Structural controls on the hydrology of crevasses on the Greenland ice sheet

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Abstract

Surface crevasses on the Greenland Ice Sheet capture nearly half of the seasonal runoff, yet their role in transferring meltwater to the bed has received little attention compared to that of supraglacial lakes and moulins. Here, we present observations of crevasse ponding and investigate controls on their hydrological behaviour at a fast-moving, marine-terminating sector of the Greenland Ice Sheet. We map surface meltwater, crevasses, and surface-parallel stress across a ~2,700 km² region using satellite data and contemporaneous uncrewed aerial vehicle (UAV) surveys. From 2017-2019 an average of 26% of the crevassed area exhibited ponding at locations that remained persistent between years despite rapid advection rates. We find that the spatial distribution of ponded crevasses does not relate to previously proposed methods for predicting the distribution of supraglacial lakes (elevation and topography) or crevasses (von Mises stress thresholds), suggesting the operation of some other physical control(s). Ponded crevasse fields were preferentially located in regions of compressive surface-parallel mean stress, which we interpret to result from the hydraulic isolation of these systems, in contrast to unponded crevasse fields, which we suggest are able to drain into the wider supraglacial and englacial network. UAV observations show that ponded crevasses can drain episodically and rapidly, likely through hydrofracture. We therefore propose that the surface stress regime informs a spatially heterogeneous transfer of meltwater through crevasses to the bed of ice sheets, with potential consequences for processes such as subglacial drainage and the heating of ice via latent heat release by refreezing meltwater.

Controls on water storage and drainage in crevasses on the Greenland Ice Sheet

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15 Key Points:

- At a marine-terminating sector of the Greenland Ice Sheet, 26% of all crevasses ponded
 between 2017-2019; the rest remained unfilled.
- Ponded crevasse locations are persistent between years but, unlike supraglacial lakes, this distribution is not topographically controlled.
- Ponds occur under compressive stress regimes, likely due to hydraulic isolation by creep
 closure, and drain predominantly via hydrofracture.

22 Abstract

- 23 Surface crevasses on the Greenland Ice Sheet capture nearly half of the seasonal runoff, yet their
- role in transferring meltwater to the bed has received little attention compared to that of
- supraglacial lakes and moulins. Here, we present observations of crevasse ponding and
- 26 investigate controls on their hydrological behaviour at a fast-moving, marine-terminating sector
- 27 of the Greenland Ice Sheet. We map surface meltwater, crevasses, and surface-parallel stress
- across a $\sim 2,700$ km² region using satellite data and contemporaneous uncrewed aerial vehicle
- 29 (UAV) surveys. From 2017-2019 an average of 26% of the crevassed area exhibited ponding at
- 30 locations that remained persistent between years despite rapid advection rates. We find that the 31 spatial distribution of ponded crevasses does not relate to previously proposed methods for
- 31 spatial distribution of ponded crevasses does not relate to previously proposed methods for 32 predicting the distribution of supraglacial lakes (elevation and topography) or crevasses (von
- 33 Mises stress thresholds), suggesting the operation of some other physical control(s). Ponded
- 34 crevasse fields were preferentially located in regions of compressive surface-parallel mean stress,
- 35 which we interpret to result from the hydraulic isolation of these systems, in contrast to
- ³⁶ unponded crevasse fields, which we suggest are able to drain into the wider supraglacial and
- 37 englacial network. UAV observations show that ponded crevasses can drain episodically and
- rapidly, likely through hydrofracture. We therefore propose that the surface stress regime
- informs a spatially heterogeneous transfer of meltwater through crevasses to the bed of ice
- 40 sheets, with potential consequences for processes such as subglacial drainage and the heating of
- 41 ice via latent heat release by refreezing meltwater.

42 **1 Introduction**

- 43 Surface crevasses are open fractures in glaciers and ice sheets ranging in width from millimetres
- to tens of metres and in length from tens of metres to kilometres. Crevasses are a visible
- 45 expression of a glacier's surface stress regimes; the size and orientation of crevasses are intrinsic
- to glacier dynamics as they are formed by extensional flow and deformation of ice through
- 47 compression or shear (Colgan *et al.*, 2016). Studying crevasses provides insight into glacier flow
- 48 (Phillips *et al.*, 2013; Dell *et al.*, 2019) and is important for the development of fracturing criteria
- 49 for supraglacial lake drainage (Das et al., 2008; Arnold et al., 2014, Poinar and Andrews, 2021),
- 50 ice calving (Benn *et al.*, 2017; Todd *et al.*, 2019), and for quantifying the dynamic influence of
- 51 water transmitted to the bed of glaciers (McGrath *et al.*, 2011; Koziol & Arnold, 2018).
- 52 Crevasses are an important pathway for the transfer of water to the subglacial environment of
- 53 glaciers and ice sheets, while water itself can drive the propagation of crevasses via
- ⁵⁴ hydrofracture (Weertman, 1973; Alley *et al.*, 2005; van der Veen, 2007; Krawczynski *et al.*,
- 55 2009). Once full-depth hydrofracture has occurred, water flow forms an efficient route for
- 56 continued meltwater delivery to the bed in the form of moulins. Many studies of the Greenland
- 57 Ice Sheet (GrIS) have largely focussed on supraglacial lake drainage as the primary method of
- routing surface meltwater to the ice sheet bed (Banwell *et al.*, 2016; Hoffman *et al.*, 2018;
- 59 Christoffersen *et al.*, 2018). However, supraglacial lakes deliver less total meltwater volume to
- 60 the ice sheet bed than crevasse fields, which may capture as much as half of seasonal surface
- 61 runoff (McGrath *et al.*, 2011; Koziol *et al.*, 2017). The limited available studies of crevasse field 62 hydrology that exist describe variable, sometimes mutually contradictory, drainage processes.
- ⁶² hydrology that exist describe variable, sometimes mutually contradictory, drainage processes.
 63 Some studies observe discrete drainage of crevasses (Lampkin *et al.*, 2013; Cavanagh *et al.*,
- 64 2017), which appear to result from episodic full-depth hydrofracture and display parallels to
- 65 supraglacial lake drainage events. In contrast, other studies suggest crevasse fields continuously,

but inefficiently, transmit a low water flux to the subglacial system without the need for full-

depth hydrofracture (Colgan *et al.*, 2011; McGrath *et al.*, 2011). So far, no studies account for

- the full spectrum of observations and assumptions surrounding the routing of water through
- 69 crevasse fields.

70 Furthermore, in parallel to this paucity of observational studies, crevasse field hydrology has

71 predominantly been neglected in numerical models of GrIS surface hydrology (e.g. Arnold *et al.*,

72 2014; Banwell *et al.*, 2013, 2016), included in only the most recent studies (e.g. Clason *et al.*,

2015; Koziol *et al.*, 2017; Koziol & Arnold, 2018). Where crevasse hydrology is included, its
 presence is predicted using spatially homogeneous stress thresholds. The use of simple stress

- 75 thresholds to predict hydrological behaviour is common across studies of GrIS supraglacial
- hydrology (Poinar *et al.*, 2015; Clason *et al.*, 2015; Everett *et al.*, 2016; Koziol *et al.*, 2017;
- 77 Williamson, *et al.*, 2018). However, these thresholds are identified from observational studies
- performed with the purpose of identifying suitable predictors of crevasse presence, not crevasse
- ⁷⁹ hydrology (Vaughan, 1993; Hambrey & Müller, 1978; Harper et al., 1998; van der Veen, 1998) -
- and may not even be suitable for that purpose (Mottram and Benn, 2009), as ice fracture is
- 81 increasingly understood to be complex and multi-dimensional (van der Veen, 1999; Colgan *et*
- *al.*, 2016, Hubbard *et al.*, in press). To date, no observational studies exist to support the use of
- any such controls, stress or otherwise, on the hydrological behaviour of crevasses.

