### Electromagnetic Radial Diffusion in the Earth's Radiation Belts as Determined by the Solar Wind Immediate Time History and a Toy Model for the Electromagnetic Fields

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#### Abstract

Diffusion-driven radiation belt models require multiple physics-based inputs to specify the radiation environment through which spacecraft travel, including diffusion coefficients. Even though event-specific coefficients are necessary for model accuracy, their routine integration in operational models has not yet been achieved. In fact, one of the key inputs, the radial diffusion coefficient, is still commonly determined by a Kp-driven parameterization. This work presents a method to determine continuous time series of time-varying radial diffusion coefficients. A theoretical model is developed in which electromagnetic radial diffusion is controlled by the magnetopause immediate time history. Specifically, radial diffusion is described as a function of the average, variance, and autocorrelation time of the geocentric stand-off distance to the subsolar point on the magnetopause. Because the magnitudes of these three magnetopause parameters vary with time and magnetic activity, so does radial diffusion. To a lesser extent, radial diffusion is also controlled by the drift frequency of the radiation belt population. Moreover, radial diffusion is quantified using a standard model in which the magnetopause is controlled by the solar wind. Although the resulting diffusion coefficients span several orders of magnitude per Kp index, the median magnitudes are remarkably similar to the ones provided by the standard Kp-driven statistical parameterization.

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9	Keywords
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13	Key points
14	1. A model in which electromagnetic radial diffusion is determined by the immediate time
15	history of the magnetopause location is presented.
16	2. With the magnetopause controlled by the solar wind, the diffusion coefficients per $Kp$
17	index average similarly to the existing standard.
18	3. A time series of electromagnetic radial diffusion coefficients with a one-minute time
19	resolution is provided for the year 2013.

#### 20 Abstract

21

Diffusion-driven radiation belt models require multiple physics-based inputs to specify the radiation environment through which spacecraft travel, including diffusion coefficients. Even though event-specific coefficients are necessary for model accuracy, their routine integration in operational models has not yet been achieved. In fact, one of the key inputs, the radial diffusion coefficient, is still commonly determined by a *Kp*-driven parameterization.

This work presents a method to determine continuous time series of time-varying radial diffusion 27 coefficients. A theoretical model is developed in which electromagnetic radial diffusion is 28 controlled by the magnetopause immediate time history. Specifically, radial diffusion is described 29 as a function of the average, variance, and autocorrelation time of the geocentric stand-off distance 30 to the subsolar point on the magnetopause. Because the magnitudes of these three magnetopause 31 32 parameters vary with time and magnetic activity, so does radial diffusion. To a lesser extent, radial diffusion is also controlled by the drift frequency of the radiation belt population. Moreover, radial 33 diffusion is quantified using a standard model in which the magnetopause is controlled by the solar 34

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#### 40 Plain Language Summary

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An increasing number of spacecraft operate through or within the terrestrial radiation belts, a 42 region where charged energetic particles are trapped in the Earth's magnetic field. Computer codes 43 simulate this dynamic radiative environment, with the objective of improving spacecraft design 44 and understanding spacecraft anomalies. These codes are physics-based models. That is, they solve 45 a master diffusion equation using a series of inputs that summarize the effects of different physical 46 processes on particles. One of the key inputs to these codes is the radial diffusion coefficient. Yet 47 its formulation is currently limited: It is an average, obtained by interpolating a few experimental 48 data points, and the time resolution is no better than three hours. By detailing the physics 49 underlying radial diffusion in a simple scenario, this work provides a new quantification for the 50 radial diffusion coefficient. The time resolution is improved, and the coefficient variability is 51 enhanced. The fact that the resulting coefficient varies around the standard values provided by the 52 53 current reference adds credibility to the method. As a result, it is expected that this new quantification will contribute to improving the accuracy of radiation belt simulations. 54

#### 55 **1. Introduction**

56

57 Diffusion-driven radiation belt models have been developed and operated since the mid-1990s 58 (Beutier & Boscher, 1995) to specify the structure, intensity and variability of the radiation 59 environment through which satellites operate (e.g., Horne et al., 2013). They consist of solving a 60 diffusion equation to describe radiation belt dynamics (e.g., Schulz & Lanzerotti, 1974), based on 61 the adiabatic theory of magnetically trapped particles (e.g. Northrop, 1963). Operating a physics-

- 62 based radiation belt model requires quantifying different inputs, including radial diffusion.
- 63

Radial diffusion is a statistical characterization of the violation of the third adiabatic invariant for
a trapped radiation belt population. It plays a key role in determining radiation belt dynamics, not
only at Earth but also at the giant planets (e.g., Lejosne & Kollmann, 2019).

