity and aftershocks. (b) Map showing only the hypocenters of the precursory activity. The broken ellipse indicates the location of the seismic gap. (c) Cross-sectional views along vertical sections A to I shown in (a). The yellow star indicates the hypocenter location of the mainshock.

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The hypocenters of the foreshocks are not uniformly distributed in the plane, but they are distributed in form of a doughnut, that is, a seismic gap forms in the center of the plane (broken ellipse in Fig. 5b). To demonstrate this distribution, we estimated the lateral distribution of the

moment release on the fault (Fig. 6a) during the foreshock sequence following Yoshida et al. 341 (2020a). We computed the seismic moment release of each earthquake by assuming that its 342 magnitude is equal to the moment magnitude. Subsequently, we summed the moment release 343 values of the points that were evenly spaced every 0.04 km by using the earthquakes within the 344 nearest grid cell. The result shown in Fig. 6b indicates that the moment release of the foreshock 345 sequence is smaller ( $(10^{11} Nm)$ ) in the region corresponding to the seismic gap than in the 346 surrounding region (i, 10<sup>11</sup> Nm). The hypocenter of the mainshock is located at the edge of this 347 seismic gap. Figure 5 shows a comparison of the hypocenters of the foreshocks and aftershocks. 348 Although aftershocks occur inside the seismic gap based on the map (Fig. 5a), they actually 349 occur in shallower areas than the foreshocks (Fig. 5c), that is, not within the seismic gap of the 350 foreshocks. 351

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Figure 6. Seismic gap of earthquakes in the foreshock period projected on the dominant plane.(a) Comparison of the size of the seismic gap with the estimated sizes of the faults associated

with the mainshock. Blue circles indicate the hypocenters of the precursory activity
corresponding to the fault sizes by assuming stress drops of 10 MPa. The yellow star indicates
the location of the mainshock hypocenter. The red circle represents the size of the fault
corresponding to the mainshock estimated based on the model of Sato and Hirasawa (1973). The
green circle represents the size of the fault corresponding to the mainshock estimated based on
the model of Madariaga (1976). (b) Moment release amount (color scale) computed for each
0.04 km grid cell. The broken ellipse represents the seismic gap.

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The median value of the estimated corner frequencies of the mainshock is 1.9 Hz (Fig. S4). The first and third quartiles are 1.8 and 2.5 Hz, respectively. Based on the median corner frequency and the models proposed by Sato and Hirasawa (1973) and Madariaga (1976), the source radius of the mainshock is 787 and 572 m, respectively. It is much smaller than the foreshock and aftershock regions but comparable to the seismic gap (Fig. 6a).

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#### 372 **3.2 Foreshock and aftershock migration**

Figures 7a–c show the occurrences of the foreshocks on a color scale. In Figs 8a–c, the occurrence of each earthquake is compared with the longitude, latitude, and depth, respectively, to illustrate their migration behavior. In the longitudinal direction (Fig. 8a), the hypocenters expand nearly symmetrically in the first 230 days of foreshock activity and concentrate in the east close to the hypocenter of the mainshock during the last ~70 days. In the latitudinal direction (Fig. 8b), the hypocenters migrate from north to south. In the depth direction (Fig. 8c), the hypocenters migrate both in the shallow and deep directions, indicating that most earthquakes

## occurred in the deeper part surrounding the mainshock hypocenter during the last $\sim$ 70 days of



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Figure 7. Spatiotemporal evolution of the hypocenters (a)–(c) before and (d)–(f) after the mainshock. (a) Projection of the hypocenters, (d) map view, (b) and (e) east–west cross section, and (c) and (f) north–south cross section. The symbol sizes corresponds to the JMA magnitude. The hypocenters are colored according to their occurrence time measured relative to that of the mainshock, that is, the mainshock occurred at time 0 and negative and positive numbers denote the days before and after the mainshock, respectively.

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Figure 8. Temporal evolution of hypocenters in the (a) latitude, (b) longitude, and (c) depth directions. (d) Temporal evolution of the aftershock hypocenters in the depth direction. The red crosses and yellow curve in (d) indicate the depth above which the shallowest 10% of the hypocenters are located (D10) for every bin with 400 events based on the occurrence time. The circle size corresponds to the JMA magnitude. The yellow star indicates the hypocenter of the mainshock.