84 Here, we aim to use remote sensing to identify the diversity in, and controls on, the hydrological

- behaviour of crevasses on an ice sheet. We make use of large-scale, satellite-derived data to
- investigate the spatial variation of crevasse hydrological state across a \sim 2,700 km² sector of the
- GrIS between 2017 and 2019. Using this data, we identify the spatial heterogeneity in crevasse
- hydrological behaviour; the interannual variability of crevasse fields; and we test potential
- topographic and dynamic controls on such behaviour. We supplement these regional observations using repeat surveys of a \sim 7 km² sector of a fast-flowing crevasse field from an
- \sim where sector of a fast-flowing crevasse field from an uncrewed aerial vehicle (UAV). These high spatial and temporal resolution observations allow
- for the identification of filling and drainage processes occurring at the scale of individual
- crevasses, as well as the validation of satellite observations.

94 **2 Methods**

95 2.1 Study Area

96 Our study area is a \sim 3000 km² sector of the western GrIS (Figure 1), which comprises six

marine-terminating outlets extending from Sermeq Kujalleq (also known as Store Glacier;

 70.4° N 50.6°W) in the south to Perlerfup Sermia (71.0°N, -50.9°W) in the north. Within this

- 99 large-scale region of interest (hereafter the 'satellite ROI'), we used UAV surveys and Structure-
- from-Motion with Multi-View Stereo (SfM-MVS) photogrammetry to assess, at high resolution,

101 a crevasse field in the Store Glacier drainage basin, 25 km from the calving front (hereafter the

¹⁰² 'UAV ROI'). The UAV ROI is 1.5 km wide and 5 km long, and was chosen based on its

- 103 coverage of an initiating crevasse field, ranging from areas with no visible crevasses through to
- areas where crevasse width exceeds 50 m.



Figure 1. Map of study region. Small red box outlines the extent of UAV surveys. Large red box outlines the extent of satellite image analysis. Dotted line marks the extent of Figures 4 and 6. Marine-terminating outlet glaciers are labelled, with the alternative names in brackets where applicable. Background is a composite of median Sentinel-2 RGB pixel values between May-October 2018.

110 2.2 Satellite data

111 2.2.1 Crevasse classification

Crevasse identification from digital elevation models can be approached in a variety of ways 112 (Florinsky & Bliakharskii, 2019), but we use a simple method that identifies crevasses from the 113 residuals between the original and a smoothed digital elevation model (DEM). We output a 114 binary crevasse mask of the satellite ROI using ArcticDEM v3 mosaic data at 2 m resolution 115 (Porter et al., 2018), processing the data in Google Earth Engine (Figure S1; Gorelick et al., 116 2017) to allow for efficient computation over the $\sim 2,700 \text{ km}^2$ study area. We first cropped the 117 ArcticDEM to the GIMP ice mask (Howat et al., 2014), before smoothing the elevation model by 118 performing an image convolution with a circular kernel of 50 m radius. Residuals greater than 1 119 m between the smoothed and raw elevation values were identified as crevasses. To compare with 120 glaciological stress estimates, the 2 m dataset was aggregated into grid cells to match the 121 resolution (200 m) and projection (NSIDC sea ice polar stereographic north) of the MEaSUREs 122 (Making Earth System Data Records for Use in Research Environments) 2018 ice sheet surface 123 velocity grid. Aggregated values represent the fraction of grid cell area classified as crevasses. 124 When partitioning into crevassed and non-crevassed regions of the ice sheet, we define a 125

126 'crevassed' pixel as that with >1% crevasse coverage. This low threshold value was chosen to

ensure that grid cells were still classified even where crevasses were small (e.g. upstream

- crevasse fields), whilst still based upon visual inspection being sufficient to filter out grid
- cells with false positive pixels.
- 130 We also classified crevasse initiation zones by manually locating the upstream boundary between
- 131 crevasse fields and bare ice from the 2 m crevasse dataset. The flow direction was determined
- from 2018 MEaSUREs (Making Earth System Data Records for Use in Research Environments)
- velocity data and a 200 m buffer around the linear boundary was used to identify pixels in the
- 134 dataset that should be classified as being in crevasse initiation zones.

135 2.2.2 Water classification

We produced a single binary map of water presence across the satellite ROI through the 2017-136 2019 melt seasons using Sentinel-2 imagery in Google Earth Engine (Figure S2). These seasons 137 were selected based on the availability of Sentinel-2 data, with 2018 specifically selected to 138 match the timing of the UAV surveys on Store Glacier. We first identified all Sentinel-2 scenes 139 with <40% cloud cover and $<70^{\circ}$ solar zenith angle from May-October of each year. We clipped 140 the images to the GIMP ice mask (Howat et al., 2014) and converted digital number values to 141 top of atmosphere reflectance. The latter have been shown to be suitable for identifying surface 142 water in Greenland from medium-resolution optical imagery (Pope, 2016), and have been used 143 for surface water classification in Sentinel-2 data (Williamson et al., 2018a). We then calculated 144 the normalised difference water index (NDWI) from bands 2 (blue) and 4 (red) for all images. 145 Following Williamson et al. (2018a)'s parameterisation for the Store Glacier region (falling 146 147 within the satellite ROI), we used an NDWI threshold of 0.25 to create binary water classification maps for each Sentinel-2 image. In order to avoid false positive identification of 148 shaded regions, we masked areas in topographic shadow, using the ArcticDEM (resampled to 149 Sentinel-2 resolution and projection) for topography and the solar zenith angle from Sentinel-2 150 image metadata. Finally, we summed the image stack to count the number of times through the 151 2018 melt season that a pixel was identified as water. To reduce false positive classifications 152 (e.g. cloud shadow, ephemeral slush zones at the beginning of the melt season) we classify as 153 water any pixel that was identified as water in ≥ 2 images through the melt season. As for 154 crevasse maps, we aggregate this data onto the velocity grid with a unit of fractional coverage of 155 156 water within each grid cell. When partitioning the ice sheet surface into 'ponded' and 'dry' regions, we define a ponded pixel as that with >1% water coverage (following our 1% threshold 157 for crevassed pixels), and furthermore a 'lake-filled' pixel as that with >95% water coverage. 158 The latter value was selected as an appropriate classification threshold for lakes by comparing a 159 range of thresholds against the high-resolution annual water-presence maps. 160

161 2.2.3 Topographic Analysis

162 In order to explore the extent of topographic controls on crevasse surface hydrology, we

identified topographic sinks that would capture the surface flow of water by filling closed

depressions in the ice sheet surface, similar to previous studies of potential lake sites elsewhere

165 on the Greenland Ice Sheet (Ignéczi *et al.*, 2016). Before filling, the ArcticDEM data were

- resampled to the resolution and projection of the velocity data. This process removed false
- 167 depressions at high spatial scales and allowed intercomparison with other data.