67

The most commonly used radial diffusion inputs for terrestrial radiation belt models are the empirical coefficients for electromagnetic radial diffusion determined by Brautigam and Albert (2000), and parameterized by the Kp index:

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$$log_{10} \left( D_{LL}^{B\&A} / L^{10} \right) = -9.325 + 0.506 \times Kp \ \left[ log_{10} (day^{-1}) \right] \tag{1}$$

72

where  $D_{LL}$  is the electromagnetic radial diffusion coefficient of a population of equatorial radiation belt particles, and the superscript "*B*&*A*" stands for Brautigam and Albert's empirical law for radial diffusion. For non-equatorial particles of the same kinetic energy, the electromagnetic radial diffusion coefficient is proportional to the one in the equatorial case (Fälthammar, 1968; Schulz & Lanzerotti, 1974, p.89). Similar parameterization for equatorial electromagnetic radial diffusion was proposed by Ozeke et al. (2014) (Drozdov et al., 2017), based on the erroneous analytic expressions for radial diffusion developed by Fei et al. (2006) (Lejosne, 2019).

80

Brautigam and Albert's empirical law for electromagnetic radial diffusion presents advantageous 81 82 features for operational models (e.g., Glauert et al., 2018). First, radiation belt simulations yield 83 plausible results when using such formulation for radial diffusion (e.g., Kim et al., 2011). Second, the implementation of the formula is straightforward. Moreover, it provides uninterrupted (i.e., 84 85 operational) evaluation of radial diffusion. On the other hand, even though the importance of using event-specific inputs to improve model accuracy is now recognized (e.g., Tu et al., 2009), their 86 87 determination is seemingly incompatible with operational models. Indeed, the development of event-specific coefficients has called for intensive work so far: It requires running potentially 88 costly numerical simulations (e.g., Li Z. et al., 2017), and/or carrying detailed analysis of specific 89 data sets when available (e.g., Ali et al., 2016). Even so, uncertainty in the magnitude of these 90 tailored, "event-specific" radial diffusion coefficients leads to uncertainty in the relative 91 contribution of other processes to the observed particle distribution (e.g., Mann et al., 2016; Shprits 92 93 et al., 2018; Mann et al., 2018). Such features hamper our ability to include event-specific radial diffusion coefficients in operational radiation belt models. 94

The objective of this work is to provide a method to build operational, event-specific, 96 97 electromagnetic diffusion coefficients. It builds on the theoretical framework underlying Brautigam and Albert (2000)'s empirical formula for electromagnetic radial diffusion. The 98 theoretical model is detailed in Section 2, together with its reformulation in terms of fluctuations 99 100 of the magnetopause location. Applying Shue et al. (1998)'s magnetopause model, the magnitude and variability of the resulting radial diffusion coefficients are discussed in Section 3. Section 4 101 presents the results in the case of the year 2013, together with a comparison with the 102 electromagnetic radial diffusion coefficients estimated according to Brautigam and Albert (2000)'s 103 formula. The approach is discussed Section 5. 104

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#### 107 2. Theoretical Model Description

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# 109 2.1. Theoretical Framework Associated with Brautigam and Albert (2000)'s Formula for 110 Electromagnetic Radial Diffusion

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Brautigam and Albert (2000)'s empirical formula for electromagnetic radial diffusion is a least squares interpolation of experimental values obtained at L = 4 by Lanzerotti and Morgan (1973) and at L = 6.6 by Lanzerotti et al. (1978). In both cases, a time interval of one week to one month of magnetic field fluctuations was analyzed to quantify an analytic expression for electromagnetic radial diffusion. The analytic expression, developed by Fälthammar (1965; 1968), and further detailed by Schulz and Eviatar (1969), is the following:

118

$$\frac{D_{LL}}{L^{10}} = \frac{\Omega^2}{8} \left(\frac{5}{7}\right)^2 \frac{R_E^2}{B_E^2} P_A(\Omega)$$
(2)

119

for equatorially mirroring particles, where  $B_E \cong 0.3 G$  is the magnetic equatorial field at the Earth surface,  $R_E \cong 6400 \ km$  is one Earth radius,  $\Omega/2\pi$  is the trapped population drift frequency, and  $P_A$  is the power spectrum of the asymmetric field fluctuations of a simplified electromagnetic field model.