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Figures 7d–f show the distribution of aftershock hypocenters colored based on the 402 occurrence time of each event. Figure 8d shows the temporal evolution of the aftershock 403 hypocenters as a function of the depth. The temporal evolution of the aftershock hypocenters in 404 both the latitudinal and longitudinal directions is shown in Fig. S7. Because the spatial 405 distribution of the aftershocks is complex, the spatiotemporal features of the aftershocks are 406 more difficult to determine than those of the foreshocks. Overall, the aftershock hypocenters 407 move upward with time, as shown in Fig. 8d, which depicts the depths above which the 408 shallowest 10% of the hypocenters are located (D10) for each bin containing 400 events, as 409 denoted by the red curve. Although earthquakes occur in a relatively deep region immediately 410 after the mainshock, the upper limit of the seismic depth (D10) gradually moves in the shallow 411 direction, that is, the hypocenters gradually move to the shallower part with time after the 412 mainshock. 413

414

#### 415 **3.3 Deviation of the seismicity from Omori's law**

416 We investigated the seismicity rate of the Kagoshima Bay earthquake sequence after the

417 mainshock. Figure 1d shows the seismicity rates of the  $M_{JMA} \ge 1.0$  events in the area surrounding

the hypocenter of the mainshock (red frame in Fig. 1b). The seismic rate was obtained by 418 calculating the reciprocal of the time required to generate ten earthquakes that were arranged in 419 chronological order. Based on Fig. 1d, the seismicity rate decreases by the power of the elapsed 420 time immediately after the mainshock, as described by the modified Omori law (Utsu, 1961). 421 The seismicity rate abruptly increases ~44 days after the mainshock, which corresponds to the 422 occurrence of the largest aftershock (M<sub>L</sub>4.4), suggesting that the increase is due to secondary 423 aftershocks. A period with a high seismicity rate started approximately 20 to 40 days after the 424 mainshock; the seismic activity was temporarily strong despite the absence of large aftershocks. 425 Based on maximum likelihood estimation, we obtained the following parameters for the 426 ETAS model:  $K_0 = 34.205$ ,  $c = 1.3163 \times 10^{-2}$ , p = 1.0685,  $\alpha = 1.5078$ , and  $\mu = 2.9603 \times 10^{-2}$ . 427 Based on Ogata (1992), the range of  $\alpha$ -values is 0.35–0.85 for swarm seismicity and 1.2–3.1 for 428 non-swarm seismicity. The  $\alpha$  value estimated for the seismic activity in Kagoshima Bay is within 429 the latter range. 430

In Fig. 9, the cumulative number of earthquakes simulated using the estimated model 431 parameters is compared with the observations. Overall, the number predicted based on the ETAS 432 model matches the observations. However, the simulated number of earthquakes is lower than 433 the observed number 20-40 days after the mainshock. To quantitatively examine the magnitude 434 of the discrepancy between the model and observations, we performed residual analysis using the 435 transformed time, similar to Ogata (1988). Figure 9c shows that the discrepancy between the 436 model and observations is high at a transformed time between 1.000 and 1.500, corresponding to 437 the period of 20-40 days after the mainshock. This deviation is significant at the 95% 438 significance level based on the assumption of a uniform distribution. 439

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Figure 9. (a) M–T diagram. (b) Observed cumulative number of aftershocks with  $M_L \ge 1.0$  (red solid line) and predicted number based on the estimated ETAS parameters (blue solid line). Each curve represents the cumulative numbers starting 0.1 days after the mainshock. (c) Results of the residual analysis, where the blue solid line shows the observed events with respect to the transformed time on the horizontal axis and cumulative number of observed  $M_L \ge 1.0$ earthquakes on the vertical axis. The black dotted line represents the transformed time at which

the assumed model fully matches the observation. The red solid and red broken lines indicate the
two-sided 95% and 99% error bounds of the Kolmogorov–Smirnov statistic, respectively. The
gray zone in (c) shows the range of the transformed time corresponding to the period of 20–44
days after the mainshock highlighted in gray in (b).