168 2.2.4 Stress Analysis

169 Strain rate and stress thresholds are commonly used to predict crevasse formation and

supraglacial lake drainage from estimates of surface velocity (e.g. Poinar et al., 2015; Stevens et

al., 2015; Christoffersen *et al.*, 2018). Inferring stress from velocity-derived strain rate requires

an additional estimate or assumption of ice temperature, but allows for comparability of critical

failure thresholds between ice masses of varying temperature (Vaughan, 1993; Colgan *et al.*,

- 174 2016). We calculate simple stress thresholds previously proposed to control surface water 175 routing in lake drainage studies, and assess their applicability to crevasse ponding. Specifically,
- we estimated the stress in the first and second principal directions (as applied by Poinar *et al.*,
- 2015 and Williamson, *et al.*, 2018), as well as the von Mises yield criterion (as applied by Clason
- *et al.*, 2015; Everett *et al.*, 2016; Koziol *et al.*, 2017; and Williamson *et al.*, 2018b), using Glen's
- flow law as the constitutive equation linking ice stress and strain rate. As a proxy for whether the
- dominant stress regime is extensional or compressive, we further calculated the mean surface-
- 181 parallel stress from the first and second principal stresses.

182 Surface strain rates were derived from MEaSUREs gridded GrIS annual velocity data for 2018

(Joughin *et al.*, 2010), with extensional strain rates defined as positive. The surface strain rate

tensor $\dot{\varepsilon}_{ij}$ is calculated from the surface-parallel components of velocity, *u* and *v* (in NSIDC

185 Polar Stereographic North grid directions x and y), as

$$\dot{\epsilon}_{ij} = \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{1}{2} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \\ \frac{1}{2} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) & \frac{\partial v}{\partial y} \end{bmatrix} = \begin{bmatrix} \dot{\epsilon}_{xx} & \dot{\epsilon}_{xy} \\ \dot{\epsilon}_{xy} & \dot{\epsilon}_{yy} \end{bmatrix}_{.}$$
(1)

186

187 Derivatives were approximated using the finite difference of the MEaSUREs velocity field. The 188 stress tensor, σ_{ij} , was calculated following the Nye-Glen isotropic flow law (Glen, 1955; Nye, 1957) as

$$\sigma_{ij} = B\dot{\epsilon}_e^{(1-n)/n} \dot{\epsilon}_{ij} \,, \tag{2}$$

where *n* is the flow law exponent with value 3 and *B* is a viscosity parameter, which we assign a value of 324 kPa $a^{1/3}$ (Cuffey and Paterson, 2010) based on an assumed 10 m ice temperature of 5°C. This uniform temperature assumption follows that made in other regional studies examining similar spatial scales (Clason *et al.*, 2015; Koziol *et al.*, 2017; Williamson *et al.*, 2018b), and matches observations made using distributed temperature sensing measurements at Store Glacier (Law *et al.*, in press). The effective strain rate, $\dot{\varepsilon}_e$, was then calculated following Cuffey and Paterson (2010) as

$$\dot{\epsilon}_{e} = \sqrt{\frac{1}{2} [\dot{\epsilon}_{xx}^{2} + \dot{\epsilon}_{yy}^{2}] + \dot{\epsilon}_{xy}^{2}}$$
(3)

198

- Because only surface-parallel stresses are considered, σ_{ij} can be expressed by two principal
- stresses. The first surface-parallel principal stress, σ_1 , was calculated as the highest (most
- 201 extensional) eigenvalue of the stress tensor, and second surface-parallel principal stress, σ_2 , as
- 202 the lowest (most compressive) eigenvalue.

The von Mises stress, σ_V , was calculated from the surface-parallel principal stresses following Vaughan (1993) as

$$\sigma_v = \sqrt{\sigma_1^2 + \sigma_2^2 - \sigma_1 \sigma_2} \tag{4}$$

205

A von Mises failure envelope was prescribed as the 95th percentile of the von Mises stress across the non-crevassed area, allowing up to 5% of the data to be misclassified (Vaughan, 1993).

The mean surface-parallel principal stress, σ_m , was calculated as the arithmetic mean of the first and second surface-parallel principal stresses as

$$\sigma_m = \frac{1}{2} [\sigma_1 + \sigma_2] \tag{5}$$

210

- 211 To explore the interaction between stress state and crevasse behaviour, we followed Vaughan
- (1993) in presenting data in the form of failure maps, presented in terms of the two surface-
- 213 parallel principal stresses.

214 2.3 UAV data

215 2.3.1 UAV photogrammetry

216 We acquired aerial imagery over a 13-day period in July 2018 (Table S1) using a custom-built,

- fixed-wing UAV with 2.1 m wing span. Imagery was collected using a Sony a6000 24 MP
- camera with a fixed 16-mm lens, processed using Structure from-Motion with Multi-View Stereo
- 219 (SfM-MVS) photogrammetry, and used to derive velocity fields within the UAV ROI as
- described by Chudley et al. (2019a). In brief, photogrammetry was performed using AgiSoft
- 221 Metashape v.1.4.3 software, and geolocated by using an on-board L1 carrier-phase GPS unit
- 222 (post- processed against a local on-ice ground station) to locate the position of aerial photos
- (Chudley *et al.*, 2019a). Outputs from the photogrammetric process were 0.15 m resolution
- orthophotos and 0.2 m resolution DEMs.
- 225 2.3.2 Surface classification
- 226 To date, UAV-based crevasse detection has been based on topographic analysis of DEMs (e.g.
- Ryan et al., 2015; Florinsky & Bliakharskii, 2019). Although useful from a hazard assessment
- 228 perspective (Florinsky & Bliakharskii, 2019), DEM-based methods alone cannot be used to
- 229 identify features such as ponded or healed crevasses, while crevasse detection is also sensitive to
- threshold choice and ultimately DEM resolution (Jones et al., 2018; Florinsky & Bliakharskii,
- 231 2019). To take advantage of the high spatial resolution and multi-dimensional outputs of UAV



Figure 2. Examples of random forest input data for regions dominated by (a-f) small and (g-l) large crevasses. (a and g) RGB orthophotos. (b and h) Brightness. (c and i) Standard deviation of RGB values. (d and j) NDWI. (e and k) Slope, with hillshade overlaid. (f and l) Black-top-hat filtered DEM, with

236 hillshade overlaid.

surveys, we used a combination of object-based image analysis (OBIA) and supervised

classification to identify crevasses and their hydrological state in a survey of the UAV ROI

flown on 2018-07-08. OBIA is based not on the numerical characteristics of individual pixels but

on objects, i.e. groups of meaningfully similar pixels segmented according to spectral

homogeneity (Blaschke, 2010). This has been used successfully in a glaciological context by K_{radii} and K_{radii} and

Kraaijenbrink *et al.* (2016, 2018) for mapping cliff/pond systems and emissivity on a debriscovered glacier. We again used Google Earth Engine to perform the full segmentation and

244 supervised classification workflow (Figure S2).

We identified a number of variables that could be used as inputs for a supervised classification 245 algorithm to identify crevasse field surface features. This included: the red, green, and blue 246 values of the orthophoto (Figure 2a;g); the 'brightness' (mean RGB values; Figure 2b;h) as per 247 Kraaijenbrink et al. (2016); the standard deviation of the RGB values, which highlighted water, 248 small crevasses, and healed crevasses (Figure 2c;i); the NDWI, from blue and red pixel values 249 (Figure 2d;j); the DEM slope, which effectively highlighted small crevasses with widths on the 250 order of a few metres (Figure 2e;k). Following Kodde et al. (2007), we also used DEM values 251 252 that were black-top-hat filtered with a 30 m structuring element that was useful in identifying large crevasses with widths on the order of tens of metres (Figure 2f;l). A black top-hat filter 253 254 morphologically closes the glacier surface at scales smaller than the structuring element, before subtracting the closed surface from the original data. This process was performed in MatLab 255

256 prior to input into Google Earth Engine.