124

125 The magnetic field model is a magnetic dipole field to which a small perturbation is superimposed 126 (Mead, 1964). The small perturbation is the sum of two components: a symmetric component, 127 S(t), independent of local time,  $\varphi$ , and an asymmetric component,  $A(t)rcos\varphi$ . An additional 128 assumption connects both symmetric and asymmetric components of the magnetic field 129 perturbation to the magnetopause location:

$$S(t) = \frac{B_1}{\mathscr{B}^3(t)} \tag{3}$$

132 and

133

$$A(t) = \frac{-B_2}{R_E \mathscr{E}^4(t)} \tag{4}$$

134

where  $B_1 \cong 0.25 \ G$  and  $B_2 \cong 0.21 \ G$ , and  $\& \sim 10 \ R_E$  is the geocentric stand-off distance to the subsolar point on the magnetopause, normalized in units of Earth Radii (e.g., Schulz & Eviatar, 137 1969). As a result, the power spectrum of the asymmetric field fluctuations is proportional to the power spectrum of the symmetric field fluctuations, and the **equation (2)** for electromagnetic radial diffusion is also:

140

$$\frac{D_{LL}}{L^{10}} = 2\Omega^2 \left(\frac{5B_2}{21B_1 B_E}\right)^2 \frac{1}{\mathscr{E}^2} P_S(\Omega)$$
(5)

141

Because a fluctuation of the magnetopause location,  $\mathscr{E}'$ , leads to a symmetric fluctuation of the magnetic field, S', that is about 10 times greater than the asymmetric one, A',  $(A'R_E = -4B_2S'/(3B_1\mathscr{E}) \sim -0.1S')$ ,  $P_S(\Omega)$  is more readily measurable than  $P_A(\Omega)$ . That is why the **equation (5)** is usually preferred to the **equation (2)** when it comes to evaluating radial diffusion experimentally (Lanzerotti & Morgan, 1973; Lanzerotti et al., 1978).

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Alternatively, one can also reformulate equation (2) in terms of fluctuations in the magnetopause
 location since the magnitude of the magnetic field asymmetry is directly related to the
 magnetopause location (equation (4)).

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## 152 2.2. Theoretical Model for Electromagnetic Radial Diffusion as Determined by the 153 Magnetopause Location

- 154
- 155 Combining equations (2) and (4) yields:

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$$\frac{D_{LL}}{L^{10}} = \frac{\Omega^2}{2} \left(\frac{20}{7}\right)^2 \left(\frac{B_2}{B_E}\right)^2 \frac{1}{\bar{\mathscr{B}}^{10}} \int_0^\infty \overline{\mathscr{B}'(0)\mathscr{B}'(u)} \cos(\Omega u) \, du \tag{6}$$

157

where  $\overline{\mathscr{b}}$  is the average magnetopause location,  $\mathscr{b}' = \mathscr{b} - \overline{\mathscr{b}}$  is the fluctuating part of the magnetopause location, and  $(u \mapsto \overline{\mathscr{b}'(0)\mathscr{b}'(u)})$  is the autocorrelation function of the magnetopause location. Further assuming that the autocorrelation function of the magnetopauselocation is subject to an exponential decay:

162

$$\overline{\mathscr{b}'(0)\mathscr{b}'(u)} = \overline{\mathscr{b}'^2} e^{-u/\tau} \tag{7}$$

163

164 where  $\tau$  is the fluctuation lifetime, and  $\overline{\mathscr{C}'}^2$  is the variance of the signal. It results that: 165

$$\frac{D_{LL}}{L^{10}} = \frac{1}{2} \left(\frac{20}{7}\right)^2 \left(\frac{B_2}{B_E}\right)^2 \frac{\overline{\mathscr{K}'^2}}{\overline{\mathscr{K}}^{10}} \frac{\Omega^2 \tau}{1 + \Omega^2 \tau^2}$$
(8)