452

The large discrepancy between the predicted and observed seismicity rates 20-40 days 453  $(\sim 1.000-1.500 \text{ in Fig. 9c})$  after the mainshock can be explained by a temporary increase in the 454 background seismicity, which was assumed to be constant over the entire period of this analysis 455 in the model. The transient increase in the background seismicity rate suggests that the 456 Kagoshima Bay earthquake sequence may have been affected by physical processes other than 457 earthquake-to-earthquake interactions, especially during this period (20-40 days) and that an 458 aseismic process may have led to the largest aftershock ( $M_1$  4.4) that occurred 44 days after the 459 mainshock. Contrarily, most aftershocks can be explained as general mainshock–aftershock 460 seismic activity, suggesting that stress changes caused by the mainshock resulted in numerous 461 aftershocks. 462

#### 464 **4 Discussion**

Our results show that: (1) the foreshocks of the 2017 M5.3 Kagoshima Bay earthquake sequence 465 occurred on a single plane with a steep dip to the east, whereas aftershocks occurred on several 466 more complex planar structures, (2) the foreshock hypocenters formed a seismic gap, and (3) the 467 foreshock and aftershock hypocenters exhibit clear migration behaviors. In this section, we 468 integrated these observations and propose a simple model that can explain the occurrence of the 469 foreshock-mainshock-aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake based 470 on the upward fluid movement, which is similar to the fault-valve model proposed by Sibson 471 (1992). 472

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#### 474 **4.1 Migration of foreshock activity along a plane**

The clear hypocenter migration observed for the foreshock sequence suggests that aseismic 475 physical processes controlled this sequence. In fact, the seismicity rate of the foreshock sequence 476 could not be reproduced by the ETAS model, suggesting that the earthquake-to-earthquake 477 interaction cannot explain this sequence. Thus, the foreshock sequence must be understood as 478 temporary increase in the background seismicity rate, similar to that of the earthquake swarm. 479 In Fig. 10, the distances of the foreshock hypocenters from the mean location of the first 480 three events are plotted against time. The expansion front of the pore pressure diffusion model 481 reported in Shapiro et al. (1997) is also shown, which can be expressed by the following equation 482 including various diffusion coefficients  $D_h$ : 483

$$\begin{array}{cc} r = \sqrt{4 \pi D_h t} \\ (9) \end{array}$$

where r is the distance from the point pressure source and t is the time. In this study, we set the initiation time to 220 days before the mainshock because the seismicity rate significantly





Figure 10. Temporal evolution of the distances between the foreshocks and initial hypocenter. Blue circles represent the hypocenters expressed by the size corresponding to the JMA magnitude. The black curves show the fluid diffusion models with  $D_h = 0.01, 0.03$ , and 0.05 m<sup>2</sup>/s. Gray straight lines show the linear spread model with migration speeds of d = 0.001, 0.003, and 0.005 km/h.

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The pore pressure diffusion model with a hydraulic diffusion coefficient of  $\sim 0.05 \text{ m}^2/\text{s}$ matches the observations better than the linear spread model. In previous studies, it has been

estimated that the hydraulic diffusion coefficient in the crust ranges from  $\sim 0.01-10 \text{ m}^2/\text{s}$  (e.g., 500 Talwani et al., 2007; Shelly et al., 2016; Yoshida & Hasegawa, 2018a), which is similar to the 501 foreshock migration speed of the M5.3 Kagoshima Bay earthquake sequence. Based on the linear 502 spread model, the propagation velocity is ~0.001–0.005 km/h. Based on previous studies, the 503 migration speed of aseismic slip propagation ranges from 0.1–1.0 km/h (e.g., Lohman & 504 McGuire, 2007; Kato et al., 2016), which is significantly higher than the migration speed of the 505 present foreshock activity. If we advance the initiation timing of propagation, the propagation 506 speed decreases. Thus, according to the migration speed and spatiotemporal pattern of the 507 foreshocks, the pore pressure diffusion model better explains the overall migration of the 508 foreshock hypocenters. 509

Aseismic creep related to the nucleation process of the mainshock might be involved in 510 the migration of the foreshocks. In fact, physical simulations indicate interseismic creep in 511 seismogenic patches from external stable-slip regions before the occurrence of unstable slip (Tse 512 & Rice, 1986). Such an expansion of quasi-static slip prior to the mainshock may explain the 513 current migration of the foreshocks (e.g., Dodge et al., 1996; Yabe & Ide, 2018). However, the 514 source of the mainshock is smaller than the foreshock area (Fig. 6a), which contradicts the 515 hypothesis because the mainshock rupture zone should include the nucleation area. Note that the 516 size of the source of the mainshock was estimated based on source models assuming a constant 517 rupture velocity (subshear rupture propagation). If the assumptions differ from reality (e.g., 518 supershear rupture propagation), the source size may differ from our estimation, explaining this 519 contradiction. However, the aftershocks migrate upward on multiple planes (Fig. 8d), which can 520 be explained with the foreshock sequence if the pore pressure migration model is adopted. Thus, 521 522 we prefer the hypothesis that pore pressure migration is primarily responsible for the generation

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of the 2017 M5.3 Kagoshima Bay earthquake sequence. The heterogeneity in the permeability
and/or pore pressure along the fault may explain the up- and downward movement of the
hypocenter along the plane (Fig. 8c).