257 We performed image segmentation using Simple Non-Iterative Clustering (SNIC) (Achanta &

Susstrunk, 2017), a computationally-efficient implementation of superpixel-based clustering.

Rather than segmenting an image into semantically meaningful objects, superpixel-based

segmentation aims to simplify the image into small, uniform, and compact clusters of similar pixels ('superpixels'), with a focus on boundary adherence. The variables described above were

pixels ('superpixels'), with a focus on boundary adherence. The variables described above were used as the input to the segmentation algorithm. We manually selected a seed spacing of 15

pixels (2.25 m) and a (relatively high) compactness factor of 200. This resulted in superpixels

small enough to display strong boundary adherence to small and healed crevasses at the scale of

metres, whilst still clearly delineating the margins of larger features such as water bodies. As an

input to the supervised classification, we calculated the average and standard deviation of values

in each superpixel from the variables described above, as well as the perimeter-to-area ratio of

the superpixel, and normalised the results.

We adopted a supervised classification approach to surface classification (Kraaijenbrink et al., 269 270 2016, 2018; Ryan et al., 2018) by training a random forest classifier. Random forests make use of an ensemble of decision trees, which classify objects by applying a series of if-then-else 271 logical conditions determined by training data. By utilising an ensemble of independent decision 272 trees, random forests aim to avoid overfitting that may occur when using a single tree. Each tree 273 utilises a randomised subset of training data, and the final result is gathered from a majority vote. 274 To reduce the amount of redundant information used to train the classifier, we performed a non-275 parametric mutual information (MI) test on our training data as a proxy for the predictive power 276 of each input variable. Rejecting input variables beneath the median MI value (Figure S3) did not 277 noticeably reduce the accuracy of the output data (Figure S4). Therefore, we used only the nine 278 most significant variables as inputs to the classifier. We constructed training datasets of 90 points 279 each, distributed across the AOI, for six distinct surface types: bare ice, snow, healed crevasses, 280 'small' crevasses, 'large' crevasses, and water. We separated 'small' and 'large' crevasses (those 281 with widths of metres vs. tens of metres) into two training datasets as they displayed distinctly 282 283 different values for properties such as brightness, slope, and the top hat filtered DEM (Figure 2). We trained the classifier on two-thirds of the dataset (60 points per classification) and retained 284 one-third (30 points per classification) for validation. Output classification performed well 285 visually (Figure S5) and validation data showed that a >95% F_1 accuracy score was observed for 286 all surface types (Figure S4, Table S2), apart from for snow and bare ice, which for our purposes 287 were not important to distinguish. Although we identified six surface types, for this analysis we 288 289 were only interested in three distinctions: crevasses (combining 'small' and 'large' crevasses), ice (combining bare ice, snow, and healed crevasses), and water. 290

291 **3 Results**

292 3.1 Satellite-based analysis

293 *3.1.1 Ponded crevasse distribution*

From the ArcticDEM elevation model and Sentinel-2 optical imagery, we mapped the

distribution of crevasses (Figure 3a) and surface water (Figure 3b) across the study region. Of the

total ice area assessed, $\sim 34\%$ ($\sim 960 \text{ km}^2$ out of $\sim 2695 \text{ km}^2$) was classified as being crevassed

(i.e. where a 200 m² grid cell has a crevasse fraction >1%). On average, 26% of this total

crevassed region was observed to exhibit surface ponding (i.e. where a 200 m² grid cell has a



Figure 3. (a) Observed crevasse fraction at 200 m resolution derived from ArcticDEM data with 2 m resolution. Manually identified crevasse initiation zones are marked in red. (b) Mean 2017-2019 observed water fraction at 200 m resolution derived from Sentinel-2 data with 10 m resolution. Black box marks the extent of insets showing water presence (in blue) at Sentinel-2 base resolution (10 m) in (i) 2017; (ii) 2018; and (iii) 2019; and underlying crevasses (in orange) at the ArcticDEM base resolution (2 m).

306	Table 1	. Crevassed	area	exhibiting	surface	ponding.	by year.
500	I abit I	· Crevusseu	urvu	exmonting	Surface	ponuing,	by your.

Year	Crevassed area	Ponded crevassed area (absolute)	Ponded crevassed area (relative)
2017		190.2 km ²	19.8%
2018	$060 \mathrm{km}^2$	264.9 km ²	27.6%
2019	900 km	290.0 km ²	30.2%
Mean	Mean		24.5%

307



309 Figure 4. Boundaries of surface depressions (i.e. basins) overlaid onto Arctic-DEM derived crevasses and

- 310 2018 water extent. Contours, from ArcticDEM, are in height above ellipsoid in metres.
- 311

312 **Table 2.** Prevalence of surface types, classified according to ArcticDEM crevasse data and mean 2017-

313 2019 Sentinel-2 data, occurring within surface depressions.

Surface type	Grid cell classification thresholds	Proportion of surface type within depressions
Crevasse	>1% crevasse fraction	5.0%
Ponded crevasses (excluding lakes)	>1% crevasse fraction 1 < n < 95% water fraction 9.7%	
Lake	>95% water fraction	78.9%

314

- water fraction >1%) across the 2017-2019 ablation seasons, ranging from 20-30% (Table 1).
- 316 Although total ponded area varies from year to year, the spatial pattern of ponded crevasses
- remained persistent between years. This can be observed qualitatively (Figure 3i-iii), and is
- supported by Pearson's correlation coefficient tests, which return statistically significant ($p < p^2$)
- 0.01 positive correlations when testing observed pixel water fraction between years (R² values:
- 2017-18, 0.68; 2018-19, 0.67; 2017-19, 0.79). The interannual spatial pattern of crevasse ponding is consistent across the study area despite ice velocity advecting crevasses kilometres
- pointing is consistent across the study area despite fee velocity advecting crevasses knohetres per year in some areas, suggesting the ability of crevasses to pond is externally controlled rather
- than a property of individual crevasses.

324 3.1.2 Topographic analysis

- 325 If the ability of a crevasse to pond was solely dependent on meltwater availability, ponded
- crevasses would be more prevalent at lower elevations, where air temperature is higher. We
- tested this hypothesis by comparing the spatial distribution of satellite-derived water fraction
- 328 (Figure 3b) with elevation. Within crevassed grid cells, there was no significant relationship
- between elevation and water fraction (R^2 value = 0.0014, p < 0.01). This analysis indicates that (air-temperature driven) meltwater availability does not exert a major control on ponded crevasse
- formation up to the limit of the elevation range of the satellite ROI (~1500 m a.s.l).
- is in the first of the first of the elevation funge of the satemic root (1000 m u.s.r).
- 332 If crevasse systems pond due to receiving meltwater that has been transported laterally across
- 333 supraglacial drainage networks, ponding should occur at the bottom of surface depressions. We
- tested this hypothesis by assessing the prevalence of meltwater ponding within surface
- depressions as identified from ArcticDEM data (Table 2). This analysis indicated that 78.9% of
- grid cells classified as lakes occurred in topographic depressions, whilst only 5.0% of crevassed
- grid cells and 9.7% of ponded crevasse grid cells were similarly located. Thus, while
 supraglacial lakes were predominantly located within surface basins (as expected), ponded
- supraglacial lakes were predominantly located within surface basins (as expected), ponded
 crevasse fields were predominantly located outside such basins (Figure 4). Infilling of surface
- basins by lateral supraglacial water transport therefore appears to explain only a minority of
- 341 crevasse ponding locations.