166

167 Because radial diffusion coefficients are usually expressed on a logarithmic scale, let us focus on 168  $log_{10}(D_{LL}/L^{10})$  in the remainder of the article: 169

$$\log_{10}(D_{LL}/L^{10}) = -10\log_{10}(\bar{\mathscr{E}}) + \log_{10}(\bar{\mathscr{E}'}^2) + \log_{10}\left(\frac{\Omega^2\tau}{1+\Omega^2\tau^2}\right) + C$$
(9)

170

171 where

172

$$C = log_{10} \left(\frac{1}{2} \left(\frac{20}{7}\right)^2 \left(\frac{B_2}{B_E}\right)^2\right) \cong 0.3$$

(10)

173

is a constant. The third term on the right-hand side of **equation (9)** is the only term that explicitly depends on the kinetic energy of the trapped population. It reaches a maximum equal to  $-log_{10}\tau$ at very high energies, when  $\Omega\tau \gg 1$ . On the other hand, assuming that the fluctuation lifetime is very small in comparison with the radiation belt population drift period ( $\Omega\tau \ll 1$ ), **equation (9)** becomes:

179

$$\log_{10}(D_{LL}/L^{10}) = F\left(\overline{\mathcal{B}}; \overline{{\mathcal{B}'}^2}; \tau\right) + 2\log_{10}\Omega + C$$
(11)

180

181 where

182

$$F\left(\overline{\mathscr{B}}; \overline{\mathscr{B'}^{2}}; \tau\right) = -10 \log_{10}\left(\overline{\mathscr{B}}\right) + \log_{10}\left(\overline{\mathscr{B'}^{2}}\right) + \log_{10}(\tau) \tag{12}$$

is a function controlled by the statistical characteristics of the magnetopause location.

- 185 186 In any case, one needs to evaluate the average magnetopause location,  $\overline{\mathcal{V}}$ , the variance of the 187 magnetopause location,  $\overline{\mathcal{V}'^2}$ , and the lifetime of the magnetopause fluctuations,  $\tau$ , in order to 188 quantify electromagnetic radial diffusion. Shue et al. (1998)'s magnetopause model provides a fast 189 and accessible way to evaluate of these magnetopause parameters. In this model, the stand-off 190 distance to the magnetopause is controlled by the dynamic pressure of the solar wind, and the 191 orientation of the interplanetary magnetic field (IMF):
- 192

$$\mathscr{b} = (10.22 + 1.29 \tanh(0.184 \times (B_z + 8.14))) D_p^{-1/6.6}$$
(13)

193

where the solar wind dynamic pressure,  $D_p$ , is in nanopascals, and the north-south component of the IMF,  $B_z$ , is in nanoteslas (Shue et al., 1998). This model will be used in the following in order to quantify radial diffusion.

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#### 199 **3. Quantification**

#### 200 **3.1. Origin of Radial Diffusion Time Variability**

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In equation (2), and thus in equations (6)-(12), A(t), and thus  $\mathscr{E}(t)$ , are considered to be realizations of a stationary stochastic process. In other words, it is assumed that the magnetopause location fluctuates randomly and that its statistical properties are time-independent. In practice, the signal  $\mathscr{E}(t)$  does not correspond to realizations of a strictly stationary process, and the statistical properties of  $\mathscr{E}$  are time varying. Thus, it is necessary to specify a sample window size to evaluate the statistical characteristics of the magnetopause location. As a result, equation (11) becomes:

209

$$log_{10}(D_{LL}/L^{10}) = F_T + 2log_{10}\Omega + C$$
(14)

210

211 where

212

$$F_T = -10\log_{10}\left(\overline{\mathscr{B}}_T\right) + \log_{10}\left(\overline{\mathscr{B}'}_T\right) + \log_{10}(\tau_T)$$
(15)

213

and the subscript indicates that the quantity depends on the window size chosen, T. The moving average of the magnetopause location is:

$$\overline{\mathscr{B}}_T = \frac{1}{T} \int_{-T/2}^{T/2} \mathscr{B}(u) du \tag{16}$$

217

and the moving variance of the magnetopause location is:

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$$\overline{\mathscr{U}'}_{T}^{2} = \frac{1}{T} \int^{T} \left( \mathscr{U}(u) - \overline{\mathscr{U}}_{T}(u) \right)^{2} du$$
(17)

220

221 Thus, the time variability of the electromagnetic radial diffusion coefficient comes from the time 222 variability of the statistical characteristics of the magnetopause location (average, variance, and lifetime). The radial diffusion coefficient increases 1) when the magnetopause average location 223 decreases, 2) when the magnetopause fluctuations increase, or 3) when the lifetime increases 224 225 (equations (14)-(15)). Which of these three possible effects has the most control over radial 226 diffusion variability? In particular, why does the radial diffusion coefficient increase with Kp? To 227 investigate this question, the three components of  $F_T$  were computed for the year 2013 with a onehour window size (T = 1h). To pilot the magnetopause location (equation (13)) solar wind inputs 228 229 with a one-min time resolution were extracted from NASA/GSFC's OMNI data set through 230 OMNIWeb (https://omniweb.gsfc.nasa.gov/). The average and the variance were computed 231 according to equation (16) and (17), respectively, and the lifetime  $\tau$  was determined by fitting the autocorrelation function to an exponential decay. The results are summarized by boxplots 232 233 parameterized by the *Kp* index and they are presented **Figure 1**.



Figure 1: Magnitude of the three radial diffusion components that depend on the statistical characteristics of the magnetopause location, A)  $-10log_{10}(\overline{\mathcal{E}})$ , B)  $log_{10}(\overline{\mathcal{E}'})$ , and C)  $log_{10}(\tau)$ (see text for definitions). The ends of the whiskers correspond to the minimum and maximum values, the bottoms and the tops of the boxes are the lower and upper quartiles, and the bands inside the boxes are the medians. The sample window size chosen for the computations is one hour (T = 1h).

242 The **Figure 1** suggests that the magnitude of radial diffusion increases with the *Kp* index both 243 because the average magnetopause location decreases with Kp (Fig. 1A) and because the fluctuations in magnetopause location increase with Kp (Fig. 1B). On the other hand, the 244 fluctuation lifetime does not seem to depend much on Kp (Fig. 1C). It is typically of the order of 245 a few minutes (< 10 min). Thus, for particles with drift periods that are such that  $\Omega < 5 \text{ mHz}$ , i.e., 246 for radiation belt particles below a few MeV (e.g. Schulz and Lanzerotti, 1974, p.13), the 247 assumption  $\Omega \tau \ll 1$  is typically valid, and the equation (11) is a good approximation of the 248 equation (10). 249

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### 251 **3.2.** Effect of the Sample Window Size on the Quantification of Radial Diffusion

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253 The statistical characteristics of the magnetopause location presented Figure 1 were determined using a sample window of one hour (T = 1h). To what extent does the choice of a sample window 254 size affect the statistical characteristics of the magnetopause location, as summarized by  $F_T$ , thus, 255 the magnitude of radial diffusion? To investigate this question, the function  $F_T$  was computed for 256 different sample window sizes 10 over the year 2013: T =257 [6 min, 12 min, 18 min, 30 min, 1 h, 2 h, 3 h, 5 h, 10 h, 24 h]. The results are summarized by 258 boxplots, and they are displayed Figure 2. 259



Figure 2: Magnitude of the parameter,  $F_T$ , which quantifies the effect of statistical characteristics of the magnetopause location on radial diffusion, as a function of the sample window size chosen for the statistical computations, *T*. The ends of the whiskers indicate the minimum and maximum values, the bottoms and the tops of the boxes are the lower and upper quartiles, and the bands inside the boxes are the medians.

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The **Figure 2** shows that the magnitude of  $F_T$  decreases as the window size, *T*, decreases. This is because the average magnetopause location fits better the instantaneous value of the magnetopause location as the window size *T* decreases. Thus, the variance decreases as the window size decreases  $(\overline{\ell'})^2 = 0$  for the asymptotic case in which *T*=0). A linear interpolation of  $F_T$  as a function of  $log_{10}(T)$  yields that, on average:

$$\frac{dF_T}{d(log_{10}(T))} \cong 1.5\tag{18}$$

274

with a standard deviation of 0.4.