However, recent observations of fluid injection-induced seismicity and natural earthquake 526 swarms suggest that an increase in the pore pressure can cause aseismic slip (Cornet et al., 1997; 527 Guglielmi et al., 2015; Ruhl et al., 2016; Yoshida & Hasegawa, 2018a; De Barros et al., 2020). In 528 the presence of fluids, the effective normal stress decreases and the critical nucleation size 529 increases; thus, the occurrence of aseismic slip is likely (e.g., Scholz, 1998). The increase in the 530 pore pressure also accelerates creep in the stable-slip segment of the fault. Both aseismic slip and 531 fluid movement may have contributed to the occurrence of foreshocks. Furthermore, the 532 poroelastic effects associated with pore pressure migration (Segall, 1989; Goebel et al., 2018) 533 and the earthquake-to-earthquake interaction (Helmstetter, 2002) may contribute to the 534 occurrence of earthquakes. 535

536

# 4.2 Seismic gap of the foreshock and aftershock sequence in the mainshock fault plane The doughnut-like pattern of the foreshocks (Fig. 6) is similar to the "Mogi doughnut" (Mogi,

1969). It has been reported that aftershocks do not occur in the mainshock region (e.g., Mendoza & Hartzell, 1988; Das & Henry, 2003; Woessner et al., 2006; Asano et al., 2011; Ebel &
Chambers, 2016; Yoshida et al., 2016b and 2020a; Ross, 2017b, 2018; Wetzler et al., 2018),
which is likely because the shear stress was released during the mainshock. In Figure 6a, the size of the seismic gap is compared with the estimated size of the fault related to the mainshock.
Because the centroid location of the mainshock was not determined, we assumed the centroid is located by a few hundred meters into the shallower region such that the mainshock centroid is

located in the center of the seismic gap shown in the figure. The fault size of the mainshock is similar to that of the seismic gap. This is consistent with the hypothesis that the mainshock rupture occurred in the seismic gap of the foreshock and aftershock activities. A similar spatial separation of the mainshock and fore- and aftershocks in the rupture area was also reported for a recent M5.2 intraplate earthquake that occurred in Akita, NE Japan (Yoshida et al., 2020).

The seismic gap in the foreshock activity may originate from the spatial heterogeneities in 551 552 the frictional and material properties along the fault plane. The fault strength of the mainshock rupture area may have been higher than that of the surrounding area, as proposed in the asperity 553 554 model of Lay & Kanamori (1981). Foreshocks can be understood as failures of small seismogenic patches in the surrounding stable area. Alternatively, the area may have been 555 covered by an impermeable medium, hindering fluid intrusion. The occurrences of foreshocks 556 and aseismic slip increased the shear stress in the future source region of the mainshock rupture. 557 The mainshock occurred in this region due to the gradually increasing pore pressure and shear 558 stress. 559

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#### 561 **4.3 Upward migration of the aftershocks along several planes**

The aftershock sequence of the Kagoshima Bay earthquake sequence follows Omori's law (Fig. 1d), suggesting that this sequence was triggered by the M5.3 mainshock. However, the aftershock sequence slightly deviates from the prediction based on the ETAS model (Figs 9b–c). The transient increase in the background seismicity rate suggests that the Kagoshima Bay earthquake sequence may have been affected by physical processes other than earthquake-toearthquake interactions, especially during this period (20 to 40 days) and that these aseismic processes may have led to the largest aftershock (M<sub>L</sub> 4.4) that occurred 44 days after the

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mainshock. Based on the model simulations of fluid injection-induced seismicity, Hainzl and
Ogata (2005) pointed out that the background seismicity rate of the ETAS model is sensitive to
the amount of injected water. In previous studies, similar observations were made for fluid
injection-induced seismicity and natural earthquake sequences (Llenos & Michael, 2013;