342 *3.1.3 Stress analysis*

343 We present strain-rate-derived stresses as failure maps, plotted in the form of density plots

- (Figure 5). To aid visualisation, each data point is plotted twice with assignments of σ_1 and σ_2
- reversed, giving symmetry across the line $\sigma_1 = \sigma_2$. Based on the stress distribution of the non-
- crevassed area, the von Mises failure envelope was prescribed at 76 kPa (marked with ellipses in
- Figure 5). However, this threshold does not differentiate either crevasse incidence nor
- 348 hydrological status. Crevasses plot both inside and outside the von Mises failure envelope
- (Figure 5b), while initiating crevasses (Figure 5c) plot predominantly within the envelope. The
- von Mises failure envelope is also not useful for differentiating crevasse ponding (Figure 5d).
- Inspection of Figure 5 does, however, reveal that initiating crevasses (Figure 5c) and ponding crevasses (Figure 5d) are separated by the line defined by $\sigma_1 = -\sigma_2$ (dashed line in Figure 5). This
- crevasses (Figure 5d) are separated by the line defined by $\sigma_1 = -\sigma_2$ (dashed line in Figure 5). This line marks the transition in mean surface-parallel stress state (σ_m) from negative (compressional;
- below the line) to positive (extensional; above the line). Thus, this analysis reveals that 89% of
- initiating crevasses are located in areas of extensional stress (cf. 54% of all crevasses). In
- contrast, 68% of ponded crevasses are located within areas of compressive stress (cf. 46% of all



Figure 5. Failure maps in the form of density plots of surface-parallel stress states for selected surface
classifications: (a) no crevasses; (b) all crevasses; (c) initiating crevasses; (d) water-filled crevasses.
Ellipses mark the prescribed von Mises stress threshold (76 kPa). Dotted line marks where mean surface-

parallel principal stress is zero. Note that data are reflected across the line X=Y.

362 crevasses). An example of the contrasting relationships between crevasse status and mean

surface-parallel stress are plotted spatially in Figure 6. While not all crevasses that are located in

compressive regimes pond, the transition between extensional and compressive σ_m regimes represents a convincing boundary between regions of crevasse initiation and ponding. This

366 suggests that a compressive mean stress regime is a necessary, but not sufficient, condition of 367 ponding.

368 3.2 UAV-based image analysis

³⁶⁹ UAV-derived observations of crevasse initiation and ponding (Figure 7a) follow similar patterns ³⁷⁰ to those revealed by the regional-scale satellite data (Figure 7b). Crevasses initiated - or at least ³⁷¹ become identifiable in the decimetre-resolution data - in the upstream section of the study zone. ³⁷² As they are advected down-glacier, crevasses width increased from decimetres to a maximum of ³⁷³ ~10–60 m (Figure 7a, i, ii). The region of crevasse initiation was coincident with a zone of ³⁷⁴ extensional σ_m in the satellite-derived data (Figure 7b). In the downstream sector of the UAV ³⁷⁵ ROI, crevasse size remained relatively stable, but displayed a higher propensity to pond in the



Figure 6. Crevasses, crevasse initiation zones, and 2018 water extent overlaid onto a shaded map of mean surface-parallel stress.

down-glacier direction (Figure 7a). This region of crevasse ponding occurs where satellite-

derived σ_m is observed to be compressive (Figure 7b).

381 Repeat UAV surveys provide insight into processes occurring at the scale of individual

crevasses. Over the 13-day period in July 2018 over which surveys were undertaken (Table S1),

three crevasse systems in the UAV ROI were observed to drain, and six underwent significant

filling. Crevasse drainages appear to be rapid. Of the three drainages identified, two represent

- crevasses that had a constant or rising water level in sequential imagery acquired prior to
- drainage. All three exhibited significant water loss between subsequent adjacent surveys (e.g.
- Figure 8a-b, c–d). One crevasse system lost a substantial volume of water in less than 24 hours (Figure 8a–b), and water levels continued to drop for the rest of the 12 day survey period (Figure
- S6b-c). This suggests that either a moulin had formed, and that water therefore continued to
- drain into the subglacial system, or that small open fractures continued to transfer water
- inefficiently into the englacial system. The filling crevasses were clustered tightly at the
- ³⁹² upstream side of the ponded crevasse system, in a location where crevasses are advecting from
- an extensional to compressive σ_m regime. Of the three crevasse drainage events identified, two
- occurred within the larger ponded system and compressive mean stress regime, while one
- occured in a smaller crevasse at the periphery of the system, in a weakly extensional regime.
- 396 These observations are consistent with the satellite-based observations in that, in general,



Figure 7. (a) Output of UAV random forest classification for 2018-07-08 survey, with insets (shaded in red and blue) showing (i) an area with large (widths 50-60 m) crevasses, and (ii) small (widths 2-3 m) crevasses. (b)
Satellite-derived data for comparison, with meltwater extent from 2018.

401 crevasses fill with water when in a compressional mean stress regime, but also show that
 402 drainages of these ponded crevasses occur discreetly and rapidly.

403 Within the UAV-derived data, our observations do not indicate significant lateral meltwater routing. Where supraglacial streams routed water between ponded crevasses, they were easily 404 identified in imagery (Figure S6a), but this was not common across the UAV ROI. When 405 406 individual crevasses drained, observations of any consequential effects on the surrounding system was limited. For the two most prominent crevasse drainages (Figure 8), we identify the 407 adjacent crevasses that also drained, either through visible supraglacial networks (marked 'S' in 408 409 Figure 8), or without visible supraglacial connections, which we thus interpret to be connected englacially (marked 'E' in Figure 8). In the first case (Figure 8a), an overflowing crevasse 410 system formed local supraglacial networks, and after one crevasse had drained, water levels 411 across the entire network dropped (Figure 8b). However, only one adjacent crevasse drained 412 without visible surface routing (Figure 8b). In the days following the drainage event, incised 413 supraglacial channels formed between the previously overflowing system (Figure S6b–c). In the 414 415 second drainage case, an individual crevasse drained without affecting water levels in the adjacent crevasses at all (Figure 8c-d). As such, in the ponded crevasse system within the UAV 416



417

Figure 8. Examples of crevasse drainage (a) before and (b) after a crevasse drained that was 418

supraglacially and/or englacially connected to adjacent crevasses; and (c) before and (d) after a crevasse 419

drained where no connections were present. Interpretations are marked where crevasses underwent direct 420

drainage (D), drained via a visible supraglacial connection to the draining crevasse (S), drained via 421 inferred englacial connection to the draining crevasse (E), or remained unconnected to a draining system

422

and did not drain (U). 423

424 ROI, we do not observe hydrological responses to drainage events that extend more than 1-2 crevasses ($\sim 100-200$ m) from the initiating crevasse. 425

4 Discussion 426

427 4.1 Performance of satellite- and UAV-based classification methods

The object-based random forest classification of UAV data (Figure 7a) enabled the identification 428 of crevasses and surface water with >95% accuracy (Figure S4; Table S2). Comparison of the 429 UAV and satellite-derived surface classifications (Figure 7a cf. 7b) shows clear agreement in the 430 distribution of surface features. The cutoff width below which crevasses are unable to be 431 432 identified from ArcticDEM v3 data is ~ 10 m (~ 5 pixels). Although this cutoff means the satellite data do not identify the smallest crevasses (such as those in Figure 7ii), the resolvable size of a 433 crevasse is approximately equal to the resolution of the Sentinel-2 bands used for NDWI 434 calculation (10 m), allowing the two satellite-derived datasets to be compared directly. Despite 435 the ArcticDEM mosaic being derived from multitemporal data (individual tiles across the 436 satellite ROI range from 2009-2017), the distribution of crevasses is consistent with the 2018 437