277 When the objective is to quantify radial diffusion, the selected window size, T, must be consistent

with the adiabatic invariant theory of magnetically trapped particles. Indeed, field fluctuations that evolve on timescales longer than the trapped population drift period conserve the third adiabatic

evolve on timescales longer than the trapped population drift period conserve the third adiabatic
invariant. On the other hand, asymmetric field fluctuations with characteristic times comprised
between the bounce and the drift period violate the third invariant, driving radial diffusion (e.g.,
Northrop, 1963). Thus, the window size, *T*, must be such that all field fluctuations that are on

timescales longer than the drift period are stored in  $\overline{\mathscr{V}}$  while field fluctuations that are between the bounce and the drift period are in  $\mathscr{V}'$ . Given the one-minute time resolution of the input signal, the characteristic time for the variation of the field is always greater than the bounce period. Nonetheless, the window size, *T*, needs to be long in comparison with the trapped population drift period in order to compute the average,  $\overline{\mathscr{V}}$ :

288

$$T = \frac{2\pi k}{\Omega} \tag{19}$$

289

where *k* is a constant greater than one: k > 1. As a result,  $F_T$  is in fact dependent on the trapped population drift frequency. Indeed, combining **equations (18)** and **(19)** yields:

292

$$\frac{d F_T}{d(log_{10}(\Omega))} \cong -1.5 \tag{20}$$

293

As the kinetic energy increases, the drift frequency increases, thus, the magnitude of  $F_T$  decreases. In other words, the particle's drift motion is less and less sensitive to field fluctuations as the drift velocity increases (the discrepancies between  $\overline{\mathscr{V}}$  and  $\mathscr{V}(t)$  decrease as the drift period - thus T decreases). Therefore, one should ideally tailor the computation of **equation (9)** according to the drift frequency. Yet, the expected dependence of radial diffusion on drift frequency is relatively weak. Indeed, for  $\Omega \tau \ll 1$ , combining **equation (20)** and **equation (14)** yields

 $d(\log_{10}(D_{LL}/L^{10}))/d(\log_{10}(\Omega)) \cong 0.5$ (21)

301

Thus, the magnitude of radial diffusion  $D_{LL}$  increases by about a factor 3 when the drift frequency increases by a factor 10. In comparison, for  $\Omega \tau \gg 1$ , assuming that the drift frequency dependence of  $F_T$  comes primarily from the variance, i.e.,  $dF/d(log_{10}(\Omega)) \approx d(log_{10}(\mathscr{E}'^2))/d(log_{10}(\Omega))$ : 305

$$d(\log_{10}(D_{LL}/L^{10}))/d(\log_{10}(\Omega)) \cong -1.5 < 0$$
<sup>(22)</sup>

Thus, there is a cutoff in radial diffusion efficiency once the drift period becomes smaller than the fluctuation lifetime. Assuming that the order of magnitude obtained **equation (22)** is valid, the magnitude of radial diffusion  $D_{LL}$  decreases by about a factor 30 when the drift frequency increases by a factor 10.

311

While the selected window size needs to be consistent with adiabatic invariant theory, it also needs to be consistent with the mathematical assumptions underlying the model. In particular, field fluctuations must be regarded as realizations of a stationary process within the time interval considered. Such conditions are most likely achieved during magnetically quiet times, and/or when considering a relatively small time interval. Since the latter is not necessarily consistent with **equation (19)**, this poses a problem to radial diffusion quantification.

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In the following, it is proposed to work with a sample window size of one hour:  $T_{1h} = 1 h$ . A onehour window is small enough to render radial diffusion variability with magnetic activity (as illustrated **Figure 1**) and to expedite the computations. It is also large enough to maintain sufficient data points to perform the required statistical analyzes. The average proportional relationship between the function,  $F_T$ , and the logarithmic of the drift frequency,  $log_{10}(\Omega)$ , is used to evaluate the appropriate value of  $F_T$  from  $F_{1h}$ . Combining **equations** (14), (19) and (20) yields:

$$log_{10}(D_{LL}/L^{10}) = F_{1h} + 1.5 \log_{10}(2\pi k/T_{1h}) + 0.5 \log_{10}(\Omega) + C$$
(23)