573 Yoshida & Hasegawa, 2018b; Kumazawa et al., 2019).

Our results indicate that the aftershock hypocenters migrated toward the shallower portion 574 on multiple planes. Such upward movements of hypocenters have been previously reported for 575 earthquake swarms following nearby large earthquakes and it has been concluded that they 576 reflect the upward pore pressure migration associated with the fault-valve behavior (Shelly et al., 577 2015; Ruhl et al., 2016; Yoshida & Hasegawa, 2018a, b). Examples are the earthquake swarms 578 that occurred in northeastern Japan following the 2011 Tohoku-Oki earthquake (Yoshida et al., 579 2016a; Yoshida & Hasegawa, 2018a, b). The earthquake swarms might originate from the pore 580 pressure increase because (1) they occurred in the stress shadow of the 2011 Tohoku-Oki 581 earthquake with a time delay of a few weeks despite the reduction in the shear stress, (2) they are 582 located beneath the caldera structures that are believed to host shallow igneous bodies, with 583 hydrothermal fluids immediately below, (3) they are located a few kilometers above S-wave 584 reflectors and the low-velocity zone including fluids, and (4) their hypocenters migrate upward 585 (Yoshida & Hasegawa, 2018a; Yoshida et al., 2019a). The Kagoshima Bay swarm was also 586 located beneath an ancient caldera and involved the upward migration of aftershocks, which can 587 be explained by an increase in the pore pressure. Fluid paths in the crust may have expanded due 588 to the deformation and shaking associated with the mainshock. Pore pressure migration may 589 explain deviations in the seismicity rate from Omori's law. These observations are consistent 590 591 with the prediction based on the fault-valve model proposed in Sibson (1992), that is, upward

fluid discharge after the mainshock. In recent geodetic studies, a porosity wave associated withthe fault-valve action was detected (Rossi et al., 2016 and 2018).

We presume that the subducting Philippine Sea Plate is the source of fluids, similar to the 594 model reported in Hasegawa et al. (2005), which is based on the geophysical and geological 595 observations in northeastern Japan. This hypothesis is supported by seismic data obtained in 596 Kyushu using tomography, which indicate that the existence of an inclined low-velocity layer 597 continuously distributed in the mantle wedge and reaching right below the volcanic front as 598 northeastern Japan (Zhao et al., 2012). The low-velocity zone is considered to represent the 599 ascending flow portion of the secondary convection within the mantle wedge and therefore 600 contains fluids from the slab and resultant melts (Hasegawa et al., 2005). The buoyancy 601 facilitated the upward migration of the fluids, as shown in simulations (e.g., Iwamori, 1998; 602 Wada et al., 2015; Horiuchi et al., 2016), and the fluids reached the source region of the 603 Kagoshima Bay sequence. 604

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### 606 4.4 Comprehensive interpretation of the seismic activity in Kagoshima Bay

Here, we summarize our simple model that comprehensively explains the observed results of the 607 foreshock-mainshock-aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake. 608 First, fluids that have infiltrated the mainshock fault plane caused the foreshock activity. 609 The hypocenter migration of the foreshock activity can be interpreted considered to be a 610 reflection of fluid movement and possibly triggered aseismic slip on the plane. Second, the 611 occurrences of foreshocks and aseismic slip increased the shear stress in the future source region 612 of the mainshock (seismic gap in Fig. 6). The mainshock finally occurred in this region due to 613 614 the gradually increasing pore pressure and shear stress. Third, the change in the stress associated

with the occurrence of the mainshock primarily triggered aftershocks in the area surrounding the
mainshock including regions outside the mainshock fault plane. Fluids started to move upward
due to the deformation and shaking associated with the mainshock. Together with the fluids, the
aftershock hypocenters moved to shallower regions. Thus, the overall sequence of the 2017 M5.3
Kagoshima Bay earthquake can be explained by consistent upward fluid movement.