UAV dataset (Figure 7a cf. 7b). This indicates that, regardless of the advection of individual 438

- 439 crevasses, interannual variation in crevasse field extent is minor across the time period in this
- study. We can therefore be confident that the ArcticDEM 2009-2017 crevasse distribution can be
- 441 meaningfully compared to the Sentinel-2 2017-2019 surface water distribution. Sentinel-2- and
- UAV-derived surface water locations also agree consistently (Figure 7a cf. 7b), with individual
 ponded crevasses able to be co-located between the Sentinel-2 and UAV datasets. The Sentinel-2
- data additionally identifies ponded crevasses that were not water-filled on the date of the UAV
- survey. In summary, the UAV data shows that we can be largely confident in our satellite-
- 446 derived crevasse and water mapping at spatial scales ≥ 10 m. It is likely that the ArcticDEM-
- 447 based crevasse mapping underestimated crevasse extent at higher elevations, as the optically-
- derived dataset will not be sensitive to snow-filled crevasses; however, false negative
- 449 classifications do not affect the conclusions drawn from this dataset.

450 4.2 Spatial variability in crevasse hydrology

Across the $\sim 2,700 \text{ km}^2$ study area, an average of 26% of the crevassed region (containing 451 crevasses >10 m in width) exhibited visible ponding between 2017 and 2019. The inter-annual 452 453 variation in ponded crevasse coverage was lowest in 2017 and highest in 2019, consistent with the lowest and highest reported ice-sheet-wide melt data (e.g. Tedesco and Fettweis, 2020) which 454 identified 2019 as an exceptional melt year. This suggests that the extent of crevasse ponding is 455 in part controlled by melt intensity, consistent with previous models conceptualising crevasses as 456 457 linear reservoirs (Colgan et al., 2011; McGrath et al 2011), i.e. as melt intensity increases beyond the capacity of crevasses to discharge water into the englacial system, more ponding will 458 459 be observed at the surface. However, inter-annual melt intensity cannot explain the spatial distribution of observed ponding. Only a minority of crevasses are observed to pond, and the 460 spatial distribution of these is consistent from year-to-year (Figure 3i-iii). These patterns occur 461 on scales <1 km, smaller than any reasonable spatial boundary in melt intensity resulting from 462 surface mass-balance drivers such as the vertical gradient in air temperature. This inference is 463 supported by statistical tests that rejected the hypothesis that crevasse ponding was more 464 prevalent at lower elevations within the ablation zone, where surface melt intensity is generally 465 higher. These local-scale patterns of crevasse ponding are also stable in space regardless of ice 466 velocity, suggesting that ponding incidence is not advected with individual crevasses. We 467 therefore conclude that likely controls on the incidence of crevasse ponding are: (i) distinct from 468 melt intensity; (ii) not associated with the properties of individual crevasses; and (iii) spatially 469 variable on the order of $10^2 - 10^3$ m. 470

471 *4.3 Controls on crevasse hydrology*

Previous studies have predicted the location of current and future supraglacial lakes on the 472 Greenland Ice Sheet by identifying depressions in the surface topography that would capture 473 supraglacial meltwater (e.g. Ignéczi et al., 2016). This could be reasonably applied to crevasse 474 ponding if meltwater could be routed, without obstruction, for long distances laterally along 475 476 hydrological gradients across crevasse fields. This would result in localised crevasse ponding within surface depressions, forming a single surface lake if water supply exceeded open crevasse 477 volume. However, our satellite observations suggest only a small fraction of crevassed area 478 479 behaves in this way: only 9.7% of the ponded crevasse region is located within surface depressions (cf. 5.0% of all crevasses and 78.9% of the supraglacial lake area). This suggests that 480 lateral supraglacial transport of water into topographic basins is not the principal cause of 481

crevasse ponding. Indeed, because ponding occurs across topographic highs (Figure 4), we infer

- that in ponded crevasse systems drainage into the wider supraglacial and/or englacial drainage
- 484 system is being restricted. This inference is supported by our UAV repeat surveys, which show
- that hydrological connections between ponded crevasses whether supraglacial or englacial are rare and have limited spatial extent, often between only a few crevasses on the scale of 100-200
- 486 m (Figure 8b,d). Even where hydrological connections exist, they appear to form as a
- 488 consequence, rather than a cause, of crevasse drainage (Figure S6b–c). If lateral meltwater flow
- is restricted, the drainage of water from ponded crevasse systems cannot, for the most part, be
- 490 caused by water being routed into wider supraglacial networks (and from there to moulins, lakes,
- 491 or the englacial system). This contrasts with previous studies, which often assume that lateral
- 492 supraglacial drainage can occur unrestricted across crevasse fields (e.g. Poinar, 2015, Clason *et al.*, 2015).
- 494 In our satellite- and UAV-derived datasets, ponded crevasses are largely restricted to regions of 495 compressive mean stress. This association may be explained by supraglacial and englacial drainage remaining open and well-connected across crevasse fields in areas characterized by 496 extensional mean stress regimes. This is consistent with the view of crevasse systems on 497 temperate valley glaciers as hydraulically connected, albeit inefficiently, to englacial and/or 498 subglacial drainage systems through a linked network of fractures (Fountain *et al.*, 2005), and 499 supported by radar observations at Sermeq Kujalleq (Store Glacier), where englacial meltwater 500 storage in crevasse-damaged ice has been inferred down to a depth of 48 m (Kendrick et al., 501 2018). In these systems, meltwater availability rarely exceeds drainage rate, explaining the 502 limited crevasse ponding observed in such extensional regions. In contrast, we suggest that in 503 compressive regimes, englacial connections undergo what Irvine-Fynn et al. (2011) described as 504 'pinch-off', whereby crevasse closure by ice creep hydraulically isolates crevasse systems from 505 the wider supraglacial and englacial drainage system, resulting in subsequent ponding. This 506 hypothesis is supported by our UAV data, which show that englacial connections between 507 508 crevasses in ponded regions are limited in prevalence and extent. While a compressive mean stress regime appears to be a necessary condition for crevasse ponding, not all crevasses located 509 within such regimes are water-filled (Figure 6). This may be because the englacial system does 510 not always close entirely: we note that, at the UAV ROI, the upstream ~400 m of the 511 compressive stress field does not exhibit ponding (Figure 7b), perhaps indicating a delay before 512 the crevasse system is fully isolated. As the velocity at the UAV ROI is $\sim 650 \text{ m a}^{-1}$, this would 513 indicate a closure time of \sim 7 months to isolate the system. 514

515 4.4 Inferred drainage mechanisms and potential implications

516 *4.4.1 Rapid drainage of ponded crevasses*

517 Given that we found little direct evidence for hydrological connections between crevasses in

- 518 ponded regimes (Section 4.2), we consider full-depth hydrofracture and drainage to the
- subglacial environment to be a likely mechanism by which ponded crevasses drain (Weertman,
- 520 1973; Boon & Sharp, 2003; van der Veen, 2007; Krawczynski *et al.*, 2009). This would be
- 521 consistent with the rapid and heterogenous drainages observed in UAV data. Analogous to
- supraglacial lake drainages via rapid hydrofracture (Das *et al.*, 2008; Doyle *et al.*, 2013; Stevens
- *et al.*, 2015; Chudley *et al.*, 2019b), rapid crevasse drainage events are expected to deliver
- distinct, isolated pulses of meltwater to the bed. The full dynamic consequences of such events

are explored in detail elsewhere (e.g. Nienow *et al.*, 2017), but it is apparent that meltwater

inputs to the bed that are rapid (Schoof, 2010) and spatially discrete (Banwell *et al.*, 2016) can