326

for  $\Omega < 5 \ mHz$ . Given the uncertainty in hands, the choice of the constant k > 1 is unimportant. It is set to k = 10 in the remainder. The radial diffusion coefficient is usually in  $[day^{-1}]$  while the angular drift velocity is usually in [mHz]. As a result, a reformulation of the **equation (23)** is:

$$\log_{10}(D_{LL}/L^{10}) = F_{1h} + 0.5 \log_{10}(\Omega) + 2.9$$
<sup>(24)</sup>

331

where  $D_{LL}$  is evaluated in  $[day^{-1}]$ ,  $F_{1h}$  is provided in  $[log_{10}(min)]$ , and  $\Omega$  is in [mHz].

333 334

#### 4. Results and Comparison with Brautigam and Albert's Empirical Formula

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The radial diffusion coefficients were computed for the year 2013 for a radiation belt population of angular drift velocity  $\Omega = 1 \ mHz$ , following **equation** (24). The time series is represented in 339 the Figure 3 and it is compared to Brautigam and Albert's estimates for electromagnetic radial diffusion. The comparison highlights a) the overall good agreement between the two times series, 340 b) the greater variability of the radial diffusion coefficients determined by the solar wind 341 immediate time history, and c) some limitations of the statistical model. For instance, Brautigam 342 and Albert's empirical formula has a lower threshold of  $log_{10}(D_{LL}/L^{10}) = -9.325$  during quiet 343 344 times (Kp = 0). The existence of a lower threshold for radial diffusion is not physical, since there would be no radial diffusion (i.e.,  $D_{LL} = 0$ ) if the electromagnetic fields were perfectly stationary. 345 On the other hand, the radial diffusion coefficients determined by the solar wind immediate time 346 347 history can be smaller, in accordance with theoretical expectations. The results were also binned 348 according to the Kp index, and they are summarized in boxplots displayed Figure 4. 349



350

Figure 3. Electromagnetic radial diffusion as a function of the day of the year (doy) in 2013. The
radial diffusion coefficients determined as a function of the solar wind immediate time history are
in black. The radial diffusion coefficients determined by Brautigam and Albert (2000)'s empirical
formula (B&A) are in red.



**Figure 4.** Statistical characterization of the electromagnetic radial diffusion magnitude for the year 2013, as a function of the *Kp* index, for a population of angular drift velocity  $\Omega = 1 \ mHz$ . The ends of the whiskers indicate the minimum and maximum values, the bottoms and the tops of the boxes are the lower and upper quartiles, and the bands inside the boxes are the medians. The values were computed for the year 2013 according to **equation (24)**, with a one-minute time resolution.

363 A linear interpolation of the medians per Kp index for the electromagnetic radial diffusion 364 magnitude yields:

365

$$log_{10}(D_{LL}/L^{10}) = -9.309 + 0.377 \times Kp \ [log_{10}(day^{-1})]$$
(25)

366

This interpolation is remarkably similar to the one obtained by Brautigam and Albert (2000) (equation (1)). The difference in the intercepts is < 1% while the slope as a function of Kp is only 25% smaller than the one found by Brautigam and Albert. One reason for such similarity may be that both estimates rely on the same theoretical toy model for the electromagnetic fields. Yet, the

- 371 radial diffusion coefficients obtained by Lanzerotti and Morgan (1973) and Lanzerotti et al. (1978) were based on an analysis of magnetic field fluctuations measured by at ground level (at L=4) and 372 373 at synchronous equatorial altitude (L=6.6). In these analyzes, the power spectrum of the fluctuations was fitted to a functional form ( $P \propto \Omega^{-s}$ , with s between 1 and 3). On the other hand, 374 the numerical evaluations proposed here rely on solar wind measurements, and the autocorrelation 375 376 function is fitted to an exponential decay (equation (7)). Because  $\tau$  is found to be very small, both fitting methods are usually equivalent: In both cases, the power spectrum decreases as  $\propto \Omega^{-2}$  over 377 378 a large frequency range. The time series of the three parameters constitutive of  $F_{1h}$  together with the magnitude of 379  $log_{10}(D_{II}/L^{10})$  computed for the year 2013 for a radiation belt population of angular drift 380
- frequency  $\Omega = 1 \ mHz$  is accessible online (http://doi.org/10.5281/zenodo.3625265).
- 382 383

#### 384 **5. Discussion**

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386 The pros and cons of the method developed in this paper are summarized in the following.