#### 621 4.5 Implications to the foreshock–mainshock–aftershock sequence

The results of previous studies suggested that many earthquake swarms are caused by the 622 movements of crustal fluids (e.g., Mogi, 1989; Italiano et al., 2001; Fischer and Horálek, 2003; 623 Parotidis et al., 2003; Bianco et al., 2004; Yukutake et al., 2011; Shelly et al., 2016; Yoshida et 624 al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). The results of the present study suggest that 625 the generation mechanism of the foreshock activity is the same as that of earthquake swarms, 626 that is, a temporary increase in background seismicity rate due to increasing pore pressure and 627 aseismic slip. The whole sequence of the Kagoshima Bay seismicity can be understood as the 628 transition from swarm activity to the mainshock-aftershock sequence. 629

The 2008 Mogul earthquake swarm, Nevada, may be a similar example. This sequence 630 was also initiated by swarm activity but shifted to a mainshock-aftershock sequence after the 631 occurrence of the M4.9 mainshock. The upward migration of the earthquakes suggests that fault-632 valve behavior is involved in the occurrence of this earthquake sequence (Ruhl et al., 2016). The 633 aftershock activities of the 2014 M<sub>L</sub> 4.8, Ubaye earthquake, France (De Barros et al., 2019), and 634 the foreshock and aftershock activities of the 2017 M5.2 Akita-Daisen event can also be 635 understood as transitions from swarm activity to mainshock-aftershock sequences (Yoshida et 636 637 al., 2020b). Similarly, aseismic slip may have caused the foreshocks and mainshock of the 2011

M9 Tohoku-Oki earthquake (Kato et al., 2012); 2014 Iquique Mw 8.1 earthquake, Chile (Kato & 638 639 Nakagawa, 2014); and 2009 M6.3 L'Aquila earthquake (Borghi et al., 2016). It is likely that pore pressure migration and aseismic slip propagation occasionally coexist (Waite & Smith, 2002; 640 641 Ross et al., 2017a; Yoshida & Hasegawa, 2018; De Barros et al., 2020) and contribute to the 642 increase in the background seismicity rate. Such aseismic processes may also cause mainshockaftershock activity without notable foreshocks. The 2019 M6.7 Yamagata-Oki earthquake, NE 643 Japan, may be an example. The earthquake occurred in the stress shadow of the 2011 Tohoku-644 Oki earthquake and exhibited an upward aftershock migration (Yoshida et al., 2020b). These 645 646 observations suggest that the monitoring of aseismic processes is crucial to understanding the seismic activity. 647

#### 649 5 Conclusions

The results of previous studies suggested that many earthquake swarms have been caused 650 by the movement of crustal fluids (e.g., Mogi, 1989; Fischer and Horálek, 2003; Parotidis et al., 651 2003; Bianco et al., 2004; Yukutake et al., 2011; Chen et al., 2012; Shelly et al., 2016; Yoshida et 652 al., 2016a; Ruhl et al., 2016; De Barros et al., 2019). In the present study, the intense foreshock-653 mainshock-aftershock sequence of the 2017 M5.3 Kagoshima Bay earthquake was examined. 654 The results show that the whole sequence can be explained by upward fluid movement: (1) most 655 foreshocks were located on a single plane with a steep dip to the east and migrated along the 656 plane. This foreshock migration can be interpreted as a reflection of fluid movement and possibly 657 triggered aseismic slip on the plane; (2) The hypocenter of the mainshock was located at the edge 658 of a seismic gap with a size comparable to that of the source of the mainshock rupture. This 659 suggests that the mainshock rupture was due to the slip of this seismic gap and the seismic gap 660 was a large seismogenic patch with higher fault strength, which finally ruptured due to the 661 increase in the pore pressure and aseismic slip in the surrounding areas; and (3) Aftershocks 662 occurred on several planes with a steep dip to the east and moved from deeper to shallower 663 regions. The upward migration can be interpreted as a reflection of post-failure fluid discharge. 664 Thus, the overall sequence of the 2017 M5.3 Kagoshima Bay earthquake can be explained by 665 upward fluid movement, as presumed by the fault-valve model (Sibson, 1992). 666

The whole sequence of the Kagoshima Bay seismicity can be understood as the transition from swarm activity to a mainshock–aftershock sequence. The results of the present study suggest that the generation mechanism of the foreshock activity is the same as that of the earthquake swarms, that is, a temporary increase in the background seismicity rate due to increasing pore pressure and aseismic slip. Aseismic processes sometimes cause a large

earthquakes that is followed by numerous aftershocks; the foreshock–mainshock–aftershocksequence may such a sequence.

674

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680 <u>bulletin/index\_e.html</u>) were used. The seismograms were collected and stored by the JMA,

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