527 influence ice dynamics. For example, rapidly draining crevasse systems at the shear margin of

Jakobshavn Isbrae have been shown to deliver meltwater to the bed at sufficient rates and volumes to overwhelm the capacity of the subglacial system (Lampkin *et al.*, 2013), increasing

530 ice mass flux across the shear margin and enhancing glacier discharge (Cavanagh *et al.*, 2017;

531 Lampkin *et al.*, 2018).

532 There are, however, several features of rapid crevasse drainages that are distinct from more widely studied lake drainage events. After hydrofracture, ongoing meltwater delivery via the 533 newly open moulin represents an important hydrological component of lake drainages (Koziol et 534 al., 2017; Hoffman et al., 2018). In contrast, the smaller catchments of individual crevasses 535 means that this effect is likely less important following crevasse drainage (although crevasses are 536 more numerous than lakes). Further, unlike lakes, it appears to be relatively common that 537 crevasse systems can drain multiple times through a single ablation season (Cavanagh et al., 538 2017). However, the net effect of this on ice dynamics has yet to be identified. Additionally, 539 crevasses that remain ponded and then refreeze at the end of the season will release latent heat 540 and facilitate ice warming (Lüthi et al., 2015) at depths of up to hundreds of metres (Hubbard et 541

542 *al.*, in press).

543 *4.4.2 Slow drainage of dry crevasses*

Approximately 74% of crevasse fields display no evidence of ponded meltwater (which we refer 544 to as 'dry' crevasses), despite there being no difference in local meltwater availability compared 545 546 to adjacent ponded regions. Since meltwater is inevitably also routed into these dry crevasses, we suggest that this water is accommodated by the wider supraglacial and englacial hydrological 547 system, stored and/or routed through pre-existing englacial pathways (e.g. Figure S7) or linked 548 fracture networks (Fountain et al., 2005; Kendrick et al., 2018), all of which are maintained by 549 an extensional stress regime. Since no ponding is observed in these regions, the condition for 550 hydrofracture is restricted, meaning that these crevasses are unlikely to route meltwater directly 551 to the bed. Instead, we suggest that this laterally routed meltwater must eventually intersect pre-552 existing moulins (Catania and Neumann, 2010), terminate at supraglacial lakes, remain as a 553 liquid reservoir (Kendrick et al., 2018), or freeze during the winter season. 554

We conceptualise that, due to low rates of lateral meltwater transport, drainage in dry crevasse 555 systems has a long total transit time to the bed. Such slow, continuous crevasse drainage has 556 previously been applied in crevasse hydrological models at the Greenland Ice Sheet by Colgan et 557 al. (2011) and McGrath et al. (2011). Colgan et al. (2011) suggested crevasse surface-to-bed 558 delivery rates may be 200-fold slower than moulins (\sim 12 hours for a 0.1 m wide crevasse cf. \sim 1 559 hour for a 1 m² moulin), whilst McGrath et al. (2011) suggested that crevasses may slow 560 englacial drainage to such an extent that a diurnal cycle of meltwater input can be damped to a 561 562 quasi-steady state discharge on the timescale of hours-days. This slow and sustained delivery of meltwater through crevasses to the glacier bed would be less likely to overwhelm temporarily the 563 transmission capacity of the subglacial drainage system. Therefore, both studies argue that 564 regions of the bed subject to this style of meltwater delivery are less likely to exhibit 565 ephemerally-enhanced basal sliding compared to regions experiencing episodic, efficient 566 meltwater pulses (as in Section 4.4.1). Additionally, this slower englacial drainage style 567

associated with crevasses may have distinct thermal consequences. It has been argued that slow

569 meltwater delivery through crevasses would deliver latent heat that results in more cryo-

570 hydrologic warming relative to regions fed by discrete moulins (Colgan *et al.*, 2011) because

densely packed and slow hydrological pathways increase the volume of ice warmed by the latent

heat release of englacial freezing relative to efficient drainage pathways (Phillips *et al.*, 2010;

573 Lüthi *et al.*, 2015). As full-depth hydrofracture is likely restricted in dry crevasse systems,

drainage in these regions may deliver less latent heat into depths on the order of hundreds of

575 metres compared to ponded crevasses, where propagation is facilitated by hydrofracture (e.g.

576 Poinar, 2015).

577 4.5 Implications for hydrological routing models

In the past, regional models of ice sheet hydrology and dynamics have often failed to include

579 crevasse drainage, instead focusing exclusively on supraglacial lake drainage (e.g. Arnold *et al.*,

2014; Banwell *et al.*, 2013, 2016). Recent regional hydrological models have begun to include

crevasse drainage in simple ways. For example, Clason *et al.* (2015) incorporated crevasse drainage, but considered it similarly to supraglacial lake drainage. These authors identified

drainage, but considered it similarly to supraglacial lake drainage. These authors identified crevassed regions based on a σ_v threshold, which were then allowed to fill and hydrofracture

according to a LEFM model (van der Veen, 2007). After full-depth hydrofracture and drainage, a

moulin was formed that continued to drain any further meltwater continuously to the bed. More

recently, Koziol *et al.* (2017) allowed crevasses to continuously drain, with meltwater produced

at the surface of crevasse fields (again identified according to a σ_v threshold) drained immediately to the bed without requiring hydrofracture. These behaviours, reflecting a paucity of

observations available at the time, were assumed to be spatially uniform. The observational

results we present herein highlight ways, summarized below, in which future studies may be able

to account further for a wide diversity of crevasse hydrology while keeping inputs and

592 classifications as simple as possible.

593 Our first recommendation is to avoid using simple stress thresholds or zero stress models to predict crevasse presence in surface routing models. Several models that incorporate crevasse 594 drainage have used a von Mises yield criterion (following Vaughan, 1993) to estimate the 595 location of crevasses for water routing (Clason et al., 2015; Koziol et al., 2017), as well as to 596 approximate tensile stress in crevasse hydrofracture (Clason et al., 2015, Morlighem et al., 597 598 2016). However, our data indicate that von Mises yield stress, σ_v , is not the most appropriate predictor of crevasse incidence and hydrology. Indeed, our analysis indicates that crevasses exist 599 across a range of σ_v values, both above and below the yield threshold prescribed following the 600 method of Vaughan (1993) (Figure 5b). Furthermore, our data indicate that even broad regions of 601 ice failure are not predicted accurately by a von Mises yield criterion (Figure 5c), with initiating 602 crevasses existing predominantly: (i) below the 76 kPa threshold prescribed following Vaughan 603 (1993), and (ii) in regions of positive mean stress. This is unsurprising considering that the 604 compressive strength of ice greatly exceeds its tensile strength, a factor that von Mises stress is 605 insensitive to. As such, we do not recommend a von Mises yield criterion as a suitable threshold 606 for identifying regions of crevasse incidence. While alternative measures, such as the first 607 principal (Benn et al., 2007) or longitudinal (Harper et al., 1998) stress, may be more appropriate 608 for predicting brittle ice failure, they are unlikely to also be a useful threshold for predicting 609 crevasse field distribution (Colgan et al., 2016), as crevasses advecting into unviable stress 610 611 regimes take time to adjust to the new equilibrium (Mottram and Benn, 2009). For studies of

612 contemporary crevasse fields, we instead recommend the use of direct observations as the

- simplest and most practical way to map crevasse locations. Herein, we present a simple method
- to achieve this based on the analysis of high-resolution DEMs, but other studies have adopted
- alternative methods such as using convolutional neural networks to classify optical imagery (Lai *et al.*, 2020). However, using satellite-derived data comes with weaknesses, such as being unable
- *et al.*, 2020). However, using satellite-derived data comes with weaknesses, such as being unabl to identify crevasses under snow cover or below the spatial resolution of the input data. The
- clustering of incipient crevasses in extensional mean stress regimes (Figure 5c) suggests that
- models could properly map crevasses from surface stresses if a more suitable stress threshold
- 620 were to be identified and subsequent advection and closure could be accounted for (e.g. Albrecht
- and Levermann, 2014).