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First, the method faces the same theoretical limitations as the ones underlying Brautigam and 388 Albert's formula for electromagnetic diffusion. Namely: It relies on an oversimplified 389 electromagnetic field model (a "toy model"). Even when fitting the simplified Mead (1964)'s 390 391 magnetic field formula to a basic external magnetic field model, such as the one developed by 392 Tsyganenko (1989), discrepancies appear. There is also little doubt that the response of the magnetospheric fields to fluctuations in the magnetopause location is more complicated than what 393 is actually described by the theoretical picture provided here. The proposed radial diffusion 394 395 coefficients are also limited at both high and low L values. Indeed, at high L values, the electromagnetic field is expected to be more distorted and more variable than predicted. In that 396 context, the distinction between L and  $L^*$  is also necessary (e.g. Roederer & Lejosne, 2018). At 397 398 low L values, electrostatic radial diffusion is probably very important (e.g., O'Brien et al., 2016; 399 Selesnick et al., 2016), and yet such diffusion process is not taken into account here.

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401 Even so, the resulting coefficients binned as a function of the Kp index display remarkable 402 agreement an empirical law that is generally considered standard. Furthermore, the theoretical picture presented here provides physical insights on the origin of radial diffusion variability: radial 403 diffusion increases as the Kp index increases both because the magnetic field is more compressed 404 (thus, the average asymmetry increases), and because it fluctuates more (thus, the variance of the 405 asymmetry increases). The model also describes how electromagnetic radial diffusion varies with 406 drift frequency. When the drift frequency increases, the part of the radial diffusion coefficient that 407 explicitly depends on energy (third term equation (9)) increases, until it plateaus (for  $\Omega \tau \gg 1$ ). 408 The term that quantifies the effect of the statistical characteristics of the magnetopause,  $F_T$ , is also 409 indirectly controlled by drift frequency. Indeed, the signal decomposition into an average and a 410 fluctuating part requires the definition of a reference. The reference, set by adiabatic invariant 411 theory, is the drift period. Field variations that evolve on time scales greater than the drift period 412 are part of the average (that is, they do not violate the third invariant), while field variations that 413

- 414 evolve on time scales shorter than the drift period constitute the fluctuating part of the signal. As 415 the drift frequency increases, the average describes more and more precisely the signal 416 instantaneous values, and the variance decreases. Thus,  $F_T$  decreases as the drift frequency increases. As a result, there is a sweet spot in drift frequency at which radial diffusion is maximal, 417  $\Omega_{max}$ . A derivation of equation (9) with respect to  $log_{10}(\Omega)$  yields  $\Omega_{max} \approx 0.6/\tau$ . With a 418 419 fluctuation lifetime,  $\tau$ , of the order of a couple of minutes,  $\Omega_{max} \approx 5 \ mHz$ . Even so, for  $\Omega \tau \ll 1$ , as is typically the case for most radiation belt particles, the resulting dependence of 420 electromagnetic radial diffusion on drift frequency is relatively weak ( $D_{LL} \propto \sim \Omega^{0.5}$ ). Such feature 421 greatly simplifies radial diffusion quantification. 422
- 423 In the most general case, radial diffusion is controlled by the asymmetry in the electromagnetic field fluctuations (e.g., Northrop, 1963; Lejosne et al., 2012). Thus, quantifying radial diffusion 424 425 requires monitoring electromagnetic field fluctuations. While previous work attempted to monitor 426 the asymmetry of the magnetic field at geostationary orbit (Lejosne et al., 2013), this new model 427 presents the advantage of being operational. Leveraging a toy model for the fields, the asymmetry 428 of the field is controlled by the magnetopause, whose location is a function of solar wind parameters. Interestingly enough, it is not the first time that the solar wind is chosen to drive radial 429 430 diffusion (Li et al., 2001). From a technical standpoint, the advantage of working with such a 431 simple model is that it highlights some of the challenges that need to be addressed to quantify radial diffusion accurately, regardless of the model complexity. In particular, this work highlights 432

some of the difficulties related to the analysis of non-stationary field fluctuations.

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