Our second recommendation is to begin accounting for the diverse representations of crevasse

- drainage. Our data suggests that the delivery of supraglacial meltwater to the glacier bed through
- 624 crevasses falls into a spectrum of behaviour, ranging from episodic rapid drainage via full-depth
- hydrofracture (Section 4.4.1) to slow and continuous englacial drainage (Section 4.4.2). At the
- 626 coarsest scale, it may be desirable to implement a binary system to account for the end-members 627 of this spectrum. Our data suggest that the mean surface-parallel stress is a useful way of
- 627 of this spectrum. Our data suggest that the mean surface-paranet stress is a useful way of 628 segregating crevasse hydrological behaviour, with crevasses in compressive regimes being
- hydrologically isolated and exhibiting episodic rapid drainage. In contrast, crevasses in
- extensional regimes are hydraulically connected, exhibiting continuous drainage into the wider
- 631 supraglacial and englacal system. Thus, in compressive regimes, drainage could be modelled as
- episodic rapid hydrofracture following Clason *et al.* (2015), while also restricting the lateral flow
- of meltwater between grid cells. In extensional regimes, meltwater could be routed laterally to
- the nearest moulin or supraglacial lake. Simple thresholding such as this could be used in
- regional hydrological models to investigate the seasonal and long-term effects of spatial
- heterogeneity in crevasse hydrology on subglacial hydrology and ice sheet dynamics (see, for
- example, Poinar *et al.*, 2019).

638 **5** Conclusions

639 Previous work on Greenland's surface hydrology has assumed that water flow through crevasses,

- if considered at all, is spatially homogeneous and can be predicted using simple physical
- 641 thresholds. Our analysis of regional satellite data and local UAV surveys has demonstrated that
- crevasses instead exhibit spatially variable but inter-annually persistent hydrology across a 2700 km^2 maximum term instance of the order of $12 \text{ cont} = 200 \text{ km}^2$
- $\sim 2,700 \text{ km}^2$ marine-terminating sector of the western GrIS. Only 26% of crevasses are observed
- to pond, which we infer to result from the hydraulic isolation of crevasse systems in areas of
 compressive mean surface-parallel stress. Through UAV surveys, these ponded crevasses were
- shown to drain rapidly and episodically, likely through full-depth hydrofracture. The remaining
- 647 74% of crevasses stay dry throughout the observational period, which we infer to be due to water
- draining into the wider englacial and supraglacial system, connected through linked fracture
- networks that are actively maintained in extensional stress regimes. Our findings indicate that
- controls on crevasse ponding are distinct from better-studied processes, such as supraglacial lake
- 651 formation and crevasse opening, that are often used to represent the mechanics of crevasse
- 652 hydrology in surface routing models. This highlights the need for a better implementation of 653 crevasse hydrology in surface routing models, particularly as early implementations show that
- 654 crevasses can act as pathways for nearly half of all meltwater (Koziol *et al.*, 2017). Our
- observations indicate that some form of simple stress threshold may still be suitable to drive

- parameterisations in regional-scale models of meltwater drainage. However, further observations
- are necessary to improve our process-based understanding of crevasse hydrology, including *in*-
- *situ* observations of crevasse-scale mechanics and ice-sheet-scale satellite observations of spatio-
- temporal variability. Understanding the full spectrum of variability in crevasse hydrology is not
- only essential to be able to model the Greenland Ice Sheet's thermodynamic response to
- increasing surface runoff in the 21st century, but has wider implications across other cryospheric
- 662 contexts, such as ice shelf hydrology and breakup (e.g. Lai *et al.*, 2020).

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- The authors declare no conflicts of interest.

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Supporting Information for

Controls on water storage and drainage in crevasses on the Greenland Ice Sheet

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Figure S1. Flow diagram visualising the production of crevasse fraction data from ArcticDEM (left) and water fraction data from Sentinel-2 optical imagery (right). Red box outlined in maps marks the extent of the UAV ROI.



Figure S2. Flowchart of the method used to classify UAV imagery. Variables appended with an asterisk were calculated from input data within GEE, whilst the top hat filter, appended with a cross, was calculated separately in Matlab. Inset as for Figure 2 of main text, showing examples of OBIA input data for regions dominated by (a-f) small and (g-l) large crevasses. (a and g) RGB orthophotos. (b and h) Brightness. (c and i) Standard deviation of RGB values. (d and j) NDWI. (e and k) Slope, with hillshade overlaid. (f and l) Black-top-hat filtered DEM, with hillshade overlaid.



Figure S3. Results of mutual information tests for all potential input variables against training data. Median value is marked by the dotted line. BTH is black tophat filter. SD is standard deviation.



Figure S4. Normalised confusion diagrams for object-based image analysis of 2018-07-08 imagery for (A) all input variables; and (B) selected input variables with mutual information test results greater than median. For quantitative accuracy assessment of this data, see Table S2.



Figure S5. Example results for object-based image analysis of 2018-07-08 imagery. RGB and classified image for all six surface types shown for a region with 'large' (a, b) and 'small' (c, d) crevasses respectively.



Figure S6. Supraglacial connections between crevasses. (A) Southwestern extent of UAV survey area, displaying clear incised supraglacial pathways between crevasses. (B–C) Crevasse system identified in main figure 7A–B in the 24 hours following (B) and 12 days following (C) drainage, showing the development of incised streams as water level lowers. Inset: subfigure extents identified in full UAV survey extent.



Figure S7. Evidence of significant lateral englacial flow channels at Store Glacier in July 2012. Channel occurs in a relict moulin (70° 33.497', -50° 05.912') located downstream of the rapidly draining Lake 028. (left) The englacial channel located within the relict moulin, with figure for scale. (right) View into the englacial channel. Although the moulin was no longer actively receiving melt, water (with a floating ice melange) existed in the channel. The endpoint was not visible.

Table S1. UAV survey date and times of flight midpoints (rounded to the nearest 5 minutes). All times in Coordinated Universal Time (UTC)

Survey Date	Time (UTC)
2018-07-05	21:10
2018-07-06	19:25
2018-07-07	17:25
2018-07-08	19:25
2018-07-18	14:20

Table S2. Accuracy assessment of random forest classification for 2018-07-08 survey, including calculated accuracy, precision, recall, F₁ score, and Matthew's Correlation Coefficient (MCC).

Class	Accuracy	Precision	Recall	F ₁ Score	МСС
Small Crevasses	1	1	1	1	1
Large Crevasses	0.99	1	0.97	0.98	0.98
Healed Crevasses	0.99	1	0.97	0.98	0.98
Water	1	1	1	1	1
Bare Ice	0.95	0.89	0.84	0.86	0.83
Snow	0.96	0.86	0.91	0.89	0.86